

## **Orbbec-OpenNI2 Extended API Instruction**

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#### 1. Overview

Orbbec SDK extends OpenNI2 to implement some functions, which including reading serial number, obtaining device, saving by Flash, obtaining and setting camera parameter, IR setting, LDP control, LDM modular control, etc. This document describes those functions and demonstrate basic procedures.

## 2. Scope

Device: Astra Series Camera which including Astra, Astra Pro, Astra Mini, etc.

Platform: Windows 7 and above; Ubuntu 14.04 and above.

#### 3. Introduction

Orbbec OpenNI2 Extended API supports Windows x86/x64, Linux x64, ARM32, ARM64 and Android. OpenNI2 should be initialized and device should be opened successfully before utilizing the extended API.

Here are the instructions for all extended APIs.

#### 4. Obtain Serial Number

```
char serNumber[12];
int dataSize = sizeof(serNumber);
memset(serNumber, 0, dataSize);
g_Device.getProperty(openni::OBEXTENSION_ID_SERIALNUMBER, (uint8_t *)&serNumber, &dataSize);
```

## 5. Obtain Device Type

```
char devType[32];
int dataSize = sizeof(devType);
memset(devType, 0, dataSize);
g_Device.getProperty(openni::OBEXTENSION_ID_DEVICETYPE, (uint8_t *)&devType, &dataSize);
```

### 6. Obtain Camera Parameters

In Astra Series, only Astra S has the calibration parameters saved at the factor. Parameters in other models can be set manually by step 7.



```
typedef struct OBCameraParams
   float 1 intr p[4];
                        //[fx,fy,cx,cy]
   float r intr p[4];
                         //[fx,fy,cx,cy]
   float r21 r[9];
                         //[r00,r01,r02;r10,r11,r12;r20,r21,r22]
   float r21_t[3];
                         //[t1,t2,t3]
                          //[k1,k2,p1,p2,k3]
   float k[5];
   int is mirror;
}OBCameraParams;
OBCameraParams
                    m CamParams;
int dataSize = sizeof(OBCameraParams);
g Device.getProperty(openni::OBEXTENSION ID CAM PARAMS,
                                                                      (uint8 t
                                                                                 *)&m CamParams,
&dataSize);
```

### 7. Set Camera Parameters to Device

```
typedef struct OBCameraParams
  float l_intr_p[4];
                                //[fx,fy,cx,cy]
  float r intr p[4];
                                //[fx,fy,cx,cy]
  float r2l_r[9];
                                //[r00,r01,r02;r10,r11,r12;r20,r21,r22]
  float r21 t[3];
                                //[t1,t2,t3]
  float k[5];
                                  //[k1,k2,p1,p2,k3]
  int is mirror;
} OBCameraParams;
OBCameraParams m CamParams = \{0\};
int dataSize = sizeof(OBCameraParams);
m CamParams.1 intr p[0] = 577.318970;
m CamParams.1 intr p[1] = 577.318970;
m CamParams.l intr p[2] = 308.729004;
m_{\text{CamParams.l_intr_p[3]}} = 269.143005;
m CamParams.r intr p[0] = 517.447998;
m CamParams.r intr p[1] = 517.447998;
m_{camParams.r_intr_p[2]} = 305.432007;
m CamParams.r intr p[3] = 250.410995;
```



```
m CamParams.r21 r[0] = 0.999972;
m_{camParams.r21_r[1]} = -0.005735;
m_{camParams.r21_r[2]} = 0.004735;
m CamParams.r21 r[3] = 0.005736;
m CamParams.r21 r[4] = 0.999983;
m CamParams.r21 r[5] = -0.000298;
m_{camParams.r21_r[6]} = -0.004733;
m_{camParams.r21_r[7]} = 0.000325;
m CamParams.r21 r[8] = 0.999989;
m CamParams.r2l t[0] = -25.147900;
m CamParams.r21 t[1] = 0.015202;
m_{camParams.r2l_t[2] = -0.648167;
m CamParams.k[0] = -0.077348;
m CamParams.k[1] = 0.208761;
m CamParams.k[2] = -0.196780;
m CamParams.k[3] = 0.000617;
m_{\text{CamParams.k}}[4] = 0.001059;
m CamParams.is mirror = 0;
g Device.setProperty(openni::OBEXTENSION ID CAM PARAMS,
                                                                  (uint8 t
                                                                             *)&m CamParams,
dataSize);
```

### 8. Obtain IR Gain Value

```
int gain = 0;
int dataSize = 4;
g_Device.getProperty(openni::OBEXTENSION_ID_IR_GAIN, (uint8_t*)&gain, &dataSize);
printf("ir gain value : 0x%x\n", gain);
```

## 9. Set IR Gain Value

```
int gain = 0;
int dataSize = 4;
g_device.getProperty(openni::OBEXTENSION_ID_IR_GAIN, (uint8_t *)&gain, &dataSize);
printf("ir gain value : 0x%x\n", gain);
gain++;
g_device.setProperty(openni::OBEXTENSION_ID_IR_GAIN, (uint8_t *)&gain, dataSize);
```



# 10. Obtain IR Exposure Value

```
int exposure = 0;
int dataSize = 4;
g_device.getProperty(openni::OBEXTENSION_ID_IR_EXP, (uint8_t*)&exposure, &dataSize);
printf("ir exposure value : 0x%x\n", exposure);
```

## 11. Set IR Exposure Value

```
int exposure = 0;
int dataSize = 4;
g_device.getProperty(openni::OBEXTENSION_ID_IR_EXP, (uint8_t *)&exposure, &dataSize);
printf("ir exposure value : 0x%x\n", exposure);
exposure += 256;
g_device.setProperty(openni::OBEXTENSION_ID_IR_EXP, (uint8_t *)&exposure, dataSize);
```

# 12. LDP Switch, Camera Re-plug is Required

```
int dataSize = 4;
int ldp_en = enable;
g_Device.setProperty(openni::OBEXTENSION_ID_LDP_EN, (uint8_t *)&ldp_en, dataSize);
```

### 13. Laser Switch

```
int dataSize = 4;
int laser_en = enable;
g_Device.setProperty(openni::OBEXTENSION_ID_LASER_EN, (uint8_t *)&laser_en, dataSize);
```