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Pipelining

Chap. 4.5



Introduction to Pipelining

Sequential Processing



Parallel Processing (Multi-core)

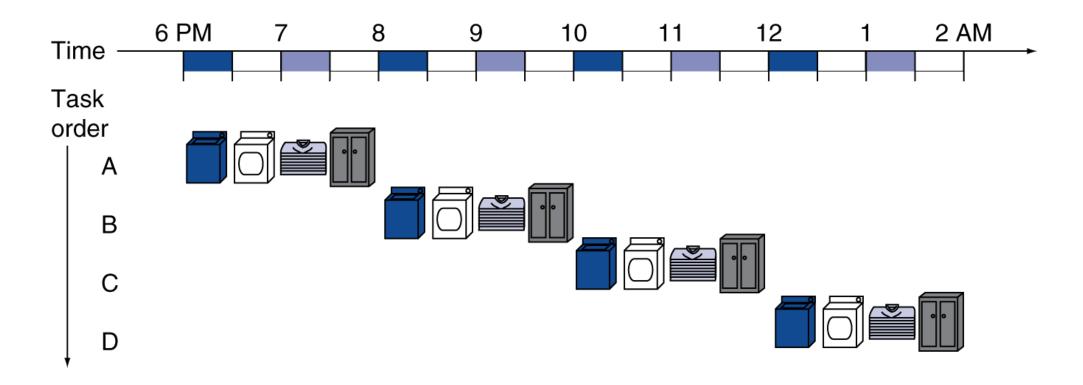


Pipelining



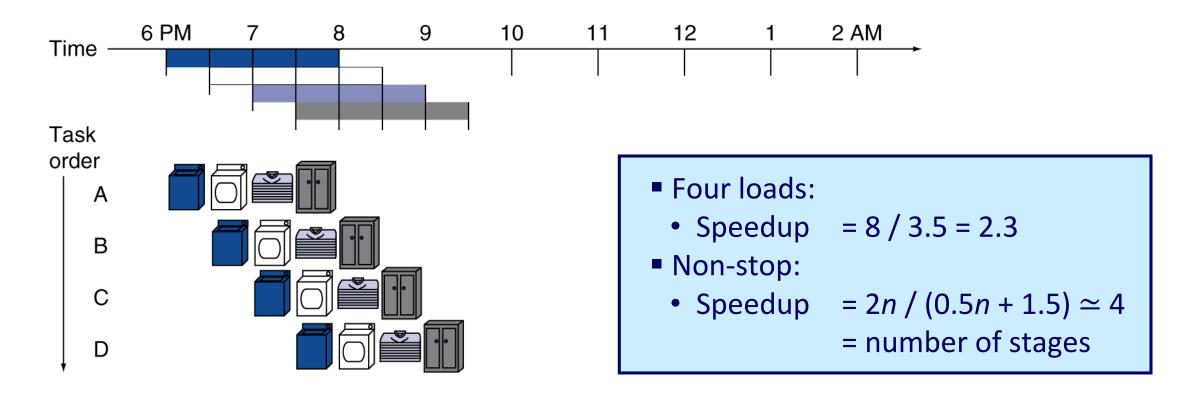
Laundry Example

Sequential processing: Wash-Dry-Fold-Store



Pipelined Laundry Example

- Overlapping execution
- Parallelism improves performance



A RISC-V Pipeline

Five stages, one step per stage

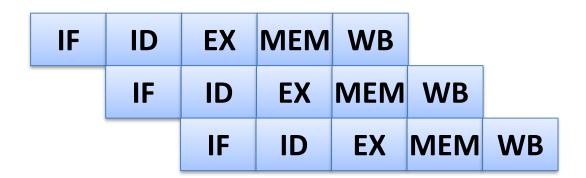
- IF: Instruction fetch from memory
- ID: Instruction decode & register read
- EX: Execute operation or calculate address
- MEM: Access memory operand
- WB: Write result back to register

