

ANALYTICAL AND GEOMETRIC MECHANICS

TUTORIAL-1

Systems & Control Engineering

§ 1. EXERCISES

1. **Question.** (*Submersions*) Comment whether the following maps are submersions or not.

(1-a) $\mathbb{R}^2 \setminus \{(0, 0)\} \ni (x, y) \mapsto f(x, y) := x^2 + y^3 \in \mathbb{R}$

(1-b) $\mathbb{GL}(2) \ni A \mapsto f(A) := \det A \in \mathbb{R}$ where $\mathbb{GL}(2) = \{M \in \mathbb{R}^{2 \times 2} \mid \det M \neq 0\}$.

2. **Question.** (*Immersion*) Comment whether the following maps are immersions or not.

(2-a) $t \in \mathbb{R} \mapsto f(t) := (\sin(t), \cos(t)) \in \mathbb{R}^2$.

(2-b) $t \in \mathbb{R} \setminus \{0\} \mapsto f(t) := (t^2, t^4) \in \mathbb{R}^2$

(2-c) $t \in [0, 2\pi[\mapsto f(t) := (\sin(t), \cos(t)) \in \mathbb{R}^2$.

3. **Question.** (*Embedding*) Comment which of the maps given in Question 2, are embedding..

4. **Question.** (*Submanifolds*) Comment which of the following sets are embedded submanifolds, also give their dimension.

(4-a) $V \subset \mathbb{R}^n$, V is a subspace with $\dim V = m$.

(4-b) $S^n := \{x \in \mathbb{R}^{n+1} \mid \|x\|^2 = 1\}$

(4-c) $\text{SO}(n) := \{A \in \mathbb{R}^{n \times n} \mid A^\top A = AA^\top = I, \det A = 1\}$

(4-d) $T^2 = S^1 \times S^1$

5. **Question.** (*Product Manifolds*) Let $M_1 \subset \mathbb{R}^{n_1}$ be an embedded submanifold of dimension m_1 , and $M_2 \subset \mathbb{R}^{n_2}$ be an embedded submanifold of dimension m_2 . Show that $M_1 \times M_2 \subset \mathbb{R}^{n_1} \times \mathbb{R}^{n_2}$ is a submanifold with dimension $m_1 + m_2$.

6. **Question.** (*Lie Groups*) Identify which of the following sets along with the respective group operator qualify as lie group

(6-a) $G := \mathbb{R}^n \quad g(x, y) := x + y$

(6-b) $G := \mathbb{R} \quad g(x, y) := xy$.

(6-c) $G := G_1 \times G_2 \quad g((x_1, y_1), (x_2, y_2)) = (g_1(x_1, x_2), g_2(y_1, y_2))$ where G_1, G_2 are lie groups with group operators g_1 and g_2 .

7. **Question.** (*Tangent Spaces*) Compute the associated tangent space to a point x on each of the following manifolds

(7-a) $S^2 = \{x \in \mathbb{R}^3 \mid \|x\|^2 = 1\}$

(7-b) $V \subset \mathbb{R}^n$, V is a subspace with dimension $V = m$

(7-c) $U \subset \mathbb{R}^n$, U is an open set.

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1. **Question.** (*Submersions*) Comment whether the following maps are submersions or not.

(1-a) $\mathbb{R}^2 \setminus \{(0,0)\} \ni (x,y) \mapsto f(x,y) := x^2 + y^3 \in \mathbb{R}$ \leftarrow

(1-b) $\underline{\mathbb{GL}(2)} \ni A \mapsto f(A) := \underline{\det A} \in \mathbb{R}$ where $\mathbb{GL}(2) = \{M \in \mathbb{R}^{2 \times 2} \mid \det M \neq 0\}$.

