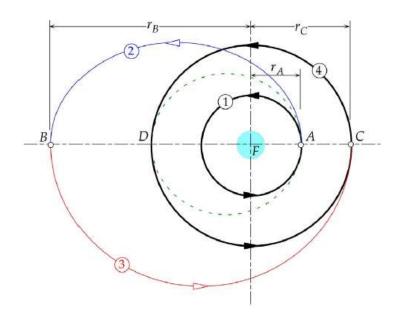
Bielliptic Hohmann Transfer



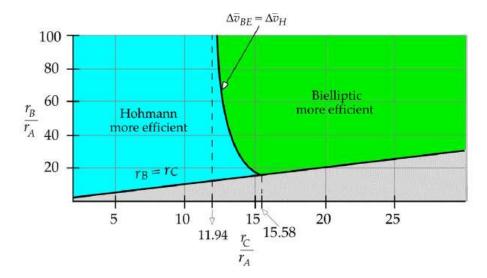
$$-\Delta V_{H} = \frac{1}{\sqrt{\alpha}} - \frac{\sqrt{2(1-\alpha)}}{\sqrt{\alpha(1+\alpha)}} - 1$$

$$\Delta \overline{V}_{BE} = \sqrt{\frac{2(K+\beta)}{K\beta}} - \frac{1+\sqrt{K}}{\sqrt{A}} - \sqrt{\frac{2}{\beta(H\beta)}} (1-\beta)$$

$$-\Delta \overline{V}_{H} = \Delta V_{total} , \Delta \overline{V}_{BE} = \Delta V_{total}$$

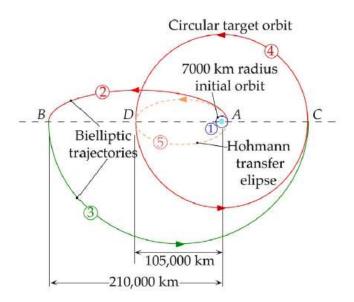
$$V_{0}$$
Hohmann V_{0} bielliptical

$$V_0 = \sqrt{\frac{M}{V_A}}$$
, $x = \frac{V_C}{V_A}$, $\beta = \frac{V_B}{V_A}$



Example

Find the total delta-v requirement for bielliptic Hohmann transfer from a geocentric circular orbit of 7000 km radius to one of 105,000 km radius. Let the apogee of the first ellipse be 210,000 km. Compare the delta-v schedule and total flight time with that for an ordinary single Hohmann transfer ellipse (see Fig. 6.9).



Details

$$V_A = 7000 \, \text{km}$$
, $V_B = 210000 \, \text{km}$, $V_C = V_D = 105000 \, \text{km}$

Orbit 1:
$$V_A)_1 = \sqrt{\frac{u}{v_A}}$$

Orbit 2:
$$V_A)_2 = \frac{\|h_2\|}{V_A}$$
, $V_B)_2 = \frac{\|h_2\|}{V_B}$

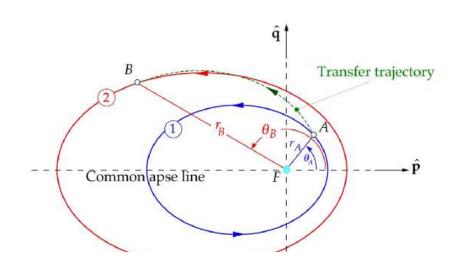
Orbit 3:
$$V_{B})_{3} = \frac{\|h_{3}\|}{V_{B}}, V_{C})_{3} = \frac{\|h_{3}\|}{V_{C}}$$

