# Chapter 3 Testing

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# More About Models: Two approaches for linear model

Parameter-free approach

$${\bf Y}={\sf E}({\bf Y})+{\bf Y}-{\sf E}({\bf Y})=\mu+\epsilon$$
 where  ${\sf E}({\bf Y})=\mu$  and  $\epsilon={\bf Y}-{\sf E}({\bf Y}).$ 

Parameter approach

$$\mathbf{Y}=\mathsf{E}(\mathbf{Y})+\mathbf{Y}-\mathsf{E}(\mathbf{Y})=\mathbf{X}eta+\epsilon$$
 where  $\mathsf{E}(\mathbf{Y})=\mathbf{X}eta$  and  $\epsilon=\mathbf{Y}-\mathbf{X}eta.$ 

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$$\mathsf{E}(\epsilon) = 0, \, \mathsf{Cov}(\epsilon) = \sigma^2 I \quad \mathsf{Ordinary Least Square}(\mathsf{OLS})$$

or

$$E(\epsilon) = 0$$
,  $Cov(\epsilon) = \sigma^2 \Sigma$  Generalized Least Square(GLS)

### More About Models

Consider

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon}, \quad \mathsf{E}(\boldsymbol{\epsilon}) = 0, \quad \mathsf{Cov}(\boldsymbol{\epsilon}) = \sigma^2 \boldsymbol{I}$$

- C(X) = Estimation space
- $M = \mathbf{X}(\mathbf{X}^T\mathbf{X})^{-}\mathbf{X}^T = \text{orthogonal projection onto } \mathcal{C}(\mathbf{X})$
- $E(\mathbf{Y}) = \mathbf{X}\boldsymbol{\beta} \in \mathcal{C}(\mathbf{X}), Cov(\mathbf{Y}) = \sigma^2 I$
- $C(\mathbf{X})^{\perp} = \text{Error space}$
- $\mathbf{I} M = \mathbf{I} \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-} \mathbf{X}^T = \text{orthogonal projection onto } \mathcal{C}(\mathbf{X})^{\perp}$
- $\epsilon \in \mathcal{C}(\mathbf{X})^T$ ,  $Cov(\epsilon) = \sigma^2 I$
- Any two linear models with the same estimation space are the same model.

### More About Models

One-Way ANOVA

$$\mathbf{y}_{ij} = \mu_i + \epsilon_{ij} = \mu + \alpha_i + \epsilon_{ij}, \text{ with } \mu_i = \mathsf{E}(\mathbf{y}_{ij}) = \mu + \alpha_i$$

$$\bar{\mu} = \mu + \bar{\alpha}_+$$

$$\mu_1 - \mu_2 = \alpha_1 - \alpha_2$$

The parameters in the two models are different, but they are related.

Simple Linear Regression

$$y_i = \beta_0 + \beta_1 x_i + \epsilon_i$$
  
=  $\gamma_0 + \gamma_1 (x_i - \bar{x}) + \epsilon_i$ 

where

$$\mathsf{E}(y_i) = \beta_0 + \beta_1 x_i = \gamma_0 + \gamma_1 (x_i - \bar{x})$$



### More About Models

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$$C(\mathbf{X}_1) = C(\mathbf{X}_1) \Rightarrow \mathbf{X}_1 = \mathbf{X}_2 T$$

so that

$$\mathbf{X}_1\boldsymbol{\beta}_1 = \mathbf{X}_2T\boldsymbol{\beta}_1 = \mathbf{X}_2\boldsymbol{\beta}_2$$

which implies that

$$\boldsymbol{\beta}_2 = T\boldsymbol{\beta}_1 + \boldsymbol{\nu} \quad \text{for } \boldsymbol{\nu} \in \mathcal{C}(\mathbf{X}_2^T)^{\perp}$$

- NOTE: A unique parameterization for  $\mathbf{X}_j$ , j=1,2 occurs if and only if  $\mathbf{X}_i^T \mathbf{X}_j$  is nonsingular.
- Exercise: Show that a unique parameterization for  $\mathbf{X}_j$ , j=1,2 means  $\mathcal{C}(\mathbf{X}_2^T)^{\perp}=\{0\}$ .



