



Will It Blend?



Writing A Custom Constraint Solver for Blender with Cython

Maryanne Wachter

May 1, 2022



Agenda

💪 *Motivation / Background*

Backend

❓ Why Cython?

🏗️ Toy problem

📦 Python package structure with Cython

⚙️ Compiling Cython packages



Agenda

Performance

-  Using Cython to release the GIL
-  Profiling Cython

Frontend

-  Why Blender?
-  Blender Development
-  Blender Add-ons



Motivation / Background



About Me

Maryanne Wachter

 structural engineer

 since 2015

 mclare.blog

 @eng_mclare





About Me

Maryanne Wachter



structural software engineer



since 2015

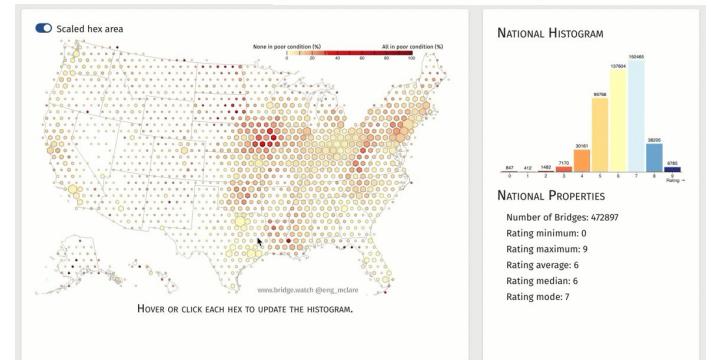
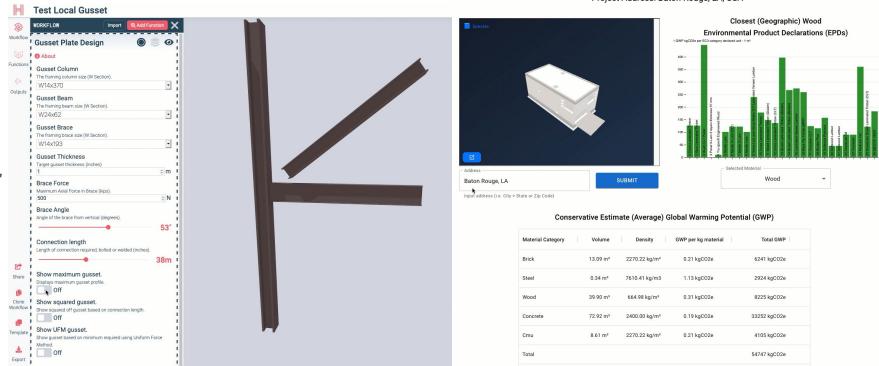


mclare.blog



@eng_mclare

Motivation / Background

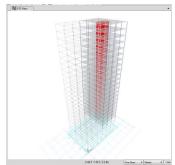




Software in the Built Environment

What I Used It For

- Building Analysis
- Building Design
- Building Data Exchange



What I Don't Like

- Terrible UX/UI
- \$\$\$
- Slow
- "Black box"



Physical and Digital Formfinding



Sagrada Família - Antonio Gaudi
1882 - present





Physical and Digital Formfinding



Sagrada Família - Antonio Gaudi
1882 - present

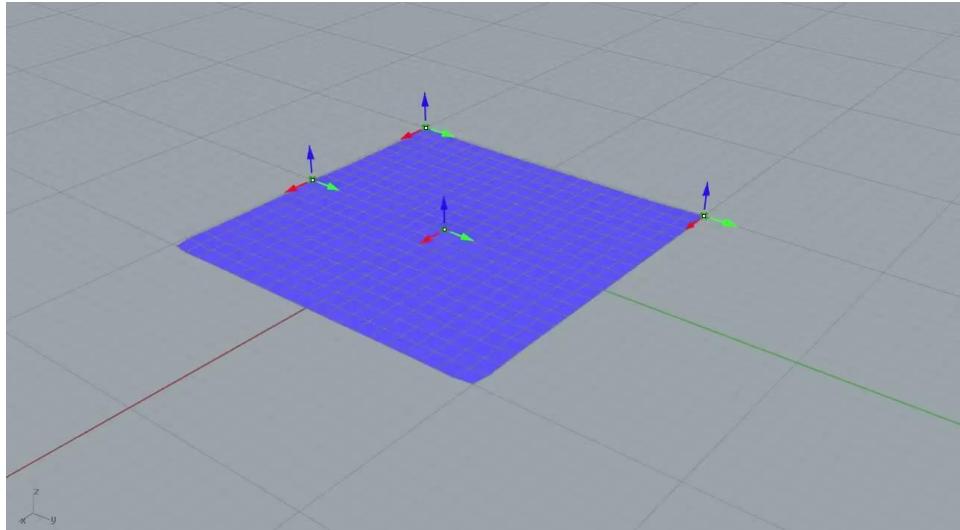
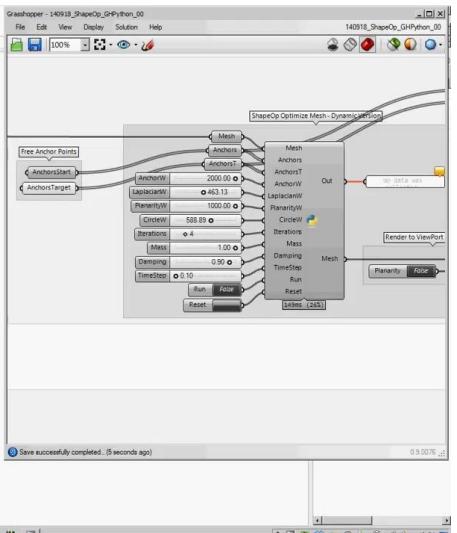
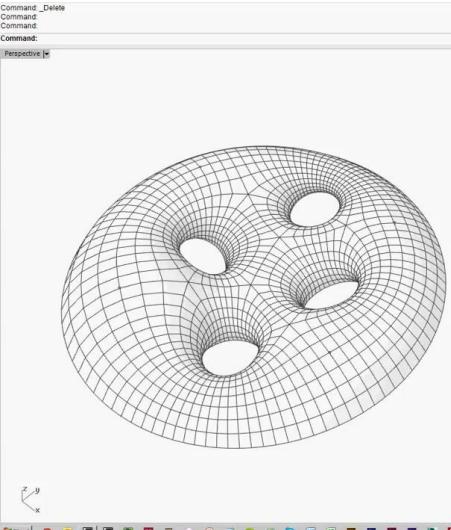
Motivation / Background



Mark Burry - The Nave Roof
<https://mcburry.net/the-west-transept/>



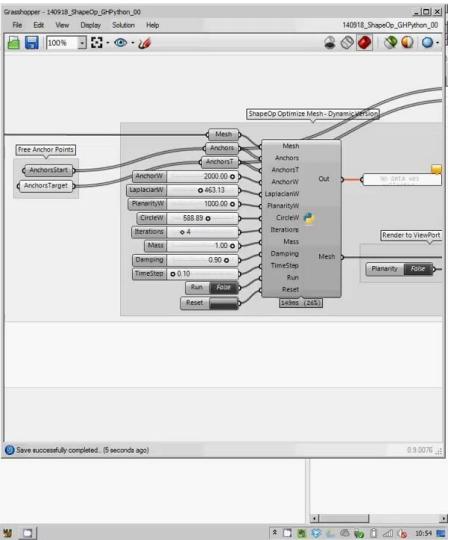
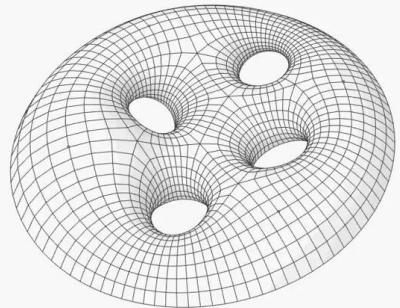
Constraint Solvers for 3d Geometry



