

Manan Patel

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EDUCATION

- **Georgia Institute of Technology, Atlanta, GA** Fall 2021 – Spring 2023
 - **M. S. in Robotics** – GPA: 3.61 / 4.0
- **Purdue University, West Lafayette, IN** Fall 2018 – Fall 2020
 - **B. S. in Mechanical Engineering** – GPA: 3.87 / 4.0

SKILLS

- **Software:** C/C++, Python, PyTorch, ROS, MATLAB, Unity, OpenGL, Simulink, SOLIDWORKS
- **Computer Vision:** SIFT, Depth from Stereo, Image classification/segmentation (ResNet, PSP net)
- **Machine Learning:** knn, k-means, GMM, Decision Trees, Neural Nets, Bayes Nets, HMM, Viterbi
- **Graph Search:** UCS, A*, Constraint Satisfaction, RRT, RRT*
- **Deep Learning:** Reinforcement Learning, CNNs
- **Parallel Processing:** MPI, threads, OpenMP, CUDA, TCP/IP
- **Mechanics:** Lagrangian Mechanics, Forward and Inverse Kinematics, Path Planning for manipulators
- **Control Systems:** PID, System ID (time, frequency), LQR, Extended Kalman Filter, Assembly language

WORK EXPERIENCE

- **Control Systems Engineer Co-op (Python, SysML)** – SharkNinja, MA June 2023 – Dec 2023
 - Classical PID and Modern Control (Project yet to be assigned)
- **Robotics Engineer Intern (3D Computer Vision)** – Equipment Share, MO Summer 2022
 - Developed computer vision pipeline for safety vest detection and depth estimation using stereo
 - Camera calibration and image rectification to undistort images
 - Color filtering to segment out safety vest colors under different lighting conditions
 - Performed one to one feature matching between keypoints in left and right camera images using SIFT
 - Estimated depth of the matched keypoints by triangulation
 - Incorporated multi-threading to boost performance

PROJECTS

- **3DOF Manipulator Dynamics and Control (MATLAB, Simulink)** Fall 2022
 - Deployed joint PD feedback control to achieve reference trajectory within error bounds
 - Applied gravity compensation using Lagranges equations of motion
 - Computed the torque required at each joint using Jacobian matrix for the manipulator
- **High Performance Computing (C++, MPI)** Spring 2022
 - Solving N-Queens problem using multi-threading
 - Simulating John Conway's game of life using custom MPI datatypes, communicators and cartesian topologies
- **Multi-modal Sensing and Navigation on Turtlebot3 (ROS, Python)** Fall 2021
 - Implemented Dead Reckoning to navigate robot through a maze based on sensory input (Lidar, Camera)
 - Designed algorithms for dynamic and static obstacle avoidance, detect and follow a particular object
 - Incorporated control architecture to regulate the movement of the robot
- **Controller Design for an Air Engine (PID, STM32, Simulink)** Fall 2020
 - Developed a PI controller to regulate the speed of a miniaturised air engine
 - Involved System ID, Controller Design, Simulation using Simulink, and Implementation

LEADERSHIP EXPERIENCE

- **Lab Teaching Assistant** – Electrical Engineering Fundamentals Lab, Purdue Aug 2019 – Dec 2020
 - Analyse and debug errors in audio amplifier circuits and validate its source
- **Tutor Chair** – Pi Tau Sigma, Purdue Aug 2019 – Dec 2020
 - Held exam review sessions for Fluid Mechanics and Control Systems for a batch of 100 students