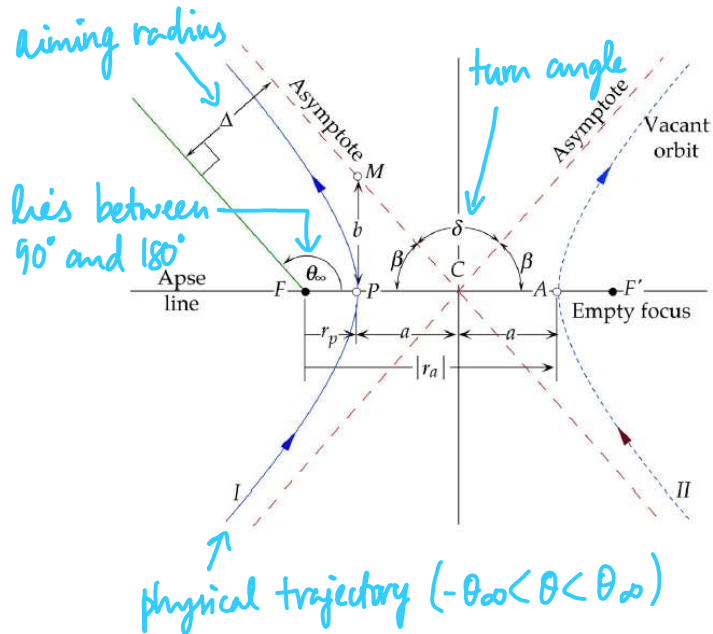


## Hyperbolic Trajectories ( $\|e\| > 1$ )



$$- \quad \|r\| = \frac{\|h\|^2}{\mu} \frac{1}{1 + \|e\| \cos \theta}$$

$$- \quad 1 + \|e\| \cos \theta = 0 \Rightarrow \theta_\infty = \cos^{-1} \left( \frac{-1}{\|e\|} \right)$$

$$- \quad \sin \theta_\infty = \sqrt{\frac{\|e\|^2 - 1}{\|e\|^2}}$$

$$- \quad \beta = 180^\circ - \theta_\infty \Rightarrow \cos \beta = -\cos \theta_\infty$$

$$- \quad \beta = \cos^{-1} \left( \frac{1}{\|e\|} \right)$$

$$\begin{aligned}
 - \quad \delta = 180^\circ - 2\beta &\Rightarrow \sin \delta/2 = \sin (90^\circ - \beta) \\
 &= \cos \beta \\
 &= \frac{1}{\|e\|}
 \end{aligned}$$

$$\|e\|$$

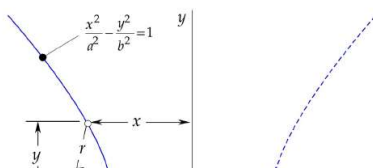
$$\begin{aligned}
 - \quad 2a &= |r_a| - r_p \\
 &= -r_a - r_p \\
 &= -\frac{\|h\|^2}{u} \left( \frac{1}{1-\|e\|} + \frac{1}{1+\|e\|} \right) \\
 &= \frac{\|h\|^2}{u} \frac{1}{\|e\|^2 - 1}
 \end{aligned}$$

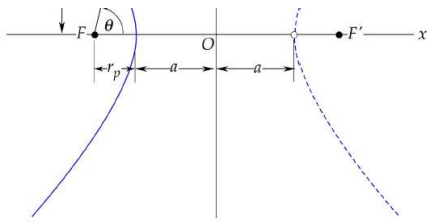
$$- \quad \|r\| = a \frac{\|e\|^2 - 1}{1 + \|e\| \cos \theta}$$

$$- \quad r_p = a(\|e\| - 1), \quad r_a = -a(\|e\| + 1)$$

$$- \quad b = a \tan \beta = -a \tan \theta_\infty = a \sqrt{\|e\|^2 - 1}$$

$$\begin{aligned}
 - \quad \Delta &= (r_p + a) \sin \beta \\
 &= a \|e\| \sin \beta \\
 &= a \|e\| \sin \theta_\infty \\
 &= a \|e\| \sqrt{1 - \frac{1}{\|e\|^2}} \\
 &= a \sqrt{\|e\|^2 - 1}
 \end{aligned}$$





$$- \quad x = -a - r_p + \|v\| \cos \theta, \quad y = \|v\| \sin \theta$$

$$\begin{aligned} & \left(\frac{x}{a}\right)^2 - \left(\frac{y}{b}\right)^2 \\ &= \left(\frac{\|v\| + \cos \theta}{1 + \|v\| \cos \theta}\right)^2 - \left(\frac{\sqrt{\|v\|^2 - 1} \sin \theta}{1 + \|v\| \cos \theta}\right)^2 \\ &= 1 \end{aligned}$$

