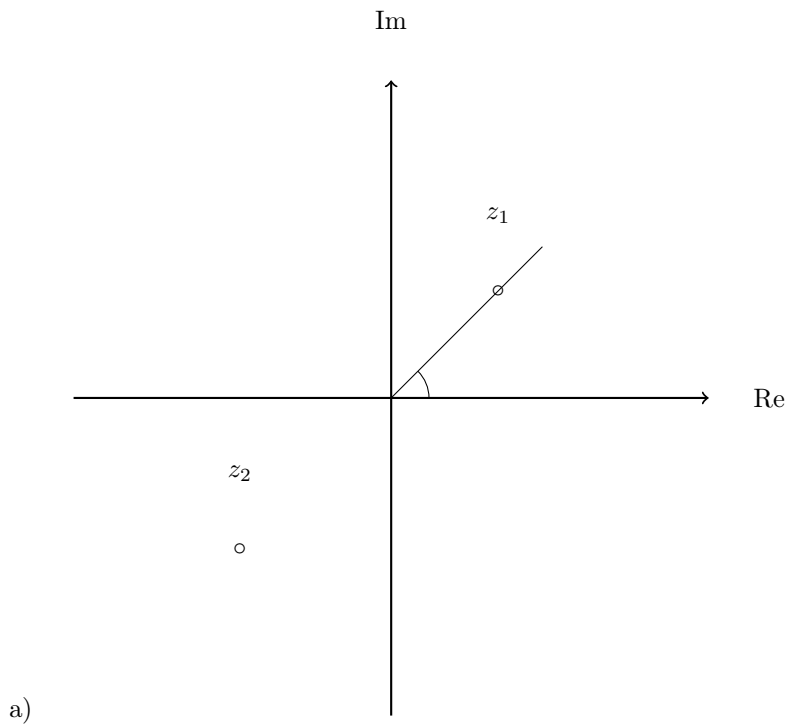


MAT110 - Obligatorisk innlevering 1

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Oppgave 1



b)

$$\begin{aligned}
 z_1 &= e^{i\frac{\pi}{4}} \quad (\text{eksponentialform}) \\
 e^{i\frac{\pi}{4}} &\rightarrow r = 1, \quad \theta = \frac{\pi}{4} \\
 &= 1(\cos \theta + i \cdot \sin \theta) \\
 &= \cos \frac{\pi}{4} + i \cdot \sin \frac{\pi}{4} \\
 &= x_1 + i \cdot y_1 \\
 \Rightarrow x_1 &= \cos \frac{\pi}{4} = \frac{1}{\sqrt{2}} = \frac{\sqrt{2}}{2} \\
 \Rightarrow y_1 &= \sin \frac{\pi}{4} = \frac{1}{\sqrt{2}} = \frac{\sqrt{2}}{2} \\
 z_1 &= \frac{\sqrt{2}}{2} + i \cdot \frac{\sqrt{2}}{2} \quad (\text{standardform})
 \end{aligned}$$

$$\begin{aligned}
 z_2 &= -1 - i \quad (\text{standardform}) \\
 &= x_2 + i \cdot y_2 \rightarrow x_2 = -1, \quad y_2 = -1 \\
 r &= \sqrt{x_2^2 + y_2^2} = \sqrt{(-1)^2 + (-1)^2} = \sqrt{2} \\
 \theta &= \tan^{-1}\left(\left|\frac{y}{x}\right|\right) \quad (\text{Generelt})
 \end{aligned}$$

Men ettersom det komplekse tallet er i 3. kvadrant $\rightarrow \theta = \alpha + \pi$

$$\alpha = \tan^{-1}\left(\left|\frac{-1}{-1}\right|\right) = \tan^{-1}(1) = \frac{\pi}{4}$$

$$\theta = \pi + \frac{\pi}{4} = \frac{5\pi}{4}$$

$$z_2 = r(\cos \theta + i \cdot \sin \theta)$$

$$z_2 = \sqrt{2}\left(\cos \frac{5\pi}{4} + i \cdot \sin \frac{5\pi}{4}\right)$$

$$z_2 = \sqrt{2} \cdot e^{i\frac{5\pi}{4}} \quad (\text{eksponentialform})$$

c)

