Back to Basics: Lambdas from Scratch

Plain old functions

```
int plus1(int x)
{
    return x+1;
}
```

```
__Z5plus1i:
leal 1(%rdi), %eax
retq
```

Function overloading

```
int plus1(int x)
    return x+1;
double plus1(double x)
    return x+1;
```

```
__Z5plus1i:
    leal 1(%rdi), %eax
    retq

__Z5plus1d:
    addsd LCPI1_0(%rip), %xmm0
    retq
```

Function templates

```
template<typename T>
T plus1(T x)
    return x+1;
auto y = plus1(42);
auto z = plus1(3.14);
```

```
_Z5plus1IiET_S0_:
    leal 1(%rdi), %eax
    retq

_Z5plus1IdET_S0_:
    addsd LCPI1_0(%rip), %xmm0
    retq
```

Class member functions

```
ZN4PlusC1Ei:
class Plus {
                                      movl %esi, (%rdi)
     int value;
                                      retq
  public:
                                   ZN4Plus6plusmeEi:
     Plus(int v);
                                      addl (%rdi), %esi
                                      movl %esi, %eax
                                      retq
     int plusme(int x) const {
          return x + value;
```

"Which function do we call?"

```
auto plus = Plus(1);
auto x = plus.plusme(42);
assert(x == 43);
```

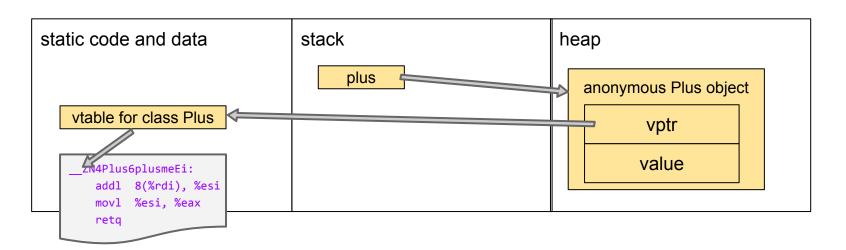
"The plusme function of the Plus class"

C++ is not Java!

The Java approach

```
auto plus = Plus(1);
auto x = plus.plusme(42);
assert(x == 43);
```

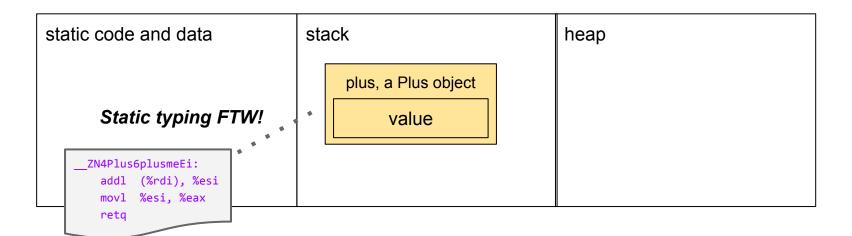
C++ lets you do this, but it's not the default.



The C++ approach

```
auto plus = Plus(1);
auto x = plus.plusme(42);
assert(x == 43);
```

```
movl $1, %esi
leaq -16(%rbp), %rdi
callq __ZN4PlusC1Ei
movl $42, %esi
leaq -16(%rbp), %rdi
callq __ZN4Plus6plusmeEi
```



Class member functions (recap)

```
ZN4PlusC1Ei:
class Plus {
                                      movl %esi, (%rdi)
     int value;
                                      reta
  public:
                                   ZN4Plus6plusmeEi:
     Plus(int v);
                                      addl (%rdi), %esi
                                      movl %esi, %eax
                                      retq
     int plusme(int x) const {
          return x + value;
                                      auto plus = Plus(1);
                                      auto x = plus.plusme(42);
```

Operator overloading

```
ZN4PlusC1Ei:
class Plus {
                                      movl %esi, (%rdi)
     int value;
                                      retq
  public:
                                   ZN4PlusclEi:
     Plus(int v);
                                      addl (%rdi), %esi
                                      movl %esi, %eax
                                      retq
     int operator() (int x) const {
          return x + value;
                                     auto plus = Plus(1);
                                     auto x = plus(42);
```

So now we can make something kind of nifty...

