System Controller Firmware API Reference Guide i.MX8DXL Die (Ver 1.21)

NXP

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Overview

The System Controller (SC) provides an abstraction to many of the underlying features of the hardware. This function runs on a Cortex-M processor which executes SC firmware (FW). This overview describes the features of the SCFW and the APIs exposed to other software components.

Features include:

- System Initialization and Boot
- System Controller Communication
- Power Management
- · Resource Management
- · Pad Configuration
- Timers
- Interrupts
- Security
- Miscellaneous

Due to this abstraction, some HW described in the SoC RM that is used by the SCFW is not directly accessible to other cores. This includes:

- All resources in the SCU subsystem (SCU M4, SCU LPUART, SCU LPI2C, etc.).
- · All resource accessed via MSI links from the SCU subsystem (inc. pads, DSC, XRDC2, eCSR)
- · OCRAM controller, CAAM MP, eDMA MP & LPCG
- DB STC & LPCG, IMG GPR
- · GIC/IRQSTR LPCG, IRQSTR.SCU and IRQSTR.CTI
- · Some features of SNVS such as the RTC, button, and LPGPR1
- · Any other resources reserved by the port of the SCFW to the board

Note also the SECO uses some resources like CAAM JR0-1, SNVS LPGPR0, etc.

2 Overview

1.1 System Initialization and Boot

The SC firmware runs on the SCU immediately after the SCU Read-only-memory (ROM) finishes loading code/data images from the first container. It is responsible for initializing many aspects of the system. This includes additional power and clock configuration and resource isolation hardware configuration. By default, the SC firmware configures the primary boot core to own most of the resources and launches the boot core. Additional configuration can be done by boot code.

1.2 System Controller Communication

Other software components in the system communicate to the SC via an exposed API library. This library is implemented to make Remote Procedure Calls (RPC) via an underlying Inter-Processor Communication (IPC) mechanism. The IPC is facilitated by a hardware-based mailbox system.

Software components (Linux, QNX, FreeRTOS, KSDK) delivered for i.MX8 already include ports of the client API. Other 3rd parties will need to first port the API to their environment before the API can be used. The porting kit release includes archives of the client API for existing SW. These can be used as reference for porting the client API. All that needs to be implemented is the IPC layer which will utilize messaging units (MU) to communicate with the SCFW.

1.3 System Controller Services

The SCFW provides API access to all the system controller functionality exported to other software systems. This includes:

1.3.1 Power Management Service

All aspects of power management including power control, bias control, clock control, reset control, and wake-up event monitoring are grouped within the SC Power Management service.

- **Power Control** The SC firmware is responsible for centralized management of power controls and external power management devices. It manages the power state and voltage of power domains as well as bias control. It also resets peripherals as required due to power state transitions. This is all done via the API by communicating power state needs for individual resources.
- Clock Control The SC firmware is responsible for centralized management of clock controls. This includes clock sources such as oscillators and PLLs as well as clock dividers, muxes, and gates. This is all done via the API by communicating clocking needs for individual resources.
- Reset Control The SC firmware is responsible for reset control. This includes booting/rebooting a partition, obtaining reset reasons, and starting/stopping of CPUs.

Before any hardware in the SoC can be used, SW must first power up the resource and enable any clocks that it requires, otherwise access will generate a bus error. More detail can be found in the Power Management section. The Power Management (PM) API is documented here.

1.3.2 Resource Management Service

SC firmware is responsible for managing ownership and access permissions to system resources. The features of the resource management service supported by SC firmware include:

- Management of system resources such as SoC peripherals, memory regions, and pads
- Allows resources to be partitioned into different ownership groupings that are associated with different execution environments including multiple operating systems executing on different cores, TrustZone, and hypervisor
- · Associates ownership with requests from messaging units within a resource partition
- · Allows memory to be divided into memory regions that are then managed like other resources
- Allows owners to configure access permissions to resources
- Configures hardware components to provide hardware enforced isolation
- · Configures hardware components to directly control secure/nonsecure attribute driven on bus fabric
- Provides ownership and access permission information to other system controller functions (e.g. pad ownership information to the pad muxing functions)

Protection of resources is provided in two ways. First, the SCFW itself checks resource access rights when API calls are made that affect a specific resource. Depending on the API call, this may require that the caller be the owner, parent of the owner, or an ancestor of the owner. Second, any hardware available to enforce access controls is configured based on the RM state. This includes the configuration of IP such as XRDC2, XRDC, or RDC, as well as management pages of IP like CAAM.

Partitions own resources, pads, and memory regions. This includes owning MU resources to communicate with the $S \leftarrow CFW$. API calls to the SCFW lookup the owner of the MU the call comes in on, and that is treated as the calling partition. Different API calls then enforce operations based on the relationship of the calling partition to the partition being acted on. This association does not directly determine who can access the programming model of a resource IP. This is solely determine by the access rights defined (per partition) for the resource. Note partitions do not have owners (they are the owners), but they do have parent/child relationships. The creator of a partition is the parent unless that parent calls the API to change the parent. If no parent is desired, then the parent should be set to 0 (the SCFW itself). Being the patent provides some rights with respect to API calling (but not peripheral access).

More detail can be found in the Resource Management section. The Resource Management (RM) API is documented here.

1.3.3 Pad Configuration Service

Pad configuration is managed by SC firmware. The pad configuration features supported by the SC firmware include:

- Configuring the mux, input/output connection, and low-power isolation mode.
- · Configuring the technology-specific pad setting such as drive strength, pullup/pulldown, etc.
- Configuring compensation for pad groups with dual voltage capability.

The Pad (PAD) API is documented here.

4 Overview

1.3.4 Timer Service

Many timer oriented services are grouped within the SC Timer service. This includes watchdogs, RTC, and system counter.

- Watchdog The SC firmware provides "virtual" watchdogs for all execution environments. Features include
 update of the watchdog timeout, start/stop of the watchdog, refresh of the watchdog, return of the watchdog
 status such as maximum watchdog timeout that can be set, watchdog timeout interval, and watchdog timeout
 interval remaining.
- Real-Time-Clock The SC firmware is responsible for providing access to the RTC. Features include setting the time, getting the time, and setting alarms.
- System Counter The SC firmware is responsible for providing access to the SYSCTR. Features include setting
 an absolute alarm or a relative, periodic alarm. Reading is done directly via local hardware interfaces available
 for each CPU.

The Timer API is documented here.

1.3.5 Interrupt Service

The System Controller needs a method to inform users about asynchronous notification events. This is done via the Interrupt service. The service provides APIs to enable/disable interrupts to the user and to read the status of pending interrupts. Reading the status automatically clears any pending state. The Interrupt (IRQ) API is documented here.

1.3.6 Security Service

The SC firmware provides access to many security functions including:

- · Image Authentication
- Generating, exporting, and loading key blobs
- · Fuse programming
- Lifecycle management
- Attestation

The Security (SECO) API is documented here.

See the SECO API Reference Guide for more info.

1.3.7 Miscellaneous Service

On previous i.MX devices, miscellaneous features were controlled using IOMUX GPR registers with signals connected to configurable hardware. This functionality is being replaced with DSC GPR signals. SC firmware is responsible for programming the GPR signals to configure these subsystem features. The SC firmware also responsible for monitoring various temperature, voltage, and clock sensors.

- **Controls** The SC firmware provides access to miscellaneous controls. Features include software request to set (write) miscellaneous controls and software request to get (read) miscellaneous controls.
- DMA The SC firmware provides access to DMA channel grouping and priority functions.
- Temp The SC firmware provides access to temperature sensors.

The Miscellaneous (MISC) API is documented here.

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6	Disclaime

Usage

3.1 SCFW API

Calling the functions in the SCFW requires a client API which utilizes an RPC/IPC layer to communicate to the SC—FW binary running on the SCU. Application environments (Linux, QNX, FreeRTOS, KSDK) delivered for i.MX8 already include ports of the client API. Other 3rd parties will need to first port the API to their environment before the API can be used. The porting kit release includes archives of the client API for existing SW. These can be used as reference for porting the client API. All that needs to be implemented is the IPC layer which will utilize messaging units (MU) to communicate with the SCFW.

The SCFW API is documented in the individual API sections. There are examples in the Details section for each service.

- · Resource Management
- Power Management
- Pad Configuration
- Timers
- Interrupts
- Miscellaneous

3.2 Loading

The SCFW is loaded by including the binary (scfw_tcm.bin) in the boot container.

3.3 Boot Flags

The image container holding the SCFW should also have the boot flags configured. This is a set of flags (32-bits) specified with the -flags option to mkimage.

These are defined as:

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Flag	Bit	Meaning
SC_BD_FLAGS_NOT_SECURE	16	Initial boot partition is not secure
SC_BD_FLAGS_NOT_ISOLATED	17	Initial boot partition is not isolated
SC_BD_FLAGS_RESTRICTED	18	Initial boot partition is restricted
SC_BD_FLAGS_GRANT	19	Initial boot partition grants access to the SCFW
SC_BD_FLAGS_NOT_COHERENT	20	Initial boot partition is not coherent
SC_BD_FLAGS_ALT_CONFIG	21	Alternate SCFW config (passed to board.c)
SC_BD_FLAGS_EARLY_CPU_START	22	Start some CPUs early
SC_BD_FLAGS_DDRTEST	23	Config for DDR stress test
SC_BD_FLAGS_NO_AP	24	Don't boot AP even if requested by ROM

See the sc_rm_partition_alloc() function for more info. Note some of the flags are inverted before calling this function! This results in a default (all 0) which is appropriate for normal OS execution. That is a partition which is secure, isolated, not restricted, not grant, coherent, no early start, and no DDR test.

3.4 CPU Start Address

The execution address passed in the boot container is used by the SCFW to start the CPU. This is done by calling sc_pm_boot() or sc_pm_cpu_start(), depending on the partition info specified in the container. This address is restricted by the hardware implementation.

3.4.1 Cortex-A Start Address

These cores are restricted to the following. Note the allowed address is CPU dependent.

Address	CPU
0x00000000	Any
0x00000040	1
0x00000080	2
0x000000C0	3
0x00000100	0
0x00000140	1
0x00000180	2
0x000001C0	3
0x00010000	1
0x00020000	2
0x00030000	3
0x80000000	Any
0x80000040	1
0x80000080	2
0x800000C0	3
0x80000100	0
0x80000140	1
0x80000180	2
0x800001C0	3
0x80010000	1
0x80020000	2
0x80030000	3

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Some devices alias OCRAM to ROM. On these, if an OCRAM address is specified the SCFW will modify it to a ROM address. This will allow the code to be fetched from the OCRAM. Be warned the PC will be in the ROM address space.

3.4.2 Cortex-M Start Address

The hardware has no mechanism to set the boot address. These cores will always start at the beginning of TCM. The SCFW will take any other address specified and write a jump instruction to the beginning of TCM.

3.5 Cortex-M4 DDR Aliasing

Devices without a SMMU include a basic translation block that can be leveraged to alias DDR memory onto the Cortex-M4 code bus. This aliasing allows performance improvements when Cortex-M4 code is located in DDR memory. The Cortex-M4 image can active aliasing during execution by updating the MCM Process ID register (MCM_PID). The DDR region will be aliased to the FlexSPI0 memory-mapped (XIP) space.

The following mappings are supported:

MCM_PID	DDR Region	Size	Alias
0x7E	0x88000000 - 0x8FFFFFF	128MB	0x08000000 - 0x0FFFFFF
0x7F	0x90000000 - 0x97FFFFF	128MB	0x10000000 - 0x17FFFFF
Other	N/A	N/A	No Alias

Aliasing must be activated while executing from a non-aliased region. The recommended flow to boot the Cortex-M4 into an aliased DDR region is as follows:

- · Link the image for the aliased region
- Reset vector must point to unaliased DDR start address
- · Specify the load address to be unaliased DDR region in the boot container
- · After Cortex-M4 execution begins from unaliased DDR, jump to the aliased region

Notes:

- Enabling aliasing via the MCM PID will result in loss of access to the corresponding FlexSPI address space.
- Use caution when using the Cortex-M4 code and system bus caches while aliasing is active to avoid coherency issues.

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Resource Management

SCFW is responsible for managing ownership and access permissions to system resources. The resource management functions of the SCFW are used to divide up the System on a Chip (SoC) resources and to control master transaction attributes and peripheral access permissions. The features supported by the SCFW are:

- Management of system resources such as SoC peripherals, memory regions and pads.
- Allows resources to be partitioned into different ownership groupings that are associated with different execution environments.
- · Allows owners to configure access permissions to resources.
- · Provides hardware enforced isolation.

See the Overview. The Resource Management (RM) API is documented here.

4.1 Partitions

One of the primary concepts of resource management in the SCFW is resource partitions (aka partitions). These are used to define a 'logical SoC' made up of resources, pads, and memory regions.

Partitions have the following characteristics. All partitions:

- · can be created and destroyed, at boot and dynamically during run-time,
- · have a hierarchical relationship, every partition has a parent,
- own resources (master and peripheral), pads, and memory regions,
- are restricted, by default, to only accessing the resources they own,
- · can be booted, rebooted, and powered down,
- have a power state; can transition to other power states,
- have a watchdog timer, RTC alarm, and system counter alarm.

Partitions are created by calling the SCFW to allocate them. Resources, pads, memory regions, etc. are then assigned or moved to the new partition thus defining the 'logical SoC'. The SCFW uses an assignment scheme for resource management rather than an allocation scheme. This is similar to virtualization and VMs.

At boot all resources belong to one partition. The SCFW creates some partitions in the board porting layer and then others are created dynamically by the running CPUs. Partitions should be created in the SCFW for any CPU that will be started by the SCFW due to parameters passed from the ROM and defined in the boot image containers.

Partitions can be created in several ways. They can be created by default by the SCFW using parameters passed from the ROM (determined by parameters in the boot container), they can be created in the board_system_config() function of the board porting layer of the SCFW, or be created dynamically by calling sc rm partition alloc().

Partitions have several attributes that are defined when they are created:

- Secure by default, master would generate secure transactions and resources would require secure access. Only a secure partition can create another secure partition. Used primarily for TrustZone.
- **Isolated** use XRDC2 to isolate. Should be true for all partitions except when a secure partition creates a non-secure partitions running on the same CPU as a secure partition. This parameter just results in the partition having the same DID as the parent.
- Restricted true if the partition cannot create partitions.
- Grant true if all resources in this partition should always remain accessible to the parent. Only used when
 creating a partition with no CPUs. Useful to just isolate the access of a bus master like a DMA channel to a
 subset of memory.
- Coherent true if this partition will contain both AP clusters running in an SMP configuration.

The boot partition parameters come from the container. See the Boot Flags section.

In addition, partitions can be made confidential using the sc_rm_set_confidential() function. A confidential partition cannot not have any resource or memory assigned to it anymore. Useful for some security related use-cases.

The parent/child relationship directly affects partition reboot. When a partition is rebooted, its child partitions are automatically deleted and all resources returned to the parent. This allows the parent to rerun and again recreate the child partition like it did when it ran the first time. For more information on resets and partition reboot, see the Reset section of the Porting Guide.

4.2 Resources

Resources represent the IP blocks in the SoC. They can be masters (i.e. generate bus transactions), peripherals (i.e. e. have a programming model), or both. Resources always have an owning (only one) partition. Access control of resources consists of two primary mechanisms:

• API Access - the SCFW API functions use info like the calling partition and resource parameter to decide if actions can be take on a resource. The ownership of the resource and hierarchical relationship of the owning partition and the calling partition are used to decide if operations are authorized. These access rights vary by function and are described in the function documentation.

4.3 Pads 13

• Hardware Protection - the SCFW programs the underlying protection hardware (XRDC2 in the case of i.MX8) to control which masters can access which peripherals. Access permissions are maintained for each resource and can be set by the owner for each accessing partition. By default, only masters in a partition can only access peripherals in the same partition.

Resources can be assigned or moved by the owner to another partition. Master resources can have security, privilege, SMMU bypass, and streamID (SID) set. Peripheral resources can have access permissions set. The security state of masters can only be set if the partition owning the master is secure. Master resources generate a domain ID (DID) on the bus identifying what partition they belong to. All master resources in a partition generate the same ID so they all have the same access rights (CPUs and all other bus masters). For example, a DC assigned to a partition can only access memory accessible to that partition. The partition needs to either own the memory or the memory needs to have access rights granted to that partition using sc_rm_set_memreg_permissions(). If this needs to be a subset of memory then a new memory region should be created using one of the split or frag functions.

Note that not all resources have independent access controls. This is a function of the hardware design. Some peripherals share access control programming. This is often the case for display and camera interfaces. The entire interface (interface IP, PWM, I2C, LPCG, etc.) are in a single 64K page and have a single access control slot.

While Cortex-A cores part of a cluster can be assigned to different partitions, this is not guaranteed to always identify bus transactions as belonging to a core. Due to variations in microarchitecture of different Cortex-A cores, they have varying abilities to identify traffic as belonging to a specific core. This ability depends on transaction type (strongly ordered, device, exclusive, normal, etc.) as well as L1/L2 cache usage. Because cores can define these transaction properties themselves, isolation between CPUs in a cluster can never be considered secure. Because of this, i.MX8 processors do not have a product requirement to support this capability and the ability to isolate cores is not tested. CPUs in a cluster should always be in the same partition as the cluster.

4.3 Pads

Pads represent the individual pads of the SoC. They are owned by partitions. They have no direct access, so access control is similar to the SCFW API access control of resources.

4.4 Memory Regions

Memory regions represent blocks of memory with a start and end address. Once defined, they have ownership and access controls similar to resources. They support both kinds of access protections. The memory region owner can:

- · assign/move to another partition
- · can create a new memory region within the bounds of an existing owned region
- · can split a region
- · can configure access permissions

The SCFW implementation supports a maximum of 64 memory regions. Beyond this, the HW implementation further restricts the number of regions and this restriction varies depending on what HW checker is used for each memory and how many regions that specific checker supports. For example, most i.MX8 SoC have a limit of 16 regions for the DDR address range. Of these 16, one is used by the SCFW to define a I/O space pass through so the effective limit for SCFW API use is 15 unique DDR regions. Also, the SCFW will optimize usage of the HW regions. For example, if two regions are coincident, it will only use one HW region to enforce the access policy. These totals are for the entire system.

4.5 SCFW API

CPUs in partitions make SCFW API calls via a remote procedure call (RPC) mechanism. The RPC mechanism serializes the call and sends it over an inter-processor communication (IPC) mechanism implemented via message units (MU). Message units are resources and since all resources are owned by a partition, the SCFW can identify the owner and hence determine the calling partition. The calling partition is often used to determine if an operation is allowed or not.

The SCFW has the following services that operate on partitions and resources:

- · Resource Management (RM) used to manage partitions, resources, pads, memory regions
- · Power Management (PM) used to boot, reboot, and change power state of partitions and resources
- · Timer used to configure and use partitions-specific watchdogs and alarms
- Interrupt (IRQ) used to manage interrupts sent to partitions via their MUs

The other services (pad, miscellaneous, and security) do not operate on partitions or resources. The Resource Management (RM) API is documented here.

Note there are eight MUs (five in LSIO, one in each M4, and one in the SCU itself) that are used to communicate to the SCFW). This is because one end of each of these is accessible only via a private bus used by the SCU.

- SC R MU 0A-4A (A side used by CPUs, B-side used by SCU)
- SC_R_M4_0_MU_1A (A side used by CPU, B-side used by SCU)
- SC R M4 1 MU 1A (A side used by CPU, B-side used by SCU)
- SC_R_SC_MU_1A in the SCU (both sides used by SCU for loopback testing)

The SCFW does not dictate which CPU uses each of these. Access is controlled by the standard SCFW RM partitioning. SCFW has to power at least one up for each CPU and these are specified in the boot container. The default in mkimage is the M4 MU for each M4 and MU 0A for the AP.

Beyond this, all usage is determined by the board.c port and the AP/M4 SW. Access to MUs is controlled by the SCFW RM partitioning which is configured in board.c and at run-time by the SW themselves. Typical usage is MU_0A is kept and used by the AP secure code and MU_1A is used by the AP non-secure code. Using AP clusters to run separate OSes or using a hypervisor would require additional usage of these MUs.

4.6 Hardware Resource/Memory Isolation

The i.MX8 SoC contains a mix of Cortex-A and Cortex-M CPUs which frequently operate in an asymmetric mode with different software environments executing on them (OSes, RTOSes, etc.). To keep these SW environments from unintentionally interfering with each other, i.MX8 contains HW mechanisms to enforce isolation. These mechanisms operate in a manner similar to ARM's TrustZone in that transactions from masters are annotated with user-side band information to indicate their domain and the access controls allow/disallow access to peripherals/memory based on this information.

The HW that does this is the XRDC2 (aka XRDC). The XRDC consists of a manager (per subsystem), MDAC, PAC, MSC, and MRC components. The MDAC is used to annotate the transactions and the PAC, MSC, and MRC are used to control access. See the figure below for the basic XRDC integration architecture. In i.MX8, the XRDC replaces the RDC and TrustZone components (CSU, TZASC, etc.) found in previous i.MX processors.

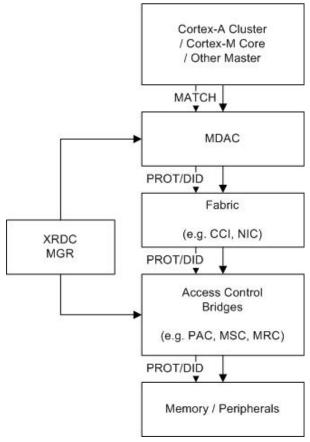


Figure 4.1 XRDC Interaction for Bus Transactions

There are five XRDC components:

- Manager (MGR) provides the programming interface for the entire XRDC
- Master Domain Assignment Controller (MDAC) identifies transaction sources/types and appends information such as domain ID (DID), streamID (SID), etc.
- Peripheral Access Controller (PAC) accepts/rejects transactions based on transaction attributes and programmed permissions; supports up to 128 different peripherals (IPS or APB based); based on module enables and/or select signals so has no concept of addressing
- Memory Space Controller (MSC) accepts/rejects transactions based on transaction attributes and programmed permissions; supports a single memory space; has no concept of addressing
- Memory Region Controller (MRC) accepts/rejects transactions based on transaction attributes and programmed permissions; supports multiple memory spaces by allowing the overall space to be divided into regions (with programmable start/end addresses)

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The SCFW configures the XRDC2 components based on partition, resource, and memory region configuration. For more information on the XRDC capabilities, refer to the XRDC2 section of the RM.

4.7 Example

The following shows the partition creation for an example system. Initially, the SCFW creates three partitions. The SCFW and SECO partitions are secure and isolated. The boot partition parameters depend on the boot flags from the boot image container. These would also normally be secure and isolated. The boot partition contains all the memory and almost all the resources. Only the minimal resources required for the SCFW and SECO to function are owned by those partitions.

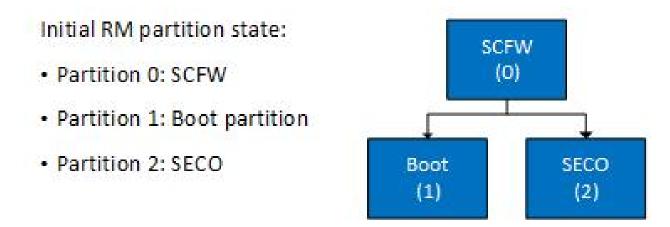


Figure 4.2 Initial Partition Configuration

Before starting the CPUs, the SCFW calls board_system_config(). This is where the partitions are created for CPUs started by the SCFW. These partitions usually have code loaded by the ROM and execution automatically started by the SCFW. Partitions can also be created for CPUs that aren't started immediately by the SCFW. Code can be loaded for these partitions by the ROM at boot by defining them as data images with mkimage. Code could also be loaded by the parent so long as it has access rights to the memory. The parent can then boot such a partition later by calling sc pm_boot(). An M4 partition would normally be non-secure.

4.7 Example 17

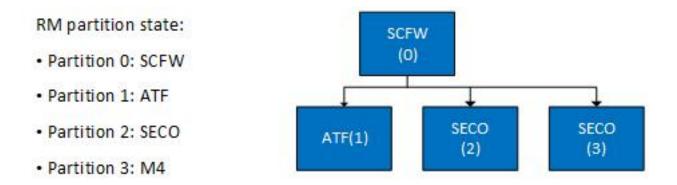


Figure 4.3 Board Partition Configuration

The boot partition can also be considered the ATF partition because that is the first thing run on the AP core. ATF creates a partition for Linux to use. This partition would typically be non-secure and not isolated. The Cortex-A CPUs, MU0A, the SC_R_SYSTEM resource, and a little bit of memory are kept by the ATF partition. All other resources are assigned to the Linux partition.

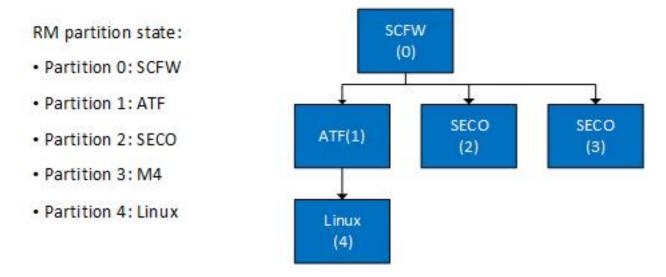


Figure 4.4 Final Partition Configuration

ATF starts Linux. Linux could dynamically create an additional partition for the other M4 to handle something like sensor fusion or a media processing engine.

Resource Ma	anagement
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Power Management

SCFW is responsible for managing the power state of the SoC. This includes static and dynamic power management, clock management, and reset control. The features supported by the SCFW are:

- · Changing the power state of the system, partitions, and resources.
- · Configuring clocks and PLLs.
- · Configuring and responding to wake-up sources.
- · Reset control including booting/rebooting a partition, obtaining reset reasons, and starting/stopping of CPUs.

See the Overview. The Power Management (PM) API is documented here.

5.1 Wake from Low Power

5.1.1 Wake Event Sources

The SoC RM provides some background on the wakeup capability of the IRQSTEER and GIC modules. The wakeup outputs of the IRQSTEER and GIC are connected to IRQ lines of the SCU and fielded by SCFW to wake up the respective CPU for wake event processing. The SCFW Interrupt Service can also generate wakeup events that do not require the GIC or IRQSTEER to remain active. Each of these wake events sources are described in the sections below. Note the tradeoff between flexibility of the wakeup method and power consumption that must considered during system design.

5.1.2 GIC Wake Events

The GIC module provides a facility to transition each redistributor interface into a sleep state with wakeup capability. AP software uses the GICR_WAKER register to quiesce the respective redistributor interface. Prior to executing WFI, AP software notifies SCFW of the request to enter a deeper low-power mode using sc_pm_req_cpu_low_power_mode(). Note that the GIC must be powered and clocked to generate a wake event. The following table shows the GIC wakeup options available:

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sc_pm_req_cpu_low_power_← mode wake src parameter	Wakeup Description	Notes
SC_PM_SRC_GIC	GIC wakeup will cause SCFW to wake the respective CPU	GIC resource must remain powered and clocked (power mode >= LP). System power consumption will be higher to keep respective subsystem with GIC powered and clocked. K← S1 power mode is inhibited with this wake method.
SC_PM_WAKE_SRC_IRQSTEE↔ R_GIC	Refer to IRQSTEER wake events in the next section	

5.1.3 IRQSTEER Wake Events

One of the IRQSTEER module instances (SC_R_IRQSTR_SCU2) is reserved for AP wake events. The IRQST—EER does not require clocks to generate a wakeup event and therefore offers lower power consumption than GIC wakeup methods. Prior to executing WFI, AP software notifies SCFW of the request to enter a deeper low-power mode using sc_pm_req_cpu_low_power_mode(). Note that the IRQSTEER must be powered to generate a wake event. The following table shows the IRQSTEER wakeup options available:

sc_pm_req_cpu_low_power_←	Wakeup Description	Notes
mode		
wake_src parameter	O at a second constitute first at a second circum	OIO LIDOOTEED
SC_PM_WAKE_SRC_IRQSTEE↔ R_GIC	2-stage wakeup with first stage being IRQSTEER and second stage being GIC	GIC and IRQSTEER resources must remain powered (power mode >= STBY). AP software must "replicate" the desired wake sources from the GIC to the IRQSTEER. System power consumption will be higher to keep respective subsystem with G← IC and IRQSTEER powered. K← S1 power mode is inhibited with this wake method.
SC_PM_WAKE_SRC_IRQSTEER	IRQSTEER wakeup will cause SC← FW to wake the "primary" CPU	IRQSTEER resource must remain powered (power mode >= STBY). System power consumption will be higher to keep respective subsystem with IRQSTEER powered. K← S1 power mode is inhibited with this wake method. Primary CPU designated using sc_pm_set_cpu← _resume.

5.1.4 SCU Wake Events

SCU wake events allow the entire system to be placed into retention/powered down. These wake sources are enabled using the SCFW IRQ service API (sc_irq_enable). Prior to executing WFI, AP software notifies SCFW of the request to enter a deeper low-power mode using sc_pm_req_cpu_low_power_mode(). The following table shows the SCU wakeup options available:

5.2 System Power Off 21

sc_pm_req_cpu_low_power_← mode wake_src parameter	Wakeup Description	Notes
SC_PM_WAKE_SRC_SCU	SCU wake event will wake the "primary" CPU	GIC and IRQSTEER resources can be powered down. KS1 power mode is possible with this wake method.

A summary of SCU wake events supported by SCFW:

- RTC
- ON_OFF button
- Pad event
- · System Counter

5.1.5 Pad Wake Events

The pad modules provide a programmable wakeup capability. Software must enable and configure the respective pad to generate a wakeup using the SCFW IRQ Service API. The following is an example of the calls required to enable and service a pad wake events for the UART RX signal (note that SCFW API return error checking removed for simplicity).

```
/* Register for PAD wakeup *
sc_irq_enable(ipc, MU_RSRC, SC_IRQ_GROUP_WAKE, SC_IRQ_PAD, SC_TRUE);
/* Enable UART_RX pad wakeup */
sc_pad_set_wakeup(ipc, UART_RX_PAD, SC_PAD_WAKEUP_LOW_LVL);
/* Enter low-power mode and wait for wakeup... */
/* Query SCU wakeup event status */
uint32_t status;
sc_irq_status(ipc, MU_RSRC, SC_IRQ_GROUP_WAKE, &status);
/* Check for pad wakeup */
if (status & SC_IRQ_PAD)
    /* Check for UART_RX pad wakeup */
    /* Note: SCFW updates pending pad wakeup config to SC_PAD_WAKEUP_OFF */
    sc_pad_wakeup_t uart_wakeup;
    sc_pad_get_wakeup(ipc, UART_RX_PAD, &uart_wakeup);
    if (uart_wakeup == SC_PAD_WAKEUP_OFF)
        /* UART_RX pad generated wake event */
        /* Else some other pad caused the wake event */
        /* Disable the UART_RX pad wakeup */
        sc_pad_set_wakeup(ipc, UART_RX_PAD, SC_PAD_WAKEUP_OFF);
```

5.2 System Power Off

The system can be powered off by calling sc_pm_set_sys_power_mode() with mode = SC_PM_PW_MODE_OFF. This calls board_power() in board.c to allow for port specific control of the PMIC. Note only a caller with access to the SC_R_SYSTEM resource can call this function.

5.3 Reset Control

For more info on resets, see the Reset section. This includes booting and rebooting partitions, rebooting the system, starting/stopping CPUs, and watchdog usage.

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Chapter 6

Resource List

The table below lists the resources available in the system (SoC specific). Resource is a parameter to many API calls.

