

# **神經與行為模型建構 (Neural & Behavioral Modeling)**

課號：Psy5352

識別碼：227U2810

教室：普 101

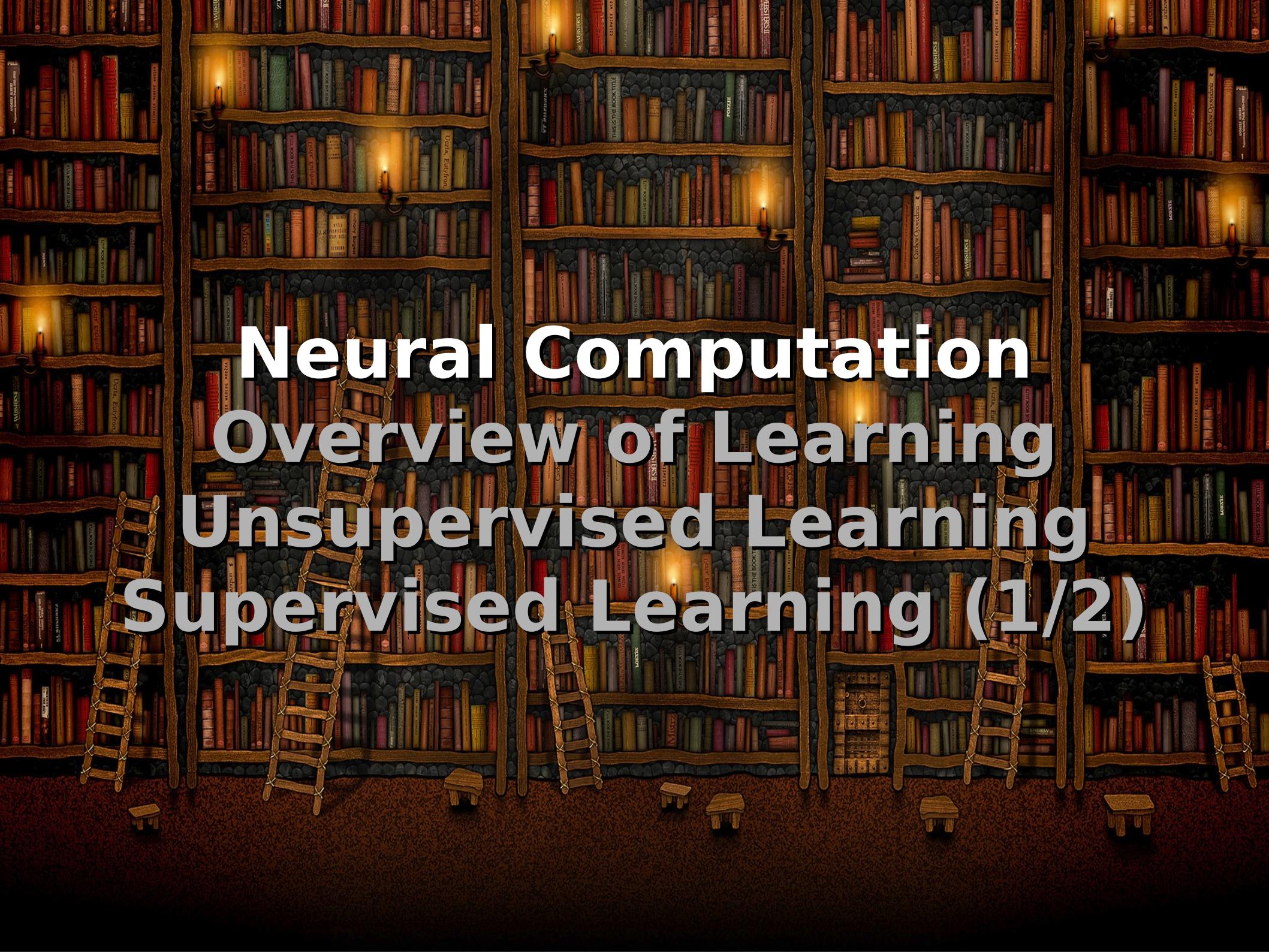
時間：— 234





學習的實驗 / 模型較複雜

!



# Neural Computation

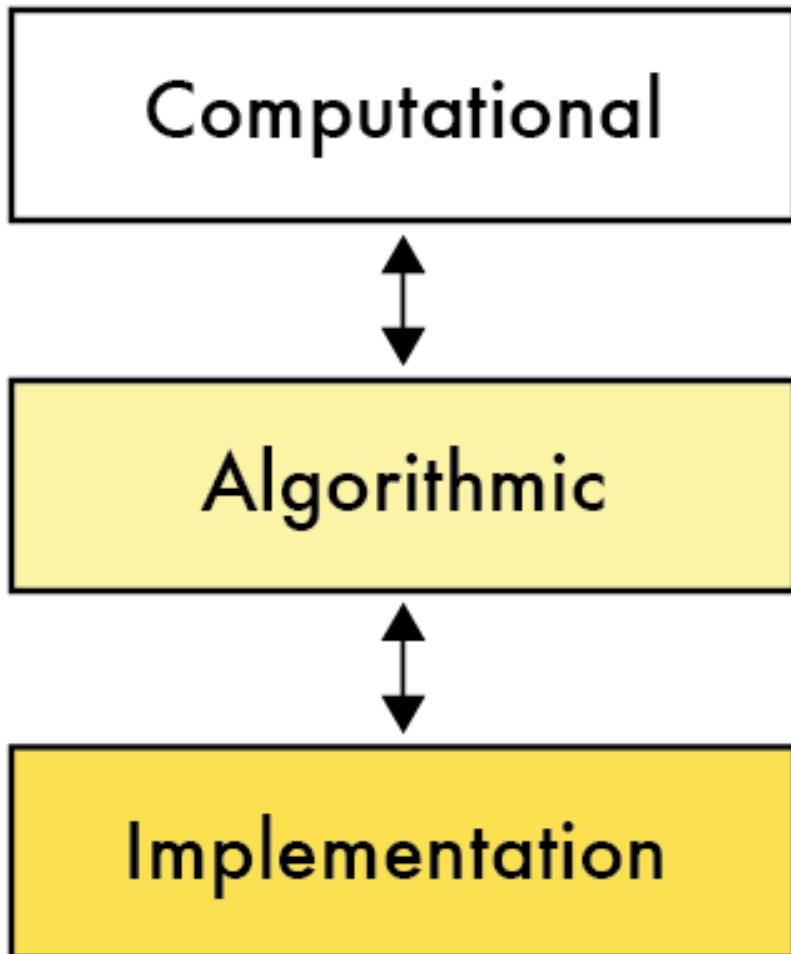
## Overview of Learning

### Unsupervised Learning

### Supervised Learning (1/2)

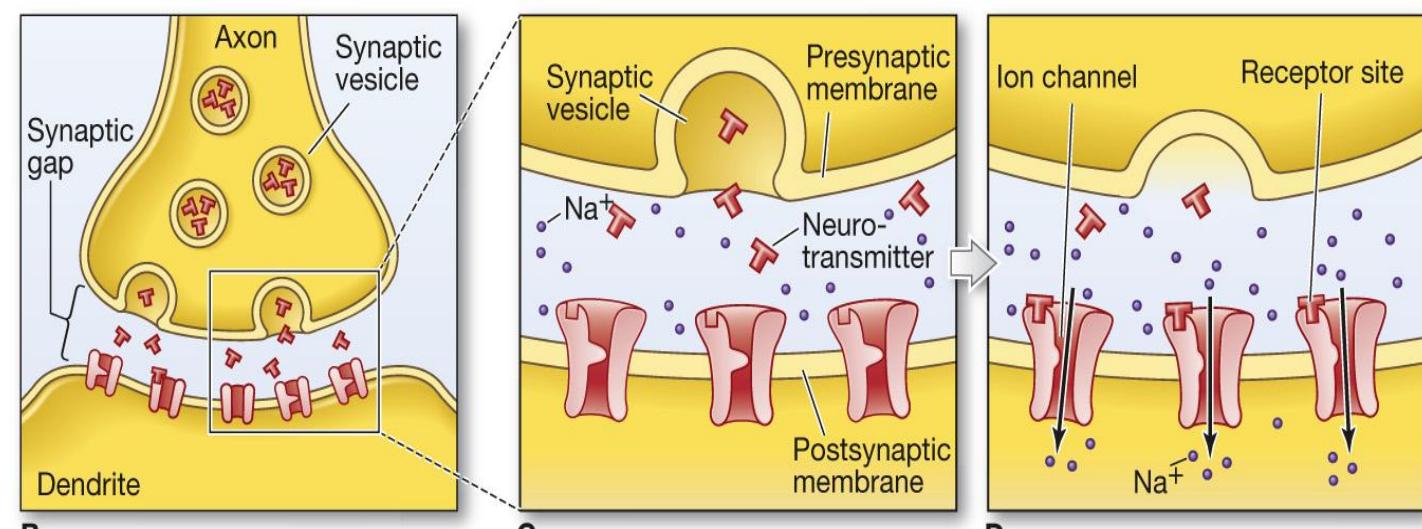
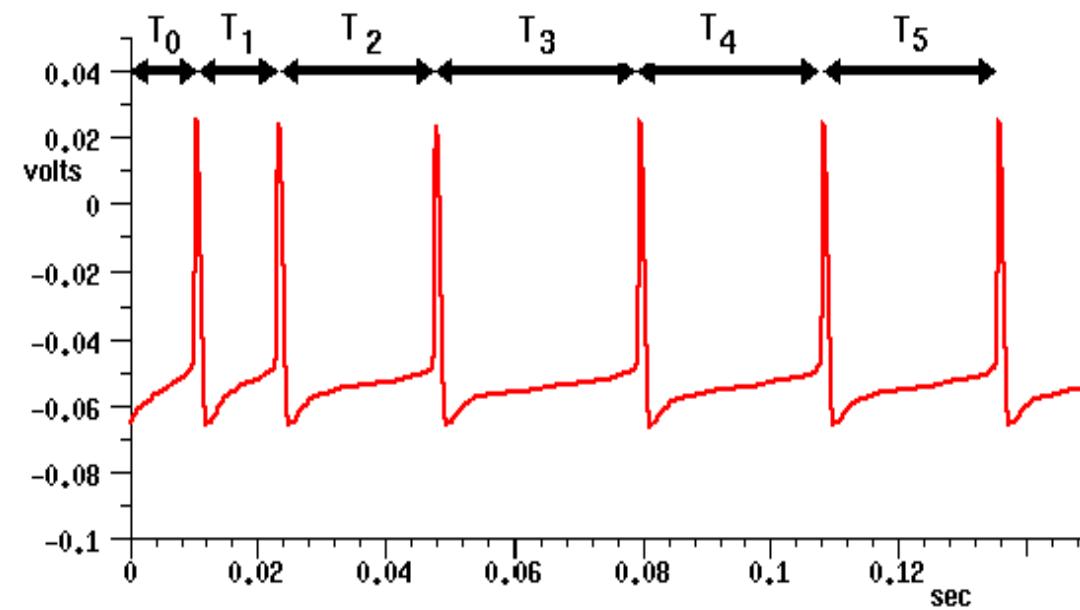
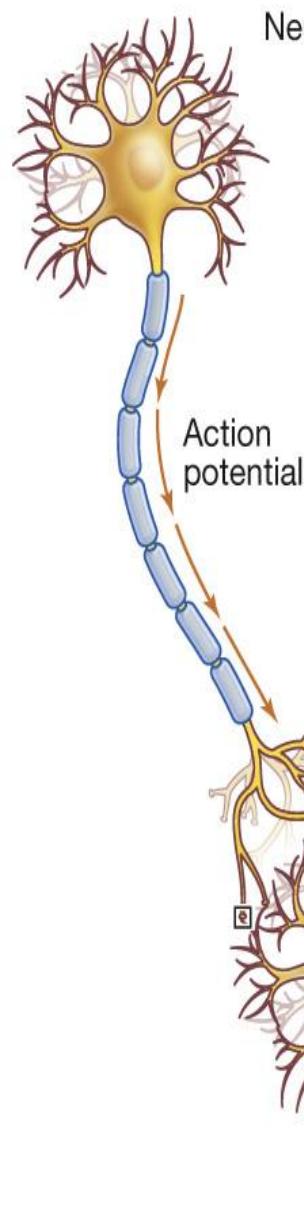
# 了解一個認知系統的特性與極限

