NETFLIX

Restricted Boltzmann Machines

Markus Pawellek

January 24, 2019

Outline

Problem

The Model

Learning

Inference

Implementation

Going Further

Problem

	Star Trek	The Matrix	Van Helsing	Harry Potter	The Hobbit
James T. Kirk	1	1	×	0	×
Trinity	×	1	0	1	1
Anna Valerious	×	×	1	×	0
Severus Snape	0	1	0	1	0
Thorin Oakenshield	1	1	1	×	0

	Star Trek	The Matrix	Van Helsing	Harry Potter	The Hobbit
James T. Kirk	1	1	×	0	×
Trinity	×	1	0	1	1
Anna Valerious	×	×	1	×	0
Severus Snape	0	1	0	1	0
Thorin Oakenshield	1	1	1	×	0

Goal:

	Star Trek	The Matrix	Van Helsing	Harry Potter	The Hobbit
James T. Kirk	1	1	×	0	×
Trinity	×	1	0	1	1
Anna Valerious	×	×	1	×	0
Severus Snape	0	1	0	1	0
Thorin Oakenshield	1	1	1	×	0

Goal:

approximately represent a complex probability distribution

	Star Trek	The Matrix	Van Helsing	Harry Potter	The Hobbit
James T. Kirk	1	1	×	0	×
Trinity	×	1	0	1	1
Anna Valerious	×	×	1	×	0
Severus Snape	0	1	0	1	0
Thorin Oakenshield	1	1	1	×	0

Goal:

- approximately represent a complex probability distribution
- learn probability distribution based on given samples

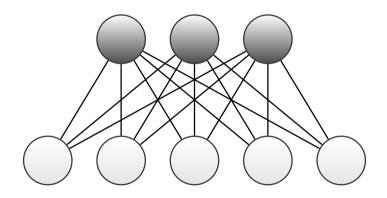
	Star Trek	The Matrix	Van Helsing	Harry Potter	The Hobbit
James T. Kirk	1	1	×	0	×
Trinity	×	1	0	1	1
Anna Valerious	×	×	1	×	0
Severus Snape	0	1	0	1	0
Thorin Oakenshield	1	1	1	×	0

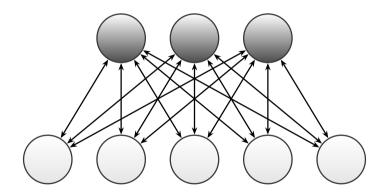
Goal:

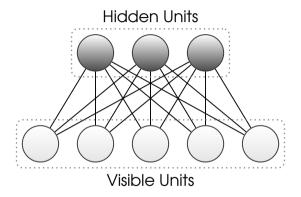
- approximately represent a complex probability distribution
- learn probability distribution based on given samples
- make predictions based on learned parameters

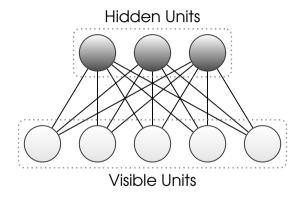


The Model

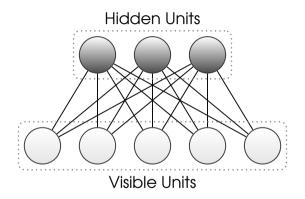






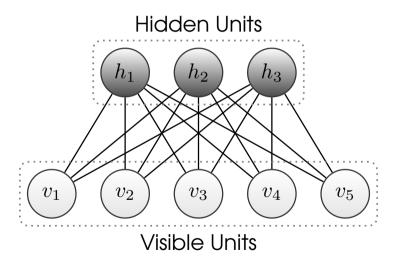


units are divided into two subsets

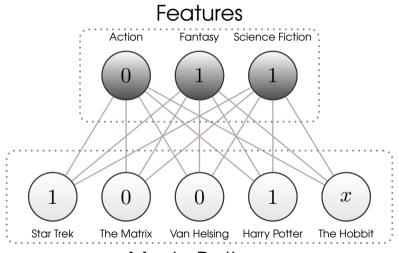


- units are divided into two subsets
- only connections between hidden and visible units are allowed

The Model: Idea – Inputs



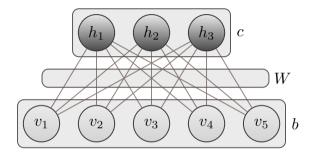
The Model: Idea – Example



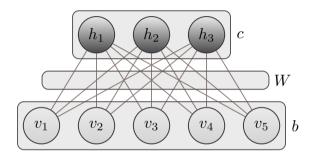
Movie Ratings



The Model: Parameters



The Model: Parameters



$$v \in V \coloneqq \{0,1\}^n$$
 $h \in H \coloneqq \{0,1\}^m$ $\vartheta \coloneqq (W,b,c) \in \mathbb{R}^{(n \times m) + n + m}$

The Model: Probability Distribution and Energy

$$p[\vartheta] \colon V \times H \to [0,1] \qquad p[\vartheta](v,h) \coloneqq \frac{e^{-E[\vartheta](v,h)}}{Z(\vartheta)}$$

