

Algebra-1 Note

lin150117

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1 Rings and Fields

Definition 1.0.1 (Group). *A group is a set G with an operation $\cdot : G \times G \rightarrow G$ such that:*

- (1) *(associative law) $\forall x, y, z \in G, (x \cdot y) \cdot z = x \cdot (y \cdot z)$*
- (2) *There is an **identity** element 1 such that $1 \cdot x = x \cdot 1 = x, \forall x \in G$*
- (3) *For any $x \in G, \exists$ an **inverse** x^{-1} such that $x \cdot x^{-1} = x^{-1} \cdot x = 1$*

*A group G is called **Abelian/commutative**, if $\forall x, y \in G, x \cdot y = y \cdot x$*

Definition 1.0.2 (Ring). *A ring is a set with two operations $+$ and \cdot such that for $x, y, z \in \mathbb{R}$*

- (1) *(commutative law) $x + y = y + x$*
- (2) *(associative law) $(x + y) + z = x + (y + z), (x \cdot y) \cdot z = x \cdot (y \cdot z)$*

(3) (*distribution law*) $(x + y) \cdot z = x \cdot z + y \cdot z, \quad z \cdot (x + y) = z \cdot x + z \cdot y$

Moreover, there is a **zero** element 0 and **identity** element $1 \neq 0$ s.t.

$\forall x \in \mathbb{R}$

(4) $x + 0 = 0 + x = x = x \cdot 1 = 1 \cdot x$

(5) \exists **opposite** $-x$ of x such that $-x + x = 0 = x + (-x)$

$x \in R$ is called **invertible** or a **unit** if $\exists x^{-1} \in R$ s.t. $x^{-1} \cdot x = x \cdot x^{-1} = 1$.

Then x^{-1} is called the **inverse** of x .

A ring $(R, +, \cdot)$ is called **commutative** if $\forall x, y \in R, xy = yx$ (say x **commutes** y)

Remark 1. If $xy = 1$, then y is called a **right inverse** of x

Proposition 1 (Cancellation law). If $x, y, z \in R, x + y = x + z$, then $y = z$.

If x is unit, $x \cdot y = x \cdot z$, then $y = z$.

Definition 1.0.3 (Field). A commutative ring is a **field** if every nonzero element is a unit

Remark 2. Columns of $C = A \cdot B$ is combination of columns of A . Rows of $C = C \cdot B$ is combination of rows of B .

Definition 1.0.4 (Elementary row operations). Type 1: Interchange r_i with r_j ,
 $i \neq j$

Type 2: For a unit $u \in \mathbb{R}$, replace r_i with $u \cdot r_i$.

Type 3: Replace r_i with $r_i + cr_j$, $i \neq j, c \in \mathbb{R}$

There are three elementary matrices not mentioned and they are invertible. We write it as $E_{i,j}, E_{i,u}, E_{i,j,c}$ and

$$E_{i,j}^{-1} = E_{i,j}, E_{i,u}^{-1} = E_{i,u^{-1}}, E_{i,j,c}^{-1} = E_{i,j,-c}$$

Remark 3. Elementary row operations on A is multiply on the left elementary matrices.

Definition 1.0.5 (Transpose). $A = (a_{i,j})$ of $m \times n$ define the **transpose** of A :
 $A^T = (a_{j,i})$

1.1 Gauss elimination

Given an equation $A\vec{x} = \vec{b}$, call $(A|\vec{b})$ the **augment matrix**

Definition 1.1.1. A matrix is called **reduced row echelon matrix** if

1. If $r_i = 0$, then $r_j = 0$ for $j > i$;
2. If $r_i \neq 0$, then the left-most nonzero entry is 1 (let $a_{i,k_i} = 1$), called a **pivot**;
3. the pivot of r_i is strictly on the right of the pivot of r_{i-1} ;

Definition 1.1.2. A system of linear equations of form of $a_{j,k_i} = 0$ for all $j < i$ is called a **reduced row echelon system**;

Call x_{k_i}, \dots, x_{k_r} **principal unknowns**, the others **free unknowns**

Proposition 2. 1. Any system of linear equations can be reduced to be a r.r.e system, preserving the set of solutions.

2. Any matrix can be reduced to a r.r.e matrix by row denoting operations.

Proposition 3. $A \in M_n(K)$, TAFE:

1. A is invertible
2. A can be reduced to I_n by row elementary operations
3. A is a product of elementary matrices.

Proposition 4. $A \in M_n(K)$, TAFE:

1. A is invertible
2. $Ax = b$ has a unique solution for any b
3. $Ax = b$ has a unique solution.

2 Determinant

Definition 2.0.1. A **permutation** of $\{1, \dots, n\}$ is a bijective map $\sigma : \{1, \dots, n\} \rightarrow \{1, \dots, n\}$ denote $(\sigma(1), \dots, \sigma(n))$.

A **transposition** is a permutation $\tau_{i,j}, i \neq j$ such that $\tau_{i,j}(i) = j, \tau_{i,j}(j) = i, \tau_{i,j}(k) = k, \forall k \neq i, j$

denote: $S_n = \{\text{permutation of } \{1, 2, \dots, n\}\}$ is called **symmetric group**

Proposition 5. Every permutation is a product of transposition.

Definition 2.0.2. $f(x_{\sigma(1)}, \dots, x_{\sigma(n)}) = (-1)^m f(x_1, \dots, x_n)$

$(-1)^m$ is called the **sign** of σ , denoted by $\text{sign}(\sigma)$

If $\text{sign}(\sigma) = 1$, then σ is called an even permutation.

If $\text{sign}(\sigma) = -1$, then σ is called an odd permutation.

We can define the determinant with three properties.

Proposition 6. R commutative, $A, B \in M_n(R) \Rightarrow \det(A \cdot B) = \det(A) \det(B)$.

Proposition 7. $\det A = \det A^t$

Proposition 8. $\det A = \sum_{(t_1, t_2, \dots, t_n)} \text{sign}(t_1, \dots, t_n) a_{1, t_1, \dots, n, t_n}$

3 vector space

Definition 3.0.1. A **vector space** over k is an Abelian group $(V, +)$ together with a **scalar multiplication** $k \times V \rightarrow V, (c, v) \mapsto c \cdot v$ such that:

- (1) $1 \cdot v = v$ for $1 \in k$, any $v \in V$
- (2) (associative law) $(ab) \cdot v = a \cdot (b \cdot v)$
- (3) (distributive law)
 - $(a + b) \cdot v = a \cdot v + b \cdot v$
 - $a \cdot (u + v) = a \cdot u + a \cdot v$
 - for all $a, b \in k, u, v \in V$