Pipelined Instruction Execution

Sequential execution



Pipelined execution



add x10, x11, x12
sub x13, x14, x15
and x5, x6, x7

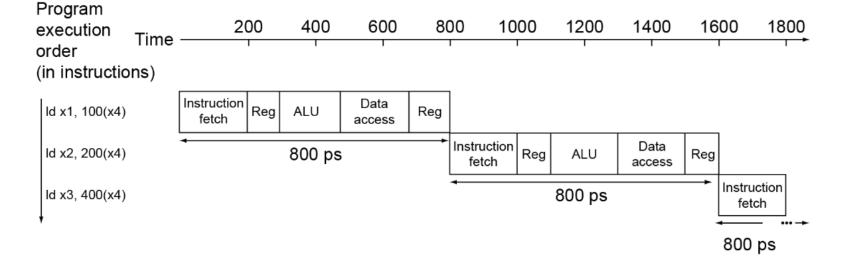
Pipeline Performance

- Assume time for stages is
 - 100ps for register read or write
 - 200ps for other stages
- Compare piplined datapath with single-cycle datapath

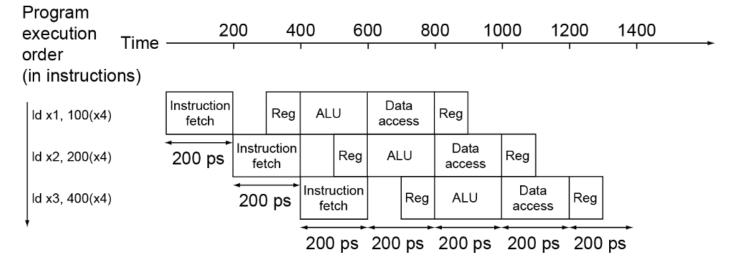
| Inst. | Inst. fetch | Register read | ALU op. | Memory access | Register write | Total time |
|--------|----------------|------------------|---------|------------------|-------------------|---------------|
| ld | 200ps | 100ps | 200ps | 200ps | 100ps | 800ps |
| sd | 200ps | 100ps | 200ps | 200ps | | 700ps |
| R-type | 200ps | 100ps | 200ps | | 100ps | 600ps |
| beq | 200ps | 100ps | 200ps | | | 500ps |

Pipeline Performance (cont'd)

Single-cycle $(T_c = 800ps)$



Pipelined $(T_c = 200ps)$



Pipeline Speedup

- If all stages are balanced
 - i.e., all take the same time

$$Time\ between\ instructions_{pipelined}\ = \frac{Time\ between\ instructions_{nonpipelined}}{Number\ of\ stages}$$

- If not balanced, speedup is less
- Speedup due to increased throughput
- Latency (time for each instruction) does not decrease

Pipelining and ISA Design

RISC-V ISA designed for pipelining

- All instructions are 32-bits
 - Easier to fetch and decode in one cycle
 - cf. x86: I- to I7-byte instructions
- Few and regular instruction formats
 - Source and destination register fields located in the same place
 - Can decode and read registers in one step
- Load/store addressing
 - Can calculate address in 3rd EX stage, access memory in 4th MEM stage

Pipeline Hazards

Hazards

Situations that prevent starting the next instruction in the next cycle

- Structural hazard
 - A required resource is busy
- Data hazard
 - Need to wait (or stall) for previous instruction to complete its data read/write
- Control hazard
 - Deciding on control action depends on previous instruction