## David Marr's 3 levels of analysis



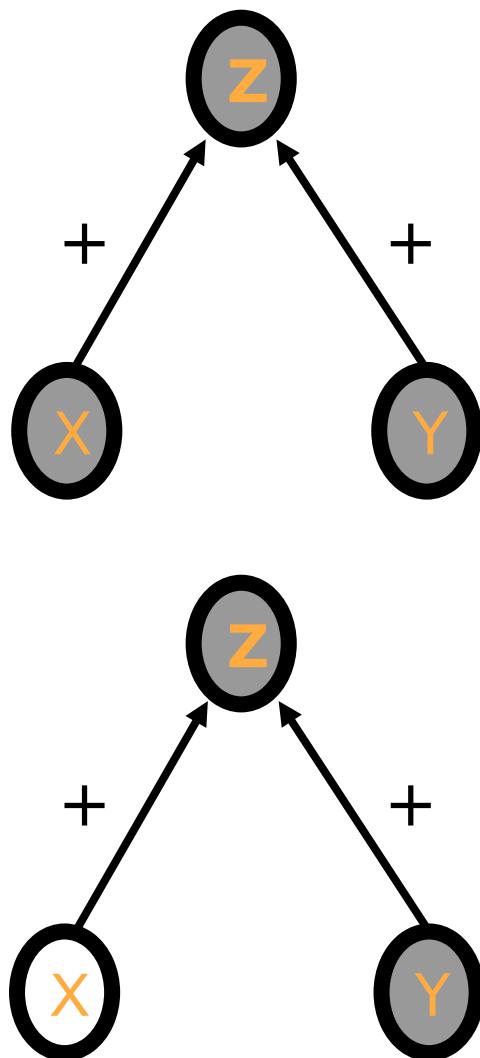
- 計算上的問題是什麼？
- 能夠用什麼演算法來解決？
- 要透過什麼硬體來實現算法？

# Implementation: 有 0 與 1 的神經元



# Implementation: 神經元做加法

如果接受刺激的神經元有個低閾值

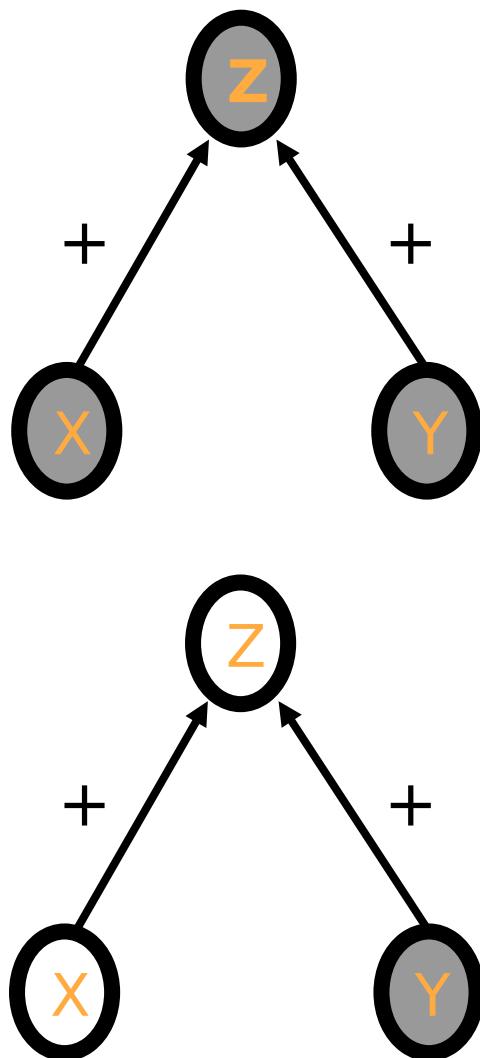


| X | Y | Z |
|---|---|---|
| 0 | 0 | 0 |
| 0 | 1 | 1 |
| 1 | 0 | 1 |
| 1 | 1 | 1 |

$$Z = X + Y \text{ (OR)}$$

# Implementation: 神經元做乘法

如果接受刺激的神經元有個高閾值

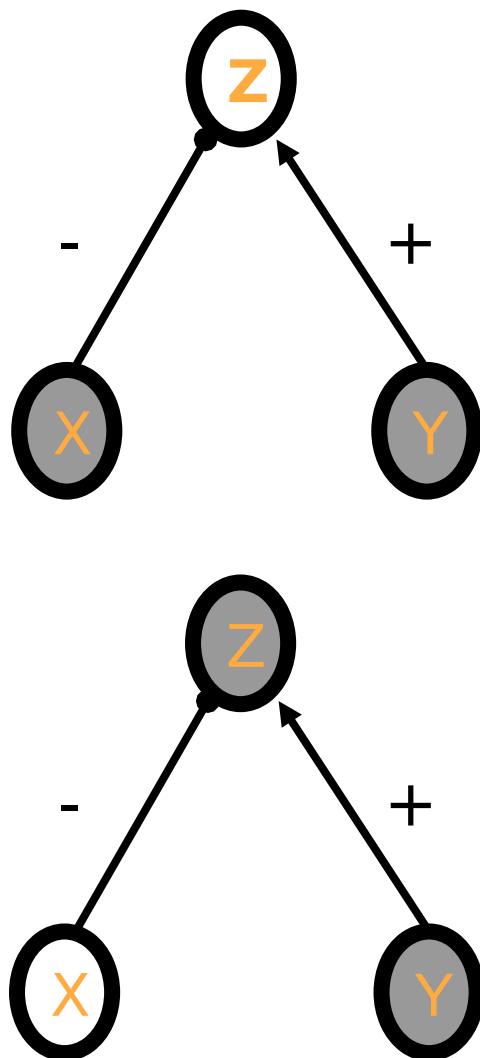


| X | Y | Z |
|---|---|---|
| 0 | 0 | 0 |
| 0 | 1 | 0 |
| 1 | 0 | 0 |
| 1 | 1 | 1 |

$$Z = X * Y \text{ (AND)}$$

# Implementation: 神經元做減法

如果開始考慮神經元彼此的抑制關係

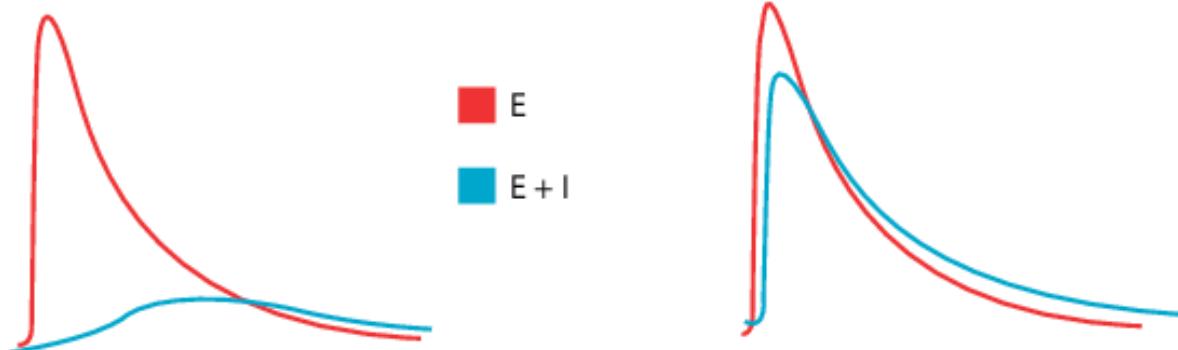
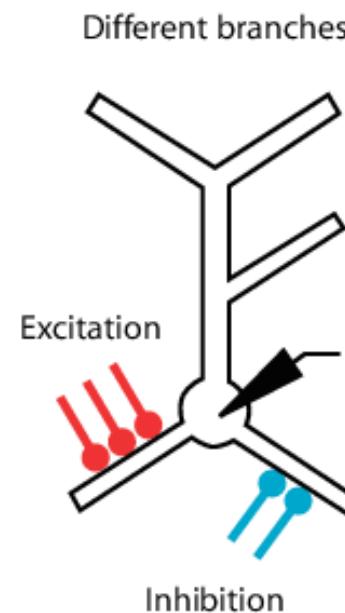
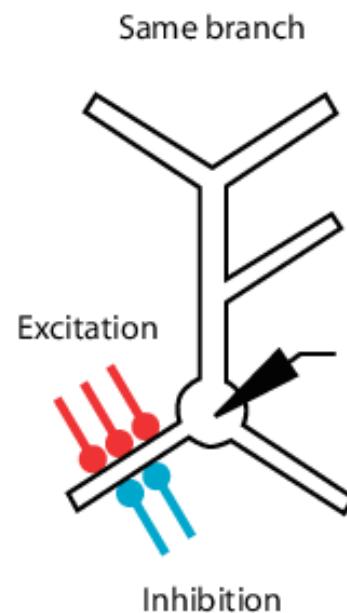