The Model: Probability Distribution and Energy

$$p[\vartheta] \colon V \times H \to [0,1]$$
 $p[\vartheta](v,h) \coloneqq \frac{e^{-E[\vartheta](v,h)}}{Z(\vartheta)}$

$$E[\vartheta] \colon V \times H \to \mathbb{R}$$
 $E[\vartheta](v,h) \coloneqq -v^{\mathrm{T}}Wh - v^{\mathrm{T}}b - h^{\mathrm{T}}c$

The Model: Probability Distribution and Energy

$$p[\vartheta] \colon V \times H \to [0,1]$$
 $p[\vartheta](v,h) \coloneqq \frac{e^{-E[\vartheta](v,h)}}{Z(\vartheta)}$

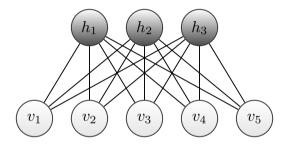
$$E[\vartheta] \colon V \times H \to \mathbb{R}$$
 $E[\vartheta](v,h) \coloneqq -v^{\mathrm{T}}Wh - v^{\mathrm{T}}b - h^{\mathrm{T}}c$

$$Z(\vartheta) \coloneqq \sum_{v \in V} \sum_{h \in H} e^{-E[\vartheta](v,h)}$$

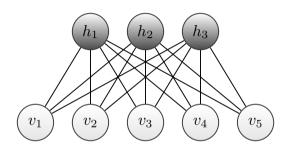
The Model: Probability Distribution for Visible Units

$$p[\vartheta] \colon V \to [0,1] \qquad p[\vartheta](v) \coloneqq \sum_{h \in H} p[\vartheta](v,h)$$

The Model: Posterior Probability



The Model: Posterior Probability



$$p[\vartheta](h|v) = \prod_{j=1}^{m} p[\vartheta] (h_j = 1|v)$$

Learning

Learning: Maximum Likelihood Estimation

$$S \in V^s$$
 $\mathcal{L}[S]: \mathbb{R}^{n \times m + n + m} \to \mathbb{R}$ $\mathcal{L}[S](\vartheta) := \frac{1}{s} \sum_{k=1}^s \ln p[\vartheta](S_k)$

- maximize the product of probabilities of given samples
- equivalent to maximizing log-likelihood function

Learning: Gradient Ascent

$$\nabla_{W} \mathcal{L}[\mathbb{S}](\vartheta) = \frac{1}{s} \sum_{k=1}^{s} \mathbb{E}_{\vartheta} \left[\mathcal{V} \mathcal{H}^{\mathrm{T}} \middle| \mathbb{S}_{k} \right] - \mathbb{E}_{\vartheta} \left[\mathcal{V} \mathcal{H}^{\mathrm{T}} \right]$$

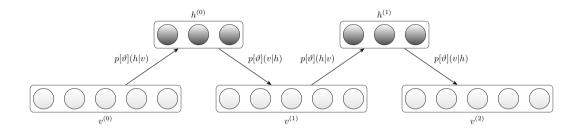
use stochastic gradient ascent with minibatches

Learning: Gradient Ascent

$$\nabla_{W} \mathcal{L}[S](\vartheta) = \frac{1}{s} \sum_{k=1}^{s} \mathbb{E}_{\vartheta} \left[\mathcal{V} \mathcal{H}^{\mathrm{T}} \middle| S_{k} \right] - \mathbb{E}_{\vartheta} \left[\mathcal{V} \mathcal{H}^{\mathrm{T}} \right]$$

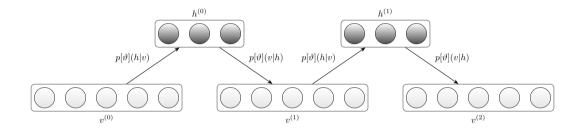
- use stochastic gradient ascent with minibatches
- evaluating the gradient introduces problems

Learning: Gibbs Sampling



 \blacktriangleright to estimate $\mathbb{E}_{\vartheta}\left[\mathcal{VH}^{T}\right]$ perform Gibbs sampling

Learning: Gibbs Sampling



- \blacktriangleright to estimate $\mathbb{E}_{\vartheta}\left[\mathcal{VH}^{T}\right]$ perform Gibbs sampling
- slow because it has to reach equilibrium

Learning: Contrastive Divergence

 \blacktriangleright abort Gibbs Sampling after $v^{(k)}$ and $h^{(k)}$ are computed

Learning: Contrastive Divergence

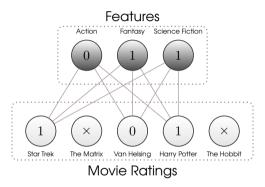
- lacktriangle abort Gibbs Sampling after $v^{(k)}$ and $h^{(k)}$ are computed
- approximate the expectation value

Learning: Contrastive Divergence

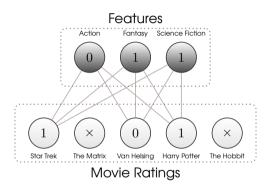
- lacktriangle abort Gibbs Sampling after $v^{(k)}$ and $h^{(k)}$ are computed
- approximate the expectation value

$$\mathbb{E}_{\vartheta} \left[\mathcal{V} \mathcal{H}^{\mathrm{T}} \right] \approx v^{(k)} h^{(k)}^{\mathrm{T}}$$