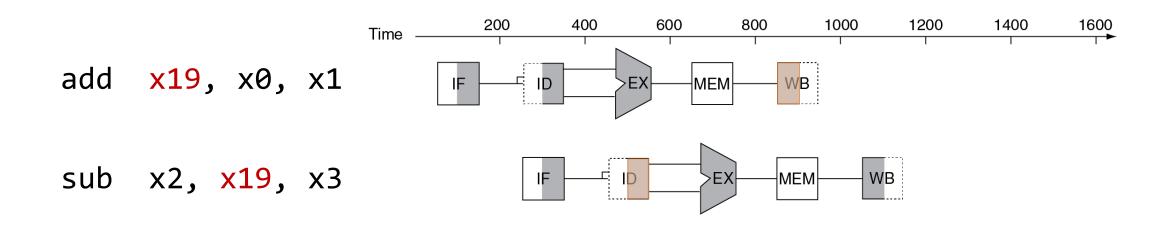
Structural Hazard

- Conflict for use of a resource
- In RISC-V pipeline with a single memory
 - Load/store requires data access
 - Instruction fetch would have to stall for that cycle
 - → Would cause a pipeline "bubble"
 - Hence, pipelined datapaths require separate instruction/data memories (or separate instruction/data caches)
- Register file also requires multiple ports (for 2 reads and 1 write)

| | IF | ID | EX | MEM | WB | Register write | | | | |
|------------------|----|----|----|-----|-----|----------------|------------------|--|--|------|
| | | IF | ID | EX | MEM | WB | Memory read/writ | | | rite |
| | | | IF | ID | EX | MEM | WB | | | |
| Register read IF | | | IF | ID | EX | MEM | WB | | | |
| Memory read | | | IF | ID | EX | MEM | WB | | | |

Data Hazard

- An instruction depends on completion of data access by a previous instruction
- Also called "Read-After-Write (RAW)" hazard
- This hazard results from an actual need for communication



Solutions to Data Hazard

Freezing the pipeline

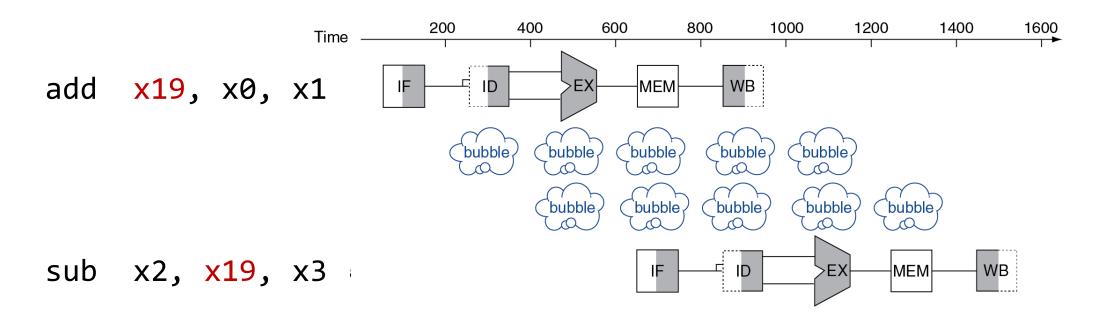
Forwarding

Compiler scheduling

Out-Of-Order execution (discussed later)

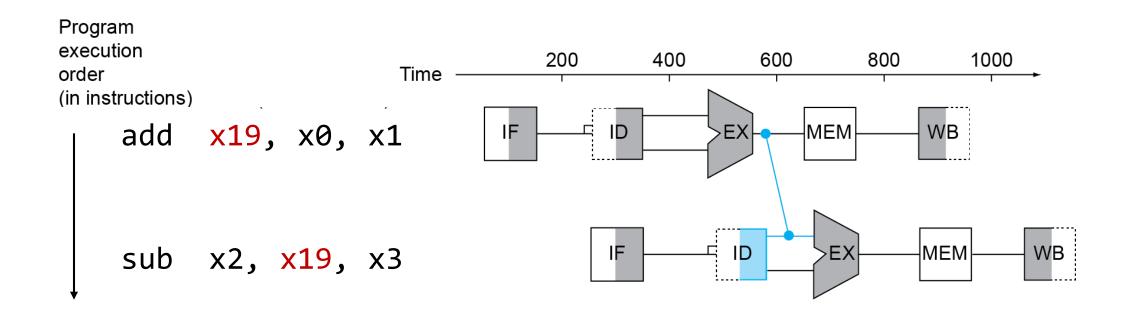
Freezing the Pipeline

- Stall the pipeline until dependences are resolved
- ALU result to next instruction (2 stalls)



