Introduction to Aerodynamics

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Course objectives

- Appreciate the role of aerodynamics in flight of aerospace vehicles
- Understand which parts of the problem are easy to solve and which are more difficult, and why
- Learn analytical techniques for solving the easy parts of the problem
- Develop qualitative understanding of the approaches for solving the more difficult parts of the problem
- Acquire the background to take up research and development challenges in aerodynamics

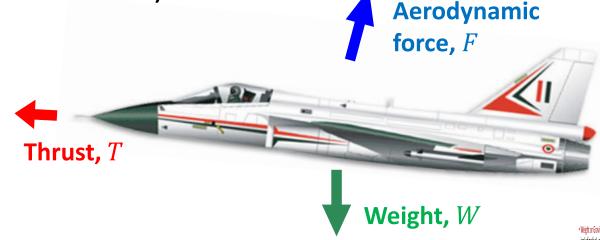


Forces on an aerospace vehicle

- Weight or Gravitational force, W: due to vehicle, all its contents, including fuel, payload and passengers
- Thrust or Propulsive force, T: force on vehicle generated by its propulsion system (think propellers, jet engines, rocket engines)

 Aerodynamic force, F: force on surface of vehicle generated by interaction with surrounding medium (air)

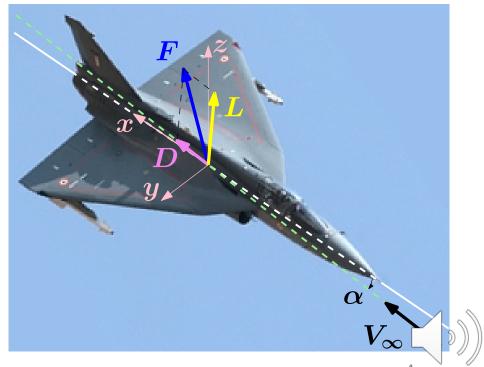
- Thrust and aerodynamic forces are often not easy to decouple
 - Propulsive force is affected by aerodynamics, and vice versa



Resolving aerodynamic force into lift and drag

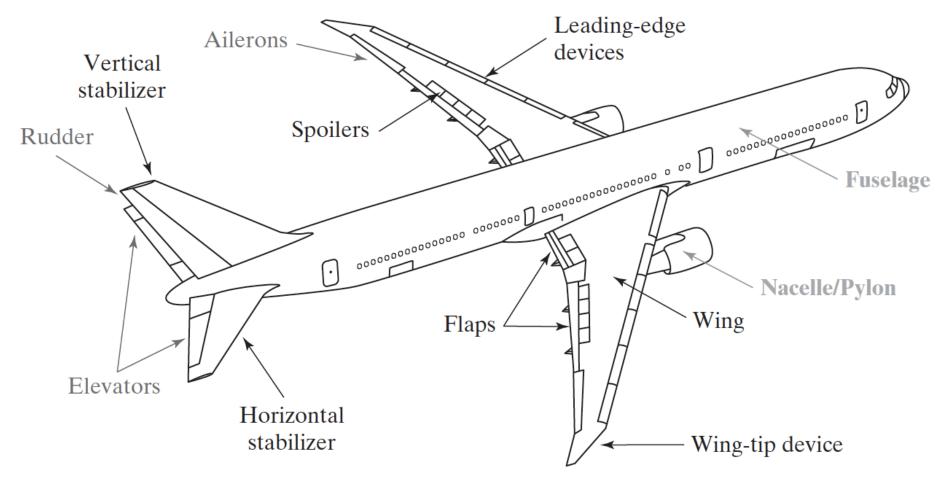
Relative wind vector, \vec{V}_{∞} : resultant of vehicle motion and breeze

- This also defines the freestream direction
- Longitudinal axis of vehicle: x-axis; positive toward rear
- y = 0 is plane of symmetry of vehicle; y is +ve toward right wing tip
- 3rd axis in right-handed system: z
- Generally, \vec{V}_{∞} is not directed along x
- Assuming no motion along y (no side slip), aerodynamic force, F, is resolved into
 - Component parallel to relative wind, drag, D
 - Component normal to relative wind, lift, L



Components of a commercial aircraft

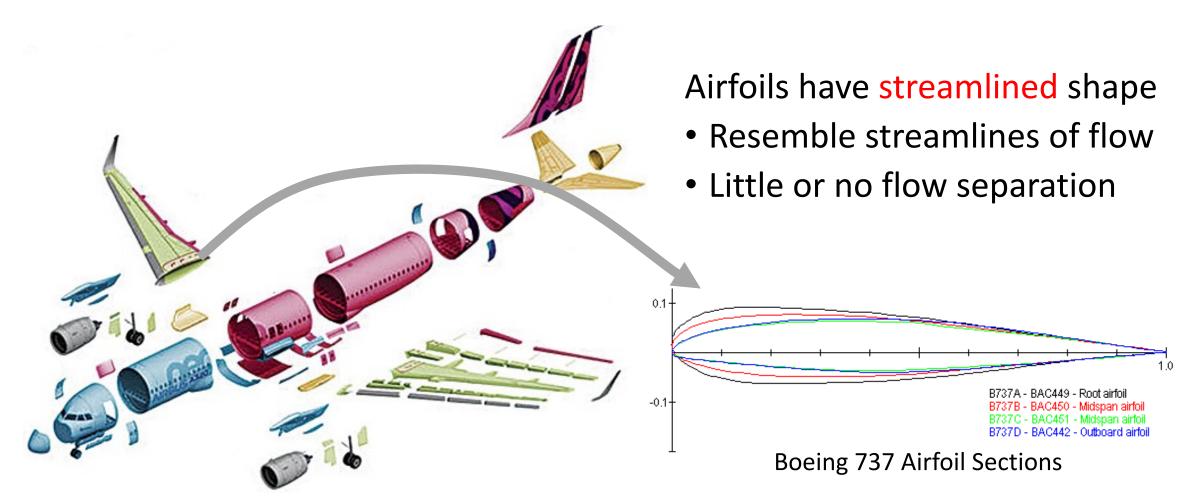
■ Lifting surfaces/devices ■ Control surfaces ■ Misc.



