# Aerospace Engineering Department, IIT Bombay AE 308 & AE 775 - Control Theory Tutorial 2

#### $\mathbf{Q}\mathbf{1}$

Linearize the nonlinear equation

$$z = x^2 + 4xy + 6y^2$$

in the region defined by  $8 \le x \le 10$ ,  $2 \le y \le 4$ .

#### $\mathbf{Q2}$

Verify whether each of the following functions is linear or nonlinear.

- 1. x(t-2)
- 2. x(t).x(t-2)
- 3.  $\frac{d}{dt}x(t)$

## $\mathbf{Q3}$

Verify whether each of the following functions is time-variant or time-invariant.

- 1. x(t-2)
- 2. t.x(t)
- $3. \ 2^{x(n)}x(n)$

## $\mathbf{Q4}$

Perform the convolution operation between the following pair of functions:

1. u(t) and u(t), where u(t) stands for the unit step function.

## Q5

Find the laplace transform of the following signals:

- 1. u(t), where u(t) stands for the unit step function.
- 2. *t*
- $3. e^{-at}$

#### Q6

Evaluate the following:

1. 
$$\mathcal{L}^{-1}\left[\frac{2s-3}{s^2-3s+2}\right]$$

2. 
$$\mathcal{L}^{-1}\left[\frac{4s^2+s+1}{s^3+s}\right]$$

3. 
$$\mathcal{L}^{-1} \left[ \frac{s^2 + 6s + 8}{s^4 + 8s^2 + 16} \right]$$