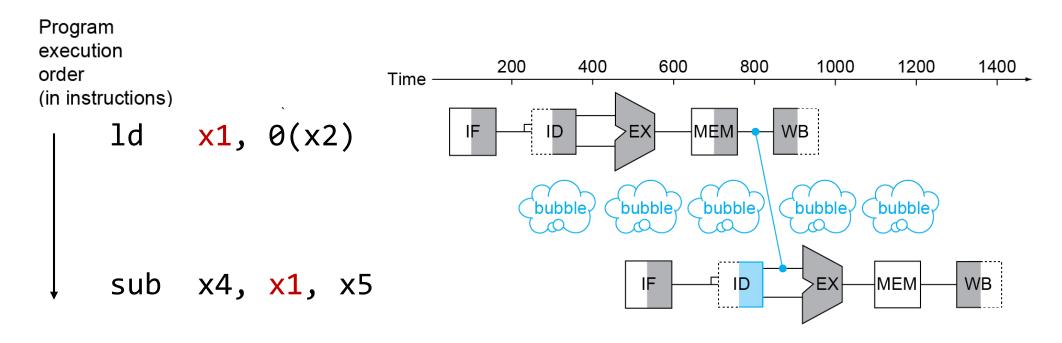
Forwarding (or Bypassing)

- Use result when it is computed
 - Don't wait for it to be stored in a register
 - Requires extra connections in the datapath

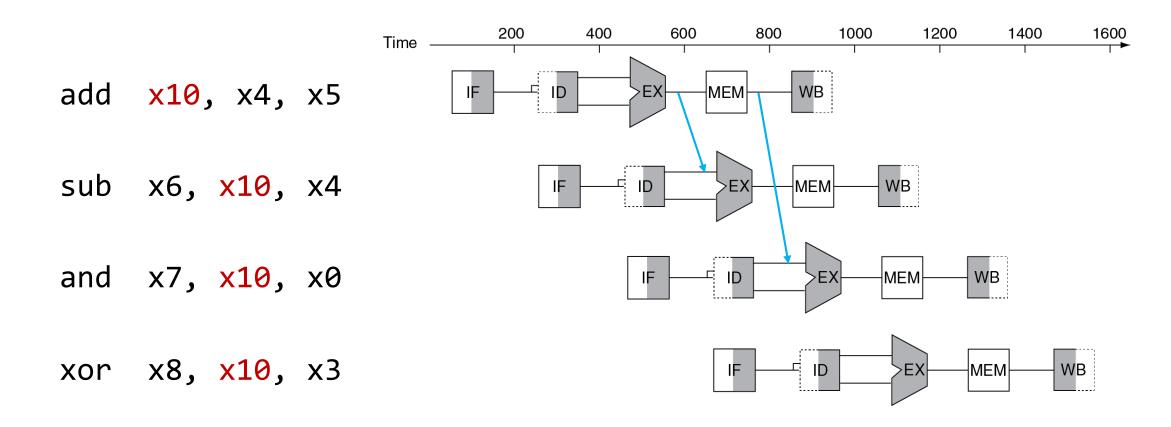


Forwarding: Load-Use Data Hazard

- Can't always avoid stalls by forwarding
 - If value not computed when needed
 - Can't forward backward in time!



