Agreement: This assignment represents my own work. I did not work on this assignment with others. All coding was done by myself.

Q1

(a)

Soft decision tree routes a sample through both children, each of whom has a specific probability weight, by calculating the probability of picking each branch at a decision node. In contrast, there is no probability involved in the routing process in a **hard decision tree** because each decision node generates a strict binary split based on a predetermined feature threshold.

Advantages (Soft): Firstly, the soft decision tree is differentiable and back-propagation compatible. Secondly, the probabilistic nature allows for smoother decision boundaries.

Advantages (Hard): Hard decision trees are easier to interpret since only the nodes along a path account for the ultimate prediction.

(b)

Roll out the recursive definition:

$$traverse(P_1, \mathbf{z}_i) = sim(P_1, \mathbf{z}_i)c_3 + (1 - sim(P_1, \mathbf{z}_i))traverse(P_2, \mathbf{z}_i)$$

$$traverse(P_2, \mathbf{z}_i) = sim(P_2, \mathbf{z}_i)c_2 + (1 - sim(P_2, \mathbf{z}_i))c_1$$

Therefore, the vector of class logits is computed as:

$$f(\mathbf{z}_i) = sim(\mathbf{P}_1, \mathbf{z}_i)c_3 + \left(1 - sim(\mathbf{P}_1, \mathbf{z}_i)\right)\left(sim(\mathbf{P}_2, \mathbf{z}_i)c_2 + \left(1 - sim(\mathbf{P}_2, \mathbf{z}_i)\right)c_1\right)$$

$$f(\mathbf{z}_i) = e^{-\|\mathbf{z}_i - P_1\|} c_3 + (1 - e^{-\|\mathbf{z}_i - P_1\|}) (e^{-\|\mathbf{z}_i - P_2\|} c_2 + (1 - e^{-\|\mathbf{z}_i - P_2\|}) c_1)$$

Where z_i is the minimizer over all prototypes, $P_{j\in 1,2}$ is the prototype of each non-leaf node, and $c_{k\in 1,2,3}$ is the classification vector for each leaf.

(c)

According to the paper, the ground-truth label y_i is one-hot encoded, therefore, in this case, the loss can be written as:

$$\ell(\mathbf{y}_{i}, \widehat{\mathbf{y}}_{i}) = -y_{i,a} \log (\widehat{y}_{i,a})$$

Therefore,

$$\frac{\partial \ell}{\partial \hat{y}_{i,a}} = -y_{i,a} \frac{1}{\hat{y}_{i,a}} = -\frac{y_{i,a}}{\hat{y}_{i,a}} \tag{1}$$

From **(b)**, we know that:

$$\hat{y}_i = e^{-\parallel z_i - P_1 \parallel} c_3 + \left(1 - e^{-\parallel z_i - P_1 \parallel}\right) \left(e^{-\parallel z_i - P_2 \parallel} c_2 + \left(1 - e^{-\parallel z_i - P_2 \parallel}\right) c_1\right)$$

Therefore,

$$\hat{y}_{i,a} = e^{-\parallel z_i - P_1 \parallel} c_{3,a} + \left(1 - e^{-\parallel z_i - P_1 \parallel}\right) \left(e^{-\parallel z_i - P_2 \parallel} c_{2,a} + \left(1 - e^{-\parallel z_i - P_2 \parallel}\right) c_{1,a}\right)$$

Where $c_{1,a}, c_{2,a}, c_{3,a}$ represent the term related to class a in vector c_1, c_2, c_3 respectively.

Let $h = ||\mathbf{z}_i - P_1||$, therefore,

$$\hat{y}_{i,a} = e^{-h} c_{3,a} + (1 - e^{-h}) \left(e^{-\parallel \mathbf{z_i} - \mathbf{P_2} \parallel} c_{2,a} + \left(1 - e^{-\parallel \mathbf{z_i} - \mathbf{P_2} \parallel} \right) c_{1,a} \right)$$

Then we can derive:

$$\frac{\partial \hat{y}_{i,a}}{\partial h} = -e^{-h}c_{3,a} + e^{-h} \left(e^{-\|\mathbf{z}_i - \mathbf{P}_2\|} c_{2,a} + \left(1 - e^{-\|\mathbf{z}_i - \mathbf{P}_2\|} \right) c_{1,a} \right)$$
(2)

Now look at *h*:

$$h = ||\mathbf{z_i} - \mathbf{P_1}|| = \sqrt{\sum_k (z_i^{(k)} - p_1^{(k)})^2}$$

Therefore,

$$\frac{\partial h}{\partial p_1^{(k)}} = \frac{1}{2\sqrt{\sum_k \left(z_i^{(k)} - p_1^{(k)}\right)^2}} 2\left(z_i^{(k)} - p_1^{(k)}\right) (-1) = \frac{p_1^{(k)} - z_i^{(k)}}{\sqrt{\sum_k \left(z_i^{(k)} - p_1^{(k)}\right)^2}}$$
(3)

By multiplying (1) (2) (3) together, the partial derivative $\frac{\partial \ell}{\partial p_1^{(k)}}$ can be derived as:

$$\begin{split} \frac{\partial \ell}{\partial p_1^{(k)}} &= \frac{\partial \ell}{\partial \hat{y}_{i,a}} \frac{\partial \hat{y}_{i,a}}{\partial h} \frac{\partial h}{\partial p_1^{(k)}} \\ \frac{\partial \ell}{\partial p_1^{(k)}} &= -\frac{y_{i,a}}{\hat{y}_{i,a}} \left(-e^{-h} c_{3,a} + e^{-h} \left(e^{-\parallel z_i - P_2 \parallel} c_{2,a} + \left(1 - e^{-\parallel z_i - P_2 \parallel} \right) c_{1,a} \right) \right) \frac{p_1^{(k)} - z_i^{(k)}}{\sqrt{\sum_k \left(z_i^{(k)} - p_1^{(k)} \right)^2}} \end{split}$$