LGG EPFL
<https://www.shapeop.org>



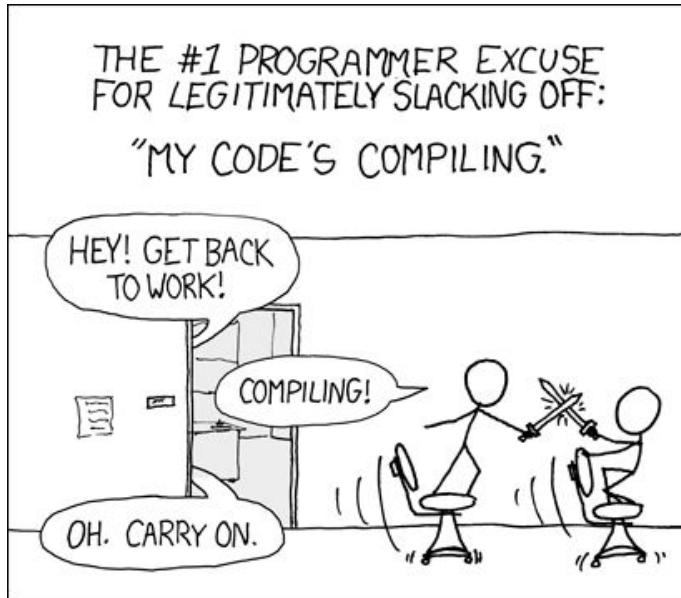
Constraint Solvers for 3d Geometry



- Terrible UX/UI
- \$\$\$
- Slow
- "Black box"



Backend Building Pymaxion



<https://xkcd.com/303/>



Why Cython?





Why Cython?

- Significant speedups are possible (can release the GIL!)
- Can create general framework to build on
- Able to preserve a Python package structure
- Able to utilize existing C++ libraries
- Looks *mostly* like Python (with some additions, i.e. static typing)



What is Cython?

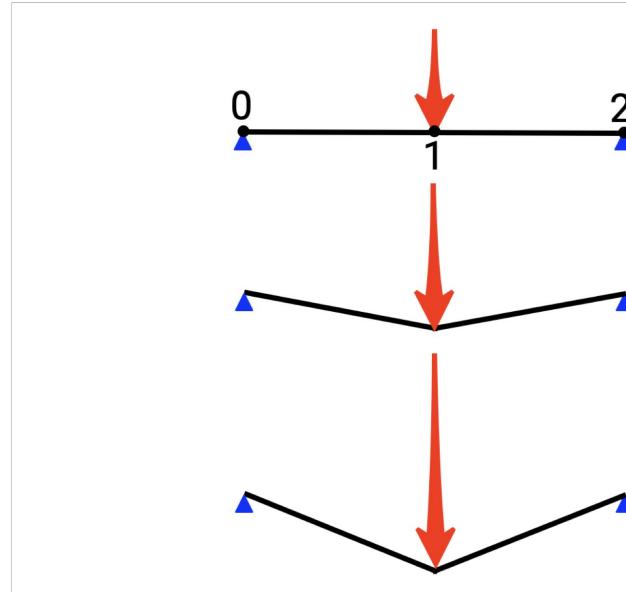
- Optimizing Static Compiler
- Provides support for debugging in Python, Cython, and C/C++ code
- Superset of Python
- Enables easily writing C-extensions for Python



Toy Constraint Problem

Constraints

- Anchors (supports) - [0, 2]
- Forces (loads) - [1]
- Cables (lengthening) -
[[0, 1], [1, 2]]

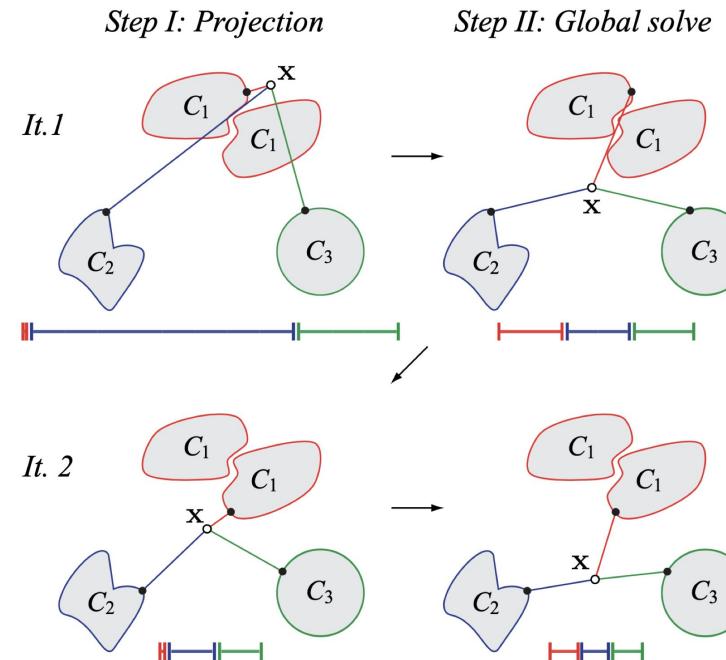




Toy Constraint Problem

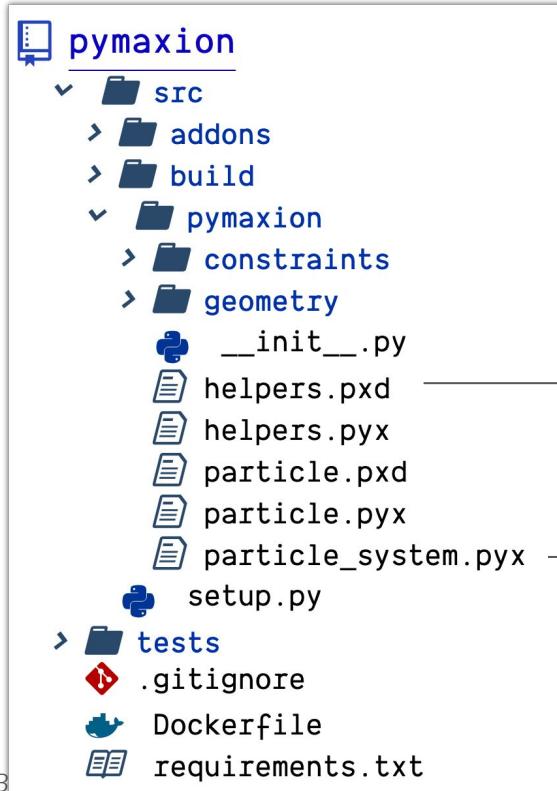
Constraints

- Anchors (supports) - $[0, 2]$
- Forces (loads) - $[1]$
- Cables (lengthening) -
 $[[0, 1], [1, 2]]$