The *_PIDx resources represent multiple contexts that the master can act as (aka process IDs). The master functions normally as PID0 but can switch to other PIDs if it needs to access the resources of another SW system. This is primarily used to support virtualization. Each master PID resource can be assigned a different SID and as a result a different translation contect in the SMMU. If not using virtualization, all PIDs for a resource should be assigned to the partition owning the master IP.

Note the resource define values (index) are listed here but the define should be used. These are defined in types.h. Functions like sc_rm_set_resource_movable() take a resource range. This range is numerical by index and not alphabetical by define name. Range should be lowest to highest index.

See also

RM: Resource Management Service PM: Power Management Service

Resource	Index	Subsystem	Instance	Description
SC_R_A35	507	A35	0	Cluster
SC_R_A35_0	508	A35	0	CPU 0
SC_R_A35_1	509	A35	0	CPU 1
SC_R_ADC_0	101	ADMA	0	ADC 0
SC_R_ASRC_0	414	ADMA	0	ASRC 0
SC_R_ATTESTATION	545	SC	0	Attestation
SC_R_AUDIO_CLK_0	493	ADMA	0	Audio clock 0
SC_R_AUDIO_CLK_1	494	ADMA	0	Audio clock 1
SC_R_AUDIO_PLL_0	325	ADMA	0	Audio PLL 0
SC_R_AUDIO_PLL_1	492	ADMA	0	Audio PLL 1
SC_R_BOARD_R0	524	BOARD	0	Misc. board component 0
SC_R_BOARD_R1	525	BOARD	0	Misc. board component 1
SC_R_BOARD_R2	526	BOARD	0	Misc. board component 2
SC_R_BOARD_R3	527	BOARD	0	Misc. board component 3
SC_R_BOARD_R4	528	BOARD	0	Misc. board component 4

Resource	Index	Subsystem	Instance	Description
SC_R_BOARD_R5	529	BOARD	0	Misc. board component 5
SC_R_BOARD_R6	530	BOARD	0	Misc. board component 6
SC_R_BOARD_R7	531	BOARD	0	Misc. board component 7
SC_R_CAAM_JR1	500	SC	0	CAAM job ring 1
SC_R_CAAM_JR1_OUT	514	SC	0	CAAM job ring 1 out
SC_R_CAAM_JR2	501	SC	0	CAAM job ring 2
SC_R_CAAM_JR2_OUT	515	SC	0	CAAM job ring 2 out
SC_R_CAAM_JR3	502	SC	0	CAAM job ring 3
SC_R_CAAM_JR3_OUT	516	SC	0	CAAM job ring 3 out
SC_R_CAN_0	105	ADMA	0	CAN 0
SC_R_CAN_1	106	ADMA	0	CAN 1
SC_R_CAN_2	107	ADMA	0	CAN 2
SC_R_DB	11	DB	0	DB
SC_R_DEBUG	354	SC	0	Debug
SC_R_DMA_0_CH0	64	ADMA	0	DMA 0 channel 0 (audio)
SC_R_DMA_0_CH1	65	ADMA	0	DMA 0 channel 1 (audio)
SC_R_DMA_0_CH10	74	ADMA	0	DMA 0 channel 10 (audio)
SC_R_DMA_0_CH11	75	ADMA	0	DMA 0 channel 11 (audio)
SC_R_DMA_0_CH12	76	ADMA	0	DMA 0 channel 12 (audio)
SC_R_DMA_0_CH13	77	ADMA	0	DMA 0 channel 13 (audio)
SC_R_DMA_0_CH14	78	ADMA	0	DMA 0 channel 14 (audio)
SC_R_DMA_0_CH15	79	ADMA	0	DMA 0 channel 15 (audio)
SC_R_DMA_0_CH16	80	ADMA	0	DMA 0 channel 16 (audio)
SC_R_DMA_0_CH17	81	ADMA	0	DMA 0 channel 17 (audio)
SC_R_DMA_0_CH18	82	ADMA	0	DMA 0 channel 18 (audio)
SC_R_DMA_0_CH19	83	ADMA	0	DMA 0 channel 19 (audio)
SC_R_DMA_0_CH2	66	ADMA	0	DMA 0 channel 2 (audio)
SC_R_DMA_0_CH20	84	ADMA	0	DMA 0 channel 20 (audio)
SC_R_DMA_0_CH21	85	ADMA	0	DMA 0 channel 21 (audio)
SC_R_DMA_0_CH22	86	ADMA	0	DMA 0 channel 22 (audio)
SC_R_DMA_0_CH23	87	ADMA	0	DMA 0 channel 23 (audio)
SC_R_DMA_0_CH24	88	ADMA	0	DMA 0 channel 24 (audio)
SC_R_DMA_0_CH25	89	ADMA	0	DMA 0 channel 25 (audio)
SC_R_DMA_0_CH26	90	ADMA	0	DMA 0 channel 26 (audio)
SC_R_DMA_0_CH27	91	ADMA	0	DMA 0 channel 27 (audio)
SC_R_DMA_0_CH28	92	ADMA	0	DMA 0 channel 28 (audio)
SC_R_DMA_0_CH29	93	ADMA	0	DMA 0 channel 29 (audio)
SC_R_DMA_0_CH3	67	ADMA	0	DMA 0 channel 3 (audio)
SC_R_DMA_0_CH30	94	ADMA	0	DMA 0 channel 30 (audio)
SC_R_DMA_0_CH31	95	ADMA	0	DMA 0 channel 31 (audio)
SC_R_DMA_0_CH4	68	ADMA	0	DMA 0 channel 4 (audio)
SC_R_DMA_0_CH5	69	ADMA	0	DMA 0 channel 5 (audio)
SC_R_DMA_0_CH6	70	ADMA	0	DMA 0 channel 6 (audio)
SC_R_DMA_0_CH7	71	ADMA	0	DMA 0 channel 7 (audio)
SC_R_DMA_0_CH8	72	ADMA	0	DMA 0 channel 8 (audio)

Resource	Index	Subsystem	Instance	Description
SC_R_DMA_0_CH9	73	ADMA	0	DMA 0 channel 9 (audio)
SC R DMA 2 CH0	254	ADMA	0	DMA 2 channel 0
SC R DMA 2 CH1	255	ADMA	0	DMA 2 channel 1
SC R DMA 2 CH10	432	ADMA	0	DMA 2 channel 10
SC R DMA 2 CH11	433	ADMA	0	DMA 2 channel 11
SC R DMA 2 CH12	434	ADMA	0	DMA 2 channel 12
SC_R_DMA_2_CH13	435	ADMA	0	DMA 2 channel 13
SC R DMA 2 CH14	436	ADMA	0	DMA 2 channel 14
SC R DMA 2 CH15	437	ADMA	0	DMA 2 channel 15
SC R DMA 2 CH16	438	ADMA	0	DMA 2 channel 16
SC R DMA 2 CH17	439	ADMA	0	DMA 2 channel 17
SC R DMA 2 CH18	440	ADMA	0	DMA 2 channel 18
SC R DMA 2 CH19	441	ADMA	0	DMA 2 channel 19
SC R DMA 2 CH2	256	ADMA	0	DMA 2 channel 2
SC R DMA 2 CH20	442	ADMA	0	DMA 2 channel 20
SC_R_DMA_2_CH21	443	ADMA	0	DMA 2 channel 21
SC R DMA 2 CH22	444	ADMA	0	DMA 2 channel 22
SC R DMA 2 CH23	445	ADMA	0	DMA 2 channel 23
SC R DMA 2 CH24	446	ADMA	0	DMA 2 channel 24
SC R DMA 2 CH25	447	ADMA	0	DMA 2 channel 25
SC R DMA 2 CH26	448	ADMA	0	DMA 2 channel 26
SC R DMA 2 CH27	449	ADMA	0	DMA 2 channel 27
SC_R_DMA_2_CH28	450	ADMA	0	DMA 2 channel 28
SC R DMA 2 CH29	451	ADMA	0	DMA 2 channel 29
SC R DMA 2 CH3	257	ADMA	0	DMA 2 channel 3
SC R DMA 2 CH30	452	ADMA	0	DMA 2 channel 30
SC R DMA 2 CH31	453	ADMA	0	DMA 2 channel 31
SC R DMA 2 CH4	258	ADMA	0	DMA 2 channel 4
SC R DMA 2 CH5	427	ADMA	0	DMA 2 channel 5
SC R DMA 2 CH6	428	ADMA	0	DMA 2 channel 6
SC R DMA 2 CH7	429	ADMA	0	DMA 2 channel 7
		ADMA	0	
SC_R_DMA_2_CH8	430			DMA 2 channel 8
SC_R_DMA_2_CH9	431	ADMA	0	DMA 2 channel 9
SC_R_DMA_3_CH0	460	ADMA	0	DMA 3 channel 0 DMA 3 channel 1
SC_R_DMA_3_CH1	461	ADMA	0	DMA 3 channel 10
SC_R_DMA_3_CH10	470	ADMA	0	
SC_R_DMA_3_CH11	471	ADMA	0	DMA 3 channel 11
SC_R_DMA_3_CH12	472	ADMA	0	DMA 3 channel 12
SC_R_DMA_3_CH13	473	ADMA	0	DMA 3 channel 13
SC_R_DMA_3_CH14	474	ADMA	0	DMA 3 channel 14
SC_R_DMA_3_CH15	475	ADMA	0	DMA 3 channel 15
SC_R_DMA_3_CH2	462	ADMA	0	DMA 3 channel 2
SC_R_DMA_3_CH3	463	ADMA	0	DMA 3 channel 3
SC_R_DMA_3_CH4	464	ADMA	0	DMA 3 channel 4
SC_R_DMA_3_CH5	465	ADMA	0	DMA 3 channel 5
SC_R_DMA_3_CH6	466	ADMA	0	DMA 3 channel 6
SC_R_DMA_3_CH7	467	ADMA	0	DMA 3 channel 7

Resource	Index	Subsystem	Instance	Description
SC_R_DMA_3_CH8	468	ADMA	0	DMA 3 channel 8
SC_R_DMA_3_CH9	469	ADMA	0	DMA 3 channel 9
SC_R_DRC_0	12	DRC	0	DDR controller/phy
SC_R_ELCDIF_PLL	323	ADMA	0	eLCDIF PLL
SC_R_ENET_0	251	CONN	0	ENET-AVB
SC_R_ENET_0_A0	290	CONN	0	ENET-AVB - alias 0
SC_R_ENET_0_A1	291	CONN	0	ENET-AVB - alias 1
SC_R_ENET_0_A2	366	CONN	0	ENET-AVB - alias 2
SC_R_ENET_1	252	CONN	0	EQOS-TSN
SC_R_ENET_1_A0	367	CONN	0	ENET-TSN - alias 0
SC_R_ENET_1_A1	368	CONN	0	ENET-TSN - alias 1
SC_R_ENET_1_A2	369	CONN	0	ENET-TSN - alias 2
SC_R_ENET_1_A3	370	CONN	0	ENET-TSN - alias 3
SC_R_ENET_1_A4	371	CONN	0	ENET-TSN - alias 4
SC_R_FSPI_0	237	LSIO	0	Flexible Serial Peripheral Interface (FSPI) 0
SC_R_FSPI_1	238	LSIO	0	FSPI 1
SC_R_FTM_0	103	ADMA	0	FTM 0
SC_R_FTM_1	104	ADMA	0	FTM 1
SC_R_GIC	18	ADMA	0	GIC
SC_R_GPIO_0	199	LSIO	0	General Purpose I/O (GPIO) 0
SC_R_GPIO_1	200	LSIO	0	GPIO 1
SC_R_GPIO_2	201	LSIO	0	GPIO 2
SC_R_GPIO_3	202	LSIO	0	GPIO 3
SC_R_GPIO_4	203	LSIO	0	GPIO 4
SC_R_GPIO_5	204	LSIO	0	GPIO 5
SC_R_GPIO_6	205	LSIO	0	GPIO 6
SC_R_GPIO_7	206	LSIO	0	GPIO 7
SC_R_GPT_0	207	LSIO	0	General Purpose Timer (GPT) 0
SC_R_GPT_1	208	LSIO	0	GPT 1
SC_R_GPT_2	209	LSIO	0	GPT 2
SC_R_GPT_3	210	LSIO	0	GPT 3
SC_R_GPT_4	211	LSIO	0	GPT 4
SC_R_GPT_5	421	ADMA	0	GPT 0
SC_R_GPT_6	422	ADMA	0	GPT 1
SC_R_GPT_7	423	ADMA	0	GPT 2
SC_R_GPT_8	424	ADMA	0	GPT 3
SC_R_HSIO_GPIO	172	HSIO	0	GPIO/MISC
SC_R_I2C_0	96	ADMA	0	I2C 0
SC_R_I2C_1	97	ADMA	0	I2C 1
SC_R_I2C_2	98	ADMA	0	I2C 2
SC_R_I2C_3	99	ADMA	0	12C 3
SC_R_IEE	239	LSIO	0	Inline Encryption Engine (IEE)
SC_R_IEE_R0	240	LSIO	0	IEE region 0
SC_R_IEE_R1	241	LSIO	0	IEE region 1
SC_R_IEE_R2	242	LSIO	0	IEE region 2
SC_R_IEE_R3	243	LSIO	0	IEE region 3
SC_R_IEE_R4	244	LSIO	0	IEE region 4

Resource	Index	Subsystem	Instance	Description
SC_R_IEE_R5	245	LSIO	0	IEE region 5
SC_R_IEE_R6	246	LSIO	0	IEE region 6
SC R IEE R7	247	LSIO	0	IEE region 7
SC R IRQSTR M4 0	15	ADMA	0	IRQSTR M4 0
SC R IRQSTR M4 1	16	ADMA	0	IRQSTR M4 1 (optional)
SC R IRQSTR SCU2	321	ADMA	0	IRQSTR SCU2/WAKE
SC R KPP	212	LSIO	0	Keypad Port (KPP)
SC_R_LCD_0	187	ADMA	0	eLCDIF 0
SC R LCD 0 PWM 0	188	ADMA	0	PWM 0
SC R M4 0 I2C	288	M4	0	I2C
SC R M4 0 INTMUX	289	M4	0	INTMUX
SC R M4 0 MU 0A0	293	M4	0	MU 0A0
SC_R_M4_0_MU_0A1	294	M4	0	MU 0A1
SC R M4 0 MU 0A2	295	M4	0	MU 0A2
SC R M4 0 MU 0A3	296	M4	0	MU 0A3
SC R M4 0 MU 0B	292	M4	0	MU 0B
SC R M4 0 MU 1A	297	M4	0	MU 1A
SC R M4 0 PID0	278	M4	0	PID0
SC R M4 0 PID1	279	M4	0	PID1
SC R M4 0 PID2	280	M4	0	PID2
SC R M4 0 PID3	281	M4	0	PID3
SC_R_M4_0_PID4	282	M4	0	PID4
SC R M4 0 PIT	286	M4	0	PIT
SC R M4 0 RGPIO	283	M4	0	RGPIO
SC_R_M4_0_SEMA42	284	M4	0	SEMA42
SC_R_M4_0_TPM	285	M4	0	TPM
SC_R_M4_0_UART	287	M4	0	UART
SC_R_MATCH_0	154	HSIO	0	Match 0
SC_R_MATCH_1	155	HSIO	0	Match 1
SC_R_MATCH_10	164	HSIO	0	Match 10
SC_R_MATCH_11	165	HSIO	0	Match 11
SC_R_MATCH_12	166	HSIO	0	Match 12
SC_R_MATCH_13	167	HSIO	0	Match 13
SC_R_MATCH_14	168	HSIO	0	Match 14
SC_R_MATCH_15	173	HSIO	0	Match 15
SC_R_MATCH_16	174	HSIO	0	Match 16
SC_R_MATCH_17	175	HSIO	0	Match 17
SC_R_MATCH_18	176	HSIO	0	Match 18
SC_R_MATCH_19	177	HSIO	0	Match 19
SC_R_MATCH_2	156	HSIO	0	Match 2
SC_R_MATCH_20	178	HSIO	0	Match 20
SC_R_MATCH_21	179	HSIO	0	Match 21
SC_R_MATCH_22	180	HSIO	0	Match 22
SC_R_MATCH_23	181	HSIO	0	Match 23
SC_R_MATCH_24	182	HSIO	0	Match 24
SC_R_MATCH_25	183	HSIO	0	Match 25
SC_R_MATCH_26	184	HSIO	0	Match 26

Resource	Index	Subsystem	Instance	Description
SC_R_MATCH_27	185	HSIO	0	Match 27
SC_R_MATCH_28	186	HSIO	0	Match 28
SC_R_MATCH_3	157	HSIO	0	Match 3
SC_R_MATCH_4	158	HSIO	0	Match 4
SC_R_MATCH_5	159	HSIO	0	Match 5
SC_R_MATCH_6	160	HSIO	0	Match 6
SC_R_MATCH_7	161	HSIO	0	Match 7
SC_R_MATCH_8	162	HSIO	0	Match 8
SC_R_MATCH_9	163	HSIO	0	Match 9
SC_R_MCLK_OUT_0	495	ADMA	0	MCLK out 0
SC_R_MCLK_OUT_1	496	ADMA	0	MCLK out 1
SC_R_MQS_0	459	ADMA	0	MQS
SC_R_MU_0A	213	LSIO	0	Message Unit (MU) 0A
SC_R_MU_10A	223	LSIO	0	MU 10A
SC_R_MU_10B	232	LSIO	0	MU 10B
SC_R_MU_11A	224	LSIO	0	MU 11A
SC_R_MU_11B	233	LSIO	0	MU 11B
SC_R_MU_12A	225	LSIO	0	MU 12A
SC_R_MU_12B	234	LSIO	0	MU 12B
SC_R_MU_13A	226	LSIO	0	MU 13A
SC_R_MU_13B	235	LSIO	0	MU 13B
SC_R_MU_1A	214	LSIO	0	MU 1A
SC_R_MU_2A	215	LSIO	0	MU 2A
SC_R_MU_3A	216	LSIO	0	MU 3A
SC_R_MU_4A	217	LSIO	0	MU 4A
SC_R_MU_5A	218	LSIO	0	MU 5A
SC_R_MU_5B	227	LSIO	0	MU 5B
SC_R_MU_6A	219	LSIO	0	MU 6A
SC_R_MU_6B	228	LSIO	0	MU 6B
SC_R_MU_7A	220	LSIO	0	MU 7A
SC_R_MU_7B	229	LSIO	0	MU 7B
SC_R_MU_8A	221	LSIO	0	MU 8A
SC_R_MU_8B	230	LSIO	0	MU 8B
SC_R_MU_9A	222	LSIO	0	MU 9A
SC_R_MU_9B	231	LSIO	0	MU 9B
SC_R_NAND	265	CONN	0	NAND BCH/GPMI/DMA
SC_R_OCRAM	324	LSIO	0	OCRAM
SC_R_OTP	357	SC	0	OTP
SC_R_PCIE_B	169	HSIO	0	PCIE B
SC_R_PERF	23	DB	0	
SC_R_PMIC_0	497	BOARD	0	PMIC 0
SC_R_PMIC_1	498	BOARD	0	PMIC 1
SC_R_PMIC_2	521	BOARD	0	PMIC 2
SC_R_PWM_0	191	LSIO	0	Pulse Width Modulator (PWM) 0
SC_R_PWM_1	192	LSIO	0	PWM 1
SC_R_PWM_2	193	LSIO	0	PWM 2
SC_R_PWM_3	194	LSIO	0	PWM 3

Resource	Index	Subsystem	Instance	Description
SC_R_PWM_4	195	LSIO	0	PWM 4
SC_R_PWM_5	196	LSIO	0	PWM 5
SC_R_PWM_6	197	LSIO	0	PWM 6
SC_R_PWM_7	198	LSIO	0	PWM 7
SC R SAI 0	318	ADMA	0	SAI 0
SC_R_SAI_1	319	ADMA	0	SAI 1
SC_R_SAI_2	320	ADMA	0	SAI 2
SC_R_SAI_3	418	ADMA	0	SAI 3
SC_R_SC_I2C	345	SC	0	I2C
SC R SC MU 0A0	347	SC	0	MU 0A0
SC R SC MU 0A1	348	SC	0	MU 0A1
SC R SC MU 0A2	349	SC	0	MU 0A2
SC R SC MU 0A3	350	SC	0	MU 0A3
SC_R_SC_MU_0B	346	SC	0	MU 0B
SC R SC MU 1A	351	SC	0	MU 1A
SC_R_SC_PID0	336	SC	0	PID0
SC_R_SC_PID1	337	SC	0	PID1
SC_R_SC_PID2	338	SC	0	PID2
SC R SC PID3	339	SC	0	PID3
SC R SC PID4	340	SC	0	PID4
SC R SC PIT	343	SC	0	PIT
SC R SC SEMA42	341	SC	0	SEMA42
SC_R_SC_TPM	342	SC	0	TPM
SC R SC UART	344	SC	0	UART
SC_R_SDHC_0	248	CONN	0	uSDHC 1
SC_R_SDHC_1	249	CONN	0	uSDHC 2
SC_R_SDHC_2	250	CONN	0	uSDHC 3
SC R SECO	499	SC	0	SECO
SC R SECO MU 2	503	SC	0	SECO MU 2
SC_R_SECO_MU_3	504	SC	0	SECO MU 3
SC R SECO MU 4	505	SC	0	SECO MU 4
SC_R_SECVIO	44	SC	0	Security Violation
SC_R_SERDES_1	171	HSIO	0	PHYx1
SC_R_SPDIF_0	416	ADMA	0	SPDIF 0
SC_R_SPI_0	53	ADMA	0	SPI 0
SC R SPI 1	54	ADMA	0	SPI 1
SC_R_SPI_2	55	ADMA	0	SPI 2
SC_R_SPI_3	56	ADMA	0	SPI 3
SC_R_SYSCNT_CMP	353	SC	0	SYSCNT CMP
SC_R_SYSCNT_RD	352	SC	0	SYSCNT RD
SC_R_SYSTEM	355	SC	0	System
SC_R_UART_0	57	ADMA	0	UART 0
SC_R_UART_1	58	ADMA	0	UART 1
SC_R_UART_2	59	ADMA	0	UART 2
SC_R_UART_3	60	ADMA	0	UART 3
SC R USB 0	259	CONN	0	USB2.0 OTG1
SC R USB 0 PHY	261	CONN	0	USB2.0 OTG1 phy
		J J		

Resource	Index	Subsystem	Instance	Description
SC_R_USB_1	260	CONN	0	USB2.0 OTG2
SC_R_USB_1_PHY	24	CONN	0	USB2.0 OTG2 phy
SC_R_V2X_MU_0	26	DB	0	APP0 MU
SC_R_V2X_MU_1	27	DB	0	APP1 MU
SC_R_V2X_MU_2	31	DB	0	SHE MU
SC_R_V2X_MU_3	40	DB	0	HSM1 MU
SC_R_V2X_MU_4	41	DB	0	HSM2 MU
SC_R_V2X_PID0	140	DB	0	V2X PID0
SC_R_V2X_PID1	141	DB	0	V2X PID1
SC_R_V2X_PID2	142	DB	0	V2X PID2
SC_R_V2X_PID3	143	DB	0	V2X PID3

Chapter 7

Clock List

The table below lists the clocks/PLLs available in the system (SoC specific). Resource and Clock are parameters to several PM API calls. Set=Y indicates the clock/PLL is not shared and the rate can be set via sc_pm_set_clock_rate(). Enable=Y indicates the clock is not auto gated and must be enabled via sc_pm_clock_enable().

See also

PM: Power Management Service

Resource	Clock	Default Rate	Set	Enable	Description
SC_R_A35	SC_PM_CLK_CPU	900MHZ	Υ		CPU
SC_R_ADC_0	SC_PM_CLK_PER		Υ	Υ	ADC 0 peripheral
SC_R_AUDIO_PLL_0	SC_PM_CLK_MISC		Υ	Υ	User programmable PLL
SC_R_AUDIO_PLL_0	SC_PM_CLK_MST_BUS		Υ	Υ	Audio rec 0
SC_R_AUDIO_PLL_0	SC_PM_CLK_SLV_BUS		Υ	Υ	Audio PLL div 0
SC_R_AUDIO_PLL_1	SC_PM_CLK_MISC		Υ	Υ	User programmable PLL
SC_R_AUDIO_PLL_1	SC_PM_CLK_MST_BUS		Υ	Υ	Audio rec 1
SC_R_AUDIO_PLL_1	SC_PM_CLK_SLV_BUS		Υ	Υ	Audio PLL div 1
SC_R_CAN_0	SC_PM_CLK_PER		Υ	Υ	CAN peripheral
SC_R_DRC_0	SC_PM_CLK_SLV_BUS	465MHZ	Υ		DRC root
SC_R_ELCDIF_PLL	SC_PM_CLK_MISC		Υ	Υ	eLCDIF PLL
SC_R_ENET_0	SC_PM_CLK_BYPASS	24MHZ	Υ	Υ	ENET 0 bypass
SC_R_ENET_0	SC_PM_CLK_PER	24MHZ	Υ	Υ	ENET 0 RX
SC_R_ENET_1	SC_PM_CLK_BYPASS	24MHZ	Υ	Υ	ENET 1 bypass
SC_R_ENET_1	SC_PM_CLK_PER	125MHZ	Υ	Υ	ENET 1 QoS
SC_R_FSPI_0	SC_PM_CLK_PER		Υ	Υ	FSPI 0 baud
SC_R_FSPI_1	SC_PM_CLK_PER		Υ	Υ	FSPI 1 baud
SC_R_FTM_0	SC_PM_CLK_PER		Υ	Υ	FTM 0 peripheral
SC_R_FTM_1	SC_PM_CLK_PER		Υ	Υ	FTM 1 peripheral
SC_R_GPT_0	SC_PM_CLK_PER		Υ	Υ	GPT 0 peripheral
SC_R_GPT_1	SC_PM_CLK_PER		Υ	Υ	GPT 1 peripheral
SC_R_GPT_2	SC_PM_CLK_PER		Υ	Υ	GPT 2 peripheral
SC_R_GPT_3	SC_PM_CLK_PER		Υ	Υ	GPT 3 peripheral

