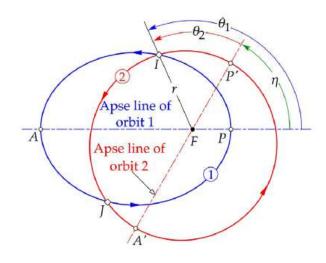
Apre Line Rotation



$$-\eta = \theta_2 - \theta_1$$

- Case 1: M, IIIII and IIell are given for both the orbits.

$$-V_{I})_{I} = \frac{\|h_{I}\|^{2}}{M} \frac{1}{1 + \|e_{I}\| \cos \theta_{I}}, \quad V_{I})_{2} = \frac{\|h_{2}\|^{2}}{M} \frac{1}{1 + \|e_{I}\| \cos \theta_{2}}$$

$$- (\gamma_{I})_{I} = (\gamma_{I})_{Z}$$

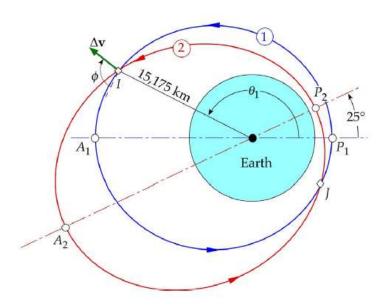
- $\|e_1\|\|h_2\|^2 \cos\theta_1 - \|e_2\|\|h_1\|^2 \cos\theta_2 = \|h_1\|^2 - \|h_2\|^2$

$$- \underbrace{\left(\frac{||e_{1}|| ||h_{1}||^{2} - ||e_{2}|| ||h_{1}||^{2} (os \eta)}_{\Delta} \cos \theta_{1} + \underbrace{\left(-\frac{||e_{2}|| ||h_{1}||^{2} Sin \eta}_{\Delta} \right) Sin \theta_{1}}_{\Delta} = \underbrace{\frac{||h_{1}||^{2} - ||h_{2}||^{2}}_{\Delta}}_{\Delta}$$

$$\left(\frac{\omega}{a}\right)$$
, $\frac{\omega}{a}$

Example

An earth satellite is in an 8000 km by 16,000 km radius orbit (orbit 1 of Fig. 6.18). Calculate the delta-v and the true anomaly θ_1 required to obtain a 7000 km by 21,000 km radius orbit (orbit 2) whose apselline is rotated 25° counterclockwise. Indicate the orientation ϕ of Δv to the local horizon.



Details

$$\|e_{1}\| = \frac{V_{A_{1}} - V_{P_{1}}}{V_{A_{1}} + V_{P_{1}}}$$
, $\|e_{2}\| = \frac{V_{A_{2}} - V_{P_{2}}}{V_{A_{2}} + V_{P_{2}}}$

$$r_{p_1} = \frac{||h_1||^2}{M} \frac{1}{1 + ||e_1||}, \quad r_{p_2} = \frac{||h_2||^2}{M} \frac{1}{1 + ||e_2||}$$

$$\phi = \tan^{-1}\left(\frac{b}{a}\right)$$
, $\Theta_1 = \phi \pm \cos^{-1}\left(\frac{c}{a}\cos\phi\right)$

$$||v|| = \frac{||h_i||^2}{M} \frac{1}{1 + ||e_i|| \cos \theta_i}$$

$$V_{\perp_{\mathcal{I}}})_{l} = \frac{||h_{l}||}{||v||}, \quad V_{\uparrow_{\mathcal{I}}})_{l} = \frac{\mathcal{M}}{||h_{l}||} ||e_{l}|| \sin \theta_{l}$$

$$V_{I}$$
) = $\sqrt{V_{L_{I}}^{2} + V_{r_{I}}^{2}}$, $V_{I} = tan^{-1} \left(\frac{V_{r_{I}}}{V_{L_{I}}} \right)$

$$V_{I})_{2} = \frac{\|h_{2}\|}{\|v\|}, \quad V_{r_{I}})_{2} = \frac{u}{\|h_{2}\|} \|e_{2}\| \sin(\theta_{1} - 25^{\circ})$$

$$V_{I})_{2} = \sqrt{V_{II})_{2}^{2} + V_{VI})_{2}^{2}}$$
, $V_{L} = \tan^{-1}\left(\frac{V_{V_{I}})_{2}}{V_{L_{I}})_{2}}\right)$

- Case 2: Impulsive manoeuvre takes place at a given true anomaly O, on orbit 1.