Forwarding: Multiple Readers

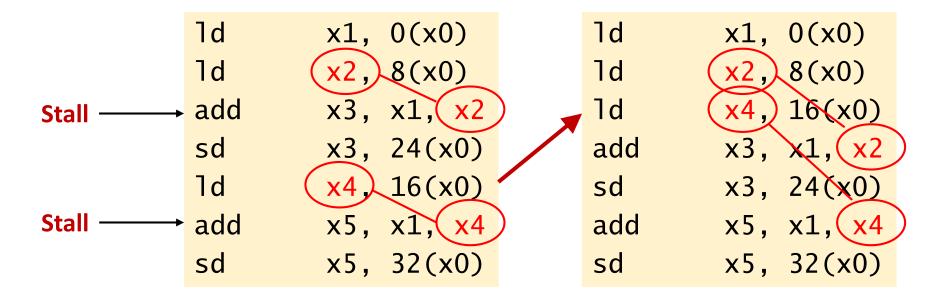


Forwarding: Multiple Writers

400 600 800 1000 1200 1400 1600 Time **x10**, x4, x5 add ID x10, x5, x6 sub ID addi **x10**, x2, 1 WB MEM ID x8, x10, x7 xor WB MEM

Compiler Scheduling

- Reorder code to avoid use of load result in the next instruction
- C code for v[3] = v[0] + v[1]; v[4] = v[0] + v[2];



13 cycles

11 cycles

Control Hazard

Branch determines flow of control

- Fetching next instruction depends on branch outcome
- Pipeline can't always fetch correct instruction: still working on ID stage of branch

In RISC-V pipeline

- Need to compare registers and compute target early in the pipeline
- Add hardware to do it in ID stage

Solutions to Control Hazard

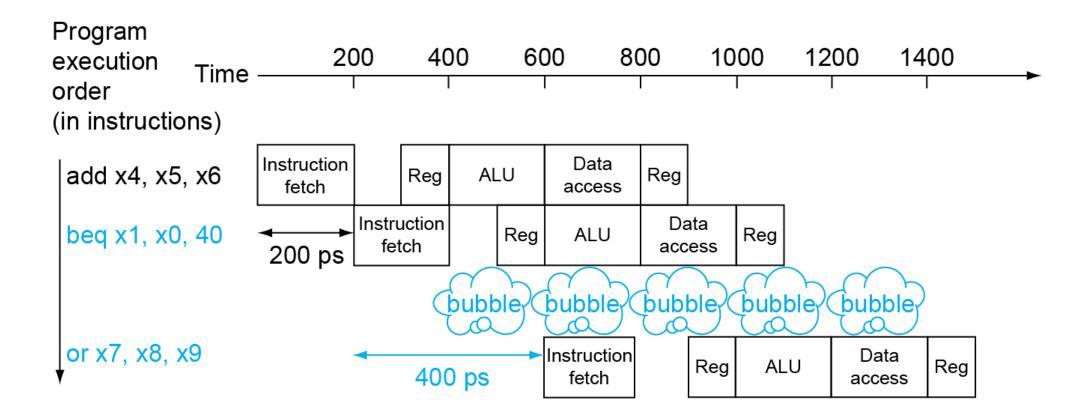
Stall on branch

Branch prediction

Delayed branch (compiler scheduling to avoid stalls)

Stall on Branch

Wait until branch outcome determined before fetching next instruction



Branch Prediction

- Longer pipelines can't readily determine branch outcome early
 - Stall penalty becomes unacceptable
- Predict outcome of branch
 - Only stall if prediction is wrong
- In RISC-V pipeline
 - Can predict branches not taken
 - Fetch instruction after branch, with no delay
 - Cancel the fetched instruction if the prediction was wrong

More-Realistic Branch Prediction

Static branch prediction

- Based on typical branch behavior
- Example: loop and if-statement branches
 - Predict backward branches taken
 - Predict forward branches not taken

Dynamic branch prediction

- Hardware measures actual branch behavior
 - e.g., record recent history of each branch
- Assume future behavior will continue the trend
 - When wrong, stall while re-fetching and update history

Summary

- Pipelining improves performance by increasing instruction throughput
 - Executes multiple instructions in parallel
 - Each instruction has the same latency
- Subject to hazards
 - Structural, data, control
- Instruction set design affects complexity of pipeline implementation