32 Clock List

SC_R_GPT_4	Resource	Clock	Default Rate	Set	Enable	Description
SC_RIZC_1 SC_PM_CLK_PER Y Y Y IZC 1 baud SC_RIZC_2 SC_PM_CLK_PER Y Y Y IZC 2 baud SC_RIZC_3 SC_PM_CLK_PER Y Y Y IZC 3 baud SC_RLCD_0 SC_PM_CLK_NISC 24MHZ Y Y Bypass SC_RLCD_0 SC_PM_CLK_SLV_BUS Y Y Y Plxel Link Mux SC_RLCD_0 SC_PM_CLK_PER Y Y PPWM0 baud PPWM0 baud SC_RLCD_0 SC_PM_CLK_PER Y Y PPWM0 baud PPWM0 baud SC_RLM_0_IZC SC_PM_CLK_PER Y Y Y PPWM0 baud SC_RLM_0_PIT SC_PM_CLK_PER Y Y LPIT peripheral SC_R.MA_0_PIT SC_PM_CLK_PER Y Y LPIT peripheral SC_R.MA_0_PIT SC_PM_CLK_PER Y Y LPIT peripheral SC_R.MA_0_PIT SC_PM_CLK_PER Y Y Y LPIT peripheral SC_R.MA_0_PIT SC_PM_CLK_PER Y	SC_R_GPT_4	SC_PM_CLK_PER		Υ	Υ	GPT 4 peripheral
SC. R. I2C.2 SC. PM. CLK. PER Y Y I2C.2 baud SC. R. I2C.3 SC. PM. CLK. PER Y Y I2C.3 baud SC. R. LCD.0 SC. PM. CLK. PER Y Y Bypass SC. R. LCD.0 SC. PM. CLK. SLV. BUS Y Y Pixel Link Mux SC. R. LCD.0 PWM	SC_R_I2C_0	SC_PM_CLK_PER		Υ	Υ	I2C 0 baud
SC R I2C 3 SC PM CLK PER Y Y I2C 3 baud SC R LCD 0 SC PM CLK MISC 24MHZ Y Y Bypass SC R LCD 0 SC PM CLK SLV BUS Y Y PLCDIF baud SC R LCD 0 SC PM CLK SLV BUS Y Y Pixel Link Mux SC R M4 0 I2C SC PM CLK PER Y Y PWM 0 baud SC R M4 0 I2C SC PM CLK PER Y Y I2C baud SC R M4 0 I2C SC PM CLK PER Y Y LPIT peripheral SC R M4 0 PID0 SC PM CLK PER Y Y LPIT peripheral SC R M4 0 IVANT SC PM CLK PER Y Y LPIT peripheral SC R M4 0 JUART SC PM CLK PER Y Y UART baud SC R NAND SC PM CLK MST BUS 500MHZ Y Y NAND GPMI SC R PERF SC PM CLK MSC 24MHZ N XTAL XTAL SC R PERF SC PM CLK MSC 24MHZ N XTAL SC R PERF SC PM CLK PER	SC_R_I2C_1	SC_PM_CLK_PER		Υ	Υ	I2C 1 baud
SC R LCD_0 SC_PM_CLK_MISC 24MHZ Y Y Bypass SC R_LCD_0 SC_PM_CLK_PER Y Y PLCDIF baud SC_R_LCD_0 SC_PM_CLK_SLV_BUS Y Y PWM 0 baud SC_R_LCD_0_PWM SC_PM_CLK_PER Y Y PWM 0 baud _0 SC_PM_CLK_PER Y Y Ize Inth Mux SC_R_M4_0_PID0 SC_PM_CLK_PER Y Y Ize Inth Peripheral SC_R_M4_0_PID0 SC_PM_CLK_PER Y Y Ize Inth Peripheral SC_R_M4_0_TPM SC_PM_CLK_PER Y Y UART baud SC_R_M4_0_TPM SC_PM_CLK_PER Y Y UART baud SC_R_NAND SC_PM_CLK_MST_BUS 500MHZ Y Y NAND BCH SC_R_NAND SC_PM_CLK_MST_BUS 24MHZ N XTAL XTAL SC_R_PERF SC_PM_CLK_MST_BUS 24MHZ N XTAL XTAL SC_R_PERF SC_PM_CLK_PER 24MHZ N XTAL XTAL SC_R_	SC_R_I2C_2	SC_PM_CLK_PER		Υ	Υ	I2C 2 baud
SC.R_LCD_0 SC.PM_CLK_PER Y Y Y Pixel Link Mux SC.R_LCD_0 SC.PM_CLK_SLV_BUS Y Y Pixel Link Mux SC.R_LCD_0_PWM→00 SC.PM_CLK_PER Y Y PWM 0 baud 0 SC.R_M4_0_IZC SC.PM_CLK_PER Y Y Y IZC baud SC.R_M4_0_PID SC.PM_CLK_PER Y Y LPIT peripheral SC.R_M4_0_PIT SC.PM_CLK_PER Y Y LPIT peripheral SC.R_M4_0_TPM SC.PM_CLK_PER Y Y LPIT peripheral SC.R_M4_0_UART SC.PM_CLK_PER Y Y LPIT peripheral SC.R_M4_0_UART SC.PM_CLK_MST_BUS 500MHZ Y Y LAND WAND GPM SC.R_M4_0_UART SC.PM_CLK_MST_BUS 500MHZ Y Y NAND GPM SC.R_NAND SC.PM_CLK_MST_BUS 24MHZ N XTAL SC.R_PERF SC.PM_CLK_MST_BUS 24MHZ N XTAL SC.R_PERF SC.PM_CLK_MST_BUS 24MHZ N	SC_R_I2C_3	SC_PM_CLK_PER		Υ	Υ	I2C 3 baud
SC_R_LOD_0 SC_PM_CLK_SLV_BUS Y Y Pixel Link Mux SC_R_LOD_0_PWM← 0_0 SC_PM_CLK_PER Y Y Y PWM 0 baud SC_R_M4_0_I2C SC_PM_CLK_PER Y Y Y I2C baud SC_R_M4_0_PID SC_PM_CLK_PER Y Y LPIT peripheral SC_R_M4_0_PIT SC_PM_CLK_PER Y Y LPIT peripheral SC_R_M4_0_PIT SC_PM_CLK_PER Y Y LPIT peripheral SC_R_M4_0_UART SC_PM_CLK_MST_BUS 500MHZ Y Y NAND SC_R_NAND SC_PM_CLK_MST_BUS 500MHZ Y Y NAND BCH SC_R_NAND SC_PM_CLK_MST_BUS 24MHZ N XTAL SC_R_PERF SC_PM_CLK_MST_BUS 24MHZ N XTAL SC_R_PERF SC_PM_CLK_MST_BUS 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PER 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PER Y Y PWM 1 peripheral SC_R_PERF	SC_R_LCD_0	SC_PM_CLK_MISC	24MHZ	Υ	Υ	Bypass
SC_R_LCD_0_PWM→ _0 SC_PM_CLK_PER Y Y PWM 0 baud SC_R_M4_0_I2C SC_PM_CLK_PER Y Y I2C baud SC_R_M4_0_PID0 SC_PM_CLK_PER Y Y LPIT peripheral SC_R_M4_0_TPM SC_PM_CLK_PER Y Y LPIT peripheral SC_R_M4_0_TPM SC_PM_CLK_PER Y Y UART baud SC_R_M4_0_TAM SC_PM_CLK_MST_BUS 500MHZ Y Y UART baud SC_R_NAND SC_PM_CLK_MST_BUS 500MHZ Y Y NAND GPMI SC_R_NAND SC_PM_CLK_MST_BUS 24MHZ N XTAL XTAL SC_R_PERF SC_PM_CLK_MST_BUS 24MHZ N XTAL XTAL SC_R_PERF SC_PM_CLK_PER 24MHZ N XTAL XTAL SC_R_PERF SC_PM_CLK_SLV_BUS 24MHZ N XTAL XTAL SC_R_PERF SC_PM_CLK_PER Y Y PWM 0 peripheral Y Y PWM 0 peripheral Y Y PWM 0 peripheral	SC_R_LCD_0	SC_PM_CLK_PER		Υ	Υ	eLCDIF baud
_O SC_R_M4_0_I2C SC_PM_CLK_PER Y Y I2C baud SC_R_M4_0_PID0 SC_PM_CLK_CPU 264MHZ Y System SC_R_M4_0_PID1 SC_PM_CLK_PER Y Y LPIT peripheral SC_R_M4_0_TPM SC_PM_CLK_PER Y Y TPM peripheral SC_R_M4_0_UART SC_PM_CLK_PER Y Y UART baud SC_R_M4_0_UART SC_PM_CLK_MST_BUS 500MHZ Y Y NAND GPMI SC_R_NAND SC_PM_CLK_MIST_BUS 500MHZ Y Y NAND BCH SC_R_NAND SC_PM_CLK_MISC 24MHZ N XTAL SC_R_PERF SC_PM_CLK_MISC 24MHZ N XTAL SC_R_PERF SC_PM_CLK_MST_BUS 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PER 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PER 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PER Y Y PWM 0 peripheral SC_R_PERF SC_PM_CLK_PER	SC_R_LCD_0	SC_PM_CLK_SLV_BUS		Υ	Υ	Pixel Link Mux
SC_R_M4_0_I2C SC_PM_CLK_PER Y Y I2C baud SC_R_M4_0_PID0 SC_PM_CLK_CPU 264MHZ Y System SC_R_M4_0_PIT SC_PM_CLK_PER Y Y Y LPIT peripheral SC_R_M4_0_UART SC_PM_CLK_PER Y Y Y PPM peripheral SC_R_NAND SC_PM_CLK_MST_BUS 500MHZ Y Y NAND GPMI SC_R_NAND SC_PM_CLK_MST_BUS 500MHZ Y Y NAND GPMI SC_R_PERF SC_PM_CLK_MST_BUS 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PER Y Y PWM 0 peripheral SC_R_PERF SC_PM_CLK_PER Y Y PWM 0 peripheral SC_R_PWM_1 SC_PM_CLK_PE	SC_R_LCD_0_PWM↔	SC_PM_CLK_PER		Υ	Υ	PWM 0 baud
SC_R_M4_0_PID0 SC_PM_CLK_CPU 264MHZ Y System SC_R_M4_0_PIT SC_PM_CLK_PER Y Y LPIT peripheral SC_R_M4_0_TPM SC_PM_CLK_PER Y Y TPM peripheral SC_R_M4_0_UART SC_PM_CLK_MET_BUS 500MHZ Y Y UART baud SC_R_NAND SC_PM_CLK_MET_BUS 500MHZ Y Y NAND GPMI SC_R_NAND SC_PM_CLK_MET_BUS 500MHZ Y Y NAND BCH SC_R_NAND SC_PM_CLK_MET_BUS 24MHZ N XTAL SC_R_PERF SC_PM_CLK_MET_BUS 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PER 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PER 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PER Y Y PWM 0 peripheral SC_R_PERF SC_PM_CLK_PER Y Y PWM 0 peripheral SC_R_PERF SC_PM_CLK_PER Y Y PWM 0 peripheral SC_R_PWM_1 SC_PM_CLK_	<u> </u>					
SC_R_M4_0_PIT SC_PM_CLK_PER Y Y LPIT peripheral SC_R_M4_0_TPM SC_PM_CLK_PER Y Y TPM peripheral SC_R_M4_0_UART SC_PM_CLK_PER Y Y UART baud SC_R_NAND SC_PM_CLK_MST_BUS 500MHZ Y Y NAND GPMI SC_R_NAND SC_PM_CLK_MISC 24MHZ N XTAL SC_R_PERF SC_PM_CLK_MISC 24MHZ N XTAL SC_R_PERF SC_PM_CLK_MST_BUS 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PER 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PER 24MHZ N XTAL SC_R_PERF SC_PM_CLK_SLV_BUS 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PER 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PER Y Y PWM 0 peripheral SC_R_PERF SC_PM_CLK_PER Y Y PWM 1 peripheral SC_R_PWM_1 SC_PM_CLK_PER Y Y PWM 2 perip					Υ	
SC_R_M4_0_TPM SC_PM_CLK_PER Y Y TPM peripheral SC_R_M4_0_UART SC_PM_CLK_PER Y Y UART baud SC_R_NAND SC_PM_CLK_MST_BUS 500MHZ Y Y NAND GPMI SC_R_NAND SC_PM_CLK_PER 400MHZ Y Y NAND BCH SC_R_PERF SC_PM_CLK_MISC 24MHZ N XTAL SC_R_PERF SC_PM_CLK_MISC 24MHZ N XTAL SC_R_PERF SC_PM_CLK_MISC 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PER 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PER 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PER Y Y PWM 0 peripheral SC_R_PERF SC_PM_CLK_PER Y Y PWM 1 peripheral SC_R_PWM_0 SC_PM_CLK_PER Y Y PWM 2 peripheral SC_R_PWM_1 SC_PM_CLK_PER Y Y PWM 2 peripheral SC_R_PWM_3 SC_PM_CLK_PER Y Y			264MHZ			•
SC_R_M4_0_UART SC_PM_CLK_PER Y Y UART baud SC_R_NAND SC_PM_CLK_MST_BUS 500MHZ Y Y NAND GPMI SC_R_NAND SC_PM_CLK_MSC 24MHZ N XTAL SC_R_PERF SC_PM_CLK_MST_BUS 24MHZ N XTAL SC_R_PERF SC_PM_CLK_MST_BUS 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PER Y Y PWM 0 peripheral SC_R_PERF SC_PM_CLK_PER Y Y PWM 1 peripheral SC_R_PWM_1 SC_PM_CLK_PER Y Y PWM 2 peripheral SC_R_PWM_3 SC_PM_CLK_PER Y Y PWM 5 peripheral SC_R_PWM_5 SC_PM_CLK_PER Y Y PWM 5 peripheral	SC_R_M4_0_PIT	SC_PM_CLK_PER			Υ	LPIT peripheral
SC_R_NAND SC_PM_CLK_MST_BUS 500MHZ Y Y NAND GPMI SC_R_NAND SC_PM_CLK_PER 400MHZ Y Y NAND BCH SC_R_PERF SC_PM_CLK_MISC 24MHZ N XTAL SC_R_PERF SC_PM_CLK_MST_BUS 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PER 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PHY 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PHY 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PER 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PER Y Y PWM 0 peripheral SC_R_PWM_0 SC_PM_CLK_PER Y Y PWM 1 peripheral SC_R_PWM_1 SC_PM_CLK_PER Y Y PWM 2 peripheral SC_R_PWM_3 SC_PM_CLK_PER Y Y PWM 5 peripheral SC_R_PWM_5 SC_PM_CLK_PER Y Y PWM 5 peripheral SC_R_PWM_6 SC_PM_CLK_PER Y Y	SC_R_M4_0_TPM	SC_PM_CLK_PER		Υ	Υ	TPM peripheral
SC_R_NAND SC_PM_CLK_PER 400MHZ Y Y NAND BCH SC_R_PERF SC_PM_CLK_MISC 24MHZ N XTAL SC_R_PERF SC_PM_CLK_MST_BUS 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PER Y Y PWW0 peripheral SC_R_PERF SC_PM_CLK_PER Y Y PWW0 peripheral SC_R_PWM_1 SC_PM_CLK_PER Y Y PWM peripheral SC_R_PWM_2 SC_PM_CLK_PER Y Y PWM peripheral SC_R_PWM_3 SC_PM_CLK_PER Y Y PWM peripheral SC_R_PWM_6 SC_PM_CLK_PER Y Y PWM peripheral SC_R_SC_IZC SC_PM_CLK_PER 24MHZ Y Y <t< td=""><td>SC_R_M4_0_UART</td><td>SC_PM_CLK_PER</td><td></td><td></td><td></td><td>UART baud</td></t<>	SC_R_M4_0_UART	SC_PM_CLK_PER				UART baud
SC_R_PERF SC_PM_CLK_MISC 24MHZ N XTAL SC_R_PERF SC_PM_CLK_MST_BUS 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PER 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PHY 24MHZ N XTAL SC_R_PERF SC_PM_CLK_SLV_BUS 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PER Y Y PWM 0 peripheral SC_R_PWM_0 SC_PM_CLK_PER Y Y PWM 1 peripheral SC_R_PWM_1 SC_PM_CLK_PER Y Y PWM 2 peripheral SC_R_PWM_2 SC_PM_CLK_PER Y Y PWM 3 peripheral SC_R_PWM_3 SC_PM_CLK_PER Y Y PWM 3 peripheral SC_R_PWM_4 SC_PM_CLK_PER Y Y PWM 5 peripheral SC_R_PWM_5 SC_PM_CLK_PER Y Y PWM 6 peripheral SC_R_PWM_7 SC_PM_CLK_PER Y Y PWM 7 peripheral SC_R_SC_IZC SC_PM_CLK_PER 24MHZ Y Y	SC_R_NAND	SC_PM_CLK_MST_BUS	500MHZ	Υ	Υ	NAND GPMI
SC_R_PERF SC_PM_CLK_MST_BUS 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PER 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PHY 24MHZ N XTAL SC_R_PERF SC_PM_CLK_SLV_BUS 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PER Y Y PWM 0 peripheral SC_R_PWM_0 SC_PM_CLK_PER Y Y PWM 1 peripheral SC_R_PWM_1 SC_PM_CLK_PER Y Y PWM 2 peripheral SC_R_PWM_2 SC_PM_CLK_PER Y Y PWM 3 peripheral SC_R_PWM_3 SC_PM_CLK_PER Y Y PWM 4 peripheral SC_R_PWM_4 SC_PM_CLK_PER Y Y PWM 5 peripheral SC_R_PWM_5 SC_PM_CLK_PER Y Y PWM 6 peripheral SC_R_PWM_7 SC_PM_CLK_PER Y Y PWM 7 peripheral SC_R_SC_IZC SC_PM_CLK_PER 24MHZ Y Y PWM 7 peripheral SC_R_SC_IZC SC_PM_CLK_PER 8MHZ	SC_R_NAND	SC_PM_CLK_PER	400MHZ	Υ	Υ	NAND BCH
SC_R_PERF SC_PM_CLK_PER 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PHY 24MHZ N XTAL SC_R_PERF SC_PM_CLK_SLV_BUS 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PER Y Y PWM 0 peripheral SC_R_PWM_0 SC_PM_CLK_PER Y Y PWM 1 peripheral SC_R_PWM_1 SC_PM_CLK_PER Y Y PWM 1 peripheral SC_R_PWM_2 SC_PM_CLK_PER Y Y PWM 3 peripheral SC_R_PWM_3 SC_PM_CLK_PER Y Y PWM 4 peripheral SC_R_PWM_4 SC_PM_CLK_PER Y Y PWM 5 peripheral SC_R_PWM_5 SC_PM_CLK_PER Y Y PWM 6 peripheral SC_R_PWM_7 SC_PM_CLK_PER Y Y PWM 6 peripheral SC_R_SC_IZC SC_PM_CLK_PER Y Y PWM 7 peripheral SC_R_SC_IZC SC_PM_CLK_PER 24MHZ Y Y PWM 6 peripheral SC_R_SC_IZC SC_PM_CLK_PER 24MHZ	SC_R_PERF	SC_PM_CLK_MISC	24MHZ	N		XTAL
SC_R_PERF SC_PM_CLK_PHY 24MHZ N XTAL SC_R_PERF SC_PM_CLK_SLV_BUS 24MHZ N XTAL SC_R_PERF SC_PM_CLK_PER Y Y PWM 0 peripheral SC_R_PWM_0 SC_PM_CLK_PER Y Y PWM 0 peripheral SC_R_PWM_1 SC_PM_CLK_PER Y Y PWM 1 peripheral SC_R_PWM_2 SC_PM_CLK_PER Y Y PWM 2 peripheral SC_R_PWM_3 SC_PM_CLK_PER Y Y PWM 3 peripheral SC_R_PWM_4 SC_PM_CLK_PER Y Y PWM 5 peripheral SC_R_PWM_5 SC_PM_CLK_PER Y Y PWM 6 peripheral SC_R_PWM_7 SC_PM_CLK_PER Y Y PWM 7 peripheral SC_R_SC_IZC SC_PM_CLK_PER 24MHZ Y Y PWM 7 peripheral SC_R_SC_PIDO SC_PM_CLK_PER 24MHZ Y Y PWM 7 peripheral SC_R_SC_PIDO SC_PM_CLK_PER 396HZ Y Y TPM peripheral SC_R_SC_UART <td>SC_R_PERF</td> <td></td> <td>24MHZ</td> <td>N</td> <td></td> <td>XTAL</td>	SC_R_PERF		24MHZ	N		XTAL
SC_RPERF SC_PM_CLK_SLV_BUS 24MHZ N XTAL SC_RPWM_0 SC_PM_CLK_PER Y Y PWM 0 peripheral SC_RPWM_1 SC_PM_CLK_PER Y Y PWM 1 peripheral SC_RPWM_2 SC_PM_CLK_PER Y Y PWM 2 peripheral SC_RPWM_3 SC_PM_CLK_PER Y Y PWM 3 peripheral SC_RPWM_4 SC_PM_CLK_PER Y Y PWM 4 peripheral SC_RPWM_5 SC_PM_CLK_PER Y Y PWM 5 peripheral SC_RPWM_6 SC_PM_CLK_PER Y Y PWM 6 peripheral SC_RSC_I2C SC_PM_CLK_PER Y Y PWM 7 peripheral SC_RSC_I2C SC_PM_CLK_PER 24MHZ Y I2C baud SC_RSC_IDD SC_PM_CLK_PER 3MHZ Y LPIT peripheral SC_RSC_ITPM SC_PM_CLK_PER 3MHZ Y TPM peripheral SC_RSC_UART SC_PM_CLK_PER 396MHZ Y Y UART baud SC_RSDHC_0 SC_PM_CLK_PER 396MHZ <td>SC_R_PERF</td> <td>SC_PM_CLK_PER</td> <td>24MHZ</td> <td>N</td> <td></td> <td>XTAL</td>	SC_R_PERF	SC_PM_CLK_PER	24MHZ	N		XTAL
SC_R_PWM_0 SC_PM_CLK_PER Y Y PWM 0 peripheral SC_R_PWM_1 SC_PM_CLK_PER Y Y PWM 1 peripheral SC_R_PWM_2 SC_PM_CLK_PER Y Y PWM 2 peripheral SC_R_PWM_3 SC_PM_CLK_PER Y Y PWM 3 peripheral SC_R_PWM_4 SC_PM_CLK_PER Y Y PWM 4 peripheral SC_R_PWM_5 SC_PM_CLK_PER Y Y PWM 5 peripheral SC_R_PWM_6 SC_PM_CLK_PER Y Y PWM 6 peripheral SC_R_PWM_7 SC_PM_CLK_PER Y Y PWM 7 peripheral SC_R_SC_I2C SC_PM_CLK_PER 24MHZ Y I2C baud SC_R_SC_PID SC_PM_CLK_PER 3MHZ Y LPIT peripheral SC_R_SC_PIT SC_PM_CLK_PER 396MHZ Y Y TPM peripheral SC_R_SC_UART SC_PM_CLK_PER 396MHZ Y Y UART baud SC_R_SDHC_0 SC_PM_CLK_PER 396MHZ Y Y uSDHC 0 peripheral SC_R	SC_R_PERF	SC_PM_CLK_PHY	24MHZ	N		XTAL
SC_R_PWM_1 SC_PM_CLK_PER Y Y PWM 1 peripheral SC_R_PWM_2 SC_PM_CLK_PER Y Y PWM 2 peripheral SC_R_PWM_3 SC_PM_CLK_PER Y Y PWM 3 peripheral SC_R_PWM_4 SC_PM_CLK_PER Y Y PWM 4 peripheral SC_R_PWM_5 SC_PM_CLK_PER Y Y PWM 5 peripheral SC_R_PWM_6 SC_PM_CLK_PER Y Y PWM 6 peripheral SC_R_PWM_7 SC_PM_CLK_PER Y Y PWM 7 peripheral SC_R_SC_I2C SC_PM_CLK_PER 24MHZ Y I2C baud SC_R_SC_PIDO SC_PM_CLK_CPU 264MHZ N System SC_R_SC_PIT SC_PM_CLK_PER 8MHZ Y LPIT peripheral SC_R_SC_UART SC_PM_CLK_PER Y Y TPM peripheral SC_R_SC_UART SC_PM_CLK_PER 396MHZ Y Y UART baud SC_R_SDHC_1 SC_PM_CLK_PER 396MHZ Y Y USDHC 1 peripheral SC_R_SDHC_2 S	SC_R_PERF	SC_PM_CLK_SLV_BUS	24MHZ			XTAL
SC_R_PWM_2 SC_PM_CLK_PER Y Y PWM 2 peripheral SC_R_PWM_3 SC_PM_CLK_PER Y Y PWM 3 peripheral SC_R_PWM_4 SC_PM_CLK_PER Y Y PWM 4 peripheral SC_R_PWM_5 SC_PM_CLK_PER Y Y PWM 5 peripheral SC_R_PWM_6 SC_PM_CLK_PER Y Y PWM 6 peripheral SC_R_PWM_7 SC_PM_CLK_PER 24MHZ Y PWM 7 peripheral SC_R_SC_I2C SC_PM_CLK_PER 24MHZ Y I2C baud SC_R_SC_PID0 SC_PM_CLK_CPU 264MHZ N System SC_R_SC_PIT SC_PM_CLK_PER 8MHZ Y LPIT peripheral SC_R_SC_PIT SC_PM_CLK_PER 38MHZ Y UART baud SC_R_SC_TPM SC_PM_CLK_PER Y Y UART baud SC_R_SC_UART SC_PM_CLK_PER 396MHZ Y Y USDHC 0 peripheral SC_R_SDHC_0 SC_PM_CLK_PER 396MHZ Y Y USDHC 1 peripheral SC_R_SDHC_2	SC_R_PWM_0	SC_PM_CLK_PER				PWM 0 peripheral
SC_R_PWM_3 SC_PM_CLK_PER Y Y PWM 3 peripheral SC_R_PWM_4 SC_PM_CLK_PER Y Y PWM 4 peripheral SC_R_PWM_5 SC_PM_CLK_PER Y Y PWM 5 peripheral SC_R_PWM_6 SC_PM_CLK_PER Y Y PWM 6 peripheral SC_R_PWM_7 SC_PM_CLK_PER Y Y PWM 7 peripheral SC_R_SC_I2C SC_PM_CLK_PER 24MHZ Y I2C baud SC_R_SC_PID0 SC_PM_CLK_CPU 264MHZ N System SC_R_SC_PIT SC_PM_CLK_PER 8MHZ Y LPIT peripheral SC_R_SC_TPM SC_PM_CLK_PER 8MHZ Y TPM peripheral SC_R_SC_UART SC_PM_CLK_PER 24MHZ Y UART baud SC_R_SDHC_0 SC_PM_CLK_PER 396MHZ Y Y uSDHC 0 peripheral SC_R_SDHC_1 SC_PM_CLK_PER 396MHZ Y Y uSDHC 1 peripheral SC_R_SPI_0 SC_PM_CLK_PER 396MHZ Y Y uSDHC 1 peripheral	SC_R_PWM_1	SC_PM_CLK_PER		Υ	Υ	PWM 1 peripheral
SC_R_PWM_4 SC_PM_CLK_PER Y Y PWM 4 peripheral SC_R_PWM_5 SC_PM_CLK_PER Y Y PWM 5 peripheral SC_R_PWM_6 SC_PM_CLK_PER Y Y PWM 6 peripheral SC_R_PWM_7 SC_PM_CLK_PER Y Y PWM 7 peripheral SC_R_SC_I2C SC_PM_CLK_PER 24MHZ Y I2C baud SC_R_SC_PID0 SC_PM_CLK_CPU 264MHZ N System SC_R_SC_PIT SC_PM_CLK_PER 8MHZ Y LPIT peripheral SC_R_SC_TPM SC_PM_CLK_PER 8MHZ Y TPM peripheral SC_R_SC_UART SC_PM_CLK_PER 24MHZ Y UART baud SC_R_SDHC_0 SC_PM_CLK_PER 396MHZ Y Y uSDHC 0 peripheral SC_R_SDHC_1 SC_PM_CLK_PER 396MHZ Y Y uSDHC 1 peripheral SC_R_SDHC_2 SC_PM_CLK_PER 396MHZ Y Y uSDHC 2 peripheral SC_R_SPI_0 SC_PM_CLK_PER Y Y SPI 0 baud	SC_R_PWM_2	SC_PM_CLK_PER		Υ	Υ	PWM 2 peripheral
SC_R_PWM_5SC_PM_CLK_PERYYPWM 5 peripheralSC_R_PWM_6SC_PM_CLK_PERYYPWM 6 peripheralSC_R_PWM_7SC_PM_CLK_PERYYPWM 7 peripheralSC_R_SC_I2CSC_PM_CLK_PER24MHZYI2C baudSC_R_SC_PID0SC_PM_CLK_CPU264MHZNSystemSC_R_SC_PITSC_PM_CLK_PER8MHZYLPIT peripheralSC_R_SC_TPMSC_PM_CLK_PERYYTPM peripheralSC_R_SC_UARTSC_PM_CLK_PER24MHZYUART baudSC_R_SDHC_0SC_PM_CLK_PER396MHZYYuSDHC 0 peripheralSC_R_SDHC_1SC_PM_CLK_PER396MHZYYuSDHC 1 peripheralSC_R_SDHC_2SC_PM_CLK_PER396MHZYYuSDHC 2 peripheralSC_R_SPI_0SC_PM_CLK_PER396MHZYYSPI 0 baudSC_R_SPI_1SC_PM_CLK_PERYYSPI 1 baudSC_R_SPI_2SC_PM_CLK_PERYYSPI 2 baudSC_R_SPI_3SC_PM_CLK_PERYYSPI 3 baud	SC_R_PWM_3	SC_PM_CLK_PER		Υ	Υ	PWM 3 peripheral
SC_R_PWM_6 SC_PM_CLK_PER Y Y PWM 6 peripheral SC_R_PWM_7 SC_PM_CLK_PER Y Y PWM 7 peripheral SC_R_SC_I2C SC_PM_CLK_PER 24MHZ Y I2C baud SC_R_SC_PID0 SC_PM_CLK_CPU 264MHZ N System SC_R_SC_PIT SC_PM_CLK_PER 8MHZ Y LPIT peripheral SC_R_SC_TPM SC_PM_CLK_PER Y Y TPM peripheral SC_R_SC_UART SC_PM_CLK_PER 24MHZ Y UART baud SC_R_SDHC_0 SC_PM_CLK_PER 396MHZ Y Y uSDHC 0 peripheral SC_R_SDHC_1 SC_PM_CLK_PER 396MHZ Y Y uSDHC 1 peripheral SC_R_SDHC_2 SC_PM_CLK_PER 396MHZ Y Y uSDHC 2 peripheral SC_R_SPI_0 SC_PM_CLK_PER Y Y SPI 0 baud SC_R_SPI_1 SC_PM_CLK_PER Y Y SPI 2 baud SC_R_SPI_2 SC_PM_CLK_PER Y Y SPI 3 baud	SC_R_PWM_4	SC_PM_CLK_PER		Υ	Υ	PWM 4 peripheral
SC_R_PWM_7 SC_PM_CLK_PER Y Y PWM 7 peripheral SC_R_SC_I2C SC_PM_CLK_PER 24MHZ Y I2C baud SC_R_SC_PID0 SC_PM_CLK_CPU 264MHZ N System SC_R_SC_PIT SC_PM_CLK_PER 8MHZ Y LPIT peripheral SC_R_SC_PM SC_PM_CLK_PER Y Y TPM peripheral SC_R_SC_UART SC_PM_CLK_PER 24MHZ Y UART baud SC_R_SDHC_0 SC_PM_CLK_PER 396MHZ Y Y USDHC 0 peripheral SC_R_SDHC_1 SC_PM_CLK_PER 396MHZ Y Y uSDHC 1 peripheral SC_R_SDHC_2 SC_PM_CLK_PER 396MHZ Y Y uSDHC 2 peripheral SC_R_SPI_0 SC_PM_CLK_PER Y Y SPI 0 baud SC_R_SPI_1 SC_PM_CLK_PER Y Y SPI 2 baud SC_R_SPI_3 SC_PM_CLK_PER Y Y SPI 3 baud	SC_R_PWM_5	SC_PM_CLK_PER		Υ	Υ	PWM 5 peripheral
SC_R_SC_I2C SC_PM_CLK_PER 24MHZ Y I2C baud SC_R_SC_PID0 SC_PM_CLK_CPU 264MHZ N System SC_R_SC_PIT SC_PM_CLK_PER 8MHZ Y LPIT peripheral SC_R_SC_TPM SC_PM_CLK_PER Y Y TPM peripheral SC_R_SC_UART SC_PM_CLK_PER 24MHZ Y UART baud SC_R_SDHC_0 SC_PM_CLK_PER 396MHZ Y Y uSDHC 0 peripheral SC_R_SDHC_1 SC_PM_CLK_PER 396MHZ Y Y uSDHC 1 peripheral SC_R_SDHC_2 SC_PM_CLK_PER 396MHZ Y Y uSDHC 2 peripheral SC_R_SPI_0 SC_PM_CLK_PER Y Y SPI 0 baud SC_R_SPI_1 SC_PM_CLK_PER Y Y SPI 1 baud SC_R_SPI_2 SC_PM_CLK_PER Y Y SPI 2 baud SC_R_SPI_3 SC_PM_CLK_PER Y Y SPI 3 baud	SC_R_PWM_6	SC_PM_CLK_PER		Υ	Υ	PWM 6 peripheral
SC_R_SC_PID0SC_PM_CLK_CPU264MHZNSystemSC_R_SC_PITSC_PM_CLK_PER8MHZYLPIT peripheralSC_R_SC_TPMSC_PM_CLK_PERYYTPM peripheralSC_R_SC_UARTSC_PM_CLK_PER24MHZYUART baudSC_R_SDHC_0SC_PM_CLK_PER396MHZYYuSDHC 0 peripheralSC_R_SDHC_1SC_PM_CLK_PER396MHZYYuSDHC 1 peripheralSC_R_SDHC_2SC_PM_CLK_PER396MHZYYuSDHC 2 peripheralSC_R_SPI_0SC_PM_CLK_PERYYSPI 0 baudSC_R_SPI_1SC_PM_CLK_PERYYSPI 1 baudSC_R_SPI_2SC_PM_CLK_PERYYSPI 2 baudSC_R_SPI_3SC_PM_CLK_PERYYSPI 3 baud	SC_R_PWM_7	SC_PM_CLK_PER		Υ	Υ	PWM 7 peripheral
SC_R_SC_PITSC_PM_CLK_PER8MHZYLPIT peripheralSC_R_SC_TPMSC_PM_CLK_PERYYTPM peripheralSC_R_SC_UARTSC_PM_CLK_PER24MHZYUART baudSC_R_SDHC_0SC_PM_CLK_PER396MHZYYuSDHC 0 peripheralSC_R_SDHC_1SC_PM_CLK_PER396MHZYYuSDHC 1 peripheralSC_R_SDHC_2SC_PM_CLK_PER396MHZYYuSDHC 2 peripheralSC_R_SPI_0SC_PM_CLK_PERYYSPI 0 baudSC_R_SPI_1SC_PM_CLK_PERYYSPI 1 baudSC_R_SPI_2SC_PM_CLK_PERYYSPI 2 baudSC_R_SPI_3SC_PM_CLK_PERYYSPI 3 baud	SC_R_SC_I2C	SC_PM_CLK_PER	24MHZ	Υ		I2C baud
SC_R_SC_PITSC_PM_CLK_PER8MHZYLPIT peripheralSC_R_SC_TPMSC_PM_CLK_PERYYTPM peripheralSC_R_SC_UARTSC_PM_CLK_PER24MHZYUART baudSC_R_SDHC_0SC_PM_CLK_PER396MHZYYuSDHC 0 peripheralSC_R_SDHC_1SC_PM_CLK_PER396MHZYYuSDHC 1 peripheralSC_R_SDHC_2SC_PM_CLK_PER396MHZYYuSDHC 2 peripheralSC_R_SPI_0SC_PM_CLK_PERYYSPI 0 baudSC_R_SPI_1SC_PM_CLK_PERYYSPI 1 baudSC_R_SPI_2SC_PM_CLK_PERYYSPI 2 baudSC_R_SPI_3SC_PM_CLK_PERYYSPI 3 baud	SC_R_SC_PID0	SC_PM_CLK_CPU	264MHZ	N		System
SC_R_SC_TPMSC_PM_CLK_PERYYTPM peripheralSC_R_SC_UARTSC_PM_CLK_PER24MHZYUART baudSC_R_SDHC_0SC_PM_CLK_PER396MHZYYuSDHC 0 peripheralSC_R_SDHC_1SC_PM_CLK_PER396MHZYYuSDHC 1 peripheralSC_R_SDHC_2SC_PM_CLK_PER396MHZYYuSDHC 2 peripheralSC_R_SPI_0SC_PM_CLK_PERYYSPI 0 baudSC_R_SPI_1SC_PM_CLK_PERYYSPI 1 baudSC_R_SPI_2SC_PM_CLK_PERYYSPI 2 baudSC_R_SPI_3SC_PM_CLK_PERYYSPI 3 baud			8MHZ	Υ		
SC_R_SC_UARTSC_PM_CLK_PER24MHZYUART baudSC_R_SDHC_0SC_PM_CLK_PER396MHZYYuSDHC 0 peripheralSC_R_SDHC_1SC_PM_CLK_PER396MHZYYuSDHC 1 peripheralSC_R_SDHC_2SC_PM_CLK_PER396MHZYYuSDHC 2 peripheralSC_R_SPI_0SC_PM_CLK_PERYYSPI 0 baudSC_R_SPI_1SC_PM_CLK_PERYYSPI 1 baudSC_R_SPI_2SC_PM_CLK_PERYYSPI 2 baudSC_R_SPI_3SC_PM_CLK_PERYYSPI 3 baud				Υ	Υ	TPM peripheral
SC_R_SDHC_0 SC_PM_CLK_PER 396MHZ Y Y uSDHC 0 peripheral SC_R_SDHC_1 SC_PM_CLK_PER 396MHZ Y Y uSDHC 1 peripheral SC_R_SDHC_2 SC_PM_CLK_PER 396MHZ Y Y uSDHC 2 peripheral SC_R_SPI_0 SC_PM_CLK_PER Y Y SPI 0 baud SC_R_SPI_1 SC_PM_CLK_PER Y Y SPI 1 baud SC_R_SPI_2 SC_PM_CLK_PER Y Y SPI 2 baud SC_R_SPI_3 SC_PM_CLK_PER Y Y SPI 3 baud		SC PM CLK PER	24MHZ	Υ		UART baud
SC_R_SDHC_1 SC_PM_CLK_PER 396MHZ Y Y uSDHC 1 peripheral SC_R_SDHC_2 SC_PM_CLK_PER 396MHZ Y Y uSDHC 2 peripheral SC_R_SPI_0 SC_PM_CLK_PER Y Y SPI 0 baud SC_R_SPI_1 SC_PM_CLK_PER Y Y SPI 1 baud SC_R_SPI_2 SC_PM_CLK_PER Y Y SPI 2 baud SC_R_SPI_3 SC_PM_CLK_PER Y Y SPI 3 baud				Υ	Υ	
SC_R_SDHC_2 SC_PM_CLK_PER 396MHZ Y Y uSDHC 2 peripheral SC_R_SPI_0 SC_PM_CLK_PER Y Y SPI 0 baud SC_R_SPI_1 SC_PM_CLK_PER Y Y SPI 1 baud SC_R_SPI_2 SC_PM_CLK_PER Y Y SPI 2 baud SC_R_SPI_3 SC_PM_CLK_PER Y Y SPI 3 baud				Υ	Υ	' '
SC_R_SPI_0 SC_PM_CLK_PER Y Y SPI 0 baud SC_R_SPI_1 SC_PM_CLK_PER Y Y SPI 1 baud SC_R_SPI_2 SC_PM_CLK_PER Y Y SPI 2 baud SC_R_SPI_3 SC_PM_CLK_PER Y Y SPI 3 baud				Υ	Υ	
SC_R_SPI_1 SC_PM_CLK_PER Y Y SPI 1 baud SC_R_SPI_2 SC_PM_CLK_PER Y Y SPI 2 baud SC_R_SPI_3 SC_PM_CLK_PER Y Y SPI 3 baud					Υ	· ·
SC_R_SPI_2 SC_PM_CLK_PER Y Y SPI 2 baud SC_R_SPI_3 SC_PM_CLK_PER Y Y SPI 3 baud						
SC_R_SPI_3 SC_PM_CLK_PER Y Y SPI 3 baud						
SU_H_UAHI_U	SC_R_UART_0	SC_PM_CLK_PER		Υ	Υ	UART 0 baud
SC_R_UART_1 SC_PM_CLK_PER Y Y UART 1 baud				Υ	Υ	
SC_R_UART_2 SC_PM_CLK_PER Y Y UART 2 baud				Υ	Υ	
SC_R_UART_3 SC_PM_CLK_PER Y Y UART 3 baud				Υ	Υ	

Chapter 8

Control List

The table below lists the miscellaneous controls available in the system (SoC specific). Resource and Control are parameters to several MISC API calls. Set=Y indicates the control can be written via sc_misc_set_control(). All controls can be read via sc_misc_get_control(). Temp sensors can be accessed via these but use raw sensor values. The sc_misc_set_temp() and sc_misc_get_temp() functions use degrees in celsius. The list below can also be used to identify which resources have an associated temp sensor for these functions.

