# Complex Analysis

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#### 1 Harmonic function

Definition 1.1 (Cauchy-Riemann equation).

$$\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y}, \qquad \frac{\partial u}{\partial y} = -\frac{\partial v}{\partial x}$$

**Definition 1.2** (Harmonic function). A function u is **harmonic** if it satisfied **Laplace equation**  $\triangle u = 0$ .

If two harmonic function u and v satisfies Cauchy-Riemann equations, then we say that v is **conjugate harmonic function of**  $u \Rightarrow u$  is conjugate harmonic of -v.

#### 1.1 Polynomial rational function

The polynomial  $P(z) = \sum_{j=0}^{n} a_j z^j$  is analytic in  $\mathbb{C}$ .

We will prove the fundamental theorem of algebra

**Theorem 1.3** (Fundamental Theorem of Algebra). Every polynomial with degree n > 0 has at least one point.

**Theorem 1.4** (Gauss-Lucus theorem). The smallest convex polygon that contain the zeros of P also contains the zeros of P'.

Proof. Only need to check.

We can get this equation.

$$\frac{P'(\alpha)}{P(\alpha)} = \sum_{j=1}^{n} \frac{1}{\alpha - \alpha_j} = 0 \Rightarrow \sum_{j=1}^{n} \frac{\overline{\alpha - \alpha_j}}{|\alpha - \alpha_j|^2}$$

Hence  $\alpha$  is linearly represented by  $\alpha_j$ .

**Proposition 1.5.** Let P and Q be two polynomial with no common zeros. Then the rational function  $R(z) = \frac{P(z)}{O(z)}$  is analytic away from the zeros of Q.

The zeros of Q are called **poles** of R, and the **order of a pole** is equal to the order of the corresponding zero of Q.

We often view R as a function from  $\hat{\mathbb{C}}$  to  $\hat{\mathbb{C}}$ .  $R_1(z) := R(\frac{1}{z})$ .

If  $R_1(0) = 0$ , the order of the zero at  $\infty$  (of R) is the order of the zero of  $R_1(z)$  at z = 0.

If  $R_1(0) = \infty$ , the order of the pole at  $\infty$  (of R) is the order of the pole of  $R_1(z)$  at z = 0.

Suppose

$$R(z) = \frac{a_n z^n + \dots + a_1 z + a_0}{b_m z^m + \dots + b_1 z + b_0}, a_n \neq 0, b_m \neq 0$$

Then

$$R_1(z) = z^{m-n} \frac{a_0 z^n + \dots + a_n}{b_0 z^m + \dots + b_m}$$

By discussing m and n, we can infer the situation of R(z) at  $\infty$ .

By adding the order of poles and zeros at  $\infty$ , we can get the following theorem.

**Theorem 1.6.** The total number of zeros and poles of a rational function are the same.

Remark 1.7. This common nnumber is called the order of the rational function.

**Corollary 1.8.** Suppose a rational function R has order p. Then every equation R(z) = a has exactly p roots.

*Proof.* 
$$\hat{R}(z) = R(z) - a$$
 has the same poles as  $R$ .

A rational function of order 1 is a **linear fraction**  $R(z) = \frac{az+b}{cz+d}$ ,  $ad-bc \neq 0$ Such fraction is often called **Möbius transformation** 

Every rational function has a representation by **partial fractions**.

• If R has a pole at  $\infty$ . Then we can write

$$R(z) = G(z) + H(z) \tag{*}$$

where G is a polynomial without constant term, and H is finite at  $\infty$ .

The degree of G is the order of the pole of R at  $\infty$ . G is called the **singular** part of R at  $\infty$ .

• Let the distinct finite poles of R be  $\beta_1, \dots, \beta_k$ . Let  $R_j(\psi) = R(\beta_j + \frac{1}{\psi})$ . Then  $R_j$  is a rational function with a pole at  $\infty$ . As in (\*), we can write

$$R_j = G_j + H_j$$

with  $H_j$  finite at  $\infty$ . Then

$$R(z) = G_j(\frac{1}{z - \beta_j}) + H(\frac{1}{z - \beta_j})$$

with  $G_j$  is a polynomial in  $\frac{1}{z-\beta_j}$  without constant term called the **singular** point of R at  $\beta_j$ .

• Let  $F(z) = R(z) - G(z) - \sum_{j=1}^k G_j(\frac{1}{z-\beta_j})$ . Then F is a rationnal function which can only have poles among  $\beta_j, \infty$ . Since by our construction, F is finite at every  $\beta_j, 1 \le j \le k$  and  $\infty$ .

So *F* is a constant.

In particular, 
$$R(z) = G(z) + \sum_{j=1}^{k} G_j(\frac{1}{z-\beta_j}) + c$$
.

#### 2 Power Series

**Theorem 2.1** (Abel's theorem). If  $\sum a_n$  converges, then  $f(z) = \sum a_n z^n \to f(1)$  as  $z \to 1$  in such a way that  $\frac{|1-z|}{1-|z|}$  remains bounded.

