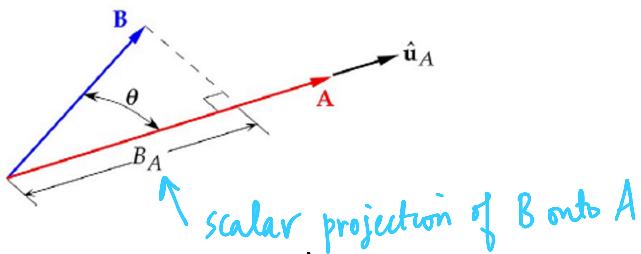


Lecture 2

- Recall that $\mathbf{A} \cdot \mathbf{B} = \|\mathbf{A}\| \|\mathbf{B}\| \cos \theta$
 $= A_x B_x + A_y B_y + A_z B_z$

If $\mathbf{A} = \mathbf{B}$, then $\|\mathbf{A}\| = \sqrt{\mathbf{A} \cdot \mathbf{A}}$

- The dot product can be used to project one vector onto the line of action of another:



Now, $B_A = \|\mathbf{B}\| \cos \theta$ and

$$\mathbf{B} \cdot \hat{\mathbf{u}}_A = \|\mathbf{B}\| \cos \theta$$

$$\text{So, } B_A = \mathbf{B} \cdot \hat{\mathbf{u}}_A = \mathbf{B} \cdot \frac{\mathbf{A}}{\|\mathbf{A}\|} = \frac{\mathbf{A} \cdot \mathbf{B}}{\|\mathbf{A}\|}$$

$$\text{Similarly, } A_B = \frac{\mathbf{A} \cdot \mathbf{B}}{\|\mathbf{B}\|}$$

- Note carefully, that $\vec{B}_A = B_A \hat{\mathbf{u}}_A = \left(\frac{\mathbf{A} \cdot \mathbf{B}}{\|\mathbf{A}\|^2} \right) \mathbf{A}$

and similarly, $\vec{A}_B = \left(\frac{\mathbf{A} \cdot \mathbf{B}}{\|\mathbf{B}\|^2} \right) \mathbf{B}$

- Observe that if $\|\mathbf{A}\| = \|\mathbf{B}\|$, then $A_B = B_A$

Example

Let $\mathbf{A} = \hat{i} + 6\hat{j} + 18\hat{k}$ and $\mathbf{B} = 42\hat{i} - 69\hat{j} + 98\hat{k}$. Calculate

- the angle between \mathbf{A} and \mathbf{B} ;
- the projection of \mathbf{B} in the direction of \mathbf{A} ;
- the projection of \mathbf{A} in the direction of \mathbf{B} .

Details

Details

$$(a) \quad \theta = \cos^{-1} \left(\frac{\mathbf{A} \cdot \mathbf{B}}{\|\mathbf{A}\| \|\mathbf{B}\|} \right)$$

$$\mathbf{A} \cdot \mathbf{B} = 1 \cdot 42 + 6 \cdot (-69) + 18 \cdot (98) = 1392$$

$$\|\mathbf{A}\| = \sqrt{1^2 + 6^2 + 18^2} = 19$$

$$\|\mathbf{B}\| = \sqrt{42^2 + (-69)^2 + 98^2} = 127$$

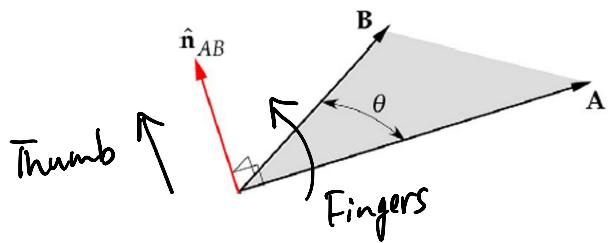
$$\theta = 54.77^\circ$$

$$(b) \quad B_A = \frac{\mathbf{A} \cdot \mathbf{B}}{\|\mathbf{A}\|} = \frac{1392}{19} = 73.26$$

$$(c) \quad A_B = \frac{\mathbf{A} \cdot \mathbf{B}}{\|\mathbf{B}\|} = \frac{1392}{127} = 10.96$$