Package Structure and Modules with Cython

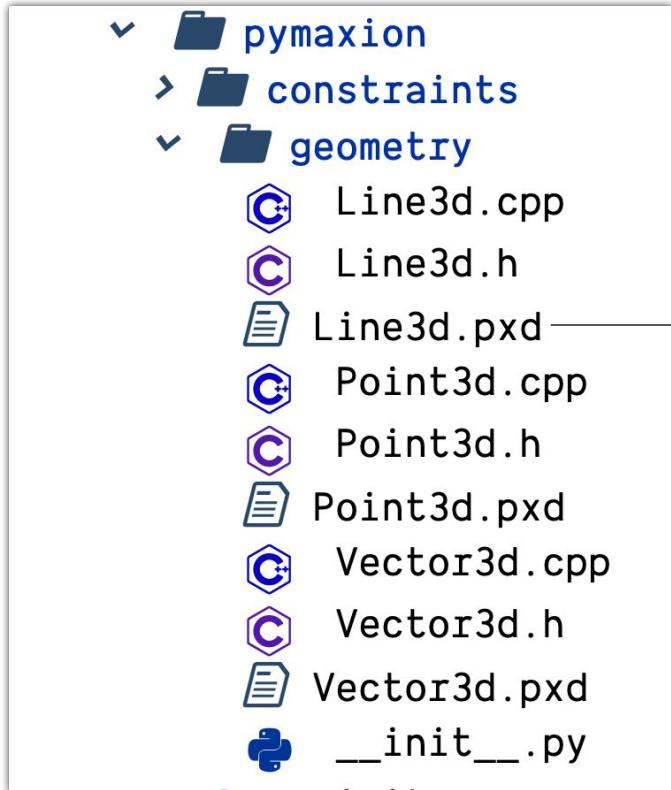
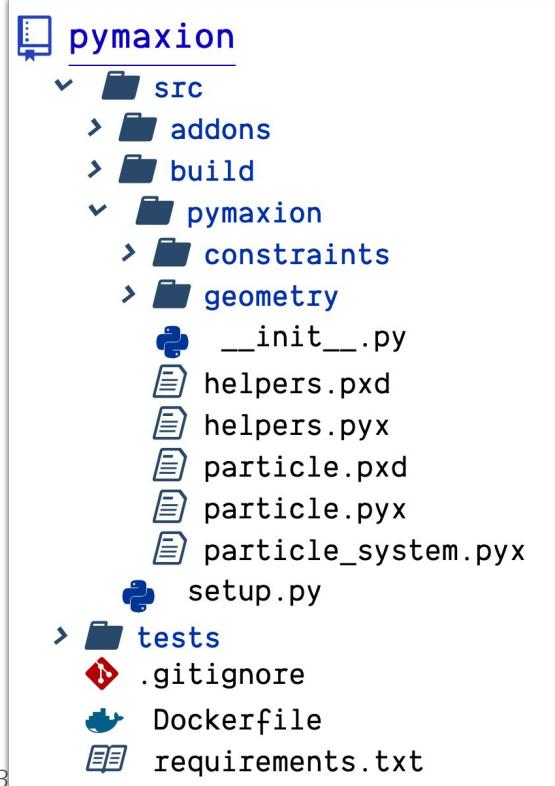


"Header" file (type declaration)

Class + methods



Package Structure and Modules with Cython



Ok a "little"
C++ here...



Package Structure and Modules with Cython

```
pymaxion
├── src
├── addons
├── build
└── pymaxion
    ├── constraints
    └── geometry
        ├── __init__.py
        ├── helpers.pxd
        ├── helpers.pyx
        ├── particle.pxd
        ├── particle.pyx
        └── particle_system.pyx
    └── setup.py
└── tests
    └── .gitignore
    └── Dockerfile
    └── requirements.txt
```

```
pymaxion
├── constraints
└── geometry
    ├── Line3d.cpp
    ├── Line3d.h
    ├── Line3d.pxd
    ├── Point3d.cpp
    ├── Point3d.h
    ├── Point3d.pxd
    ├── Vector3d.cpp
    ├── Vector3d.h
    └── Vector3d.pxd
    └── __init__.py
```

**But mostly
Cython
files**

```
pymaxion
├── src
├── addons
├── build
└── pymaxion
    ├── constraints
    │   ├── __init__.py
    │   ├── anchor.pxd
    │   ├── anchor.pyx
    │   ├── bar.pxd
    │   ├── bar.pyx
    │   ├── cable.pxd
    │   ├── cable.pyx
    │   ├── constraint.pxd
    │   ├── constraint.pyx
    │   ├── force.pxd
    │   ├── force.pyx
    │   ├── rod.pxd
    │   └── rod.pyx
    └── geometry
        ├── __init__.py
        ├── helpers.pxd
        ├── helpers.pyx
        ├── particle.pxd
        ├── particle.pyx
        └── particle_system.pyx
    └── setup.py
```



Package Structure and Modules with Cython

- Only one level of subclassing allowed!
- .pxd files are needed for importing into other modules at the same folder level (Cython "headers")

```
1 from libcpp.vector cimport vector
2 from pymaxion.geometry.Vector3d cimport Vector3d
3 from pymaxion.geometry.Point3d cimport Point3d
4
5 cdef class Constraint:
6     cdef public int constraint_n_particles
7     cdef vector[int] *particle_index
8     cdef vector[Vector3d] *move_vectors
9     cdef vector[double] *weighting
10    cdef vector[double] *strength
11    cdef public list particles
12    cdef void calculate(Constraint, double[:, :] arr) nogil
13    cdef void sum_moves(Constraint, double[:, :] p_sum, double[:] w_sum) nogil
```

src/pymaxion/constraints/constraint.pxd

```
1 from libcpp.vector cimport vector
2 from pymaxion.constraints.constraint cimport Constraint
3 from pymaxion.geometry.Point3d cimport Point3d
4
5 cdef class Anchor(Constraint):
6     cdef vector[Point3d] *anchor_pt
7
8     @staticmethod
9     cdef Anchor from_Point3d(Point3d pt, double strength)
```

src/pymaxion/constraints/anchor.pxd



Package Structure and Modules with Cython

```
1 from libcpp.vector cimport vector
2 from pymaxion.geometry.Vector3d cimport Vector3d
3 from pymaxion.geometry.Point3d cimport Point3d
4
5 cdef class Constraint:
6     cdef public int constraint_n_particles
7     cdef vector[int] *particle_index
8     cdef vector[Vector3d] *move_vectors
9     cdef vector[double] *weighting
10    cdef vector[double] *strength
11    cdef public list particles
12    cdef void calculate(Constraint, double[:, :] arr) nogil
13    cdef void sum_moves(Constraint, double[:, :] p_sum, double[:] w_sum) nogil
```

