

## Lecture 9: Stability of Learning Algorithms

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Scribe: Groups 1 &amp; 2

## 9.1 Characterization of Stability of an Algorithm

Let  $A$  be a Learning Algorithm and  $S$  be the Data set which is fed into the Learning algorithm. The outcome/output of the learning algorithm is  $A(S)$ . (We can think of  $A(S)$  as a vector to define a norm)

**Definition 9.1.** (Stability) A learning algorithm  $A$  is said to be stable iff

$$\|A(S) - A(S')\| \leq \mathcal{O}\left(\frac{1}{|S|}\right)$$

For every  $S$  and  $S'$  such that  $|S \setminus S'| = |S' \setminus S| = 1$ .

The condition on  $S$  and  $S'$  means that there is only a one element mismatch between the sets.

Consider instead, what happens if we just delete one element  $e$  from the set and take the norm of the difference: (Stability towards single element deletions)

$$\|A(S) - A(S \setminus e)\|$$

We want to find the relation of the above with the previously defined notion of stability. This is dealt with in the following theorem.

**Proposition 9.2.** Let  $A$  be a Learning Algorithm,  $S = \{(x_i, y_i)\}$  be a data set and  $e$  be a single data point,  $e = (x_r, y_r)$  for some  $r$  such that  $e \in S$ . The following is a sufficient condition for the Algorithm to be stable:

$$\|A(S) - A(S \setminus e)\| = \mathcal{O}\left(\frac{1}{|S|}\right) \quad \forall e, S$$

*Proof.* Consider set  $S$  and  $S'$  such that  $|S \setminus S'| = |S' \setminus S| = 1$ . This means that there exists  $e$  and  $e'$  such that  $S \setminus e = S' \setminus e'$ . We shall also be using Triangle inequality. Let us start with the expression in the definition of stability:

$$\|A(S) - A(S')\| = \|A(S) - A(S \setminus e) + A(S' \setminus e') - A(S')\|$$

(We can do this since  $S \setminus e = S' \setminus e'$ ). Now applying Triangle inequality to the right hand side:

$$\|A(S) - A(S')\| \leq \|A(S) - A(S \setminus e)\| + \|A(S' \setminus e') - A(S')\|$$

But we already have :

$$\|A(S) - A(S \setminus e)\| = \mathcal{O}\left(\frac{1}{|S|}\right)$$

$$\|A(S' \setminus e') - A(S')\| = \mathcal{O}\left(\frac{1}{|S'|}\right)$$

Using this, we have:

$$\|A(S) - A(S')\| \leq \mathcal{O}\left(\frac{1}{|S|}\right) + \mathcal{O}\left(\frac{1}{|S'|}\right)$$

Since  $|S| = |S'|$  :

$$\|A(S) - A(S')\| \leq \mathcal{O}\left(\frac{1}{|S|}\right)$$

□

**Note:** If we add noise to  $x_i$  then accuracy will decrease, but our model will become more stable.

## 9.2 Applying stability to classification

Let us say we have a dataset  $D = \{(x_i, y_i)\}$ . Let us say we have some convex loss function  $l(w^T x, y)$  which is Lipschitz continuous. Let us define the following function over  $S \subset D$  which has regularization

$$F_w(S) = \sum_S (l(w^T x_i, y_i) + \lambda \|w\|^2)$$

Using this function we can define the following vector which minimizes the sum of the loss as

$$w^*(S) = \operatorname{argmin}_w F_w(S)$$

**Proposition 9.3.** *For the defined  $F_w(S)$  with a convex and Lipschitz  $l(w^T x, y)$ ,  $w^*$  is stable.*

*Proof.* Let us define the notation  $l(w^*(S), e) = l(w^*(S)^T x, y)$ . Now we take a close look at the value  $F_{w^*(S')}(S) - F_{w^*(S)}(S)$ . We must have the following hold

$$F_{w^*(S')}(S) - F_{w^*(S)}(S) = F_{w^*(S')}(S') - F_{w^*(S)}(S') + l(w^*(S'), e) - l(w^*(S), e) + l(w^*(S), e') - l(w^*(S'), e')$$

Since  $w^*(S') = \operatorname{argmin}_w F_w(S')$  we have  $F_{w^*(S')}(S') - F_{w^*(S)}(S') \leq 0$  hence

$$F_{w^*(S')}(S) - F_{w^*(S)}(S) \leq l(w^*(S'), e) - l(w^*(S), e) + l(w^*(S), e') - l(w^*(S'), e') \leq 2L \|w^*(S) - w^*(S')\|$$

The last part of the inequality comes by combining the triangle inequality with the Lipschitz condition of  $l(w^*(S'), e) - l(w^*(S), e) \leq L \|w^*(S) - w^*(S')\|$ .

We can also expand  $F_{w^*(S')}(S) - F_{w^*(S)}(S)$  as a Taylor expansion about the point  $w^*(S)$ .

$$F_{w^*(S')}(S) - F_{w^*(S)}(S) = \frac{\partial F_w(S)}{\partial w} \Big|_{w=w^*(S)} (w - w^*(S)) + \frac{1}{2} (w - w^*(S))^T H (w - w^*(S)) + \dots$$

Here  $H(F_w(S))$  is the Hessian for the function  $F_w(S)$  with respect to  $w$ . We know that  $w^*(S)$  minimizes  $F_w(S)$  hence the first term vanishes and we are left with the inequality

$$F_{w^*(S')}(S) - F_{w^*(S)}(S) \geq \frac{1}{2}(w^*(S') - w^*(S))^T H(F_{w^*(S')}(S))(w^*(S') - w^*(S))$$

We know that  $l(w, e)$  is a convex function hence the Hessian  $H(l(w, e))$  is positive semi-definite. Hence we can surely conclude that the Hessian of the sum of all  $l(w, e)$  terms is also positive semi-definite.

Now we can look at the regularization term, this will have to add a  $2\lambda|S|I$  to the Hessian by definition and so we can conclude that  $H(F_w(S)) \geq 2\lambda|S|I$  since the loss terms Hessian will anyways be positive semi-definite. Hence we have

$$F_{w^*(S')}(S) - F_{w^*(S)}(S) \geq \frac{2\lambda|S|}{2}(w^*(S') - w^*(S))^T (w^*(S') - w^*(S)) \geq \lambda|S|\|w^*(S') - w^*(S)\|^2$$

By combining the two inequalities we obtain by using first the Lipschitz condition and then that of convexity we obtain

$$\lambda|S|\|w^*(S') - w^*(S)\|^2 \leq F_{w^*(S')}(S) - F_{w^*(S)}(S) \leq 2L\|w^*(S) - w^*(S')\|$$

This subsequently reduces to

$$\|w^*(S') - w^*(S)\| \leq \frac{2L}{\lambda|S|} = \mathcal{O}\left(\frac{1}{|S|}\right)$$

Hence we have proven that with a convex and Lipschitz  $l(w^T x, y)$ ,  $w^*$  is stable. □

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