Note the control define values are defined in types.h.

See also

MISC: Miscellaneous Service

Resource	Control	Width	Set	Description
SC_R_CAN_0	SC_C_IPG_DOZE	1	Υ	CAN0 IPG_DOZE
SC_R_CAN_0	SC_C_IPG_STOP	1	Υ	CAN0 IPG_STOP
SC_R_CAN_0	SC_C_IPG_STOP_ACK	1	Υ	CAN0 IPG_STOP_ACK
SC_R_CAN_1	SC_C_IPG_DOZE	1	Υ	CAN1 IPG_DOZE
SC_R_CAN_1	SC_C_IPG_STOP	1	Υ	CAN1 IPG_STOP
SC_R_CAN_1	SC_C_IPG_STOP_ACK	1	Υ	CAN1 IPG_STOP_ACK
SC_R_CAN_2	SC_C_IPG_DOZE	1	Υ	CAN2 IPG_DOZE
SC_R_CAN_2	SC_C_IPG_STOP	1	Υ	CAN2 IPG_STOP
SC_R_CAN_2	SC_C_IPG_STOP_ACK	1	Υ	CAN2 IPG_STOP_ACK
SC_R_DRC_0	SC_C_CALIB0	0	Υ	Call DQS2DQ init function (for stress test only)
SC_R_DRC_0	SC_C_CALIB1	0	Υ	Call RDBI bit deskew function (for stress test only)
SC_R_DRC_0	SC_C_TEMP	16		Temperature sensor value
SC_R_DRC_0	SC_C_TEMP_HI	16	Υ	Temperature sensor high limit alarm value
SC_R_DRC_0	SC_C_TEMP_LOW	16	Υ	Temperature sensor low limit alarm value
SC_R_ENET←	SC_C_CLKDIV	1	Υ	ENET1 divided clock
_0				
SC_R_ENET↔	SC_C_DISABLE_125	1	Υ	ENET1 125/25MHz clock disable
_0				
SC_R_ENET⊷	SC_C_DISABLE_50	1	Υ	ENET1 50MHz clock disable
_0				

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Resource	Control	Width	Set	Description
SC_R_ENET↔	SC_C_IPG_STOP	1	Υ	ENET1 IPG stop mode
_0				
SC_R_ENET↔	SC_C_RXC_DLY	2	Υ	ENET1 RGMII RXC delay
_0	22 2 25 125			
SC_R_ENET↔ _0	SC_C_SEL_125	1	Y	ENET1 125/25MHz ref clk sel
SC_R_ENET↔ _0	SC_C_TIMER_SEL	1	Y	ENET1 timer input selection
SC_R_ENET↔ _0	SC_C_TXCLK	1	Y	ENET1 TXCLK selection
SC_R_ENET↔ _1	SC_C_CLK_GEN_EN	1	Υ	ENET2 EQOS MAC Transmit and receive clock enable
SC_R_ENET↔ _1	SC_C_DISABLE_125	1	Y	ENET2 125/25MHz clock disable
SC_R_ENET↔	SC_C_DISABLE_50	1	Υ	ENET2 50MHz clock disable
_1				
SC_R_ENET↔ _1	SC_C_INTF_SEL	3	Y	ENET2 selection of the PHY interface
SC_R_ENET↔	SC_C_SEL_125	1	Υ	ENET2 125/25MHz ref clk sel
_1				
SC_R_ENET↔ _1	SC_C_TIMER_SEL	1	Y	ENET2 timer input selection
SC_R_FSPI_0	SC_C_MISC0	9	Υ	FSPI 0 swap
SC_R_FSPI_0	SC_C_MISC1	9	Υ	FSPI 0 swap mask
SC_R_PMIC_0	SC_C_TEMP	8		Temperature sensor temp
SC_R_PMIC_0	SC_C_TEMP_HI	8	Υ	Temperature sensor high limit alarm temp
SC_R_PMIC_1	SC_C_TEMP	8		Temperature sensor temp
SC_R_PMIC_1	SC_C_TEMP_HI	8	Υ	Temperature sensor high limit alarm temp
SC_R_PMIC_2	SC_C_TEMP	8		Temperature sensor temp
SC_R_PMIC_2	SC_C_TEMP_HI	8	Υ	Temperature sensor high limit alarm temp
SC_R_SDHC↔ _0	SC_C_VOLTAGE	1	Υ	uSDHC1 IO voltage
SC_R_SDHC↔ _1	SC_C_VOLTAGE	1	Y	uSDHC2 IO voltage
SC_R_SDHC↔ _2	SC_C_VOLTAGE	1	Υ	uSDHC3 IO voltage
SC_R_SYSTEM	SC_C_ID	9		Chip ID and revision value
SC_R_SYSTEM	SC_C_MODE	8		Boot mode pads
SC_R_SYSTEM	SC_C_TEMP	16		Temperature sensor value
SC_R_SYSTEM	SC_C_TEMP_HI	16	Υ	Temperature sensor high limit alarm value
SC_R_SYSTEM	SC_C_TEMP_LOW	16	Υ	Temperature sensor low limit alarm value

Chapter 9

Pad List

The table below lists the pads available in the system (SoC specific). Pad is a parameter to several PAD API calls.

Note, if two pads are configured for the same IP signal, one is successful and the other will not get the signal. This prioritization is done in HW and some pads have a default mux setting to a signal that another pad can be set to. If SW tries to set the other pad to this setting, it may not make a connection if that pad is lower priority in the HW than the one that has this setting due to default. To resolve this, the SW has to move the conflicting pad to something other than the offending signal. This isn't always possible if the offending pad is owned by another partition. As a result, the SCFW changes the mux configuration of all the pads that could be in conflict to GPIO as those are never in conflict. Refer to the SC_PAD_INIT_INIT define in the SoC-specific soc.h for a list of these pads.

Note the pad define values (index) are listed here but the define should be used. These are defined in the SoC-specific pads.h. Functions like sc_rm_set_pad_movable() take a pad range. This range is numerical by index and not alphabetical by define name. Range should be lowest to highest index.

See also

PAD: Pad Service

Pad	Index	Mux Options
SC_P_ADC_IN0	81	ADMA.ADC.IN0, M40.I2C0.SCL, M40.GPIO0.IO00,
		ADMA.I2C0.SCL, LSIO.GPIO1.IO10, ADMA.LCD↔
		IF.D14
SC_P_ADC_IN1	80	ADMA.ADC.IN1, M40.I2C0.SDA, M40.GPIO0.I↔
		O01, ADMA.I2C0.SDA, LSIO.GPIO1.IO09, ADM↔
		A.LCDIF.D13
SC_P_ADC_IN2	83	ADMA.ADC.IN2, M40.UART0.RX, M40.GPIO0.I↔
		O02, ADMA.ACM.MCLK_IN0, LSIO.GPIO1.IO12,
		ADMA.LCDIF.D16
SC_P_ADC_IN3	82	ADMA.ADC.IN3, M40.UART0.TX, M40.GPIO0.I↔
		O03, ADMA.ACM.MCLK_OUT0, LSIO.GPIO1.I↔
		O11, ADMA.LCDIF.D15
SC_P_ADC_IN4	85	ADMA.ADC.IN4, M40.TPM0.CH0, M40.GPIO0.I←
		O04, ADMA.LCDIF.LCDRESET, LSIO.GPIO1.IO14
SC_P_ADC_IN5	84	ADMA.ADC.IN5, M40.TPM0.CH1, M40.GPIO0.I↔
		O05, ADMA.LCDIF.LCDBUSY, LSIO.GPIO1.IO13,
		ADMA.LCDIF.D17

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Pad	Index	Mux Options
SC_P_COMP_CTL_GPIO_1V8_3V3_ENET_EN↔	35	
ETB0		
SC_P_COMP_CTL_GPIO_1V8_3V3_ENET_EN↔	42	
ETB1		
SC_P_COMP_CTL_GPIO_1V8_3V3_GPIOCT	46	
SC_P_COMP_CTL_GPIO_1V8_3V3_GPIOLH	96	
SC_P_COMP_CTL_GPIO_1V8_3V3_GPIORHB	60	
SC_P_COMP_CTL_GPIO_1V8_3V3_GPIORHD	119	
SC_P_COMP_CTL_GPIO_1V8_3V3_GPIORHK	73	
SC_P_COMP_CTL_GPIO_1V8_3V3_GPIORHT	79	
SC_P_COMP_CTL_GPIO_1V8_3V3_PCIESEP	3	
SC_P_COMP_CTL_GPIO_1V8_3V3_QSPI0A	127	
SC_P_COMP_CTL_GPIO_1V8_3V3_QSPI0B	135	
SC_P_COMP_CTL_GPIO_1V8_3V3_SD1FIX0	21	
SC_P_COMP_CTL_GPIO_1V8_3V3_VSELSEP	28	
SC_P_COMP_CTL_GPIO_3V3_USB3IO	8	
SC P CTL NAND DQS P N	27	
SC P CTL NAND RE P N	24	
SC P EMMC0 CLK	9	CONN.EMMC0.CLK, CONN.NAND.READY B, L↔
		SIO.GPIO4.IO07
SC P EMMC0 CMD	10	CONN.EMMC0.CMD, CONN.NAND.DQS, LSIO.↔
		GPIO4.IO08
SC_P_EMMC0_DATA0	11	CONN.EMMC0.DATA0, CONN.NAND.DATA00,
		LSIO.GPIO4.IO09
SC_P_EMMC0_DATA1	12	CONN.EMMC0.DATA1, CONN.NAND.DATA01,
		LSIO.GPIO4.IO10
SC_P_EMMC0_DATA2	13	CONN.EMMC0.DATA2, CONN.NAND.DATA02,
		LSIO.GPIO4.IO11
SC_P_EMMC0_DATA3	14	CONN.EMMC0.DATA3, CONN.NAND.DATA03,
00 B 514400 BATA4		LSIO.GPIO4.IO12
SC_P_EMMC0_DATA4	15	CONN.EMMC0.DATA4, CONN.NAND.DATA04,
CC D FMMCO DATAE	16	LSIO.GPIO4.IO13 CONN.EMMC0.DATA5, CONN.NAND.DATA05,
SC_P_EMMC0_DATA5	16	LSIO.GPIO4.IO14
SC P EMMC0 DATA6	17	CONN.EMMC0.DATA6, CONN.NAND.DATA06,
GO_I _LIMIMOU_DATAU	''	LSIO.GPIO4.IO15
SC P EMMC0 DATA7	18	CONN.EMMC0.DATA7, CONN.NAND.DATA07,
00		LSIO.GPIO4.IO16
SC_P_EMMC0_RESET_B	20	CONN.EMMCO.RESET_B, CONN.NAND.WP_B,
		LSIO.GPIO4.IO18
SC_P_EMMC0_STROBE	19	CONN.EMMC0.STROBE, CONN.NAND.CLE, LS⇔
		IO.GPIO4.IO17
SC_P_ENET0_MDC	45	CONN.ENET0.MDC, ADMA.I2C3.SCL, CONN.E↔
		QOS.MDC, LSIO.GPIO5.IO11, LSIO.GPIO7.IO17
SC_P_ENET0_MDIO	44	CONN.ENET0.MDIO, ADMA.I2C3.SDA, CONN.↔
		EQOS.MDIO, LSIO.GPIO5.IO10, LSIO.GPIO7.I↔
		O16
SC_P_ENET0_REFCLK_125M_25M	43	CONN.ENET0.REFCLK_125M_25M, CONN.EN↔
		ET0.PPS, CONN.EQOS.PPS_IN, CONN.EQOS.←
		PPS_OUT, LSIO.GPIO5.IO09

Pad	Index	Mux Options
SC_P_ENET0_RGMII_RXC	36	CONN.ENET0.RGMII_RXC, CONN.NAND.WE_← B, CONN.USDHC1.CLK, LSIO.GPIO5.IO03
SC_P_ENET0_RGMII_RXD0	38	CONN.ENET0.RGMII_RXD0, CONN.USDHC1.D← ATA0, LSIO.GPIO5.IO05
SC_P_ENET0_RGMII_RXD1	39	CONN.ENET0.RGMII_RXD1, CONN.USDHC1.D← ATA1, LSIO.GPIO5.IO06
SC_P_ENET0_RGMII_RXD2	40	CONN.ENET0.RGMII_RXD2, CONN.ENET0.RM← II_RX_ER, CONN.USDHC1.DATA2, LSIO.GPI← O5.IO07
SC_P_ENET0_RGMII_RXD3	41	CONN.ENET0.RGMII_RXD3, CONN.NAND.ALE, CONN.USDHC1.DATA3, LSIO.GPIO5.IO08
SC_P_ENET0_RGMII_RX_CTL	37	CONN.ENET0.RGMII_RX_CTL, CONN.USDH ← C1.CMD, LSIO.GPIO5.IO04
SC_P_ENET0_RGMII_TXC	29	CONN.ENET0.RGMII_TXC, CONN.ENET0.RCL← K50M_OUT, CONN.ENET0.RCLK50M_IN, CON← N.NAND.CE1_B, LSIO.GPIO4.IO29, CONN.USD← HC2.CLK
SC_P_ENET0_RGMII_TXD0	31	CONN.ENET0.RGMII_TXD0, CONN.USDHC1.V← SELECT, LSIO.GPIO4.IO31, CONN.USDHC2.D← ATA0
SC_P_ENET0_RGMII_TXD1	32	CONN.ENET0.RGMII_TXD1, CONN.USDHC1.WP, LSIO.GPIO5.IO00, CONN.USDHC2.DATA1
SC_P_ENET0_RGMII_TXD2	33	CONN.ENET0.RGMII_TXD2, CONN.NAND.CE0← _B, CONN.USDHC1.CD_B, LSIO.GPIO5.IO01, C← ONN.USDHC2.DATA2
SC_P_ENET0_RGMII_TXD3	34	CONN.ENET0.RGMII_TXD3, CONN.NAND.RE_← B, LSIO.GPIO5.IO02, CONN.USDHC2.DATA3
SC_P_ENET0_RGMII_TX_CTL	30	CONN.ENET0.RGMII_TX_CTL, CONN.USDH ← C1.RESET_B, LSIO.GPIO4.IO30, CONN.USDH ← C2.CMD
SC_P_ENET1_REFCLK_125M_25M	59	ADMA.SPDIF0.EXT_CLK, ADMA.LCDIF.D12, C← ONN.EQOS.REFCLK_125M_25M, LSIO.GPIO0.← IO12, LSIO.GPIO6.IO06
SC_P_ENET1_RGMII_RXC	51	, ADMA.LCDIF.D04, CONN.EQOS.RGMII_RXC, LSIO.GPIO0.IO04
SC_P_ENET1_RGMII_RXD0	57	ADMA.SPDIF0.RX, ADMA.MQS.R, ADMA.LCD← IF.D10, CONN.EQOS.RGMII_RXD0, LSIO.GPI← O0.IO10, LSIO.GPIO6.IO04
SC_P_ENET1_RGMII_RXD1	54	, ADMA.LCDIF.D07, CONN.EQOS.RGMII_RXD1, LSIO.GPIO0.IO07, LSIO.GPIO6.IO01
SC_P_ENET1_RGMII_RXD2	53	, ADMA.LCDIF.D06, CONN.EQOS.RGMII_RXD2, LSIO.GPIO0.IO06, LSIO.GPIO6.IO00
SC_P_ENET1_RGMII_RXD3	52	, ADMA.LCDIF.D05, CONN.EQOS.RGMII_RXD3, LSIO.GPIO0.IO05
SC_P_ENET1_RGMII_RX_CTL	58	ADMA.SPDIF0.TX, ADMA.MQS.L, ADMA.LCDI← F.D11, CONN.EQOS.RGMII_RX_CTL, LSIO.GPI← O0.IO11, LSIO.GPIO6.IO05
SC_P_ENET1_RGMII_TXC	47	LSIO.GPIO0.IO00, CONN.EQOS.RCLK50M_OUT, ADMA.LCDIF.D00, CONN.EQOS.RGMII_TXC, C← ONN.EQOS.RCLK50M_IN

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Pad	Index	Mux Options
SC_P_ENET1_RGMII_TXD0	55	, ADMA.LCDIF.D08, CONN.EQOS.RGMII_TXD0, LSIO.GPIO0.IO08, LSIO.GPIO6.IO02
SC_P_ENET1_RGMII_TXD1	56	, ADMA.LCDIF.D09, CONN.EQOS.RGMII_TXD1, LSIO.GPIO0.IO09, LSIO.GPIO6.IO03
SC_P_ENET1_RGMII_TXD2	48	, ADMA.LCDIF.D01, CONN.EQOS.RGMII_TXD2, LSIO.GPIO0.IO01
SC_P_ENET1_RGMII_TXD3	50	, ADMA.LCDIF.D03, CONN.EQOS.RGMII_TXD3, LSIO.GPIO0.IO03
SC_P_ENET1_RGMII_TX_CTL	49	, ADMA.LCDIF.D02, CONN.EQOS.RGMII_TX_C↔ TL, LSIO.GPIO0.IO02
SC_P_FLEXCAN0_RX	86	ADMA.FLEXCANO.RX, ADMA.SAI2.RXC, ADM → A.UARTO.RTS_B, ADMA.SAI1.TXC, LSIO.GPI ← O1.IO15, LSIO.GPIO6.IO08
SC_P_FLEXCAN0_TX	87	ADMA.FLEXCANO.TX, ADMA.SAI2.RXD, ADM⇔ A.UARTO.CTS_B, ADMA.SAI1.TXFS, LSIO.GPI⇔ O1.IO16, LSIO.GPIO6.IO09
SC_P_FLEXCAN1_RX	88	ADMA.FLEXCAN1.RX, ADMA.SAI2.RXFS, ADM ← A.FTM.CH2, ADMA.SAI1.TXD, LSIO.GPIO1.IO17, LSIO.GPIO6.IO10
SC_P_FLEXCAN1_TX	89	ADMA.FLEXCAN1.TX, ADMA.SAI3.RXC, ADM← A.DMA0.REQ_IN0, ADMA.SAI1.RXD, LSIO.GPI← O1.IO18, LSIO.GPIO6.IO11
SC_P_FLEXCAN2_RX	90	ADMA.FLEXCAN2.RX, ADMA.SAI3.RXD, ADM← A.UART3.RX, ADMA.SAI1.RXFS, LSIO.GPIO1.I← O19, LSIO.GPIO6.IO12
SC_P_FLEXCAN2_TX	91	ADMA.FLEXCAN2.TX, ADMA.SAI3.RXFS, ADM↔ A.UART3.TX, ADMA.SAI1.RXC, LSIO.GPIO1.I↔ O20, LSIO.GPIO6.IO13
SC_P_JTAG_TRST_B	97	SCU.JTAG.TRST_B, SCU.WDOG0.WDOG_OUT
SC_P_MCLK_IN0	67	ADMA.ACM.MCLK_IN0, ADMA.LCDIF.VSYNC, ADMA.SPI2.SDI, LSIO.GPIO0.IO19, ADMA.LCD← IF.RS
SC_P_MCLK_IN1	66	ADMA.ACM.MCLK_IN1, ADMA.I2C3.SDA, ADM← A.LCDIF.EN, ADMA.SPI2.SCK, ADMA.LCDIF.D17, ADMA.LCDIF.D03
SC_P_MCLK_OUT0	68	ADMA.ACM.MCLK_OUT0, ADMA.LCDIF.CLK, A← DMA.SPI2.SDO, LSIO.GPIO0.IO20, ADMA.LCDI← F.WR_RWN
SC_P_PCIE_CTRL0_CLKREQ_B	1	HSIO.PCIE0.CLKREQ_B, LSIO.GPIO4.IO01, LS↔ IO.GPIO7.IO01
SC_P_PCIE_CTRL0_PERST_B	0	HSIO.PCIE0.PERST_B, LSIO.GPIO4.IO00, LSI↔ O.GPIO7.IO00
SC_P_PCIE_CTRL0_WAKE_B	2	HSIO.PCIE0.WAKE_B, LSIO.GPIO4.IO02, LSIO.↔ GPIO7.IO02
SC_P_PMIC_I2C_SCL	98	SCU.PMIC_I2C.SCL, SCU.GPIO0.IOXX_PMIC_← A35_ON, LSIO.GPIO2.IO01
SC_P_PMIC_I2C_SDA	99	SCU.PMIC_I2C.SDA, SCU.GPIO0.IOXX_PMIC_← GPU_ON, LSIO.GPIO2.IO02
SC_P_PMIC_INT_B	100	SCU.DSC.PMIC_INT_B
SC_P_QSPI0A_DATA0	121	LSIO.QSPI0A.DATA0, LSIO.GPIO3.IO09
SC_P_QSPI0A_DATA1	120	LSIO.QSPI0A.DATA1, LSIO.GPIO3.IO10

Pad	Index	Mux Options
SC_P_QSPI0A_DATA2	123	LSIO.QSPI0A.DATA2, LSIO.GPIO3.IO11
SC_P_QSPI0A_DATA3	122	LSIO.QSPI0A.DATA3, LSIO.GPIO3.IO12
SC_P_QSPI0A_DQS	125	LSIO.QSPI0A.DQS, LSIO.GPIO3.IO13
SC_P_QSPI0A_SCLK	126	LSIO.QSPI0A.SCLK, LSIO.GPIO3.IO16
SC_P_QSPI0A_SS0_B	124	LSIO.QSPI0A.SS0_B, LSIO.GPIO3.IO14
SC_P_QSPI0B_DATA0	131	LSIO.QSPI0B.DATA0, LSIO.GPIO3.IO18
SC_P_QSPI0B_DATA1	130	LSIO.QSPI0B.DATA1, LSIO.GPIO3.IO19
SC_P_QSPI0B_DATA2	133	LSIO.QSPI0B.DATA2, LSIO.GPIO3.IO20
SC_P_QSPI0B_DATA3	132	LSIO.QSPI0B.DATA3, LSIO.GPIO3.IO21
SC_P_QSPI0B_DQS	129	LSIO.QSPI0B.DQS, LSIO.GPIO3.IO22
SC_P_QSPI0B_SCLK	128	LSIO.QSPI0B.SCLK, LSIO.GPIO3.IO17
SC_P_QSPI0B_SS0_B	134	LSIO.QSPI0B.SS0_B, LSIO.GPIO3.IO23, LSIO.↔ QSPI0A.SS1_B
SC_P_SCU_BOOT_MODE0	105	SCU.DSC.BOOT_MODE0
SC_P_SCU_BOOT_MODE1	104	SCU.DSC.BOOT_MODE1
SC_P_SCU_BOOT_MODE2	106	SCU.DSC.BOOT_MODE2, SCU.DSC.RTC_CLO← CK_OUTPUT_32K
SC_P_SCU_GPIO0_00	101	SCU.GPIO0.IO00, SCU.UART0.RX, M40.UAR← T0.RX, ADMA.UART3.RX, LSIO.GPIO2.IO03
SC_P_SCU_GPIO0_01	102	SCU.GPIO0.IO01, SCU.UART0.TX, M40.UAR← T0.TX, ADMA.UART3.TX, SCU.WDOG0.WDOG← _OUT
SC_P_SCU_PMIC_STANDBY	103	SCU.DSC.PMIC_STANDBY
SC_P_SNVS_TAMPER_IN0	111	, ADMA.SAI2.RXFS, LSIO.GPIO2.IO09_IN, LSI← O.GPIO6.IO23_IN
SC_P_SNVS_TAMPER_IN1	112	, ADMA.SAI3.RXC, LSIO.GPIO2.IO10_IN, LSIO.← GPIO6.IO24_IN
SC_P_SNVS_TAMPER_IN2	113	, ADMA.SAI3.RXD, LSIO.GPIO2.IO11_IN, LSIO.← GPIO6.IO25_IN
SC_P_SNVS_TAMPER_IN3	114	, ADMA.SAI3.RXFS, LSIO.GPIO2.IO12_IN, LSI← O.GPIO6.IO26_IN
SC_P_SNVS_TAMPER_OUT1	107	, LSIO.GPIO2.IO05_IN, LSIO.GPIO6.IO19_IN
SC_P_SNVS_TAMPER_OUT2	108	, LSIO.GPIO2.IO06_IN, LSIO.GPIO6.IO20_IN
SC_P_SNVS_TAMPER_OUT3	109	, ADMA.SAI2.RXC, LSIO.GPIO2.IO07_IN, LSIO.↔ GPIO6.IO21 IN
SC_P_SNVS_TAMPER_OUT4	110	, ADMA.SAI2.RXD, LSIO.GPIO2.IO08_IN, LSIO.↔ GPIO6.IO22 IN
SC_P_SPI0_CS0	78	ADMA.SPI0.CS0, ADMA.SAI0.RXD, M40.TPM0.← CH1, M40.GPIO0.IO03, LSIO.GPIO1.IO08, ADM← A.LCDIF.D12
SC_P_SPI0_CS1	77	ADMA.SPI0.CS1, ADMA.SAI0.RXC, ADMA.SA⇔ I1.TXD, ADMA.LCD_PWM0.OUT, LSIO.GPI01.I⇔ O07, ADMA.LCDIF.D11
SC_P_SPI0_SCK	74	ADMA.SPI0.SCK, ADMA.SAI0.TXC, M40.I2C0.S← CL, M40.GPI00.IO00, LSIO.GPI01.IO04, ADMA.← LCDIF.D08
SC_P_SPI0_SDI	75	ADMA.SPI0.SDI, ADMA.SAI0.TXD, M40.TPM0.C← H0, M40.GPI00.IO02, LSIO.GPI01.IO05, ADM← A.LCDIF.D09

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Pad	Index	Mux Options
SC_P_SPI0_SDO	76	ADMA.SPI0.SDO, ADMA.SAI0.TXFS, M40.I2C0.↔
		SDA, M40.GPIO0.IO01, LSIO.GPIO1.IO06, ADM↔
SC P SPI1 CS0	118	A.LCDIF.D10 . ADMA.I2C3.SDA, ADMA.SPI1.CS0, LSIO.GPI←
30_1_3111_030	110	03.1003
SC_P_SPI1_SCK	115	, ADMA.I2C2.SDA, ADMA.SPI1.SCK, LSIO.GPI↔
00 B 0814 081	1	03.1000
SC_P_SPI1_SDI	117	, ADMA.I2C3.SCL, ADMA.SPI1.SDI, LSIO.GPI← O3.IO02
SC P SPI1 SDO	116	, ADMA.I2C2.SCL, ADMA.SPI1.SDO, LSIO.GPI↔
		O3.IO01
SC_P_SPI3_CS0	64	ADMA.SPI3.CS0, ADMA.ACM.MCLK_OUT1, AD↔
		MA.LCDIF.HSYNC, LSIO.GPIO0.IO16, ADMA.L← CDIF.CS
SC P SPI3 CS1	65	ADMA.SPI3.CS1, ADMA.I2C3.SCL, ADMA.LCDI↔
00_1_0110_001		F.RESET, ADMA.SPI2.CS0, ADMA.LCDIF.D16, A↔
		DMA.LCDIF.RD_E
SC_P_SPI3_SCK	61	ADMA.SPI3.SCK, ADMA.LCDIF.D13, LSIO.GPI↔
		O0.IO13, ADMA.LCDIF.D00
SC_P_SPI3_SDI	63	ADMA.SPI3.SDI, ADMA.LCDIF.D15, LSIO.GPI↔ O0.IO15, ADMA.LCDIF.D02
SC P SPI3 SDO	62	ADMA.SPI3.SDO, ADMA.LCDIF.D14, LSIO.GPI↔
00_1_01.10_020	02	O0.IO14, ADMA.LCDIF.D01
SC_P_UART0_RX	92	ADMA.UARTO.RX, ADMA.MQS.R, ADMA.FLEX↔
		CAN0.RX, SCU.UART0.RX, LSIO.GPIO1.IO21, L↔
OO D HADTO TV	00	SIO.GPIO6.IO14
SC_P_UART0_TX	93	ADMA.UARTO.TX, ADMA.MQS.L, ADMA.FLEXC← ANO.TX, SCU.UARTO.TX, LSIO.GPIO1.IO22, LS←
		IO.GPIO6.IO15
SC_P_UART1_CTS_B	72	ADMA.UART1.CTS_B, LSIO.PWM3.OUT, ADM↔
		A.LCDIF.D17, LSIO.GPT1.COMPARE, LSIO.GPI←
OO D HADTA DTO D	74	O0.IO24, ADMA.LCDIF.D07
SC_P_UART1_RTS_B	71	ADMA.UART1.RTS_B, LSIO.PWM2.OUT, ADM← A.LCDIF.D16, LSIO.GPT1.CAPTURE, LSIO.GP←
		To.CLK, ADMA.LCDIF.D06
SC_P_UART1_RX	70	ADMA.UART1.RX, LSIO.PWM1.OUT, LSIO.GP←
		T0.COMPARE, LSIO.GPT1.CLK, LSIO.GPIO0.I↔
00 B HARTA TV		O22, ADMA.LCDIF.D05
SC_P_UART1_TX	69	ADMA.UART1.TX, LSIO.PWM0.OUT, LSIO.GP↔ T0.CAPTURE, LSIO.GPIO0.IO21, ADMA.LCDIF.↔
		D04
SC_P_UART2_RX	95	ADMA.UART2.RX, ADMA.FTM.CH0, ADMA.FLE↔
		XCAN1.RX, LSIO.GPIO1.IO24, LSIO.GPIO6.IO17
SC_P_UART2_TX	94	ADMA.UART2.TX, ADMA.FTM.CH1, ADMA.FLE←
SC D LISD SS2 TC0	4	XCAN1.TX, LSIO.GPIO1.IO23, LSIO.GPIO6.IO16 ADMA.I2C1.SCL, CONN.USB OTG1.PWR, CO←
SC_P_USB_SS3_TC0	4	NN.USB OTG2.PWR, LSIO.GPIO4.IO03, LSIO.
		GPIO7.IO03
SC_P_USB_SS3_TC1	5	ADMA.I2C1.SCL, CONN.USB_OTG2.PWR, LSI↔
		O.GPIO4.IO04, LSIO.GPIO7.IO04

Pad	Index	Mux Options
SC_P_USB_SS3_TC2	6	ADMA.I2C1.SDA, CONN.USB_OTG1.OC, CON← N.USB_OTG2.OC, LSIO.GPIO4.IO05, LSIO.GPI← O7.IO05
SC_P_USB_SS3_TC3	7	ADMA.I2C1.SDA, CONN.USB_OTG2.OC, LSIO.← GPIO4.IO06, LSIO.GPIO7.IO06
SC_P_USDHC1_CD_B	26	CONN.USDHC1.CD_B, CONN.NAND.DQS_P, A← DMA.SPI2.CS0, CONN.NAND.DQS, LSIO.GPI← O4.IO22, LSIO.GPIO7.IO11
SC_P_USDHC1_RESET_B	22	CONN.USDHC1.RESET_B, CONN.NAND.R← E_N, ADMA.SPI2.SCK, CONN.NAND.WE_B, LSIO.GPIO4.IO19, LSIO.GPIO7.IO08
SC_P_USDHC1_VSELECT	23	CONN.USDHC1.VSELECT, CONN.NAND.RE_P, ADMA.SPI2.SDO, CONN.NAND.RE_B, LSIO.GP ← IO4.IO20, LSIO.GPIO7.IO09
SC_P_USDHC1_WP	25	CONN.USDHC1.WP, CONN.NAND.DQS_N, AD ← MA.SPI2.SDI, CONN.NAND.ALE, LSIO.GPIO4.I ← O21, LSIO.GPIO7.IO10

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Chapter 10

RPC Protocol

Clients of the SCFW make function calls using a Remote Procedure Call (RPC) mechanism. This is constructed on top of an Inter-Processor Communication (IPC) layer. The RPC mechanism is independent of the IPC mechanism. All that is required is that the IPC mechanism can send and receive messages consisting of a series of 32-bit words. Message lengths can vary between different APIs but are fixed for a specific API.