Bertin and Cummings, Aerodynamics for Engineers, 2013



Wing section shape is called airfoil



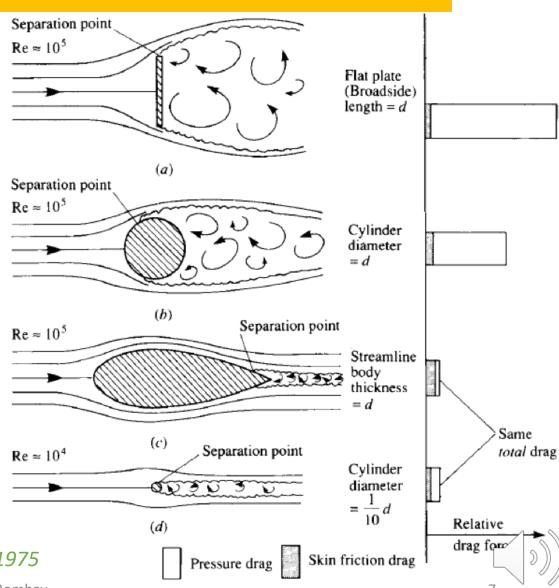




Drag forces on bluff and streamlined bodies

3 bodies of same size (but different shape), 1 much smaller; all operating at same speed

- Streamlining reduces pressure drag even in cylinder vs. normal plate, but much more so in teardrop shape
- Skin friction drag increases slightly due to increase in exposed surface
- Much smaller cylinder has same drag at same speed (1/10th Re) than airfoil
 - Think of wire bracing in early biplanes



Talay, Introduction to the aerodynamics of flight, NASA SP-367, 1975

Review question

Refresh your prior knowledge of the drag force vs. Reynolds number behaviour of flow over a circular cylinder



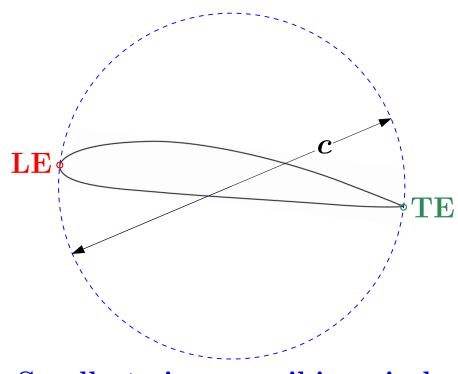
Airfoil Geometry

Introduction to Aerodynamics



Airfoil geometry: Chord

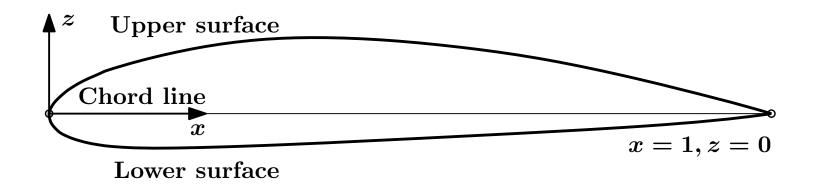
- Airfoil section: usual section obtained when horizontal wing is cut by vertical plane parallel to center-plane
- Usually has rounded leading edge (LE) and (almost) sharp trailing edge (TE)
- Chord, c: diameter of smallest circle circumscribing the airfoil
 - Most unambiguous for sharp TE
- 2 contact points w/ airfoil are LE & TE
- ullet Airfoil 'L' dimensions normalized by c



Smallest circumscribing circle

Airfoil geometry: Axes convention

- Chord line is x-axis, from LE to TE
 - N.B.: Reused notation! This may differ from longitudinal axis of vehicle!
- y-axis points into the plane of the diagram
- z-axis goes thru LE; completes right-handed system; points "up"
- Flow is assumed to go from left to right (LE to TE)
- Both x- and z-axes are normalized by the chord length c





Airfoil geometry: Camber

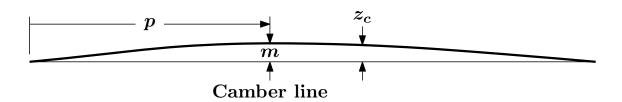
At any point along the chord, a point may be marked midway between the upper and lower surfaces

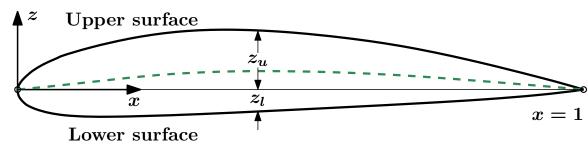
Camber line: locus of all such points

Camber function, $z_c(x)$, is expressed as a fraction of chord

It is parameterized by:

- Max camber, m (max deviation of camber line from chord line)
 - Typical values up to 5%
- Location of max camber, p