$$- \quad \varepsilon = \frac{\mu}{2a} \quad (\text{why?})$$

↓

does not depend on the  
eccentricity

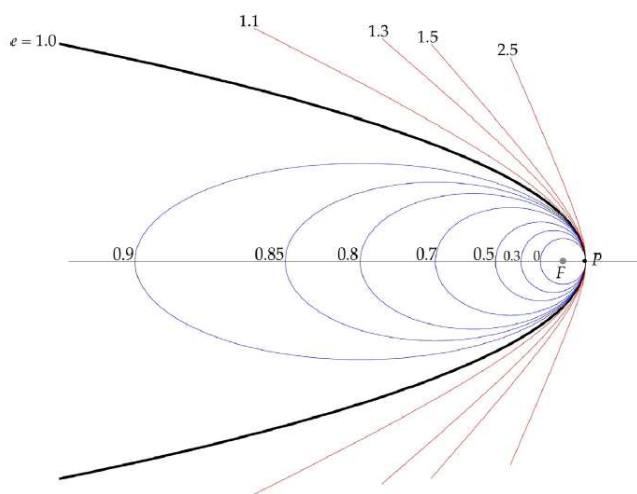
$$- \quad \frac{\|v\|^2}{2} - \frac{\mu}{\|r\|} = \frac{\mu}{2a}$$

$$- \quad V_\infty = \sqrt{\frac{\mu}{a}} \quad (\text{hyperbolic excess speed})$$

$$- \quad \frac{\|v\|^2}{2} - \frac{\mu}{\|r\|} = \frac{V_\infty^2}{2}$$

$$- \quad \|v\|^2 = V_{\text{esc}}^2 + \underbrace{V_\infty^2}_{C_1}$$

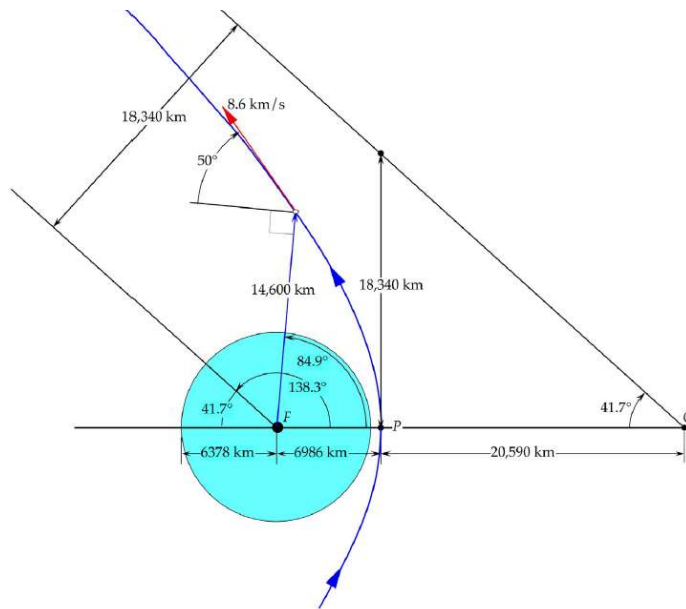
- $V_\infty$  represents the excess K.E. over that which is required to simply escape from the centre of attraction.
- $C_3$  is a measure of energy required for an inter-planetary mission. It is also a measure of the maximum energy a launch vehicle can impart to a spacecraft of a given mass.
- $$V_\infty = \frac{\mu}{\|h\|} \|e\| \sin \theta_\infty = \frac{\mu}{\|h\|} \sqrt{\|e\|^2 - 1}$$



## Example

At a given point of a spacecraft's geocentric trajectory, the radius is 14,600 km, the speed is 8.6 km/s, and the flight path angle is  $50^\circ$ . Show that the path is a hyperbola and calculate the following:

- angular momentum
- eccentricity
- true anomaly
- radius of the perigee
- semimajor axis
- $C_3$
- turn angle
- aiming radius



