

Path Independence and FTLI

We've previously seen how vector line integrals are (mostly) independent of the parametrization of the curve, which we restate in the following theorem.

Theorem 1. *Let $\vec{F} : X \subset \mathbb{R}^n \rightarrow \mathbb{R}^n$ be a vector field, and consider a curve parametrized by simple C^1 parametrizations $\vec{x} : [a, b] \rightarrow \mathbb{R}^n$ and $\vec{y} : [c, d] \rightarrow \mathbb{R}^n$.*

If \vec{x} and \vec{y} have the same orientation, then

$$\int_{\vec{x}} \vec{F} \cdot d\vec{s} = \int_{\vec{y}} \vec{F} \cdot d\vec{s}.$$

If \vec{x} and \vec{y} have opposite orientations, then

$$\int_{\vec{x}} \vec{F} \cdot d\vec{s} = - \int_{\vec{y}} \vec{F} \cdot d\vec{s}.$$

Now, let's suppose we have two different curves, but they start and end at the same points. Will vector line integrals over these paths be equal?

PICTURE

Surprisingly, for some vector fields, the answer is “yes.” This is called path independence, and we'll explore which vector fields have this property.

Path Independence

A vector field is path independent if its line integrals depend only on the start and end points, and not on the path we take to get between the points.

Definition 1. *A continuous vector field is called path independent if $\int_C \vec{F} \cdot d\vec{s} = \int_D \vec{F} \cdot d\vec{s}$ for any two simple, piecewise C^1 , oriented curves C and D with the same start and end points.*

Let's quickly review the meaning of the requirements on the curves C and D .

A curve is *simple* if it (isn't too “bumpy.” / doesn't intersect itself, except the start and end point can be the same. \checkmark / is smooth.)

Learning outcomes: Understand the definition of path independent. Use the Fundamental Theorem of Line Integrals to compute vector line integrals of conservative vector fields, or to show that a vector field is path independent.

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A curve is C^1 if it (is continuous. / is differentiable. / has continuous partial derivatives. ✓)

A curve is *oriented* if it (has a specified direction. ✓/ knows which way is North.)

Let's look at some examples.

Example 1. Consider the vector field $\vec{F}(x, y) = (y, 0)$. Let $\mathbf{x}(t)$ be the path from $(1, 0)$ to $(0, 1)$ along a straight line. Let $\mathbf{y}(t)$ be the path from $(1, 0)$ to $(0, 1)$ counterclockwise around the unit circle. Compute $\int_{\mathbf{x}} \vec{F} \cdot d\mathbf{s}$ and $\int_{\mathbf{y}} \vec{F} \cdot d\mathbf{s}$. Are they equal?

We'll begin by parametrizing our paths.

$$\mathbf{x}(t) = (\boxed{1-t}, \boxed{t}) \quad \text{for } t \in [0, 1]$$

$$\mathbf{y}(t) = (\boxed{\cos(t)}, \boxed{\sin(t)}) \quad \text{for } t \in [0, \frac{\pi}{2}]$$

Now, we compute these line integrals using the definition

$$\int_{\mathbf{x}} \vec{F} \cdot d\mathbf{s} = \int_a^b \vec{F}(\mathbf{x}(t)) \cdot \mathbf{x}'(t) dt.$$

Integrating along \mathbf{x} , we have

$$\begin{aligned} \int_{\mathbf{x}} \vec{F} \cdot d\mathbf{s} &= \int_a^b \vec{F}(\mathbf{x}(t)) \cdot \mathbf{x}'(t) dt \\ &= \int_{\boxed{0}}^{\boxed{1}} (t, 0) \cdot (-1, 1) dt \\ &= \int_{\boxed{0}}^{\boxed{1}} -t dt \\ &= \boxed{-\frac{1}{2}} \end{aligned}$$

Integrating along \mathbf{y} , we have

$$\begin{aligned} \int_{\mathbf{y}} \vec{F} \cdot d\mathbf{s} &= \int_a^b \vec{F}(\mathbf{y}(t)) \cdot \mathbf{y}'(t) dt \\ &= \int_0^{\pi/2} (\sin(t), 0) \cdot (\boxed{-\sin(t)}, \boxed{\cos(t)}) dt \\ &= \int_0^{\pi/2} \boxed{-\sin^2(t)} dt \\ &= \boxed{-\frac{\pi}{4}} \end{aligned}$$

Comparing $\int_x \vec{F} \cdot d\mathbf{s}$ and $\int_y \vec{F} \cdot d\mathbf{s}$, we see that they are

Multiple Choice:

- (a) Equal.
- (b) Not equal. ✓

As a result, we know that the vector field \vec{F} ...