# 3 Exponential, Trigonometric and logorithmic functions

## 3.1 Exponential and Trigonometric function

The **exponential function** is defined as the solution if the differential equation

$$\begin{cases} f'(z) = f(z) \\ f(0) = 1 \end{cases}$$

We denote  $e^z = \exp z = \sum_{n=0}^{\infty} \frac{z^n}{n!}$ .

The **trigonometric function** are defined by

$$\cos z = \frac{e^{iz} + e^{-iz}}{2}$$
  $\sin z = \frac{e^{iz} - e^{-iz}}{2i}$ 

## 3.2 Logorithmic Functions

The **logorithmic function**  $\ln$  is defined by  $z = \ln w$  is a root of the equation  $e^z = w$ .

For  $w \neq 0$ , we write z = x + iy, then

$$e^{x+iy} = w \Leftrightarrow \begin{cases} e^x = |w| \\ e^{iy} = \frac{w}{|w|} \end{cases}$$

The first equation has a unique solution  $x = \ln |w|$ .

The second equation  $e^{iy} = \frac{w}{|w|}$  has a unique solution  $y_0 \in [0, 2\pi)$ .

If we write  $w = re^{i\theta}$ , then  $x = \ln w$ ,  $y = \theta = \arg w$ .

Thus, for  $w \neq 0$ , we have

$$\ln w = \ln |w| + i \arg w$$

The function  $\ln$  is actually not single-valued. But we can define a single-valued function Ln

We define

$$a^b = \exp(b \ln a)$$

We will prove Ln is analytic in  $\mathbb{C} - (-\infty, 0]$  but not continuous in  $(-\infty, 0]$ . Ln is the principle branch of the logithm.

## 4 Conformal Mappings

#### 4.1 Connectedness

**Theorem 4.1.** A nonempty open set in  $\mathbb{C}$  is connected iff any two of its points can be joined by a polygon which lies in the set.( i.e. Connectedness is equivalent to Path Connectedness)

An nonempty connected subsetis called a region

## 4.2 Compactness

**Definition 4.2.** A set X is **totally bounded** if  $\forall \epsilon > 0$ , X can be covered by finitely many balls of radius  $\epsilon$ 

**Theorem 4.3.** A set is compact iff it is complete and totally bounded.

**Theorem 4.4.** A subset  $X \subset is$  compact iff exery infinite sequence of X has a limit point in X.

#### 4.3 Continuous Functions

**Theorem 4.5.** Continous function maps connected space to connected space.

**Theorem 4.6.** Continous function maps compact space to compact space.

#### 4.4 Arcs and closed surves

The equation of an  $\operatorname{arc} r$  in  $\mathbb C$  can be represented by one of the terms

- $x = x(t), y = y(t), \alpha \leqslant t \leqslant \beta, x, y$  are continuous at t
- $z(t) = x(t) + iy(t), \alpha \le t \le \beta$ .
- the continous mapping  $\gamma: [\alpha, \beta] \to \mathbb{C}$ .

For a nondecreasing function  $\varphi: [\alpha, \beta] \to [\alpha, \beta]$ ,  $z = z(\varphi(t)), \alpha' \leqslant \tau \leqslant \beta'$  is **change** of parameter of z(t).

The change is **reversible** iff  $\varphi$  is strictly increasing.

If  $\gamma$  is differentiable, then call  $\gamma$  a **curve**.

 $\gamma$  is **simple** , or a **Jordan curve**, if  $\gamma$  is injective.

 $\gamma$  is closed curve if  $\gamma(0) = \gamma(1)$ .

#### 4.5 Analytic Functions in Regions

A function f is analytic on an arbitrary set A if it is the restriction to A of a function which is analytic in some open set containing A.

**Theorem 4.7.** An analytic function in a region (i.e. open and connected)  $\Omega$  whose derivative is 0 must reduce to a constant. The same hold if the real part, the imaginary part, the modulus, or the argument is constant.

#### 4.6 Conformal Mappings

Suppose  $f: \Omega \to \mathbb{C}$  is analytic in  $\Omega$ .  $r_1 = z_1(t), r_2 = z_2(t), \alpha \leqslant t \leqslant \beta$ .  $z_0 = z_1(t_0) = z_2(t_0'), z_1'(t_0) \neq 0, z_2'(\hat{t_0}) \neq 0, \alpha < t_0, \hat{t_0} < \beta$ .  $f'(z_0) \neq 0, w_1(t) = f(z_1(t_0)), w_2 = f(z_2(\hat{t_0}))$   $\Gamma_1 = \{w_1(t) | \alpha \leqslant t \leqslant \beta\}, \Gamma_2 = \{w_2(t) | \alpha \leqslant t \leqslant \beta\}$ 

Then

$$w'_1(t) = f'(z_1(t))z'_1(t)$$
  
$$w'_2(t) = f'(z_2(\hat{t}))z'_2(\hat{t})$$

 $\Rightarrow$ 

$$w'_1(t_0) \neq 0, w'_2(t_0) \neq 0$$

$$\arg w'_1(t_0) = \arg f'(z_1(t_0))z'_1(t_0)$$

$$\arg w'_2(t_0) = \arg f'(z_2(\hat{t_0}))z'_2(\hat{t_0})$$

So the "angle"  $\arg w_1'(t_0) - \arg w_2'(\hat{t_0} = \arg z_1(t_0) - \arg z_2(\hat{t_0})$  remains the same. Now we give the definition.