Learning: Example

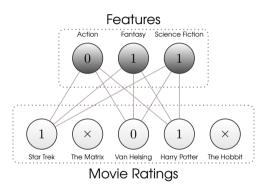


Learning: Example



one RBM for every user with connections for rated movies

Learning: Example

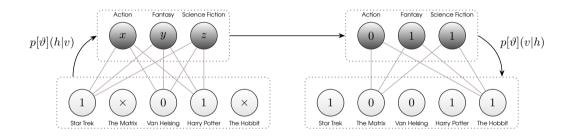


- one RBM for every user with connections for rated movies
- weights and biases off all RBM are tied together

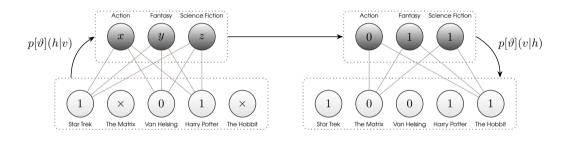


Inference

Inference: Example

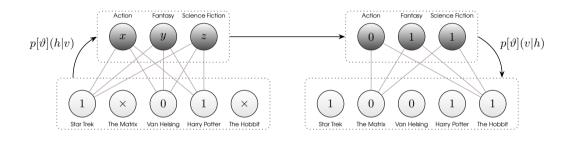


Inference: Example



compute hidden values only for rated movies

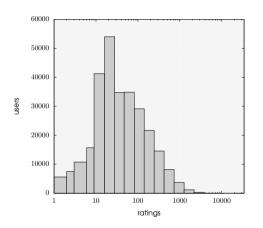
Inference: Example

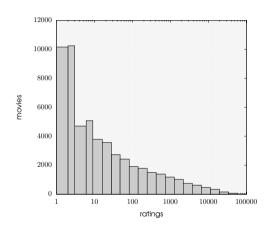


- compute hidden values only for rated movies
- compute visible values of unrated movies based on hidden values

Implementation

Implementation: MovieLens Dataset by GroupLens





 $ightharpoonup \sim$ 27,000,000 ratings, \sim 58,000 movies, \sim 280,000 users



Implementation: Rating Database

	Star Trek	The Matrix	Van Helsing	Harry Potter	The Hobbit
James T. Kirk	1	1	×	0	×
Trinity	×	1	0	1	1
Anna Valerious	×	×	1	×	0
Severus Snape	0	1	0	1	0
Thorin Oakenshield	1	1	1	×	0

- ▶ implement as sparse matrix in CSR format
- entries should be floating point

Implementation: Training and Testing

- same users in training and testing dataset
- divide ratings of users into training and testing dataset
- learn biases and weights for every user only for rated movies

Going Further

Going Further: Tweak the Learning

- Contrastive Divergence Variants
- Momentum
- Weight Decay
- Different types of units

Going Further: Applications

- language modeling and document retrieval
- classification
- reducing dimensionality of data

References

- (1) Fischer, Asja and Christian Igel: An introduction to restricted bottzmann machines. LNCS, 7441:14–36, 2012.
- (2) GroupLens: Movielens dataset, 2018. https://grouplens.org/datasets/movielens/latest/, visited on 2019-01-21.
- (3) Harper, F. Maxwell und Joseph A. Konstan: The MovieLens Datasets: History and Context. ACM Trans. Interact. Intell. Syst., 5(4):19:1–19:19, Dezember 2015, ISSN 2160-6455. http://doi.acm.org/10.1145/2827872.
- (4) Hinton, Geoffrey: A practical guide to training restricted boltzmann machines: Version 1. 2010. https:// www.cs.toronto.edu/~hinton/absps/guideTR.pdf.
- (5) Montúfar, Guido: Restricted boltzmann machines: Introduction and review. CoRR, abs/1806.07066, 2018. http://arxiv.org/abs/1806.07066.
- (6) Murphy, Kevin P.: Machine Learning: A Probabilistic Perspective. MIT Press, 2012, ISBN 978-0-262-01802-9.

- (7) Nefflix: Nefflix prize, 2009. https://www.netflixprize.com/index.html, visited on 2019-01-21.
- (8) Netflix: Netflix prize dataset, 2009. https://archive.org/details/nf_prize_dataset.tar, visited on 2019-01-21.
- (9) Nefflix: Nefflix logo, 2018. https://mms.businesswire.com/media/20150827005946/en/482959/5/etflix-Logo.jpg?download=1, visited on 2019-01-21.
- (10) Oppermann, Artem: Deep learning meets physics: Restricted boltzmann machines part i, 2018. https://towardsdatascience.com/deep-learningmeets-physics-restricted-boltzmann-machinespart-i-6df5c4918c15, visited on 2019-01-22.
- (11) Salakhutdinov, Ruslan, Andriy Mnih, and Geoffrey Hinton: Restricted boltzmann machines for collaborative filtering. Proceedings of the 24th international conference on Machine learning, pages 791–798, 2007.