# First Problem Assignment

# Problem 17

#### Statement

Consider the sending from s to t game. Compute (or provide bounds for) the PoA and the PoS for the following social cost/utility functions:

(a) 
$$C(s) = \begin{cases} \sum_{i \in N} u_i(s) & \text{if there is a path from } s \text{ to } t \text{ in } G[s]. \\ n^2 & \text{otherwise.} \end{cases}$$

- (b)  $U(s) = \max_{i \in N} u_i(s)$ .
- (c)  $U(s) = \sum_{i \in N} u_i(s)$ .

## Solution

In order to ease the explanation, I define the following functions:

- LP(G) = "number of vertices that are inside the longest path of G".
- SP(G) = "number of vertices that are inside the shortest path of G".

Both situations (longest and shortest paths) leads to a NE.

- Longest path: all vertices that are on the way between s and t (i.e., all possible vertices that can be included in the path) are included in the (longest) path. Hence, all vertices are "happy".
- Shortest path: no vertex outside the (shortest) path can be part of it with only changing its own action.

With this, I can start with the computation of the bounds.

(a) Here I use the formulas of PoA and PoS for the cost functions, which are:

$$PoA(\Gamma) = \frac{max_{s \in NE(\Gamma)}C(s)}{min_{s \in A}C(s)} \qquad PoS(\Gamma) = \frac{min_{s \in NE(\Gamma)}C(s)}{min_{s \in A}C(s)}$$
(1)

I know that  $min_{s \in NE(\Gamma)}C(s) = min_{s \in A}C(s) = min(SP(G), n^2)$  since the minimum path will be always a NE and the shortest possible one. If G is unconnected,  $SP(G) = \infty$  and  $\forall s \in A, C(s) = n^2$ .

By the statement, I also know that if there is not a path from s to t in G[s], then  $\max_{s \in \text{NE}(\Gamma)} C(s) = n^2$ .

If G is connected

$$\frac{LP(G)}{SP(G)} \le \text{PoA}(\Gamma) \le \frac{n^2}{SP(G)}$$
 (2)

Moreover, the largest value of SP(G) is SP(G) = LP(G), and the smallest value of it is SP(G) = 1, therefore

$$1 \le \operatorname{PoA}(\Gamma) \le n^2 \tag{3}$$

If G is unconnected, it is possible that no path from s to t exists. This implies that  $min_{s\in A}C(s)=max_{s\in NE(\Gamma)}C(s)=n^2$  can happen. However, it does not affect the bounds.

$$\frac{n^2}{n^2} = 1 \le \text{PoA}(\Gamma) \le n^2 \tag{4}$$

As I explained before,  $min_{s \in NE(\Gamma)}C(s) = min_{s \in A}C(s) = min(SP(G), n^2)$ , so PoS = 1.

(b) Here, and in the following point, I use the formulas of PoA and PoS for the utility functions, which are:

$$PoA(\Gamma) = \frac{max_{s \in A}U(s)}{min_{s \in NE(\Gamma)}U(s)} \qquad PoS(\Gamma) = \frac{max_{s \in A}U(s)}{max_{s \in NE(\Gamma)}U(s)}$$
 (5)

In this case  $\forall s, 0 \leq U(s) \leq 1$ .

If G is connected, there always exists a path from s to t, so  $\max_{s \in A} U(s) = 1$ . It can happen that a NE exists with no path from s to t, if there is no single action from any of the vertices that connects s to t. In this case,  $\min_{s \in \text{NE}(\Gamma)} U(s) = 0$ . Then, PoA can be bounded as follows:

$$\frac{1}{1} = 1 \le \text{PoA} \le \infty = \frac{1}{0} \tag{6}$$

Because there always exists a path between s and t, PoS = 1.

If G is unconnected,  $\max_{s \in A} U(s) = 1$  is not true because maybe a path from s to t does not exist. Then, the PoA and PoS can be equal to the indeterminate form  $\frac{0}{0}$ .

(c) If G is connected, there always exists a path from s to t, so  $\max_{s \in A} U(s) = LP(G)$ . As in (b), it can happen that a NE exists with no path from s to t, so  $\min_{s \in NE(\Gamma)} U(s)$  can be 0, otherwise it is equal to SP(G). Then

$$\frac{LP(G)}{SP(G)} \le \text{PoA} \le \infty = \frac{LP(G)}{0} \tag{7}$$

As in (b), if G is unconnected, PoA and PoS can be equal to the indeterminate form  $\frac{0}{0}$ .

# Problem 28

#### Statement

Consider a GSP auction for n players. Recall that in such an auction each bid profile b defines an allocation  $\pi$  mapping slots to players. We say that an allocation is reasonable if for each pair i, j of slots

$$\frac{\alpha_j}{\alpha_i} + \frac{\gamma_{\pi(i)} v_{\pi(i)}}{\gamma_{\pi(j)} v_{\pi(j)}} \ge 1.$$

- (a) Prove that when b is a NE, the corresponding allocation  $\pi$  is reasonable.
- (b) Use the previous fact to show that the price of anarchy, on pure strategies, of the GSP auction is at most 2.