**Definition 4.8.** w = f(z) is said to be **conformal** in  $\Omega$  if f is analytic in  $\Omega$  and  $f'(z) \neq 0$  for  $\forall z \in \Omega$ .

Easy to prove that linear change of scale at  $z_0$  is independent of the direction.

i.e. 
$$|f'(z_0)| = \lim_{z \to z_0} \frac{\delta \sigma}{\delta s}$$

#### 4.7 Length and Area

The **length** of a differentiable arc  $\gamma$  with the equation z(t)=x(t)+iy(t),  $a\leqslant t\leqslant b$ 

$$L(\gamma) = \int_{a}^{b} \sqrt{(x'(t))^{2} + (y'(t))^{2}} dt = \int_{a}^{b} |z'(t)| dt$$

For  $\Gamma = f(\gamma)$  where f conformal mapping.

Then

$$L(\Gamma) = \int_{a}^{b} |f'(z(t))| \cdot |z'(t)| dt$$

The **area** of  $E \subset \mathbb{R}$  is  $A(E) = \iint_E \mathrm{d}x \mathrm{d}y$ 

Then by the differentiable functional transformation, the area  $\hat{E} = f(E)$  is

$$A(\hat{E}) = \int \int_{E} |u_x v_y - u_y v_x| \mathrm{d}x \mathrm{d}y$$

If f is the conformal mapping of an open set containing E, then by Caucht-Riemann equation

$$A(\hat{E}) = \iiint_{E} |f'(z)|^{2} dx dy$$

#### 5 Möbius Transformation

Recall that a **Möbius transformation** is a function of the form

$$w = s(z) = \frac{az+b}{cz+d}$$
,  $ad-bc \neq 0$ 

Then it has an inverse  $z = S^{-1}(w) = \frac{dw - b}{-cw + a}$ .

We may define  $S(\infty) = \lim_{z \to \infty} S(z) = \frac{a}{c}$ ,  $S(\frac{-d}{c}) = \infty$ 

With these definition,  $S: \hat{\mathbb{C}} \to \hat{\mathbb{C}}$  is a topological mapping. Here one may use the chordal metric to define the topology.

$$S'(z) = \frac{ad - bc}{(cz + d)^2}$$

Then S is conformal in  $\hat{\mathbb{C}} - \{-\frac{d}{c}, \infty\}$ .

 $w = z + \alpha$  is called a parallel translation.

w = kz with |k| = 1 is a **rotation**.

w = kz with k > 0 is a homothetic transformation.

 $x = \frac{1}{z}$  is called an **inversion**.

**Proposition 5.1.** Every Möbius transformation is a composition of the above four operations.

#### 5.1 Cross ratio

For three distinct points  $z_2, z_3, z_4 \in \hat{\mathbb{C}}$ , we can find a Möbius transformation S such that  $S(z_2) = 0, S(z_3) = 1, S(z_4) = \infty$ .

**Lemma 5.2.** The Möbius transformation satisfying the above conditions is unique.

The **cross ratio**  $(z_1, z_2, z_3, z_4)$  is the image  $z_1$  under the Möbius transformation which maps  $z_2$  to 1,  $z_3$  to 0 and  $z_4$  to  $\infty$ .

**Theorem 5.3.** If  $z_1, z_2, z_3, z_4 \in \hat{\mathbb{C}}$  are distinct, and T is any Möbius transformation, then  $(Tz_1, Tz_2, Tz_3, Tz_4) = (z_1, z_2, z_3, z_4)$ .

**Lemma 5.4.** *Let* T *be a Möbius transformation,*  $T(\mathbb{R})$  *is either a circle or a straight line.* 

**Theorem 5.5.** The cross ratio  $(z_1, z_2, z_3, z_4)$  is real iff the four points lie on a circle or a straight line.

Remark 5.6. One may prove the theorem by elementary geometry

**Theorem 5.7.** A Möbius transformation maps circles into circles.

#### 5.2 Symmetry

Suppose T is a Möbius transformation which maps  $\hat{\mathbb{R}}$  onto a circle C. z We say that w = Tz and  $w^* = T\bar{z}$  are **symmetric** w.r.t. C.

**Remark 5.8.** This definition is independent of T. Suppose S is another Möbius transformation which maps  $\hat{\mathbb{R}}$  onto C, then  $S^{-1}T$  maps  $\hat{\mathbb{R}}$  to  $\hat{\mathbb{R}}$ , and this  $S^{-1}w=S^{-1}Tz$  and  $S^{-1}w^*=S^{-1}T\bar{z}$  are conjugate.

The points z and  $z^*$  are symmetric w.r.t C through  $z_1, z_2, z_3$  iff  $(z^*, z_1, z_2, z_3) = \overline{(z, z_1, z_2, z_3)}$ .

This can be another definition.

Note that only the points on C are symmetric to themselves.