The RPC protocol is documented here for reference ONLY. It is expected clients will make use of the exported API. Using the protocol directly is not supported and makes it impossible to provide customer support.

10.1 Remote Procedure Call

The RPC implementation is all generated via script. Interface Description Language (IDL) lines exist in the API header files to describe the calling conventions of each API call. This supports integer and unsigned values of 8-, 16-, 32-, and 64-bit sizes. Special provisions are also provided for boolean types and error returns. Float is not supported.

The RPC mechanism is synchronous. Almost all API calls construct a series of 32-bit words to form a request, send the request, receive a response, deconstruct the response (also a series of 32-bit words), and return to the caller. The corresponding function on the SCFW side (server side) is not called until a complete valid request is received.

Messages consist of a header followed by a variable number of parameter words. Parameter words are packed starting with the largest parameters. Parameters passed by pointer may exist in the send request and the response depending on how they are defined in the IDL (in, out, both). Empty slots are undefined and may not be 0.

The header is a single 32-bit word consisting of four bytes:

- · version the protocol version
- size size of the message in words including the header
- · svc service index
- · func function index within the service

Note for return messages, svc=1U. Also, to minimize the number of words in the return value, func is replaced by the return value if it is an 8-bit type.

10.2 Inter-Processor Communication

The primary IPC mechanism implemented by the SCFW is via Message Unit (MU) IP (up to eight of them).

The MU has four TX and four RX registers, each capable of generating an interrupt. The SCFW IPC uses all four to create a single channel in both directions.

All message start with the first MU TX register. Words are written in order into successive registers and wrap back to the first if the message is greater than four words. Transmission blocks if the next TX register is not empty. The response is handled the same way. It always starts with the first RX register and wraps if the message is longer than four words. Transmission blocks if the next RX register is empty. On the SCFW-side, this is all interrupt driven. The message is buffered (per MU) and the API call into the SCFW only occurs when a complete valid request is received.

RPC messages can take many mS to complete. The API is fully synchronous and a timeout period should not be used as it would confuse the IPC state machine in the SCFW.

There is also an IPC mechanism implemented via UART as part of the SCFW debug monitor. This can be used to write test code that runs on a host connected via the SCU UART.

10.3 Interrupts

10.3.1 SCFW to Client Interrupts

The client-side IPC driver usually makes use of the MU TX/RX interrupts to transfer data. In addition, the SCFW makes use of the MU general-purpose interrupts to inform the client of various events that need attention. These four interrupts are defined in the rpc.h file delivered as part of the API export package:

Interrupt	MU GIRx	Use
SC_RPC_MU_GIR_SVC	0	Interrupt Service Request
SC_RPC_MU_GIR_WAKE	1	Cortex-M Wake
SC_RPC_MU_GIR_BOOT	2	Cold Boot Flag
SC_RPC_MU_GIR_DBG	3	Cortex-M Debug Wake

10.3.1.1 Interrupt Service Request

This interrupt is generated when the SCFW needs servicing. This behavior is managed using the Interrupt Service API. Interrupts are collected into groups, each containing up to 32 interrupts. The groups and interrupts are listed in the api.h file for the interrupt service.

The client should call <code>sc_irq_enable()</code> to enable an interrupt. When the interrupt is serviced, the client should call <code>sc_irq_status()</code> for each group to determine the needed actions and figure out what component (i.e. OS driver) call-backs should be called. Calling <code>sc_irq_status()</code> also clears the pending status of the interrupt. As a result, the SCFW Interrupt Service acts as an interrupt collector/dispatcher mechanism.

10.3.1.2 Cortex-M Wake

This MU general-purpose IRQ is used to force a wakeup event prior to stopping a Cortex-M CPU in order to maintain coherency between the AWIC and core sleep state. Cortex-M SW should always enable.

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10.3.1.3 Cold Boot Flag

This interrupt is not used as an interrupt. It is used as a clearable flag that indicates the client is booting after a cold reset. Because the SoC has multiple CPUs that could be sharing memory, a cold reset of a single CPU may not be able to actually reset the memory that CPU is using. This flag informs clients they should clear any state maintained in memory.

10.3.1.4 Cortex-M Debug Wake

This MU general-purpose IRQ is used to force a wakeup event prior to attaching debug to a Cortex-M CPU. This wake event will be sent when the respective CoreSight GPR (Granular Power Requestor) is set by the debugger to notify SCFW that power/clocks should be restored to Cortex-M core debug registers. Cortex-M SW should always enable.

10.3.2 Client to SCFW Interrupts

Interrupt	MU GIRx	Use
SC_RPC_MU_GIR_RST	0	RPC/IPC Reset Request

10.3.2.1 RPC/IPC Reset Request

This MU general-purpose IRQ is used to request the SCFW to reset the RPC/IPC interface. This request can be used to recover the RPC/IPC interface if a client driver/task is terminated/restarted in the middle of RPC/IPC communication. The RPC/IPC reset sequence should be executed as follows:

- 1. Driver or task performing RPC/IPC communication is stopped
- 2. Client requests RPC reset by writing to the SC RPC MU GIR RST bit of the MU.CR register
- Client polls MU.CR register until SC_RPC_MU_GIR_RST bit is cleared to indicate SCFW has completed the RPC/IPC reset
- 4. Client side of MU module should be reconfigured for RPC/IPC communication
- 5. RPC/IPC communication can proceed normally

10.4 Flags/Status

10.4.1 SCFW to Client Flags/Status

SCFW makes use of the MU general-purpose flags to provide the client status and information. Currently these flags are only used to convey the instance (Core ID) of Cortex-M4 subsystems.

MU Fx	Use
0-2	Conveys subsystem instance (only Cortex-M4 subsystems)

10.5 Porting

The SCFW porting kit contains ports of the SCFW client API for ATF, FreeRTOS, Linux, QNX, and u-boot. All implement the same API and protocol. The variations involve license, directory structure, file names, and include paths.

```
scfw_export_atf.tar.gz
scfw_export_freertos.tar.gz
scfw_export_linux.tar.gz
scfw_export_qnx.tar.gz
scfw_export_uboot.tar.gz
scfw_export_headers.tar.gz
```

Integrating the API involves implementing the IPC layer. This primarily involves implementing:

```
void sc_call_rpc(sc_ipc_t ipc, sc_rpc_msg_t *msg, sc_bool_t no_resp)
```

This function should send the message pointed to by msg via an MU (identified by ipc), word by word. If no_resp is SC_FALSE then it should wait on a response and return it in the same structure pointed to by msg. sc_call_rpc() must be atomic and often requires a semaphore to insure this is the case. The size of the message is in the message itself. The IPC implementation can be interrupt or poll driven, directly to the MU or via an MU driver.

The IPC layer typically implements functions like:

```
sc_err_t sc_ipc_open(sc_ipc_t *ipc, sc_ipc_id_t id)
void sc_ipc_close(sc_ipc_t ipc)
void sc_ipc_read(sc_ipc_t ipc, void *data)
void sc_ipc_write(sc_ipc_t ipc, const void *data)
```

but that is up to the implementer. All that the SCFW API requires is that sc_call_rpc() be implemented.

10.6 API Message Formats

Below is a list of all API calls and their message formats to send a request and receive a response. A select few API calls do not return a response (self reset and reboot functions).

Messages are expected to be in little-endian format. The description accounts for this in the location of the parameter but within a parameter bytes may be in a reverse order depending on how the protocol is examined.

10.6.1 sc_pm_set_sys_power_mode()

Send								
w[0]	func=19U		svc=2U	I	size=2U	 	ver=1U	I
w[1]	undefined	l 	undefined		undefined	l 	mode	
Receive								
w[0]	err	 	svc=1U	 	size=1U	 	ver=1U	

10.6.2 sc_pm_set_partition_power_mode()

Send								
w[0]	func=1U	ı	svc=2U	I	size=2U	l	ver=1U	
w[1]	undefined	 	undefined	 	mode	 	pt 	I
Receive								
w[0]	err	ı	svc=1U	 	size=1U	 	ver=1U	

10.6.3 sc_pm_get_sys_power_mode()

Send								
w[0]	func=2U	ı	svc=2U	I	size=2U	ı	ver=1U	
w[1]	undefined	 	undefined	l 	undefined	I	pt 	
Receive								
w[0]	err	I	svc=1U	I	size=2U	l	ver=1U	I
w[1]	undefined		undefined	I	undefined		mode	I

10.6.4 sc_pm_partition_wake()

Send								
w[0]	func=28U		svc=2U	 	size=2U		ver=1U	I
w[1]	undefined	ı	undefined	I	undefined	ı	pt	I
Receive								
[0]w	err	I	svc=1U	l	size=1U	l	ver=1U	

10.6.5 sc_pm_set_resource_power_mode()

Send								
w[0]	func=3U	I	svc=2U	I	size=2U	I	ver=1U	
w[1]	undefined	ı	mode	I		resource		ı
Receive								
w[0]	err	 	svc=1U	 	size=1U	 	ver=1U	

10.6.6 sc_pm_set_resource_power_mode_all()

Send								
w[0]	func=22U	ı	svc=2U	ı	size=2U	ı	ver=1U	I
w[1]	mode	 	pt	 		exclude		
Receive								
w[0]	err		svc=1U	I	size=1U	 	ver=1U	

10.6.7 sc_pm_get_resource_power_mode()

Send								
w[0]	func=4U	I	svc=2U	I	size=2U	I	ver=1U	ı
w[1]	undefined		undefined	ı	r	esource		
Receive								
w[0]	err	I	svc=1U	I	size=2U	ı	ver=1U	
w[1]	undefined		undefined	I	undefined		mode	

10.6.8 sc_pm_req_low_power_mode()

Send								
w[0]	func=16U	 	svc=2U	l	size=2U	 	ver=1U	ı
w[1]	undefined		mode	- 1		resource		1
Receive								
w[0]	err		svc=1U		size=1U		ver=1U	

10.6.9 sc_pm_req_cpu_low_power_mode()

Send

10.6.10 sc_pm_set_cpu_resume_addr()

					size=4U		
w[1]			add:	ress			
w[2]			add:	ress	(LSW)		
	undefined	I			re	esource	
Receive							
	err				size=1U	I	ver=1U
	func=21U				size=4U		
							 ver=111
w[1]			add:	ress			
w[2]			add	ress	(LSW)		
	undefined						
Receive							
 w[0]	err	 	svc=1U		size=1U		
Send	c_pm_req_sys_						17
Send w[0]	func=18U		svc=2U		size=3U		
Send w[0] w[1]	func=18U		svc=2U sys_if	 	r	esource	
Send w[0] w[1]	func=18U		svc=2U		r	esource	
Send w[0] w[1]	func=18U		svc=2U sys_if	 	r	esource	

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w[1]				rate				
w[2]	undefined	I	clk	I	resource			
Receive								
w[0]	err	ı	svc=1U	I	size=2U		ver=1U	
w[1]				rate				1

10.6.14 sc_pm_get_clock_rate()

[0]w	func=6U	1	svc=2U	1	size=2U	1	ver=1U	- 1
w[1]	undefined	ı	clk			resource		
Receive								
w[0]	err	1	svc=1U	-	size=2U	1	ver=1U	1
W[1]				rate				

10.6.15 sc_pm_clock_enable()

Send

w[0]	func=7U		svc=2U		size=3U		ver=1U	
w[1]	enable		clk		re	esource		
w[2]	undefined	 	undefined		undefined	l	autog	I
Receive								
w[0]	err		svc=1U		size=1U		ver=1U	

10.6.16 sc_pm_set_clock_parent()

Send

w[0]	func=14U	ı	svc=2U	I	size=2U	ı	ver=1U	
w[1]	parent	l	clk		1	esource		
Receive								
w[0]	err	 	svc=1U	 	size=1U	l	ver=1U	

10.6.17 sc_pm_get_clock_parent()

Send								
w[0]	func=15U	I	svc=2U	I	size=2U		ver=1U	
w[1]	undefined	ı	clk	I	r	esource		
Receive								
w[0]	err	ı	svc=1U	ı	size=2U	Ι	ver=1U	
w[1]	undefined	ı	undefined	ı	undefined		parent	I

10.6.18 sc_pm_reset()

Send								
w[0]	func=13U		svc=2U	I	size=2U	l	ver=1U	I
w[1]	undefined	 	undefined		undefined	 	type	
Receive								
w[0] 	err		svc=1U		size=1U		ver=1U	

10.6.19 sc_pm_reset_reason()

Send								
w[0]	func=10U	 	svc=2U	 	size=1U	 	ver=1U	
Receive								
w[0]	err	 	svc=1U	 	size=2U		ver=1U	I
w[1]	undefined		undefined	ı	undefined		reason	

10.6.20 sc_pm_get_reset_part()

Send								
w[0]	func=26U	 	svc=2U		size=1U	 	ver=1U	I
Receive								
w[0]	err	ı	svc=1U	I	size=2U	ı	ver=1U	
w[1]	undefined	 	undefined	 	undefined	 	pt	I

10.6.21 sc_pm_boot()

w[4] undefined Receive w[0] err 10.6.22 sc_pm_set_box Send w[0] func=27U w[1]	resource	boot. boot. pt svc=1U	_addr addr 	(MSW) (LSW) reso	 urce_cp urce_de 	u v
w[3] r w[4] undefined ecceive w[0] err 0.6.22 sc_pm_set_boo end w[0] func=27U w[1]	resource	bootmu	_addr 	(LSW) reso reso	 urce_cp urce_de 	u v
w[3] r w[4] undefined Receive w[0] err 	resource	_mu	 	reso reso	urce_cp urce_de 	u v
w[4] undefined w[0] err 10.6.22 sc_pm_set_box w[0] func=27U w[1]	ot_parm(pt 	I 	reso	urce_de 	v
10.6.22 sc_pm_set_boo Send w[0] func=27U w[1]	ot_parm(svc=1U) svc=2U				
w[0] err 10.6.22 sc_pm_set_box Send w[0] func=27U w[1]	ot_parm(svc=1U) svc=2U				
Send w[0] func=27U w[1] w[2]	 	svc=2U				
w[2]				size=5U		ver=1U
w[1] 						
w[1] 			1			
w[2]						
			_			
w[3] r	 resource		_		 urce_cp	
	<u>'</u>					
Receive w[0] err		svc=1U		size=1U		 ver=1U

10.6.24 sc_pm_reboot_partition()

Send								
w[0]	func=12U	ı	svc=2U	I	size=2U		ver=1U	
w[1]	undefined	 	undefined		type	 	pt	
Receive								
w[0]	err	 	svc=1U	 	size=1U	 	ver=1U	

Receive

10.6.25 sc pm reboot continue()

w[1] 	func=25U undefined err	 	undefined	 			ver=1U	
w[1] 	func=25U undefined err	 	svc=2U undefined	 	undefined			
w[1] Receive w[0]	undefined err	 	undefined	 	undefined	1		
 w[0]	err	1					pt	- 1
	err	1						
			500-10	- 1	size=1U	1		
10.6.26 sc_	pm_cpu_start	()						
Send								
w[0]	func=11U		svc=2U		size=4U	l	ver=1U	
w[1]				ress (MSW)			- 1
w[2]			addi	ress (LSW)			
		-	enable			resource		-
Receive								
			svc=1U					
10.6.27 sc_	pm_cpu_rese	t()						
			svc=2U					
				ress (MSW)			
w[1]								
				ress (LSW)			

| w[0] | err | svc=1U | size=1U | ver=1U |

10.6.29 sc_pm_is_partition_started()

Send								
w[0]	func=24U	ı	svc=2U	ı	size=2U		ver=1U	
w[1]	undefined		undefined		undefined		pt	
Receive								
w[0]	result		svc=1U	 I	size=1U	 	ver=1U	

10.6.30 sc_rm_partition_alloc()

ver=1U
secure
coherent
ver=1U
pt

10.6.31 sc_rm_set_confidential()

Send								
w[0]	func=31U	ı	svc=3U	ı	size=2U	l	ver=1U	I
w[1]	undefined		undefined	 	retro	I	pt	
Receive								
w[0]	err		svc=1U	 	size=1U		ver=1U	

10.6.32 sc_rm_partition_free()

e=2U ver=1U
Fined pt
e=1U ver=1U l
- f

10.6.33 sc_rm_get_did()

Send								
w[0]	func=26U		svc=3U		size=1U		ver=1U	
Receive								
w[0]	result	 	svc=1U	 	size=1U		ver=1U	

10.6.34 sc_rm_partition_static()

Send								
w[0]	func=3U		svc=3U	I	size=2U		ver=1U	
w[1]	undefined	 	undefined	 	did	 	pt	
Receive								
w[0]	err	 	svc=1U	 	size=1U		ver=1U	

10.6.35 sc_rm_partition_lock()

Send								
w[0]	func=4U	ı	svc=3U	ı	size=2U	I	ver=1U	
w[1]	undefined		undefined	I	undefined	l 	pt	
Receive								
w[0]w	err		svc=1U	I	size=1U	I	ver=1U	- 1

10.6.36 sc_rm_get_partition()

Send								
w[0]	func=5U	I	svc=3U	I	size=1U	I	ver=1U	- 1
Receive								
w[0]	err	I	svc=1U		size=2U		ver=1U	
w[1]	undefined	I	undefined	I	undefined	ı	pt	1

10.6.37 sc_rm_set_parent()

Send								
w[0]	func=6U	ı	svc=3U	l	size=2U	ı	ver=1U	I
w[1]	undefined	 	undefined		pt_parent	l	pt	
Receive								
w[0]	err		svc=1U	ı	size=1U	 	ver=1U	I

10.6.38 sc_rm_move_all()

Send								
w[0]	func=7U	ı	svc=3U	l	size=2U		ver=1U	
w[1]	move_pads		move_rsrc	I	pt_dst 	I	pt_src	I
Receive								
w[0]	err	 	svc=1U	 	size=1U	 	ver=1U	

10.6.39 sc_rm_assign_resource()

Send								
w[0]	func=8U	I	svc=3U	ı	size=2U	I	ver=1U	I
w[1]	undefined	 	pt			resource		
Receive								
w[0]	err	 	svc=1U	 	size=1U	 	ver=1U	

10.6.40 sc_rm_set_resource_movable()

Send								
w[0]	func=9U	I	svc=3U	I	size=3U	ı	ver=1U	I
w[1]	resc	ource_	lst	I	resc	ource_:	fst	I
w[2]	undefined	ı	undefined		undefined		movable	
Receive								
w[0]	err	ı	svc=1U		size=1U		ver=1U	

10.6.41 sc_rm_set_subsys_rsrc_movable()

Send								
w[0]	func=28U	I	svc=3U	I	size=2U	l	ver=1U	
w[1]	undefined	I	movable	I		resource		
Receive								
w[0]w	err	1	svc=1U	1	size=1U	1	ver=1U	1

10.6.42 sc_rm_set_master_attributes()

Send								
w[0]	func=10U	ı	svc=3U	ı	size=3U	ı	ver=1U	
w[1]	pa	I	sa	I	r	esourc	e 	
w[2]	undefined	I	undefined	I	undefined	ı	smmu_bypass	
Receive								
w[0]	err	 	svc=1U		size=1U		ver=1U	

10.6.43 sc_rm_set_master_sid()

Send								
w[0]	func=11U	 	svc=3U		size=2U	l	ver=1U	
w[1]		sid		I		resource		
Receive								
w[0]	err	I	svc=1U	ı	size=1U	ı	ver=1U	

10.6.44 sc_rm_set_peripheral_permissions()

Send								
w[0]	func=12U	I	svc=3U	I	size=2U	I	ver=1U	
w[1]	perm	l	pt	 		resource		
Receive								
w[0]	err	 	svc=1U	 	size=1U	 	ver=1U	I

10.6.45 sc_rm_is_resource_owned()

Send								
w[0]	func=13U	ı	svc=3U	ı	size=2U	I	ver=1U	I
w[1]	undefined	l	undefined	ı		resource		
Receive								
	result		svc=1U		size=1U		 ver=1U	
W[O]		' 	3 4 C - 1 O	'	3126-10	 		

10.6.46 sc_rm_get_resource_owner()

Send								
w[0]	func=33U		svc=3U	 	size=2U		ver=1U	
w[1]	undefined	 	undefined		r	esource		I
Receive								
w[0]	err	l	svc=1U	ı	size=2U		ver=1U	
w[1]	undefined	 	undefined	ı	undefined		pt	

10.6.47 sc_rm_is_resource_master()

Send								
w[0]	func=14U	I	svc=3U		size=2U	 	ver=1U	
w[1]	undefined	ı	undefined	l		resource		
Receive								
w[0] w	result	I	svc=1U	I	size=1U	I	ver=1U	1

10.6.48 sc_rm_is_resource_peripheral()

Send								
w[0]	func=15U	I	svc=3U		size=2U	l	ver=1U	
w[1]	undefined	 	undefined			resource		
Receive								
w[0]	result		svc=1U		size=1U	 	ver=1U	

10.6.49 sc_rm_get_resource_info()

Send								
w[0]	func=16U	I	svc=3U	ı	size=2U	I	ver=1U	I
w[1]	undefined		undefined	 	1	esource		
Receive								
[0]w	err	ı	svc=1U	l	size=2U	l	ver=1U	
w[1]	undefined		undefined	 		sid		I

10.6.50 sc_rm_memreg_alloc()

func=17U		svc=3U		size=5U	I	ver=1U	
		_		, ,			
		addr_	start	(LSW)			
		addr.	_end (MSW)			ı
err	ı	svc=1U	l				
undefined	 	undefined	 				
	err	err	addraddraddraddraddraddraddraddr	addr_start addr_start addr_end (addr_end (addr_start (MSW) addr_start (LSW) addr_end (MSW) addr_end (LSW) err svc=1U size=2U	addr_start (MSW) addr_start (LSW) addr_end (MSW) addr_end (LSW) err svc=1U size=2U	addr_start (LSW) addr_end (MSW) addr_end (LSW) err svc=1U size=2U ver=1U

10.6.51 sc_rm_memreg_split()

Send								
					size=6U			I
w[1]				start				1
w[2]			_	start	(LSW)			- 1
w[3]			addr	_end (MSW)			
w[4]	addr_end (LSW)							- 1
					undefined	ı	mr	I
Receive								
w[0]					size=2U			- 1
					undefined			I

10.6.52 sc_rm_memreg_frag()

Send								
w[0]	func=32U	ı	svc=3U		size=5U	ı	ver=1U	
w[1]			addr_	start	(MSW)			
w[2]			addr_		(LSW)			
w[3]			addr.	_end (
w[4]				_end (
Receive								
					size=2U	'		
					undefined			

10.6.53 sc_rm_memreg_free()

Send								
w[0]	func=18U		svc=3U	 	size=2U		ver=1U	I
w[1]	undefined	I	undefined	I	undefined	ı	mr	ı
Receive								
w[0] w	err	I	svc=1U	1	size=1U	- 1	ver=1U	-

10.6.54 sc_rm_find_memreg()

Send								
w[0]	func=30U	I	svc=3U	I	size=5U	ı	ver=1U	
w[1]			addr_	start	(MSW)			
w[2]			addr_	start	(LSW)			
w[3]	addr_end (MSW)							
w[4]			addr	_end (LSW)			
Receive								
w[0]	err		svc=1U		size=2U	l	ver=1U	
w[1]	undefined	 	undefined	 	undefined	l	mr	

10.6.55 sc_rm_assign_memreg()

Send								
w[0]	func=19U	I	svc=3U		size=2U		ver=1U	
w[1]	undefined	ı	undefined	I	mr	l	pt	
Receive								
receive								
w[0]	err	l 	svc=1U	 	size=1U		ver=1U	

10.6.56 sc_rm_set_memreg_permissions()

Send								
w[0]	func=20U	ı	svc=3U	l	size=2U		ver=1U	I
w[1]	undefined		perm		pt		mr	
Receive								
w[0]	err	 	svc=1U	 	size=1U	I	ver=1U	

10.6.57 sc_rm_set_memreg_iee()

Send								
w[0]	func=34U	I	svc=3U	I	size=2U	I	ver=1U	-
w[1]	undefined		rmsg		det		mr	
Receive								
w[0]	err	 	svc=1U	 	size=1U		ver=1U	

10.6.58 sc_rm_is_memreg_owned()

Send								
w[0] w	func=21U		svc=3U	I	size=2U	I	ver=1U	1
w[1]	undefined		undefined	1	undefined	ı	mr	
D								
Receive								
w[0]	result	l 	svc=1U		size=1U	l 	ver=1U	

10.6.59 sc_rm_get_memreg_info()

Send								
w[0]	func=22U	ı	svc=3U	I	size=2U	I	ver=1U	
w[1]	undefined	l	undefined	ı	undefined	ı	mr	
Receive								
w[0]	err		svc=1U		size=5U		ver=1U	
w[1]			addr_	start	(MSW)			
w[2]			addr_	start	(LSW)			ı
w[3]			addr	_end (MSW)			I
w[4]	addr_end (LSW)							

10.6.60 sc_rm_assign_pad()

Send								
w[0]	func=23U	I	svc=3U	ı	size=2U	I	ver=1U	
w[1]	undefined	l 	pt	 		pad		I
Receive								
w[0]	err	-	svc=1U		size=1U	1	ver=1U	

10.6.61 sc_rm_set_pad_movable()

Send								
w[0]	func=24U	I	svc=3U	ı	size=3U	I	ver=1U	
w[1]		pad_ls	t 			pad_fst	: 	
w[2]	undefined	 	undefined		undefined	 	movable	I
Receive								
w[0]	err		svc=1U		size=1U		ver=1U	

10.6.62 sc_rm_is_pad_owned()

Send								
w[0]w	func=25U	I	svc=3U	I	size=2U	1	ver=1U	- 1

w[1]	undefined	I	undefined	1		pad		I
Receive								
w[0]	result	 	svc=1U	 	size=1U	 	ver=1U	
10.6.63 so	c_rm_dump()							
Send								
w[0] 	func=27U	 	svc=3U	 	size=1U 	 	ver=1U 	
Receive								
	undefined	 	svc=1U		size=1U	 	ver=1U	
10.6.64 so	c_timer_set_wd	og_tim	eout()					
Send								
w[0]	func=1U		svc=5U	l	size=2U	 	ver=1U	
w[1]			t	imeout	: 			
Receive								
w[0]	err		svc=1U		size=1U		ver=1U	
10.6.65 so	c_timer_set_wd	og_pre	_timeout()					
Send								
w[0]	func=12U	l	svc=5U	ı	size=2U		ver=1U	I
w[1]			pre	e_timed	out 			
Receive								
w[0]	err	 	svc=1U	 I	size=1U		ver=1U	
10.6.66 sc	c_timer_set_wd	og_win	idow()					
Send								
	func=19U			 I	size=2U		ver=1U	
w[1]			ī	vindow				
Receive								
	err		svc=1U				 ver=1U	 I

10.6.67 sc_timer_start_wdog()

Send								
w[0]	func=2U		svc=5U	ı	size=2U	ı	ver=1U	I
w[1]	undefined	 	undefined		undefined	 	lock	
Receive								
w[0]	err	 	svc=1U	 	size=1U	 	ver=1U	

10.6.68 sc_timer_stop_wdog()

Send								
w[0]	func=3U		svc=5U	ı	size=1U		ver=1U	
Receive								
w[0]	err		svc=1U		size=1U		ver=1U	

10.6.69 sc_timer_ping_wdog()

