

# Manan Patel

215 10<sup>th</sup> St NW  
Atlanta, GA 30318

(646) 633 3612  
mpatel608@gatech.edu  
<https://m-a-c-e.github.io/website/>

## EDUCATION

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- **Georgia Institute of Technology**, Atlanta, GA Fall 2021 – Spring 2023
  - **M. S. in Robotics** – GPA: 3.54 / 4.0
- **Purdue University**, West Lafayette, IN Fall 2018 – Fall 2020
  - **B. S. in Mechanical Engineering** – GPA: 3.87 / 4.0

## SKILLS

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- **Software:** C/C++, Python, PyTorch, ROS, MATLAB, Unity, OpenGL, Simulink, SOLIDWORKS
- **Computer Vision:** SIFT, Depth from Stereo, Image classification/segmentation (ResNet, PSP net)
- **Machine Learning:** knn, k-means, GMM, Decision Trees, Neural Nets, Bayes Nets, HMM, Viterbi
- **Graph Search:** UCS, A\*, Constraint Satisfaction, RRT, RRT\*
- **Deep Learning:** Reinforcement Learning, CNNs
- **Parallel Processing:** MPI, threads, OpenMP, CUDA, TCP/IP
- **Mechanics:** Lagrangian Mechanics, Forward and Inverse, Actuator control, Path Planning
- **Control Systems:** PID, System ID (time, frequency), LQR, Extended Kalman Filter, Assembly language, STM32

## WORK EXPERIENCE

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- **Robotics Engineering Intern (3D Computer Vision)** – Equipment Share, MO Summer 2022
  - Developed computer vision pipeline for safety vest detection and depth estimation using stereo
  - Camera calibration and image rectification to undistort images
  - Color filtering to segment out safety vest colors under different lighting conditions
  - Performed one to one feature matching between keypoints in left and right camera images using SIFT
  - Estimated depth of the matched keypoints by triangulation
  - Incorporated multi-threading to boost performance

## RESEARCH PROJECTS

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- **Neural Network Based Control Policy for a 2-DOF Robot (Deep RL, Gazebo, ROS)** Fall 2022
  - Designing a neural network to learn policy for following a wall using LiDAR data as input
  - Investigate real time weight update to account for changing dynamics

## ACADEMIC PROJECTS

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- **High Performance Computing (C++, MPI)** Spring 2022
  - Solving N-Queens problem using multi-threading
  - Simulating John Conway's game of life using custom MPI datatypes, communicators and cartesian topologies
- **Multi-modal Sensing and Navigation on Turtlebot3 (ROS, Python)** Fall 2021
  - Implemented Dead Reckoning to navigate robot through a maze based on sensory input (Lidar, Camera)
  - Designed algorithms for dynamic and static obstacle avoidance, detect and follow a particular object
  - Incorporated control architecture to regulate the movement of the robot
- **Controller Design for an Air Engine (PID, STM32, Simulink)** Fall 2020
  - Developed a PI controller to regulate the speed of a miniaturised air engine
  - Involved System ID, Controller Design, Simulation using Simulink, and Implementation

## LEADERSHIP EXPERIENCE

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- **Lab Teaching Assistant** – Electrical Engineering Fundamentals Lab, Purdue Aug 2019 – Dec 2020
  - Analyse and debug errors in audio amplifier circuits and validate its source