

updated 19 March 2019

2.3 additional exercises

1. Repeat the instructions for exercise 1 in the text for the system below.

$$\begin{aligned}x' &= .1x - 3y \\ y' &= 3x + .1y\end{aligned}$$

For part (a), show that $(x, y) = (e^{1t} \cos 3t, e^{1t} \sin 3t)$ is a solution to the initial value problem $x(0) = 1, y(0) = 1$. Then do the same parts (b), (c), (d) as in exercise 1 in the text.

2.4 additional exercises

1. Solve the following system for $x = x(t), y = y(t)$, where a, b, c are constants and initial values are $x(0) = x_0, y(0) = y_0$. Notice that you will need to consider two cases: $a \neq c$ and $a = c$.

$$\begin{aligned}x' &= ax \\ y' &= bx + cy\end{aligned}$$

2. Sketch the graph of $y = e^{at}(bt + c)$ for 8 possible cases: $a = \pm 1, b = \pm 1, c = 0, 1$.

3.1 and 3.2 additional exercises

1. Let A be an $n \times n$ matrix and suppose $A\vec{v} = \lambda\vec{v}$ for some $\vec{v} \neq 0$ and some scalar λ , that is, λ is an eigenvalue for A with a corresponding eigenvector \vec{v} . Let $\vec{w} = \frac{\vec{v}}{|\vec{v}|}$. Show that $|\vec{w}| = 1$ and that $A\vec{w} = \lambda\vec{w}$. This exercise justifies the common practice of assuming that eigenvectors have norm 1.
2. Let A be a 2×2 matrix with distinct real eigenvalues λ_1, λ_2 and corresponding eigenvectors \vec{v}_1, \vec{v}_2 .
 - (a) Show that \vec{v}_1, \vec{v}_2 are independent.
 - (b) Let $\Lambda = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix}$ and let B be the 2×2 matrix whose first column is \vec{v}_1 and whose second column is \vec{v}_2 . Show that

$$A = B\Lambda B^{-1}.$$

- (c) Suppose that, in addition to being independent, the eigenvectors \vec{v}_1, \vec{v}_2 are orthogonal and have unit length. Show that

$$A = \lambda_1 \vec{v}_1 \vec{v}_1^T + \lambda_2 \vec{v}_2 \vec{v}_2^T.$$

3.4 additional exercises

Consider the linear differential equation

$$(0.0.1) \quad \vec{x}' = A\vec{x}$$

where A be a 2×2 matrix with real entries, and suppose that A has a complex eigenvalue λ that is not real. Let \vec{v} be a corresponding eigenvector.

1. Show that the eigenvalues λ_1, λ_2 of A have the form $\alpha + i\beta$ for some real numbers α, β , with $\beta \neq 0$.
2. Show that $\vec{x} = e^{\lambda t}\vec{v}$ is a solution to (0.0.1).
3. Show that $\vec{x} = e^{\bar{\lambda}t}\bar{\vec{v}}$ is also a solution (the horizontal bar symbol indicated complex conjugation).
4. Show that the real and imaginary parts of $e^{\lambda t}\vec{v}$ are both solutions, and argue why $\vec{v}, \bar{\vec{v}}$ are independent.
5. Conclude that the general solution to (0.0.1) is a superposition of the real and imaginary parts of $e^{\lambda t}\vec{v}$.

3.5 additional exercises

Consider the linear differential equation (0.0.1) above, but this time suppose that A has a repeated real eigenvalue λ with eigenvector an \vec{v} , and that there do *not* exist two independent eigenvectors.

1. Show that it is possible to find a vector \vec{w} so that $A\vec{w} = \lambda\vec{w} + \vec{v}$, such that \vec{v}, \vec{w} are independent.
2. Show that $e^{\lambda t}(\vec{w} + t\vec{v})$ is a solution to (0.0.1).
3. Conclude that the general solution to (0.0.1) is given by

$$c_1 e^{\lambda t} \vec{v} + c_2 e^{\lambda t} (\vec{w} + t\vec{v}).$$

4. Find the general solution for (0.0.1) with $A = \frac{1}{2} \begin{pmatrix} 5 & 1 \\ -1 & 7 \end{pmatrix}$.