Send								
w[0]	func=4U		svc=5U	 	size=1U		ver=1U	
Receive								
w[0]	err	 	svc=1U	 	size=1U	 	ver=1U	

10.6.70 sc_timer_get_wdog_status()

Send								
w[0]	func=5U	l	svc=5U	l	size=1U	I	ver=1U	
Receive								
w[0]	err	l	svc=1U	l	size=4U	ı	ver=1U	
w[1]				timeout	=			-
w[2]			ma	x_time	out			
w[3]	remaining_time							

10.6.71 sc_timer_pt_get_wdog_status()

Send								
w[0]	func=13U		svc=5U	I	size=2U		ver=1U	
	undefined							
Receive								
	err	I	svc=1U	ı	size=4U	ı	ver=1U	
w[1]				timeou	t 			
w[2]			rema	ining_	time			
w[3]	undefined							
	func=10U		svc=5U	 	size=2U	 	ver=1U	
10.6.72 s	c_timer_set_wd	og_ac	tion()					
Send								
w[0] 	func=10U			 	size=2U		ver=1U 	
w[1] 	undefined	 	undefined		action		pt 	
Receive								
Receive w[0]	err	 	svc=1U	 	size=1U	 	ver=1U	
w[0]	err c_timer_set_rtc	time(size=1U	l	ver=1U	
10.6.73 so	c_timer_set_rtc func=6U) svc=5U		size=3U	 	ver=1U	
10.6.73 so	c_timer_set_rtc func=6U)		size=3U	 	ver=1U	
10.6.73 so	c_timer_set_rtc func=6U		svc=5U	1	size=3U		ver=1U	
10.6.73 so	c_timer_set_rtc func=6U		svc=5U	1	size=3U		ver=1U	

10.6.74 sc_timer_get_rtc_time()

Send							
w[0]w	func=7U	svc=5U	1	size=1U	-	ver=1U	

Receive

[0]w	err		svc=1U	I	size=3U	I	ver=1U	
w[1]	day	ı	mon	ı		year		
w[2]	undefined	ı	sec	ı	min	ı	hour	

10.6.75 sc_timer_get_rtc_sec1970()

Send								
w[0]	func=9U	 	svc=5U	 	size=1U	 	ver=1U	
Receive								
w[0]	err		svc=1U	 	size=2U	 	ver=1U	I
w[1]				sec				I

10.6.76 sc_timer_set_rtc_alarm()

Send								
w[0]	func=8U	ı	svc=5U	ı	size=3U	ı	ver=1U	I
w[1]	day		mon			year		ا
w[2]	undefined	l 	sec	I	min	 	hour	
Receive								
w[0]	err	l	svc=1U	 	size=1U		ver=1U	

10.6.77 sc_timer_set_rtc_periodic_alarm()

Send								
w[0]	func=14U		svc=5U	ı	size=2U		ver=1U	
w[1]				sec				
Receive								
w[0]	err	 	svc=1U	l	size=1U		ver=1U	

| w[1] |

| w[2] |

Receive

10.6.78 sc_timer_cancel_rtc_alarm()

Send								
00114								
w[0]	func=15U	 	svc=5U	 	size=1U	 	ver=1U	
Receive								
w[0]	err	 	svc=1U	 	size=1U	 	ver=1U	
10.6.79 sc	_timer_set_rtc	_calb()						
Send								
	func=11U				size=2U		ver=1U	
					undefined			
w[0] 		 	svc=1U		size=1U	 	ver=1U	
w[0]		 	svc=1U			l	ver=1U	
10.6.80 sc	err _timer_set_sys	sctr_ala	svc=1U arm() svc=5U	 	size=1U	 	ver=1U	
10.6.80 sc	err _timer_set_sys	sctr_ala	svc=1U arm() svc=5U	 	size=1U	 	ver=1U	
10.6.80 sc	err _timer_set_sys	sctr_ala	svc=1U arm() svc=5U tio	 	size=1U size=3U	 	ver=1U	
10.6.80 sc	err _timer_set_sys	sctr_ala	svc=1U arm() svc=5U tio	l l cks (M	size=1U size=3U	 	ver=1U	

w[0] w	err	1	svc=1U	1	size=1U	1	ver=1U	

ticks (MSW)

ticks (LSW)

10.6.82 sc_timer_cancel_sysctr_alarm()

Send								
w[0]	func=18U		svc=5U		size=1U		ver=1U	
Receive								
w[0]	err	 	svc=1U	I	size=1U		ver=1U	I

10.6.83 sc_pad_set_mux()

Send								
w[0]	func=1U		svc=6U		size=3U		ver=1U	
w[1]	config		mux	I		pad		
w[2]	undefined		undefined		undefined	l	iso	
Receive								
w[0]	err		svc=1U	 	size=1U	 	ver=1U	

10.6.84 sc_pad_get_mux()

Send								
w[0]	func=6U	I	svc=6U	ı	size=2U	I	ver=1U	
w[1]	undefined	 	undefined			pad		
Receive								
w[0]w	err	1	svc=1U	I	size=2U	1	ver=1U	-

10.6.85 sc_pad_set_gp()

| w[1] | undefined | iso |

Send								
w[0]	func=2U	ı	svc=6U	I	size=3U	l	ver=1U	
w[1]				ctrl				
w[2]	undefined		undefined	l		pad		
Receive								
w[0]	err	 	svc=1U	l	size=1U		ver=1U	I

config |

10.6.86 sc_pad_get_gp()

Send						
w[0]	func=7U	svc=6U		size=2U	I	ver=1U
w[1]	undefined	undefined	 		pad	
Receive						
w[0]	err	svc=1U		size=2U	I	ver=1U
w[1]			ctrl			
10.6.87	sc_pad_set_wakeu	p()				
Send						
w[0]	func=4U	svc=6U		size=2U		ver=1U
w[1]	undefined	wakeup			pad	
Receive						
				size=1U		111
10.6.88	sc_pad_get_wakeu	p()	 	5126-10		ver=1U
1 0.6.88 Send	sc_pad_get_wakeu	p()				
Send w[0]	sc_pad_get_wakeu	p() svc=6U	 	size=2U		ver=1U
10.6.88 Send	sc_pad_get_wakeu	p() svc=6U	 	size=2U		ver=1U
10.6.88 Send w[0]	sc_pad_get_wakeu	p() svc=6U	 	size=2U		ver=1U
0.6.88 Send w[0] w[1]	sc_pad_get_wakeu	p() svc=6U undefined		size=2U		ver=1U
10.6.88 Send	sc_pad_get_wakeu func=9U undefined err	p() svc=6U undefined		size=2U	pad	ver=1U
W[0] w[1] Receive w[0]	func=9U undefined err undefined	p() svc=6U undefined svc=1U	 	size=2U	pad	ver=1U ver=1U
10.6.88 Send w[0] w[1] Receive	sc_pad_get_wakeu func=9U undefined err	p() svc=6U undefined svc=1U	 	size=2U	pad	ver=1U ver=1U
W[0] W[1] Receive W[0] W[1]	func=9U undefined err undefined	p() svc=6U undefined svc=1U	 	size=2U	pad	ver=1U ver=1U
W[0] W[1] W[0] W[1] W[1] W[1] W[1]	func=9U undefined err undefined	p() svc=6U undefined svc=1U undefined		size=2U size=2U undefined	pad	ver=1U ver=1U
0.6.88 Send	func=9U undefined err undefined sc_pad_set_all()	p() svc=6U undefined svc=1U undefined	 	size=2U size=2U undefined size=4U	pad	ver=1U ver=1U wakeup
0.6.88 Send	func=9U undefined err undefined sc_pad_set_all()	svc=6U undefined svc=1U undefined svc=6U	 	size=2U size=2U undefined size=4U	 	ver=1U ver=1U wakeup
0.6.88 Send	func=9U undefined err undefined sc_pad_set_all()	svc=6U undefined svc=1U undefined svc=6U undefined	 	size=2U size=2U undefined size=4U	pad	ver=1U ver=1U wakeup ver=1U
W[0]	sc_pad_get_wakeu func=9U undefined err undefined sc_pad_set_all() func=5U config	svc=6U undefined svc=1U undefined svc=6U undefined	 	size=2U size=2U undefined size=4U	pad	ver=1U ver=1U wakeup ver=1U

10.6.90 sc_pad_get_all()

	func=10U	l	svc=6U	T	size=2U		ver=1U	
			undefined			pad		
Receive								
w[0]	err	I	svc=1U	ı	size=3U	ı	ver=1U	
w[1]				ctrl				
w[2]	wakeup				config	I	mux	
Send								
Send								
	func=15U	 	svc=6U		size=3U	 	ver=1U	
w[0]	func=15U			 val	size=3U	 	ver=1U	
w[0] w[1]				val	size=3U	l pad	ver=1U	
w[0] w[1]				val	size=3U		ver=1U	

Send

w[0]	func=16U	1	svc=6U		size=2U	I	ver=1U	- 1
w[1]	undefined		undefined	I		pad		
Receive								
w[0]	err	ı	svc=1U	ı	size=2U	ı	ver=1U	
w[1]				val				

10.6.93 sc_pad_config()

Send

w[0]	func=17U	1	svc=6U	I	size=3U	I	ver=1U	- 1
w[1]				val				

w[2]	undefined	 	undefined			pad		I
Receive								
w[0]	err		svc=1U	 	size=1U	I	ver=1U	

10.6.94 sc_pad_set_gp_28fdsoi()

Send								
w[0]	func=11U	I	svc=6U	ı	size=2U	ı	ver=1U	
w[1]	ps	I	dse	I		pad		
Receive								
w[0]	err		svc=1U	 	size=1U	 	ver=1U	

10.6.95 sc_pad_get_gp_28fdsoi()

Send								
w[0]	func=12U		svc=6U	 	size=2U		ver=1U	
w[1]	undefined	ı	undefined	I		pad		- 1
Receive								
w[0]	err	 I	svc=1U	 I	size=2U	 	ver=1U	
w[1]	undefined		undefined	 	ps		dse	

10.6.96 sc_pad_set_gp_28fdsoi_hsic()

Send								
w[0]	func=3U	ı	svc=6U		size=3U		ver=1U	
w[1]	pus	I	dse			pad		
w[2]	undefined	l	pue		pke		hys	
Receive								
w[0]	err	 	svc=1U		size=1U	 	ver=1U	

10.6.97 sc_pad_get_gp_28fdsoi_hsic()

Send								
w[0]	func=8U	ı	svc=6U	I	size=2U	I	ver=1U	
w[1]	undefined	ı	undefined	I		pad		
Receive								
w[0]	err	ı	svc=1U	I	size=3U	ı	ver=1U	
w[1]	pke	ı	hys	I	pus	I	dse	
w[2]	undefined	ı	undefined	ı	undefined	ı	pue	

10.6.98 sc_pad_set_gp_28fdsoi_comp()

Send								
w[0]	func=13U		svc=6U		size=3U	l	ver=1U	
w[1]	rasrcp		compen	l		pad		
w[2]	psw_ovr	ı	nasrc_sel	ı	fastfrz	ı	rasrcn	I
Receive								
w[0]	err		svc=1U	 	size=1U	 	ver=1U	

10.6.99 sc_pad_get_gp_28fdsoi_comp()

Send								
w[0]	func=14U		svc=6U	ı	size=2U		ver=1U	I
w[1]	undefined		undefined	I		pad		
Receive								
w[0]	err	I	svc=1U		size=3U	 	ver=1U	I
w[1]	nasrc	l	rasrcn	ı	rasrcp	ı	compen	
w[2]	psw_ovr	l	compok	ı	nasrc_sel	ı	fastfrz	I

10.6.100 sc_misc_set_control()

Send								
[0]w	func=1U	1	svc=7U	1	size=4U	1	ver=1U	-

Receive	undefined			ctrl			
w[3] Receive	undefined						
Receive	undefined			val			
		 	undefined	l		resource	
w[0]							
	err	 	svc=1U	 	size=1U	 	ver=1U
10.6.101 s	c_misc_get_co	ntrol()					
Send							
w[0]			svc=7U		size=3U		ver=1U
w[1]				ctrl			
w[2]	undefined	 	undefined	 	:	resource	
Receive							
w[0]	err		svc=1U		size=2U		ver=1U
 w[1]				val			
10.6.102 s	c_misc_set_ma	ax_dm	a_group()				
Send							
			svc=7U	1	size=2U	1	
w[0]	func=4U						ver=1U
	func=4U undefined		undefined	 		<u>'</u> 	ver=1U pt
			undefined				

| w[0] | err | svc=1U | size=1U | ver=1U |

10.6.104 sc_misc_debug_out()

Send								
w[0]	func=10U		svc=7U		size=2U		ver=1U	I
w[1]	undefined		undefined		undefined	l	ch	
Receive								
w[0]	undefined		svc=1U	l	size=1U	l	ver=1U	I

10.6.105 sc_misc_waveform_capture()

Send								
w[0]	func=6U		svc=7U		size=2U		ver=1U	I
w[1]	undefined	ı	undefined		undefined	l	enable	
Receive								
w[0]	err	 	svc=1U	 	size=1U	 	ver=1U	

10.6.106 sc_misc_build_info()

Send								
w[0]	func=15U	ı	svc=7U	ı	size=1U	ı	ver=1U	I
Receive								
w[0]	undefined	ı	svc=1U	ı	size=3U	l	ver=1U	
w[1]				build				
w[2]				commit				ا

10.6.107 sc_misc_api_ver()

Send								
w[0]	func=35U		svc=7U		size=1U		ver=1U	
Receive								
w[0]	undefined	ı	svc=1U	ı	size=3U	ı	ver=1U	
w[1]		cl_min		I		cl_maj		
w[2]		sv_min				sv_maj		

10.6.108 sc_misc_unique_id()

Send								
w[0]	func=19U		svc=7U		size=1U		ver=1U	
Receive								
w[0]	undefined	l	svc=1U	ı	size=3U	l	ver=1U	
w[1]				id_l				
w[2]				id_h				

10.6.109 sc_misc_set_ari()

Send								
w[0]	func=3U	I	svc=7U	I	size=3U	I	ver=1U	ı
w[1]	resource_mst			ı	resource			I
w[2]	undefined	I	enable	I		ari		ı
Receive								
w[0]	err	I	svc=1U	I	size=1U		ver=1U	-

10.6.110 sc_misc_boot_status()

Send								
w[0]	func=7U		svc=7U	ı	size=2U	ı	ver=1U	I
w[1]	undefined	I	undefined	I	undefined	ı	status	I

10.6.111 sc_misc_boot_done()

Send								
w[0]	func=14U	1	svc=7U	1	size=2U	I	ver=1U	
w[1]	undefined	I	undefined			cpu		
Receive								
w[0]	err		svc=1U	l 	size=1U	I	ver=1U	I

10.6.112 sc_misc_otp_fuse_read()

1 [0]w	func=11U		svc=7U		size=2U		ver=1U
w[1] 				word 			
Receive							
w[0]							
w[1]				val			
10.6.113 Send	sc_misc_otp_fu	ise_wr	ite()				
	func=17U	l	svc=7U		size=3U	l	ver=1U
w[1]				word			
w[2]				val			
Receive							
	err		svc=1U		size=1U		ver=1U
10.6.114 Send	sc_misc_set_te				size=3U	I	ver=1U
 w[0]							
w[0] 		celsiu	IS	1	r	esource	
w[0] w[1]		celsiu	s 		r	esource	temp
w[0] w[1]		celsiu	s 		r	esource	

10.6.115 sc_misc_get_temp()

Send								
w[0]	func=13U		svc=7U		size=2U	I	ver=1U	
w[1]	undefined		temp		:	resource		
Receive								
w[0]	err		svc=1U	I	size=2U	I	ver=1U	
w[1]	undefined	 	tenths			celsius		

10.6.116 sc_misc_get_boot_dev()

Send								
	 func=16U						1II	
					5126-10			
Receive								
w[0]	undefined		svc=1U	 	size=2U	l	ver=1U	
w[1]	undefined		undefined	ı		dev		

10.6.117 sc_misc_get_boot_type()

Send								
w[0]	func=33U	 	svc=7U	 	size=1U		ver=1U	
Receive								
w[0]	err	I	svc=1U	I	size=2U		ver=1U	
w[1]	undefined		undefined		undefined	 	type	

10.6.118 sc_misc_get_boot_container()

Send								
w[0]	func=36U		svc=7U		size=1U	 	ver=1U	
Receive								
Receive								
w[0]w	err	I	svc=1U	I	size=2U	1	ver=1U	1
w[1]	undefined		undefined		undefined		idx	

10.6.119 sc_misc_get_button_status()

Send								
w[0]	func=18U	I	svc=7U	I	size=1U		ver=1U	
Receive								
w[0]	undefined	I	svc=1U		size=2U	l	ver=1U	
w[1]	undefined	I	undefined	ı	undefined	ı	status	1

10.6.120 sc_misc_rompatch_checksum()

Send								
w[0]	func=26U		svc=7U	 	size=1U		ver=1U	
Receive								
w[0]	err	I	svc=1U	I	size=2U		ver=1U	
w[1]			C.	hecksur	n			

10.6.121 sc_misc_board_ioctl()

Send								
w[0]	func=34U	I	svc=7U	I	size=4U	I	ver=1U	
w[1]				parm1				1
w[2]				parm2				
w[3]				parm3				
Receive								
	err							
w[1]				parm1				
w[2]				parm2				1
w[3]				parm3				

10.6.122 sc_seco_image_load()

Send | w[0] | func=1U | svc=9U | size=7U | ver=1U | w[1] | addr_src (MSW) addr_src (LSW) | w[2] | | w[3] | addr_dst (MSW) | w[4] | addr_dst (LSW) | w[5] | len | w[6] | undefined | undefined | fw Receive | w[0] | err | svc=1U | size=1U | ver=1U

10.6.123 sc_seco_authenticate()

Send								
w[0]	func=2U		svc=9U		size=4U		ver=1U	
w[1]			addr	(MSV	√)			
w[2]			addr	(LSV	√)			
w[3]	undefined	I	undefined	I	undefined	ı	cmd	ı
Receive								
w[0]	err	l 	svc=1U		size=1U	l 	ver=1U	

10.6.124 sc_seco_enh_authenticate()

Send								
w[0]	func=24U	ı	svc=9U	ı	size=6U		ver=1U	1
w[1]				dr (MS	W)			
w[2]				dr (LS	W)			
w[3]				mask1				
w[4]				mask2				
w[5]	undefined		undefined	I	undefined			
D :								
Receive								
w[0]	err	 	svc=1U	 	size=1U	I	ver=1U	

10.6.125 sc_seco_forward_lifecycle()

Send								
w[0]	func=3U		svc=9U	I	size=2U		ver=1U	
w[1]				change				
Receive								
w[0] w	err		svc=1U		size=1U		ver=1U	
w[0]	err 	I	svc=1U	I	size=1U 	I	ver=1U	

10.6.126 sc_seco_return_lifecycle()

Send								
		I	svc=9U	I	size=3U	1	ver=1U	
w[1]			ad	dr (MSW)				-
w[2]				dr (LSW)				
Receive								
			svc=1U					
10.6.127 s	c_seco_comm							
Send	func=5U	nit()	svc=9U					
Send w[0] w[1]	func=5U	nit()		 info				
Send w[0] w[1] Receive	func=5U	nit()		 				
Send	func=5U	nit()		 info	size=2U	 		

10.6.128 sc_seco_attest_mode()

Send								
w[0]	func=6U	l	svc=9U	ı	size=2U	ı	ver=1U	I
w[1]				mode				
Receive								
w[0]	err	 	svc=1U		size=1U	 	ver=1U	

10.6.129 sc_seco_attest()

Send								
w[0]	func=7U	I	svc=9U	I	size=3U	I	ver=1U	
w[1]			noı	nce (MS	SW)			I
w[2]			noı	nce (LS	SW)			I
Receive								
w[0]	err	 	svc=1U	l	size=1U	I	ver=1U	

10.6.130 sc_seco_get_attest_pkey()

Send								
w[0]	func=8U	l	svc=9U	ı	size=3U	l	ver=1U	I
w[1]			addr	(MSW)				I
w[2]			addr	(LSW)				
Receive								
w[0]	err		svc=1U		size=1U		ver=1U	

10.6.131 sc_seco_get_attest_sign()

Send								
w[0]	func=9U	I	svc=9U	l	size=3U	I	ver=1U	
w[1]			ado	dr (MSW)			
w[2]			ado	dr (LSW)			

Receive								
w[0]	err	1	svc=1U	1	size=1U	-	ver=1U	- 1

10.6.132 sc_seco_attest_verify()

Send								
w[0]	func=10U	I	svc=9U	I	size=3U		ver=1U	1
w[1]			addr	(MSW)				I
w[2]			addr	(LSW)				I
Receive								
w[0]	err	l	svc=1U		size=1U	I	ver=1U	

10.6.133 sc_seco_gen_key_blob()

Send								
w[0]	func=11U	ı	svc=9U		size=7U	ı	ver=1U	
w[1]			load	_addr	(MSW)			
w[2]			load	_addr	(LSW)			

w[3]			expor	t_addr	(MSW)			
w[4]			expor	t_addr	(LSW)			
w[5]				id				
w[6]	undefined	 	undefined	l		max_size		
Receive								
w[0]	err	l	svc=1U	ı	size=1U		ver=1U	

10.6.134 sc_seco_load_key()

S	end	

w[0]	func=12U	l	svc=9U	l	size=4U	l	ver=1U	I
w[1]			addı	(MSW)				I
w[2]			addı	(LSW)				
w[3]				id				

Receive

[0]w	err	1	svc=1U	- 1	size=1U	ver=1U	-

10.6.135 sc_seco_get_mp_key()

Send

w[0]	func=13U	ı	svc=9U	I	size=4U	 	ver=1U	
w[1]			dst_	addr	(MSW)			
w[2]			dst_	addr	(LSW)			
w[3]	undefined	 	undefined	 		dst_size		
w[3] Receive	undefined	 	undefined	I		dst_size		l

10.6.136 sc_seco_update_mpmr()

Send

w[0]	func=14U	 	svc=9U	I	size=4U	 	ver=1U	
w[1]			addr	(MSW)				
w[2]			addr	(LSW)				

w[3]	undefined	 	undefined	 	lock	 	size	ا
Receive								
 w[0]	err	 	svc=1U	 	size=1U	 	ver=1U	
10.6.137	sc_seco_get_m	p_sign	()					
Send								
w[0]	func=15U	 	svc=9U	I	size=6U	l	ver=1U	I
 w[1]			_	addr (1				
 w[2]				addr (1				
w[3]			dst_a	addr (1	MSW)			
 w[4]			dst_;	addr (1	LSW)			
 w[5]		st_siz		 		sg_size		
Receive								
	err err sc_seco_build_i		svc=1U	 	size=1U	 	ver=1U	
10.6.138			svc=1U	 	size=1U	l	ver=1U	
10.6.138	sc_seco_build_i		svc=1U	l 	size=1U	I	ver=1U	
10.6.138 s	sc_seco_build_i	info()						
10.6.138 s	sc_seco_build_i	info()	svc=9U		size=1U		ver=1U	
10.6.138 s Send w[0] Receive	sc_seco_build_i func=16U undefined	info()	svc=9U svc=1U		size=1U size=3U		ver=1U	
10.6.138 s Send w[0] Receive	sc_seco_build_i	info()	svc=9U svc=1U		size=1U size=3U		ver=1U	
10.6.138 s Send w[0] Receive w[0]	sc_seco_build_i func=16U undefined	info()	svc=9U svc=1U	version	size=1U size=3U		ver=1U	
10.6.138 s Send w[0] Receive w[0] w[1] w[2]	sc_seco_build_i func=16U undefined	info()	svc=9U svc=1U	version	size=1U size=3U		ver=1U	
10.6.138 s Send w[0] Receive w[0] w[1] w[2]	sc_seco_build_i func=16U undefined	info()	svc=9U svc=1U	version	size=1U size=3U		ver=1U	
10.6.138 s Send w[0] Receive w[0] w[1] w[2]	sc_seco_build_i func=16U undefined	info()	svc=9U svc=1U	version	size=1U size=3U		ver=1U	
10.6.138 s Send w[0] Receive w[0] w[1] w[2] 10.6.139 s	sc_seco_build_i func=16U undefined sc_seco_chip_i	info()	svc=9U svc=1U	version	size=1U size=3U		ver=1U	
10.6.138 s Send w[0] Receive w[0] w[1] w[2]	sc_seco_build_i func=16U undefined sc_seco_chip_il	info()	svc=9U svc=1U	version	size=1U size=3U		ver=1U	

w[2]		uid_h	
w[3]	monotonic		lc

10.6.140 sc_seco_enable_debug()

S	end 								
I	w[0]	func=18U	l	svc=9U	ı	size=3U	I	ver=1U	I
1	w[1]			addr	(MSW)				
I	w[2]			addr	(LSW)				I
R	eceive								
-									
	w[0] 	err 	 	svc=1U 	 	size=1U	I	ver=1U 	

10.6.141 sc_seco_get_event()

Send								
w[0]	func=19U	I	svc=9U	ı	size=2U	I	ver=1U	I
w[1]	undefined		undefined		undefined		idx	
Receive								

w[0] w	err	svc=1U		size=2U	ver=1U	
w[1]			event			1

10.6.142 sc_seco_fuse_write()

Send
w[0]	func=20U	svc=9U	size=3U	ver=1U
w[1]	addr (MSW)			
w[2]	addr (LSW)			
Receive				
w[0]	err	svc=1U	size=1U	ver=1U

10.6.143 sc_seco_patch()

Send								
w[0]	func=21U		svc=9U	I	size=3U		ver=1U	
w[1]			addr	(MSW)				
w[2]			addr	(LSW)				
Receive								
w[0]	err	I	svc=1U	I	size=1U	1	ver=1U	- 1

10.6.144 sc_seco_set_mono_counter_partition()

Send								
w[0]	func=28U		svc=9U	I	size=2U		ver=1U	
w[1]	undefined		undefined	ı		she		I
Receive								
w[0]	err		svc=1U		size=2U	l	ver=1U	
w[1]	undefined	1	undefined	I		she		- 1

10.6.145 sc_seco_set_fips_mode()

Send								
w[0]	func=29U	ı	svc=9U	I	size=2U	ı	ver=1U	I
w[1]	undefined	l	undefined		undefined	l	mode	
Receive								
w[0]	err	l	svc=1U	 	size=2U	ı	ver=1U	
w[1]				reason				

10.6.146 sc_seco_start_rng()

Send								
w[0] w	func=22U	I	svc=9U	I	size=1U	I	ver=1U	1
Receive								
w[0] w	err	l	svc=1U		size=2U	l	ver=1U	
w[1]				status				

10.6.147 sc_seco_sab_msg()

Send								
w[0]	func=23U	ı	svc=9U	ı	size=3U	l	ver=1U	
w[1]			addr	(MSW)				I
w[2]			addr	(LSW)				
Receive								
w[0]	err	l 	svc=1U	 	size=1U	 	ver=1U	

10.6.148 sc_seco_secvio_enable()

Send								
w[0]	func=25U		svc=9U		size=1U		ver=1U	
Receive								
w[0]	err	 	svc=1U	 	size=1U	l	ver=1U	I

10.6.149 sc_seco_secvio_config()

Send								
w[0]	func=26U	I	svc=9U	 	size=7U		ver=1U	l
w[1]				data0				I
w[2]				data1				
w[3]				data2				
w[4]				data3				
w[5]				data4				I
w[6]	undefined	ı	size	ı	access	ı	id	I
Receive								
w[0]	err	I	svc=1U		size=6U		ver=1U	
w[1]				data0				I
w[2]				data1				I
w[3]				data2				I
w[4]				data3				_ _
w[5]				data4				

10.6.150 sc_seco_secvio_dgo_config()

Send								
w[0]	func=27U	ı	svc=9U	ı	size=3U	l	ver=1U	1
w[1]				data				ı
w[2]	undefined	ı	undefined	l	access	 	id	1
Receive								
Veceive								
[0]w	err	I	svc=1U	l	size=2U		ver=1U	
w[1]				data				1

10.6.151 sc_irq_enable()

Send								
w[0]	func=1U		svc=8U	ı	size=3U	I	ver=1U	
w[1]				mask				
w[2]	enable	ı	group	ı		resource		ı
Receive								
w[0]	err	l	svc=1U	l	size=1U	I	ver=1U	

10.6.152 sc_irq_status()

Send								
w[0]	func=2U		svc=8U	I	size=2U		ver=1U	
w[1]	undefined		group			resource		
Receive								
w[0]	err		svc=1U		size=2U	l	ver=1U	
w[1]				status				

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Chapter 11

Module Index

11.1 Modules

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Chapter 12

File Index

12.1 File List

Here is a list of all documented files with brief descriptions:

platform/config/mx8dxl/pads.h
Header file used to configure SoC pad list
platform/main/ipc.h
Header file for the IPC implementation
platform/main/types.h
Header file containing types used across multiple service APIs
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Header file containing the public API for the System Controller (SC) Power Management (PM) func-
tion
platform/svc/rm/api.h
Header file containing the public API for the System Controller (SC) Resource Management (RM)
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Chapter 13

Module Documentation

13.1 IRQ: Interrupt Service

Module for the Interrupt (IRQ) service.

Macros

#define SC_IRQ_NUM_GROUP 7U
 Number of groups.

Typedefs

typedef uint8_t sc_irq_group_t

This type is used to declare an interrupt group.

typedef uint8_t sc_irq_temp_t

This type is used to declare a bit mask of temp interrupts.

• typedef uint8_t sc_irq_wdog_t

This type is used to declare a bit mask of watchdog interrupts.

• typedef uint8_t sc_irq_rtc_t

This type is used to declare a bit mask of RTC interrupts.

typedef uint8_t sc_irq_wake_t

This type is used to declare a bit mask of wakeup interrupts.

Functions

- sc_err_t sc_irq_enable (sc_ipc_t ipc, sc_rsrc_t resource, sc_irq_group_t group, uint32_t mask, sc_bool_t enable)

 This function enables/disables interrupts.
- sc_err_t sc_irq_status (sc_ipc_t ipc, sc_rsrc_t resource, sc_irq_group_t group, uint32_t *status)

This function returns the current interrupt status (regardless if masked).

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Defines for sc_irq_group_t

#define SC_IRQ_GROUP_TEMP 0U

Temp interrupts.

· #define SC IRQ GROUP WDOG 1U

Watchdog interrupts.

• #define SC_IRQ_GROUP_RTC 2U

RTC interrupts.

• #define SC_IRQ_GROUP_WAKE 3U

Wakeup interrupts.

#define SC_IRQ_GROUP_SYSCTR 4U

System counter interrupts.

#define SC IRQ GROUP REBOOTED 5U

Partition reboot complete.

#define SC IRQ GROUP REBOOT 6U

Partition reboot starting.

Defines for sc_irq_temp_t

#define SC_IRQ_TEMP_HIGH (1UL << 0U)

Temp alarm interrupt.

#define SC_IRQ_TEMP_CPU0_HIGH (1UL << 1U)

CPU0 temp alarm interrupt.

#define SC_IRQ_TEMP_CPU1_HIGH (1UL << 2U)

CPU1 temp alarm interrupt.

#define SC_IRQ_TEMP_GPU0_HIGH (1UL << 3U)

GPU0 temp alarm interrupt.

#define SC_IRQ_TEMP_GPU1_HIGH (1UL << 4U)

GPU1 temp alarm interrupt.

#define SC_IRQ_TEMP_DRC0_HIGH (1UL << 5U)

DRC0 temp alarm interrupt.

#define SC_IRQ_TEMP_DRC1_HIGH (1UL << 6U)

DRC1 temp alarm interrupt.

#define SC_IRQ_TEMP_VPU_HIGH (1UL << 7U)

DRC1 temp alarm interrupt.