| X | Z |
|---|---|
| 0 | 1 |
| 1 | 0 |

$$Z = 1 - X \text{ (NOT)}$$

# Implementation: 神經元做除法

神經元間的抑制可以導致減法或除法

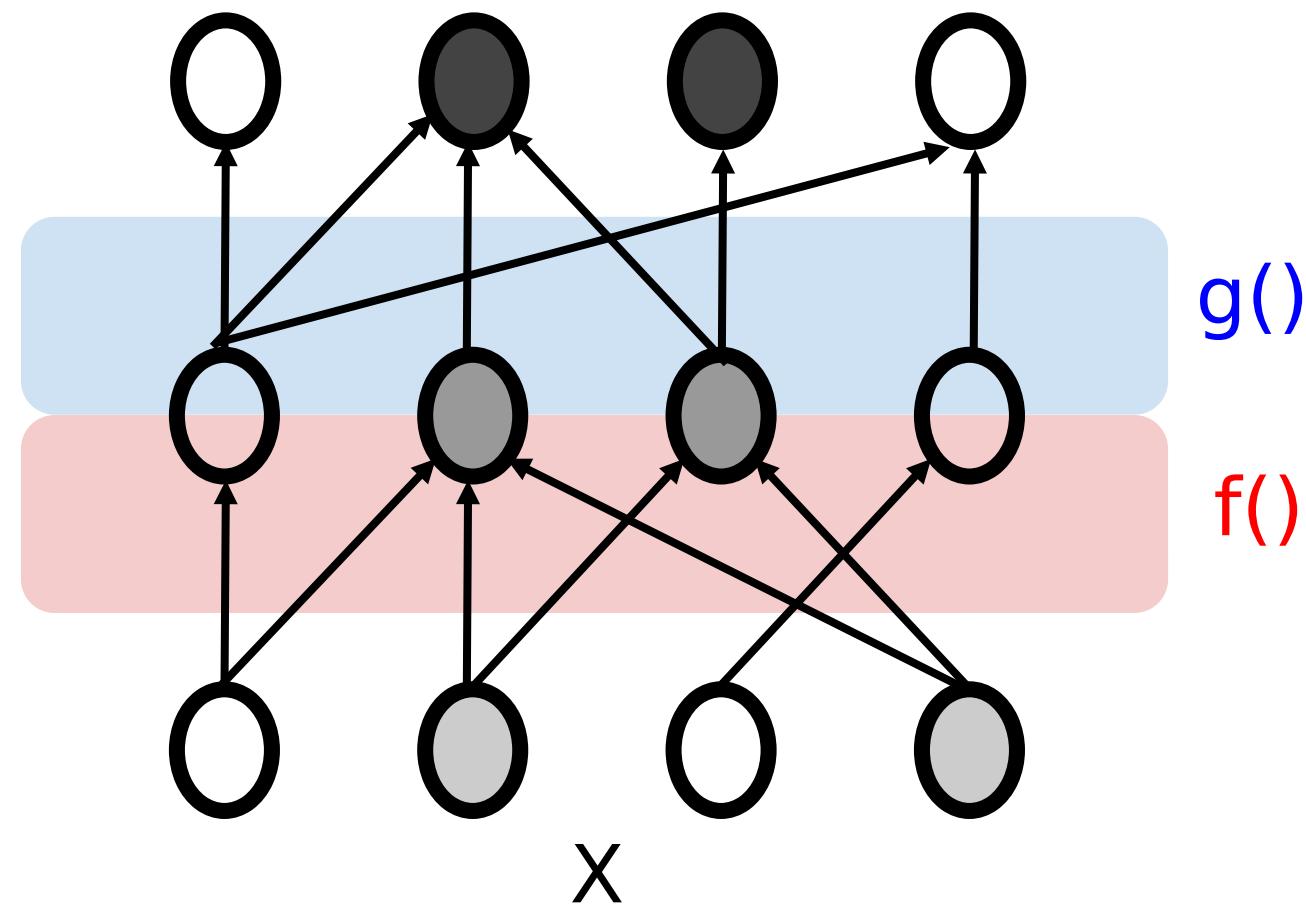


- E
- E + I

# Algorithm: 基本計算的組合

一個神經網路透過組合基本的計算來實現演算法

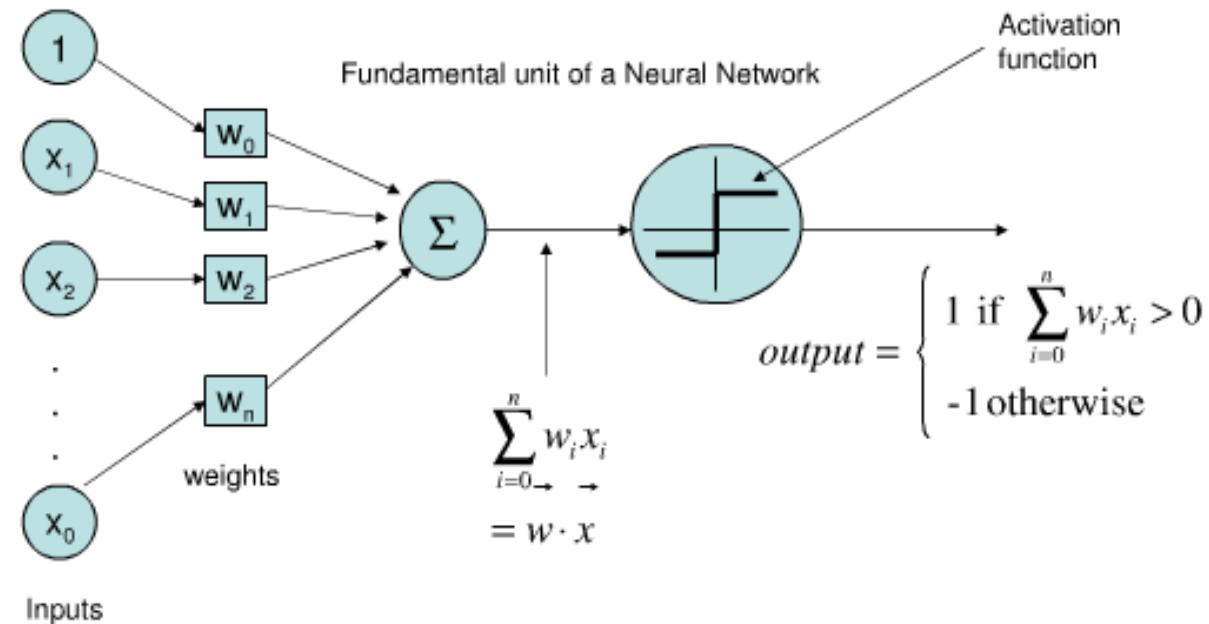
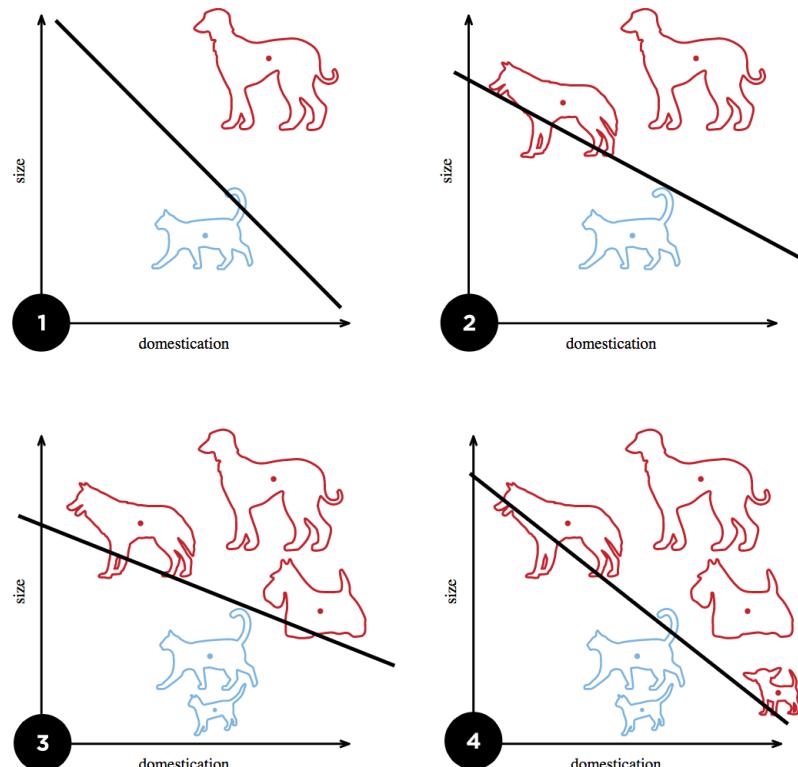
$$Y = g(f(X))$$