Consider

$$\begin{array}{lll} \mathbf{Y} &=& \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon}, & \boldsymbol{\epsilon} \sim \textit{N}(0, \mathbf{I}_{\textit{n}}) \\ \text{Let's partition } \mathbf{X} \text{ into } \mathbf{X} = (\mathbf{X}_{0}, \mathbf{X}_{1}) \colon \mathcal{C}(\mathbf{X}_{0}) \subset \mathcal{C}(\mathbf{X}) \\ \mathbf{Y} &=& \mathbf{X}_{0}\boldsymbol{\beta}_{0} + \mathbf{X}_{1}\boldsymbol{\beta}_{1} + \boldsymbol{\epsilon} & \colon \text{Full Model(FM)} \\ \mathbf{Y} &=& \mathbf{X}_{0}\boldsymbol{\gamma} + \boldsymbol{\epsilon} & \colon \text{Reduced Model(RM)} \end{array}$$

Hypothesis testing procedure can be described as

$$H_0$$
: Reduced Model(RM)  $H_1$ : Full Model(FM)

Example 3.2.0: pp. 52–54

- Let M and  $M_0$  be the orthogonal projection onto  $C(\mathbf{X})$  and  $C(\mathbf{X}_0)$  respectively.
- Note that with  $\mathcal{C}(\mathbf{X}_0) \subset \mathcal{C}(\mathbf{X})$ ,  $M-M_0$  is the orthogonal projection onto the orthogonal complement of  $\mathcal{C}(\mathbf{X}_0)$  with respect to  $\mathcal{C}(\mathbf{X})$ , that is,

$$\mathcal{C}(X_0)_{\mathcal{C}(\mathbf{X})}^{\perp} = \mathcal{C}(M-M_0) = \mathcal{C}(M\cap M_0^{\perp})$$
 check! and  $\hat{\mu} = \hat{\mathsf{E}}(\mathbf{Y}) = M\mathbf{Y}$  under FM  $\hat{\mu}_0 = \hat{\mathsf{E}}(\mathbf{Y}) = M_0\mathbf{Y}$  under RM

- If RM is true, then  $M\mathbf{Y} M_0\mathbf{Y} = (M M_0)\mathbf{Y}$  should be reasonably small.
- Note that  $E(M M_0)Y = 0$



The decision about whether RM is appropriate hinges on deciding whether the vector  $(M - M_0)$ Y is large.

An obvious measure of the size of  $(M - M_0)\mathbf{Y}$  is

$$[(M-M_0)\mathbf{Y}]^T[(M-M_0)\mathbf{Y}] = \mathbf{Y}^T(M-M_0)\mathbf{Y}.$$

A reasonable measure of the size of  $(M - M_0)\mathbf{Y}$  is given by  $\mathbf{Y}^T(M - M_0)\mathbf{Y}/r(M - M_0)$ 

Note that

$$\mathsf{E}\left[\frac{\mathbf{Y}^{\mathsf{T}}(M-M_0)\mathbf{Y}}{r(M-M_0)}\right] = \sigma^2 + \frac{\beta^{\mathsf{T}}\mathbf{X}^{\mathsf{T}}(M-M_0)\mathbf{X}\beta}{r(M-M_0)}$$

**Theorem 3.2.1.** Consider  $\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon}, \quad \boldsymbol{\epsilon} \sim \mathcal{N}(0, \mathbf{I}_n)$  with  $\mathcal{C}(\mathbf{X}_0) \subset \mathcal{C}(\mathbf{X})$ 

$$\mathbf{Y} = \mathbf{X}_0 \boldsymbol{\beta}_0 + \mathbf{X}_1 \boldsymbol{\beta}_1 + \boldsymbol{\epsilon}$$
: Full Model(FM)

 $\mathbf{Y} = \mathbf{X}_0 \gamma + \boldsymbol{\epsilon}$ : Reduced Model(RM)