Multiple Choice:

- (a) ...is path independent.
- (b) ...is not path independent. ✓
- (c) ...might be path independent. There isn't enough information to tell.

Now, let's investigate integrating a different vector field along those same paths.

Example 2. Consider the vector field $\vec{F}(x, y) = (y, x)$. Let $\mathbf{x}(t)$ be the path from $(1, 0)$ to $(0, 1)$ along a straight line. Let $\mathbf{y}(t)$ be the path from $(1, 0)$ to $(0, 1)$ counterclockwise around the unit circle. Compute $\int_x \vec{F} \cdot d\mathbf{s}$ and $\int_y \vec{F} \cdot d\mathbf{s}$. Are they equal?

Once again, we begin by parametrizing our paths.

$$\mathbf{x}(t) = (1 - t, t) \quad \text{for } t \in [0, 1]$$

$$\mathbf{y}(t) = (\cos(t), \sin(t)) \quad \text{for } t \in [0, \frac{\pi}{2}]$$

Next, we compute these line integrals using the definition

$$\int_x \vec{F} \cdot d\mathbf{s} = \int_a^b \vec{F}(\mathbf{x}(t)) \cdot \mathbf{x}'(t) dt.$$

Integrating along \mathbf{x} , we have

$$\begin{aligned} \int_x \vec{F} \cdot d\mathbf{s} &= \int_a^b \vec{F}(\mathbf{x}(t)) \cdot \mathbf{x}'(t) dt \\ &= \int_0^1 (\boxed{t}, \boxed{1-t}) \cdot (-1, 1) dt \\ &= \int_0^1 \boxed{1-2t} dt \\ &= \boxed{0} \end{aligned}$$

Integrating along \mathbf{y} , we have

$$\begin{aligned}\int_{\mathbf{y}} \vec{F} \cdot d\mathbf{s} &= \int_a^b \vec{F}(\mathbf{y}(t)) \cdot \mathbf{y}'(t) dt \\ &= \int_0^{\pi/2} (\boxed{\sin(t)}, \boxed{\cos(t)}) \cdot (-\sin(t), \cos(t)) dt \\ &= \int_0^{\pi/2} \boxed{-\sin^2(t) + \cos^2(t)} dt \\ &= \boxed{0}\end{aligned}$$

Comparing $\int_x \vec{F} \cdot d\mathbf{s}$ and $\int_{\mathbf{y}} \vec{F} \cdot d\mathbf{s}$, we see that they are

Multiple Choice:

- (a) Equal. ✓
- (b) Not equal.

As a result, we know that the vector field \vec{F} ...

Multiple Choice:

- (a) ...is path independent.
- (b) ...is not path independent.
- (c) ...might be path independent. There isn't enough information to tell. ✓

In fact, it turns out that the vector field $\vec{F}(x, y) = (y, x)$ is path independent. However, in order to check directly that a vector field \vec{F} is path independent, we would need to check the line integrals over any path between any two points in the domain. Of course, this is impossible! We will need to find different methods for showing that a vector field is path independent. Our first result in this direction is the Fundamental Theorem of Line Integrals.

Fundamental Theorem of Line Integrals

We now introduce the Fundamental Theorem of Line Integrals, which gives us a powerful way to compute the integral of a gradient vector field over a piecewise C^1 curve. In particular, note the conditions on the domain X : it must be open and path-connected.

Theorem 2. Fundamental Theorem of Line Integrals

Let $f : X \subset \mathbb{R}^n \rightarrow \mathbb{R}$ be C^1 , where X is open and path-connected. Then if C is any piecewise C^1 curve from \mathbf{A} to \mathbf{B} , then

$$\int_C \nabla f \cdot d\mathbf{s} = f(\mathbf{B}) - f(\mathbf{A})$$

This should look vaguely familiar - it resembles the Fundamental Theorem of Calculus from single variable calculus, also called the evaluation theorem.

We now prove the Fundamental Theorem of Line Integrals in the special case where we have a *simple* parametrization of the curve C .

Proof Let $\mathbf{x}(t)$ be a simple parametrization of C , where $t \in [a, b]$, $\mathbf{x}(a) = \mathbf{A}$, and $\mathbf{x}(b) = \mathbf{B}$ (so the starting point is \mathbf{A} , and the ending point is \mathbf{B}).