## Details

$$V_{esc} = \sqrt{\frac{2m}{||r||}} < ||v||$$

$$(a) \quad \tan \gamma = \frac{V_r}{V_{\perp}}$$

$$||v|| = \sqrt{V_r^2 + V_{\perp}^2}$$

$$||h|| = ||r|| V_{\perp}$$

$$(b) \quad V_r = \frac{\mu}{||h||} ||e|| \sin \theta$$

$$||r|| = \frac{||h||^2}{\mu} \frac{1}{1 + ||e|| \cos \theta}$$

$$(c) \quad ||r|| = \frac{||h||^2}{\mu} \frac{1}{1 + ||e|| \cos \theta}$$

$$(d) \quad r_p = \frac{\|h\|^2}{\mu} \frac{1}{1+\|e\|}$$

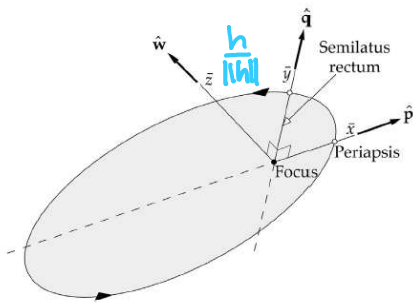
$$(e) \quad a = \frac{\|h\|^2}{\mu} \frac{1}{\|e\|^2 - 1}$$

$$(f) \quad v_\infty^2 = \|v\|^2 - v_{esc}^2$$

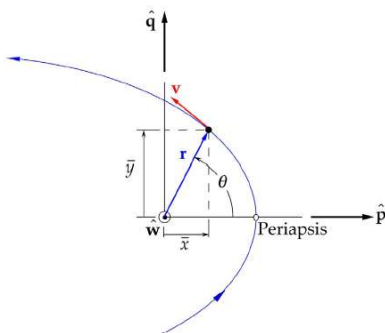
$$(g) \quad \delta = 2 \sin^{-1} \left( \frac{1}{\|e\|} \right)$$

$$(h) \quad \Delta = a \sqrt{\|e\|^2 - 1}$$

Perifocal Frame



- It is the "natural frame" for an orbit.



$$- \quad r = \bar{x} \hat{p} + \bar{y} \hat{q}, \quad \bar{x} = \|r\| \cos \theta, \quad \bar{y} = \|r\| \sin \theta$$

$$- \quad r = \frac{\|h\|^2}{\mu} \frac{1}{1 + \|e\| \cos \theta} (\cos \theta \hat{p} + \sin \theta \hat{q})$$

$$- \quad v = \dot{r} = \dot{\bar{x}} \hat{p} + \dot{\bar{y}} \hat{q}$$

$$- \quad \dot{\bar{x}} = \frac{\dot{\|r\|}}{\|r\|} \cos \theta - \|r\| \dot{\theta} \sin \theta$$

$$- \quad \dot{\bar{y}} = \frac{\dot{\|r\|}}{\|r\|} \sin \theta + \|r\| \dot{\theta} \cos \theta$$

$$- \quad \frac{\dot{\|r\|}}{\|r\|} = \frac{\mu}{\|h\|} \|e\| \sin \theta$$

$$- \quad \|r\| \dot{\theta} = \frac{\mu}{\|h\|} (1 + \|e\| \cos \theta)$$

$$- \quad \dot{\bar{x}} = -\frac{\mu}{\|h\|} \sin \theta, \quad \dot{\bar{y}} = \frac{\mu}{\|h\|} (\|e\| + \cos \theta)$$

## Example

An earth orbit has an eccentricity of 0.3, an angular momentum of  $60,000 \text{ km}^2/\text{s}$ , and a true anomaly of  $120^\circ$ . What are the position vector  $r$  and velocity vector  $v$  in the perifocal frame of reference?

## Details

$$r = \frac{\|h\|^2}{\mu} \frac{1}{1 + \|e\| \cos \theta} (\cos \theta \hat{p} + \sin \theta \hat{q})$$

$$\mathbf{v} = \frac{\mu}{\|\mathbf{h}\|} [-\sin \theta \hat{\mathbf{p}} + (\|\mathbf{e}\| + \cos \theta) \hat{\mathbf{q}}]$$

## Example

An earth satellite has the following position and velocity vectors at a given instant:

$$\mathbf{r} = 7000\hat{\mathbf{p}} + 9000\hat{\mathbf{q}} \text{ (km)}$$

$$\mathbf{v} = -3.3472\hat{\mathbf{p}} + 9.1251\hat{\mathbf{q}} \text{ (km/s)}$$

Calculate the specific angular momentum  $h$ , the true anomaly  $\theta$ , and the eccentricity  $e$ .

## Details

$$\mathbf{h} = \mathbf{r} \times \mathbf{v}$$

$$\mathbf{r} \cdot \hat{\mathbf{p}} = \|\mathbf{r}\| \cos \theta$$

$$\|\mathbf{r}\| = \frac{\|\mathbf{h}\|^2}{\mu} \frac{1}{1 + \|\mathbf{e}\| \cos \theta}$$