The mapping  $z \mapsto z^*$  is 1-1 and is called **reflection** w.r.t. C.

#### 5.2.1 geometric meaning of symmetry

Case1: C is a straight line. We may assume  $z_3 = \infty$ .

 $z, z^*$  are symmetric w.r.t. C if and only if

$$\frac{z^* - z_2}{z_1 - z_2} = \frac{\bar{z} - \bar{z_2}}{\bar{z_1} - \bar{z_2}}$$

Then

$$|z^* - z_2| = |z - z_2|, \quad \forall z_2 \in C \text{ and } z_2 \neq \infty$$

$$\operatorname{Im} \frac{z^* - z_2}{z_1 - z_2} = \operatorname{Im} \frac{\bar{z} - \bar{z_2}}{\bar{z_1} - \bar{z_2}}$$

So C is the bisecting normal of the segment between z and  $z^*$ .

Case2: C is the circle |z - a| = R.

Then for 
$$\forall$$
 distinct  $z_1, z_2, z_3 \in \mathbb{C}$ ,  $\overline{(z, z_1, z_2, z_3)} = \overline{(z - a, z_1 - a, z_2 - a, z_3 - a)}$   
=  $(\bar{z} - \bar{a}, \bar{z_1} - \bar{a}, \bar{z_2} - \bar{a}, \bar{z_3} - \bar{a}) = (\bar{z} - \bar{a}, \frac{R^2}{z_1 - a}, \frac{R^2}{z_2 - a}, \frac{R^2}{z_3 - a}) = (\frac{R^2}{\bar{z} - \bar{a}}, z_1 - a, z_2 - a, z_3 - a)$ 

$$a, z_3 - a)$$
  
=  $(\frac{R^2}{\bar{z} - \bar{a}}, z_1, z_2, z_3).$ 

Then the symmetric point of z w.r.t. C is

$$z^* = \frac{R^2}{\bar{z} - \bar{a}} + a$$

or

$$(z^* - a)(\bar{z} - \bar{a}) = R^2$$

 $\Rightarrow$ 

$$\begin{cases} |z^* - a| \cdot |z - a| = R^2 \\ \frac{z^* - a}{z - a} = \frac{(z^* - a)(\bar{z} - \bar{a})}{|z - a|^2} > 0 \end{cases}$$

**Theorem 5.9** (The Symmetric principle). If a Möbius transformation maps a circle  $C_1$  onto a circle  $C_2$ , then it transforms any pair of symmetric points w.r.t.  $C_1$  into a pair of symmetric points w.r.t.  $C_2$ .

*Proof.* Case1:  $C_1 = \hat{\mathbb{R}}$ . Let T be the Möbius transformation which maps  $\hat{\mathbb{R}}$  onto  $C_2$ .  $\forall z \in \mathbb{C}$ , by definition, w = Tz and  $w^* = T\bar{z}$  are symmetric w.r.t.  $C_2$ .

Case2:  $C_1$  is a general circle. Let  $T:C_1\to C_2$  and  $S:\mathbb{R}\to C_2$  be Möbius transformation.

Suppose  $w, w^*$  are symmetric w.r.t.  $C_1$ . Then there exists z s.t.  $w = Sz, w^* = S\overline{z}$ .

Then we can find  $Tw = TSz, Tw^* = TS\bar{z}$  are symmetric w.r.t.  $C_2$  since  $TS: \hat{\mathbb{R}} \to C_2$ 

**Remark 5.10.** 1. The Möbius transformation from  $C_1$  to  $C_2$  satisfies  $z_1 \mapsto$ 

 $w, z_2 \mapsto w_2, z_3 \mapsto w_3$  where  $z_1, z_2, z_3 \in C_1$ ,  $w_1, w_2, w_3 \in C_2$  is given by

$$(w, w_1, w_2, w_3) = (z, z_1, z_2, z_3, )$$

2. The Möbius transformation from  $C_1$  to  $C_2$  satisfies  $z_1 \mapsto w_1$ ,  $z_2 \mapsto w_2$  where  $z_1 \in C_1, z_2 \notin C_1$ ,  $w_1 \in C_2, w_2 \notin C_2$  is given by

$$(w, w_1, w_2, w_2^*) = (z, z_1, z_2, z_2^*)$$

#### 5.3 Steiner Circles

For 
$$S(z) = \frac{az+b}{cz+d}$$
,  $S'(z) = \frac{ad-bc}{(cz+d)^2}$ .

A point  $z \notin$  a circle C is said to on the **right**(**left,resp.**) of C if  $Im(z, z_1, z_2, z_3) > 0$ ( $Im(z, z_1, z_2, z_3) < 0$ )

#### Remark 5.11.

- 1. This agrees with everyday use since  $(i, 1, 0, \infty) = i$
- 2. This distinct between left and right is the same for all triples, while the meaning may be reversed.

(If 
$$C = \hat{\mathbb{R}}$$
, then  $(z, z_1, z_2, z_3) = \frac{az+b}{cz+d}$  with  $a, b, c, d \in \mathbb{R} \Rightarrow \operatorname{Im}(z, z_1, z_2, z_3) = \frac{ad-bc}{|cz+d|^2} \operatorname{Im}(z)$ )

3. We can define an absolute positive orientation of all finite circles by requiring that  $\infty$  should be lie to the right of the oriented circles.