Because
$$h = ||\mathbf{z_i} - \mathbf{P_1}|| = \sqrt{\sum_k (z_i^{(k)} - p_1^{(k)})^2}$$
,

$$\frac{\partial \ell}{\partial p_1^{(k)}} = \frac{-y_{i,a}}{\hat{y}_{i,a}} \Big(-e^{-\parallel \mathbf{z_i} - \mathbf{P_1} \parallel} c_{3,a} + e^{-\parallel \mathbf{z_i} - \mathbf{P_1} \parallel} \Big(e^{-\parallel \mathbf{z_i} - \mathbf{P_2} \parallel} c_{2,a} + \Big(1 - e^{-\parallel \mathbf{z_i} - \mathbf{P_2} \parallel} \Big) c_{1,a} \Big) \Big) \frac{p_1^{(k)} - z_i^{(k)}}{\parallel \mathbf{z_i} - \mathbf{P_1} \parallel}$$

(d)

Each prototype P_n is replaced with its nearest latent patch present in the training data \tilde{z}_n^* by using the equation below:

$$P_{\rm n} \leftarrow \tilde{z}_n^*$$
, $\tilde{z}_n^* = \operatorname{argmin} \|\tilde{z}^* - P_{\rm n}\|$

Then, the prototype P_n can be visualized as a patch of training image corresponding to \tilde{z}_n^* .

$HW5_Q2$

October 30, 2023

```
[1]: # import necessary dependencies
     import argparse
     import os, sys
     import time
     import datetimek
     from tqdm import tqdm_notebook as tqdm
     import numpy as np
     import torch
     import torch.nn as nn
     import torch.nn.functional as F
     import torch.nn as nn
     import torch.optim as optim
     import matplotlib.pyplot as plt
     import random
[2]: def set_all_seeds(RANDOM_SEED):
        random.seed(RANDOM SEED)
                                      # python random generator
        np.random.seed(RANDOM_SEED) # numpy random generator
        torch.manual_seed(RANDOM_SEED)
        torch.cuda.manual_seed_all(RANDOM_SEED)
        torch.backends.cudnn.deterministic = True
        torch.backends.cudnn.benchmark = False
     set_all_seeds(42)
[3]: class SimpleCIFAR10Classifier(nn.Module):
        def __init__(self):
             super(SimpleCIFAR10Classifier, self).__init__()
             self.conv1 = nn.Conv2d(3, 8, 5)
             self.conv2 = nn.Conv2d(8, 16, 3)
             self.fc1 = nn.Linear(16*6*6, 120)
             self.fc2 = nn.Linear(120, 84)
             self.fc3 = nn.Linear(84, 10)
```

```
def forward(self, x):
    out = F.relu(self.conv1(x))
    out = F.max_pool2d(out, 2)
    out = F.relu(self.conv2(out))
    out = F.max_pool2d(out, 2)
    out = out.view(out.size(0), -1)
    out = F.relu(self.fc1(out))
    out = F.relu(self.fc2(out))
    out = self.fc3(out)
    return out
```

```
[4]: # useful libraries
     import torchvision
     import torchvision.transforms as transforms
     from torch.utils.data import DataLoader
     transform = transforms.Compose(
         [transforms.ToTensor(),
         transforms.Normalize((0.5, 0.5, 0.5), (0.5, 0.5, 0.5))])
     ##################
     # YOUR CODE HERE #
     ##################
     # adjust batch size to your need
     batch_size = 64
     trainset = torchvision.datasets.CIFAR10(root='./data', train=True,
                                             download=True, transform=transform)
     train_loader = torch.utils.data.DataLoader(trainset, batch_size=batch_size,
                                               shuffle=True, num_workers=2)
     testset = torchvision.datasets.CIFAR10(root='./data', train=False,
                                            download=True, transform=transform)
     val_size = int(0.5 * len(testset))
     test_size = len(testset) - val_size
     valset, testset = torch.utils.data.random_split(testset, [val_size, test_size])
     val_loader = torch.utils.data.DataLoader(valset, batch_size=batch_size,
                                              shuffle=False, num workers=2)
     test_loader = torch.utils.data.DataLoader(testset, batch_size=batch_size,
                                              shuffle=False, num_workers=2)
```

```
print(len(trainset), len(valset), len(testset))
```

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1 (a)

```
[5]: net = SimpleCIFAR10Classifier().cuda()
     INITIAL LR = 0.01
     MOMENTUM = 0.9
     criterion = nn.CrossEntropyLoss()
     optimizer = optim.SGD(net.parameters(), lr=INITIAL_LR, momentum=MOMENTUM)
     EPOCHS = 30
     CHECKPOINT_FOLDER = "./saved_model"
     best_val_acc = 0
     # Training Loop
     train_losses = []
     val losses = []
     for i in range(0, EPOCHS):
        net.train()
        print("Epoch %d:" %i)
        total examples = 0
         correct_examples = 0
         # Record training loss
        train_loss = 0
         # Looping through training loader
         for batch_idx, (inputs, targets) in enumerate(train_loader):
             ##################
             # YOUR CODE HERE #
             ###################
             # Send input and target to device
             inputs, targets = inputs.cuda(), targets.cuda()
             # compute the model output logits and training loss
             outputs = net(inputs)
             loss = criterion(outputs, targets)
             # back propogation & optimizer update parametes
             optimizer.zero_grad()
             loss.backward()
```

```
optimizer.step()
       # calculate predictions
       _, predictions = torch.max(outputs, 1)
      correct_examples += (predictions == targets).sum().item()
      total examples += inputs.shape[0]
      train loss += loss.cpu().detach().numpy()
  # calculate average training loss and accuracy
  avg_loss = train_loss / len(train_loader)
  avg acc = correct examples / total examples
  print("Training loss: %.4f, Training accuracy: %.4f" %(avg_loss, avg_acc))
  train losses.append(avg loss)
  # Evaluate the validation set performance
  net.eval()
  total_examples = 0
  correct_examples = 0
  # Record validation loss
  val loss = 0
  # disable gradient during validation, which can save GPU memory
  with torch.no grad():
      for batch_idx, (inputs, targets) in enumerate(val_loader):
           ##################
           # YOUR CODE HERE #
           ###################
           # Send input and target to device
           inputs, targets = inputs.cuda(), targets.cuda()
           # compute the model output logits and training loss
          outputs = net(inputs)
           loss = criterion(outputs, targets)
           # count the number of correctly predicted samples in the current_
\rightarrow ba.t.ch
           _, predictions = torch.max(outputs, 1)
           correct_examples += (predictions == targets).sum().item()
          total_examples += inputs.shape[0]
          val_loss += loss.cpu().detach().numpy()
  # calculate average validation loss and accuracy
  avg_loss = val_loss / len(val_loader)
  avg_acc = correct_examples / total_examples
  print("Validation loss: %.4f, Validation accuracy: %.4f" % (avg_loss,
→avg acc))
```

```
val_losses.append(avg_loss)
    # save the model checkpoint
    current_learning_rate = optimizer.state_dict()['param_groups'][0]['lr']
    if avg_acc > best_val_acc:
        best_val_acc = avg_acc
        if not os.path.exists(CHECKPOINT FOLDER):
            os.makedirs(CHECKPOINT_FOLDER)
        print("Saving ...")
         state = {'state_dict': net.state_dict(),
                 'epoch': i,
                 'lr': current learning rate}
        torch.save(state, os.path.join(CHECKPOINT_FOLDER, 'best_model.bin'))
    print('')
print(f"Best validation accuracy: {best_val_acc:.4f}")
Epoch 0:
Training loss: 1.8587, Training accuracy: 0.3090
Validation loss: 1.5058, Validation accuracy: 0.4594
Saving ...
Epoch 1:
Training loss: 1.3745, Training accuracy: 0.5023
Validation loss: 1.3045, Validation accuracy: 0.5366
Saving ...
Epoch 2:
Training loss: 1.1939, Training accuracy: 0.5760
Validation loss: 1.1641, Validation accuracy: 0.5888
Saving ...
Epoch 3:
Training loss: 1.0741, Training accuracy: 0.6174
Validation loss: 1.1005, Validation accuracy: 0.6140
Saving ...
Epoch 4:
Training loss: 0.9947, Training accuracy: 0.6489
Validation loss: 1.0457, Validation accuracy: 0.6350
Saving ...
Epoch 5:
Training loss: 0.9217, Training accuracy: 0.6745
Validation loss: 1.0606, Validation accuracy: 0.6342
```