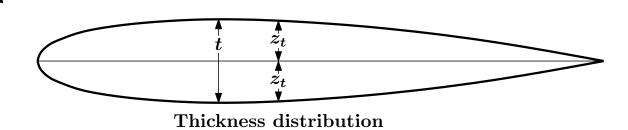


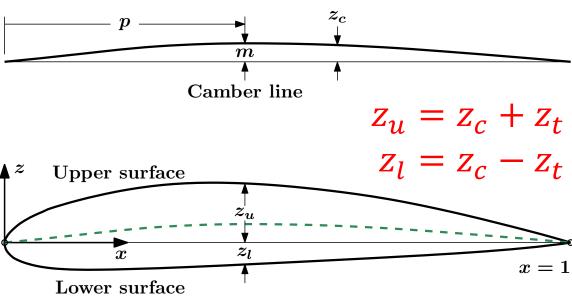
Airfoil geometry: Thickness distribution

Distances from camber line to upper & lower surfaces at any point along chord are same by definition

This is thickness distribution, $z_t(x)$, expressed as a fraction of chord It is parameterized by:

- Max thickness, t (total, not half)
 - Typically limited to 18%
- Location of max thickness
 - Typical values between 25% & 60%

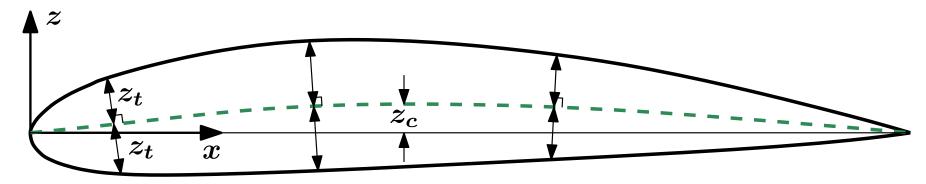






True (almost equivalent) airfoil definition

The actual (NACA) definition of the camber line is such that the thickness is distributed normal to it, instead of normal to the chord



Parametric equation:

$$x_U = x - z_t \sin \theta$$
, $z_U = z_c + z_t \cos \theta$
 $x_L = x + z_t \sin \theta$, $z_L = z_c - z_t \cos \theta$
 $\theta = \tan^{-1}(dz_c/dx)$

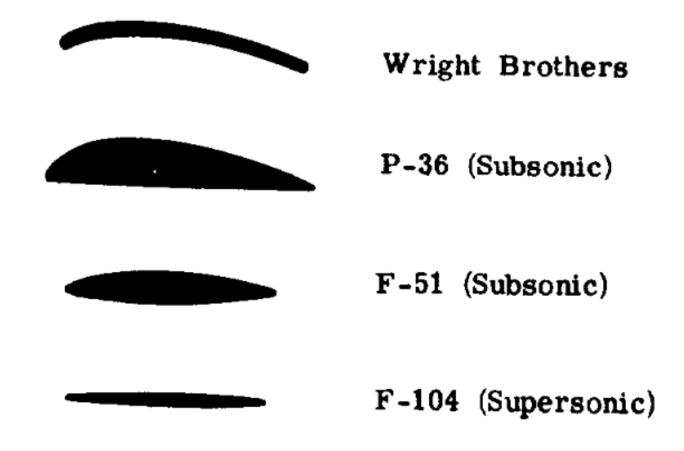
$$z_U = z_c + z_t \cos \theta$$

$$z_L = z_c - z_t \cos \theta$$

As long as the camber is small, the actual difference is negligible

Examples of airfoil shapes

Airfoil shapes are carefully tailored to the specific use

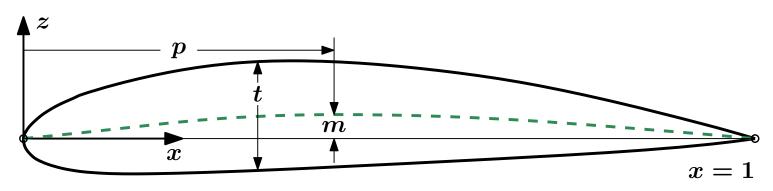




Airfoil nomenclature: NACA 4-digit series

NACA 4-digit series (eg. NACA XXXX) airfoil is easiest to generate

- 1st digit: Max camber (m) in 100ths of chord
- 2^{nd} digit: Location of max camber point (p) in 10^{th} s of chord
- Last 2 digits: Max thickness (t) in 100ths of chord
- □ NACA 2410 => 2% max. camber @ 40% chord; 10% max. thickness
- □ NACA 6508 => 6% max. camber @ 50% chord; 8% max. thickness



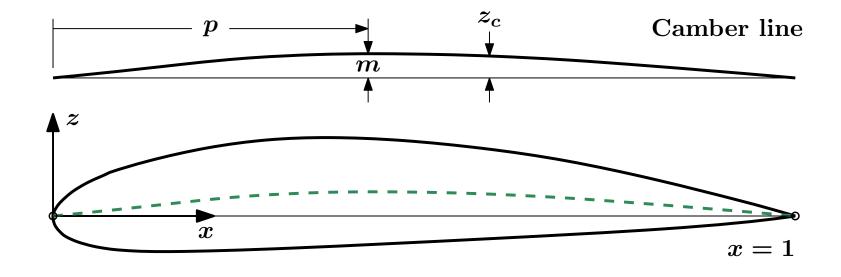


NACA 4-digit series definition: camber

Camber function w/ maximum of m at x=p (all normalized by c):