Consider a Möbius transformation of the form

$$w = k \cdot \frac{z - a}{z - b}$$

Here,  $z = a \mapsto w = 0, z = b \mapsto w = \infty$ .

Then circles through a, b maps to straight line through  $0, \infty$ .

The concentric circle about the origin,  $|w|=\rho$ , correspond to circles with the equation

$$\left| \frac{z - a}{z - b} \right| = \frac{\rho}{|k|}$$

These are the circles of **Apollonius** with limit points a and b.

Denote by  $C_1$  the circles through a, b and  $C_2$  the circles of Apollonius with these limit points. The configuration formed by all the circles  $C_1$  and  $C_2$  is called the **Steiner circles**(or **circular net**)

#### Theorem 5.12.

- (a) There is exactly one  $C_1$  and one  $C_2$  through each point in  $\hat{\mathbb{C}}\setminus\{a,b\}$
- (b) Every  $C_1$  meets every  $C_2$  under right angle.
- (c) Reflection in a  $C_1$  transforms every  $C_2$  into itself and every  $C_1$  into another  $C_1$ .
- (d) The limit points a, b are symmetric w.r.t. each  $C_2$ , but not w.r.t. other circles.

*Proof.* If the limit points are  $0, \infty$ , those properties are trivial in the w-plane. The general case follows since all properties are invariant under Möbius transformations.

## 6 Elementary Conformal mapping

**Example 6.1.**  $w = z^{\alpha}$  where  $\alpha > 0$ .

Let  $S(u_1, u_2)$  with  $0 < \varphi_2 - \varphi_1 \le 2\pi$  be  $\{z \in \mathbb{C} : z \neq 0, \varphi_1 < \arg(z) < \varphi_2\}$  where  $\arg(z)$  can be chosen as any value of it.

Then  $S(\varphi_1, \varphi_2)$  is a region.

In this region, a unique value of  $w=z^{\alpha}$  is defined by  $\arg w=\alpha\arg z$ .

This function is analytic with  $\frac{\mathrm{d}w}{\mathrm{d}z} = \alpha \frac{w}{z}$ .

This function is 1-1 only if  $\alpha(\varphi_2-\varphi_1) \leq 2\pi$ .

**Example 6.2.** 
$$w = e^z \text{ maps } \{z \in \mathbb{C} : -\frac{\pi}{2} < \text{Im}(z) < \frac{\pi}{2} \} \text{ onto } \{w \in \mathbb{C} : \text{Re}(w) > 0 \}$$

**Example 6.3.** 
$$w = \frac{z-1}{z+1} \text{ maps } \{z \in \mathbb{C} : \text{Re}(z) > 0\} \text{ onto } \{ww \in \mathbb{C} : |w| < 1\}$$

Example 6.4.

$$\mathbb{C}\backslash[-1,1] \xrightarrow{z_1 = \frac{z+1}{z-1}} \mathbb{C}\backslash(-\infty,0] \xrightarrow{z_2 = \sqrt{z_1}} \left\{ \operatorname{Re}(z_2) > 0 \right\} \xrightarrow{w = \frac{z_2 - 1}{z_2 + 1}} \left\{ w \in \mathbb{C} : |w| < 1 \right\} \quad (6.1)$$

#### 6.1 Elementary Riemann surfaces

**Example 6.5.**  $w = z^n$ ,  $n \in \mathbb{Z}_+$  and n > 1.

There is a 1-1 correspondence between each angle  $\frac{(k-1)2\pi}{n} < \arg z < \frac{k\cdot 2\pi}{n}, k=1,2,\cdots,n$  and while w-plane except for the positive real axis.

**Example 6.6.**  $w=e^z$ . This function maps each parallel strip  $(k-1)2\pi < \text{Im } z < k \cdot 2\pi, k \in \mathbb{Z}$  onto a sheet with a cut along the positive axis.

## 7 Complex Integration

#### 7.1 Fundamental Theorems

#### 7.1.1 Line integral and rectifiable arcs

Let f(t) = u(t) + iv(t) be a complex-valued defined on  $t \in [a, b] \subset \mathbb{R}$  where u, v are real-valued functions. If f is continuous on [a, b], we may define the **integral** 

$$\int_{a}^{b} f(t)dt := \int_{a}^{b} u(t)dt + i \int_{a}^{b} v(t)dt$$

Let  $\gamma$  br a piecewise differential arc in  $\mathbb C$  with the equation  $z=z(t), a\leqslant t\leqslant b$ . If f is continuous on  $\gamma$ , then f(z(t)) is conitnuous on [a,b], and we define

$$\int_{\gamma} f(z) dz = \int_{a}^{b} f(z(t))z'(t) dt$$
(7.1)

The integral defined in 7.1 is independent of the parametrization of  $\gamma$ . Suppose that anther parametrization of  $\gamma$  is  $\gamma:(\alpha,\beta)\to\mathbb{C}, \tau\mapsto z(t(\tau))$ , where  $t:(\alpha,\beta)\to(a,b), \tau\mapsto t(\tau)$  is piecewise differentiable. Then we have

$$\int_{a}^{b} f(z(t))z'(t)dt = \int_{\alpha}^{\beta} f(z(t(\tau)))z'(t(\tau))t'(\tau)dt = \int_{\alpha}^{\beta} f(z(t(\tau)))\frac{\mathrm{d}z(t(\tau))}{\mathrm{d}\tau}d\tau$$
 (7.2)

For an arc  $\gamma$  with equation  $z=z(t), a\leqslant t\leqslant b$ , we define  $-\gamma$  by  $z=z(-t), -b\leqslant t\leqslant a$ .