src/pymaxion/constraints/constraint.pxd



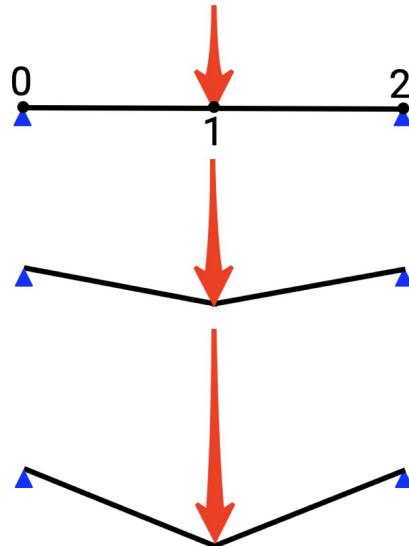
Package Structure and Modules with Cython

```
46     cdef void calculate(Constraint self, double[:, :] arr) nogil:
47         pass
48
49     cdef void sum_moves(Constraint self, double[:, :] p_sum, double[:] w_sum) nogil:
50         cdef int i
51         for i in range(self.constraint_n_particles):
52             p_index = self.particle_index[0].at(i)
53             curr_move = self.move_vectors[0].at(i)
54             curr_strength = self.strength[0].at(i)
55             w_sum[p_index] += curr_strength
56             p_sum[p_index, 0] += curr_move.x * curr_strength
57             p_sum[p_index, 1] += curr_move.y * curr_strength
58             p_sum[p_index, 2] += curr_move.z * curr_strength
```

src/pymaxion/constraints/constraint.pyx



Package Structure and Modules with Cython



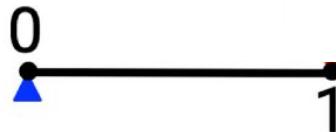
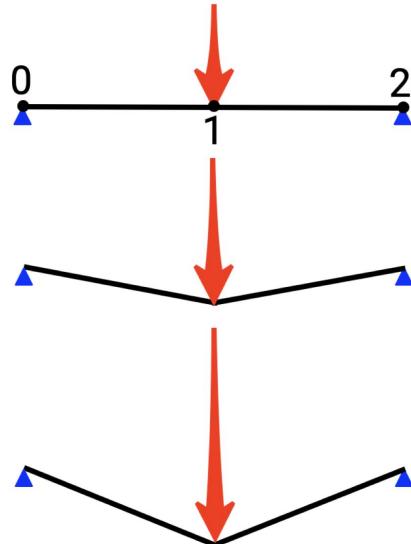
0
●

```
53 cdef void calculate(Anchor self, double[:, :] arr) nogil:
54     cdef Vector3d cur_pos
55     anchor_pt = self.anchor_pt[0].at(0)
56     p_index = self.particle_index[0].at(0)
57     cur_pos = Vector3d(anchor_pt.x, anchor_pt.y, anchor_pt.z)
58     new_pos = cur_pos.vector_subtract(Vector3d(arr[p_index, 0],
59                                                 arr[p_index, 1],
60                                                 arr[p_index, 2]))
61     self.move_vectors[0].at(0).set_value(new_pos.x,
62                                         new_pos.y,
63                                         new_pos.z)
```

src/pymaxion/constraints/anchor.pyx



Package Structure and Modules with Cython



```
48     cdef void calculate(Cable self, double[:, :] arr) nogil:
49         cdef Vector3d start_pt
50         cdef Vector3d end_pt
51         cdef double current_length
52         cdef double length_diff
53         cdef Vector3d force_start
54         cdef Vector3d force_end
55         cdef Vector3d force_dir
56
57         p1 = self.particle_index[0].at(0)
58         p2 = self.particle_index[0].at(1)
59         start_pt = Vector3d(arr[p1, 0], arr[p1, 1], arr[p1, 2])
60         end_pt = Vector3d(arr[p2, 0], arr[p2, 1], arr[p2, 2])
61
62         force_dir = end_pt.vector_subtract(start_pt)
63         current_length = force_dir.length()
64         force_dir.vector_unitize()
65         length_diff = current_length - self.rest_length
66         if length_diff > 0.0:
67             force_start = force_dir.vector_scale(0.5 * length_diff)
68             force_end = force_dir.vector_scale(-0.5 * length_diff)
69         else:
70             force_start = Vector3d(0, 0, 0)
71             force_end = Vector3d(0, 0, 0)
72
73         self.move_vectors[0].at(0).set_value(force_start)
74         self.move_vectors[0].at(1).set_value(force_end)
```

src/pymaxion/constraints/cable.pyx



Compiling Cython

```
11 def scandir(dir, files=[]):
12     for file in os.listdir(dir):
13         path = os.path.join(dir, file)
14         if os.path.isfile(path) and path.endswith("pyx"):
15             files.append(path.replace(os.path.sep, ".")[:-4])
16         elif os.path.isdir(path):
17             scandir(path, files)
18     return files
19
20 def makeExtension(extName):
21     extPath = extName.replace(".", os.path.sep) + ".pyx"
22     print(extName)
23     return Extension(
24         name=extName,
25         sources=[extPath],
26         include_dirs=[numpy_include, ".", geo_include],
27         extra_compile_args=["-fopenmp"],
28         extra_link_args=["-fopenmp"],
29         language="c++",
30     )
31
32 # Find all includes
33 numpy_include = numpy.get_include()
34 # Add includes for C++ only libraries (no .pyx wrapped)
35 geo_include = os.path.abspath("./pymaxion/geometry")
36 extNames = scandir("pymaxion")
37
38 # build up set of Extension objects
39 extensions = [makeExtension(name) for name in extNames]
40
41 # Create a dictionary of arguments for setup
42 setup_args = {
43     "name": "pymaxion",
44     "packages": ["pymaxion", "pymaxion.goals", "pymaxion.geometry"],
45     "py_modules": [],
46     "ext_modules": cythonize(extensions,
47                             emit_linenums=True,
48                             compiler_directives={'language_level': 3}),
49     "requires": [],
50     "cmdclass": {"build_ext": build_ext},
51 }
52
53 setup(**setup_args)
```

```
20 def makeExtension(extName):
21     extPath = extName.replace(".", os.path.sep) + ".pyx"
22     print(extName)
23     return Extension(
24         name=extName,
25         sources=[extPath],
26         include_dirs=[numpy_include, ".", geo_include],
27         extra_compile_args=["-fopenmp"],
28         extra_link_args=["-fopenmp"],
29         language="c++",
30     )
```

```
$ python setup.py build_ext -inplace
```



Compiling Cython

```
pymaxion
├── src
│   ├── addons
│   ├── build
│   └── pymaxion
│       ├── constraints
│       ├── geometry
│       │   ├── __init__.py
│       │   ├── helpers.pxd
│       │   ├── helpers.pyx
│       │   ├── particle.pxd
│       │   ├── particle.pyx
│       │   └── particle_system.pyx
│       └── setup.py
└── tests
    ├── .gitignore
    ├── Dockerfile
    └── requirements.txt
```

```
pymaxion
├── src
│   ├── addons
│   ├── build
│   └── pymaxion
│       ├── constraints
│       ├── geometry
│       │   ├── __init__.py
│       │   ├── helpers.cpp
│       │   ├── helpers.cpython-310-darwin.so
│       │   ├── helpers.pxd
│       │   ├── helpers.pyx
│       │   ├── particle.cpp
│       │   ├── particle.cpython-310-darwin.so
│       │   ├── particle.pxd
│       │   ├── particle.pyx
│       │   ├── particle_system.cpp
│       │   ├── particle_system.cpython-310-darwin.so
│       │   └── particle_system.pyx
│       └── setup.py
└── tests
    ├── .gitignore
    ├── Dockerfile
    └── requirements.txt
```



Performance



Before you release the GIL...