# Computational Problem: 區分貓狗

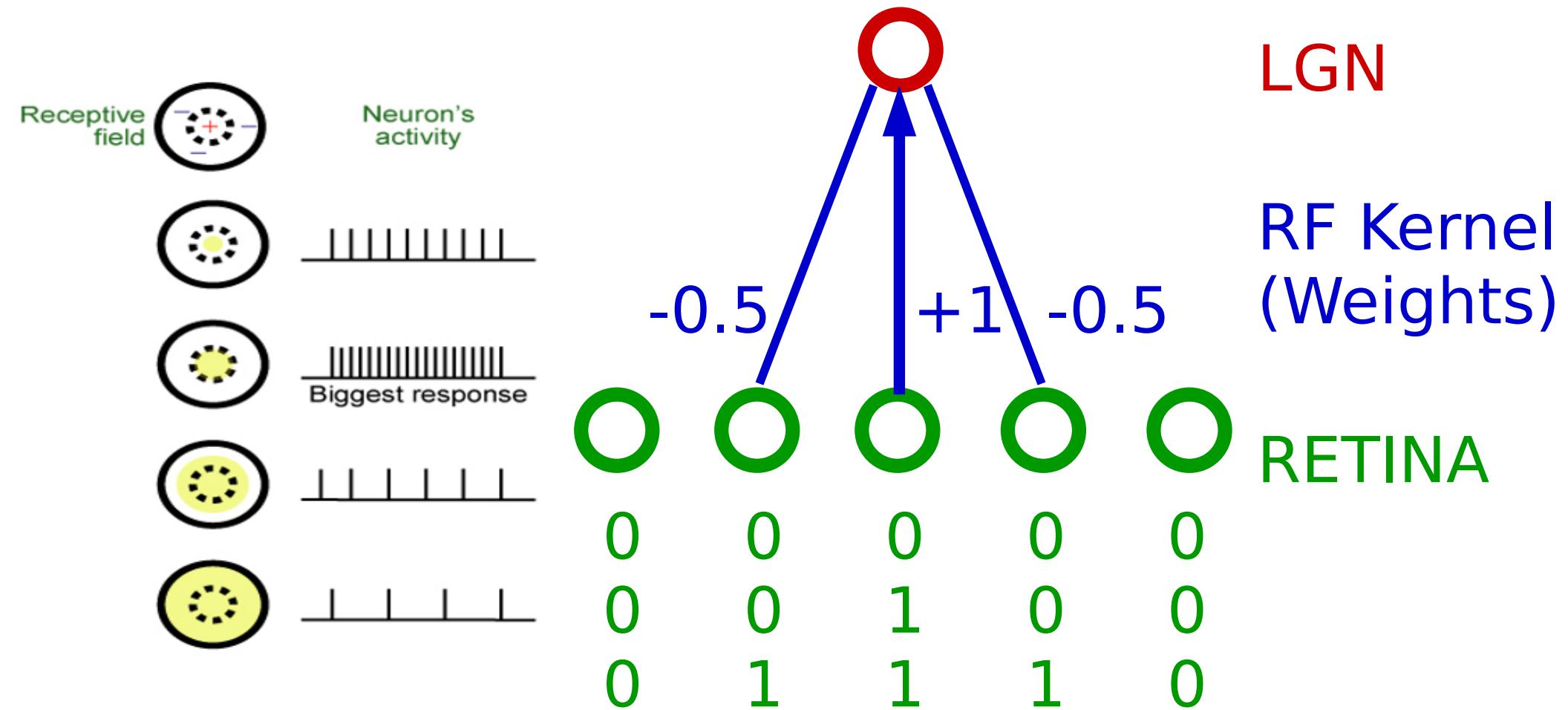
Perceptron (Rosenblatt, 1958)  
Cognitron (Fukushima, 1975)

$$y > ax + b \Rightarrow y - ax - b > 0 \Rightarrow w_2 x_2 + w_1 x_1 + w_0 1 > 0$$



$$y < ax + b \Rightarrow y - ax - b < 0 \Rightarrow w_2 x_2 + w_1 x_1 + w_0 1 < 0$$

# Neuron as a Pattern Recognizer



```
RETINA=matrix('0 0 0 0 0;0 0 1 0 0;0 1 1 1 0')
```

```
LGN_RF=matrix('0;-0.5;1;-0.5;0')
```

```
LGN_RESPONSE=RETINA*LGN_RF
```

# Neural Computation

## Overview of Learning

### Unsupervised Learning

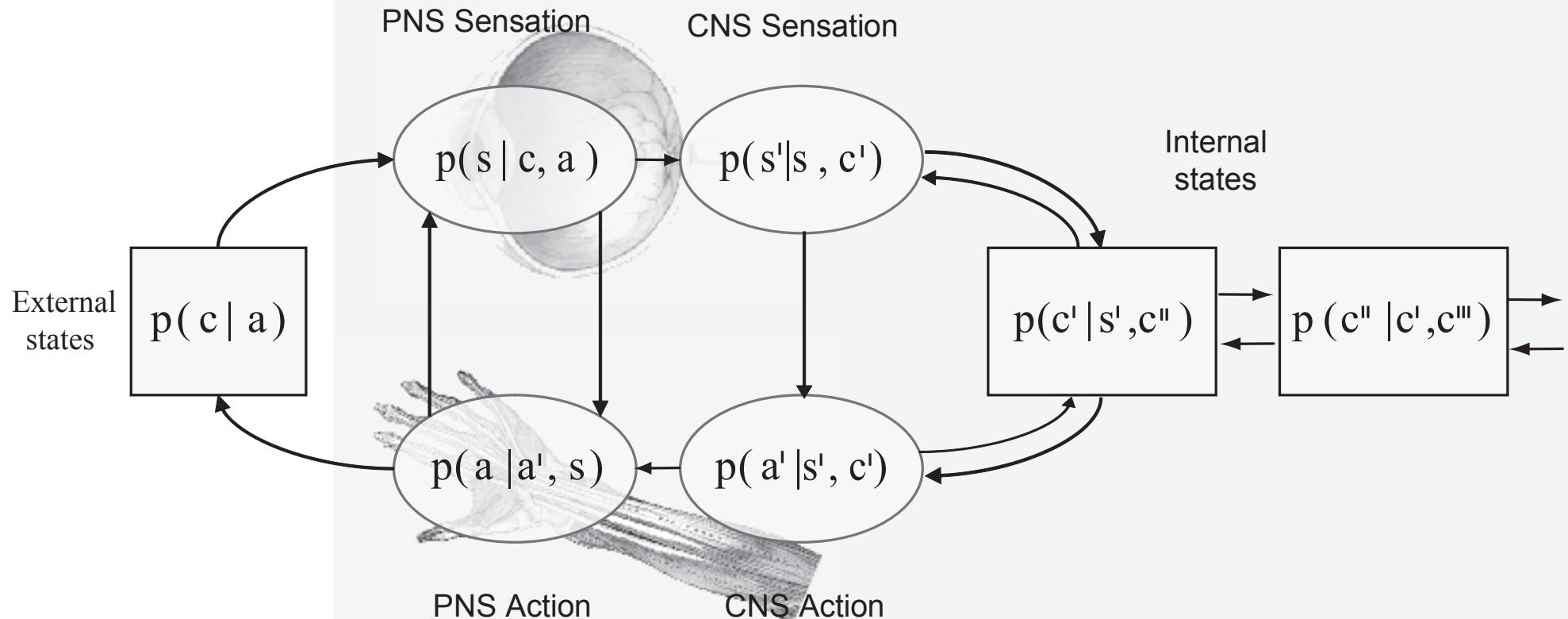
### Supervised Learning (1/2)

# 學習 / 記憶的目的：預測與控制

學習和演化的目的都是更適應環境

Environment

Agent



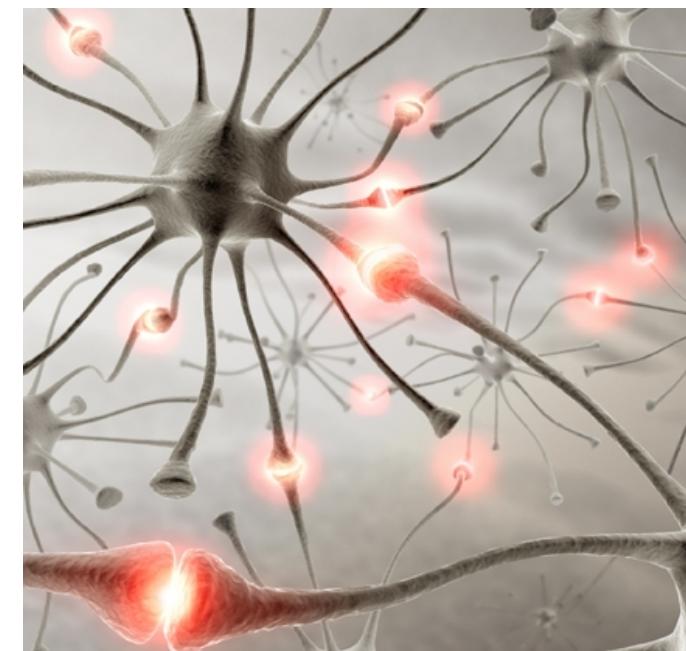
# 學習中的兩難 (Dilemma)



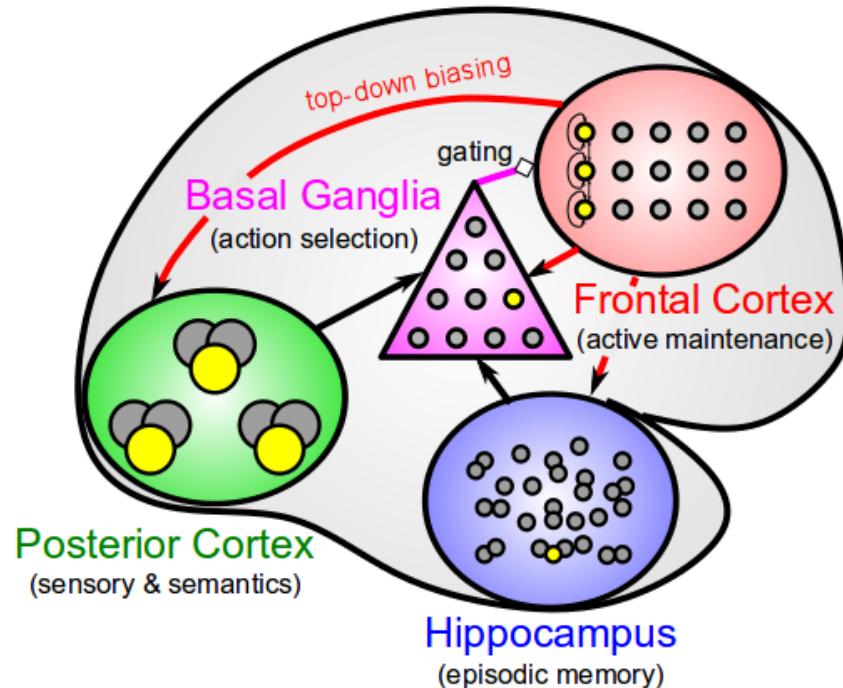
**Learning vs. Performance**  
行為上，正在學習一件事時表現通常不好，表現好時表示其實已相當熟練沒學到什麼。