Then we compute the line integral as:

$$\int_C \nabla f \cdot d\mathbf{s} = \int_{\mathbf{x}} \nabla f \cdot d\mathbf{s}.$$

By the definition, we can compute this line integral as

$$\int_{\mathbf{x}} \nabla f \cdot d\mathbf{s} = \int_a^b \nabla f(\mathbf{x}(t)) \cdot \mathbf{x}'(t) dt.$$

The integrand here should look familiar from one of the multivariable versions of the chain rule - it's the derivative of $f(\mathbf{x}(t))$. Making this replacement, we have

$$\int_{\mathbf{x}} \nabla f \cdot d\mathbf{s} = \int_a^b \frac{d}{dt}(f(\mathbf{x}(t))) dt.$$

Now, we can apply the Fundamental Theorem of Calculus (from single variable) to evaluate this integral, since an antiderivative for the integrand will be given by $f(\mathbf{x}(t))$. From this we obtain:

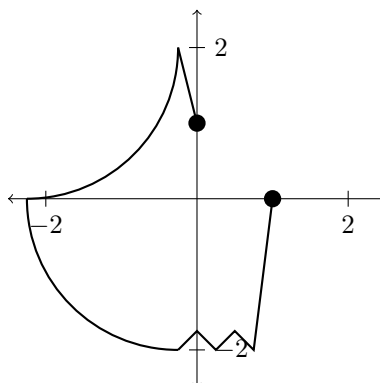
$$\begin{aligned} \int_{\mathbf{x}} \nabla f \cdot d\mathbf{s} &= (f(\mathbf{x}(t)))|_a^b \\ &= f(\mathbf{x}(b)) - f(\mathbf{x}(a)) \\ &= f(\mathbf{B}) - f(\mathbf{A}) \end{aligned}$$

In the last step, we use that \mathbf{A} and \mathbf{B} are the start and end points of $\mathbf{x}(t)$, respectively.

Thus, we have proven the Fundamental Theorem of Line Integrals (when we have a simple parametrization of the curve C). ■

Before discussing how the Fundamental Theorem of Line Integrals relates to path independence, let's look at how this helps us compute integrals of gradient vector fields.

Example 3. Let $\vec{F}(x, y) = (y, x)$. Observe that $\vec{F} = \nabla f$, where $f(x, y) = xy$. Compute $\int_C \vec{F} \cdot d\mathbf{s}$ for the curve C below, starting at $(0, 1)$ and ending at $(1, 0)$.



Explanation. We certainly would like to avoid parametrizing this curve! So, we will use the Fundamental Theorem of Line Integrals to compute this integral.

First, let's verify that $\vec{F} = \nabla f$ for $f(x, y) = xy$.

$$\begin{aligned}\frac{\partial}{\partial x} xy &= \boxed{y} \\ \frac{\partial}{\partial y} xy &= \boxed{x}\end{aligned}$$

Thus, we have $\nabla f(x, y) = (y, x) = \vec{F}(x, y)$.

We can then use the Fundamental Theorem of Line Integrals to compute $\int_C \vec{F} \cdot d\mathbf{s}$.

$$\begin{aligned}\int_C \vec{F} \cdot d\mathbf{s} &= \int_C \nabla f \cdot d\mathbf{s} \\ &= f(0, 1) - f(1, 0) \\ &= \boxed{0}\end{aligned}$$

Now, it turns out that we can use the Fundamental Theorem of Line Integrals to prove the following corollary about the relationship between conservative vector fields and path independence. Note once again that we require the domain to be open and path-connected.

Corollary 1. If \vec{F} is a conservative vector field defined on an open and connected domain X , then \vec{F} is path independent.

Proof Let C and D be two curves with starting point \mathbf{A} and ending point \mathbf{B} . We will show that $\int_C \vec{F} \cdot d\mathbf{s} = \int_D \vec{F} \cdot d\mathbf{s}$.

Recall that “ \vec{F} is conservative” means that $\vec{F} = \nabla f$ for some function f , which will enable us to use the Fundamental Theorem of Line Integrals (FTLI). Then we have:

$$\begin{aligned}\int_C \vec{F} \cdot d\mathbf{s} &= \int_C \nabla f \cdot d\mathbf{s} \\ &= f(\mathbf{B}) - f(\mathbf{A}) && \text{(by FTLI)} \\ &= \int_D \nabla f \cdot d\mathbf{s} && \text{(also by FTLI)} \\ &= \int_D \vec{F} \cdot d\mathbf{s}.\end{aligned}$$

Thus, we have shown that $\int_C \vec{F} \cdot d\mathbf{s} = \int_D \vec{F} \cdot d\mathbf{s}$, and so have shown that \vec{F} is path independent. ■

This corollary, with the Fundamental Theorem of Line Integrals, gives us a new tool for computing line integrals.