- Use Cython for static typing!
- Use special comment blocks
- Write Python wrappers for Cython cdef functions and C attributes



Before you release the GIL...

- Use Cython for static typing!
- Use special comment blocks
- Write Python wrappers for Cython cdef functions and C attributes

```
1 from libcpp.vector cimport vector
2 from pymaxion.geometry.Vector3d cimport Vector3d
3 from pymaxion.geometry.Point3d cimport Point3d
4
5 cdef class Constraint:
6     cdef public int constraint_n_particles
7     cdef vector[int] *particle_index
8     cdef vector[Vector3d] *move_vectors
9     cdef vector[double] *weighting
10    cdef vector[double] *strength
11    cdef public list particles
12    cdef void calculate(Constraint, double[:, :] arr) nogil
13    cdef void sum_moves(Constraint, double[:, :] p_sum, double[:] w_sum) nogil
```

src/pymaxion/constraints/constraint.pxd



Before you release the GIL...

- Use Cython for static typing!
- Use special comment blocks
- Write Python wrappers for Cython cdef functions and C attributes

```
1 # distutils: language = c++
2 # cython: cdivision = True
3 # cython: boundscheck = False
4 # cython: wraparound = False
5 # cython: linetrace = True
6 # cython: language_level = 3
7
8
9 from libc.stdlib cimport free
10 from pymaxion.geometry.Vector3d cimport Vector3d
11 from pymaxion.particle cimport Particle
12 import numpy as np
```

src/pymaxion/particle_system.pyx



Before you release the GIL...

- Use Cython for static typing!
- Use special comment blocks
- Write Python wrappers for Cython cdef functions and C attributes

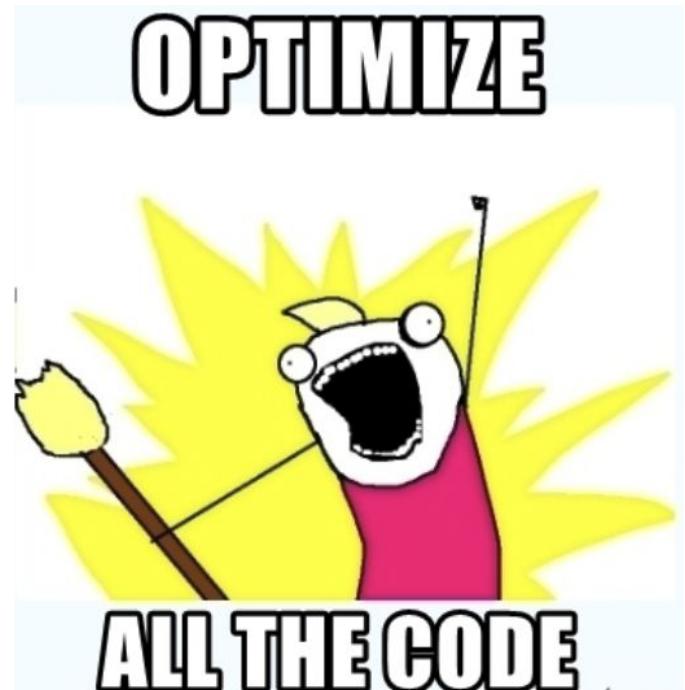
```
74     @property
75     def weighting(Constraint self):
76         return [weighting for weighting in self.weighting[:1]][0]
77
78     @property
79     def strength(Constraint self):
80         return [strength for strength in self.strength[:1]][0]
81
82     def py_calculate(Constraint self, double[:, :] arr):
83         return self.calculate(arr)
84
85     def py_sum_moves(Constraint self, double[:, :] p_sum, double[:] w_sum):
86         return self.sum_moves(p_sum, w_sum)
```

src/pymaxion/constraints/constraint.pyx



Releasing the GIL!

- Utilize cdef methods only (signature must match in .pxd and .pyx file)
- Use nogil in function signature (only indicates it can be used without GIL)





Releasing the GIL!

- Check python interference with cython --cplus \$file.pyx -a

```
+009: import numpy as np
010: from cython cimport PyObject
011: from cython.parallel import parallel, prange
012: from libc.stdlib cimport malloc, free
013: from numpy cimport ndarray
014: from libc.stdio cimport printf
015:
016: from pymaxion.goals.goal cimport Goal
017: from pymaxion.goals.anchor cimport Anchor
018: from pymaxion.particle cimport Particle
019: from pymaxion.geometry.Point3d cimport Point3d
020: from pymaxion.geometry.Vector3d cimport Vector3d
021:
+022: cdef class ParticleSystem(object):
023:     cdef int n_goals
024:     cdef int n_particles
025:     cdef PyObject **goals
026:     cdef PyObject **particles
+027:     cdef public list ref_goals
+028:     cdef public list ref_particles
+029:     cdef public ndarray particle_positions
+030:     cdef public ndarray particle_sum_moves
+031:     cdef public ndarray particle_sum_weights
+032:     cdef public ndarray particle_velocities
033:
+034:     def __cinit__(ParticleSystem self):
+035:         self.goals = NULL
+036:         self.particles = NULL
+037:         self.n_goals = 0
+038:         self.n_particles = 0
039:
+040:     def __init__(ParticleSystem self):
+041:         self.ref_goals = []
+042:         self.ref_particles = []
```



Releasing the GIL!

- Use memoryviews double[:, :] arr for fast Numpy array access

```
211      # memory view must be created before nogil
212      cdef double [:, :] p_pos = self.particle_positions
213      cdef double [:, :] p_vel = self.particle_velocities
214      cdef double [:, :] p_moves = self.particle_sum_moves
215      cdef double [:] p_weights = self.particle_sum_weights
216      # set up C++ only objects for nogil
217      self.constraints = <PyObject **>malloc(self.n_constraints*cython.sizeof(
218                                              cython.pointer(PyObject)))
```

src/pymaxion/particle_system.pyx

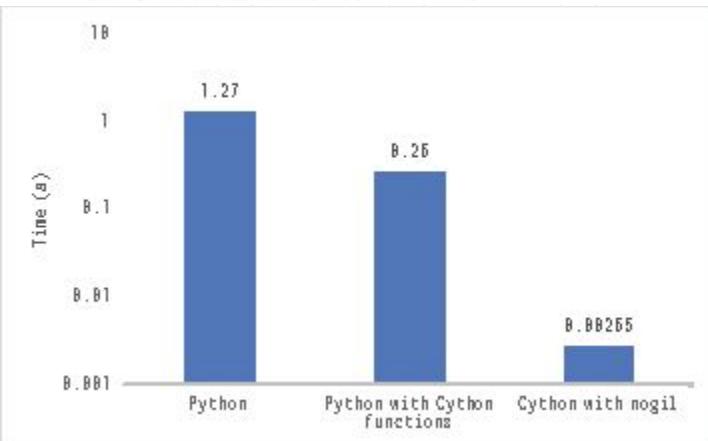


Releasing the GIL!