Then we have

$$\int_{-\gamma} f(z) dz = \int_{-b}^{-a} f(z(-t)) \frac{dz(-t)}{dt} dt$$

$$= -\int_{-a}^{-b} f(z(-t)) z'(-t) dt$$

$$= -\int_{a}^{b} f(z(\tau)) z'(\tau) d\tau$$

$$= -\int_{\gamma} f(z) dz$$

So we have those properties:

#### Proposition 7.1.

(a) 
$$\int_{-\gamma} f(z) dz = -\int_{\gamma} dz$$

(b) Let f and g be two continuous functions on the piecewise differentiable arc  $\gamma$ , then

$$\int_{\gamma} (\lambda_1 f + \lambda_2 g) dz = \lambda_1 \int_{\gamma} f dz + \lambda_2 \int_{\gamma} g dz, \forall \lambda_1, \lambda_2 \in \mathbb{C}$$

(c) If  $\gamma$  can be subdivided into two pieces differentiable arcs  $\gamma_1$  and  $\gamma_2$ , and f is continuous on  $\gamma_1$ , then

$$\int_{\gamma} f dz = \int_{\gamma_1} f dz + \int_{\gamma_2} f dz$$

(d) (c) implies that the integral of a closed curve doesn't depend on the starting point on the curve

**Example 7.2.** Evaluate  $\int_{\gamma} \frac{1}{z-a} dz$  where  $\gamma$  is the circle centered at  $a \in \mathbb{C}$  with radius R.

Let  $z = z(t) = a + Re^{it}$ . Then the integral is  $2\pi i$ 

#### 7.1.2 The fundamental theorem of Calculus for integrals in $\mathbb C$

The line integral w.r.t.  $\bar{z}$  is defined by

$$\int_{\gamma} f(z) \overline{\mathrm{d}z} = \overline{\int_{\gamma} \overline{f(z)} \mathrm{d}z}$$

With this notation, line integrals w.r.t. x = Re(z) and y = Im(z) can be defined by

$$\int_{\gamma} f(z) dx = \frac{1}{2} \left[ \int_{\gamma} f(z) dz + \int_{\gamma} f(z) \overline{dz} \right]$$

$$\int_{\gamma} f(z) dy = \frac{1}{2i} \left[ \int_{\gamma} f(z) dz - \int_{\gamma} f(z) \overline{dz} \right]$$

if we write  $f(z) = \mu + i\nu$ , we have

$$\int_{\gamma} f(z)dz = \int_{\gamma} f(z)dx + i \int_{\gamma} f(z)dy = \int_{\gamma} (\mu dx - \nu dy) + i \int_{\gamma} (\nu dx + \mu dy)$$

**Remark 7.3.** It is followed by the intuition. We can view the integration as the multiplication between f and dz.

The integral w.r.t. arc length is defined by

$$\int_{\gamma} f(z)|\mathrm{d}z| = \int_{a}^{b} f(z(t))|z'(t)|\mathrm{d}t$$

This integral is again independent of the parametrization. It is easy to check

$$\int_{-\gamma} f(z)|\mathrm{d}z| = \int_{\gamma} f(z)|\mathrm{d}z|$$

Now we define **length** of a curve  $\gamma$ :  $L(\gamma) = \int_{\gamma} |\mathrm{d}z|$ 

We have the inequality:

$$\left| \int_{\gamma} f dz \right| \leq \int_{\gamma} |f| \cdot |dz| \leq L(\gamma) \cdot \sup_{z \leq \gamma} |f(z)|$$

The length of an arc  $\gamma$  (z=z(t)) can also be defined as the least upper bound of all sums

$$\sum_{i=1}^{n} |z(t_i) - z(t_{i-1})|$$

where  $a = t_0 < t_1 < \cdots < t_n = b$  If this least upper bound is finite, we say that the arc is **rectifiable** 

It is easy to show that piecewise differentiable arcs are rectifiable.

The integral of a continuous function f on a rectifiable arc may be defined as

$$\int_{\gamma} f(z) dz = \lim_{k \to 1} \sum_{k=1}^{n} f(z(\psi_k)) [z(t_k) - z(t_{k-1})]$$

**Theorem 7.4.** Let  $\Omega \subset \mathbb{C}$  be a region, and P,Q two (possibly complex-valued) functions that are continuous on  $\Omega$ ,  $\gamma$  closed curve. The integral  $\int_{\gamma} p(x,y) dx + Q(x,y) dy$  depends only on the end point of  $\gamma$  iff there exists a function U(x,y) on  $\Omega$  with  $\frac{\partial U}{\partial x} = P, \frac{\partial U}{\partial y} = Q$ .