Strategies for Computing Line Integrals

We now have a few options for computing line integrals:

- (a) Using the original definition:

$$\int_C \vec{F} \cdot d\mathbf{s} = \int_a^b \vec{F}(\mathbf{x}(t)) \cdot \mathbf{x}'(t) dt$$

- (b) If \vec{F} is conservative (so $\vec{F} = \nabla f$ for some f):

- (i) We can use the Fundamental Theorem of Line Integrals:

$$\int_C \vec{F} \cdot d\mathbf{s} = f(\mathbf{B}) - f(\mathbf{A})$$

- (ii) Since the vector field is path independent, we can find an *easier* path with the same start and end points, and integrate over that path.

Let's look at how these different methods can be used in an example.

Example 4. Let $\vec{F}(x, y) = (2xy^2, 2x^2y)$, and consider $\mathbf{x}(t) = (2 \cos(\pi t), \sin(\pi t^2))$ for $t \in [0, 1]$. Compute $\int_{\mathbf{x}} \vec{F} \cdot d\mathbf{s}$.

Explanation. We'll evaluate this integral in three different ways.

First, let's evaluate using the definition of vector line integrals.

$$\begin{aligned}\int_x \vec{F} \cdot d\mathbf{s} &= \int_a^b \vec{F}(\mathbf{x}(t)) \cdot \mathbf{x}'(t) dt \\ &= \int_0^1 (4 \cos(\pi t) \sin^2(\pi t^2), 8 \cos^2(\pi t) \sin(\pi t^2)) \cdot \left(\boxed{-2\pi \sin(\pi t)}, \boxed{2\pi t \cos(\pi t^2)} \right) dt \\ &= \int_0^1 \boxed{-8\pi \cos(\pi t) \sin(\pi t) \sin^2(\pi t^2) + 16\pi t \cos(\pi t^2) \cos^2(\pi t) \sin(\pi t^2)} dt\end{aligned}$$

This is an integral that it might be possible to figure out how to compute, but we certainly do not want to! We can use a computer algebra system to see that the result is 0, but to compute the integral by hand, we will turn to our other methods.

For our alternate methods, we need to find a potential function $f(x, y)$ such that $\vec{F} = \nabla f$. It turns out that $f(x, y) = x^2 y^2$ works. Let's verify this.

$$\begin{aligned}\frac{\partial}{\partial x}(x^2 y^2) &= \boxed{2xy^2} \\ \frac{\partial}{\partial y}(x^2 y^2) &= \boxed{2x^2 y}\end{aligned}$$

Now that we have our function $f(x, y) = x^2 y^2$ such that $\vec{F} = \nabla f$, we will use the Fundamental Theorem of Line Integrals to evaluate. Note the start and end points of our curve

$$\begin{aligned}\mathbf{A} &= \mathbf{x}(0) = (\boxed{2}, \boxed{0}) \\ \mathbf{B} &= \mathbf{x}(1) = (\boxed{-2}, \boxed{0})\end{aligned}$$

$$\begin{aligned}\int_x \vec{F} \cdot d\mathbf{s} &= \int_x \nabla f \cdot d\mathbf{s} \\ &= f(\mathbf{B}) - f(\mathbf{A}) \\ &= \boxed{0}\end{aligned}$$

Note that this is a much easier computation than the integral we had from the first method.

Finally, we compute the line integral using the third method. We have already shown that \vec{F} is a conservative vector field (by finding f such that $\vec{F} = \nabla f$), and

hence we know that \vec{F} is path independent. So we can compute this integral by instead integrating over an easier path with the same start and end points, $(2, 0)$ and $(-2, 0)$, respectively. Let's choose the straight line from $(2, 0)$ to $(-2, 0)$, and parametrize this curve.

$$\mathbf{y}(t) = (\boxed{t}, 0) \quad \text{for } t \in [-2, 2]$$

Now we can integrate over y instead, which will be a much easier computation.

$$\begin{aligned} \int_x \vec{F} \cdot d\mathbf{s} &= \int_y \vec{F} \cdot d\mathbf{s} \\ &= \int_{-2}^2 \vec{F}(\mathbf{y}(t)) \cdot \mathbf{y}'(t) dt \\ &= \int_{-2}^2 (\boxed{0}, \boxed{0}) \cdot (1, 0) dt \\ &= \int_{-2}^2 \boxed{0} dt \\ &= \boxed{0} \end{aligned}$$

So we've seen that we can compute this line integral in a few different ways, using the fact that the vector field is conservative.

Depending on the particular problem or example, any one of these methods might be easier than the others. You should practice trying these different methods, and see which you prefer! However, remember that for the second and third options, we need to first verify that the vector field \vec{F} is conservative. This usually means finding a potential function f such that $\vec{F} = \nabla f$.