#define SC_IRQ_TEMP_PMIC0_HIGH (1UL << 8U)

PMIC0 temp alarm interrupt.

#define SC_IRQ_TEMP_PMIC1_HIGH (1UL << 9U)

PMIC1 temp alarm interrupt.

#define SC_IRQ_TEMP_LOW (1UL << 10U)

Temp alarm interrupt.

#define SC_IRQ_TEMP_CPU0_LOW (1UL << 11U)

CPU0 temp alarm interrupt.

#define SC_IRQ_TEMP_CPU1_LOW (1UL << 12U)

CPU1 temp alarm interrupt.

#define SC_IRQ_TEMP_GPU0_LOW (1UL << 13U)

GPU0 temp alarm interrupt.

- #define SC_IRQ_TEMP_GPU1_LOW (1UL << 14U)
 GPU1 temp alarm interrupt.
- #define SC_IRQ_TEMP_DRC0_LOW (1UL << 15U)
 DRC0 temp alarm interrupt.
- #define SC_IRQ_TEMP_DRC1_LOW (1UL << 16U)

DRC1 temp alarm interrupt.

#define SC_IRQ_TEMP_VPU_LOW (1UL << 17U)

DRC1 temp alarm interrupt.

#define SC_IRQ_TEMP_PMIC0_LOW (1UL << 18U)

PMIC0 temp alarm interrupt.

• #define SC_IRQ_TEMP_PMIC1_LOW (1UL << 19U)

PMIC1 temp alarm interrupt.

• #define SC_IRQ_TEMP_PMIC2_HIGH (1UL << 20U)

PMIC2 temp alarm interrupt.

#define SC_IRQ_TEMP_PMIC2_LOW (1UL << 21U)

PMIC2 temp alarm interrupt.

Defines for sc_irq_wdog_t

#define SC_IRQ_WDOG (1U << 0U)
 Watchdog interrupt.

Defines for sc_irq_rtc_t

#define SC_IRQ_RTC (1U << 0U)
 RTC interrupt.

Defines for sc_irq_wake_t

#define SC_IRQ_BUTTON (1U << 0U)

Button interrupt.

#define SC_IRQ_PAD (1U << 1U)

Pad wakeup.

#define SC_IRQ_USR1 (1U << 2U)

User defined 1.

#define SC_IRQ_USR2 (1U << 3U)

User defined 2.

#define SC_IRQ_BC_PAD (1U << 4U)

Pad wakeup (broadcast to all partitions)

#define SC_IRQ_SW_WAKE (1U << 5U)

Software requested wake.

#define SC_IRQ_SECVIO (1U << 6U)

Security violation.

Defines for sc_irq_sysctr_t

#define SC_IRQ_SYSCTR (1U << 0U)
 SYSCTR interrupt.

13.1.1 Detailed Description

Module for the Interrupt (IRQ) service.

13.1.2 Function Documentation

13.1.2.1 sc_irq_enable()

This function enables/disables interrupts.

If pending interrupts are unmasked, an interrupt will be triggered.

Parameters

in	ipc	IPC handle
in	resource	MU channel
in	group	group the interrupts are in
in	mask	mask of interrupts to affect
in	enable	state to change interrupts to

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

• SC_PARM if group invalid

13.1.2.2 sc_irq_status()

This function returns the current interrupt status (regardless if masked).

Automatically clears pending interrupts.

Parameters

in	ipc	IPC handle
in	resource	MU channel
in	group	groups the interrupts are in
in	status	status of interrupts

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

• SC_PARM if group invalid

The returned *status* may show interrupts pending that are currently masked.

13.2 MISC: Miscellaneous Service

Module for the Miscellaneous (MISC) service.

Macros

#define SC_MISC_DMA_GRP_MAX 31U
 Max DMA channel priority group.

Typedefs

typedef uint8_t sc_misc_dma_group_t

This type is used to store a DMA channel priority group.

typedef uint8_t sc_misc_boot_status_t

This type is used report boot status.

• typedef uint8_t sc_misc_temp_t

This type is used report boot status.

typedef uint8_t sc_misc_bt_t

This type is used report the boot type.

Defines for type widths

#define SC_MISC_DMA_GRP_W 5U
 Width of sc_misc_dma_group_t.

Defines for sc_misc_boot_status_t

- #define SC_MISC_BOOT_STATUS_SUCCESS 0U Success
- #define SC_MISC_BOOT_STATUS_SECURITY 1U Security violation.

Defines for sc misc temp t

#define SC_MISC_TEMP 0U
 Temp sensor.

#define SC_MISC_TEMP_HIGH 1U

Temp high alarm.

#define SC_MISC_TEMP_LOW 2U

Temp low alarm.

Defines for sc_misc_bt_t

- #define SC_MISC_BT_PRIMARY 0U
- Primary boot.

 #define SC MISC BT SECONDARY 1U

Secondary boot.

• #define SC_MISC_BT_RECOVERY 2U

Recovery boot.

• #define SC MISC BT MANUFACTURE 3U

Manufacture boot.

#define SC_MISC_BT_SERIAL 4U

Serial boot.

Control Functions

- sc_err_t sc_misc_set_control (sc_ipc_t ipc, sc_rsrc_t resource, sc_ctrl_t ctrl, uint32_t val)
- sc_err_t sc_misc_get_control (sc_ipc_t ipc, sc_rsrc_t resource, sc_ctrl_t ctrl, uint32_t *val)

This function gets a miscellaneous control value.

This function sets a miscellaneous control value.

DMA Functions

- $\bullet \ \ \mathsf{sc_err_t} \ \mathsf{sc_misc_set_max_dma_group} \ (\mathsf{sc_ipc_t} \ \mathsf{ipc}, \ \mathsf{sc_rm_pt_t} \ \mathsf{pt}, \ \mathsf{sc_misc_dma_group_t} \ \mathsf{max})$
 - This function configures the max DMA channel priority group for a partition.
- sc_err_t sc_misc_set_dma_group (sc_ipc_t ipc, sc_rsrc_t resource, sc_misc_dma_group_t group)

This function configures the priority group for a DMA channel.

Debug Functions

void sc_misc_debug_out (sc_ipc_t ipc, uint8_t ch)

This function is used output a debug character from the SCU UART.

• sc_err_t sc_misc_waveform_capture (sc_ipc_t ipc, sc_bool_t enable)

This function starts/stops emulation waveform capture.

void sc_misc_build_info (sc_ipc_t ipc, uint32_t *build, uint32_t *commit)

This function is used to return the SCFW build info.

void sc_misc_api_ver (sc_ipc_t ipc, uint16_t *cl_maj, uint16_t *cl_min, uint16_t *sv_maj, uint16_t *sv_min)

This function is used to return the SCFW API versions.

void sc_misc_unique_id (sc_ipc_t ipc, uint32_t *id_l, uint32_t *id_h)

This function is used to return the device's unique ID.

Other Functions

sc_err_t sc_misc_set_ari (sc_ipc_t ipc, sc_rsrc_t resource, sc_rsrc_t resource_mst, uint16_t ari, sc_bool_t enable)

This function configures the ARI match value for PCIe/SATA resources.

void sc misc boot status (sc ipc t ipc, sc misc boot status t status)

This function reports boot status.

• sc err t sc misc boot done (sc ipc t ipc, sc rsrc t cpu)

This function tells the SCFW that a CPU is done booting.

sc_err_t sc_misc_otp_fuse_read (sc_ipc_t ipc, uint32_t word, uint32_t *val)

This function reads a given fuse word index.

sc_err_t sc_misc_otp_fuse_write (sc_ipc_t ipc, uint32_t word, uint32_t val)

This function writes a given fuse word index.

- sc_err_t sc_misc_set_temp (sc_ipc_t ipc, sc_rsrc_t resource, sc_misc_temp_t temp, int16_t celsius, int8_t tenths)

 This function sets a temp sensor alarm.
- sc_err_t sc_misc_get_temp (sc_ipc_t ipc, sc_rsrc_t resource, sc_misc_temp_t temp, int16_t *celsius, int8_t *tenths)

This function gets a temp sensor value.

void sc misc get boot dev (sc ipc t ipc, sc rsrc t *dev)

This function returns the boot device.

sc_err_t sc_misc_get_boot_type (sc_ipc_t ipc, sc_misc_bt_t *type)

This function returns the boot type.

sc_err_t sc_misc_get_boot_container (sc_ipc_t ipc, uint8_t *idx)

This function returns the boot container index.

void sc_misc_get_button_status (sc_ipc_t ipc, sc_bool_t *status)

This function returns the current status of the ON/OFF button.

sc_err_t sc_misc_rompatch_checksum (sc_ipc_t ipc, uint32_t *checksum)

This function returns the ROM patch checksum.

• sc_err_t sc_misc_board_ioctl (sc_ipc_t ipc, uint32_t *parm1, uint32_t *parm2, uint32_t *parm3)

This function calls the board IOCTL function.

13.2.1 Detailed Description

Module for the Miscellaneous (MISC) service.

13.2.2 Function Documentation

13.2.2.1 sc_misc_set_control()

This function sets a miscellaneous control value.

Parameters

in	ipc	IPC handle	
in	resource resource the control is associated with		
in	ctrl	control to change	
in	val	value to apply to the control	

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC_PARM if arguments out of range or invalid,
- SC_ERR_NOACCESS if caller's partition is not the resource owner or parent of the owner

Refer to the Control List for valid control values.

13.2.2.2 sc_misc_get_control()

This function gets a miscellaneous control value.

Parameters

in	ipc	IPC handle
in	resource	resource the control is associated with
in	ctrl control to get	
out	val	pointer to return the control value

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- · SC_PARM if arguments out of range or invalid,
- SC_ERR_NOACCESS if caller's partition is not the resource owner or parent of the owner

Refer to the Control List for valid control values.

13.2.2.3 sc_misc_set_max_dma_group()

This function configures the max DMA channel priority group for a partition.

Parameters

in	ipc	IPC handle	
in	pt handle of partition to assign max		
in	n max max priority group (0-31)		

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- · SC_PARM if arguments out of range or invalid,
- SC_ERR_NOACCESS if caller's partition is not the parent of the affected partition

Valid *max* range is 0-31 with 0 being the lowest and 31 the highest. Default is the max priority group for the parent partition of *pt*.

13.2.2.4 sc_misc_set_dma_group()

This function configures the priority group for a DMA channel.

Parameters

in	ipc	IPC handle
in	resource	DMA channel resource
in	group	priority group (0-31)

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- · SC_PARM if arguments out of range or invalid,
- SC_ERR_NOACCESS if caller's partition is not the owner or parent of the owner of the DMA channel

Valid *group* range is 0-31 with 0 being the lowest and 31 the highest. The max value of *group* is limited by the partition max set using sc_misc_set_max_dma_group().

13.2.2.5 sc_misc_debug_out()

This function is used output a debug character from the SCU UART.

Parameters

in	ipc	IPC handle
in	ch	character to output

13.2.2.6 sc_misc_waveform_capture()

This function starts/stops emulation waveform capture.

Parameters

	in	ipc	IPC handle
I	in	enable	flag to enable/disable capture

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

• SC_ERR_UNAVAILABLE if not running on emulation

13.2.2.7 sc_misc_build_info()

This function is used to return the SCFW build info.

Parameters

in	ipc IPC handle	
out	build pointer to return build number	
out	out commit pointer to return commit ID (g	

13.2.2.8 sc_misc_api_ver()

This function is used to return the SCFW API versions.

Parameters

in	ipc	IPC handle	
out	cl_maj	pointer to return major part of client version	
out	cl_min	pointer to return minor part of client version	
out	sv_maj	v_maj pointer to return major part of SCFW version	
out	sv_min	pointer to return minor part of SCFW version	

Client version is the version of the API ported to and used by the caller. SCFW version is the version of the SCFW binary running on the CPU.

Note a major version difference indicates a break in compatibility.

13.2.2.9 sc_misc_unique_id()

This function is used to return the device's unique ID.

Parameters

in	ipc	IPC handle	
out	id←	pointer to return lower 32-bit of ID [31:0]	
	_/		
out	id←	pointer to return upper 32-bits of ID [63:32]	
	_h		

13.2.2.10 sc_misc_set_ari()

This function configures the ARI match value for PCIe/SATA resources.

Parameters

in	ipc	IPC handle
in	resource	match resource
in	resource_mst	PCIe/SATA master to match
in	ari	ARI to match
in	enable	enable match or not

Returns

Returns an error code (SC ERR NONE = success).

Return errors:

- · SC_PARM if arguments out of range or invalid,
- SC_ERR_NOACCESS if caller's partition is not the owner or parent of the owner of the resource and translation

For PCIe, the ARI is the 16-bit value that includes the bus number, device number, and function number. For SATA, this value includes the FISType and PM_Port.

13.2.2.11 sc_misc_boot_status()

This function reports boot status.

Parameters

in	ipc	IPC handle
in	status	boot status

This is used by SW partitions to report status of boot. This is normally used to report a boot failure.

13.2.2.12 sc_misc_boot_done()

This function tells the SCFW that a CPU is done booting.

Parameters

in	ipc	IPC handle
in	сри	CPU that is done booting

This is called by early booting CPUs to report they are done with initialization. After starting early CPUs, the SCFW halts the booting process until they are done. During this time, early CPUs can call the SCFW with lower latency as the SCFW is idle.

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- · SC_PARM if arguments out of range or invalid,
- SC_ERR_NOACCESS if caller's partition is not the CPU owner

13.2.2.13 sc_misc_otp_fuse_read()

This function reads a given fuse word index.

Parameters

in	ipc	IPC handle
in	word	fuse word index
out	val	fuse read value

Returns

Returns and error code (SC_ERR_NONE = success).

Return errors codes:

- SC_ERR_PARM if word fuse index param out of range or invalid
- · SC ERR NOACCESS if read operation failed
- · SC_ERR_LOCKED if read operation is locked

13.2.2.14 sc_misc_otp_fuse_write()

This function writes a given fuse word index.

Only the owner of the SC_R_SYSTEM resource or a partition with access permissions to SC_R_SYSTEM can do this.

Parameters

in	ipc	IPC handle
in	word	fuse word index
in	val	fuse write value

The command is passed as is to SECO. SECO uses part of the *word* parameter to indicate if the fuse should be locked after programming. See the "Write common fuse" section of the SECO API Reference Guide for more info.

Returns

Returns and error code (SC_ERR_NONE = success).

Return errors codes:

- SC_ERR_PARM if word fuse index param out of range or invalid
- SC_ERR_NOACCESS if caller does not have SC_R_SYSTEM access
- SC_ERR_NOACCESS if write operation failed
- · SC_ERR_LOCKED if write operation is locked

13.2.2.15 sc_misc_set_temp()

This function sets a temp sensor alarm.

Parameters

in	ipc	IPC handle
in	resource	resource with sensor
in	temp	alarm to set
in	celsius	whole part of temp to set
in	tenths	fractional part of temp to set

Returns

Returns and error code (SC_ERR_NONE = success).

This function will enable the alarm interrupt if the temp requested is not the min/max temp. This enable automatically clears when the alarm occurs and this function has to be called again to re-enable.

Return errors codes:

- · SC_ERR_PARM if parameters invalid
- · SC_ERR_NOACCESS if caller does not own the resource
- SC_ERR_NOPOWER if power domain of resource not powered

13.2.2.16 sc_misc_get_temp()

This function gets a temp sensor value.

Parameters

in	ipc	IPC handle
in	resource	resource with sensor
in	temp	value to get (sensor or alarm)
out	celsius	whole part of temp to get
out	tenths	fractional part of temp to get

Returns

Returns and error code (SC_ERR_NONE = success).

Return errors codes:

- SC_ERR_PARM if parameters invalid
- SC_ERR_BUSY if temp not ready yet (time delay after power on)
- SC_ERR_NOPOWER if power domain of resource not powered

13.2.2.17 sc_misc_get_boot_dev()

This function returns the boot device.

Parameters

in	ipc	IPC handle
out	dev	pointer to return boot device

13.2.2.18 sc_misc_get_boot_type()

This function returns the boot type.

Parameters

in	ipc	IPC handle
out	type	pointer to return boot type

Returns

Returns and error code (SC_ERR_NONE = success).

Return errors code:

• SC_ERR_UNAVAILABLE if type not passed by ROM

```
13.2.2.19 sc_misc_get_boot_container()
```

This function returns the boot container index.

Parameters

in	ipc	IPC handle
out	idx	pointer to return index

Return idx = 1 for first container, 2 for second.

Returns

Returns and error code (SC_ERR_NONE = success).

Return errors code:

· SC_ERR_UNAVAILABLE if index not passed by ROM

13.2.2.20 sc_misc_get_button_status()

This function returns the current status of the ON/OFF button.

Parameters

in	ipc	IPC handle
out	status	pointer to return button status

13.2.2.21 sc_misc_rompatch_checksum()

This function returns the ROM patch checksum.

Parameters

	in	ipc	IPC handle
I	out	checksum	pointer to return checksum

Returns

Returns and error code (SC_ERR_NONE = success).

13.2.2.22 sc_misc_board_ioctl()

This function calls the board IOCTL function.

Parameters

in	ipc	IPC handle
in,out	parm1	pointer to pass parameter 1
in,out	parm2	pointer to pass parameter 2
in,out	parm3	pointer to pass parameter 3

Returns

Returns and error code (SC_ERR_NONE = success).

13.3 PAD: Pad Service

Module for the Pad Control (PAD) service.

Typedefs

```
    typedef uint8_t sc_pad_config_t
```

This type is used to declare a pad config.

typedef uint8 t sc pad iso t

This type is used to declare a pad low-power isolation config.

• typedef uint8_t sc_pad_28fdsoi_dse_t

This type is used to declare a drive strength.

typedef uint8_t sc_pad_28fdsoi_ps_t

This type is used to declare a pull select.

typedef uint8_t sc_pad_28fdsoi_pus_t

This type is used to declare a pull-up select.

typedef uint8_t sc_pad_wakeup_t

This type is used to declare a wakeup mode of a pad.

Defines for type widths

#define SC_PAD_MUX_W 3U
 Width of mux parameter.

Defines for sc_pad_config_t

 #define SC_PAD_CONFIG_NORMAL 0U Normal.

" I C OO DAD

#define SC_PAD_CONFIG_OD 1U

Open Drain.

• #define SC PAD CONFIG OD IN 2U

Open Drain and input.

#define SC_PAD_CONFIG_OUT_IN 3U

Output and input.

Defines for sc_pad_iso_t

#define SC_PAD_ISO_OFF 0U

ISO latch is transparent.

#define SC_PAD_ISO_EARLY 1U

Follow EARLY ISO.

• #define SC_PAD_ISO_LATE 2U

Follow LATE_ISO.

• #define SC_PAD_ISO_ON 3U

ISO latched data is held.

Defines for sc_pad_28fdsoi_dse_t

- #define SC_PAD_28FDSOI_DSE_18V_1MA 0U
 Drive strength of 1mA for 1.8v.
- #define SC_PAD_28FDSOI_DSE_18V_2MA 1U
 Drive strength of 2mA for 1.8v.
- #define SC_PAD_28FDSOI_DSE_18V_4MA 2U
 Drive strength of 4mA for 1.8v.
- #define SC_PAD_28FDSOI_DSE_18V_6MA 3U
 Drive strength of 6mA for 1.8v.
- #define SC_PAD_28FDSOI_DSE_18V_8MA 4U
 Drive strength of 8mA for 1.8v.
- #define SC_PAD_28FDSOI_DSE_18V_10MA 5U
 Drive strength of 10mA for 1.8v.
- #define SC_PAD_28FDSOI_DSE_18V_12MA 6U
 Drive strength of 12mA for 1.8v.
- #define SC_PAD_28FDSOI_DSE_18V_HS 7U
 High-speed drive strength for 1.8v.
- #define SC_PAD_28FDSOI_DSE_33V_2MA 0U
 Drive strength of 2mA for 3.3v.
- #define SC_PAD_28FDSOI_DSE_33V_4MA 1U
 Drive strength of 4mA for 3.3v.
- #define SC_PAD_28FDSOI_DSE_33V_8MA 2U
 Drive strength of 8mA for 3.3v.
- #define SC_PAD_28FDSOI_DSE_33V_12MA 3U
 Drive strength of 12mA for 3.3v.
- #define SC_PAD_28FDSOI_DSE_DV_HIGH 0U
 High drive strength for dual volt.
- #define SC_PAD_28FDSOI_DSE_DV_LOW 1U
 Low drive strength for dual volt.

Defines for sc_pad_28fdsoi_ps_t

- #define SC_PAD_28FDSOI_PS_KEEPER 0U
 Bus-keeper (only valid for 1.8v)
- #define SC_PAD_28FDSOI_PS_PU 1U
 Pull-up.
- #define SC_PAD_28FDSOI_PS_PD 2U
 Pull-down.
- #define SC_PAD_28FDSOI_PS_NONE 3U
 No pull (disabled)

Defines for sc_pad_28fdsoi_pus_t

```
    #define SC_PAD_28FDSOI_PUS_30K_PD 0U
30K pull-down
```

#define SC_PAD_28FDSOI_PUS_100K_PU 1U
 100K pull-up

 #define SC_PAD_28FDSOI_PUS_3K_PU 2U 3K pull-up

 #define SC_PAD_28FDSOI_PUS_30K_PU 3U 30K pull-up

Defines for sc_pad_wakeup_t

#define SC_PAD_WAKEUP_OFF 0U
 Off.

• #define SC_PAD_WAKEUP_CLEAR 1U

Clears pending flag.

#define SC_PAD_WAKEUP_LOW_LVL 4U

Low level.

#define SC_PAD_WAKEUP_FALL_EDGE 5U

Falling edge.

• #define SC_PAD_WAKEUP_RISE_EDGE 6U

Rising edge.

• #define SC PAD WAKEUP HIGH LVL 7U

High-level.

Generic Functions

- sc_err_t sc_pad_set_mux (sc_ipc_t ipc, sc_pad_t pad, uint8_t mux, sc_pad_config_t config, sc_pad_iso_t iso)

 This function configures the mux settings for a pad.
- sc_err_t sc_pad_get_mux (sc_ipc_t ipc, sc_pad_t pad, uint8_t *mux, sc_pad_config_t *config, sc_pad_iso_t *iso)

This function gets the mux settings for a pad.

sc_err_t sc_pad_set_gp (sc_ipc_t ipc, sc_pad_t pad, uint32_t ctrl)

This function configures the general purpose pad control.

sc_err_t sc_pad_get_gp (sc_ipc_t ipc, sc_pad_t pad, uint32_t *ctrl)

This function gets the general purpose pad control.

sc_err_t sc_pad_set_wakeup (sc_ipc_t ipc, sc_pad_t pad, sc_pad_wakeup_t wakeup)

This function configures the wakeup mode of the pad.

sc_err_t sc_pad_get_wakeup (sc_ipc_t ipc, sc_pad_t pad, sc_pad_wakeup_t *wakeup)

This function gets the wakeup mode of a pad.

• sc_err_t sc_pad_set_all (sc_ipc_t ipc, sc_pad_t pad, uint8_t mux, sc_pad_config_t config, sc_pad_iso_t iso, uint32_t ctrl, sc_pad_wakeup_t wakeup)

This function configures a pad.

• sc_err_t sc_pad_get_all (sc_ipc_t ipc, sc_pad_t pad, uint8_t *mux, sc_pad_config_t *config, sc_pad_iso_t *iso, uint32_t *ctrl, sc_pad_wakeup_t *wakeup)

This function gets a pad's config.

SoC Specific Functions

sc_err_t sc_pad_set (sc_ipc_t ipc, sc_pad_t pad, uint32_t val)

This function configures the settings for a pad.

sc_err_t sc_pad_get (sc_ipc_t ipc, sc_pad_t pad, uint32_t *val)

This function gets the settings for a pad.

sc_err_t sc_pad_config (sc_ipc_t ipc, sc_pad_t pad, uint32_t val)

This function writes a configuration register.

Technology Specific Functions

sc_err_t sc_pad_set_gp_28fdsoi (sc_ipc_t ipc, sc_pad_t pad, sc_pad_28fdsoi_dse_t dse, sc_pad_28fdsoi_ps_t ps)

This function configures the pad control specific to 28FDSOI.

sc_err_t sc_pad_get_gp_28fdsoi (sc_ipc_t ipc, sc_pad_t pad, sc_pad_28fdsoi_dse_t *dse, sc_pad_28fdsoi_ps_t *ps)

This function gets the pad control specific to 28FDSOI.

 sc_err_t sc_pad_set_gp_28fdsoi_hsic (sc_ipc_t ipc, sc_pad_t pad, sc_pad_28fdsoi_dse_t dse, sc_bool_t hys, sc_pad_28fdsoi_pus_t pus, sc_bool_t pke, sc_bool_t pue)

This function configures the pad control specific to 28FDSOI.

• sc_err_t sc_pad_get_gp_28fdsoi_hsic (sc_ipc_t ipc, sc_pad_t pad, sc_pad_28fdsoi_dse_t *dse, sc_bool_t *hys, sc_pad_28fdsoi_pus_t *pus, sc_bool_t *pke, sc_bool_t *pue)

This function gets the pad control specific to 28FDSOI.

• sc_err_t sc_pad_set_gp_28fdsoi_comp (sc_ipc_t ipc, sc_pad_t pad, uint8_t compen, sc_bool_t fastfrz, uint8_t rasrcp, uint8_t

This function configures the compensation control specific to 28FDSOI.

• sc_err_t sc_pad_get_gp_28fdsoi_comp (sc_ipc_t ipc, sc_pad_t pad, uint8_t *compen, sc_bool_t *fastfrz, uint8_t *rasrcp, uint8_t *rasrcp, sc_bool_t *nasrc_sel, sc_bool_t *compok, uint8_t *nasrc, sc_bool_t *psw_ovr)

This function gets the compensation control specific to 28FDSOI.

13.3.1 Detailed Description

Module for the Pad Control (PAD) service.

Pad configuration is managed by SC firmware. The pad configuration features supported by the SC firmware include:

- Configuring the mux, input/output connection, and low-power isolation mode.
- · Configuring the technology-specific pad setting such as drive strength, pullup/pulldown, etc.
- · Configuring compensation for pad groups with dual voltage capability.

Pad functions fall into one of three categories. Generic functions are common to all SoCs and all process technologies. SoC functions are raw low-level functions. Technology-specific functions are specific to the process technology.

The list of pads is SoC specific. Refer to the SoC Pad List for valid pad values. Note that all pads exist on a die but may or may not be brought out by the specific package. Mapping of pads to package pins/balls is documented in the

associated Data Sheet. Some pads may not be brought out because the part (die+package) is defeatured and some pads may connect to the substrate in the package.

Some pads (SC_P_COMP_*) that can be specified are not individual pads but are in fact pad groups. These groups have additional configuration that can be done using the sc_pad_set_gp_28fdsoi_comp() function. More info on these can be found in the associated Reference Manual.

Pads are managed as a resource by the Resource Manager (RM). They have assigned owners and only the owners can configure the pads. Some of the pads are reserved for use by the SCFW itself and this can be overridden with the implementation of board_config_sc(). Additionally, pads may be assigned to various other partitions via the implementation of board_system_config().

Note muxing two input pads to the same IP functional signal will result in undefined behavior.

The following SCFW pad code is an example of how to configure pads. In this example, two pads are configured for use by the i.MX8QXP I2C 0 (ADMA.I2C0). Another dual-voltge pad is configured as SPI 0 SCK (ADMA.SPI0.SCK).

The ipc parameter most functions take is a handle to the IPC channel opened to communicate to the SC. It is implementation defined. Most API ports include an sc_ipc_open() and sc_ipc_close() function to manage this. The sc_ipc_open() takes an argument to identify the communication channel (usually the MU address) and returns the IPC handle that all API calls should then use.

```
1 /* Configure I2C_0 SCL pad */
2 sc_pad_set_mux(ipc, SC_P_MIPI_CSI0_GPI00_00, 1, SC_PAD_CONFIG_OD_IN, SC_PAD_ISO_OFF);
3 sc_pad_set_gp_28fdsoi(ipc, SC_P_MIPI_CSI0_GPI00_00, SC_PAD_28FDSOI_DSE_18V_1MA, SC_PAD_28FDSOI_PS_PU);
4
5 /* Configure I2C_0 SDA pad */
6 sc_pad_set_mux(ipc, SC_P_MIPI_CSI0_GPI00_01, 1, SC_PAD_CONFIG_OD_IN, SC_PAD_ISO_OFF);
7 sc_pad_set_gp_28fdsoi(ipc, SC_P_MIPI_CSI0_GPI00_01, SC_PAD_28FDSOI_DSE_18V_1MA, SC_PAD_28FDSOI_PS_PU);
8
9 /* Configure SPI0 SCK pad (dual-voltage) */
10 sc_pad_set_mux(ipc, SC_P_SPI0_SCK, 0, SC_PAD_CONFIG_NORMAL, SC_PAD_ISO_OFF);
11 sc_pad_set_gp_28fdsoi(ipc, SC_P_SPI0_SCK, SC_PAD_28FDSOI_DSE_DV_LOW, SC_PAD_28FDSOI_PS_NONE);
```

The first pair of pads in question are MIPI_CSI0_GPIO0_00 (used for SCL) and MIPI_CSI0_GPIO0_01 (used for SDA). I2C 0 is mux select 1 for both pads.

The first two lines configure the SCL pad. The first configures the SCL pad for mux select 1, and as open-drain with with input. The second configures the drive strength and enables the pull-up.

The last two lines do the same for the SDA pad.

For 28FDSIO single voltage pads, SC_PAD_28FDSOI_DSE_DV_HIGH and SC_PAD_28FDSOI_DSE_DV_LOW are not valid drive strenths.

```
0 /* Configure I2C_0 SCL pad */
1 sc_pad_set_mux(ipc, SC_P_MIPI_CSI0_GPI00_00, 1, SC_PAD_CONFIG_OD_IN, SC_PAD_ISO_OFF);
2 sc_pad_set_gp_28fdsoi(ipc, SC_P_MIPI_CSI0_GPI00_00, SC_PAD_28FDSOI_DSE_18V_1MA, SC_PAD_28FDSOI_PS_PU);
3
4 /* Configure I2C_0 SDA pad */
5 sc_pad_set_mux(ipc, SC_P_MIPI_CSI0_GPI00_01, 1, SC_PAD_CONFIG_OD_IN, SC_PAD_ISO_OFF);
6 sc_pad_set_gp_28fdsoi(ipc, SC_P_MIPI_CSI0_GPI00_01, SC_PAD_28FDSOI_DSE_18V_1MA, SC_PAD_28FDSOI_PS_PU);
```

The next pad configured is SPI0_SCK. It is configured as mux select 0. the first line configures the mux select as 0 and normal push-pull. The second line configures the drive strength and no pull-up. Note the drive strength setting is different for this dual voltage pad.

```
7 /* Configure SPIO SCK pad (dual-voltage) */
9 sc_pad_set_mux(ipc, SC_P_SPIO_SCK, 0, SC_PAD_CONFIG_NORMAL, SC_PAD_ISO_OFF);
10 sc_pad_set_gp_28fdsoi(ipc, SC_P_SPIO_SCK, SC_PAD_28FDSOI_DSE_DV_LOW, SC_PAD_28FDSOI_PS_NONE);
```

For 28FDSIO dual voltage pads, only SC_PAD_28FDSOI_DSE_DV_HIGH and SC_PAD_28FDSOI_DSE_DV_LOW are valid drive strenths.

The voltage of the pad is determined by the supply for the pad group (the VDD SPI SAI 1P8 3P3 pad in this case).

13.3.2 Typedef Documentation

```
13.3.2.1 sc_pad_config_t
typedef uint8_t sc_pad_config_t
```

This type is used to declare a pad config.

