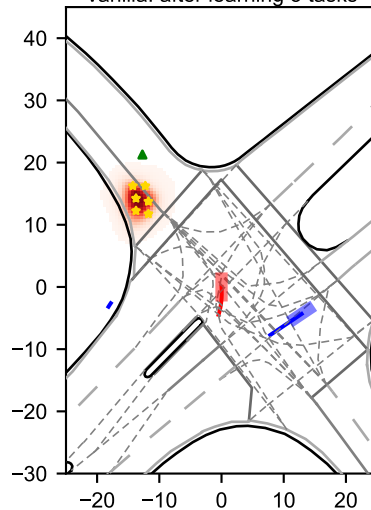
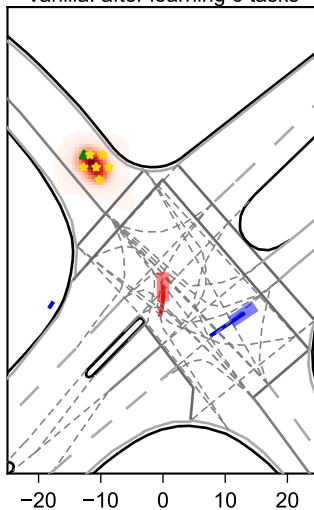


— Observed trajectories of TV      — Observed trajectories of background vehicle      ▲ Ground truth      ★ Predicted goal

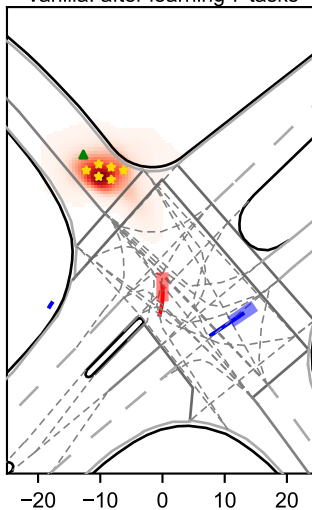
Vanilla: after learning 5 tasks



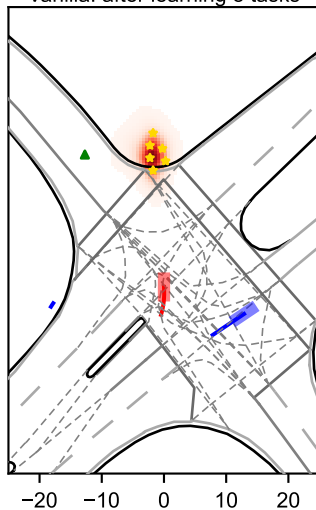
Vanilla: after learning 6 tasks



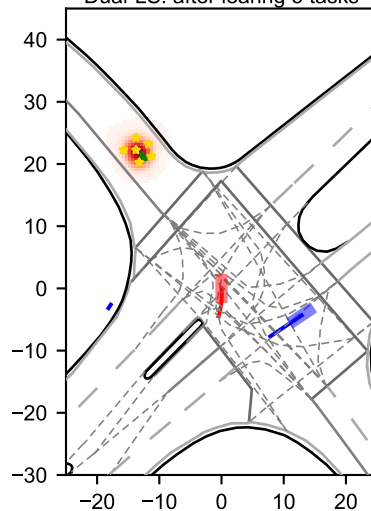
Vanilla: after learning 7 tasks



Vanilla: after learning 8 tasks



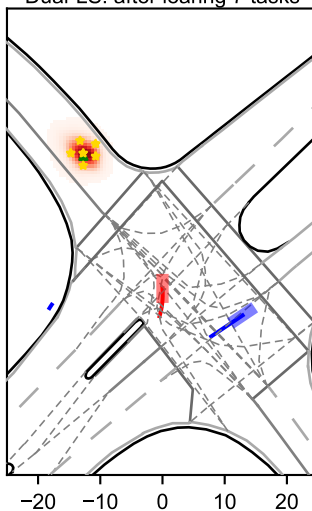
Dual-LS: after learning 5 tasks



Dual-LS: after learning 6 tasks



Dual-LS: after learning 7 tasks



Dual-LS: after learning 8 tasks

