

1. (a) $\lambda = (z_1, z_2, z_3, z_4)$ means $(z_1, z_2, z_3, z_4) \mapsto (\lambda, 1, 0, \infty)$

By definition, $\lambda = \frac{z_1 - z_3}{z_1 - z_4} \cdot \frac{z_2 - z_4}{z_2 - z_3} \Rightarrow (z_1, z_2, z_3, z_4)$ depends on how the (z_j, z_k, z_l) maps to

$\{1, 0, \infty\}$, i.e.

$$\lambda = (1234) = (2143) = (3412) = (4321)$$

$$1-\lambda = (1324) = (2413) = (3142) = (4231)$$

$$\frac{1}{\lambda} = (1243) = (2134) = (3421) = (4312)$$

$$\frac{1}{1-\lambda} = (1342) = (2431) = (3124) = (4213)$$

$$\frac{\lambda-1}{\lambda} = (1423) = (2314) = (3241) = (4132)$$

$$\frac{\lambda}{\lambda-1} = (1432) = (2341) = (3214) = (4123)$$

$$(b) \text{ By (a), } (1234) = \lambda, (4123) = \frac{\lambda}{\lambda-1} \Rightarrow \begin{cases} |z_2 - z_3|/|z_1 - z_4| = \frac{1}{|\lambda|} |z_1 - z_3|/|z_2 - z_4| \\ |z_1 - z_2| \cdot |z_3 - z_4| = \left| \frac{\lambda-1}{\lambda} \right| |z_1 - z_3| \cdot |z_2 - z_4| \end{cases}$$

Since z_1, \dots, z_4 are distinct, $\lambda \neq 0$. z_1, \dots, z_4 consecutive (on the same circle), $z_2 \mapsto 1, z_3 \mapsto 0, z_4 \mapsto \infty$, we have

$$z_1 \mapsto \lambda > 1 \quad \begin{array}{c} z_4 \\ \infty \\ z_3 \quad z_2 \quad z_1 \\ 0 \quad 1 \quad \lambda \end{array} \Rightarrow \lambda > 0, \frac{\lambda-1}{\lambda} > 0$$

$$\text{Hence } |z_2 - z_3| \cdot |z_1 - z_4| + |z_1 - z_2| \cdot |z_3 - z_4| = |z_1 - z_3| \cdot |z_2 - z_4|$$

2. If given $z_1 \mapsto 1, z_2 \mapsto -1, z_3 \mapsto k, z_4 \mapsto -k$, then let $T = -k \frac{(k+1)z - (k-1)}{(k+1)z + k - 1}$, we have

$T_1 = -1, T_0 = k, T_\infty = -k$. Denote $\lambda = (z_1, z_2, z_3, z_4)$, then TS maps z_2, z_3, z_4 to $-1, k, -k$

$$\Rightarrow T(z_1) = 1. \text{ Hence } \lambda = (z_1, \dots, z_4) = (1, -1, k, -k) = \left(\frac{1-k}{1+k} \right)^2$$

$$\Rightarrow k = \frac{1+\sqrt{\lambda}}{1-\sqrt{\lambda}} \text{ or } \frac{1-\sqrt{\lambda}}{1+\sqrt{\lambda}}. \text{ Here } \lambda = z_2, z_3, z_4 \mapsto 1, 0, \infty.$$

If we only know $\{z_1, \dots, z_4\} \mapsto \{z_1, z_2\}$, then by 1.(a) there are 6 choices of such λ .

3. Assume T maps \mathbb{R} to some circle, and $f: w = Tz \mapsto w^* = T\bar{z}$ be the reflection,

then \forall circle C on \mathbb{C} , $T^{-1}(C)$ is also a circle $\Rightarrow \overline{T^{-1}(C)}$ is a circle.

So $f(C) = T(\overline{T^{-1}(C)})$ is a circle.

$$4. \text{ ① By HW2.b, } T = Re^{i\theta} \frac{z}{R} = e^{i\theta} z, \text{ or } T = Re^{i\theta} \frac{R}{z} = R^2 \frac{e^{i\theta}}{z}, \text{ or } T = \frac{Re^{i\theta} \frac{z}{R} - \alpha}{\alpha \frac{z}{R} - 1} = \frac{Rz - \alpha R^2}{\alpha z - R} e^{i\theta} (\alpha \in \mathbb{C})$$

$$\text{② Assume } T = \frac{az+b}{cz+d}, \text{ if } a=0, \text{ then } T = R^2 \frac{e^{i\theta}}{z}; \text{ if } c=0, \text{ then } T = Re^{i\theta} z.$$