Epoch 6:

Training loss: 0.8584, Training accuracy: 0.6966 Validation loss: 1.0272, Validation accuracy: 0.6518

Saving ...

Epoch 7:

Training loss: 0.8094, Training accuracy: 0.7156 Validation loss: 1.0099, Validation accuracy: 0.6476

Epoch 8:

Training loss: 0.7581, Training accuracy: 0.7310 Validation loss: 1.0078, Validation accuracy: 0.6548 Saving ...

Epoch 9:

Training loss: 0.7111, Training accuracy: 0.7477 Validation loss: 1.0560, Validation accuracy: 0.6482

Epoch 10:

Training loss: 0.6745, Training accuracy: 0.7601 Validation loss: 1.0871, Validation accuracy: 0.6482

Epoch 11:

Training loss: 0.6360, Training accuracy: 0.7736 Validation loss: 1.0997, Validation accuracy: 0.6426

Epoch 12:

Training loss: 0.6000, Training accuracy: 0.7859
Validation loss: 1.1334, Validation accuracy: 0.6558
Saving ...

Epoch 13:

Training loss: 0.5781, Training accuracy: 0.7921 Validation loss: 1.1609, Validation accuracy: 0.6418

Epoch 14:

Training loss: 0.5427, Training accuracy: 0.8049 Validation loss: 1.2202, Validation accuracy: 0.6306

Epoch 15:

Training loss: 0.5203, Training accuracy: 0.8129 Validation loss: 1.2312, Validation accuracy: 0.6490

Epoch 16:

Training loss: 0.5012, Training accuracy: 0.8201 Validation loss: 1.3026, Validation accuracy: 0.6452

Epoch 17:

Training loss: 0.4744, Training accuracy: 0.8292 Validation loss: 1.2977, Validation accuracy: 0.6468

Epoch 18:

Training loss: 0.4565, Training accuracy: 0.8365 Validation loss: 1.3221, Validation accuracy: 0.6458

Epoch 19:

Training loss: 0.4412, Training accuracy: 0.8414
Validation loss: 1.4556, Validation accuracy: 0.6382

Epoch 20:

Training loss: 0.4235, Training accuracy: 0.8481 Validation loss: 1.5195, Validation accuracy: 0.6318

Epoch 21:

Training loss: 0.4129, Training accuracy: 0.8513 Validation loss: 1.5120, Validation accuracy: 0.6432

Epoch 22:

Training loss: 0.3956, Training accuracy: 0.8586 Validation loss: 1.5268, Validation accuracy: 0.6270

Epoch 23:

Training loss: 0.3856, Training accuracy: 0.8616 Validation loss: 1.6055, Validation accuracy: 0.6316

Epoch 24:

Training loss: 0.3657, Training accuracy: 0.8709 Validation loss: 1.7347, Validation accuracy: 0.6336

Epoch 25:

Training loss: 0.3621, Training accuracy: 0.8700 Validation loss: 1.6591, Validation accuracy: 0.6300

Epoch 26:

Training loss: 0.3598, Training accuracy: 0.8712 Validation loss: 1.7372, Validation accuracy: 0.6390

Epoch 27:

Training loss: 0.3449, Training accuracy: 0.8761 Validation loss: 1.7351, Validation accuracy: 0.6188

Epoch 28:

Training loss: 0.3367, Training accuracy: 0.8798 Validation loss: 1.9336, Validation accuracy: 0.6136

Epoch 29:

Training loss: 0.3397, Training accuracy: 0.8795 Validation loss: 1.8522, Validation accuracy: 0.6248

Best validation accuracy: 0.6558

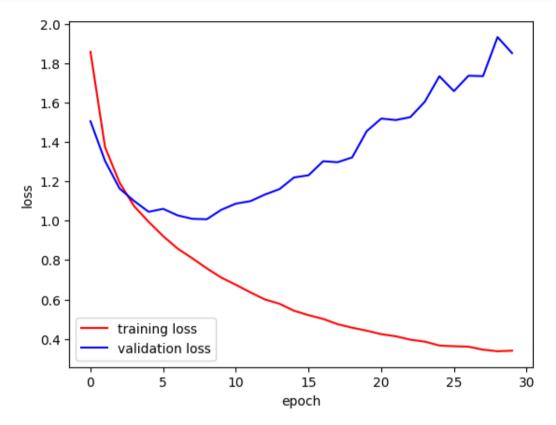
2 (b)