$$\begin{aligned} z_1 + z_2 &= \left(\frac{\sqrt{2}}{2} + \sqrt{2}i\right) + (-1 - i) \\ &= \left(\frac{\sqrt{2}}{2} - 1\right) + \left(\frac{\sqrt{2}}{2} - 1\right) \cdot i \\ &= (0.7071 - 1) + (0.7071 - 1) \cdot i \\ &= -0.29 - 0.29i \end{aligned}$$

$$\begin{aligned} \frac{z_1}{z_2} &= \frac{e^{i\frac{\pi}{4}}}{\sqrt{2}e^{i\frac{5\pi}{4}}} = \frac{1}{\sqrt{2}}e^{i\frac{\pi}{4}-i\frac{5\pi}{4}} = \frac{1}{\sqrt{2}}e^{-i\pi} \\ &= \frac{1}{\sqrt{2}}(\cos(-\pi) + i\sin(-\pi)) = \frac{1}{\sqrt{2}}(-1 + i(0)) = -\frac{1}{\sqrt{2}} + i0 \\ &= -\frac{\sqrt{2}}{2} \end{aligned}$$

$$\begin{aligned} z_1 &= \frac{\sqrt{2}}{2} + i\frac{\sqrt{2}}{2} \\ \bar{z}_1 &= \frac{\sqrt{2}}{2} - i\frac{\sqrt{2}}{2} \\ -\bar{z}_1 &= -1\left(\frac{\sqrt{2}}{2} - i\frac{\sqrt{2}}{2}\right) = -\frac{\sqrt{2}}{2} + i\frac{\sqrt{2}}{2} \end{aligned}$$

d) $z^6 = 1 + i$. La $w = 1 + i$, da må vi finne den 6. roten av w .

Først konverterer vi w til eksponentialform.

$$r = \sqrt{1^2 + 1^2} = \sqrt{2}$$

$$\theta = \tan^{-1}(1) = \frac{\pi}{4}$$

$$w = 1 + i = \sqrt{2}e^{i\frac{\pi}{4}}$$

Videre tar vi i bruk De Moivres thm for røtter:

Hvis $z^n = w = re^{i\theta}$, da er røttene gitt ved $z_k = \sqrt[n]{r}e^{i(\frac{\theta+2\pi k}{n})}$, for $k = 0, 1, 2, \dots, n-1$.

I dette tilfellet blir $n = 6, r = \sqrt{2}$ og $\theta = \frac{\pi}{4}$.

$$\sqrt[6]{r} = \sqrt[6]{\sqrt{2}} = \sqrt[6]{2^{\frac{1}{2}}} = 2^{(\frac{1}{2})(\frac{1}{6})} = 2^{\frac{1}{12}} = \sqrt[12]{2}.$$

Videre finner vi argumentene for $k = 0, 1, 2, 3, 4, 5$:

Det generelle argumentet er $\phi_k = \frac{\frac{\pi}{4} + 2\pi k}{6} = \frac{\pi}{24} + \frac{2\pi k}{6} = \frac{\pi}{24} + \frac{\pi k}{3}$.

$$\begin{aligned} k = 0 : \phi_0 &= \frac{\pi}{24} \\ k = 1 : \phi_1 &= \frac{\pi}{24} + \frac{\pi}{3} = \frac{9\pi}{24} \\ k = 2 : \phi_2 &= \frac{\pi}{24} + \frac{2\pi}{3} = \frac{17\pi}{24} \\ k = 3 : \phi_3 &= \frac{\pi}{24} + \pi = \frac{25\pi}{24} \\ k = 4 : \phi_4 &= \frac{\pi}{24} + \frac{4\pi}{3} = \frac{33\pi}{24} \\ k = 5 : \phi_5 &= \frac{\pi}{24} + \frac{5\pi}{3} = \frac{41\pi}{24} \end{aligned}$$

Det er seks løsninger:

$$z_k = 2^{\frac{1}{12}} \cdot e^{i\phi_k}, \text{ for } k = 0, 1, 2, 3, 4, 5.$$

Oppgave 2

$$\text{a)} \quad \begin{bmatrix} 1 & 0 & 2k & k & 2 \\ 1 & 1 & (2k-1) & 0 & 1 \\ -2 & 0 & -4k & k & 5 \end{bmatrix} - R_1 + R_2 \begin{bmatrix} 1 & 0 & 2k & k & 2 \\ 0 & 1 & -1 & -k & -1 \\ -2 & 0 & -4k & k & 5 \end{bmatrix} 2R_1 + R_3 \begin{bmatrix} 1 & 0 & 2k & k & 2 \\ 0 & 1 & -1 & -k & -1 \\ 0 & 0 & 0 & 3k & 5 \end{bmatrix}$$