(i) Under the Full Model(FM),

$$\frac{\mathbf{Y}^{T}(M-M_{0})\mathbf{Y}/r(M-M_{0})}{\mathbf{Y}^{T}(\mathbf{I}-M)\mathbf{Y}/r(\mathbf{I}-M)} \sim F\left(df_{1}, df_{2}, \frac{\beta^{T}\mathbf{X}^{T}(M-M_{0})\mathbf{X}\beta}{2\sigma^{2}}\right)$$

where  $df_1 = r(M - M_0)$ ,  $df_2 = r(I - M)$ 

(ii) Under the Reduced Model(RM),

$$\frac{\mathbf{Y}^{T}(M-M_{0})\mathbf{Y}/r(M-M_{0})}{\mathbf{Y}^{T}(\mathbf{I}-M)\mathbf{Y}/r(\mathbf{I}-M)}\sim F(df_{1},df_{2},0)$$

where 
$$df_1 = r(M - M_0)$$
,  $df_2 = r(I - M)$ 

#### Note:

$$\mathbf{M} - M_0 = (I - M_0) - (I - M)$$
  
 $\mathbf{Y}^T (M - M_0) \mathbf{Y} = \mathbf{Y}^T (I - M_0) \mathbf{Y} - \mathbf{Y}^T (I - M) \mathbf{Y}$   
 $= SSE_{RM} - SSE_{FM}$ 

Example 3.2.2.; pp. 58-59

Assume that

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon}$$
 is correct.

Want to test the adequacy of a model

$$\mathbf{Y} = \mathbf{X}_0 \gamma + \mathbf{X} b + \epsilon$$

where  $C(\mathbf{X}_0) \subset C(\mathbf{X})$  and some known vector  $\mathbf{X}b = \text{offset}$ 

Example 3.2.3.; Multiple Regression

$$\mathbf{Y} = \beta_0 J + \beta_1 X_1 + \beta_2 X_2 + \beta_3 X_3 + \epsilon$$

To test  $H_0: \beta_2 = \beta_3 + 5, \beta_1 = 0,...$ 

In addition,

$$\frac{\mathbf{Y}^{*T}(M-M_0)\mathbf{Y}^*/r(M-M_0)}{\mathbf{Y}^{*T}(I-M)\mathbf{Y}^*/r(I-M)} \sim F(r(M-M_0), r(I-M), \delta^2)$$

where the noncentrality parameter  $\delta^2$  is

$$\delta^2 = \frac{1}{2\sigma^2} \beta^{*T} \mathbf{X}^T (M - M_0) \mathbf{X} \beta^*$$



Example 3.2.3.

$$\begin{array}{rcl} 0 &=& \beta^{*T}\mathbf{X}^T(M-M_0)\mathbf{X}\beta^* \\ \text{if and only if} & 0 &=& (M-M_0)\mathbf{X}\beta^* & \text{why?} \\ \text{if and only if} & \mathbf{X}\beta &=& M_0(\mathbf{X}\beta-\mathbf{X}b)+\mathbf{X}b & \text{why?} \\ \text{which holds if} & \gamma &=& (\mathbf{X}_0^T\mathbf{X}_0)^-\mathbf{X}_0(\mathbf{X}\beta-\mathbf{X}b)=(\mathbf{X}_0^T\mathbf{X}_0)^-\mathbf{X}_0\mathbf{X}\beta^* \\ \text{Furthermore,} & & \mathbf{Y}^{*T}(M-M_0)\mathbf{Y}^* &=& \mathbf{Y}^{*T}(I-M_0)\mathbf{Y}^*-\mathbf{Y}^{*T}(I-M)\mathbf{Y}^* \\ \text{and} & & & \mathbf{Y}^{*T}(I-M)\mathbf{Y}^* &=& \mathbf{Y}^T(I-M)\mathbf{Y} \end{array}$$

$$H_0: \mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon} \quad \text{and} \quad \boldsymbol{\Lambda}^T \boldsymbol{\beta} = 0$$
 (1)

$$\Lambda^{T}\beta = 0 \iff \beta \in \mathcal{N}(\Lambda^{T}) = \mathcal{C}(X)^{\perp} 
\iff \beta \perp \mathcal{C}(\Lambda) 
\iff \beta \perp \mathcal{C}(\Gamma) \text{ if } \exists \Gamma \text{ so that } \mathcal{C}(\Gamma) = \mathcal{C}(\Lambda) 
\iff \beta \perp \mathcal{C}(U) \text{ if } \exists U \text{ so that } \mathcal{C}(U) = \mathcal{C}(\Lambda)^{\perp} 
\iff \beta = U\gamma \text{ for some } \gamma$$
(2)

Thus, letting 
$$\mathbf{X}_0 = \mathbf{X}U$$
, (in general,  $\mathcal{C}(\mathbf{X}_0) \subset \mathcal{C}(\mathbf{X})$ )
$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon} = \mathbf{X}U\boldsymbol{\gamma} + \boldsymbol{\epsilon} = \mathbf{X}_0\boldsymbol{\gamma} + \boldsymbol{\epsilon}$$
(3)

Suppose  $C(\mathbf{X}_0) = C(\mathbf{X})$ . Then there is nothing to test and  $\Lambda^T \beta = 0$  involves only arbitrary side conditions that do not affect the model.