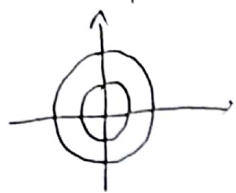
If $a, c \neq 0$, then $T(\frac{b}{a}) = 0, T(\frac{d}{c}) = \infty$ is a pair of symmetric points $\Rightarrow \frac{b}{a}, \frac{d}{c}$ are symmetric points.

$$\text{Let } \alpha = \frac{b}{a}, \text{ then } \frac{d}{c} = \frac{R^2}{\alpha} \Rightarrow T = \frac{a\bar{\alpha}}{c} \frac{z - \alpha}{\alpha z - R^2}. \text{ Take } z = R, \text{ then } |Tz| = R \Rightarrow \left| \frac{a\bar{\alpha}}{c} \right| = R^2$$

$$\text{Hence } T = R^2 e^{i\theta} \frac{z - \alpha}{\alpha z - R^2}. (\alpha \in \mathbb{C})$$



5. We may assume the circles has center $z=0$ and radii $R>Y$.



Let T be the Möbius transformation, and $T(R), T(Y)$ has center γ ,

then $R' = |Tz - \gamma|$ on $|z|=R$, $Y' = |Tz - \gamma|$ on $|z|=Y$.

Let $S = T - \gamma$, then by Ex 4 we have $S = \frac{R'}{R} e^{i\theta} z = \frac{Y'}{Y} e^{i\theta'} z$, or $S = e^{i\theta} R' \frac{R}{z} = e^{i\theta'} Y' \frac{Y}{z}$

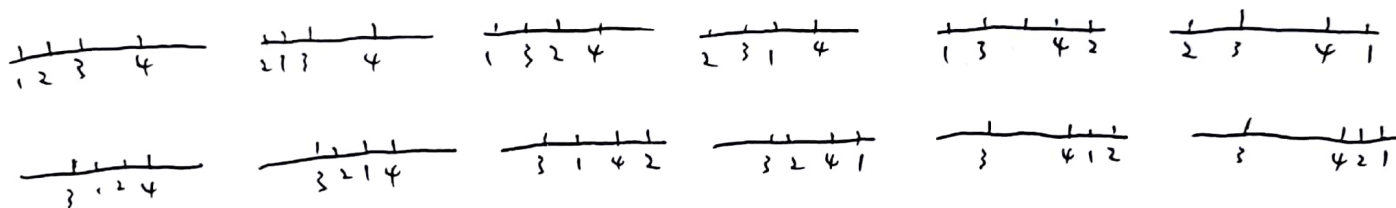
or $S = R' e^{i\theta} \frac{\frac{z}{R} - \alpha}{\bar{\alpha} \frac{z}{R} - 1} = Y' e^{i\theta'} \frac{\frac{z}{Y} - \alpha'}{\bar{\alpha}' \frac{z}{Y} - 1}$. In all case the ratios are the same.

6. We can find a Möbius function that maps the circle to \mathbb{R} .

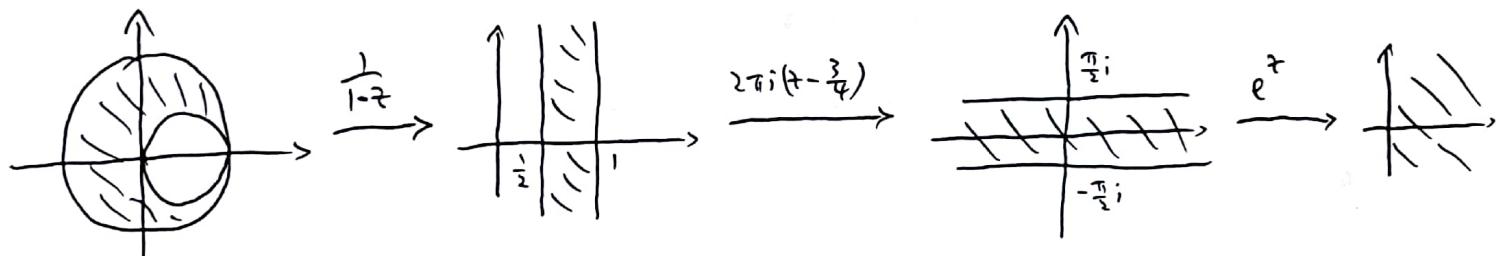
Since Möbius function doesn't change the orientation, we can assume $z_i \in \mathbb{R}$.

By definition $(z_1, z_2, z_3, z_4) = \frac{z_1 - z_3}{z_1 - z_4} \cdot \frac{z_2 - z_4}{z_2 - z_3}$, and it's easy to check that $(z_1, z_3, z_4), (z_2, z_3, z_4)$ ~~has~~

have the same orientation $\Leftrightarrow (z_1, z_2, z_3, z_4) > 0$ from the following 12 cases:



7.



8.

