Ordinary least squares method

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Breast cancer dataset

```
1) ID number
2) Diagnosis (M = malignant, B = benign)
3) radius (mean)
4) texture (mean)
5) perimeter (mean)
6) area (mean)
7) smoothness (mean)
8) compactness (mean)
9)
   concavity (mean)
10) concave points (mean)
11) symmetry (mean)
12) fractal dimension (mean)
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Breast cancer dataset

```
13) radius (stderr)
14) texture (stderr)
15) perimeter (stderr)
16) area (stderr)
17) smoothness (stderr)
18) compactness (stderr)
19) concavity (stderr)
20) concave points (stderr)
21) symmetry (stderr)
22) fractal dimension (stderr)
```

Breast cancer dataset

```
23) radius (worst)
24) texture (worst)
25) perimeter (worst)
26) area (worst)
27) smoothness (worst)
28) compactness (worst)
29) concavity (worst)
30) concave points (worst)
31) symmetry (worst)
32) fractal dimension (worst)
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Linear representation

$$A_{\text{lin}} = \begin{bmatrix} f_{1,1} & \dots & f_{1,m} \\ f_{2,1} & \dots & f_{2,m} \\ \vdots & \dots & \vdots \\ f_{n,1} & \dots & f_{n,m} \end{bmatrix}$$
(1)

Linear system of equations

$$Ax = y, A \in \mathbb{R}^{n \times m}, y \in \mathbb{R}^{n \times 1}$$
 (2)

System of equations is:

- underdetermined: n < m
- overdetermined: n > m

Number of solutions:

- Infinitely many solutions:
 - rank([A, y]) = rank(A) and rank(A) < m
- Exactly one solution:
 - rank([A, y]) = rank(A) and rank(A) = m
- No solution:
 - rank([A, y]) = rank(A) + 1

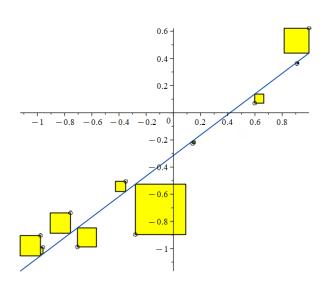
$$Aw \cong y, \quad A \in \mathbb{R}^{n \times m}, \quad y \in \mathbb{R}^{n \times 1}$$
 (3)

n – number of instances (number of equations) m – number of features (number of searched weights)

 $A \in \mathbb{R}^{n \times m}$ is a known matrix of features $y \in \mathbb{R}^{n \times 1}$ is a known column vectors of labels $w \in \mathbb{R}^{m \times 1}$ is a searched vector of feature weights

$$\min_{w} ||Aw - y||_2 \tag{4}$$

Ordinary least squares method



$$\min_{w} ||Aw - y||_{2} = \min_{w} ||Aw - y||_{2}^{2} = \min_{w} J(w)$$

$$J(w) = ||Aw - y||_{2}^{2} = (Aw - y)^{T} (Aw - y)$$

$$= (Aw)^{T} (Aw) - (Aw)^{T} y - y^{T} (Aw) + y^{T} y$$

$$= (Aw)^{T} (Aw) - 2(Aw)^{T} y + y^{T} y$$

$$= w^{T} A^{T} Aw - 2w^{T} A^{T} y + y^{T} y$$

$$\frac{\partial J}{\partial w} = 2A^{T} Aw - 2A^{T} y = 0$$

Normal equations

$$A^T A w = A^T y \tag{5}$$

Linear representation

$$A_{\text{lin}} = \begin{bmatrix} f_{1,1} & f_{1,2} & f_{1,3} & f_{1,4} \\ f_{2,1} & f_{2,2} & f_{2,3} & f_{2,4} \\ \vdots & \vdots & \vdots & \vdots \\ f_{n,1} & f_{n,2} & f_{n,3} & f_{n,4} \end{bmatrix}$$
(6)