EXAMPLE 3.3.1. pp. 62-64



Estimable 
$$\Lambda^T \beta \iff \Lambda = \mathbf{X}^T P$$
 for some  $P$ 

#### Remark:

$$\mathcal{C}(\textit{MP}) \equiv \mathcal{C}(\textit{M} - \textit{M}_0) = \mathcal{C}(\textbf{X} - \textbf{X}_0) = \mathcal{C}(\textbf{X}) \cap \mathcal{C}(\textbf{X}_0)^{\perp} = \mathcal{C}(\textbf{X}_0)^{\perp}_{\mathcal{C}(\textbf{X})}$$

Thus, its distribution for testing  $H_0: \Lambda^T \beta = 0$  is given by

$$\frac{\mathbf{Y}^T M_{MP} \mathbf{Y} / r(M_{MP})}{\mathbf{Y}^T (I - M) \mathbf{Y} / r(I - M)} \sim F(r(M_{MP}), r(I - M), \delta^2)$$
 (5)

where  $\delta^2 = \boldsymbol{\beta}^T \mathbf{X}^T M_{MP} \mathbf{X} \boldsymbol{\beta}$ 

#### **Proposition 3.3.2**

$$\mathcal{C}(\textit{M}-\textit{M}_0) = \mathcal{C}(\textbf{X}_0)^{\perp}_{\mathcal{C}(\textbf{X})} \equiv \mathcal{C}(\textbf{X}\textit{U})^{\perp}_{\mathcal{C}(\textbf{X})} = \mathcal{C}(\textit{MP})$$



$$\begin{split} H_0: \mathbf{Y} &= \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon} \quad \text{and} \quad \boldsymbol{\Lambda}^T\boldsymbol{\beta} = 0 \\ &\iff H_0: \mathbf{Y} &= \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon} \quad \text{and} \quad \boldsymbol{P}^T\mathbf{X}\boldsymbol{\beta} = 0 \\ &\iff H_0: \mathbf{Y} &= \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon} \quad \text{and} \quad \boldsymbol{P}^T\boldsymbol{M}\mathbf{X}\boldsymbol{\beta} = 0 \quad (\boldsymbol{M}\mathbf{X} = \mathbf{X}) \\ &\iff \mathbf{E}(\mathbf{Y}) \in \mathcal{C}(\mathbf{X}) \quad \text{and} \quad \mathbf{E}(\mathbf{Y}) \perp \mathcal{C}(\boldsymbol{MP}) \\ &\iff \mathbf{E}(\mathbf{Y}) \in \mathcal{C}(\mathbf{X}) \cap \mathcal{C}(\boldsymbol{MP})^\perp \\ \text{and} \\ &\mathcal{C}(\mathbf{X}_0) = \mathcal{C}(\mathbf{X}) \cap \mathcal{C}(\boldsymbol{MP})^\perp = \mathcal{C}(\boldsymbol{MP})^\perp_{\mathcal{C}(\mathbf{X})} \\ &\Rightarrow \quad \mathcal{C}(\mathbf{X}_0)^\perp_{\mathcal{C}(\mathbf{X})} = \mathcal{C}(\boldsymbol{MP}) \\ &\iff \mathbf{X}_0 = (I - \boldsymbol{M}_{\boldsymbol{MP}})\mathbf{X} \end{split}$$

Theorem 3.3.3

$$\mathcal{C}[(I-M_{MP})\mathbf{X}] = \mathcal{C}(\mathbf{X}) \cap \mathcal{C}(MP)^{\perp} = \mathcal{C}(\mathbf{X}) \cap \mathcal{C}(P)^{\perp}$$