Lambdas reduce boilerplate

```
class Plus {
    int value;
  public:
    Plus(int v): value(v) {}
    int operator() (int x) const {
        return x + value;
auto plus = Plus(1);
assert(plus(42) == 43);
```

Lambdas reduce boilerplate

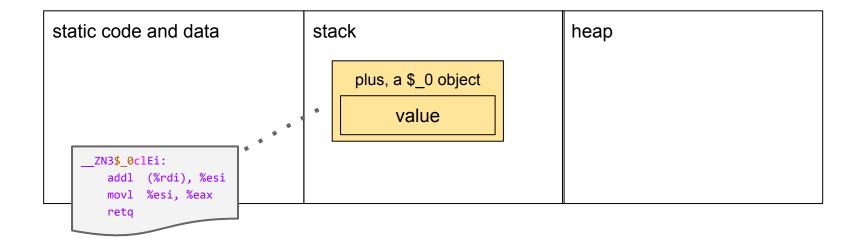
```
auto plus = [value=1](int x) { return x + value; };
```

```
assert(plus(42) == 43);
```

Same implementation

```
auto plus = [value=1](int x) {
    return x + value;
};
```

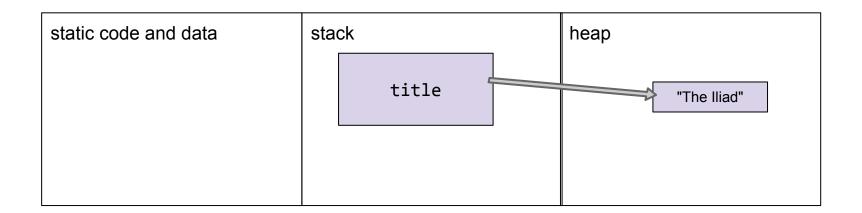
```
movl $1, %esi
leaq -16(%rbp), %rdi
callq __ZN3$_0C1Ei
movl $42, %esi
leaq -16(%rbp), %rdi
callq __ZN3$_0clEi
```



Closures without garbage collection

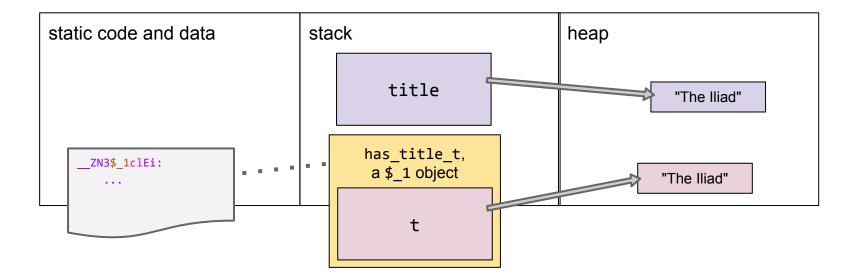
```
bool contains title(const std::vector<Book>& shelf,
                    std::string title)
    auto has_title_t = [t=title](const Book& b) {
        return b.title() == t;
    };
    return v.end() !=
        std::find if(v.begin(), v.end(), has title t);
```

Closures without garbage collection



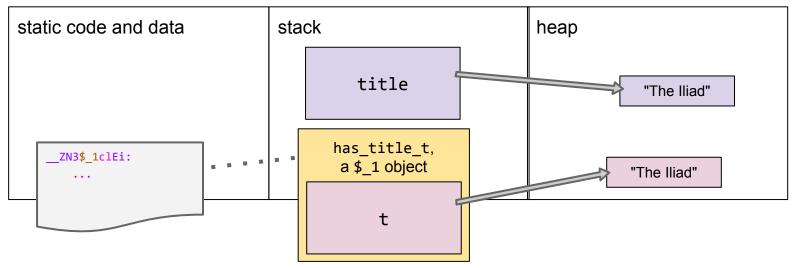
Closures without garbage collection

```
auto has_title_t = [t=title](const Book& b) {
    return b.title() == t;
};
```