*Proof.* " $\Leftarrow$ ": If such a U exists, then

$$\int_{\gamma} P dx + Q dy = \int_{\gamma} \frac{\partial U}{\partial x} dx + \frac{\partial U}{\partial y} dy = \int_{\gamma} \frac{dU}{dt} dt = U(\gamma(b)) - U(\gamma(a))$$

" $\Rightarrow$ ": Fix a point  $(x_0, y_0) \in \Omega$ . We define  $U(x, y) = \int_{\gamma} P dx + Q dy$  where  $\gamma$  is any curve between  $(x_0, y_0)$  and (x, y). Easy to check that it is true.

**Theorem 7.5** (Fundamental theorem of Calculus for integrals on  $\mathbb{C}$ ). Let f be continuous on a region  $\Omega$  containing  $\gamma$ .  $\int_{\gamma} f dz$  depends on the endpoints iff f is the derivative of an analytic function F in  $\Omega$ .

**Remark 7.6.** We will prove  $\int_{\gamma} f dz = F(\omega_2) - F(\omega_1)$  where  $\gamma$  begins at  $\omega_1$  and ends at  $\omega_2$ .

*Proof.* Transform the line integration into the composition of two real integration.

**Corollary 7.7.** If F is analytic on  $\Omega$  with F'=f, and  $\gamma$  is a closed curve in  $\Omega$ , then  $\int_{\gamma} f dz = 0$ . Conversely if f is continuous on  $\Omega$  and  $\int_{\gamma} f dz = 0$  for any closed curve in  $\Omega$ , then f is the derivartive of an analytic function F in  $\Omega$ .

#### 7.1.3 Cauchy's theorem for a rectangle

There is some notes in this section:

R is the rectangle in  $\mathbb{C}$ ,  $R = \{x + iy \in \mathbb{C} : a \leq x \leq b, c \leq y \leq d\}$ . And  $\partial R$  is boundary curve oriented in the counterclockwise direction.

**Theorem 7.8** (Cauch's theorem for a rectangle). If f is analytic on an open set which contains R, then  $\int_{\partial R} f(z) dz = 0$ 

*Proof.* For  $\forall$  rectangle  $\tilde{R}$  inside R, we define  $Z(\tilde{R}) = \int_{\partial \tilde{R}} f(z) dz$ . Then  $Z(R) = Z(R_1) + Z(R_2)$  if R is divided into  $Z_1, Z_2$ .

Since we can divide R into four equal rectangles, and find a rectangle with  $|Z(R^{(1)})| \geqslant \frac{1}{4}|Z(R)|$ . Then repeat the above steps and we obetain a sequence of nested rectangles  $R \supset R^{(1)} \supset \cdots$  with the property

$$Z(R^{(n)}) \geqslant \frac{1}{4} |Z(R^{(n-1)})| \geqslant \dots \geqslant \frac{1}{4^n} Z(R)$$
 (7.3)

 $\forall \delta > 0$ ,  $\exists n \in \mathbb{N}$  s.t.  $R^{(n)} \subset \{z \in \mathbb{C} : |z - z_0| < \delta\}, \forall n \geqslant N$ , where  $z_0$  is the limit of  $R^{(n)}$  as  $n \to \infty$ .

f is analytic in  $R \Rightarrow \forall \epsilon, \exists \delta > 0$  s.t.

$$\left| \frac{f(z) - f(z_0)}{z - z_0} - f'(z_0) \right| < \epsilon, \forall z \text{ with } |z - z_0| < \delta$$
 (7.4)

We assume that  $\delta$  satisfies both conditions. We have

$$Z(R^{(n)}) = \int_{\partial R^{(n)}} f(z) dz = \int_{\partial R^{(n)}} [f(z) - f(z_0) - (z - z_0) f'(z_0)] dz$$
$$\Rightarrow |Z(R^{(n)})| \le \epsilon \int_{\partial R^{(n)}} |z - z_0| dz \text{ by 7.4}$$

Let  $d_n$  be the length of diagonal of  $R^{(n)}$ ,  $L_n$  be the length of its perimeter. Then  $|z-z_0| \leq d_n, \ \forall z \in \partial R^{(n)}$ .

 $\Rightarrow |Z(R^{(n)})| \le \epsilon d_n L_n = \epsilon \frac{D}{2^n} \cdot \frac{L}{2^n}$  where D, L are the diameter and perimeter of R.

$$\Rightarrow |Z(R)| \stackrel{7.3}{\leqslant} 4^n |Z(R^{(n)})| \leqslant \epsilon DL \Rightarrow Z(R) = 0 \text{ since } \epsilon \text{ is arbitary.}$$

We will next prove the following stronger theorem:

**Theorem 7.9** (stronger version of Cauchy's theorem for a rectangle). Let f be analytic on  $R' = R \setminus \{\psi_1, \dots, \psi_m\}, m \in \mathbb{N}$ . If  $\lim_{z \to \psi_j} (z - \psi_j) f(z) = 0, \forall 1 \leq j \leq m$ , then  $\int_{\mathbb{R}^n} f(z) dz = 0$ .