$$z_{c} = \frac{m}{p^{2}} (2px - x^{2}), \qquad x \in [0, p]$$

$$z_{c} = \frac{m}{(1-p)^{2}} (1 - 2p + 2px - x^{2}), \qquad x \in [p, 1]$$





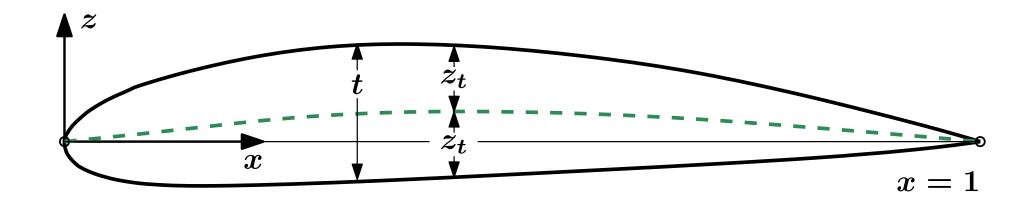
NACA 4-digit series definition

• Thickness distribution having maximum of t (total, not half):

$$z_t = 5t(0.2969\sqrt{x} - 0.1260x - 0.3516x^2 + 0.2843x^3 - 0.1015x^4)$$

• This gives a slightly blunt TE; a sharp TE is needed in computations

$$z_t = 5t(0.2969\sqrt{x} - 0.1260x - 0.3516x^2 + 0.2843x^3 - 0.1036x^4)$$



Problems

Show for yourself that

- 1. The camber function is smooth and differentiable
- 2. The thickness function results in a smoothly rounded LE
- 3. The thickness function peaks at about 30% of chord
- 4. The maximum thickness of the airfoil is indeed approximately t
- 5. The trailing edge is indeed sharp with the last equation



Wing Geometry

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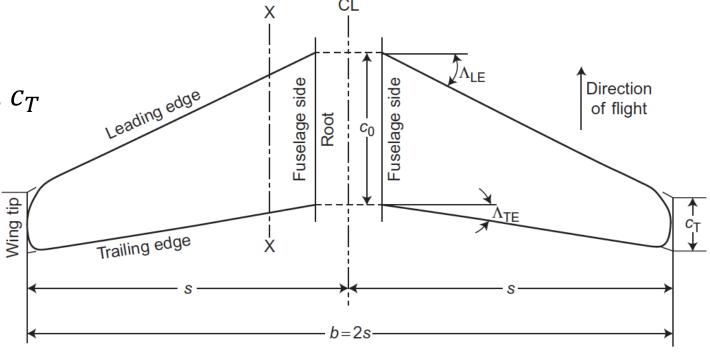
Wing geometry: Terminology for wing planform

Wing planform is its shape as seen on a plan (top) view of aircraft

- Wing span, b
- Wing area, S
- Chords

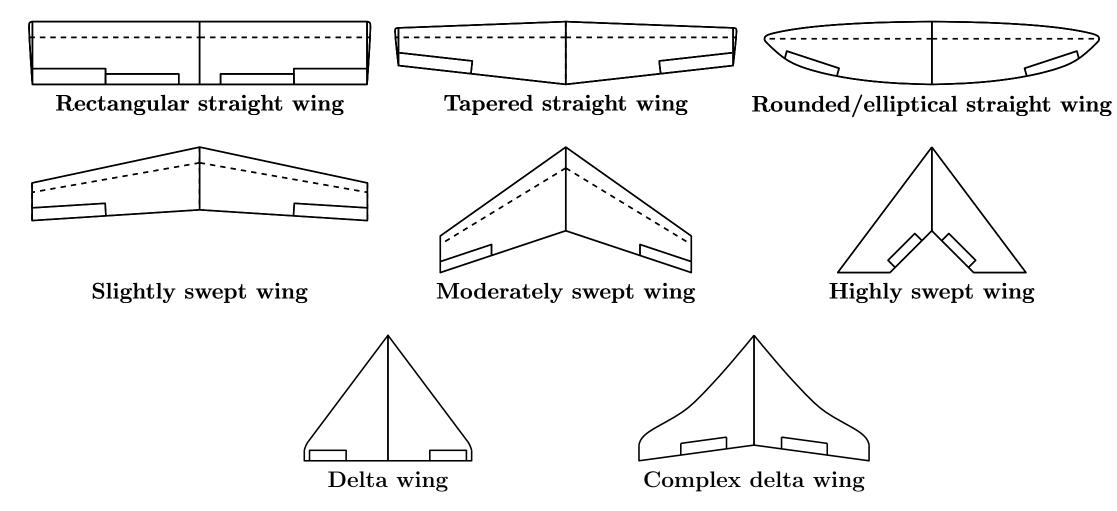
ullet Root chord, c_{0} , and tip chord, c_{T}

- Taper ratio (c_T/c_0)
- Mean chord, \bar{c} (: = S/b)
- Aspect ratio, $AR = b/\bar{c}$
 - Alternatively, $AR = b^2/S$
- ullet Sweep back, Λ_{LE} and Λ_{TE}



