

Analysis-1 Note

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Contents

1 Introduction

1.1 proposition,logic,simple set theory

There are some symbols we should to know:

$$P \vee Q : \text{or} \quad | \quad P \wedge Q : \text{and} \quad | \quad \neg P : \text{not} \quad |$$

xRy means $(x, y) \in R$, for $R \subset X \times Y$, which is called a relationship.

For $R \subset X \times Y$, **define** $R^{-1} := \{(y, x) \in Y \times X : xRy\}$.

For $S \subset Y \times Z$, **define** $S \circ R := \{(x, y) \in X \times Z : \exists y \in Y, s.t. xRy \wedge ySz\}$

Definition 1.1.1 (equivalent relationship). $\sim \subset X \times X$ is an equivalent relationship if

$$(1) \quad \forall x \in X, x \sim x$$

$$(2) \quad \forall x, y \in X, x \sim y \Rightarrow y \sim x$$

$$(3) \quad x \sim y, y \sim z \Rightarrow x \sim z$$

For an equivalent relationship, we can **define** $[x] := \{y \in X : y \sim x\}$ be the equivalent class of x . For that there is a map called **quotient mapping**

Definition 1.1.2 (partially ordered relation). For $\leq \subset X \times X$, if

$$(1) \ x \leq x$$

$$(2) \ x \leq y, y \leq z \Rightarrow x \leq z$$

$$(3) \ x \leq y, y \leq x \Rightarrow y = x$$

we call it **partial ordered relation**

If $\forall x, y \in X, (x \leq y) \vee (y \leq x)$, we call it **total order** or **linear order**.

Definition 1.1.3. (X, \leq) is a **partially ordered set** for $A \subset X$, define

$$1. \ x < y \text{ iff } x \leq y \text{ and } x \neq y$$

$$2. \ s \in X \text{ is an upper bound(lower bound) iff } \forall a \in A, a \leq s(s \leq a)$$

$$3. \ m \in A \text{ is a maximal(minimal) element iff } \nexists a \in A \text{ s.t. } m < a(a < m)$$

$$4. \ m \in A \text{ is the greatest(least) element iff } m \text{ is the upper(lower) bound and } m \in A$$

1.2 Metric spaces, convergence of sequences, and continuous functions

1.3 Introduction

1.4 Basic definitions and examples

Definition 1.4.1. Let X be a set. A function $d : X \times X \rightarrow \mathbb{R}_{\geq 0}$ is called a **metric** if for all $x, y, z \in X$ we have

$$(1) \ d(x, y) = d(y, x)$$

$$(2) \ d(x, y) = 0 \text{ iff } x = y$$

$$(3) \ (\text{Triangle inequality}) \ d(x, z) \leq d(x, y) + d(y, z)$$

The pair (X, d) , or simply X is called a **metric space**. If $x \in X$ and $r \in (0, +\infty]$, the set

$$B_X(x, r) = \{y \in X : d(x, y) < r\}$$

often abbreviated to $B(x, r)$, is called the **open ball** with center x and radius r . If $r \in [0, +\infty)$,

$$\overline{B}_X(x, r) = \{y \in X : d(x, y) \leq r\}$$

also abbreviated to $\overline{B}(x, r)$ is called the **closed ball** with center x and radius r .

Unless otherwise stated, the metric on \mathbb{R}^n and \mathbb{C}^n (and their subsets) are assumed to be the **Euclidean metrics**.

Example 1. Let $X = X_1 \times \cdots \times X_N$ where each X_i is a metric space with metric d_i . Write $x = (x_1, \dots, x_N) \in X$ and $y = (y_1, \dots, y_N) \in X$. Then the following are metrics on X :

$$d(x, y) = d_1(x_1, y_1) + \cdots + d_N(x_N, y_N) \quad (1)$$

$$\delta(x, y) = \max\{d_1(x_1, y_1), \dots, d_N(x_N, y_N)\} \quad (2)$$

$$\rho(x, y) = \sqrt{d_1(x_1, y_1)^2 + \cdots + d_N(x_N, y_N)^2} \quad (3)$$

With respect to the metric δ , the open balls of X are "polydisks"

$$B_X(x, r) = B_{X_1}(x_1, r) \times \cdots \times B_{X_N}(x_N, r)$$

There is no standard choice of metric on the product of metric spaces. d, δ, ρ are all good, and they are equivalent in the following sense:

Definition 1.4.2. We say that two metrics d_1, d_2 on a set X are **equivalent** and write $d_1 \approx d_2$, if there exist $\alpha, \beta > 0$ such that for any $x, y \in X$ we have

$$d_1(x, y) \leq \alpha d_2(x, y), \quad d_2(x, y) \leq \beta d_1(x, y)$$

This is an equivalence relation. More generally, we may write $d_1 \lesssim d_2$ if $d_1 \leq \alpha d_2$ for some $\alpha > 0$. Then $d_1 \approx d_2$ iff $d_1 \lesssim d_2$ and $d_2 \lesssim d_1$.

Example 2. We have $\delta \leq \rho \leq d \leq N\delta$. So $\delta \approx \rho \approx d$.

Given finitely many metric spaces X_1, \dots, X_N , the metric on the product space $X = X_1 \times \dots \times X_N$ is chosen to be any one that is equivalent to the ones defined before. In the case that each X_i is a subset of \mathbb{R} or \mathbb{C} , we choose the metric on X to be the **Euclidean metric**

Definition 1.4.3. Let (X, d) be a metric space. Then a **metric subspace** is denotes an object $(Y, d|_Y)$ where $Y \subset X$ and $d|_Y$ is the restriction of d to Y , namely for all $y_1, y_2 \in Y$ we set

$$d|_Y(y_1, y_2) = d(y_1, y_2)$$

1.5 Convergence of sequences

Definition 1.5.1. Let $(x_n)_{n \in \mathbb{Z}_+}$ be a sequence in a metric space X . Let $x \in X$. We say that x is a **limit** of x_n and write $\lim_{n \rightarrow \infty} x_n = x$, if: For every real number $\epsilon > 0$ there exists $N \in \mathbb{Z}_+$ such that for every $n \geq N$ we have $d(x_n, x) < \epsilon$.

Proposition 1. Any sequence $(x_n)_{n \in \mathbb{Z}_+}$ in a metric space X has at most one limit

Proposition 2 (Squeeze theorem). Suppose that (x_n) is a sequence in a metric space X , Let $x \in X$. Suppose that there is a sequence (a_n) in $\mathbb{R}_{\geq 0}$ such that $\lim_{n \rightarrow \infty} a_n = 0$ and that $d(x_n, x) \leq a_n$ for all n . Then $\lim_{n \rightarrow \infty} x_n = x$

Definition 1.5.2. X is a metric space. We say X is **sequentially compact** if every sequence in X has a convergent subsequence.

Lemma 1 (Extreme Value Theorem). If X is sequentially compact, $f : X \rightarrow \mathbb{R}$ continuous. Then f attains its max and min on X . In particular $f(X)$ is a bounded subset of \mathbb{R} .

Example 3. If $X = A_1 \cup \dots \cup A_n$, each A_i is sequentially compact, then X is sequentially compact.

Example 4. Finite set is sequentially compact.

Proposition 3. *If X, Y are sequentially compact, then $X \times Y$ is sequentially compact.*

Proof. Pick (x_n, y_n) in $X \times Y$. Since X is sequentially compact, x_n has subsequence, $x_{n_k} \rightarrow x \in X$. Since Y is sequentially compact, y_{n_k} has subsequence, $y_{n_{k_i}} \rightarrow y \in Y$. Then $(x_{n_{k_i}}, y_{n_{k_i}}) \rightarrow (x, y) \in X \times Y$. \square

Proposition 4. *If $f : X \rightarrow Y$ continuous, X is sequentially compact, then $f(X)$ is sequentially compact.*

Example 5. *If A is sequentially compact subset of \mathbb{R} , then $\sup A, \inf A \in A$.*

Theorem 1.5.1. *$[a, b] \subset \overline{\mathbb{R}}$ is sequentially compact. Then $I_1 \times \cdots \times I_n$ is sequentially compact where $I_i = [a, b]$.*

Definition 1.5.3. *If (x_n) is a sequence in X . We say $x \in X$ is a **cluster/accumulation point** of (x_n) if x is a limit point of a subsequence of (x_n) .*