211
212
213
214
215
216
217
218
219
220
221
222
223

```
# memory view must be created before nogil
cdef double [:, :] p_pos = self.particle_positions
cdef double [:, :] p_vel = self.particle_velocities
cdef double [:, :] p_moves = self.particle_sum_moves
cdef double [:] p_weights = self.particle_sum_weights
# set up C++ only objects for nogil
self.constraints = <PyObject **>malloc(self.n_constraints*cython.sizeof(
    cython.pointer(PyObject)))
for i in range(self.n_constraints):
    self.constraints[i] = <PyObject*>self.ref_constraints[i]
with nogil:
    while flag == False:
        for j in range(self.n_particles):
```





Evaluating Cython performance - py-spy

Prep work:

```
"ext_modules": cythonize(extensions, emit_linums=True)
```

pymaxion/src/setup.py

```
#line 212 "pymaxion/particle_system.pyx"
```

pymaxion/src/*.cpp (Cython generated C++ files)

```
# cython: linetrace = True
```

pymaxion/src/*.pyx

<https://github.com/benfred/py-spy>



Evaluating Cython performance - py-spy



```
$ docker run -td -cap-add SYS_PTRACE $IMAGE_NAME
```

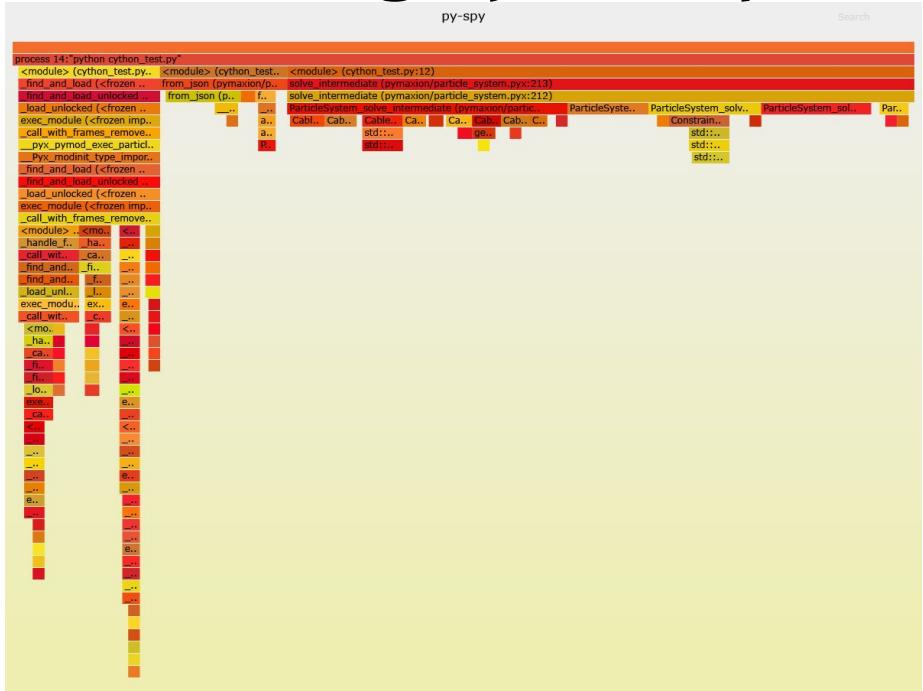
```
$ sudo docker exec -t $CONTAINER_NAME bash -c "PYTHONPATH=/code/src && py-spy record --subprocesses --native -o profile.svg -- python cython_test.py"
```

```
$ docker cp $CONTAINER_NAME:/code/tests/open_mp_tests/profile.svg ~/open_mp_tests/
```

<https://github.com/benfred/py-spy>



Evaluating Cython performance - py-spy



timeit()

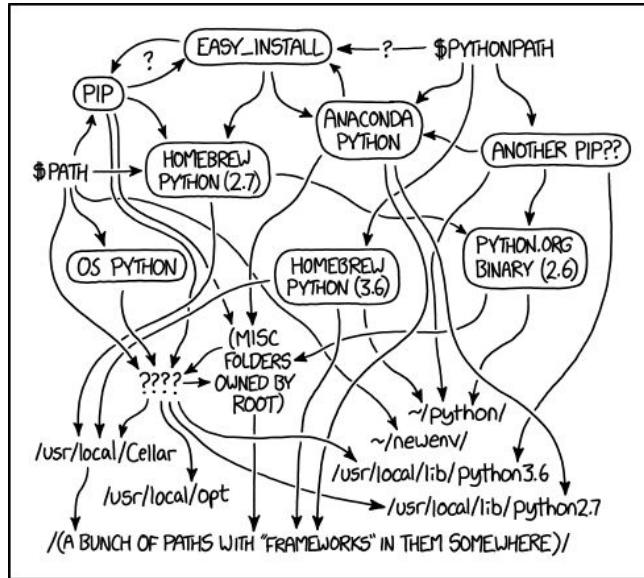
cProfile

profilehooks

py-spy



Frontend BlenderPymaxion



MY PYTHON ENVIRONMENT HAS BECOME SO DEGRADED
THAT MY LAPTOP HAS BEEN DECLARED A SUPERFUND SITE.

<https://xkcd.com/1987/>



What is Blender?

- 3d Computer graphics software
- Free and Open Source (GNU GPL licensed)
- Possibilities include 3D modelling, fluid and smoke simulation, soft body simulation





Blender Add-ons

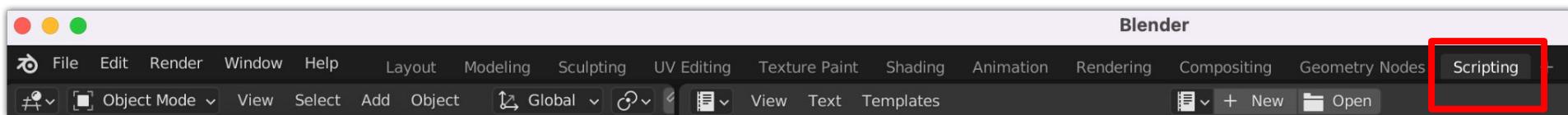
- Community made plugins
- Some free, some paid
- Extend capabilities of Blender





Adding your Cython package to Blender

- Build with Cython using the same Blender python version
 - (use whatever flavor virtualenv rather than the Blender python)
- Check your blender version from scripting tab interactive console `print(sys.version_info)`





Adding your Cython package to Blender

- Add Cython package to site-packages using symlinks

```
ln -s
```

```
/Users/mclare/workspaces/current/pymaxion/src/pymaxion  
/Users/mclare/Blender.app/.../site-packages/pymaxion
```