$$(1) \quad x_1 + 2kx_3 + kx_4 = 2$$

$$(2) \quad x_2 - x_3 - kx_4 = -1$$

$$(3) \quad 3kx_4 = 9$$

$$\text{b)} \quad \text{Fra (3)} \quad 3kx_4 = 9$$

Case 1:

$$k \neq 0 \Rightarrow x_4 = \frac{3}{k}$$

Vi setter $x_4 = \frac{3}{k}$ inn i (2):

$$x_2 = x_3 + k\frac{3}{k} - 1 = x_3 + 2$$

Så vi trenger verdien til x_3 for å beregne x_2 .

Vi setter $x_4 = \frac{3}{k}$ inn i (1):

$$x_1 + 2kx_3 + k\frac{3}{k} = x_1 + 2kx_3 + 3 = 2$$

$$\Rightarrow x_1 = -1 - 2kx_3$$

For $x \neq$, x_1 og x_2 er uttrykt med bruk av den frie variablen x_3 .

Derfor er det uendelig mange løsninger for alle $k \neq 0$.

Case 2:

$$k = 0 \Rightarrow (3) \text{ blir } 0 \cdot x_4 = 9 \Rightarrow 0 = 9.$$

Dette er umulig og vi kan konkludere at det er ingen løsning for $k = 0$.

Utifra dette kan vi konkludere at det kan ikke være akkurat en eller akkurat to løsninger i dette tilfelle.

c)

$$(3) \quad (3)(6)x_4 = 9 \Rightarrow 18x_4 = 9 \Rightarrow x_4 = \frac{1}{2}$$

$$(2) \quad x_2 - x_3 - 6\left(\frac{1}{2}\right) = -1 \Rightarrow x_2 - x_3 - 3 = -1 \Rightarrow x_2 = x_3 + 2$$

$$(1) \quad x_1 + 2(6)x_3 + 6\left(\frac{1}{2}\right) = 2 \Rightarrow x_1 + 12x_3 + 3 = 2 \Rightarrow x_1 = -1 - 12x_3$$

$$\therefore (x_1, x_2, x_3, x_4) = (-1 - 12t, t + 2, t, \frac{1}{2}), t \in \mathbb{R} \quad (\text{Uendelig mange løsninger})$$

Oppgave 3

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & -1 \\ 2 & 3 & 3 \end{bmatrix}, \quad B = \begin{bmatrix} 1 & 1 \\ 1 & -1 \\ -1 & 2 \end{bmatrix}$$

a) $A + B$ er ikke mulig ettersom matrisene har ulike dimensjoner.

$$3A = \begin{bmatrix} 3 & 3 & 3 \\ 3 & 6 & -3 \\ 6 & 9 & 9 \end{bmatrix}, \quad B^T = \begin{bmatrix} 1 & -1 & 2 \\ 1 & 1 & -1 \end{bmatrix}$$

$3A - B^T$ er ikke mulig ettersom matrisene har ulike dimensjoner.

$$AB = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & -1 \\ 2 & 3 & 3 \end{bmatrix} \cdot \begin{bmatrix} 1 & 1 \\ 1 & -1 \\ -1 & 2 \end{bmatrix} = \begin{bmatrix} 1*1+1*1+1(-1) & 1*1+1(-1)+1*2 \\ 1*1+2*1-1(-1) & 1*1+2(-1)-1*2 \\ 2*1+3*1+3(-1) & 2*1+3(-1)+3*2 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 4 & -3 \\ 2 & 5 \end{bmatrix}$$

BA er ikke mulig ettersom dimensjonene på matrisene må være $m \times p \cdot p \times n$ for å gjennomføre multiplikasjon.