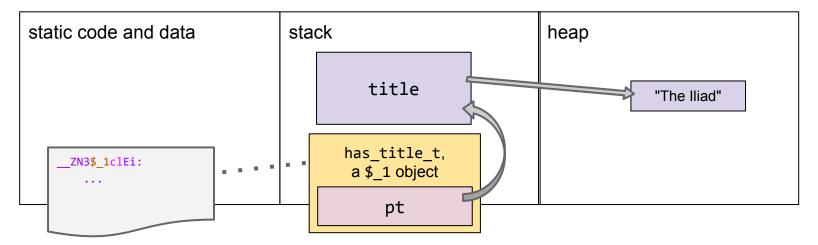


Copy semantics by default

```
auto has_title_t = [t=title](const Book& b) {
    return b.title() == t;
};
auto t=title; would make a
    copy of the string. Likewise,
    with [t=title], the lambda
    captures a copy of the string.
```

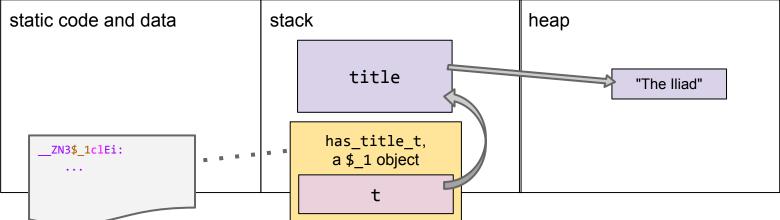


Capturing a pointer



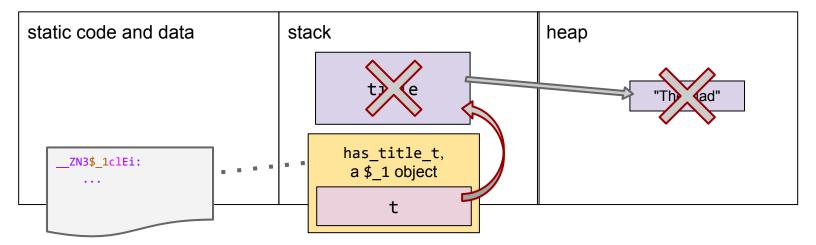
Capturing a reference

```
auto has_title_t = [&t=title](const Book& b) {
    return b.title() == t;
};
auto &t=title; and likewise
[&t=title] mean to capture a
    reference that refers to title.
```



Beware of dangling references

```
auto has_title_t = [&t=title](const Book& b) {
    return b.title() == t;
};
return has_title_t;
```



Capturing "by move"?

```
auto has_title_t = [t=title](const Book& b) {
          return b.title() == t;
                                                                  This copies title into the
                                                                   lambda's captured state.
    };
                                                                     What if we wanted to
                                                                     move it in, instead?
static code and data
                                                        heap
                            stack
                                     title
                                                                    "The Iliad"
                                  has title t,
    ZN3$ 1clEi:
                                   a $ 1 object
                                                                   "The Iliad"
```

Capturing "by move"

```
auto has_title_t = [t=std::move(title)](const Book& b) {
                                                                auto t=std::move(title);
         return b.title() == t;
                                                                       and likewise
    };
                                                               [t=std::move(title)] capture
                                                                a string by value, but prefer
                                                                   the move-constructor.
static code and data
                                                      heap
                           stack
                                   title
                                                                 "The Iliad"
                                 has title t,
   ZN3$ 1clEi:
                                 a $ 1 object
                                                                                       24
```

Many redundant shorthands

```
• [t=title]() { decltype(title) ... use(t); }
  [title]() { decltype(title) ... use(title); }
                                                      No array decay
 [&t=title]() { use(t); }
  [&title]() { use(title); }
  To capture only what is "needed" —
   o [=]() { use(title); }

  [&]() { use(title); } The most useful!
```

Globals/statics aren't captured; neither are unevaluated operands

Puzzle

```
#include <stdio.h>
int g = 10;
auto kitten = [=]() { return g+1; };
auto cat = [g=g]() { return g+1; };
int main() {
    g = 20;
    printf("%d %d\n", kitten(), cat());
```

Puzzle

```
#include <stdio.h>
int g = 10;
auto kitten = [=]() { return g+1; };
auto cat = [g=g]() { return g+1; };
int main() {
    g = 20;
    printf("21 11\n", kitten(), cat());
```

Other features of lambdas

Convertible to raw function pointer (if captureless)

```
int (*fp)(int) = [](int x) { return x + 1; };
```

This is a very common idiom in some kinds of C++ code.