## Stability vs. Plasticity

大腦中，神經結構的變化雖可幫助學習新事物，但這些結構上的改變也意味著對舊事物的遺忘。



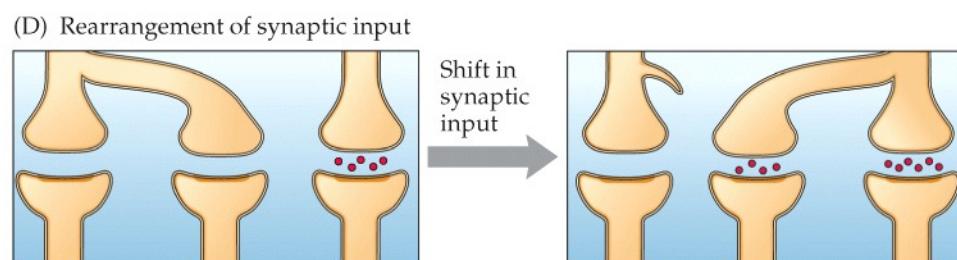
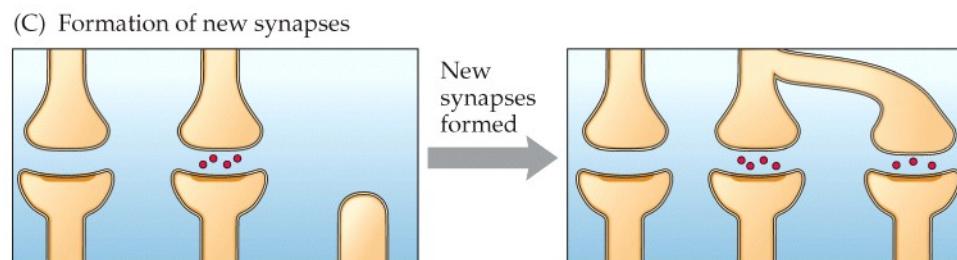
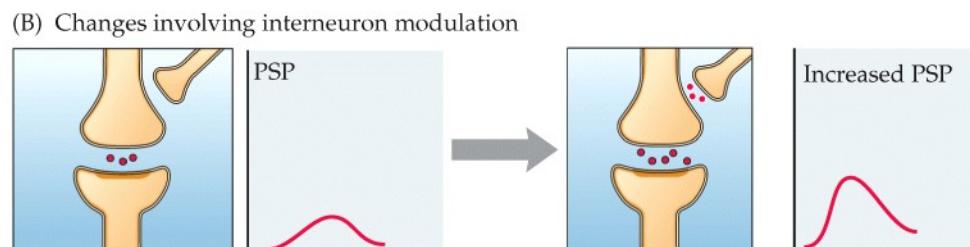
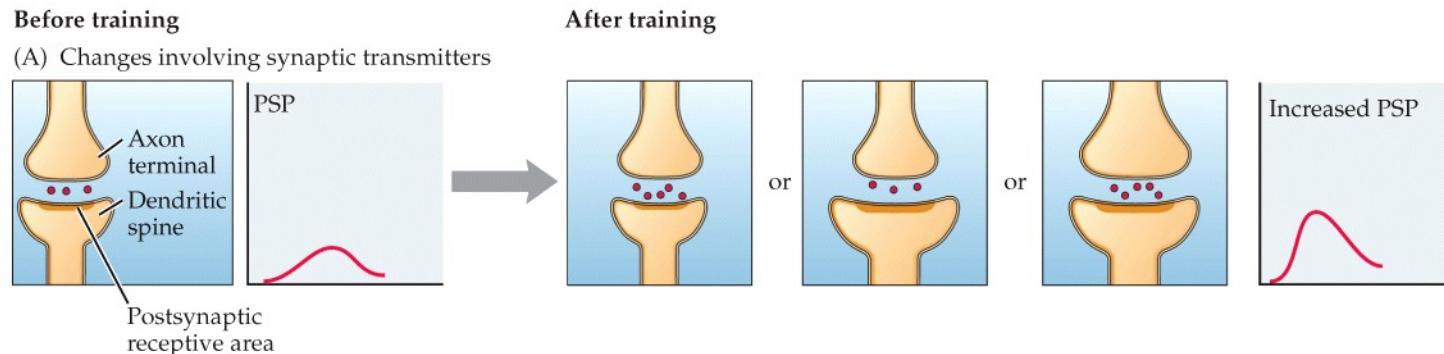
# 不同腦區的計算 / 學習性質



| Area                 | Learning Signal |       |          | Dynamics  |            |           |
|----------------------|-----------------|-------|----------|-----------|------------|-----------|
|                      | Reward          | Error | Self Org | Separator | Integrator | Attractor |
| <b>Basal Ganglia</b> | +++             | ---   | ---      | ++        | -          | ---       |
| <b>Cerebellum</b>    | ---             | +++   | ---      | +++       | ---        | ---       |
| <b>Hippocampus</b>   | +               | +     | +++      | +++       | ---        | +++       |
| <b>Neocortex</b>     | ++              | +++   | ++       | ---       | +++        | +++       |