$f: U \rightarrow V$ is a submersion if

for all $x \in U$ $Df(x)$ is an onto map.
(surjective)

$f: U \rightarrow V$ is an immersion if

for all $x \in U$ $Df(x)$ is an injective map

1) $\mathbb{R}^2 \rightarrow \mathbb{R} : (x,y) \mapsto x^2 + y^3$

$Df(x,y) = [2x, 3y^2]$

$\text{rank } Df(x,y) = 1$ for all $(x,y) \neq 0$

2) $\mathbb{GL}(\mathbb{R}, 2) \mapsto \mathbb{R} \quad \begin{bmatrix} a & b \\ c & d \end{bmatrix} \mapsto \det(A)$

$\det(A) = ad - bc$

$Df = [d \quad -c \quad -b \quad a]$

unless $a, b, c, d = 0$

$\text{rank}(Df) = 1 \Rightarrow$ it's a submersion

3) $f: \mathbb{R} \rightarrow \mathbb{R}^2$ and it's a submersion \times

$f(x,y) = x = [1, 0]$

$f(x,y) = (x, 0)$

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}^2 \quad f(x, y) = (x, y)$$

[Diffeomorphism \subseteq Submersions.]

2. Question. (**Immersion**) Comment whether the following maps are immersions or not.

(2-a) $t \in \mathbb{R} \mapsto f(t) := (\sin(t), \cos(t)) \in \mathbb{R}^2 \rightarrow (t, t^3)$

(2-b) $t \in \mathbb{R} \setminus \{0\} \mapsto f(t) := (t^2, t^4) \in \mathbb{R}^2 \leftarrow [t \in \mathbb{R} \mapsto f(t) = (t^2, t^4) \neq \text{not an immersion}]$

(2-c) $t \in [0, 2\pi[\mapsto f(t) := (\sin(t), \cos(t)) \in \mathbb{R}^2 \leftarrow$

3. Question. (**Embedding**) Comment which of the maps given in Question 2 are embed-

Q 2a) $[0, 2\pi[\mapsto f(t) = (\sin(t), \cos(t))$
 $f(t) := [\sin(t), \cos(t)]$

$[a, b[\subseteq \mathbb{R} \mapsto (a, b)$

$Df(t) = \begin{bmatrix} \cos t \\ -\sin t \end{bmatrix}$, $\text{rank}(Df) = 1$ for all t
 and hence it is an immersion.

$Df(t): \mathbb{R} \rightarrow \mathbb{R}^2$

$[f: U \subset \mathbb{R}^n \rightarrow V \subset \mathbb{R}^m]$

$Df(t): \mathbb{R}^n \rightarrow \mathbb{R}^m$

$\downarrow \mathbb{R}^n$
 $f(x+t) = f(x) + Df(x)t + o(t)$
 $\frac{o(t)}{\|t\|} \rightarrow 0 \quad t \rightarrow 0$
 $t \in \mathbb{R}^n$

$U \mapsto Df(x) \cdot v$ \rightarrow Surjective \Rightarrow Submersion
 \rightarrow Injective \Rightarrow Immersion

Surjective & Injective (Bijective) \Rightarrow Diffeomorphism.

(2-c) $t \in [0, 2\pi[\mapsto f(t) := (\sin(t), \cos(t)) \in \mathbb{R}^2$

3. Question. (**Embedding**) Comment which of the maps given in Question 2, are embedding..

$(0, 2\pi) \ni t \mapsto (\sin t, \cos t)$

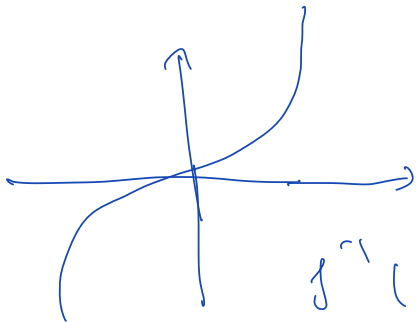
$f: U \rightarrow f(U)$ needs to be a homeomorphism.