The unary + operator forces any expression to "scalar" type. For most types that's not very useful. But for lambdas it's idiomatic!

```
template<class T> void fn(T t);
fn(+[:](int x){ return x+1; }); // calls fn<int(*)(int)>
```

Other features of lambdas

Default-constructible (if captureless)

```
auto lam = [](int x) { return x + 1; };
decltype(lam) copy; // OK!
```

Constexpr by default, but not noexcept by default

```
static_assert(lam(42) == 43); // OK!
static_assert(not noexcept(lam(42)));
New in C++17!
```

Lambdas may have local state (but not in the way you think)

```
auto counter = []() { static int i; return ++i; };
auto c1 = counter;
auto c2 = counter; // make two copies of the counter
std::cout << c1() << c1() << c1() << '\n';
std::cout << c2() << c2() << c2() << '\n';
 // 123
 // 456
```

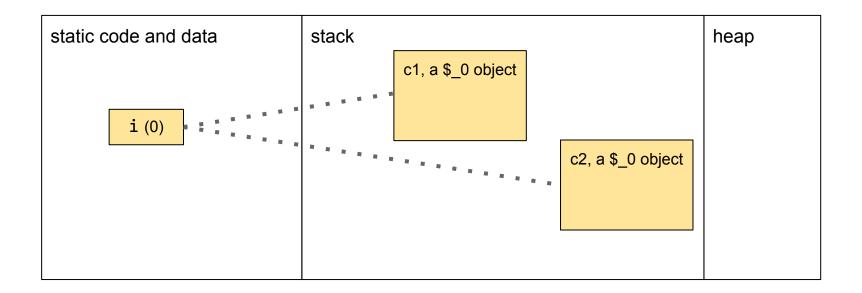
```
auto counter = []() { static int i; return ++i; };
```

That closure type behaves just like the following class type:

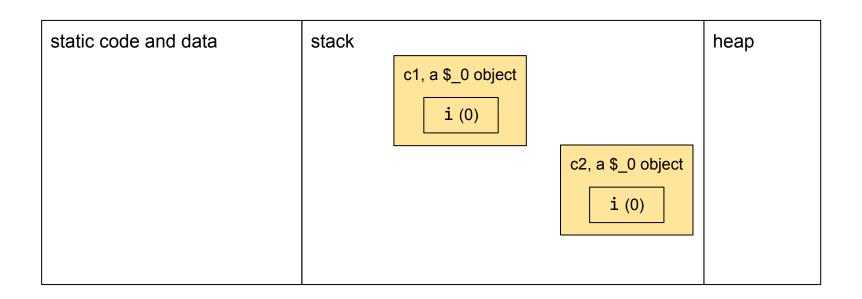
```
class Counter {
    // no captured data members
public:
    int operator() const {
        static int i; return ++i;
    }
};
```

There is just one static i, shared by **all** callers of Counter::operator()!

```
[]() { static int i; return ++i; };
```



```
[i=0]() { return ++i; };
```

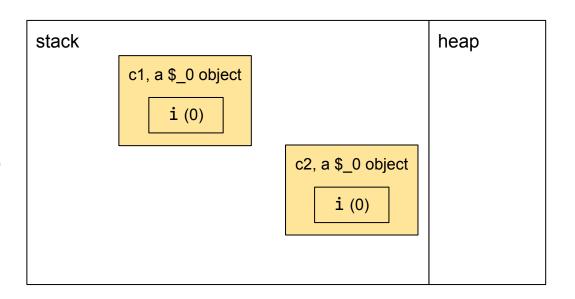


```
[i=0]() { return ++i; };
```

Compiler errors!

error: increment of
read-only variable 'i'

error: cannot assign to
a variable captured by
copy in a non-mutable
lambda



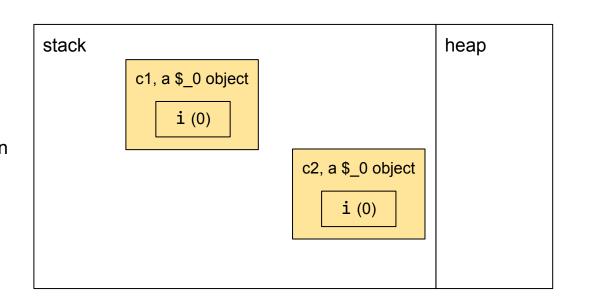
Per-lambda mutable state (right)

```
[i=0]() mutable { return ++i; };
```

mutable does not affect the constness of the data members themselves.