EXAMPLE 3.3.4.: pp.66-67



$$\Lambda^{T}\beta \text{ is estimable, i.e., } \Lambda = \mathbf{X}^{T}P$$

$$\mathcal{C}(\Lambda) = \mathcal{C}(\mathbf{X}^{T}P) = \mathcal{C}(MP)$$
and  $\mathbf{X}\hat{\beta} = M\mathbf{Y}$ , and  $\Lambda^{T}\hat{\beta} = P^{T}\mathbf{X}\hat{\beta} = P^{T}M\mathbf{Y}$ 

$$\mathbf{Y}^{T}M_{MP}\mathbf{Y} = \mathbf{Y}^{T}M(P^{T}MP)^{-}MP\mathbf{Y}$$

$$= \hat{\beta}^{T}\Lambda[P^{T}\mathbf{X}(\mathbf{X}^{T}\mathbf{X})^{-}\mathbf{X}^{T}P]^{-}\Lambda^{T}\hat{\beta}$$

$$= \hat{\beta}^{T}\Lambda[\Lambda^{T}(\mathbf{X}^{T}\mathbf{X})^{-}\Lambda]^{-}\Lambda^{T}\hat{\beta}$$

Thus,

(5) = 
$$\frac{\hat{\boldsymbol{\beta}}^T \Lambda [\Lambda^T (\mathbf{X}^T \mathbf{X})^- \Lambda]^- \Lambda^T \hat{\boldsymbol{\beta}} / r(\Lambda)}{MSE} \sim F(r(MP), r(I - M), \delta^2)$$

where

$$\delta^2 = \frac{\beta^T \Lambda [\Lambda^T (\mathbf{X}^T \mathbf{X})^- \Lambda]^- \Lambda^T \beta}{2\sigma^2}$$

$$Cov(\Lambda^T \hat{\boldsymbol{\beta}}) = \sigma^2 \Lambda^T (\mathbf{X}^T \mathbf{X})^- \Lambda$$



For 
$$H_0: \lambda^T \boldsymbol{\beta} = 0, \ \lambda \in \mathbf{R}^p$$
,

$$\mathbf{Y}^{T} M_{MP} \mathbf{Y} = \hat{\boldsymbol{\beta}}^{T} \lambda [\lambda^{T} (\mathbf{X}^{T} \mathbf{X})^{-} \lambda]^{-} \lambda^{T} \hat{\boldsymbol{\beta}}$$
$$= \frac{(\lambda^{T} \hat{\boldsymbol{\beta}})^{2}}{\lambda^{T} (\mathbf{X}^{T} \mathbf{X})^{-} \lambda}$$

and, under  $H_0: \lambda^T \beta = 0$ 

$$F = (5) = \frac{(\lambda^T \hat{\boldsymbol{\beta}})^2}{MSE[\lambda^T (\mathbf{X}^T \mathbf{X})^{-} \lambda]} \sim F(1, r(I - M))$$

**Definition 3.3.5.** The condition  $E(\mathbf{Y}) \perp \mathcal{C}(MP)$  is called the constraint by  $\Lambda^T \beta = 0$  where  $\Lambda = \mathbf{X}^T P$ :  $\mathcal{C}(MP) =$  the constraint by  $\Lambda^T \beta = 0$ .

**Do Exercise 3.5:** Show that a necessary and sufficient condition for  $\rho_1^T \mathbf{X} \boldsymbol{\beta} = 0$  and  $\rho_2^T \mathbf{X} \boldsymbol{\beta} = 0$  to determine orthogonal constraints on the model is that  $\rho_1^T \mathbf{X} \rho_2 = 0$ .

# **Theoretical Complements**

- Consider testing  $\Lambda^T \beta = 0$  when  $\Lambda^T \beta$  is NOT estimable
- Let  $\Lambda_0^T \beta$  be estimable part of  $\Lambda^T \beta$ .
- $\Lambda_0$  is chosen so that

$$\mathcal{C}(\Lambda_0) = \mathcal{C}(\Lambda) \cap \mathcal{C}(\mathbf{X}^T)$$

which means that  $\Lambda^T\beta=0$  implies that  $\Lambda^T_0\beta=0$  but  $\Lambda^T_0\beta$  is estimable because

$$\mathcal{C}(\Lambda_0) \subset \mathcal{C}(\mathbf{X}^T).$$

### **Theoretical Complements**

**Theorem 3.3.6.** Let  $\mathcal{C}(\Lambda_0) = \mathcal{C}(\Lambda) \cap \mathcal{C}(\mathbf{X}^T)$  and  $\mathcal{C}(U_0) = \mathcal{C}(\Lambda_0)^{\perp}$ . Then  $\mathcal{C}(\mathbf{X}U) = \mathcal{C}(\mathbf{X}U_0)$ . Thus  $\Lambda^T\beta = 0$  and  $\Lambda_0^T\beta = 0$  induce the same reduced model.

