



## Design Brief

|                          |  |
|--------------------------|--|
| <b>Client</b>            | Ms. Guzman   |
| <b>Target Consumer</b>   | Manufacturers, warehouses, healthcare systems, food/beverage producers, and large-scale logistics operators.   |
| <b>Designer(s)</b>       | Matthew Jeide, Preston Maxwell, Samuel Webster   |
| <b>Problem Statement</b> | Manual handling of cargo can introduce errors, safety risks, and inefficiencies. A significant number of hours in manufacturing/warehousing are spent moving materials manually, this time could instead be dedicated to higher-value tasks if this process could be automated.      |
| <b>Design Statement</b>  | We will design an AGV (automated guided vehicle) to automate these tedious processes. The AGV will be compact to increase efficiency in both cost and power.   |
| <b>Criteria</b>          | <ol style="list-style-type: none"><li>1. Able to pick up and store cargo.</li><li>2. Able to drop off cargo and able to retrieve cargo from storage.</li><li>3. Follows a designated colored path on the floor.</li><li>4. Able to recognize cargo on its path to pick up.</li></ol> |
| <b>Constraints</b>       | <ol style="list-style-type: none"><li>1. The design must be cost-effective, given only 3 motors and a servo.</li><li>2. The weight should be minimal.</li><li>3. The design must be structurally sound.</li><li>4. The prototype must be able to balance itself and move.</li></ol>  |