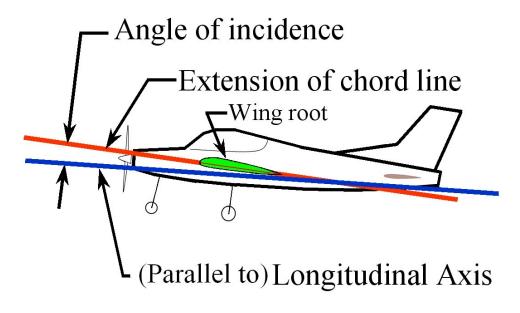


Examples of wing planform



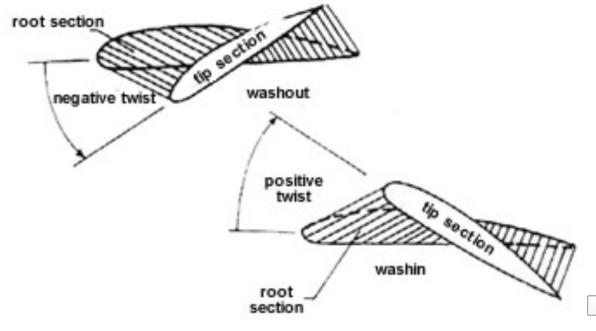
The third dimension

- Dihedral angle, Γ
- Geometric angle of incidence
- Twist: wash-in, wash-out





same NACA sections used throughout

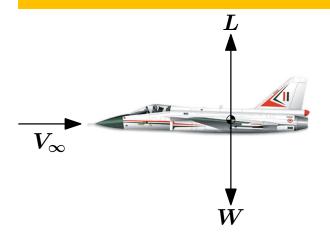


Aerodynamic Forces on an Airfoil

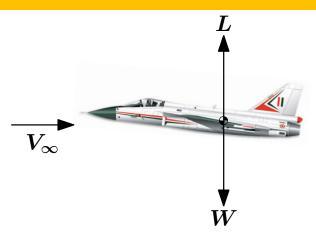
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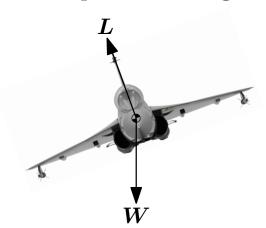
Review: Flight condition and direction of lift



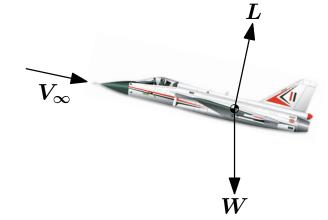
High-speed level flight



Low-speed level flight



Banked circling flight



Climbing flight

Houghton et al., Aerodynamics for Engineering Students, 2013

Aerodynamic forces: Contributions

Aerodynamic forces due to fluid on a surface can be resolved into

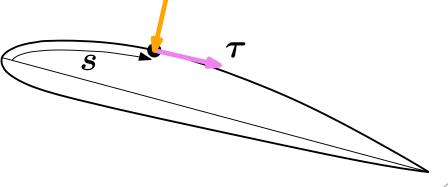
- Contribution from pressure (normal force per unit area)
- Contribution from shear stress (tangential force per unit area)

For 2D (airfoil) section, only one component of shear stress relevant

s =(Body-fitted) coordinate along surface, measured from LE

p = p(s) =Surface pressure distribution on airfoil section

 $\tau = \tau(s) =$ Surface shear stress distribution on airfoil section

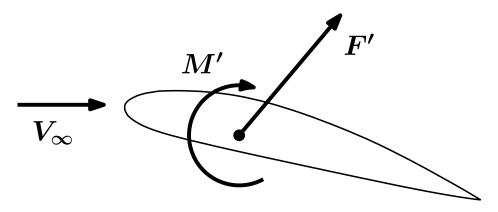


Aerodynamic forces: Resultant

Net effect of surface stresses $p \& \tau$ integrated over entire section:

- A resultant (sectional) aerodynamic force per unit span, F'
- A resultant (sectional) aerodynamic moment per unit span, M' (pitching moment in 2D), about a chosen point

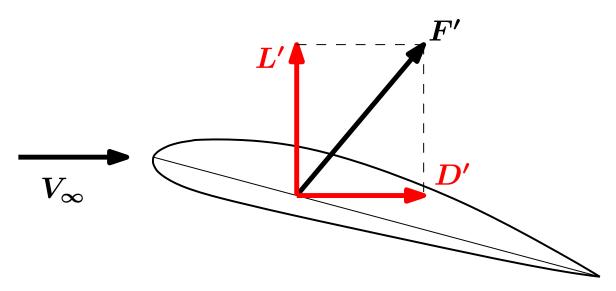
Primes on symbols (F' & M') signify forces/moments per unit span These are also called *sectional* force & *sectional* pitching moment



Aerodynamic forces: Components

Resultant force F' can be split into either of 2 sets of components One resolution is w.r.t. the direction of relative wind (\vec{V}_{∞})

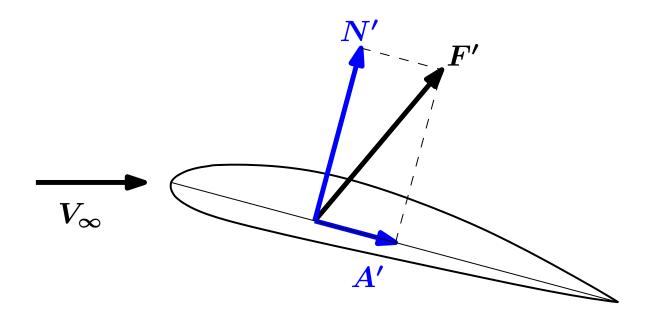
- L' := (Sectional) lift force = component of $F' \perp \vec{V}_{\infty}$
- D' := Drag force = component of $F' \parallel \vec{V}_{\infty}$



Aerodynamic forces: Components (alternative)

Another resolution is w.r.t. chord line

- $N' := Normal force = component of <math>F' \perp chord$
- $A' := Axial force = component of F' \parallel chord$



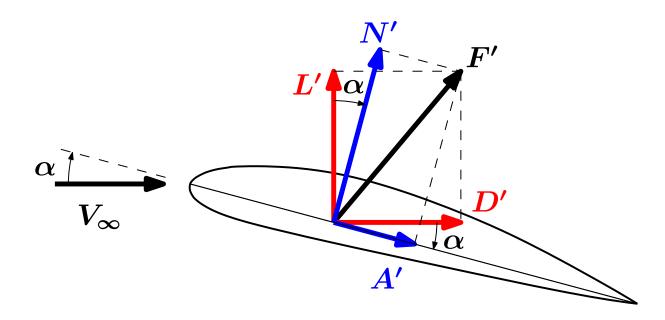
Aerodynamic forces: Components' relation

Angle-of-attack, α : = angle between chord line & \vec{V}_{∞}

• N.B.: α is measured +ve clockwise (i.e., $\alpha > 0$ means airfoil is pitched up)!