# 突觸連結變強的生物機制

雖有不同機制但數學上都是  $\Delta W_{ij}$  變大



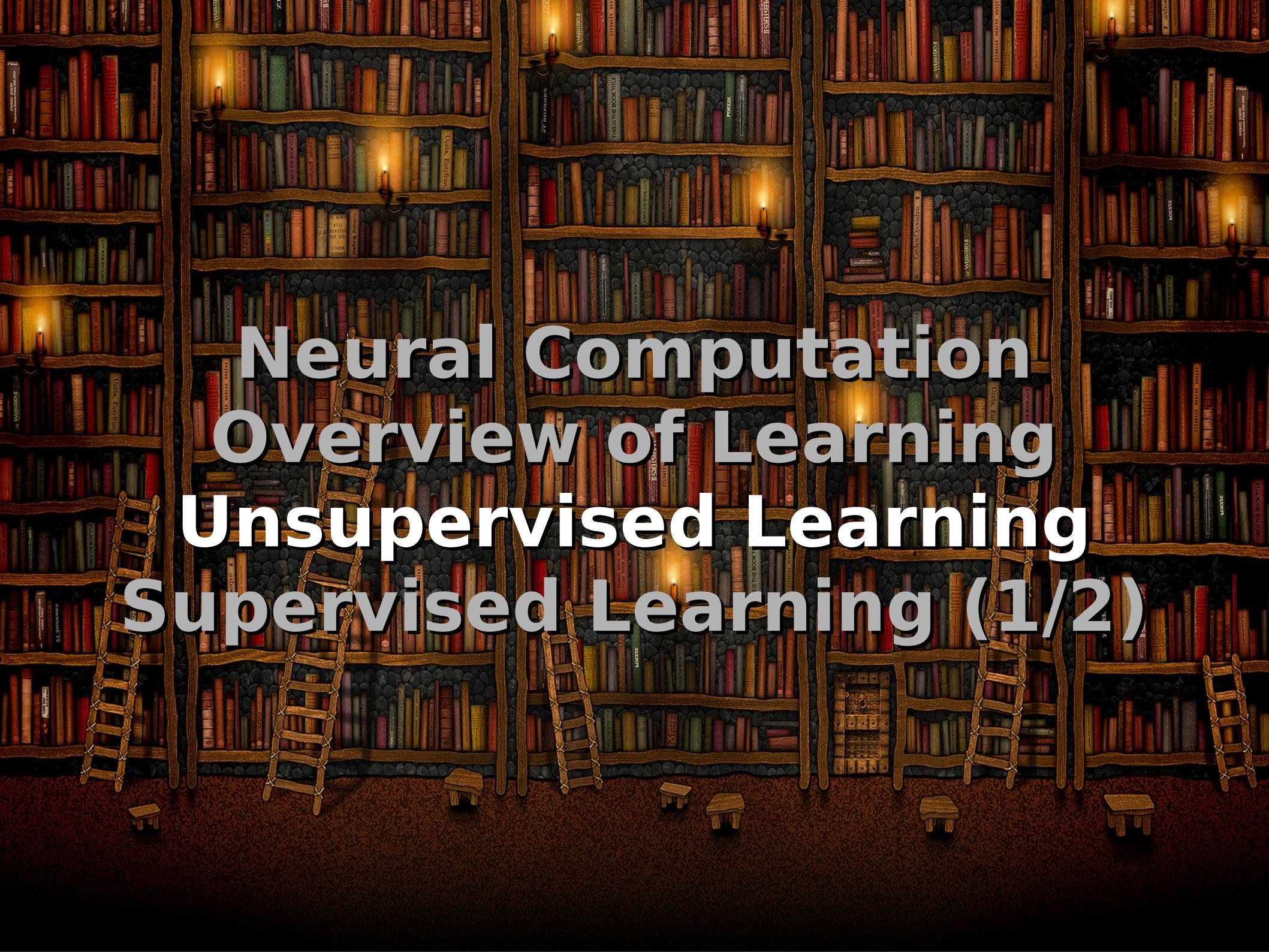
# 人與機器的歸納學習

皆有以下三種情境

非監督式學習：事物沒有標籤（對錯或名字）  
小孩發現有些生物會動，有些不會動

監督式學習：事物有明確標籤或該怎麼做  
爸媽教小孩會動的叫動物，不會動的叫植物

強化式學習：只知道特定事件後會有賞罰  
小孩發現打動物會被咬，打植物卻沒事



# Neural Computation

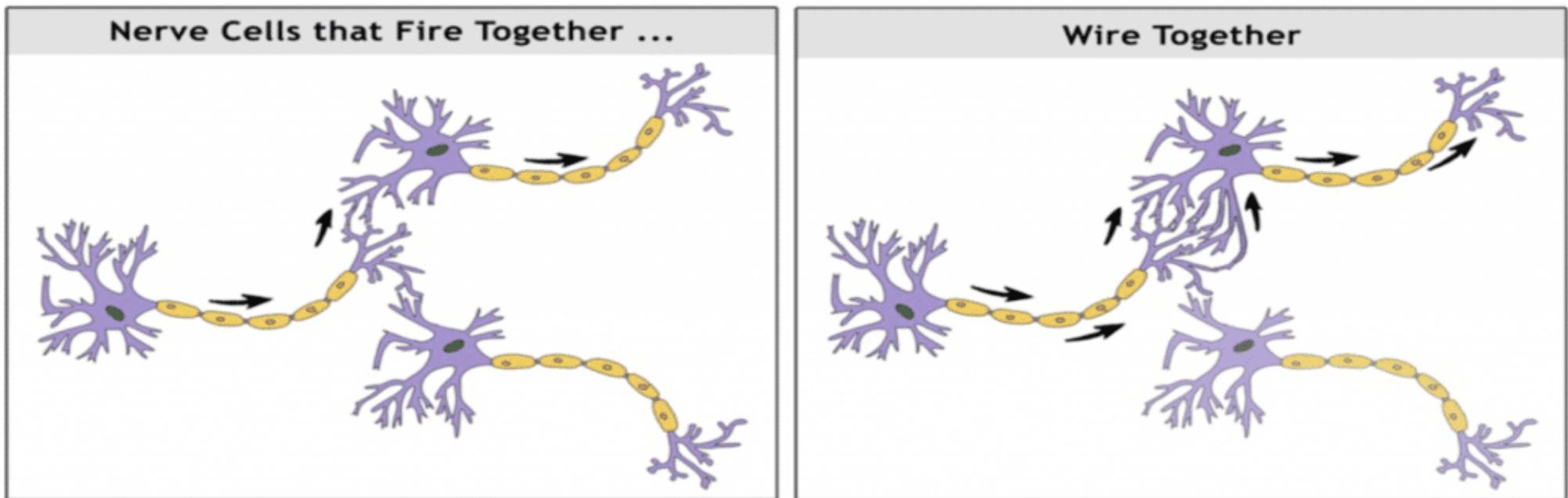
## Overview of Learning

### Unsupervised Learning

### Supervised Learning (1/2)

# Hebbian Learning Rule

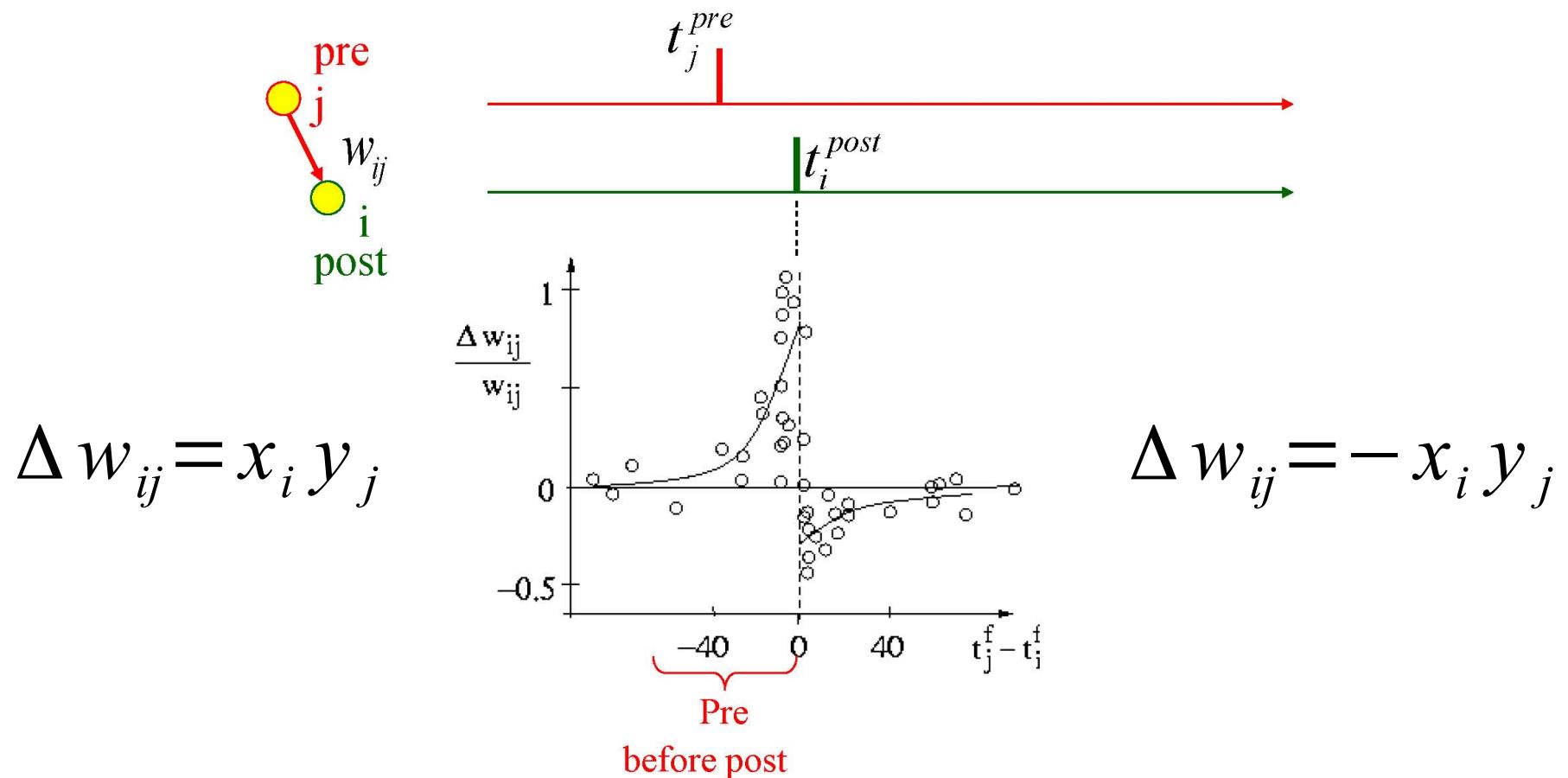
$$w_{ij}^{new} = w_{ij}^{old} + x_i y_j \Rightarrow \Delta w_{ij} = x_i y_j$$



但一神經連接一直強化到後來會不會爆掉？

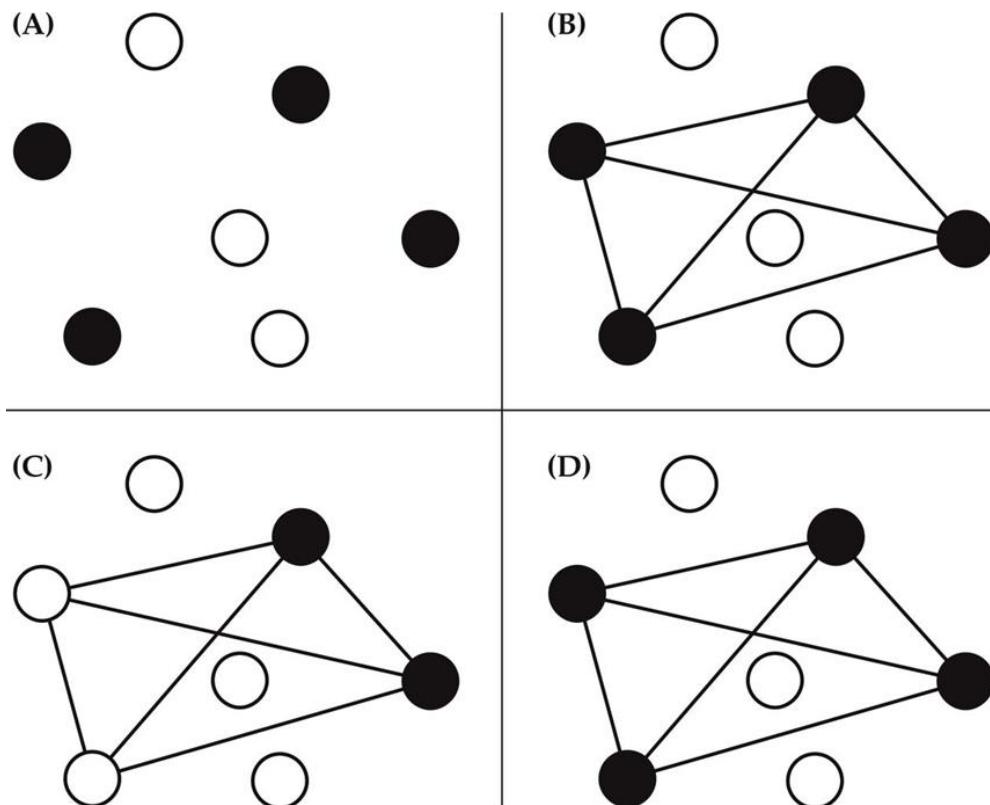
# Hebbian vs. Anti-Hebbian

生物上發現 Spike Timing Dependent Plasticity (STDP) 中兩者並存：



# Hopfield Network

學習時是 Hebbian + Anti-Hebbian Rules  
回想時是透過證據彼此間的正 / 負相關來投票



Memorize:

$$w_{ij} = \frac{1}{n} \sum_{p=1}^n \Delta w_{ij} = \frac{1}{n} \sum_{p=1}^n x_i^p x_j^p$$

Cued Recall:

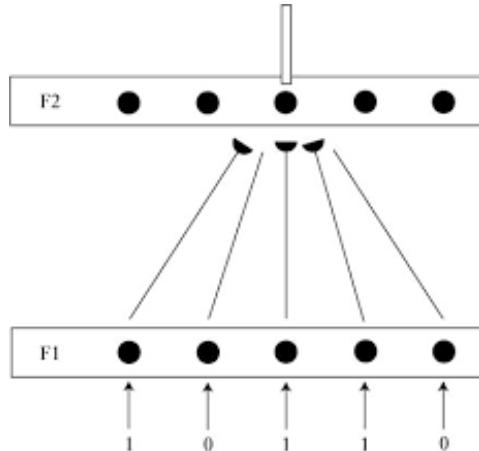
$$x_i = \begin{cases} +1, & \sum_j w_{ij} x_j \geq \theta_i \\ -1, & \text{otherwise} \end{cases}$$