[6]: <All keys matched successfully>

```
# YOUR CODE HERE #
    ###################
    # write another loop to evaluate trained model performance on the test split
    net.eval()
    total examples = 0
    correct examples = 0
    with torch.no grad():
        for batch idx, (inputs, targets) in enumerate(test loader):
            inputs, targets = inputs.cuda(), targets.cuda()
            outputs = net(inputs)
            _, predictions = torch.max(outputs, 1)
            correct_examples += (predictions == targets).sum().item()
            total_examples += inputs.shape[0]
    avg_acc = correct_examples / total_examples
    print("Testing accuracy: %.4f" % (avg_acc))
```

Testing accuracy: 0.6512

```
plt.ylabel('loss')
plt.legend(['training loss', 'validation loss'])
plt.show()
```



As can be seen from the above figure, when the epoch increases, the training loss decreases, while the validation loss decreases and then increases, which means that this model is overfitting. By comparing training accuracy and testing accuracy, we can also draw the conclusion of overfitting.

3 (C)

3.0.1 L1 Regularization

```
[9]: INITIAL_LR = 0.01
   net = SimpleCIFAR10Classifier().cuda()
   MOMENTUM = 0.9
   criterion = nn.CrossEntropyLoss()
   optimizer = optim.SGD(net.parameters(), lr=INITIAL_LR, momentum=MOMENTUM)

EPOCHS = 30
   CHECKPOINT_FOLDER = "./saved_model"
```

```
###################
# YOUR CODE HERE #
##################
# set your own L1 regularization weight
RFG = 1e-4
# write training loops with L1 regularization and validation loops (Hint:
⇔similar to (a))
best val acc = 0
# Training Loop
train losses = []
val losses = []
for i in range(0, EPOCHS):
   net.train()
   print("Epoch %d:" %i)
   total_examples = 0
   correct_examples = 0
    # Record training loss
   train loss = 0
    # Looping through training loader
   for batch idx, (inputs, targets) in enumerate(train loader):
        # Send input and target to device
        inputs, targets = inputs.cuda(), targets.cuda()
        # compute the model output logits and training loss
        outputs = net(inputs)
        # calculate L1 term
       L1_term = torch.tensor(0.).cuda()
        for name, weights in net.named_parameters():
            if 'bias' not in name:
                L1_term += torch.norm(weights, 1)
       CE_term = criterion(outputs, targets)
       loss = CE_term + REG * L1_term
        # back propogation & optimizer update parametes
        optimizer.zero grad()
        loss.backward()
        optimizer.step()
        # calculate predictions
```

```
, predictions = torch.max(outputs, 1)
       correct_examples += (predictions == targets).sum().item()
      total examples += inputs.shape[0]
      train_loss += loss.cpu().detach().numpy()
  # calculate average training loss and accuracy
  avg_loss = train_loss / len(train_loader)
  avg acc = correct examples / total examples
  print("Training loss: %.4f, Training accuracy: %.4f" %(avg_loss, avg_acc))
  train losses.append(avg loss)
  # Evaluate the validation set performance
  net.eval()
  total_examples = 0
  correct examples = 0
  # Record validation loss
  val loss = 0
  # disable gradient during validation, which can save GPU memory
  with torch.no_grad():
      for batch idx, (inputs, targets) in enumerate(val loader):
           # Send input and target to device
           inputs, targets = inputs.cuda(), targets.cuda()
           # compute the model output logits and training loss
          outputs = net(inputs)
           loss = criterion(outputs, targets)
           # count the number of correctly predicted samples in the current \Box
\hookrightarrow batch
          _, predictions = torch.max(outputs, 1)
          correct_examples += (predictions == targets).sum().item()
          total_examples += inputs.shape[0]
          val_loss += loss.cpu().detach().numpy()
  # calculate average validation loss and accuracy
  avg_loss = val_loss / len(val_loader)
  avg_acc = correct_examples / total_examples
  print("Validation loss: %.4f, Validation accuracy: %.4f" % (avg_loss, __
→avg_acc))
  val_losses.append(avg_loss)
  # save the model checkpoint
  current_learning_rate = optimizer.state_dict()['param_groups'][0]['lr']
  if avg_acc > best_val_acc:
      best_val_acc = avg_acc
```

```
if not os.path.exists(CHECKPOINT_FOLDER):
            os.makedirs(CHECKPOINT FOLDER)
         print("Saving ...")
         state = {'state_dict': net.state_dict(),
                 'epoch': i,
                 'lr': current_learning_rate}
         torch.save(state, os.path.join(CHECKPOINT_FOLDER, 'best_model_L1.bin'))
    print('')
print(f"Best validation accuracy: {best val acc:.4f}")
Epoch 0:
Training loss: 2.0072, Training accuracy: 0.3284
Validation loss: 1.5097, Validation accuracy: 0.4496
Saving ...
Epoch 1:
Training loss: 1.5350, Training accuracy: 0.5071
Validation loss: 1.2679, Validation accuracy: 0.5592
Saving ...
Epoch 2:
Training loss: 1.3480, Training accuracy: 0.5849
Validation loss: 1.1599, Validation accuracy: 0.5884
Saving ...
Epoch 3:
Training loss: 1.2504, Training accuracy: 0.6189
Validation loss: 1.1450, Validation accuracy: 0.5996
Saving ...
Epoch 4:
Training loss: 1.1912, Training accuracy: 0.6475
Validation loss: 1.0420, Validation accuracy: 0.6408
Saving ...
Epoch 5:
Training loss: 1.1346, Training accuracy: 0.6691
Validation loss: 1.0064, Validation accuracy: 0.6468
Saving ...
Epoch 6:
Training loss: 1.1016, Training accuracy: 0.6867
Validation loss: 0.9673, Validation accuracy: 0.6588
Saving ...
```

Epoch 7:

Training loss: 1.0705, Training accuracy: 0.7016 Validation loss: 0.9538, Validation accuracy: 0.6688

Saving ...

Epoch 8:

Training loss: 1.0444, Training accuracy: 0.7139
Validation loss: 0.9571, Validation accuracy: 0.6774

Saving ...