-
$$||N_1|| = ||N_1|| \left[\Lambda^{T_1} \right] + \nabla \Lambda^T \right] = ||N_1|| + ||M_1 \nabla \Lambda^T$$

$$- V_{r_{I}})_{I} = V_{r_{I}})_{I} + \Delta V_{r}$$

$$- \underline{\mathcal{M}}_{\|\mathbf{e}_{\mathbf{z}}\| \leq \mathbf{m} \theta_{\mathbf{z}} = \mathbf{v}_{\mathbf{v}_{\mathbf{i}}} \Big|_{\mathbf{i}} + \Delta \mathbf{v}_{\mathbf{r}}$$

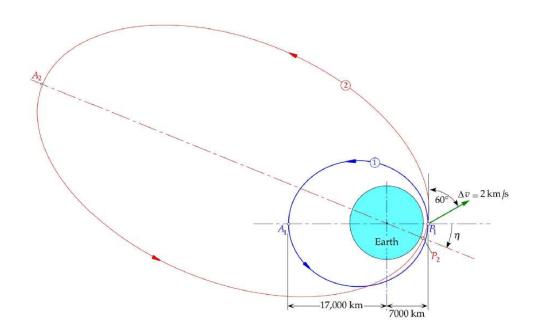
$$-\sin\theta_2 = \frac{1}{\|e_2\|} \frac{(\|h_1\| + \|r\|\Delta V_{\perp})(u\|e_1\|\sin\theta_1 + \|h_1\|\Delta V_r)}{u\|h_1\|}$$

$$-\cos\theta_{2} = \frac{1}{\|e_{2}\|} \frac{\left(\|h_{1}\| + \|r\|\Delta V_{\perp}\right)^{2} \|e_{1}\|(\cos\theta_{1} + (2\|h_{1}\| + \|r\|\Delta V_{\perp})\|r\|\Delta V_{\perp}}{\|h_{1}\|^{2}}$$

-
$$\tan \theta_2 = \frac{\left[V_{\perp z}\right]_1 + \Delta V_{\perp} \left[V_{r_z}\right]_1 + \Delta V_{r_z}}{\left[V_{\perp z}\right]_1 + \Delta V_{\perp}\right]^2 \|e_1\| \cos \theta_1 + \mu \left[2V_{\perp z}\right]_1 + \Delta V_{\perp} \left[V_{r_z}\right]_1}$$

Example

An earth satellite in orbit 1 of Fig. 6.19 undergoes the indicated delta-v maneuver at its perigee. Determine the rotation η of its apse line as well as the new perigee and apogee.



Details

$$\|e_{l}\| = \frac{V_{A_{l}} - V_{P_{l}}}{V_{A_{l}} + V_{P_{l}}}$$

$$V_{P_l} = \frac{\|h_l\|^2}{M} \frac{1}{1 + \|e_l\|}$$

$$V_{\perp \rho_1})_1 = \frac{\|h_1\|}{r_{\rho_1}}, \quad V_{r\rho_1})_1 = 0$$

$$\Delta V_{\perp} = \Delta V \omega S 60^{\circ}$$
, $\Delta V_{r} = \Delta V S in 60^{\circ}$

$$\tan \theta_z = \dots$$

$$||e_2|| = ...$$

$$r_{P_2} = \frac{||h_2||^2}{|u|} \frac{1}{||+||e_2||}, \quad r_{A_2} = \frac{||h_2||^2}{|u|} \frac{1}{||-||e_2||}$$