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# A rendezvous based coordination and communication model for multi-agent system

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Abstract

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This paper proposes a rendezvous based approach to coordinate rescue intervention in an urban area where radio communication is not available. The approach use a method for partitioning the city in some regions and then pre-plan a meeting schedule for agents to exchange their knowledge about key information such as civilian's position and status. The approach has been implemented and evaluated on the RoboCup rescue simulator.

*Note: This article was originally prepared for the 2011 IEEE International Conference on Intelligent Computing and Integrated Systems (ICISS)*

**Published in:**

Conference Anthology, IEEE

**Date of Conference:**

1-8 Jan. 2013

**Page(s):**

1 - 4

**Conference Location :**

China

**DOI:**

10.1109/ANTHOLOGY.2013.6784731

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