f, f^{-1} are well defined and are continuous on $U \subseteq f(U)$.

$$f: t \mapsto (t, t^3) \quad \text{immersion} \quad \checkmark$$

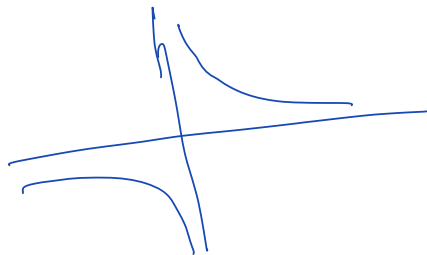
Immersion ✓

Embedding \hookrightarrow



$$f^{-1}(t, 3) = t$$

$$j: [t \mapsto \gamma_t]$$



Manifolds: a set M is called a manifold if $M \subset \mathbb{R}^n$

a) for each $a \in M$, open set $U \in \mathcal{a}$, & subbasis \mathcal{a}

$\varphi: \mathbb{C} \rightarrow \mathbb{R}^k$ such that $M \cap U = f^{-1}(U)$

where $C \in \mathbb{R}^K$



MANU such that this
is a well set of a submanifold

a) manifolds, also give their dimension.

(4-a) $V \subset \mathbb{R}^n$, V is a subspace with $\dim V = m$.

(4-b) $S^n := \{x \in \mathbb{R}^{n+1} \mid \|x\|^2 = 1\}$

(4-c) $SO(n) := \{A \in \mathbb{R}^{n \times n} \mid A^T A = A A^T = I, \det A = 1\}$

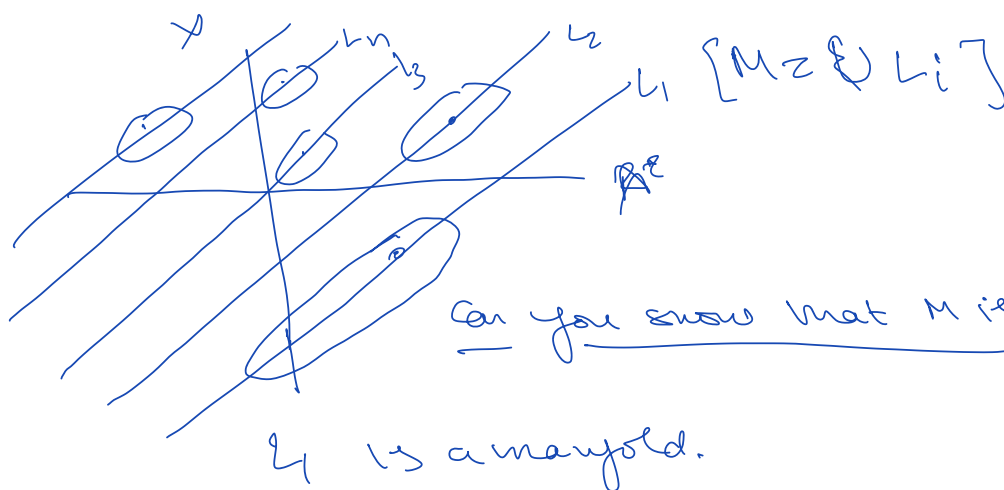
(4-d) $T^2 = S^1 \times S^1$

5. Question. (**Product Manifolds**) Let $M_1 \subset \mathbb{R}^{n_1}$ be an embe

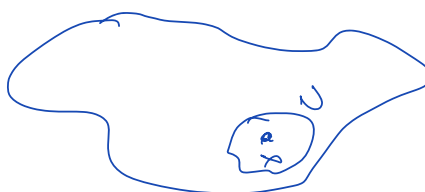
$$b) S^n = \{x \in \mathbb{R}^{n+1} \mid \|x\|^2 = 1\}. \quad \left. \begin{array}{l} U \subset \mathbb{R}^n \\ M \cap U \subset M \end{array} \right\}$$

$$\varphi: \mathbb{R}^{n+1} \rightarrow \mathbb{R} \quad \varphi(x) = \|x\|^2$$

$S^n = \varphi^{-1}(\{1\}) \Rightarrow$ this is a manifold.