- The cross product of two vectors is a vector defined as follows:

$$\boxed{\mathbf{A} \times \mathbf{B} = \|\mathbf{A}\| \|\mathbf{B}\| \sin \theta \hat{n}_{AB}}$$



$$A \times B = -(B \times A) \quad (\text{anti-commutative})$$

- $\hat{i}, \hat{j}, \hat{k}$

$$\begin{aligned}\hat{i} \times \hat{i} &= 0, & \hat{j} \times \hat{j} &= 0, & \hat{k} \times \hat{k} &= 0 \\ \hat{i} \times \hat{j} &= \hat{k}, & \hat{j} \times \hat{k} &= \hat{i}, & \hat{k} \times \hat{i} &= \hat{j}\end{aligned}$$

- Given two vectors A and B,

$$\begin{aligned}A &= A_x \hat{i} + A_y \hat{j} + A_z \hat{k} \\ B &= B_x \hat{i} + B_y \hat{j} + B_z \hat{k}\end{aligned}$$

$$\boxed{A \times B = (A_y B_z - A_z B_y) \hat{i} - (A_x B_z - A_z B_x) \hat{j} + (A_x B_y - A_y B_x) \hat{k}}$$

$$\text{or, } A \times B = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$$

- Note that $\hat{n}_{AB} = \frac{A \times B}{\|A \times B\|}$.

- Note that the area of the parallelogram spanned by A and B = $\|A \times B\|$.

Note that $A \times B = 0 \Leftrightarrow$ one vector

- Note that $A \times B = 0 \Leftrightarrow$ one vector is a scalar multiple of the other.

Example

Let $A = -3\hat{i} + 7\hat{j} + 9\hat{k}$ and $B = 6\hat{i} - 5\hat{j} + 8\hat{k}$.

Find a unit vector, which lies in the plane of A and B and is perpendicular to A .

Details

Compute $D = A \times B \Rightarrow A \perp D, B \perp D$.

Compute $C = D \times A \Rightarrow C \perp D, C \perp A$.

So, $A, B, C \perp D \Rightarrow A, B, C$ are coplanar

Hence, $\hat{u}_c = \frac{C}{\|C\|}$.

bac - cab Rule

$$A \times (B \times C) = B(A \cdot C) - C(A \cdot B)$$

vector triple product

$$\begin{aligned} &= (A \cdot C)B - (A \cdot B)C \\ &= (A_x(x + A_y(y + A_z(z))B \\ &\quad - (A_x B_x + A_y B_y + A_z B_z)C \end{aligned}$$

Proof

$$A = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$$

$$B = B_x \hat{i} + B_y \hat{j} + B_z \hat{k}$$

$$C = C_x \hat{i} + C_y \hat{j} + C_z \hat{k}$$

$$\begin{aligned} &\text{.. component } x \\ &(A_x(x + A_y(y + A_z(z))B_x \\ &\quad - (A_x B_x + A_y B_y + A_z B_z)(x \\ &\quad .. = (A \cdot C)B_x \end{aligned}$$

$$C = C_x \hat{i} + C_y \hat{j} + C_z \hat{k}$$

- LHS

$$= (A \cdot C) B_x - (A \cdot B) C_x$$

Let us find the x -component of the RHS

$$(A \cdot C) B_x - (A \cdot B) C_x$$

Let us now compute the x -component of the LHS using

\hat{i}	\hat{j}	\hat{k}
A_x	A_y	A_z
$B_y C_z - B_z C_y$	$B_z C_x - B_x C_z$	$B_x C_y - B_y C_x$

$\begin{aligned} &\text{x-component} \\ &A_y (B_x C_y - B_y C_x) \\ &- A_z (B_z C_x - B_x C_z) \\ &= A_y B_x C_y - A_y B_y C_x \\ &- A_z B_z C_x + A_z B_x C_z \\ &= A_y C_y B_x + A_z C_z B_x + A_x B_x C_z \\ &- A_y B_y C_x - A_z B_z C_x \\ &= (A \cdot C) B_x - (A \cdot B) C_x \end{aligned}$

- Another useful identity

$$A \cdot (B \times C) = (A \times B) \cdot C$$

scalar triple product

↓
Geometric meaning?