Orbit 4:
$$V_c)_{4} = V_D)_{4} = \sqrt{\frac{u}{v_D}}$$

t bielliptical =
$$\frac{1}{2} \left(\frac{2\pi}{\sqrt{M}} a_2^{3h} + \frac{2\pi}{\sqrt{M}} a_3^{3/2} \right)$$

$$V_A)_5 = \frac{\|h_5\|}{V_A}$$
, $V_D)_5 = \frac{\|h_5\|}{V_D}$

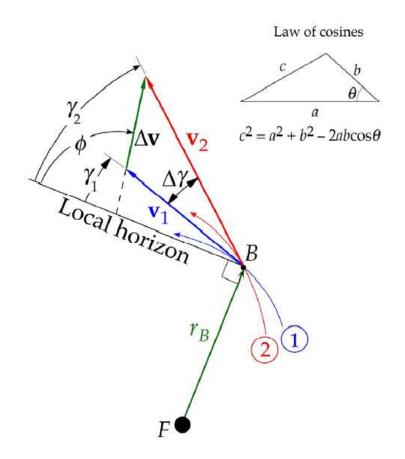
Non-Hohmann Transfers with a Common Apse Line



$$- r_A = \frac{\|h_2\|^2}{M} \frac{1}{1 + \|e\| \cos \theta_A}, \quad r_B = \frac{\|h_2\|^2}{M} \frac{1}{1 + \|e\| \cos \theta_B}$$

$$- ||e|| = \frac{V_A - V_B}{V_A \omega_A - V_B \omega_A - V_B \omega_B}$$

$$||h|| = \sqrt{Mr_A r_B} \sqrt{\frac{\cos \theta_A - \cos \theta_B}{r_A \cos \theta_A - r_B \cos \theta_B}}$$



$$- ||\Delta V|| = \sqrt{(V_2 - V_1) \cdot (V_2 - V_1)} = \sqrt{||V_1||^2 + ||V_2||^2 - 2||V_1|| ||V_2|| \cos \Delta V}$$

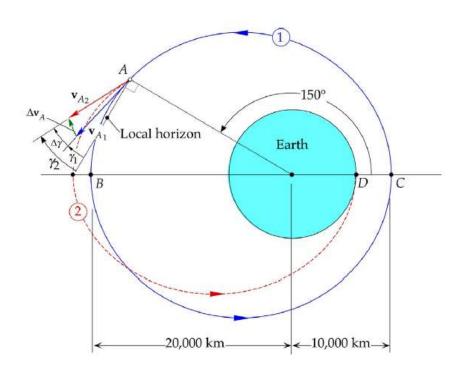
-
$$tan \emptyset = \frac{\Delta V_r}{\Delta V_s}$$

$$- \xi = \underbrace{V \cdot V}_{2} - \underbrace{\mu}_{V}$$

$$-\Delta \xi = V \cdot \Delta V + \frac{1}{2} \Delta V \cdot \Delta V = \|V\| \|\Delta V\| \cos \Delta Y + \frac{1}{2} \|\Delta V\|^{2}$$

Example

A geocentric satellite in orbit 1 of Fig. 6.15 executes a delta-v maneuver at A, which places it on orbit 2, for reentry at D. Calculate Δv at A and its direction relative to the local horizon.



Details

Orbit 1:
$$||e_1|| = \frac{r_B - r_C}{r_B + r_C}$$
, $r_A = \frac{||h_1||^2}{M} \frac{1}{1 + ||e_1|| \cos \theta_A}$

$$V_{\perp A})_{l} = \frac{||h_{l}||}{|V_{A}|}, |V_{V_{A}}|_{l} = \frac{M}{||h_{l}||} ||e_{l}|| \sin \theta_{A}$$

$$(V_A)_1 = \sqrt{(V_{\perp A})_1^2 + (V_{\perp A})_1^2}$$
, $(V_{\perp A})_1 = tam^{-1} \left(\frac{(V_{\perp A})_1}{(V_{\perp A})_1} \right)$

Orbit 2:
$$V_{\perp_A})_2 = \frac{||h_2||}{|V_A|}$$
, $V_{V_A})_2 = \frac{||M_2||}{||h_2||} ||e_2|| \sin \theta_A$

$$(V_A)_2 = \sqrt{(V_{\perp A})_2^2 + (V_{\uparrow A})_2^2}$$
, $Y_2 = \tan^{-1} \left(\frac{(V_{\uparrow A})_2}{(V_{\perp A})_2} \right)$