Quadratic representation

 $\begin{aligned} & A_{\mathsf{quad}} = \\ & \left[f_{1,1}, f_{1,2}, f_{1,3}, f_{1,4}, f_{1,1}^2, f_{1,2}^2, f_{1,3}^2, f_{1,4}^2, f_{1,1}f_{1,2}, f_{1,1}f_{1,3}, f_{1,1}f_{1,4}, f_{1,2}f_{1,3}, f_{1,2}f_{1,4}, f_{1,3}f_{1,4} \right] \\ & \vdots \\ & f_{n,0}, f_{n,1}, f_{n,2}, f_{n,3}, f_{n,0}^2, f_{n,1}^2, f_{n,3}^2, f_{n,4}^2, f_{n,1}f_{n,2}, f_{n,1}f_{n,3}, f_{n,1}f_{n,4}, f_{n,2}f_{n,3}, f_{n,2}f_{n,4}, f_{n,3}f_{n,4} \right] \end{aligned}$

- features $f_{k,i}$
- quadratic features $f_{k,i}^2$
- interaction terms $f_{k,i}f_{k,j}$

Normal equations

$$w = \underbrace{(A^T A)^{-1} A^T}_{\text{pseudoinverse matrix}} y \tag{7}$$

$$w = A^{\dagger} y \tag{8}$$

$$\min_{w} J(w) = \min_{w} \sum_{i=1}^{n} (y_i - w^T x_i)^2$$
 (9)

Equations (7) and (8) have only theoretical importance. In practice, explicit matrix inverse should be avoided and normal equations are used to find weights w:

$$A^T A w = A^T y \tag{10}$$

Conditioning of least squares

Condition number of matrix A:

$$\kappa(A) = \operatorname{cond}(A) \stackrel{\mathrm{df}}{=} ||A|| \cdot ||A^{-1}|| \tag{11}$$

It can be found with np.linalg.cond.

$$\operatorname{cond}(A^T A) = \operatorname{cond}(A)^2 \tag{12}$$

- Conditionining of a square linear system of equations Aw = y depends only on A.
- Conditionining of a least squares problem $Aw \cong y$ depends both on A and y.
- Ill-conditioning does not harm predictions residual of normal equations will be small
- The values of weights will be poorly determined

Normal equations

- \bullet A^TA is not guaranteed to be non-singular
- The method is overly sensitive to the condition number of matrix
- QR and SVD are numerically more stable alternatives but computationally slower

A is well-conditioned normal equations
A is not well-conditioned but is not rank deficient QR
A is rank deficient SVD

Normal equations

$$w = \underbrace{(A^T A + \lambda I)^{-1} A^T}_{\text{pseudoinverse matrix}} y \tag{13}$$

$$\min_{w} J(w) = \sum_{i=1}^{n} (y_i - w^T x_i)^2 + \lambda w^T w$$
 (14)

Equation (13) has only theoretical importance. In practice, explicit matrix inverse should be avoided and normal equations are used to find weights w:

$$(A^T A + \lambda I)w = A^T y \tag{15}$$

Beyond least squares method

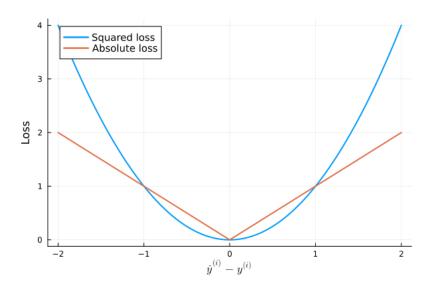
$$\min_{w} ||Aw - y||_2$$

- Cost function $J(w) = \sum_{i=1}^{n} (y_i w^T x_i)^2$
- Differences $y_i w^T x_i$ have Gaussian distribution
- There is explicit formula for w

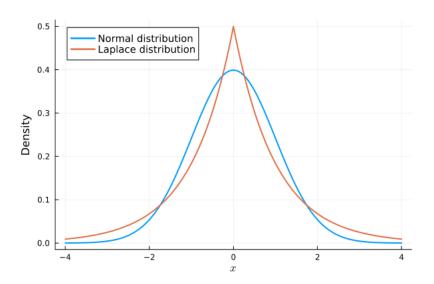
$$\min_{w} ||Aw - y||_1$$

- Cost function $J(w) = \sum_{i=1}^{n} |y_i w^T x_i|$
- Differences $y_i w^T x_i$ have Laplace distribution
- There is no explicit formula for w

Cost functions



Distributions



References

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- [2] Michael T. Heath, Chapter 3: Linear Least Squares http://heath.cs.illinois.edu/scicomp/notes/cs450_ chapt03.pdf
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