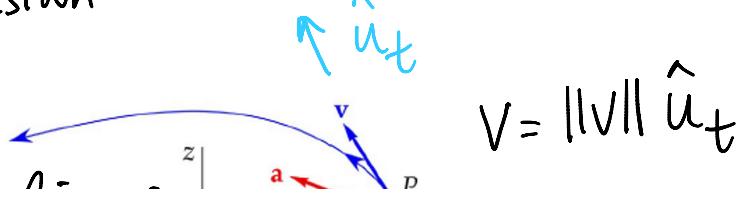
Example

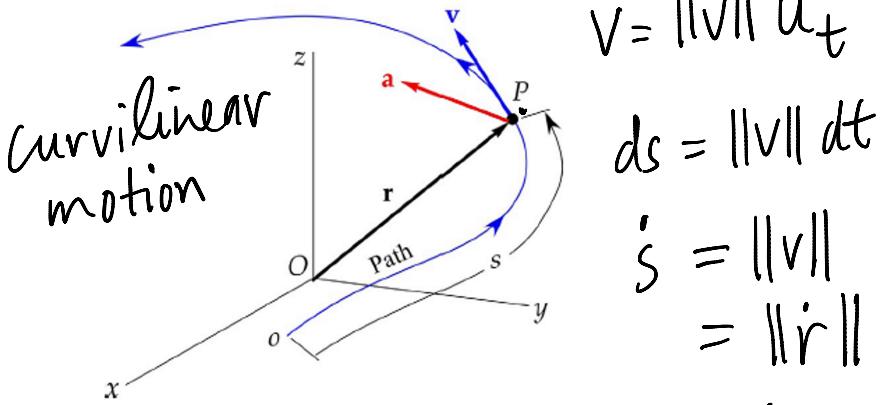
If $F = EX\{DX[AX(BX(C))]\}$, then use the bac-cab rule to reduce this expression to one involving only dot products.

Details

$$\begin{aligned}
 F &= EX\{DX[B(A \cdot C) - C(A \cdot B)]\} \\
 &= (A \cdot C)[EX(DXB)] - (A \cdot B) \\
 &\quad [EX(DXC)] \\
 &= (A \cdot C)[D(E \cdot B) - B(E \cdot D)] - (A \cdot B) \\
 &\quad [D(E \cdot C) - C(E \cdot D)] \\
 &= D[(A \cdot C)(E \cdot B) - (A \cdot B)(E \cdot C)] \\
 &\quad - (A \cdot C)(E \cdot D)B + (A \cdot B)(E \cdot D)C
 \end{aligned}$$

- To track the motion of a particle P, we need a clock and a non-rotating Cartesian coordinate system.





$$V = \|V\| \hat{u}_t$$

$$ds = \|V\| dt$$

$$\begin{aligned}\dot{s} &= \|V\| \\ &= \|r\|\end{aligned}$$

$$r(t) = x(t)\hat{i} + y(t)\hat{j} + z(t)\hat{k}$$

$$V(t) = \dot{r}(t)$$

$$\begin{aligned}&= \dot{x}(t)\hat{i} + \dot{y}(t)\hat{j} + \dot{z}(t)\hat{k} \\ &= V_x(t)\hat{i} + V_y(t)\hat{j} + V_z(t)\hat{k}\end{aligned}$$

$$a(t) = \ddot{r}(t) \quad a_x(t) = \frac{d}{dt} V_x(t), \dots$$

$$\begin{aligned}&= a_x(t)\hat{i} + a_y(t)\hat{j} + a_z(t)\hat{k}\end{aligned}$$

- Note Carefully, that $\|\dot{r}\| \neq \overline{\|r\|}$

Example: $r(t) = \hat{i} + t\hat{j} + t^2\hat{k}$ (m)

$$\dot{r}(t) = \hat{j} + 2t\hat{k}$$

$$\|\dot{r}(1)\| = \sqrt{1^2 + 2^2} = \sqrt{5} \text{ (m/sec)}$$

$$\overline{\|r(t)\|} = \frac{d}{dt} \sqrt{1^2 + t^2 + t^4}$$

$$\| \mathbf{v} \| = \frac{\| \mathbf{v} \|}{dt} \cdot (2t + 4t^3)$$

$$= \frac{1}{2\sqrt{1+t^2+t^4}} \cdot (2t + 4t^3)$$

At time $t=1$ sec, the above expression
is equal to $\sqrt{3}$ (m/sec).