$$B^T A = \begin{bmatrix} 1 & 1 & -1 \\ 1 & -1 & 2 \end{bmatrix} \cdot \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & -1 \\ 2 & 3 & 3 \end{bmatrix} = \begin{bmatrix} 1(1)+1(1)-1(2) & 1(1)+1(2)-1(3) & 1(1)+1(-1)-1(3) \\ 1(1)-1(1)+2(2) & 1(1)-1(2)+2(3) & 1(1)-1(-1)+2(3) \end{bmatrix} = \begin{bmatrix} 0 & 0 & -3 \\ 4 & 5 & 8 \end{bmatrix}$$

b) $A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & -1 \\ 2 & 3 & 3 \end{bmatrix}$

$$\begin{aligned} \det(A) &= 1 \cdot \begin{vmatrix} 2 & -1 \\ 3 & 3 \end{vmatrix} - 1 \cdot \begin{vmatrix} 1 & -1 \\ 2 & 3 \end{vmatrix} + 1 \cdot \begin{vmatrix} 1 & 2 \\ 2 & 3 \end{vmatrix} \\ &= 1 \cdot (6 + 3) - 1(3 + 2) + 1(3 - 4) \\ &= 9 - 5 - 1 = 3 \end{aligned}$$

c) $\left[\begin{array}{ccc|ccc} 1 & 1 & 1 & 1 & 0 & 0 \\ 1 & 2 & -1 & 0 & 1 & 0 \\ 2 & 3 & 3 & 0 & 0 & 1 \end{array} \right] \sim -R_1 + R_2 \left[\begin{array}{ccc|ccc} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & -2 & -1 & 1 & 0 \\ 2 & 3 & 3 & 0 & 0 & 1 \end{array} \right] \sim -2R_1 + R_3 \left[\begin{array}{ccc|ccc} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & -2 & -1 & 1 & 0 \\ 0 & 1 & 1 & -2 & 0 & 1 \end{array} \right]$

$$\sim -R_2 R_3 \left[\begin{array}{ccc|ccc} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & -2 & -1 & 1 & 0 \\ 0 & 0 & 3 & -1 & -1 & 1 \end{array} \right] \sim \frac{1}{3} R_3 \left[\begin{array}{ccc|ccc} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & -2 & -1 & 1 & 0 \\ 0 & 0 & 1 & -\frac{1}{3} & -\frac{1}{3} & \frac{1}{3} \end{array} \right] \sim 2R_3 + R_2 \left[\begin{array}{ccc|ccc} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & -\frac{5}{3} & \frac{1}{3} & \frac{2}{3} \\ 0 & 0 & 1 & -\frac{1}{3} & -\frac{1}{3} & \frac{1}{3} \end{array} \right]$$

$$\sim -R_2 + R_1 \left[\begin{array}{ccc|ccc} 1 & 0 & 1 & \frac{8}{3} & -\frac{1}{3} & -\frac{2}{3} \\ 0 & 1 & 0 & -\frac{5}{3} & \frac{1}{3} & \frac{2}{3} \\ 0 & 0 & 1 & -\frac{1}{3} & -\frac{1}{3} & \frac{1}{3} \end{array} \right] \sim -R_3 + R_1 \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 3 & 0 & -1 \\ 0 & 1 & 0 & -\frac{5}{3} & \frac{1}{3} & \frac{2}{3} \\ 0 & 0 & 1 & -\frac{1}{3} & -\frac{1}{3} & \frac{1}{3} \end{array} \right]$$

$$A^{-1} = \begin{bmatrix} 3 & 0 & -1 \\ -\frac{5}{3} & \frac{1}{3} & \frac{2}{3} \\ -\frac{1}{3} & -\frac{1}{3} & \frac{1}{3} \end{bmatrix}$$

$$\text{d) } A\vec{x} = \vec{b}, \text{ der } \vec{b} = \begin{bmatrix} 1 \\ 4 \\ 2 \end{bmatrix}$$

$$\Rightarrow \vec{x} = A^{-1}\vec{b} = \begin{bmatrix} 3 & 0 & -1 \\ -\frac{5}{3} & \frac{1}{3} & \frac{2}{3} \\ -\frac{1}{3} & -\frac{1}{3} & \frac{1}{3} \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 4 \\ 2 \end{bmatrix}$$

$$3(1) + 0(4) - 1(2) = 3 - 2 = 1$$

$$-\frac{5}{3}(1) + \frac{1}{3}(4) + \frac{2}{3}(2) = -\frac{5}{3} + \frac{4}{3} + \frac{4}{3} = 1$$

$$-\frac{1}{3}(1) - \frac{1}{3}(4) + \frac{1}{3}(2) = -\frac{1}{3} - \frac{4}{3} + \frac{2}{3} = -1$$

$$x_1 = 1, x_2 = 1, x_3 = -1$$

e)