Epoch 9:

Training loss: 1.0288, Training accuracy: 0.7232 Validation loss: 0.9681, Validation accuracy: 0.6638

Epoch 10:

Training loss: 1.0009, Training accuracy: 0.7353 Validation loss: 0.9956, Validation accuracy: 0.6660

Epoch 11:

Training loss: 0.9881, Training accuracy: 0.7441 Validation loss: 0.9653, Validation accuracy: 0.6730

Epoch 12:

Training loss: 0.9785, Training accuracy: 0.7505 Validation loss: 0.9690, Validation accuracy: 0.6764

Epoch 13:

Training loss: 0.9592, Training accuracy: 0.7598 Validation loss: 0.9990, Validation accuracy: 0.6778 Saving ...

Epoch 14:

Training loss: 0.9555, Training accuracy: 0.7657 Validation loss: 1.0464, Validation accuracy: 0.6626

Epoch 15:

Training loss: 0.9368, Training accuracy: 0.7732 Validation loss: 0.9986, Validation accuracy: 0.6748

Epoch 16:

Training loss: 0.9342, Training accuracy: 0.7759
Validation loss: 1.0015, Validation accuracy: 0.6704

Epoch 17:

Training loss: 0.9355, Training accuracy: 0.7780 Validation loss: 1.0244, Validation accuracy: 0.6646

Epoch 18:

Training loss: 0.9214, Training accuracy: 0.7855 Validation loss: 0.9922, Validation accuracy: 0.6860

Saving ...

Epoch 19:

Training loss: 0.9120, Training accuracy: 0.7910 Validation loss: 1.0662, Validation accuracy: 0.6568

Epoch 20:

Training loss: 0.9062, Training accuracy: 0.7940 Validation loss: 1.0720, Validation accuracy: 0.6708

Epoch 21:

Training loss: 0.9025, Training accuracy: 0.7981 Validation loss: 1.0943, Validation accuracy: 0.6542

Epoch 22:

Training loss: 0.8958, Training accuracy: 0.8027 Validation loss: 1.0644, Validation accuracy: 0.6666

Epoch 23:

Training loss: 0.8971, Training accuracy: 0.8031 Validation loss: 1.0926, Validation accuracy: 0.6724

Epoch 24:

Training loss: 0.8991, Training accuracy: 0.8035 Validation loss: 1.1183, Validation accuracy: 0.6638

Epoch 25:

Training loss: 0.8935, Training accuracy: 0.8084 Validation loss: 1.1439, Validation accuracy: 0.6608

Epoch 26:

Training loss: 0.8869, Training accuracy: 0.8146 Validation loss: 1.1514, Validation accuracy: 0.6614

Epoch 27:

Training loss: 0.8864, Training accuracy: 0.8167 Validation loss: 1.1763, Validation accuracy: 0.6630

Epoch 28:

Training loss: 0.8788, Training accuracy: 0.8192 Validation loss: 1.1614, Validation accuracy: 0.6708

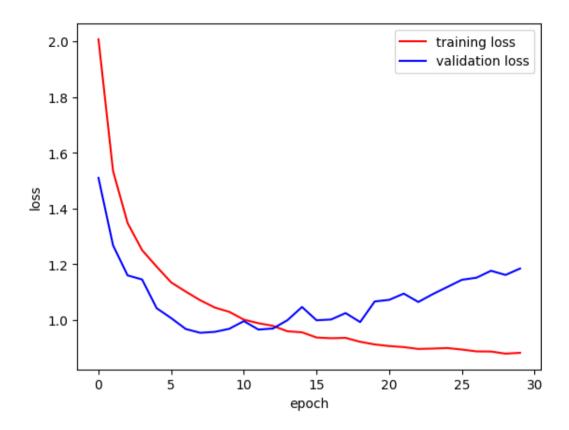
Epoch 29:

Training loss: 0.8819, Training accuracy: 0.8204 Validation loss: 1.1843, Validation accuracy: 0.6654 Best validation accuracy: 0.6860

[10]: <All keys matched successfully>

```
# YOUR CODE HERE #
     ###################
     # write another loop to evaluate trained model performance on the test split
     net.eval()
     total examples = 0
     correct_examples = 0
     with torch.no_grad():
         for batch_idx, (inputs, targets) in enumerate(test_loader):
             inputs, targets = inputs.cuda(), targets.cuda()
             outputs = net(inputs)
             _, predictions = torch.max(outputs, 1)
             correct_examples += (predictions == targets).sum().item()
             total_examples += inputs.shape[0]
     avg_acc = correct_examples / total_examples
     print("Testing accuracy: %.4f" % (avg_acc))
```

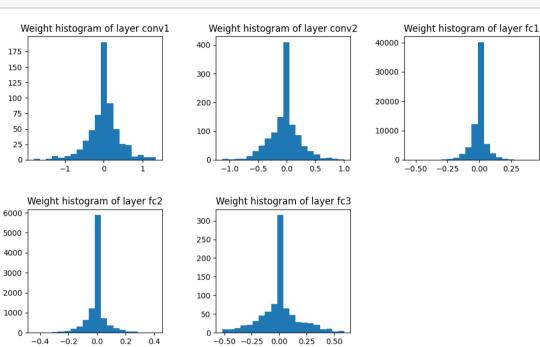
Testing accuracy: 0.6844



The figure above shows that this model is less overfitting than the model without L1 regularization. And the testing accuracy of this model (0.6844) is larger than the model without L1 regularization (0.6512). Therefore, this model is better.

3.0.2 Visualize the model weights

```
plt.subplot(230 + plt_i)
   _ = plt.hist(weight, bins=20)
   plt.title("Weight histogram of layer " + name)
plt.show()
```



4 (d)

