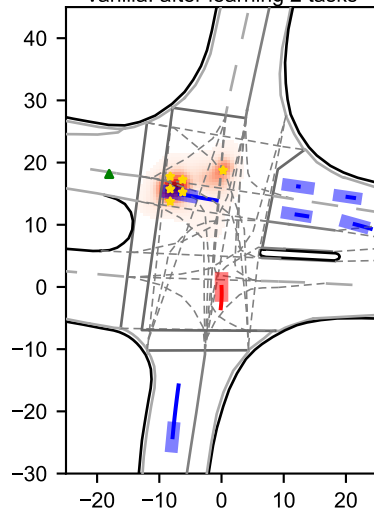
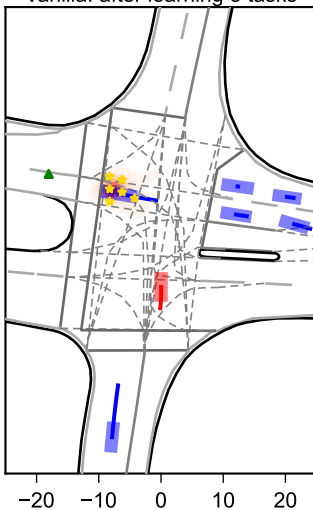


— Observed trajectories of TV      — Observed trajectories of background vehicle      ▲ Ground truth      ★ Predicted goal

Vanilla: after learning 2 tasks



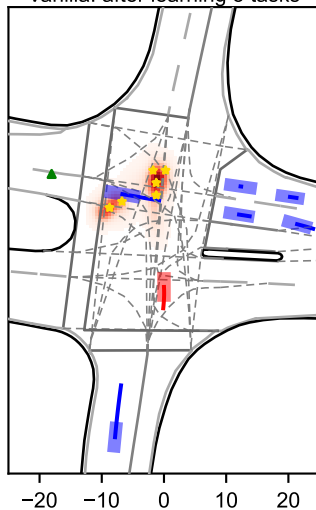
Vanilla: after learning 3 tasks



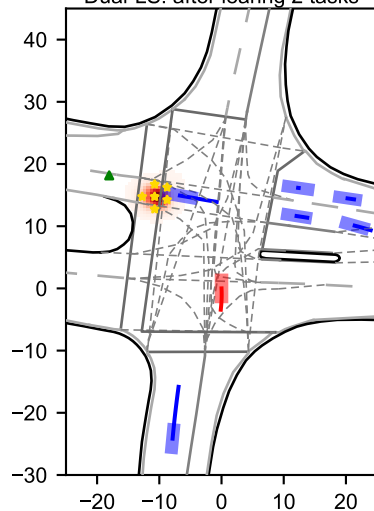
Vanilla: after learning 4 tasks



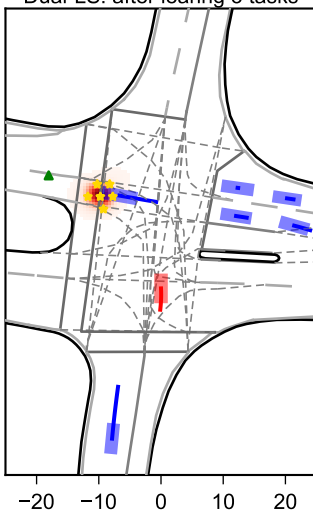
Vanilla: after learning 5 tasks



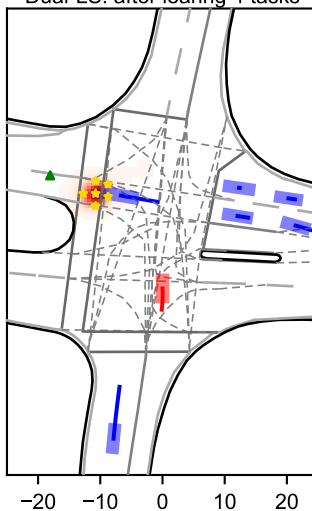
Dual-LS: after learning 2 tasks



Dual-LS: after learning 3 tasks



Dual-LS: after learning 4 tasks



Dual-LS: after learning 5 tasks