Thus, $L' = N' \cos \alpha - A' \sin \alpha$, $D' = N' \sin \alpha + A' \cos \alpha$

Alt., $N' = L' \cos \alpha + D' \sin \alpha$, $A' = -L' \sin \alpha + D' \cos \alpha$



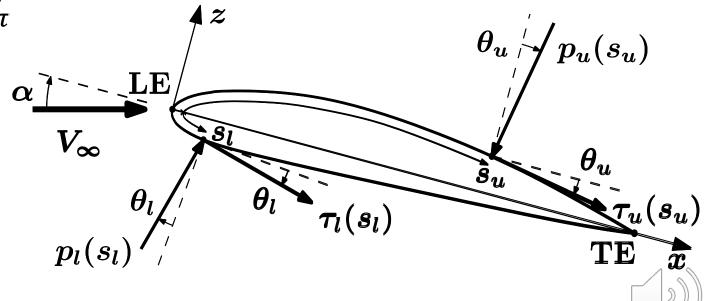
Pressure & shear contributions to axial force

Shear part,
$$A'_{\tau} = \int_{\text{LE}}^{\text{TE}} \tau_u \cos \theta_u \, ds_u + \int_{\text{LE}}^{\text{TE}} \tau_l \cos \theta_l \, ds_l$$

Pressure part,
$$A'_p = -\int_{LE}^{TE} p_u \sin \theta_u \, ds_u + \int_{LE}^{TE} p_l \sin \theta_l \, ds_l$$

Total axial force, $A' = A'_p + A'_{\tau}$

N.B.: θ_u & θ_l are measured positive clockwise!

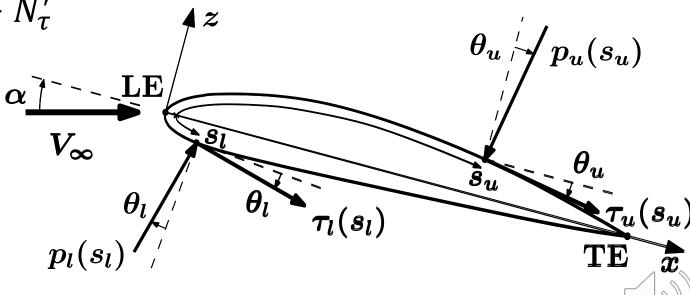


Pressure & shear contributions to normal force

Shear part,
$$N_{\tau}' = -\int_{\text{LE}}^{\text{TE}} \tau_u \sin \theta_u \, ds_u - \int_{\text{LE}}^{\text{TE}} \tau_l \sin \theta_l \, ds_l$$

Pressure part,
$$N_p' = -\int_{LE}^{TE} p_u \cos \theta_u \, ds_u + \int_{LE}^{TE} p_l \cos \theta_l \, ds_l$$

Total normal force, $N' = N_p' + N_\tau'$



Approximations for slender airfoils

For slender airfoils, surface's slope (θ_u or θ_l) is small everywhere

I.e.,
$$\cos \theta_u \approx 1$$
, $\sin \theta_u \approx -dz_u/dx$, $\cos \theta_l \approx 1$, $\sin \theta_l \approx -dz_l/dx$

$$N_p' = -\int_{\text{LE}}^{\text{TE}} p_u \cos \theta_u \, ds_u + \int_{\text{LE}}^{\text{TE}} p_l \cos \theta_l \, ds_l \approx \int_0^c (-p_u + p_l) dx$$

$$N_{\tau}' = -\int_{\mathrm{LE}}^{\mathrm{TE}} \tau_{u} \sin \theta_{u} \, ds_{u} - \int_{\mathrm{LE}}^{\mathrm{TE}} \tau_{l} \sin \theta_{l} \, ds_{l} \approx \int_{0}^{c} \left(\tau_{u} \frac{dz_{u}}{dx} + \tau_{l} \frac{dz_{l}}{dx} \right) dx$$

$$A_{\tau}' = \int_{\text{LE}}^{\text{TE}} \tau_u \cos \theta_u \, ds_u + \int_{\text{LE}}^{\text{TE}} \tau_l \cos \theta_l \, ds_l \approx \int_0^c (\tau_u + \tau_l) dx$$

$$A'_{p} = -\int_{\text{LE}}^{\text{TE}} p_{u} \sin \theta_{u} \, ds_{u} + \int_{\text{LE}}^{\text{TE}} p_{l} \sin \theta_{l} \, ds_{l} \approx \int_{0}^{c} \left(p_{u} \frac{dz_{u}}{dx} - p_{l} \frac{dz_{l}}{dx} \right) dx$$

Approximations for slender airfoils at low AoA

If the AoA, α , is small, then $\cos \alpha \approx 1$, $\sin \alpha \approx \alpha \ll 1$ For *streamlined* airfoils, A' and N' are of similar order Along with the preceding simplifications for slender airfoils, one has

$$L' = N' \cos \alpha - A' \sin \alpha \approx N' - A' \alpha \approx N'_p \approx \int_0^c (p_l - p_u) dx$$