4.0.1 L2 Regularization

```
optimizer = optim.SGD(net.parameters(), lr=INITIAL_LR, momentum=MOMENTUM, __
 ⇔weight decay=REG)
# write training loops with L2 regularization and validation loops (Hint:
⇔similar to (a))
best_val_acc = 0
# Training Loop
train losses = []
val losses = []
for i in range(0, EPOCHS):
   net.train()
   print("Epoch %d:" %i)
   total examples = 0
   correct examples = 0
   # Record training loss
   train loss = 0
    # Looping through training loader
   for batch_idx, (inputs, targets) in enumerate(train_loader):
        # Send input and target to device
        inputs, targets = inputs.cuda(), targets.cuda()
        # compute the model output logits and training loss
        outputs = net(inputs)
       loss = criterion(outputs, targets)
        # back propogation & optimizer update parametes
        optimizer.zero grad()
       loss.backward()
        optimizer.step()
        # calculate predictions
        _, predictions = torch.max(outputs, 1)
        correct_examples += (predictions == targets).sum().item()
        total_examples += inputs.shape[0]
        train_loss += loss.cpu().detach().numpy()
    # calculate average training loss and accuracy
   avg_loss = train_loss / len(train_loader)
   avg_acc = correct_examples / total_examples
   print("Training loss: %.4f, Training accuracy: %.4f" %(avg_loss, avg_acc))
   train_losses.append(avg_loss)
    # Evaluate the validation set performance
```

```
net.eval()
    total_examples = 0
    correct_examples = 0
    # Record validation loss
    val loss = 0
    # disable gradient during validation, which can save GPU memory
    with torch.no grad():
        for batch_idx, (inputs, targets) in enumerate(val_loader):
            # Send input and target to device
            inputs, targets = inputs.cuda(), targets.cuda()
            # compute the model output logits and training loss
            outputs = net(inputs)
            loss = criterion(outputs, targets)
            # count the number of correctly predicted samples in the current,
 \hookrightarrow batch
            _, predictions = torch.max(outputs, 1)
            correct_examples += (predictions == targets).sum().item()
            total_examples += inputs.shape[0]
            val_loss += loss.cpu().detach().numpy()
    # calculate average validation loss and accuracy
    avg_loss = val_loss / len(val_loader)
    avg_acc = correct_examples / total_examples
    print("Validation loss: %.4f, Validation accuracy: %.4f" % (avg_loss, __
 →avg acc))
   val_losses.append(avg_loss)
    # save the model checkpoint
    current_learning_rate = optimizer.state_dict()['param_groups'][0]['lr']
    if avg acc > best val acc:
        best_val_acc = avg_acc
        if not os.path.exists(CHECKPOINT_FOLDER):
           os.makedirs(CHECKPOINT_FOLDER)
        print("Saving ...")
        state = {'state_dict': net.state_dict(),
                'epoch': i,
                'lr': current_learning_rate}
        torch.save(state, os.path.join(CHECKPOINT_FOLDER, 'best_model_L2.bin'))
    print('')
print(f"Best validation accuracy: {best_val_acc:.4f}")
```

Epoch 0: Training loss: 1.8003, Training accuracy: 0.3377 Validation loss: 1.4931, Validation accuracy: 0.4670 Saving ... Epoch 1: Training loss: 1.3692, Training accuracy: 0.5064 Validation loss: 1.3354, Validation accuracy: 0.5248 Saving ... Epoch 2: Training loss: 1.1990, Training accuracy: 0.5730 Validation loss: 1.1813, Validation accuracy: 0.5764 Saving ... Epoch 3: Training loss: 1.0901, Training accuracy: 0.6149 Validation loss: 1.0992, Validation accuracy: 0.6090 Saving ... Epoch 4: Training loss: 1.0045, Training accuracy: 0.6429 Validation loss: 1.0363, Validation accuracy: 0.6386 Saving ... Epoch 5: Training loss: 0.9417, Training accuracy: 0.6660 Validation loss: 1.0312, Validation accuracy: 0.6464 Saving ... Epoch 6: Training loss: 0.8864, Training accuracy: 0.6877 Validation loss: 1.0074, Validation accuracy: 0.6474 Saving ... Epoch 7: Training loss: 0.8403, Training accuracy: 0.7028 Validation loss: 1.0510, Validation accuracy: 0.6424 Epoch 8: Training loss: 0.7966, Training accuracy: 0.7190 Validation loss: 1.0413, Validation accuracy: 0.6488 Saving ... Epoch 9: Training loss: 0.7618, Training accuracy: 0.7339

Validation loss: 1.0218, Validation accuracy: 0.6522

Saving ...

Epoch 10:

Training loss: 0.7266, Training accuracy: 0.7451 Validation loss: 1.0391, Validation accuracy: 0.6550 Saving ...

Epoch 11:

Training loss: 0.7070, Training accuracy: 0.7504 Validation loss: 1.0023, Validation accuracy: 0.6642 Saving ...

Epoch 12:

Training loss: 0.6698, Training accuracy: 0.7624 Validation loss: 1.0192, Validation accuracy: 0.6600

Epoch 13:

Training loss: 0.6457, Training accuracy: 0.7699
Validation loss: 1.0219, Validation accuracy: 0.6608

Epoch 14:

Training loss: 0.6316, Training accuracy: 0.7766 Validation loss: 1.0383, Validation accuracy: 0.6626

Epoch 15:

Training loss: 0.6154, Training accuracy: 0.7820 Validation loss: 1.0313, Validation accuracy: 0.6638

Epoch 16:

Training loss: 0.5845, Training accuracy: 0.7917 Validation loss: 1.0596, Validation accuracy: 0.6676 Saving ...

Epoch 17:

Training loss: 0.5693, Training accuracy: 0.7968
Validation loss: 1.1095, Validation accuracy: 0.6494

Epoch 18:

Training loss: 0.5504, Training accuracy: 0.8042 Validation loss: 1.0569, Validation accuracy: 0.6740 Saving ...

Epoch 19:

Training loss: 0.5445, Training accuracy: 0.8053 Validation loss: 1.0697, Validation accuracy: 0.6554

Epoch 20:

Training loss: 0.5247, Training accuracy: 0.8130 Validation loss: 1.0893, Validation accuracy: 0.6612

```
Epoch 22:
     Training loss: 0.4984, Training accuracy: 0.8213
     Validation loss: 1.1513, Validation accuracy: 0.6476
     Epoch 23:
     Training loss: 0.4988, Training accuracy: 0.8212
     Validation loss: 1.1073, Validation accuracy: 0.6726
     Epoch 24:
     Training loss: 0.4839, Training accuracy: 0.8281
     Validation loss: 1.1281, Validation accuracy: 0.6596
     Epoch 25:
     Training loss: 0.4690, Training accuracy: 0.8325
     Validation loss: 1.1648, Validation accuracy: 0.6530
     Epoch 26:
     Training loss: 0.4645, Training accuracy: 0.8341
     Validation loss: 1.2120, Validation accuracy: 0.6484
     Epoch 27:
     Training loss: 0.4596, Training accuracy: 0.8361
     Validation loss: 1.1712, Validation accuracy: 0.6542
     Epoch 28:
     Training loss: 0.4459, Training accuracy: 0.8419
     Validation loss: 1.2016, Validation accuracy: 0.6516
     Epoch 29:
     Training loss: 0.4470, Training accuracy: 0.8407
     Validation loss: 1.1980, Validation accuracy: 0.6500
     Best validation accuracy: 0.6740
# YOUR CODE HERE #
      ##################
      # load trained model weight
      net = SimpleCIFAR10Classifier().cuda()
      net.load_state_dict(torch.load(os.path.join(CHECKPOINT_FOLDER, 'best_model_L2.
       ⇔bin'))['state_dict'])
```