It affects the const-qualification of the lambda type's operator().

Therefore it is all-or-nothing.



Lambdas + Templates = Generic Lambdas

Class member function templates

```
class Plus {
    int value;
  public:
    Plus(int v);
    template<class T>
    T plusme(T x) const {
        return x + value;
```

```
ZNK4Plus6plusmeIiEET S1 :
   addl (%rdi), %esi
   movl %esi, %eax
   reta
ZNK4Plus6plusmeIdEET S1 :
   cvtsi2sdl (%rdi), %xmm1
   addsd %xmm0, %xmm1
           %xmm1, %xmm0
   movaps
   retq
  auto plus = Plus(1);
  auto x = plus.plusme(42);
  auto y = plus.plusme(3.14);_{37}
```

Class member function templates

```
ZNK4PlusclIiEET S1:
class Plus {
                                       addl (%rdi), %esi
     int value;
                                       movl %esi, %eax
                                       reta
  public:
     Plus(int v);
                                    ZNK4PlusclIdEET S1:
                                       cvtsi2sdl (%rdi), %xmm1
                                       addsd %xmm0, %xmm1
     template<class T>
                                       movaps %xmm1, %xmm0
                                       retq
     T operator()(T x) const {
          return x + value;
                                      auto plus = Plus(1);
                                      auto x = plus(42);
                                      auto y = plus(3.14);
```

So now we can make something kind of nifty...

Generic lambdas reduce boilerplate

```
class Plus {
    int value;
  public:
    Plus(int v): value(v) {}
    template<class T>
    auto operator() (T x) const {
        return x + value;
auto plus = Plus(1);
assert(plus(42) == 43);
```

Generic lambdas reduce boilerplate

```
auto plus = [value=1](auto x) { return x + value; };
```

```
assert(plus(42) == 43);
```

Generic lambdas are just templates under the hood.

Variadic function templates

```
ZNK4PlusclIJidiEEEDaDpT :
class Plus {
                                            cvtsi2sdl %esi, %xmm2
                                            addl (%rdi), %edx
  int value;
                                            cvtsi2sdl %edx, %xmm1
public:
                                            addsd %xmm1, %xmm0
                                            addsd %xmm2, %xmm0
  Plus(int v);
                                            reta
                                           ZNK4PlusclIJPKciEEEDaDpT :
  template<class... As>
                                            addl (%rdi), %edx
                                            movslq %edx, %rax
  auto operator()(As... as) {
                                            addq %rsi, %rax
                                            reta
     return sum(as..., value);
                                           auto plus = Plus(1);
                                           auto x = plus(42, 3.14, 1);
                                           auto y = plus("foobar", 2);_{43}
```

Variadic lambdas reduce boilerplate

```
class Plus {
    int value;
  public:
    Plus(int v): value(v) {}
    template<class... As>
    auto operator() (As... as) const {
        return sum(as..., value);
auto plus = Plus(1);
assert(plus(42, 3.14, 1) == 47.14);
```

Variadic lambdas reduce boilerplate

```
auto plus = [value=1](auto... as) {
    return sum(as..., value);
};

assert(plus(42, 3.14, 1) == 47.14);
```

What is this in a lambda?

What is this in a lambda?

```
auto has_title_t = [t=title](const Book& b) {
    return b.title() == t;
};
```

You might think that t (being a member of the underlying closure instance) should also be accessible inside the lambda via "this->t."

Not so!

The underlying closure instance is just that: *underlying*. It's how the lambda is *implemented*. But at the source level, we want this to expose a different property...

What is this in a lambda?

```
class Widget {
    void work(int);
                                                             It's good that these two
    void synchronous_foo(int x) {
                                                             "this" expressions mean
         this->work(x);
                                                                the same thing!
                                                               We can reuse code
                                                             snippets without counting
    void asynchronous_foo(int x) {
                                                              brackets so carefully.
         fire_and_forget([=]() {
              this->work(x);
         });
```

Ways of capturing this

```
[this]() { this->work(); }
      Both equivalent to [ptr=this]() { ptr->work(); }
• [&]() { this->work(); }
     Also equivalent to [ptr=this]() { ptr->work(); }
• New in C++17! [*this]() { this->work(x); }
      Equivalent to [obj=*this]() { obj.work(); }

    "Capture *this by move" has no shorthand equivalent.

     Just write [obj=std::move(*this)]() { obj.work(x); }
```

How do I name the parameter type(s) of a generic lambda?