Sectional lift force is almost solely determined by pressure distribution, not by shear stress

 In particular, by the pressure differential on the upper (suction) and lower (pressure) surfaces



Pitching Moment on an Airfoil

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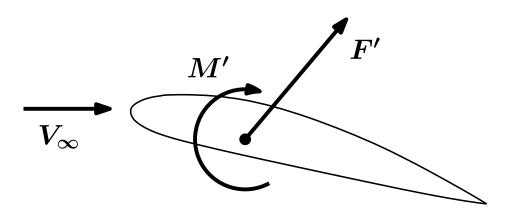


Resultant aerodynamic pitching moment

Net *rotational* effect of surface pressure p and surface shear stress τ *integrated* over entire section:

• A resultant aerodynamic moment M' (pitching moment in 2D), about a chosen point

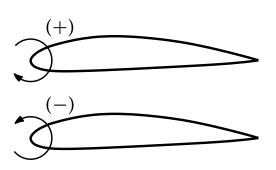
Prime reflects the fact that the moment is "per unit span" It is thus also called *sectional* pitching moment



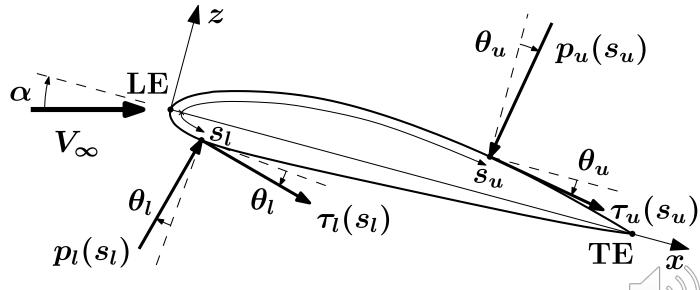
Pitching moment from pressure and shear

About LE, sectional pitching moment is (see sign convention):

$$M'_{LE} = \int_{\text{LE}}^{\text{TE}} [(p_u \cos \theta_u + \tau_u \sin \theta_u)x + (-p_u \sin \theta_u + \tau_u \cos \theta_u)z]ds_u$$
$$+ \int_{\text{LE}}^{\text{TE}} [(-p_l \cos \theta_l + \tau_l \sin \theta_l)x + (p_l \sin \theta_l + \tau_l \cos \theta_l)z]ds_l$$



Positive if tending to increase AoA



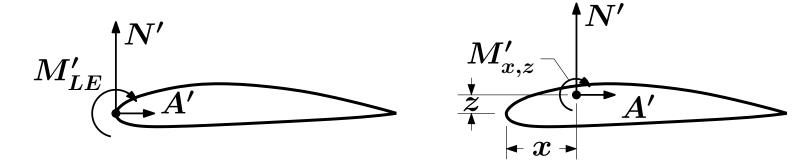
Review of Forces and Moment Systems

Moment on a system can be reported about any point

Given the moment about one point (and forces on the system),
 moment about another point can be calculated from equivalence

Setting origin of coordinate system at LE,

$$M'_{LE} = M'_{x,z} - xN' + zA'$$



Reference point @ LE

Reference point @ (x, z)



Center of pressure

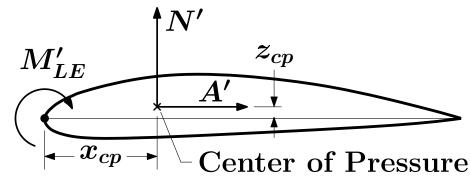
It's the point thru which resultant of surface-distributed forces act Alternatively, it's the point about which (pitching) moment vanishes

• Skin friction contribution to pitching moment is usually negligible owing to slender shape of airfoils (hence the terminology)

Setting origin at LE, $M'_{LE} = -x_{CP}N' + z_{CP}A'$ (since $M'_{CP} = 0$)

- As airfoils are slender, z_{CP} is usually negligible $\implies x_{CP} \approx -M_{LE}'/N'$
- If AoA is small, then $L' \approx N'$

$$\Rightarrow x_{CP} \approx -M_{LE}'/L'$$

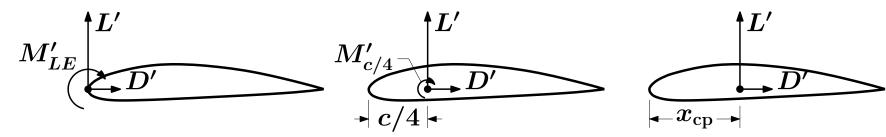


Equivalent specs of airfoil forces & moment

As L' decreases, $x_{CP} \approx -M'_{LE}/L'$ becomes difficult to measure

- Thus, center of pressure is not always a convenient concept However, this is no problem since L' and D' can be placed at any point as long as M' is also specified about that point
- Later we will find that quarter-chord point is particularly suitable

Equivalent descriptions:
$$M'_{LE} = -xL' + M'_{x} = -\frac{c}{4}L' + M'_{c/4} = -x_{CP}L'$$



Resultant force at:

Leading edge

Quarter-chord point

Center of pressure

Aerodynamic center

Sectional pitching moment vanishes at center of pressure

But location of center of pressure may shift with AoA

Aerodynamic center (x_{ac}, z_{ac}) is defined as a point about which sectional pitching moment is independent of AoA

• Usually, $z_{ac} \approx 0$ for slender airfoils

Although this may seem miraculous, existence of such a point is:

- Due to the slenderness of airfoils,
- Due to the limitation of their operation to small AoAs, and
- Limited focus on operation at high Reynolds nos.