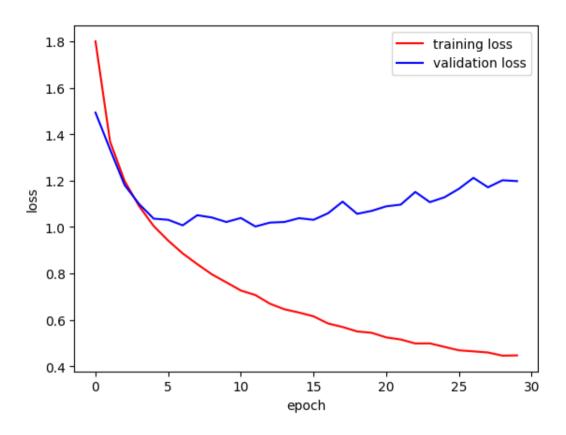
Epoch 21:

Training loss: 0.5156, Training accuracy: 0.8154
Validation loss: 1.0968, Validation accuracy: 0.6624

[15]: <All keys matched successfully>

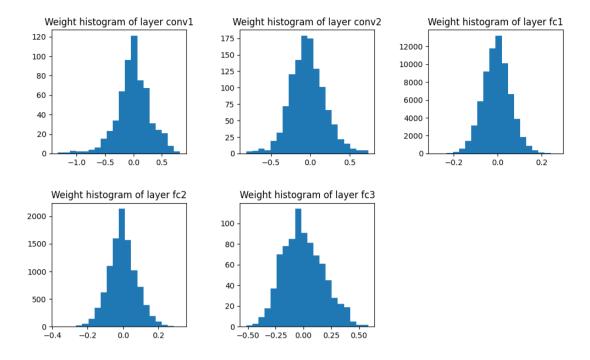
```
# YOUR CODE HERE #
     ####################
     # write another loop to evaluate trained model performance on the test split
     net.eval()
     total_examples = 0
     correct_examples = 0
     with torch.no_grad():
         for batch_idx, (inputs, targets) in enumerate(test_loader):
             inputs, targets = inputs.cuda(), targets.cuda()
             outputs = net(inputs)
             _, predictions = torch.max(outputs, 1)
             correct_examples += (predictions == targets).sum().item()
             total_examples += inputs.shape[0]
     avg_acc = correct_examples / total_examples
     print("Testing accuracy: %.4f" % (avg_acc))
```

Testing accuracy: 0.6702



4.0.2 Visualize the model weights

```
[18]: import matplotlib.pyplot as plt
      plt.figure(figsize=(12,7))
      plt.subplots_adjust(wspace = 0.4, hspace = 0.4)
      plt_i = 0
      for name, module in net.named_modules():
          if 'conv' in name or 'fc' in name:
              ##################
              # YOUR CODE HERE #
              ##################
              # extract weight from layers
              weight = module.weight.cpu().detach().numpy().flatten()
              # Visualize the weights
              plt_i += 1
              plt.subplot(230 + plt_i)
              _ = plt.hist(weight, bins=20)
              plt.title("Weight histogram of layer "+name)
      plt.show()
```



5 (e)

5.0.1 comment on the differences between L1 and L2 regularization.

The weight histograms for L1 regularization exhibit sharp spikes at zero, while the weights for L2 regularization are more evenly spread around zero.

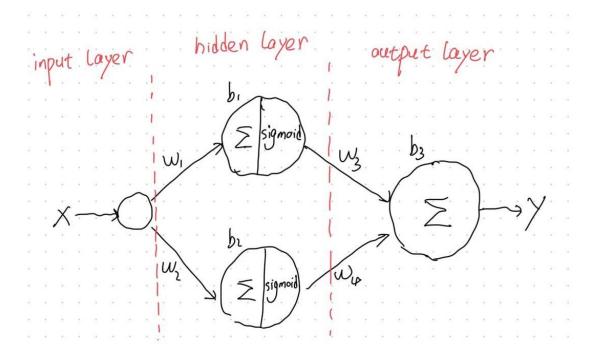
Effects on model weights: L1 regularization penalizes the absolute value of the weights, which compels the model to be sparse; while L2 penalizes the square of the weights, which encourages tiny weights but doesn't impose sparsity.

Effects on model performance: L1 Regularization sets many weights to zero, which lead to a simpler model. It works well if the dataset has irrelevant or redundant features. In comparison, L2 Regularization keeps more features, potentially improving model performance; nevertheless, failure to properly adjust the REG increases the danger of overfitting.

3.1

(a)

The NN is implemented as below:



The weight and bias values are designed as below:

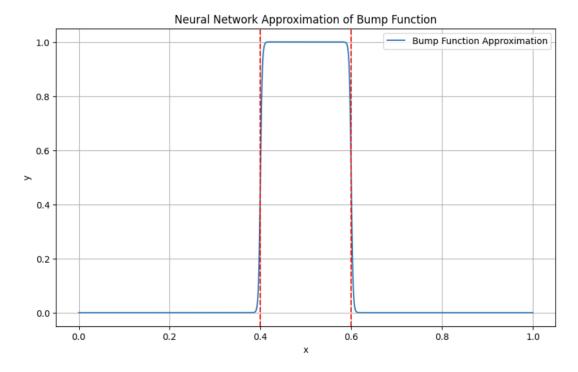
$$w_1 = 500, w_2 = -500, w_3 = 1, w_4 = 1$$
 $b_1 = -0.4w_1 = -200, b_2 = -0.6w_2 = 300, b_3 = -1$

Therefore, the approximated bump function is derived as:

$$y = w_3 sigmoid(w_1 x + b_1) + w_4 sigmoid(w_2 x + b_2) + b_3$$

 $y = sigmoid(500x - 200) + sigmoid(-500x + 300) - 1$

Then the approximated bump function is plotted as below:



The minimum number of hidden neurons for this approximation is 2,

because at least two neurons are required to achieve a combination of a step-up function and a step-down function.