b) Immersion / Embedding condition for every $x \in M, \exists U \subset \mathbb{R}^n$ and $V \subset \mathbb{R}^m$ an Immersion φ such that $\varphi(U) = M \cap U$



$$M \cap U = \varphi(U)$$

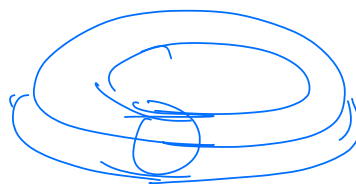
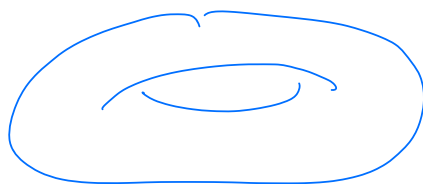
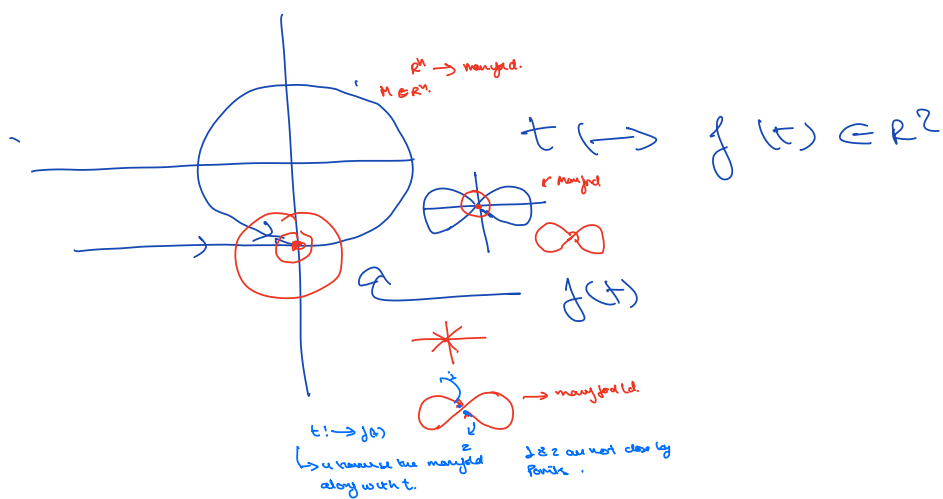
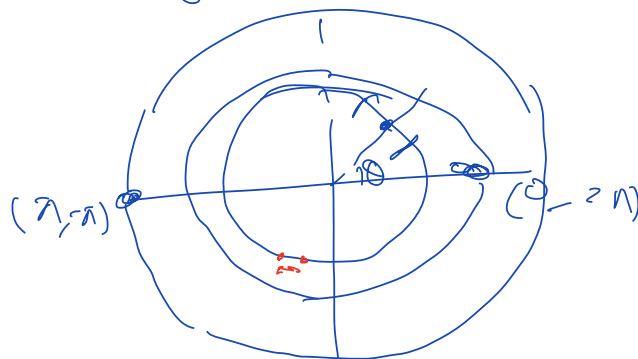
\Rightarrow free \hookrightarrow φ : must be an embedding.

$$S^1_2 = \{ (x, y) \in \mathbb{R}^2 \mid x^2 + y^2 = 1 \}$$

$$(x, y) = (\cos \theta, \sin \theta)$$

$$\theta \mapsto \varphi(\theta) = (\cos \theta, \sin \theta)$$

$$\theta \in (0, 2\pi), \quad \varphi_2: [-\pi, \pi) \rightarrow \mathbb{R}^2, \quad \theta = (\cos \theta, \sin \theta)$$