**Proposition 3.3.7.** Let  $\Lambda_0^T \beta$  be estimable and  $\Lambda \neq 0$ . Then

$$\Lambda^T \boldsymbol{\beta} = 0 \Longrightarrow \mathcal{C}(\mathbf{X}U) \neq \mathcal{C}(\mathbf{X}).$$

Corollary 3.3.8.

$$\mathcal{C}(\Lambda_0) = \mathcal{C}(\Lambda) \cap \mathcal{C}(\mathbf{X}^T) = \{0\} \iff \mathcal{C}(\mathbf{X}U) = \mathcal{C}(\mathbf{X}).$$

Consider  $H_0: \Lambda^T \beta = d$ , where  $d \in \mathcal{C}(\mathbf{X}^T)$ , which is solvable. Let b so that  $\Lambda^T b = d$ . Then

$$\begin{split} \boldsymbol{\Lambda}^T \boldsymbol{\beta} &= \boldsymbol{\Lambda}^T \boldsymbol{b} = \boldsymbol{d} \Longleftrightarrow \boldsymbol{\Lambda}^T (\boldsymbol{\beta} - \boldsymbol{b}) = \boldsymbol{0} \\ &\iff (\boldsymbol{\beta} - \boldsymbol{b}) \perp \mathcal{C}(\boldsymbol{\Lambda}) \\ &\iff (\boldsymbol{\beta} - \boldsymbol{b}) \in \mathcal{C}(\boldsymbol{U}) \quad \text{where} \quad \mathcal{C}(\boldsymbol{U}) = \mathcal{C}(\boldsymbol{\Lambda})^{\perp} \\ &\iff \boldsymbol{\beta} - \boldsymbol{b} = \boldsymbol{U}\boldsymbol{\gamma} \quad \text{for some } \boldsymbol{\gamma} \\ &\iff \mathbf{X}\boldsymbol{\beta} - \mathbf{X}\boldsymbol{b} = \mathbf{X}\boldsymbol{U}\boldsymbol{\gamma} \quad \text{i.e. } \mathbf{X}\boldsymbol{\beta} = \mathbf{X}\boldsymbol{U}\boldsymbol{\gamma} + \mathbf{X}\boldsymbol{b} \end{split}$$

and

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon} = \mathbf{X}\boldsymbol{U}\boldsymbol{\gamma} + \mathbf{X}\boldsymbol{b} + \boldsymbol{\epsilon}$$

$$= \mathbf{X}_0\boldsymbol{\gamma} + \mathbf{X}\boldsymbol{b} + \boldsymbol{\epsilon} \text{ where } \mathbf{X}_0 = \mathbf{X}\boldsymbol{U}$$
 (6)

If  $\Lambda = \mathbf{X}^T P$ , then  $\mathcal{C}(\mathbf{X}_0)_{\mathcal{C}(\mathbf{X})}^{\perp} = \mathcal{C}(MP)$  and its test statistic is

$$F = \frac{(\mathbf{Y} - \mathbf{X}b)^{T} M_{MP} (\mathbf{Y} - \mathbf{X}b) / r(M_{MP})}{(\mathbf{Y} - \mathbf{X}b)^{T} (I - M) (\mathbf{Y} - \mathbf{X}b) / r(I - M)}$$
$$= \frac{(\Lambda^{T} \hat{\beta} - d)^{T} [\Lambda^{T} (\mathbf{X}^{T} \mathbf{X})^{-} \Lambda]^{-} (\Lambda^{T} \hat{\beta} - d) / r(\Lambda)}{MSE} \sim F(?,?,?)$$

**Remark:** If  $\Lambda^T \beta = d$ , the same reduced model results if we take  $\Lambda^T \beta = d_0$  where  $d_0 = d + \Lambda^T \nu$  and  $\nu \perp \mathcal{C}(\mathbf{X}^T)$ . Note that, in this construction, if  $\Lambda^T \beta = d$  is estimable,  $d_0 = d$  for any  $\nu$ .

EXAMPLE 3.3.9.: pp.71-72