## Solution

- (a) I first divided the prove in two parts, when  $i \geq j$  and i < j.
  - $\mathbf{i} \geq \mathbf{j}$ : Using the fact that  $\alpha_1 \geq \alpha_2 \geq ... \geq \alpha_n$ :

$$\alpha_j \ge \alpha_i \Rightarrow \frac{\alpha_j}{\alpha_i} \ge 1$$

•  $\mathbf{i} < \mathbf{j}$ : Using the fact that b is a NE, I can use the NE property for i < j, which is:

$$\alpha_i(\gamma_{\pi(i)}v_{\pi(i)} - \gamma_{\pi(i+1)}b_{\pi(i+1)}) \ge \alpha_i(\gamma_{\pi(i)}v_{\pi(i)} - \gamma_{\pi(i)}b_{\pi(i)})$$

Since  $0 \le b_k \le v_k$  (for all k), it is easy to see that  $-\gamma_{\pi(i)}b_{\pi(i)} \ge -\gamma_{\pi(i)}v_{\pi(i)}$ , hence

$$\alpha_i(\gamma_{\pi(j)}v_{\pi(j)} - \gamma_{\pi(i)}b_{\pi(i)}) \ge \alpha_i(\gamma_{\pi(j)}v_{\pi(j)} - \gamma_{\pi(i)}v_{\pi(i)})$$

As I said,  $0 \le b_k$ , so

$$\alpha_j(\gamma_{\pi(j)}v_{\pi(j)}) \ge \alpha_j(\gamma_{\pi(j)}v_{\pi(j)} - \gamma_{\pi(j+1)}b_{\pi(j+1)})$$

All this leads to

$$\alpha_{j}(\gamma_{\pi(j)}v_{\pi(j)}) \geq \alpha_{i}(\gamma_{\pi(j)}v_{\pi(j)} - \gamma_{\pi(i)}v_{\pi(i)})$$

$$\frac{\alpha_{j}}{\alpha_{i}} \geq \frac{\gamma_{\pi(j)}v_{\pi(j)} - \gamma_{\pi(i)}v_{\pi(i)}}{\gamma_{\pi(j)}v_{\pi(j)}}$$

$$\frac{\alpha_{j}}{\alpha_{i}} \geq \frac{\gamma_{\pi(j)}v_{\pi(j)}}{\gamma_{\pi(j)}v_{\pi(j)}} - \frac{\gamma_{\pi(i)}v_{\pi(i)}}{\gamma_{\pi(j)}v_{\pi(j)}}$$

$$\frac{\alpha_{j}}{\alpha_{i}} \geq 1 - \frac{\gamma_{\pi(i)}v_{\pi(i)}}{\gamma_{\pi(j)}v_{\pi(j)}}$$

Finally, I obtain the initial inequality.

$$\frac{\alpha_j}{\alpha_i} + \frac{\gamma_{\pi(i)} v_{\pi(i)}}{\gamma_{\pi(j)} v_{\pi(j)}} \ge 1.$$

# Problem 35

## Statement

Consider a the following decision process which runs on a leader-follower society with n members. The interaction among the society is represented by a bipartite directed graph G=(L,F,E) having the following property: all the vertices in L have in-degree 0 and all the vertices in F have out-degree 0. The decision process is defined by two parameters  $\alpha$ ,  $0 \le \alpha \le 1$  and q,  $0 \le q \le n$ .

When the society has to reach a decision about some topic, each member takes an initial position. We model this situation as an initial decision vector  $x \in \{0,1\}^n$ . Then, each  $i \in F$  looks at the values  $p_{i1} = |\{(j,i) \in E \mid x_j = 1\}|$  and  $p_{i0} = |\{(j,i) \in E \mid x_j = 0\}|$  and reconsiders its position according to the following algorithm.

- If  $p_{i1} > \alpha(p_{i1} + p_{i0})$  and  $p_{i0} < \alpha(p_{i1} + p_{i0})$ ,  $x_i = 1$
- If  $p_{i0} > \alpha(p_{i1} + p_{i0})$  and  $p_{i1} < \alpha(p_{i1} + p_{i0})$ ,  $x_i = 0$

Finally, the society reaches a "yea" (1) when  $\sum_{i=1}^{n} x_i \geq q$ , and a "nay" (0) otherwise.

- (a) Assuming that a coalition S is represented as the initial decision vector  $x \in \{0,1\}^n$  defined as  $x_i = 1$  iff  $i \in S$ , the decision system process defines a cooperative game assigning to a coalition S a value in  $v(S) \in \{0,1\}$ . Is this game simple?
- (b) Provide a characterization of the games in the family with non-empty core.
- (c) Can the Banzhaf value of player i be computed in polynomial time?

## Solution

- (a) Yes, it is a WVG to be exact. We can represent it as  $\Gamma = (q; x)$ , and also as  $\Gamma = (N, S)$ , being S either the winning or the losing coalition (depending on the problem). I assume that x has already passed through the algorithm.
- (b) To know if a simple game has a non-empty core, you only have to ensure that it has at least one veto player. A player p is a veto player if v(C) = 0, for any  $C \subseteq N \setminus \{p\}$ . The only scenario where a veto player exists is when  $\sum_{i=i}^{n} \mathbf{x_i} = \mathbf{q}$ . In this case v(C) = 1. Then, the q nodes  $x_i = 1$  are all veto players because if I remove one from the game, then v(C) = 0.