(b)

- (1) The steepness of the step-up part is determined by w_1 . The larger w_1 is, the steeper the step-up part is. The steepness of the step-down part is determined by w_2 . The smaller w_2 is, the steeper the step-down part is.
- (2) The step-up location is determined by b_1 . The step-down location is determined by b_2 . Below shows the relationship between b_1 and step-up location x_{up} and the relationship between b_2 and step-down location x_{down} .

$$b_1 = -x_{uv}w_1$$
, $b_2 = -x_{down}w_2$

(3) The height of the bump is determined by w_3 and w_4 . The relationship

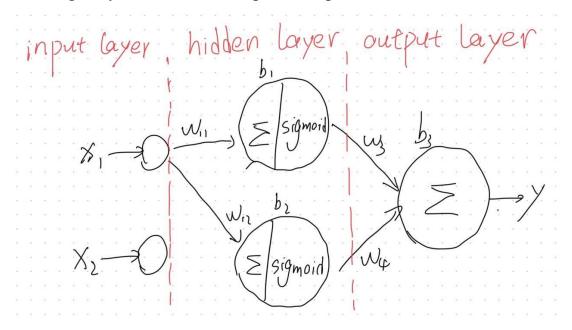
is shown below:

$$height = w_3 = w_4$$

3.2

(a)

The single layer NN with two inputs is implemented as below:



The weight and bias values are designed as below:

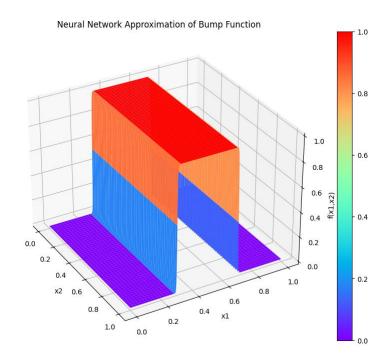
$$w_{11}=500, w_{12}=-500, w_3=1, w_4=1$$
 $b_1=-0.3w_{11}=-150, b_2=-0.7w_{12}=350, b_3=-1$

Therefore, the approximated bump function is derived as:

$$y = w_3 sigmoid(w_{11}x_1 + b_1) + w_4 sigmoid(w_{12}x_1 + b_2) + b_3$$

$$y = sigmoid(500x_1 - 150) + sigmoid(-500x_1 + 350) - 1$$

Then the approximated bump function is plotted as below:

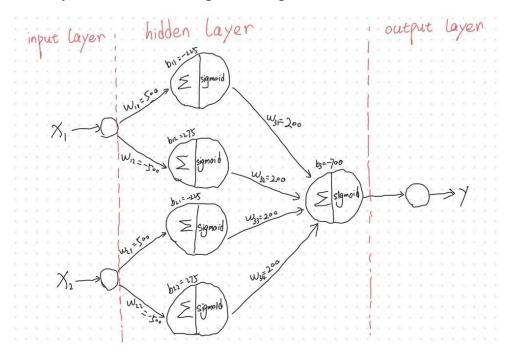


The minimum number of hidden neurons for this approximation is 2,

because at least two neurons are required to achieve a combination of a step-up function and a step-down function for x_1 .

(b)

The two-layer NN with two inputs is implemented as below:

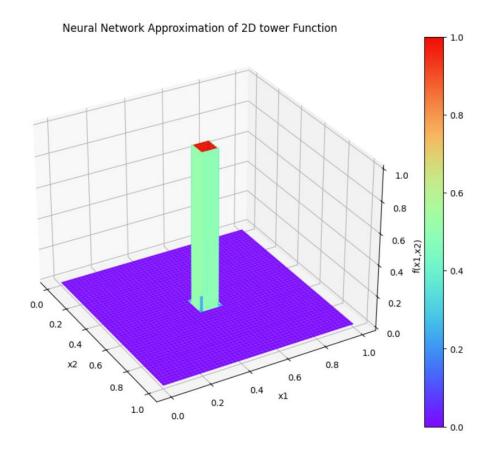


The approximated 2D tower function is derived as:

$$\begin{split} y = sigmoid(w_{31}sigmoid(w_{11}x_1 + b_{11}) + w_{32}sigmoid(w_{12}x_1 + b_{12}) \\ + w_{33}sigmoid(w_{21}x_2 + b_{21}) + w_{34}sigmoid(w_{22}x_2 + b_{22}) + b_3) \end{split}$$

$$y = sigmoid(200 sigmoid(500 x_1 - 225) + 200 sigmoid(-500 x_1 + 275) \\ + 200 sigmoid(500 x_2 - 225) + 200 sigmoid(-500 x_2 + 275) - 700)$$

The approximated 2D tower function is plotted as below:



The minimum number of hidden neurons for this approximation is 5, two for x_1 direction bump in the first hidden layer, two for x_2 direction bump in the first hidden layer, and one for the second hidden layer.

(c)

In the worst case, the gradient of $f(x_1, x_2)$ for both directions are always t, and the maximum error for each tower function, ϵ is the height change

of $f(x_1, x_2)$ over its base square, which can be derived as below:

$$\epsilon = st$$

Where *s* is the base square size of each tower function.

Therefore, the area of base square, s^2 is calculated as:

$$s^2 = \left(\frac{\epsilon}{t}\right)^2$$

To fill the 2D unit square with these tower functions, the number of tower functions is determined as:

$$N = \frac{unit\ square\ area}{base\ square\ area} = \frac{1}{s^2} = \left(\frac{t}{\epsilon}\right)^2 \tag{1}$$

Therefore, the minimum number of tower functions that can guarantee to make such an approximation for all possible function f that satisfies the conditions is $\left(\frac{t}{\epsilon}\right)^2$.

In addition, according to part b and equation (1), the relationship between the gradient limit t, error bound ϵ , and the total required hidden neuron number N_{hidden} is shown below:

$$N_{hidden} \propto N \rightarrow N_{hidden} \propto \left(\frac{t}{\epsilon}\right)^2$$