5. **Question. (Product Manifolds)** Let $M_1 \subset \mathbb{R}^{n_1}$ be an embedded submanifold of dimension m_1 , and $M_2 \subset \mathbb{R}^{n_2}$ be an embedded submanifold of dimension m_2 . Show that $M_1 \times M_2 \subset \mathbb{R}^{n_1} \times \mathbb{R}^{n_2}$ is a submanifold with dimension $m_1 + m_2$.

$$\rightarrow x \in M_1, y \in M_2, (x, y) \in M_1 \times M_2$$

Since M_1, M_2 are submanifolds $\exists U_1, U_2, \varphi_1, \varphi_2$
 $[U_1 \subset \mathbb{R}^{n_1}, U_2 \subset \mathbb{R}^{n_2}]$

$$\text{s.t. } \varphi_1(U_1) = M_1 \cap U_1, \left\{ \begin{array}{l} \varphi_2(U_2) = M_2 \cap U_2 \end{array} \right.$$

$$\varphi: U_1 \times U_2 \rightarrow U_1 \times U_2$$

$$\varphi(x, y) := [\underbrace{\varphi_1(x)}_{\text{homeomorphism on } U_1}, \underbrace{\varphi_2(y)}_{\text{homeomorphism on } U_2}]$$

components homeomorphisms $\Rightarrow \varphi$ is an homeomorphism

Claim

$$1) \quad \varphi(U_1 \times U_2) = (M_1 \times M_2) \cap (U_1 \times U_2) \Rightarrow \varphi \text{ is an embedding.}$$

$$2) \quad \varphi \text{ is an immersion.}$$

$$3) \quad \varphi \text{ is an embedding.}$$

$$\begin{aligned} \varphi(U_1 \times U_2) &\supseteq \varphi_1(U_1) \times \varphi_2(U_2) \\ &= (M_1 \cap U_1) \times (M_2 \cap U_2) \\ &= (M_1 \times M_2) \cap (U_1 \times U_2) \end{aligned}$$

$$2) \quad \varphi \text{ is an immersion}$$

$$D\varphi = \begin{bmatrix} D\varphi_1 & 0 \\ 0 & D\varphi_2 \end{bmatrix}$$

Since $D\varphi_1$ is injective
 $D\varphi_2$ is injective

$$\Rightarrow D\varphi \text{ is injective} \Rightarrow \varphi \text{ is immersion.}$$

$\Rightarrow M_1 \times M_2$ is a submanifold.

$T_2 = S_1 \times S_1 \Rightarrow$ it is a manifold.

Note: $S_1 \times S_1 \neq S^2$

Theoretical result: Every open set of \mathbb{R}^n is a regular manifold

6. Question. (**Lie Groups**) Identify which of the following sets along with the respective group operator qualify as lie group

(6-a) $G := \mathbb{R}^n$ $g(x, y) := x + y$

(6-b) $G := \mathbb{R}$ $g(x, y) := xy$ $\rightarrow \mathbb{R} \setminus \{0\}$

(6-c) $G := G_1 \times G_2$ $g((x_1, y_1), (x_2, y_2)) = (g_1(x_1, x_2), g_2(y_1, y_2))$ where G_1, G_2 are lie groups with group operators g_1 and g_2 . \leftarrow

a) $(G, g(x, y))$ set with a binary operator attached to it satisfying:

1) for all $x, y \in G$, $g(x, y) \in G$.

2) Identity element: e .

$$g(e, x) = g(x, e) = x.$$

3) Inverse element: for all $x \in G \exists y \in G$.

$$\text{st } g(x, y) = g(y, x) = e.$$

4) Associativity

$$g(x, g(y, z)) = g(g(x, y), z)$$

often we denote:

$$g(x, y) \text{ by } x \cdot y.$$

$\mathbb{R}^1 \rightarrow \text{group}, \text{ } \text{SO}(2) \text{ is a group.}$

\hookrightarrow set of invertible matrices under multiplication is a group

$$I : (x) \longrightarrow y \text{ st } g(x, y) = e$$

A group is a Lie group if, $I, g(x, y)$ are smooth.