Definition 1.5.4. *Let (x_n) in $\overline{\mathbb{R}}$. $\alpha_n = \inf(x_n, x_{n+1}, \dots), \beta_n = \sup(x_n, x_{n+1}, \dots)$. Then we have $\alpha_n \leq x_n \leq \beta_n$. **Define***

$$\liminf x_n = \lim_{n \rightarrow \infty} \alpha_n = \sup \alpha_n$$

$$\limsup x_n = \lim_{n \rightarrow \infty} \beta_n = \inf \beta_n$$

Theorem 1.5.2. *Let $S := \{\text{cluster point of } x_n \text{ in } \overline{\mathbb{R}}\}$, $B := \limsup x_n$, $A := \liminf x_n$. Then $B = \max S$, $A = \min S$. In particular, $A, B \in S$, so $S \neq \emptyset$*

Theorem 1.5.3. *Let X be sequentially compact, (x_n) in X . The following are equivalent:*

- (1) x_n converges.
- (2) (x_n) has only one cluster point.

Corollary 1. *Let (x_n) in \mathbb{R}^N . The following is equivalent:*

- (1) (x_n) converges.

(2) (x_n) is bounded and has at most one cluster point.

Corollary 2. Let (x_n) in $\overline{\mathbb{R}}$, then (x_n) converges in $\overline{\mathbb{R}}$ iff $\liminf x_n = \limsup x_n$.

Corollary 3. If (x_n) in \mathbb{R} . Then (x_n) converges in \mathbb{R} iff (x_n) is bounded and $\liminf x_n = \limsup x_n$

Definition 1.5.5. A sequence (x_n) in X is called a **Cauchy sequence** if

· $\forall \epsilon > 0, \exists N \in \mathbb{Z}_+, \text{ s.t. } \forall m, n \geq N, d(x + m, x_n) < \epsilon.$

· $\forall \epsilon > 0, \exists N, \text{ s.t. } \forall n \geq N, d(x_n, x_N) < \epsilon.$

Cauchy sequence are bounded.

Proposition 5. Every convergent sequence in X is Cauchy sequence.

Definition 1.5.6. X is called **complete** if every Cauchy sequence in X converges.

Theorem 1.5.4. If (x_n) is Cauchy with at least one cluster point. Then (x_n) converges. Therefore, every sequentially compact space is complete.

Corollary 4. $\mathbb{R}^N, \mathbb{C}^N \cong \mathbb{R}^N$ are complete under Euclidean metric.

Definition 1.5.7. $A \subset X$. We say A is closed if the following is true:

If $(x_n) \in A$ converges to $x \in X$, then $x \in A$

Proposition 6. $A \subset X, d_A = d_X|_A$.

(1) A is complete; (2) A is closed.

Then (1) \Rightarrow (2) and if X is complete then (2) \Rightarrow (1)

Theorem 1.5.5. If X is a metric space. Then X is compact $\Leftrightarrow X$ is sequentially compact.

Definition 1.5.8. X is a topo. space. X is called **net-compact** if every net in X has a convergent subnet.

X is called **countably compact** if every countable open cover of X has a finite subcover.

Easy to see that:

compact \Rightarrow countably compact.

Proposition 7. *For topology space, net-compact \Leftrightarrow compact.*

For metric space, Four compactness are equivalent.

Example 6 (Extreme Value Theorem). *If X is compact, $f : X \rightarrow \mathbb{R}$ continuous, then f attains its max (and min).*

It suffices to prove $f(X)$ is bounded.

steps of proof:

Step1: Prove finiteness locally;

Step2: Use compactness to go from local to global.

Proposition 8. *X is a topo. space. TFAE:*

- (1) X is compact.
- (2) (Increasing chain property) *If $(U_\mu)_{\mu \in I}$ is an increasing net of open subsets of X , s.t. $\cup_{\mu \in I} U_\mu = X$, then $\exists \mu \in I$ s.t. $U_\mu = X$.*
- (3) (Decreasing chain property) *If $(U_\mu)_{\mu \in I}$ is a decreasing net of closed subsets of X , s.t. $\forall \mu \in I, U_\mu \neq \emptyset$, then $\cap_{\mu \in I} U_\mu \neq \emptyset$*