*Proof.* WLOG, we may assume f is not analytic at only one point  $\psi \in R$ . If we put psi into a small rectangle  $S_0$ , then the previous theorem tells us  $\int_{\partial R} f(z) dz = \int_{\partial S_0} f(z) dz$ .

 $\forall \epsilon > 0$ , we may choose  $S_0$  small enough such that  $|f(z)| \leq \frac{\epsilon}{|z - \epsilon|}, \ \forall z \in \partial S_0$ 

$$\Rightarrow |\int_{\partial R} f(z) dz \leqslant \epsilon \int_{\partial S_0} \frac{|dz|}{|z - \psi|} \leqslant \epsilon \frac{1}{\frac{l}{2}} \cdot 4l = 8\epsilon$$

$$\Rightarrow \int_{\partial R} f(z) dz = 0 \text{ since } \epsilon \text{ is arbitrary.}$$

#### 7.1.4 Cauchy's Theorem for a disk

$$\Delta := \{ z \in \mathbb{C} : |z - z_0| < R \} \text{ where } R > 0.$$

**Theorem 7.10** (Cauchy's Theorem for a disk). If f is analytic in an open disk  $\Delta$ , then  $\int_{\gamma} f(z) dz = 0$  for closed curve  $\gamma$  in  $\Delta$ .

*Proof.* Suppose the center of  $\Delta$  is  $z_0 = x_0 + iy_0$ , z = x + iy. We define

$$F(z) = \int_{\gamma} f(z) \mathrm{d}z$$

where  $\gamma$  is the horizotal line segment from  $z_0$  to  $(x, y_0)$  added with vertical line segment from  $(x, y_0)$  to z. We have

$$\frac{\partial F}{\partial y} = \lim_{\delta y \to 0} \frac{F(x, y + \delta y) - F(x, y)}{\delta y} = \lim_{\delta y \to 0} \frac{1}{\delta y} \int_{\delta x} f(z) dz = i f(z)$$
 (7.5)

By Cauchy' thm on rectangles, one has  $F(z) = -\int_{\tilde{\gamma}} f(z) dz$ , where  $\tilde{\gamma}$  is the vertical line segment from  $z_0$  to  $(x_0, y)$  added with horizontal line segment from  $(x_0, y)$  to

z.

Similarly, 
$$\frac{\partial F}{\partial x} = f(z)$$
.  
 $\Rightarrow \frac{\partial F}{\partial x} = -i \frac{\partial F}{\partial y} \Rightarrow F$  is analytic in  $\Delta$  with derivative  $f$ .

By Fundamental Theorem 7.5 of Calulus  $\Rightarrow \int_{\gamma} f(z) dz = 0$  for  $\forall$  closed curve in  $\Delta$ .

Here is a stronger version.

**Theorem 7.11** (stronger version of Cauchy's Theorem for a disk). Let f be analytic in a region  $\Delta' = \Delta \setminus \{\psi_1, \cdots, \psi_m\}$  with  $m \in \mathbb{N}$ . If f satisfies  $\lim_{z \to \psi_j} (z - \psi_j) f(z) = 0, \forall 1 \le j \le m$ , then  $\int_{\gamma} f(z) dz = 0, \forall \gamma \text{ closed in } \Delta'$ 

*Proof.* It is similar to the above proof.

For the case no  $\psi_j$  lies on  $x=x_0$  and  $y=y_0$ , we can find a similar curve  $\gamma$  with last segment is a vertical one. Let  $F(z)=\int_{\gamma}f(z)\mathrm{d}z$ . And continue the process of proof of the previous theorem.

For the case that  $\exists \ \psi_j$  lies on the lines  $x=x_0, y=y_0$ , we actually can move the center to another point s.t. no  $\psi_j$  lies on the lines  $x=x_0', y=y_0'$ .

#### 7.2 Cauchy's integral formula

## 7.2.1 Index of a point with resect to a closed curve

**Lemma 7.12.** If the piecewise differentiable closed curve  $\gamma$  does not pass through  $z \in \mathbb{C}$ , then the value of the integral  $\int_{\gamma} \frac{d\zeta}{\zeta - z}$  is a multiple of  $2\pi i$ .

Proof. 
$$\gamma: \zeta = \zeta(t), \alpha \leqslant t \leqslant \beta. \ h(t) = \int_{\alpha}^{t} \frac{\zeta'(x)}{\zeta(s)-z} \mathrm{d}s.$$

 $z \in \gamma \Rightarrow h$  is defined and continuous on  $[\alpha, \beta]$ . For all t s.t.  $\zeta'(t)$  is continuous, we have

$$h'(t) = \frac{\zeta'(t)}{\zeta(t) - z} \Rightarrow \frac{\mathrm{d}}{\mathrm{d}t} \left[ e^{-h(t)} (\zeta(t) - z) \right] = 0$$

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