Adding your Add-on to Blender

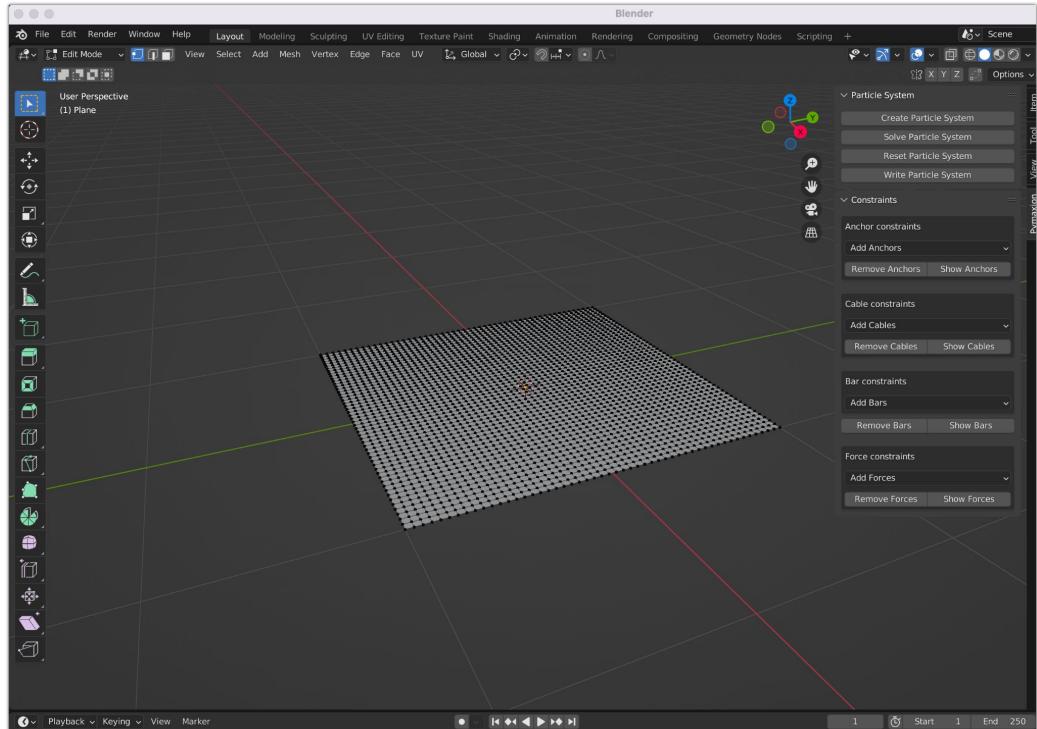
- Lots of disagreement about best way to develop with Blender
 - script hot reloading
 - close and relaunch Blender
- At *minimum* add Blender at the command line (easier to see and debug)
- Add Blender UI package to add-ons directory using symlinks

```
ln -s /Users/mclare/workspaces/current/blenderPymaxion  
/Users/mclare/Blender.app/Contents/Resources/3.2/scripts/addons
```



Blender Add-on Interface Creation

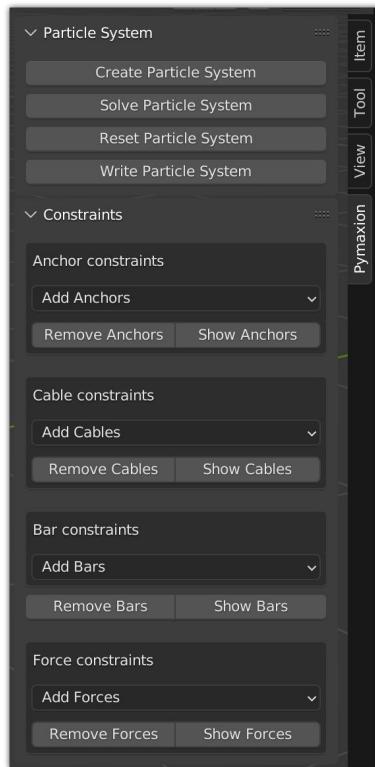
- Typical files:
 - `__init__.py`
 - `operator.py`
 - `ui.py`
 - `properties.py`





Blender Add-on Interface Creation

- Typical files:
 - `__init__.py`
 - `operator.py`
 - `ui.py`
 - `properties.py`





Blender Operators

- where you define all the actions taken in the UI
- where you import your external Cython package!
- specific Blender class structure in terms of attributes and methods

```
1 import bpy
2 from bpy.props import EnumProperty
3 from bpy.types import Operator
4 from profilehooks import profile
5 import json
6 from math import pi
7
8 # Pymaxion imports
9 from pymaxion.constraints.anchor import Anchor
10 from pymaxion.particle_system import ParticleSystem
11 from pymaxion.particle import Particle
12 from pymaxion.constraints.cable import Cable
13 from pymaxion.constraints.force import Force
14 from pymaxion.constraints.bar import Bar
```

blender_pymaxion/operator.py



Blender Operators

- where you define all the actions taken in the UI
- where you import your external Cython package!
- specific Blender class structure in terms of attributes and methods

```
72 class solve_particle_system(Operator):
73     bl_idname = "pymaxion_blender.solve_particle_system"
74     bl_label = "Solve Particle System"
75
76     def __init__(self):
77         print("Start")
78
79     def __del__(self):
80         print("End")
81
82     def execute(self, context):
83         if bpy.data.objects["Pymaxion Particle System"]:
84             obj = bpy.data.objects["Pymaxion Particle System"]
85             bpy.context.view_layer.objects.active = obj
86             new_obj = obj.copy()
87             new_obj.data = obj.data.copy()
88             obj.name = "Pymaxion Initial Particle System"
89             new_obj.name = "Pymaxion Particle System"
90             bpy.context.collection.objects.link(new_obj)
91             obj.hide_set(True)
92             print("Found particle system!")
93             data = self.profile_run(new_obj)
94
95             return {"FINISHED"}
```

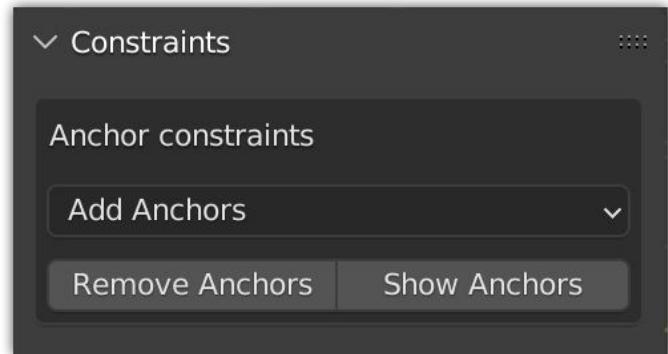
blender_pymaxion/operator.py



Blender UI

- Blender specific class prefix naming
- Blender specific class methods and attributes

```
34 class PYMAXION_PT_constraints(Panel):
35     bl_idname = "PYMAXION_PT_constraints"
36     bl_label = "Constraints"
37     bl_space_type = "VIEW_3D"
38     bl_region_type = "UI"
39     bl_category = "Pymaxion"
40
41     def draw(self, context):
42         layout = self.layout
43         scene = context.scene
44
45         box = layout.box()
46         box.label(text="Anchor constraints")
47         box.popover("PYMAXION_PT_Anchor")
48         row = box.row(align=True)
49         row.operator(
50             "pymaxion_blender.anchor_constraint", text="Remove Anchors"
51         ).action = "REMOVE"
52         row.operator(
53             "pymaxion_blender.anchor_constraint", text="Show Anchors"
54         ).action = "SHOW"
```