What's the T in std::forward<T>?

```
auto plus = [](auto... args) {
    return sum(args...);
};

auto times = [](auto&&... args) {
    return product(std::forward<???>(args)...);
};
```

Two possible solutions (at least)

```
auto one = [](auto&&... args) {
    return product(std::forward<decltype(args)>(args)...);
};

auto two = []<class... Ts>(Ts&&... args) {
    return product(std::forward<Ts>(args)...);
};
```

Note — std::forward<Ts> can always be spelled static_cast<Ts&&>, or std::forward<decltype(a)> can be spelled static_cast<decltype(a)>, to save some template instantiations.

"So are lambdas kind of like std::function, then?" "Why does C++ have both?"

Come to my next talk!

Type Erasure From Scratch

1:30pm today in Aurora A

How do I write functions that accept lambdas as arguments?

How do I pass lambdas around?

The "STL" way to accept lambdas is to make all your code into templates, and define those templates in header files.

```
class Shelf {
     template<class Func>
    void for_each_book(Func f) {
          for (const Book& b : books_) f(b);
                                                           This template definition must
                                                           be visible in the same TU as a
                                                          declaration of $_1::operator()
                                                             — so, the same TU as the
                      Suppose this lambda type
                                                                 lambda itself.
                        gets mangled as $ 1.
Shelf myshelf;
myshelf.for each book([](auto&& book){ book.print(); });
```

How do I pass lambdas around?

Alternatively, you can use *type erasure* to capture your lambda inside a library type that exposes just the call operator.

```
class Shelf {
    void for_each_book(ConcreteCBType f) {
        for (const Book& b : books_) f(b);
    }
    We construct a
};
ConcreteCBType object (by implicit conversion) from our original rvalue of type $_1.
Shelf myshelf;
myshelf.for_each_book([](auto&& book){ book.print(); });
This function definition must be in the same TU as a declaration of ConcreteCBType::operator() — so, you have more freedom where to place it.
```

ConcreteCBType might just be an alias for std::function<void(const Book&)>.

How do I pass lambdas around?

Perhaps write a template interface with a type-erased implementation. Look, ma, no implicit conversions!

```
class Shelf {
   using ConcreteCBType = FunctionRef<void(const Book&)>;
   void for each book impl(const ConcreteCBType& f);
public:
    template<class F>
   void for each book(const F& f) {
        for each book_impl(ConcreteCBType(f));
```

Lambdas may be copyable or not

```
std::unique_ptr<int> prop;
auto lamb = [p = std::move(prop)]() { };
auto lamb2 = std::move(lamb); // OK
auto lamb3 = lamb; // error: call to implicitly-deleted copy constructor
```

A lambda's type is copyable, movable, or neither, depending as its captures are copyable, movable, or neither.

```
std::function is always copyable.
```

Therefore, there are some lambdas that can't be stored in a std::function.

```
std::function<void()> f = std::move(lamb); // cascade of errors
```

Working around noncopyability

```
auto lamb = something move-only;
Consider placing the single instance on the heap and sharing access to it:
    std::function<void()> f3 = [
        p = std::make shared<decltype(lamb)>(std::move(lamb))
    1() { (*p)(); };
Or use a move-only function type such as folly::Function.
    my::unique function<void()> f4 = std::move(lamb); // OK
```

Every codebase needs a move-only function type!

Questions?

Puzzle footnote

```
int g = 10;
auto ocelot = [g]() { return g+1; };
```

The above is ill-formed and requires a diagnostic.

5.1.2 [expr.prim.lambda]/10: The *identifier* in a *simple-capture* is looked up using the usual rules for unqualified name lookup (3.4.1); each such lookup **shall** find an entity. An entity that is designated by a *simple-capture* is said to be *explicitly captured*, and **shall** be this or a variable **with automatic storage duration** declared in the reaching scope of the local lambda expression.

In GCC this is just a warning, and the lambda does not capture g's value.