特徵似 hippocampus 的 auto-associative memory

# InStar Learning

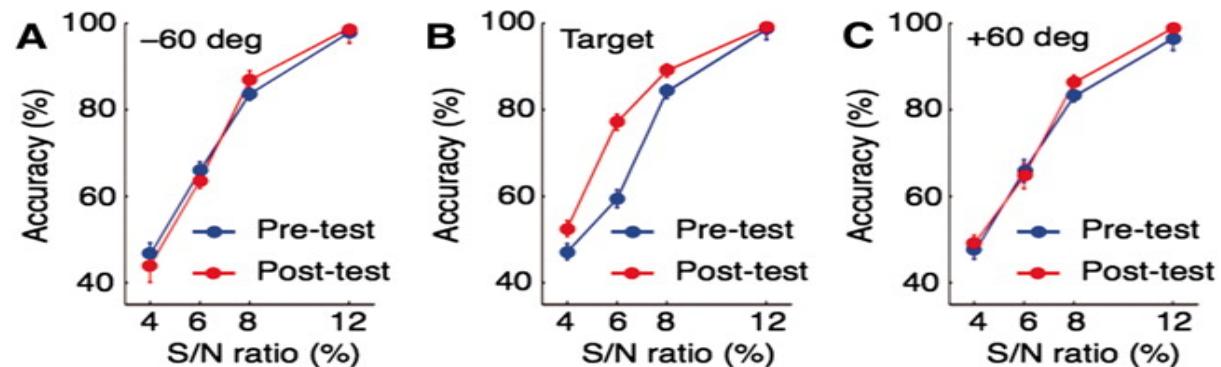
InStar: 突觸後神經元學習辨認突觸前的樣式

Post:



Pre:

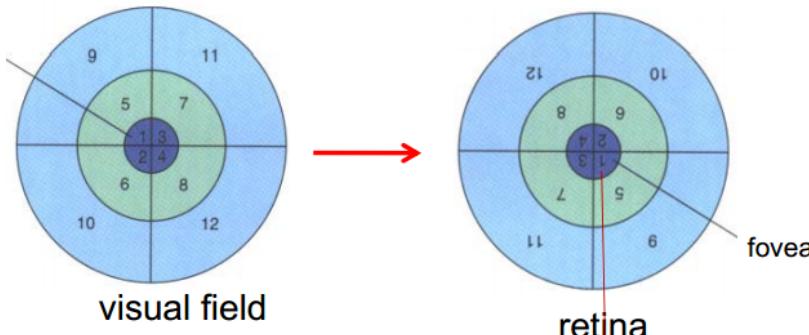
$$\Delta \vec{W}_j^{1 \rightarrow 2} = y_j (\vec{x} - \vec{w}_j^{1 \rightarrow 2})$$



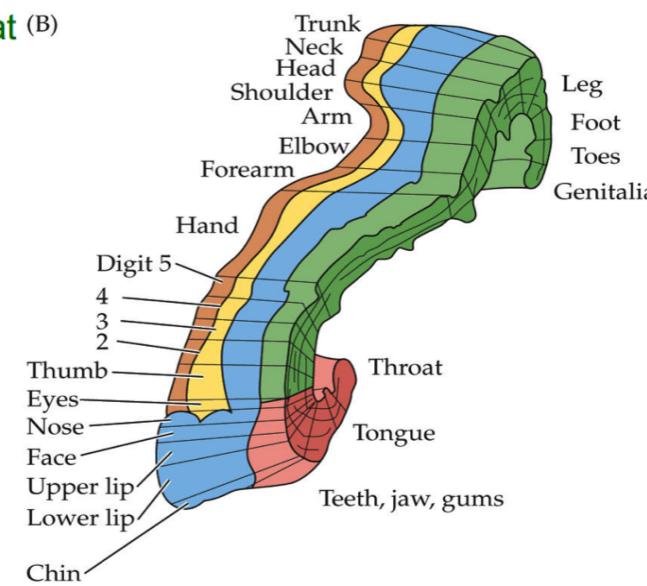
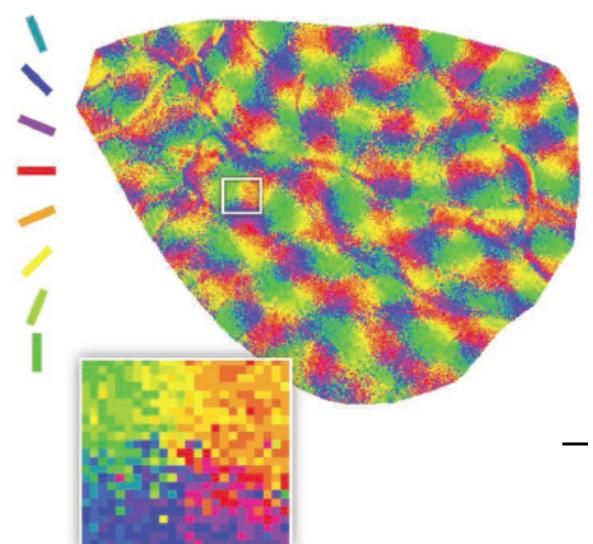
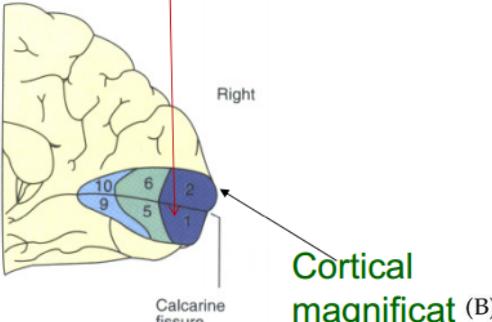
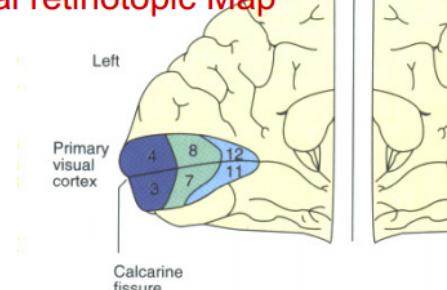
```
W=random.rand(3) # random initial weights  
for i in range(10): # 10 trials  
    x=array([0,1,0])+0.1*random.rand(3)#same S.+noise  
    y=dot(W,x) # the only postsynaptic neuron  
    W=W+y*(x-W) # postsynaptically gated InStar  
    print(W,y)
```

# Topological Maps in the Brain

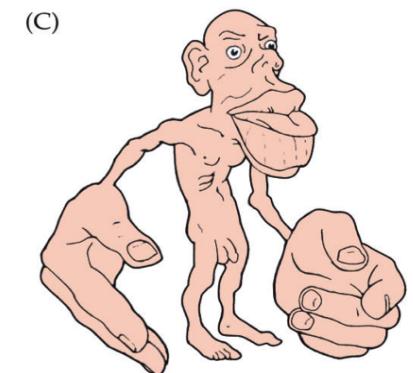
Tonotopic Map Has Columnar Organization



Cortical retinotopic Map



|                                     |   |         |
|-------------------------------------|---|---------|
| Primary somatosensory cortex (S1)   | { | Area 1  |
|                                     |   | Area 2  |
|                                     |   | Area 3a |
| Secondary somatosensory cortex (S2) |   | Area 3b |