\rightarrow Lie group is a manifold in its own right and also a sub manifold in appropriate Euclidean space.

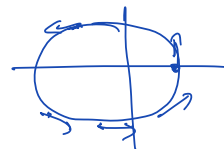
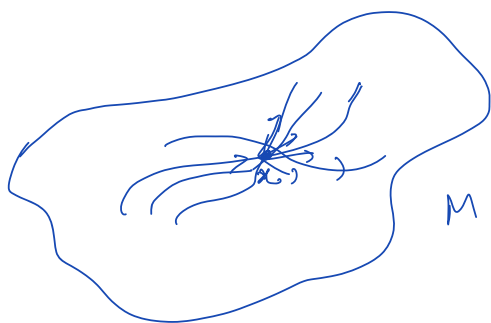
groups with group operators g_1 and g_2 .

7. **Question.** (*Tangent Spaces*) Compute the associated tangent space to a point x on each of the following manifolds

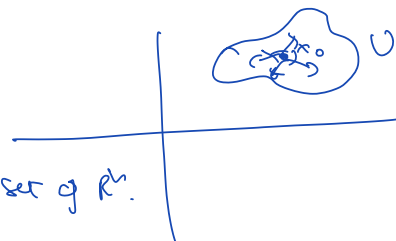
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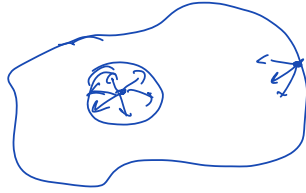


$T_x M = \{ \text{all velocity vectors that a curve lying on } M \text{ and passing through } x \text{ can possess} \}$



$$T_x U = \{ \mathbb{R}^n \}$$

U is an open set of \mathbb{R}^n .



$$S^2 = \{ \|x\|_2 = 1 \}.$$

$$\chi(t) \text{ on } S^2$$

$$\|x(t)\|_2 = 1$$

$$\frac{d}{dt} \|x(t)\|_2^2 = 0$$

$$\chi^T(t) \cdot \frac{d\chi}{dt} = 0$$

$$\chi^T(t) \cdot v = 0$$

$$T_x S^2 = \{ v \in \mathbb{R}^3 \mid \chi^T v = 0 \}$$

For an manifold defined as

$$M = \{ x \in \mathbb{R}^n \mid f(x) = c \}$$

$$T_x M = \ker (Df(x))$$

$$M = \{ \varphi(x) \mid x \in \mathbb{R}^n \} \quad \text{immersion}$$

$$T_x M = \ker (D\varphi)$$

$$\text{eg.} \quad S^1 = \{ (\cos \theta, \sin \theta) \mid \theta \in [0, 2\pi[\}$$

$$T_\theta S^1 = \{ (\cos \theta, -\sin \theta) \}.$$

Tangent space $\rightarrow (\underline{x}, T_x M) \rightarrow$ Bond vector notation

$TM := \bigcup_{x \in M} [x, T_x M] \rightarrow$ shows that this is a manifold.

Prove that TM is a manifold.

$$SO(N) = \{ A^T A = I, A^T = -A \}$$

$$\Rightarrow \frac{d}{dt} (A^T(t) A(t)) = 0$$

$$A^T(t) \frac{dA(t)}{dt} + \frac{dA^T(t)}{dt} A(t) = 0$$

$$A^T \cdot v + v^T A = 0$$

$$T_A SO(N) = \{ v \in \mathbb{R}^{N \times N} \mid A^T v + v^T A = 0 \}$$

Dimension of a manifold.

$$= \dim(M) = \dim(T_x M)$$

For a connected manifold $\dim(T_{x_1} M) = \dim(T_{x_2} M)$

x_1, x_2