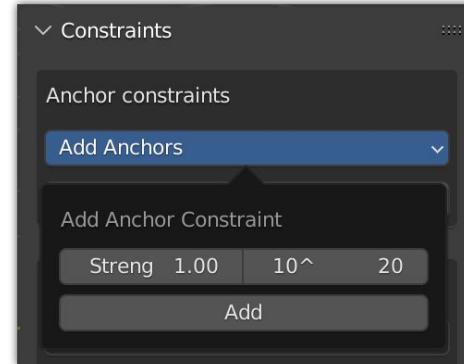




Blender UI

- Blender specific class prefix naming
- Blender specific class methods and attributes

```
96 class PYMAXION_PT_Anchor(Panel):
97     bl_label = "Add Anchors"
98     bl_idname = "PYMAXION_PT_Anchor"
99     bl_options = {"INSTANCED"}
100    bl_space_type = "VIEW_3D"
101    bl_region_type = "WINDOW"
102
103    def draw(self, context):
104        layout = self.layout
105        scene = context.scene
106        propertyGroup = getattr(scene, "Anchor")
107
108        layout.label(text="Add Anchor Constraint")
109        row = layout.row(align=True)
110        row.prop(propertyGroup, "base", text="Strength Value")
111        row.prop(propertyGroup, "power", text="10^")
112        row = layout.row(align=True)
113        row.operator("pymaxion_blender.anchor_constraint", text="Add").action = "ADD"
```





Blender Properties

- Typical files:
 - `__init__.py`
 - `operator.py`
 - `ui.py`
 - **`properties.py`**

```
import bpy

class MyPropertyGroup(bpy.types.PropertyGroup):
    custom_1: bpy.props.FloatProperty(name="My Float")
    custom_2: bpy.props.IntProperty(name="My Int")

bpy.utils.register_class(MyPropertyGroup)

bpy.types.Object.my_prop_grp = bpy.props.PointerProperty(type=MyPropertyGroup)
```

<https://docs.blender.org/api/current/bpy.types.PropertyGroup.html>



Blender Properties

- Typical files:
 - `__init__.py`
 - `operator.py`
 - `ui.py`
 - ~~`properties.py`~~

```
"Anchor": [
    {
        "name": "base",
        "type": "float",
        "attr": "base",
        "min": 1,
        "max": 10,
        "default": 1,
        "precision": 2
    },
    {
        "name": "power",
        "type": "int",
        "attr": "power",
        "min": -30,
        "max": 30,
        "default": 20
    }
],
```



Blender Properties

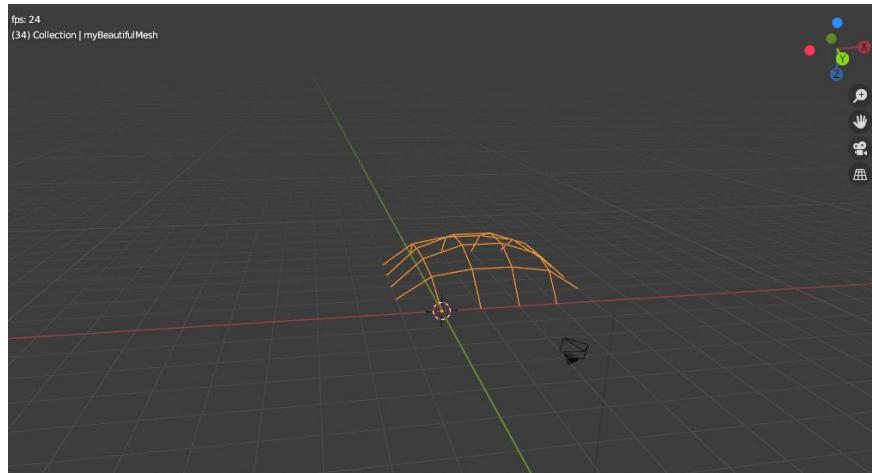
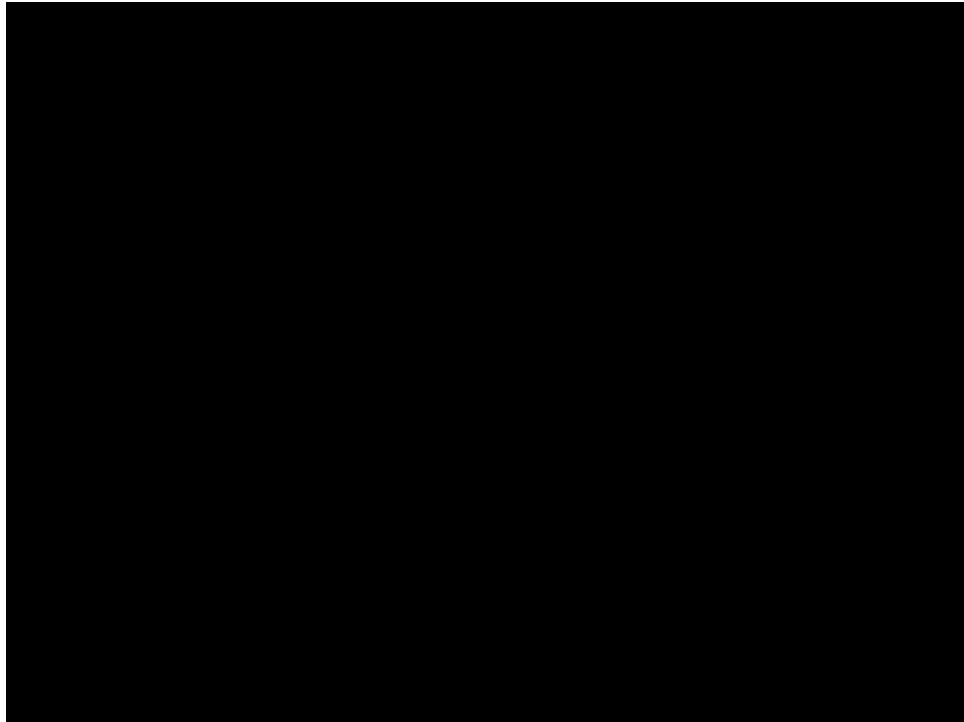
- Typical files:
 - `__init__.py`
 - `operator.py`
 - `ui.py`
 - ~~`properties.py`~~

```
46     def register():
47         for cls in classes:
48             register_class(cls)
49
50         # Load custom property groups from json
51         dir_path = os.path.dirname(os.path.realpath(__file__))
52         with open(dir_path + '/assets/property_groups.json', 'r') as f:
53             properties = json.load(f)
54
55         for groupName, attributeDefinitions in properties.items():
56             attributes = {}
57             for attributeDefinition in attributeDefinitions:
58                 attType = attributeDefinition['type']
59                 attName = attributeDefinition['name']
60                 # Note: type of attribute must be removed for class
61                 if attType == 'float':
62                     attributeDefinition.pop('type')
63                     attributes[attName] = FloatProperty(**attributeDefinition)
64                 elif attType == 'int':
65                     attributeDefinition.pop('type')
66                     attributes[attName] = IntProperty(**attributeDefinition)
67                 else:
68                     raise TypeError('Unsupported type (%s) for %s on %s!' % (attType, attName, groupName))
69
70         propertyGroupClass = type(groupName, (PropertyGroup,), {'__annotations__': attributes})
71         bpy.utils.register_class(propertyGroupClass)
72         setattr(bpy.types.Scene, groupName, PointerProperty(type=propertyGroupClass))
73         bpy.propertyGroups[groupName] = propertyGroupClass
```

blender_pymaxion/__init__.py



Pymaxion - Blender Demo!



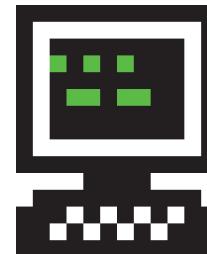


<https://github.com/m-clare/pymaxion>
[@eng_mclare](https://github.com/m-clare)

Thank you!



nyc.pyladies.com



recurse.com