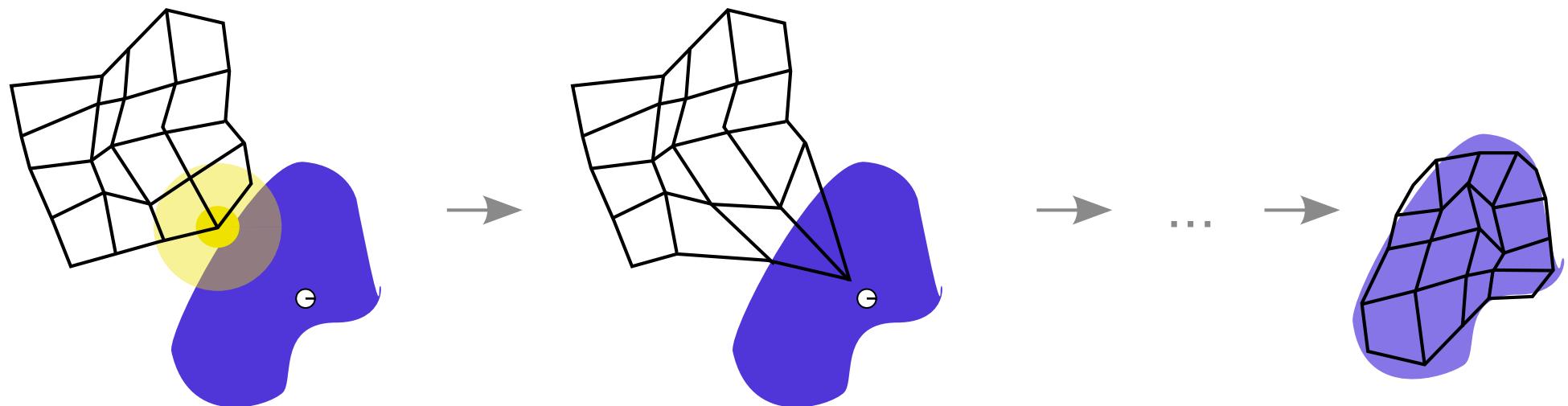


# Self-Organizing Map

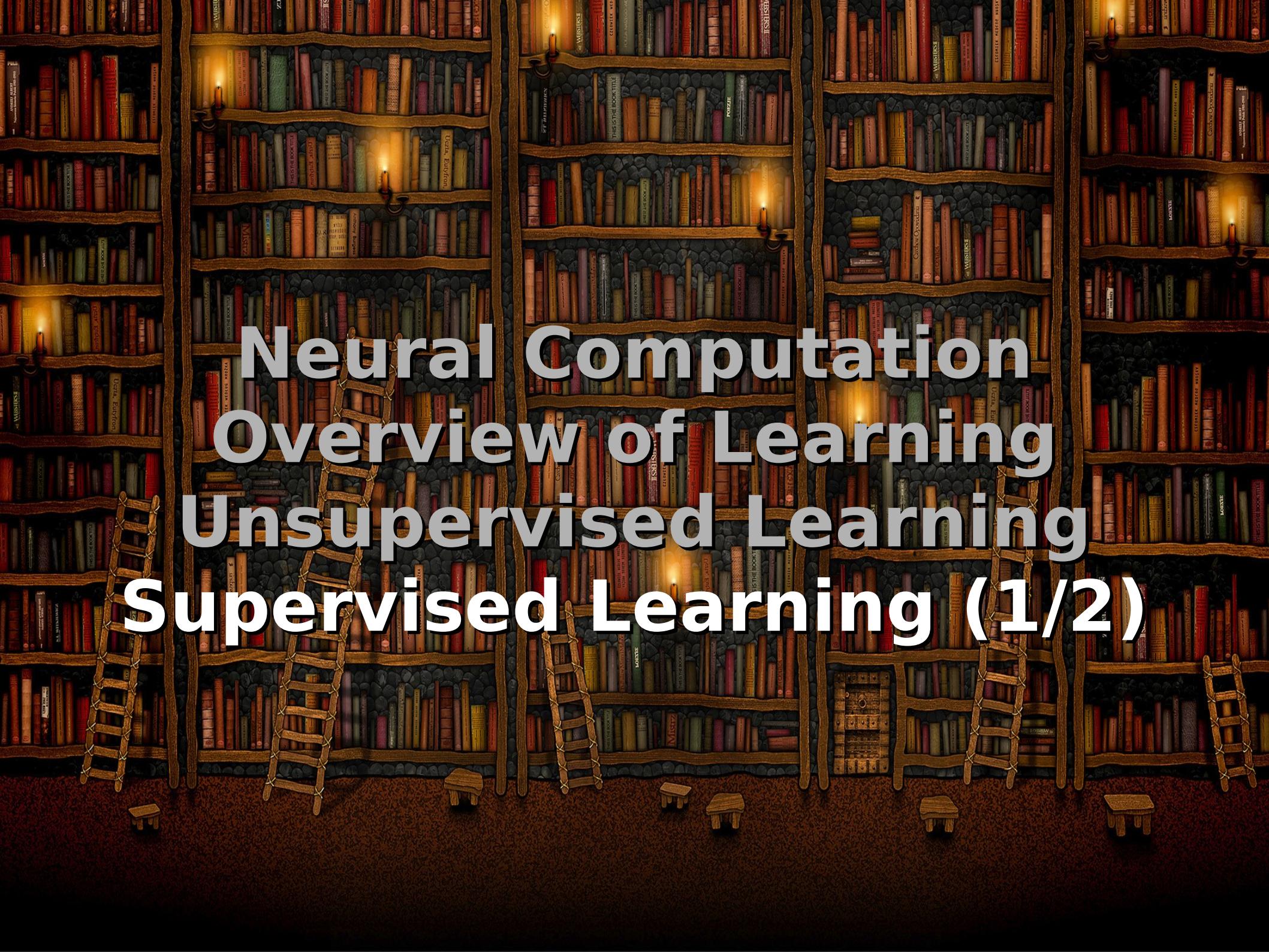
只是 InStar 的變形：每次學習的是一個贏者  $y_i$  的近鄰

$$\Delta \vec{w}_i = N(y_j, y_i)(\vec{x} - \vec{w}_i)$$

N 是某種 neighborhood function (如常態分佈)



學辨認刺激但保留神經元間的拓撲關係 (V1/A1/SMC)



# Neural Computation

## Overview of Learning

### Unsupervised Learning

### Supervised Learning (1/2)

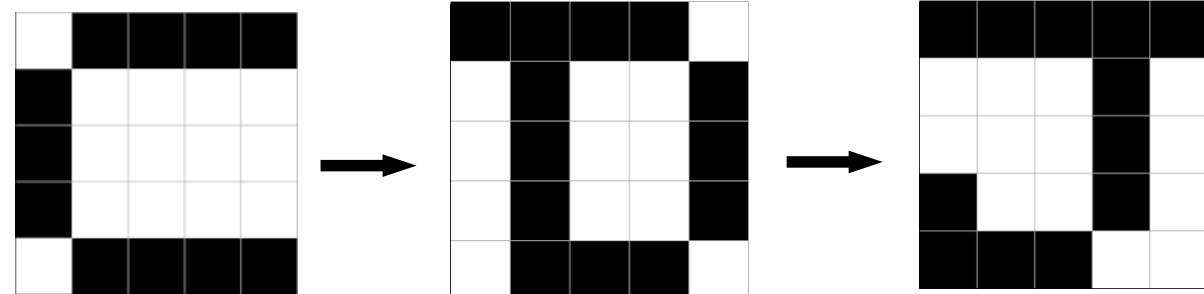
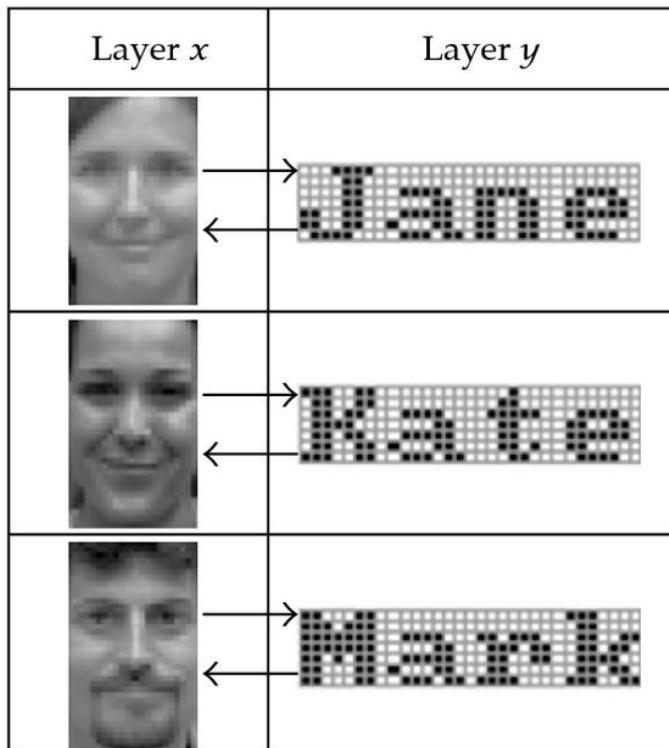
# Supervised Hebbian Learning

精神和 Unsupervised Hebbian Learning 一樣：

$$\Delta w_{ij} = x_i y_j$$

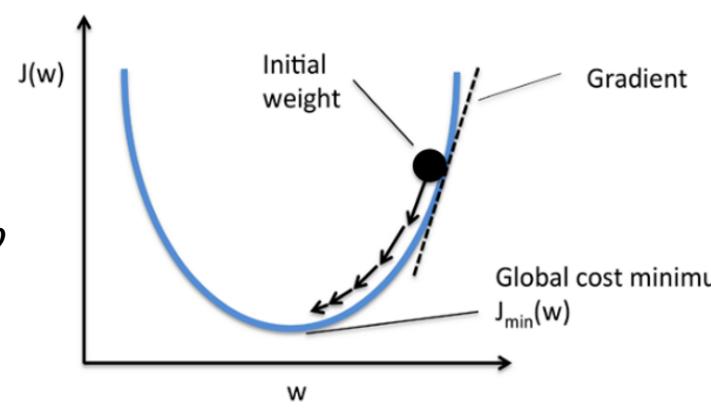
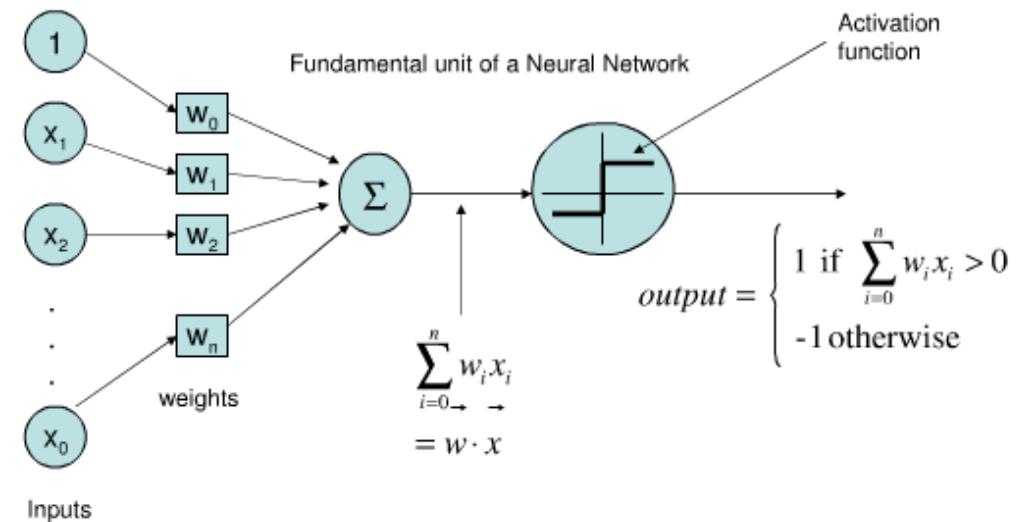
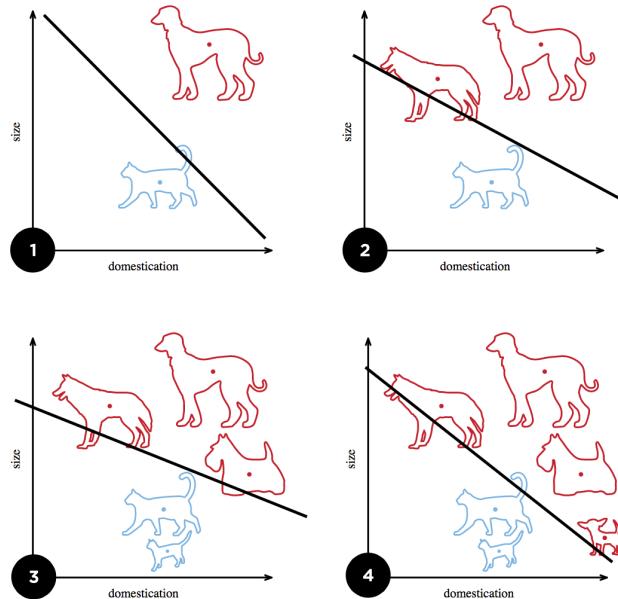
$$w_{ij} = \frac{1}{n} \sum_{p=1}^n \Delta w_{ij} = \sum_{p=1}^n x_i^p y_j^p$$

Hopfield 網路可改為 Hetero-associative Memory  
來連結不同本質 / 維度的 x 與 y 或產生 x 的序列



# Perceptron: 分類

學習規則通常由 gradient descent 推導而來



$$E = - \sum_p (W X^p) Y^p$$

$$W^{new} = W^{old} + \Delta W = W^{old} - \partial E(W) / \partial W = W^{old} + \sum_p \underline{X^p Y^p}$$

這不就是 Supervised Hebbian 嗎 !?

# Game Over