Knowledge of A/D center is crucial for design of aerospace vehicles



Dimensional Analysis in Aerodynamics

Introduction to Aerodynamics



Dimensional analysis of airfoil forces

Let F' be any (sectional) A/D force per unit span on a 2D (airfoil) section

$$F' = f(\rho_{\infty}, V_{\infty}, c, \alpha, \mu_{\infty}, a_{\infty}, \text{geometry})$$

This is a dimensional equation; all terms have dimensions of force/length Reformulate as an equivalent dimensionless equation; one option is

$$\frac{F'}{0.5\rho_{\infty}V_{\infty}^2c} = \hat{f}\left(\alpha, \frac{\rho_{\infty}V_{\infty}c}{\mu_{\infty}}, \frac{V_{\infty}}{a_{\infty}}, \text{shape}\right)$$

Fundamental: Shows that dimensionless sectional force (called sectional force coefficient) depends only on AoA, Reynolds no., Mach no. & shape N.B.: Reynolds no. and Mach no. refer to freestream values

Sectional force/moment coefficients on 2D sections

 $q_{\infty} \coloneqq 0.5 \rho_{\infty} V_{\infty}^2$ is "dynamic head" of flow (0.5 is from Bernoulli's eqn.) Relevant airfoil *sectional* force coefficients (coeff.) are:

Lift coeff.,
$$c_l := \frac{L'}{q_\infty c}$$
; Drag coeff., $c_d := \frac{D'}{q_\infty c}$

Normal force coeff., $c_n := \frac{N'}{q_\infty c}$; Axial force coeff., $c_a := \frac{A'}{q_\infty c}$

By analogy, pitching moment coeff., $c_m := \frac{M'}{q_\infty c^2}$

N.B.: sectional coefficients' symbols have lower case 'c' and subscripts All are functions of AoA, Reynolds no. & Mach no. (& shape of course)



Dimensional analysis of 3D aerodynamic forces

Let F be any aerodynamic force on a 3D (wing) body

$$F = f(\rho_{\infty}, V_{\infty}, \overline{c}, b, \alpha, \mu_{\infty}, a_{\infty}, \text{geometry})$$

Reformulate as an equivalent dimensionless equation; one option is

$$\frac{F}{0.5\rho_{\infty}V_{\infty}^{2}S} = \hat{f}\left(\alpha, \frac{\rho_{\infty}V_{\infty}\bar{c}}{\mu_{\infty}}, \frac{V_{\infty}}{a_{\infty}}, AR, \text{shape}\right)$$

I.e., dimensionless force (called force coefficient) depends only on AoA, Reynolds no., Mach no., aspect ratio and shape

$$C_L = \frac{L}{q_{\infty}S};$$
 $C_D = \frac{D}{q_{\infty}S};$ $C_N = \frac{N}{q_{\infty}S};$ $C_A = \frac{A}{q_{\infty}S};$ $C_M = \frac{M}{q_{\infty}S\overline{c}}$

N.B.: coefficients' symbols have upper case 'C' and subscripts



Pressure coefficient and skin friction coefficient

Pressure & shear stresses can also be reduced to non-dimensional coefficients, following the same principle of dimensional analysis

Pressure coeff.:
$$C_p = \frac{p-p_\infty}{q_\infty}$$
Skin friction coeff.: $c_f = \frac{\tau}{q_\infty}$

Both are functions of AoA, Reynolds no., Mach no. & shape Also, function of non-dimensional position on body surface (following similarity)

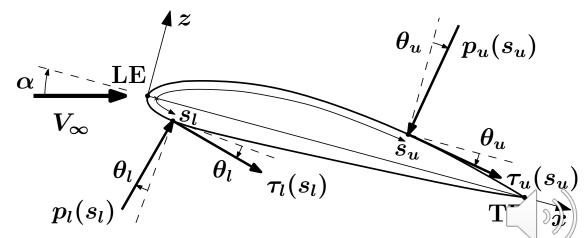
Expressing c_n , c_a , c_l & c_d in terms of C_p & c_f

All aerodynamic force coefficients can be found from the pressure and skin friction coefficients

$$c_n = \int_{\text{LE}}^{\text{TE}} \left(-C_{p,u} \cos \theta_u - c_{f,u} \sin \theta_u \right) \frac{ds_u}{c} + \int_{\text{LE}}^{\text{TE}} \left(C_{p,l} \cos \theta_l - c_{f,l} \sin \theta_l \right) \frac{ds_l}{c}$$

$$c_a = \int_{\text{LE}}^{\text{TE}} \left(-C_{p,u} \sin \theta_u + c_{f,u} \cos \theta_u \right) \frac{ds_u}{c} + \int_{\text{LE}}^{\text{TE}} \left(C_{p,l} \sin \theta_l + c_{f,l} \cos \theta_l \right) \frac{ds_l}{c}$$

$$c_l = c_n \cos \alpha - c_a \sin \alpha$$
$$c_d = c_n \sin \alpha + c_a \cos \alpha$$



Goal of study of aerodynamics

Clearly, the foregoing demonstrates the principle stated earlier, viz.

- Aerodynamic lift, drag & moments on a body are the surfaceintegrated pressure and shear stress distributions over the body

Goal of aerodynamics is to determine p(s) and $\tau(s)$ for a given body shape and freestream condition, thus yielding the coefficients of aerodynamic forces and moments

Streamlining of airfoils results in pressure dominating over shear for the all-important lift force & pitching moment

A simplified endeavour is to calculate p(s) only on airfoils and wings for *estimating* the coefficients of lift and pitching moment



End of Topic

Introduction to Aerodynamics