It determines how the output data is driven, pull-up is controlled, and input signal is connected. Normal and OD are typical and only connect the input when the output is not driven. The IN options are less common and force an input connection even when driving the output.

```
13.3.2.2 sc_pad_iso_t
typedef uint8_t sc_pad_iso_t
```

This type is used to declare a pad low-power isolation config.

ISO_LATE is the most common setting. ISO_EARLY is only used when an output pad is directly determined by another input pad. The other two are only used when SW wants to directly control isolation.

```
13.3.2.3 sc_pad_28fdsoi_dse_t
typedef uint8_t sc_pad_28fdsoi_dse_t
```

This type is used to declare a drive strength.

Note it is specific to 28FDSOI. Also note that valid values depend on the pad type.

```
13.3.2.4 sc_pad_28fdsoi_ps_t
typedef uint8_t sc_pad_28fdsoi_ps_t
```

This type is used to declare a pull select.

Note it is specific to 28FDSOI.

```
13.3.2.5 sc_pad_28fdsoi_pus_t
typedef uint8_t sc_pad_28fdsoi_pus_t
```

This type is used to declare a pull-up select.

Note it is specific to 28FDSOI HSIC pads.

13.3.3 Function Documentation

This function configures the mux settings for a pad.

This includes the signal mux, pad config, and low-power isolation mode.

Parameters

in	ipc	IPC handle
in	pad	pad to configure
in	mux	mux setting
in	config	pad config
in	iso	low-power isolation mode

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC_PARM if arguments out of range or invalid,
- SC_ERR_NOACCESS if caller's partition is not the pad owner

Note muxing two input pads to the same IP functional signal will result in undefined behavior.

Refer to the SoC Pad List for valid pad values.

```
13.3.3.2 sc_pad_get_mux()
```

This function gets the mux settings for a pad.

This includes the signal mux, pad config, and low-power isolation mode.

Parameters

	in	ipc	IPC handle
	in	pad	pad to query
Γ	out	mux	pointer to return mux setting
	out	config	pointer to return pad config
	out	iso	pointer to return low-power isolation mode

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- · SC_PARM if arguments out of range or invalid,
- · SC_ERR_NOACCESS if caller's partition is not the pad owner

Refer to the SoC Pad List for valid pad values.

```
13.3.3.3 sc_pad_set_gp()
```

This function configures the general purpose pad control.

This is technology dependent and includes things like drive strength, slew rate, pull up/down, etc. Refer to the SoC Reference Manual for bit field details.

Parameters

in	ipc	IPC handle
in	pad	pad to configure
in	ctrl	control value to set

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC_PARM if arguments out of range or invalid,
- · SC_ERR_NOACCESS if caller's partition is not the pad owner

Refer to the SoC Pad List for valid pad values.

13.3.3.4 sc_pad_get_gp()

This function gets the general purpose pad control.

This is technology dependent and includes things like drive strength, slew rate, pull up/down, etc. Refer to the SoC Reference Manual for bit field details.

Parameters

in	ipc	IPC handle
in	pad	pad to query
out	ctrl	pointer to return control value

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC_PARM if arguments out of range or invalid,
- · SC_ERR_NOACCESS if caller's partition is not the pad owner

Refer to the SoC Pad List for valid pad values.

13.3.3.5 sc_pad_set_wakeup()

This function configures the wakeup mode of the pad.

Parameters

in	ipc	IPC handle
in	pad	pad to configure
in	wakeup	wakeup to set

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC_PARM if arguments out of range or invalid,
- · SC_ERR_NOACCESS if caller's partition is not the pad owner

Refer to the SoC Pad List for valid pad values.

13.3.3.6 sc_pad_get_wakeup()

This function gets the wakeup mode of a pad.

Parameters

in	ipc	IPC handle
in	pad	pad to query
out	wakeup	pointer to return wakeup

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC_PARM if arguments out of range or invalid,
- SC_ERR_NOACCESS if caller's partition is not the pad owner

Refer to the SoC Pad List for valid pad values.

13.3.3.7 sc_pad_set_all()

This function configures a pad.

Parameters

in	ipc	IPC handle
in	pad	pad to configure
in	mux	mux setting
in	config	pad config
in	iso	low-power isolation mode
in	ctrl	control value
in	wakeup	wakeup to set

See also

```
sc_pad_set_mux().
sc_pad_set_gp().
```

Return errors:

- SC_PARM if arguments out of range or invalid,
- · SC_ERR_NOACCESS if caller's partition is not the pad owner

Returns

```
Returns an error code (SC_ERR_NONE = success).
```

Note muxing two input pads to the same IP functional signal will result in undefined behavior.

Refer to the SoC Pad List for valid pad values.

```
13.3.3.8 sc_pad_get_all()
```

This function gets a pad's config.

Parameters

in	ipc	IPC handle
in	pad	pad to query
out	mux	pointer to return mux setting
out	config	pointer to return pad config
out	iso	pointer to return low-power isolation mode
out	ctrl	pointer to return control value
out	wakeup	pointer to return wakeup to set

See also

```
sc_pad_set_mux().
sc_pad_set_gp().
```

Return errors:

- · SC_PARM if arguments out of range or invalid,
- · SC_ERR_NOACCESS if caller's partition is not the pad owner

Returns

Returns an error code (SC_ERR_NONE = success).

Refer to the SoC Pad List for valid pad values.

```
13.3.3.9 sc_pad_set()
```

This function configures the settings for a pad.

This setting is SoC specific.

Parameters

in	ipc	IPC handle
in	pad	pad to configure
in	val	value to set

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC_PARM if arguments out of range or invalid,
- · SC_ERR_NOACCESS if caller's partition is not the pad owner

Refer to the SoC Pad List for valid pad values.

```
13.3.3.10 sc_pad_get()
```

This function gets the settings for a pad.

This setting is SoC specific.

Parameters

in	ipc	IPC handle
in	pad	pad to query
out	val	pointer to return setting

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC_PARM if arguments out of range or invalid,
- · SC_ERR_NOACCESS if caller's partition is not the pad owner

Refer to the SoC Pad List for valid pad values.

```
13.3.3.11 sc_pad_config()
```

This function writes a configuration register.

This setting is SoC specific.

Parameters

in	ipc	IPC handle
in	pad	pad to configure
in	val	value to set

Use to configure various HSIC and NAND congiruation settings.

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- · SC_PARM if arguments out of range or invalid,
- · SC_ERR_NOACCESS if caller's partition is not the pad owner

Refer to the SoC Pad List for valid pad values.

13.3.3.12 sc_pad_set_gp_28fdsoi()

This function configures the pad control specific to 28FDSOI.

Parameters

in	ipc	IPC handle
in	pad	pad to configure
in	dse	drive strength
in	ps	pull select

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC_PARM if arguments out of range or invalid,
- · SC_ERR_NOACCESS if caller's partition is not the pad owner,
- SC_ERR_UNAVAILABLE if process not applicable

Refer to the SoC Pad List for valid pad values.

13.3.3.13 sc_pad_get_gp_28fdsoi()

This function gets the pad control specific to 28FDSOI.

Parameters

in	ipc	IPC handle
in	pad	pad to query
out	dse	pointer to return drive strength
out	ps	pointer to return pull select

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC_PARM if arguments out of range or invalid,
- · SC_ERR_NOACCESS if caller's partition is not the pad owner,
- SC_ERR_UNAVAILABLE if process not applicable

Refer to the SoC Pad List for valid pad values.

13.3.3.14 sc_pad_set_gp_28fdsoi_hsic()

This function configures the pad control specific to 28FDSOI.

Parameters

in	ipc	IPC handle
in	pad	pad to configure
in	dse	drive strength
in	hys	hysteresis
in	pus	pull-up select
in	pke	pull keeper enable
in	pue	pull-up enable

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- · SC_PARM if arguments out of range or invalid,
- SC_ERR_NOACCESS if caller's partition is not the pad owner,
- SC_ERR_UNAVAILABLE if process not applicable

Refer to the SoC Pad List for valid pad values.

13.3.3.15 sc_pad_get_gp_28fdsoi_hsic()

This function gets the pad control specific to 28FDSOI.

Parameters

in	ipc	IPC handle
in	pad	pad to query
out	dse	pointer to return drive strength
out	hys	pointer to return hysteresis
out	pus	pointer to return pull-up select
out	pke	pointer to return pull keeper enable
out	pue	pointer to return pull-up enable

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- · SC PARM if arguments out of range or invalid,
- · SC_ERR_NOACCESS if caller's partition is not the pad owner,
- SC_ERR_UNAVAILABLE if process not applicable

Refer to the SoC Pad List for valid pad values.

13.3.3.16 sc_pad_set_gp_28fdsoi_comp()

This function configures the compensation control specific to 28FDSOI.

Parameters

in	ipc	IPC handle
in	pad	pad to configure
in	compen	compensation/freeze mode
in	fastfrz	fast freeze
in	rasrcp	compensation code for PMOS
in	rasrcn	compensation code for NMOS
in	nasrc_sel	NASRC read select
in	psw_ovr	2.5v override

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC_PARM if arguments out of range or invalid,
- · SC_ERR_NOACCESS if caller's partition is not the pad owner,
- SC_ERR_UNAVAILABLE if process not applicable

Refer to the SoC Pad List for valid pad values.

Note *psw_ovr* is only applicable to pads supporting 2.5 volt operation (e.g. some Ethernet pads).

13.3.3.17 sc_pad_get_gp_28fdsoi_comp()

This function gets the compensation control specific to 28FDSOI.

Parameters

in	ipc	IPC handle
in	pad	pad to query
out	compen	pointer to return compensation/freeze mode
out	fastfrz	pointer to return fast freeze

Parameters

out	rasrcp	pointer to return compensation code for PMOS
out	rasrcn	pointer to return compensation code for NMOS
out	nasrc_sel	pointer to return NASRC read select
out	compok	pointer to return compensation status
out	nasrc	pointer to return NASRCP/NASRCN
out	psw_ovr	pointer to return the 2.5v override

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC_PARM if arguments out of range or invalid,
- SC_ERR_NOACCESS if caller's partition is not the pad owner,
- SC_ERR_UNAVAILABLE if process not applicable

Refer to the SoC Pad List for valid pad values.

13.4 PM: Power Management Service

Module for the Power Management (PM) service.

Typedefs

```
• typedef uint8_t sc_pm_power_mode_t
```

This type is used to declare a power mode.

· typedef uint8_t sc_pm_clk_t

This type is used to declare a clock.

typedef uint8_t sc_pm_clk_parent_t

This type is used to declare the clock parent.

typedef uint32_t sc_pm_clock_rate_t

This type is used to declare clock rates.

• typedef uint8_t sc_pm_reset_type_t

This type is used to declare a desired reset type.

typedef uint8_t sc_pm_reset_reason_t

This type is used to declare a reason for a reset.

typedef uint8_t sc_pm_sys_if_t

This type is used to specify a system-level interface to be power managed.

typedef uint8_t sc_pm_wake_src_t

This type is used to specify a wake source for CPU resources.

Defines for type widths

```
• #define SC_PM_POWER_MODE_W 2U
```

Width of sc_pm_power_mode_t.

• #define SC_PM_CLOCK_MODE_W 3U

Width of sc_pm_clock_mode_t.

• #define SC PM RESET TYPE W 2U

Width of sc_pm_reset_type_t.

• #define SC_PM_RESET_REASON_W 4U

Width of sc pm reset reason t.

Defines for ALL parameters

#define SC_PM_CLK_ALL ((sc_pm_clk_t) UINT8_MAX)
 All clocks.

Defines for sc_pm_power_mode_t

• #define SC_PM_PW_MODE_OFF 0U

Power off.

· #define SC PM PW MODE STBY 1U

Power in standby.

• #define SC_PM_PW_MODE_LP 2U

Power in low-power.

• #define SC_PM_PW_MODE_ON 3U

Power on.

Defines for sc_pm_clk_t

- #define SC_PM_CLK_SLV_BUS 0U Slave bus clock.
- #define SC_PM_CLK_MST_BUS 1U
- #define SC_PM_CLK_PER 2U

Peripheral clock.

Master bus clock.

#define SC_PM_CLK_PHY 3U

Phy clock.

• #define SC_PM_CLK_MISC 4U

Misc clock.

• #define SC_PM_CLK_MISC0 0U

Misc 0 clock.

#define SC_PM_CLK_MISC1 1U

Misc 1 clock.

#define SC_PM_CLK_MISC2 2U

Misc 2 clock.

• #define SC_PM_CLK_MISC3 3U

Misc 3 clock.

• #define SC_PM_CLK_MISC4 4U

Misc 4 clock.

• #define SC_PM_CLK_CPU 2U

CPU clock.

#define SC_PM_CLK_PLL 4U

PLL.

#define SC_PM_CLK_BYPASS 4U

Bypass clock.

Defines for sc_pm_clk_parent_t

#define SC_PM_PARENT_XTAL 0U

Parent is XTAL.

• #define SC_PM_PARENT_PLL0 1U

Parent is PLL0.

• #define SC_PM_PARENT_PLL1 2U

Parent is PLL1 or PLL0/2.

• #define SC_PM_PARENT_PLL2 3U

Parent in PLL2 or PLL0/4.

• #define SC_PM_PARENT_BYPS 4U

Parent is a bypass clock.

Defines for sc_pm_reset_type_t

• #define SC_PM_RESET_TYPE_COLD 0U

Cold reset.

#define SC_PM_RESET_TYPE_WARM 1U

Warm reset.

#define SC_PM_RESET_TYPE_BOARD 2U

Board reset.

Defines for sc_pm_reset_reason_t

#define SC_PM_RESET_REASON_POR 0U
 Power on reset.

• #define SC_PM_RESET_REASON_JTAG 1U

JTAG reset.

• #define SC_PM_RESET_REASON_SW 2U

Software reset.

#define SC_PM_RESET_REASON_WDOG 3U

Partition watchdog reset.

#define SC_PM_RESET_REASON_LOCKUP 4U

SCU lockup reset.

#define SC_PM_RESET_REASON_SNVS 5U

SNVS reset.

#define SC_PM_RESET_REASON_TEMP 6U

Temp panic reset.

#define SC_PM_RESET_REASON_MSI 7U

MSI reset.

#define SC_PM_RESET_REASON_UECC 8U

ECC reset.

#define SC PM RESET REASON SCFW WDOG 9U

SCFW watchdog reset.

#define SC_PM_RESET_REASON_ROM_WDOG 10U

SCU ROM watchdog reset.

• #define SC_PM_RESET_REASON_SECO 11U

SECO reset.

#define SC_PM_RESET_REASON_SCFW_FAULT 12U

SCFW fault reset.

#define SC_PM_RESET_REASON_V2X_DEBUG 13U

V2X debug switch.

Defines for sc pm sys if t

#define SC PM SYS IF INTERCONNECT 0U

System interconnect.

• #define SC PM SYS IF MU 1U

AP -> SCU message units.

#define SC PM SYS IF OCMEM 2U

On-chip memory (ROM/OCRAM)

• #define SC_PM_SYS_IF_DDR 3U

DDR memory.

Defines for sc_pm_wake_src_t

#define SC PM_WAKE_SRC_NONE 0U

No wake source, used for self-kill.

· #define SC PM WAKE SRC SCU 1U

Wakeup from SCU to resume CPU (IRQSTEER & GIC powered down)

• #define SC_PM_WAKE_SRC_IRQSTEER 2U

Wakeup from IRQSTEER to resume CPU (GIC powered down)

#define SC_PM_WAKE_SRC_IRQSTEER_GIC 3U

Wakeup from IRQSTEER+GIC to wake CPU (GIC clock gated)

#define SC_PM_WAKE_SRC_GIC 4U

Wakeup from GIC to wake CPU.

Power Functions

sc_err_t sc_pm_set_sys_power_mode (sc_ipc_t ipc, sc_pm_power_mode_t mode)

This function sets the system power mode.

• sc err t sc pm set partition power mode (sc ipc t ipc, sc rm pt t pt, sc pm power mode t mode)

This function sets the power mode of a partition.

sc_err_t sc_pm_get_sys_power_mode (sc_ipc_t ipc, sc_rm_pt_t pt, sc_pm_power_mode_t *mode)

This function gets the power mode of a partition.

sc_err_t sc_pm_partition_wake (sc_ipc_t ipc, sc_rm_pt_t pt)

This function sends a wake interrupt to a partition.

• sc_err_t sc_pm_set_resource_power_mode (sc_ipc_t ipc, sc_rsrc_t resource, sc_pm_power_mode_t mode)

This function sets the power mode of a resource.

 sc_err_t sc_pm_set_resource_power_mode_all (sc_ipc_t ipc, sc_rm_pt_t pt, sc_pm_power_mode_t mode, sc_rsrc_t exclude)

This function sets the power mode for all the resources owned by a child partition.

sc_err_t sc_pm_get_resource_power_mode (sc_ipc_t ipc, sc_rsrc_t resource, sc_pm_power_mode_t *mode)

This function gets the power mode of a resource.

sc_err_t sc_pm_req_low_power_mode (sc_ipc_t ipc, sc_rsrc_t resource, sc_pm_power_mode_t mode)

This function specifies the low power mode some of the resources can enter based on their state.

 sc_err_t sc_pm_req_cpu_low_power_mode (sc_ipc_t ipc, sc_rsrc_t resource, sc_pm_power_mode_t mode, sc_pm_wake_src_t wake_src)

This function requests low-power mode entry for CPU/cluster resources.

sc_err_t sc_pm_set_cpu_resume_addr (sc_ipc_t ipc, sc_rsrc_t resource, sc_faddr_t address)

This function is used to set the resume address of a CPU.

sc_err_t sc_pm_set_cpu_resume (sc_ipc_t ipc, sc_rsrc_t resource, sc_bool_t isPrimary, sc_faddr_t address)

This function is used to set parameters for CPU resume from low-power mode.

sc_err_t sc_pm_req_sys_if_power_mode (sc_ipc_t ipc, sc_rsrc_t resource, sc_pm_sys_if_t sys_if, sc_pm_power_mode_t hpm, sc_pm_power_mode_t lpm)

This function requests the power mode configuration for system-level interfaces including messaging units, interconnect, and memories.

Clock/PLL Functions

- sc_err_t sc_pm_set_clock_rate (sc_ipc_t ipc, sc_rsrc_t resource, sc_pm_clk_t clk, sc_pm_clock_rate_t *rate)

 This function sets the rate of a resource's clock/PLL.
- sc_err_t sc_pm_get_clock_rate (sc_ipc_t ipc, sc_rsrc_t resource, sc_pm_clk_t clk, sc_pm_clock_rate_t *rate)

 This function gets the rate of a resource's clock/PLL.
- sc_err_t sc_pm_clock_enable (sc_ipc_t ipc, sc_rsrc_t resource, sc_pm_clk_t clk, sc_bool_t enable, sc_bool_t autog)

This function enables/disables a resource's clock.

- sc_err_t sc_pm_set_clock_parent (sc_ipc_t ipc, sc_rsrc_t resource, sc_pm_clk_t clk, sc_pm_clk_parent_t parent)

 This function sets the parent of a resource's clock.
- sc_err_t sc_pm_get_clock_parent (sc_ipc_t ipc, sc_rsrc_t resource, sc_pm_clk_t clk, sc_pm_clk_parent_t *parent)

This function gets the parent of a resource's clock.

Reset Functions

sc_err_t sc_pm_reset (sc_ipc_t ipc, sc_pm_reset_type_t type)

This function is used to reset the system.

• sc err t sc pm reset reason (sc ipc t ipc, sc pm reset reason t *reason)

This function gets a caller's reset reason.

sc_err_t sc_pm_get_reset_part (sc_ipc_t ipc, sc_rm_pt_t *pt)

This function gets the partition that caused a reset.

• sc_err_t sc_pm_boot (sc_ipc_t ipc, sc_rm_pt_t pt, sc_rsrc_t resource_cpu, sc_faddr_t boot_addr, sc_rsrc_t resource_mu, sc_rsrc_t resource_dev)

This function is used to boot a partition.

sc_err_t sc_pm_set_boot_parm (sc_ipc_t ipc, sc_rsrc_t resource_cpu, sc_faddr_t boot_addr, sc_rsrc_t resource_mu, sc_rsrc_t resource_dev)

This function is used to change the boot parameters for a partition.

void sc_pm_reboot (sc_ipc_t ipc, sc_pm_reset_type_t type)

This function is used to reboot the caller's partition.

• sc err t sc pm reboot partition (sc ipc t ipc, sc rm pt t pt, sc pm reset type t type)

This function is used to reboot a partition.

sc_err_t sc_pm_reboot_continue (sc_ipc_t ipc, sc_rm_pt_t pt)

This function is used to continue the reboot a partition.

sc_err_t sc_pm_cpu_start (sc_ipc_t ipc, sc_rsrc_t resource, sc_bool_t enable, sc_faddr_t address)

This function is used to start/stop a CPU.

void sc_pm_cpu_reset (sc_ipc_t ipc, sc_rsrc_t resource, sc_faddr_t address)

This function is used to reset a CPU.

• sc_err_t sc_pm_resource_reset (sc_ipc_t ipc, sc_rsrc_t resource)

This function is used to reset a peripheral.

sc_bool_t sc_pm_is_partition_started (sc_ipc_t ipc, sc_rm_pt_t pt)

This function returns a bool indicating if a partition was started.

13.4.1 Detailed Description

Module for the Power Management (PM) service.

The following SCFW PM code is an example of how to configure the power and clocking of a UART. All resources MUST be powered on before accessing.

The ipc parameter most functions take is a handle to the IPC channel opened to communicate to the SC. It is implementation defined. Most API ports include an sc_ipc_open() and sc_ipc_close() function to manage this. The sc_ipc_open() takes an argument to identify the communication channel (usually the MU address) and returns the IPC handle that all API calls should then use.

Refer to the SoC-specific Resource List for a list of resources. Refer to the SoC-specific Clock List for a list of clocks.

```
1 sc_pm_clock_rate_t rate = SC_160MHZ;
2
3 /* Powerup UART 0 */
4 sc_pm_set_resource_power_mode(ipc, SC_R_UART_0, SC_PM_PW_MODE_ON);
5
6 /* Configure UART 0 baud clock */
7 sc_pm_set_clock_rate(ipc, SC_R_UART_0, SC_PM_CLK_PER, &rate);
8
9 /* Enable UART 0 clock */
10 sc_pm_clock_enable(ipc, SC_R_UART_0, SC_PM_CLK_PER, SC_TRUE, SC_FALSE);
```

First, a variable is declared to hold the rate to request and return for the UART peripheral clock. Note this is the baud clock going into the UART which is then further divided within the UART itself.

```
0 sc_pm_clock_rate_t rate = SC_160MHZ;
```

Then change the power state of the UART to the ON state.

```
1 /* Powerup UART 0 */
3 sc_pm_set_resource_power_mode(ipc, SC_R_UART_0, SC_PM_PW_MODE_ON);
```

Then configure the UART peripheral clock. Note that due to hardware limitation, the exact rate may not be what is requested. The rate is guarenteed to not be greater than the requested rate. The actual rate is returned in the varaible. The actual rate should be used when configuring the UART IP. Note that 160MHz is used as that can be divided by the UART to hit all the common UART rates within required error. Other frequencies may have issues and the caller needs to calculate the baud clock error rate. See the UART section of the SoC RM.

```
4 /* Configure UART 0 baud clock */
6 sc_pm_set_clock_rate(ipc, SC_R_UART_0, SC_PM_CLK_PER, &rate);
```

Then enable the clock.

```
7 /* Enable UART 0 clock */
9 sc_pm_clock_enable(ipc, SC_R_UART_0, SC_PM_CLK_PER, SC_TRUE, SC_FALSE);
```

At this point, the UART IP can be configured and used.

13.4.2 Typedef Documentation

```
13.4.2.1 sc_pm_power_mode_t
```

```
typedef uint8_t sc_pm_power_mode_t
```

This type is used to declare a power mode.

Note resources only use SC_PM_PW_MODE_OFF and SC_PM_PW_MODE_ON. The other modes are used only as system power modes.

13.4.3 Function Documentation

13.4.3.1 sc_pm_set_sys_power_mode()

This function sets the system power mode.

Only the owner of the SC_R_SYSTEM resource or a partition with access permissions to SC_R_SYSTEM can do this.

Parameters

in	ipc	IPC handle
in	mode	power mode to apply

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC_ERR_PARM if invalid mode,
- · SC ERR NOACCESS if caller does not have SC R SYSTEM access

See also

```
sc_pm_set_sys_power_mode().
```

13.4.3.2 sc_pm_set_partition_power_mode()

This function sets the power mode of a partition.

Parameters

in	ipc	IPC handle
in	pt	handle of partition
in	mode	power mode to apply

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC_ERR_PARM if invalid partition or mode != SC_PM_PW_MODE_OFF,
- SC_ERR_NOACCESS if caller's partition is not the owner or parent of pt

This function can only be used to turn off a partition by calling with mode equal to SC_PM_PW_MODE_OFF. After turning off, the partition can be booted with sc_pm_reboot_partition() or sc_pm_boot(). It cannot be used to turn off the calling partition as the MU could not return the an error response.

For dynamic power management of a partition, use sc_pm_req_low_power_mode(), sc_pm_req_cpu_low_power_mode(), and sc_pm_req_sys_if_power_mode() with a WFI for controlled power state transitions.

13.4.3.3 sc_pm_get_sys_power_mode()

This function gets the power mode of a partition.

Parameters

in	ipc	IPC handle
in	pt	handle of partition
out	mode	pointer to return power mode

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

SC_ERR_PARM if invalid partition

13.4.3.4 sc_pm_partition_wake()

This function sends a wake interrupt to a partition.

Parameters

in	ipc	IPC handle
in	pt	handle of partition to wake

Returns

Returns an error code (SC_ERR_NONE = success).

An SC_IRQ_SW_WAKE interrupt is sent to all MUs owned by the partition that have this interrupt enabled. The CPU using an MU will exit a low-power state to service the MU interrupt.

Return errors:

• SC_ERR_PARM if invalid partition

13.4.3.5 sc_pm_set_resource_power_mode()

This function sets the power mode of a resource.

Parameters

in	ipc	IPC handle
in	resource	ID of the resource
in	mode	power mode to apply

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC_ERR_PARM if invalid resource or mode,
- · SC ERR PARM if resource is the MU used to make the call,
- SC_ERR_NOACCESS if caller's partition is not the resource owner or parent of the owner

Resources must be at SC_PM_PW_MODE_LP mode or higher to access them, otherwise the master will get a bus error or hang.

Note some resources are still not accessible even when powered up if bus transactions go through a fabric not powered up. Examples of this are resources in display and capture subsystems which require the display controller or the imaging subsystem to be powered up first.

Note that resources are grouped into power domains by the underlying hardware. If any resource in the domain is on, the entire power domain will be on. Other power domains required to access the resource will also be turned on. Bus clocks required to access the peripheral will be turned on. Refer to the SoC RM for more info on power domains and access infrastructure (bus fabrics, clock domains, etc.).

When the resource transitions to the SC_PM_PW_MODE_OFF, all of the settings, including clock rate, will be lost; immaterial of the state of other resources in the same power domain.

13.4.3.6 sc pm_set_resource_power_mode_all()

This function sets the power mode for all the resources owned by a child partition.

Parameters

in	ipc	IPC handle
in	pt	handle of child partition
in	mode	power mode to apply
in	exclude	resource to exclude

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC_ERR_PARM if invalid partition or mode,
- SC_ERR_NOACCESS if caller's partition is not the parent (with grant) of pt

This functions loops through all the resources owned by *pt* and sets the power mode to *mode*. It will skip setting *exclude* (SC_R_LAST to skip none).

This function can only be called by the parent. It is used to implement some aspects of virtualization.

13.4.3.7 sc_pm_get_resource_power_mode()

This function gets the power mode of a resource.

Parameters

in	ipc	IPC handle
in	resource	ID of the resource
out	mode	pointer to return power mode

Returns

Returns an error code (SC_ERR_NONE = success).

Note only SC_PM_PW_MODE_OFF and SC_PM_PW_MODE_ON are valid. The value returned does not reflect the power mode of the partition.

13.4.3.8 sc_pm_req_low_power_mode()

This function specifies the low power mode some of the resources can enter based on their state.

This API is only valid for the following resources: SC_R_A53, SC_R_A53_0, SC_R_A53_1, SC_R_A53_2, SC_R ← _A53_3, SC_R_A72_0, SC_R_A72_1, SC_R_CC1, SC_R_A35, SC_R_A35_0, SC_R_A35_1, SC_R_← A35_2, SC_R_A35_3. For all other resources it will return SC_ERR_PARAM. This function will set the low power mode the cores, cluster and cluster associated resources will enter when all the cores in a given cluster execute WFI.

Parameters

in	ipc	IPC handle
in	resource	ID of the resource
in	mode	power mode to apply

Returns

Returns an error code (SC_ERR_NONE = success).

13.4.3.9 sc_pm_req_cpu_low_power_mode()

This function requests low-power mode entry for CPU/cluster resources.

This API is only valid for the following resources: SC_R_A53, SC_R_A53_x, SC_R_A72, SC_R_A72_x, SC_R_A35, SC_R_A35_x, SC_R_CCI. For all other resources it will return SC_ERR_PARAM. For individual core resources, the specified power mode and wake source will be applied after the core has entered WFI. For cluster resources, the specified power mode is applied after all cores in the cluster have entered low-power mode. For multicluster resources, the specified power mode is applied after all clusters have reached low-power mode.

Parameters

in	ipc	IPC handle
in	resource	ID of the resource
in	mode	power mode to apply
in	wake_src	wake source for low-power exit

Returns

Returns an error code (SC_ERR_NONE = success).

13.4.3.10 sc_pm_set_cpu_resume_addr()

This function is used to set the resume address of a CPU.

Parameters

in	ipc	IPC handle
in	resource	ID of the CPU resource
in	address	64-bit resume address

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- · SC_ERR_PARM if invalid resource or address,
- · SC ERR NOACCESS if caller's partition is not the parent of the resource (CPU) owner

Note the address is limited by the hardware implementation. See the CPU Start Address section in the Porting Guide.

13.4.3.11 sc_pm_set_cpu_resume()

This function is used to set parameters for CPU resume from low-power mode.

Parameters

in	ipc	IPC handle
in	resource	ID of the CPU resource
in	isPrimary	set SC_TRUE if primary wake CPU
in	address	64-bit resume address

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC ERR PARM if invalid resource or address,
- · SC ERR NOACCESS if caller's partition is not the parent of the resource (CPU) owner

Note the address is limited by the hardware implementation. See the CPU Start Address section in the Porting Guide.

13.4.3.12 sc_pm_req_sys_if_power_mode()

This function requests the power mode configuration for system-level interfaces including messaging units, interconnect, and memories.

This API is only valid for the following resources: SC_R_A53, SC_R_A72, and SC_R_M4_x_PID_y. For all other resources, it will return SC_ERR_PARAM. The requested power mode will be captured and applied to system-level resources as system conditions allow.

Parameters

in	ipc	IPC handle
in	resource	ID of the resource
in	sys_if	system-level interface to be configured
in	hpm	high-power mode for the system interface
in	lpm	low-power mode for the system interface

Returns

Returns an error code (SC_ERR_NONE = success).

13.4.3.13 sc_pm_set_clock_rate()

This function sets the rate of a resource's clock/PLL.

Parameters

in	ipc	IPC handle
in	resource	ID of the resource
in	clk	clock/PLL to affect
in,out	rate	pointer to rate

Note the actual rate is returned in rate.

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC_ERR_PARM if invalid resource or clock/PLL,
- SC_ERR_NOACCESS if caller's partition is not the resource owner or parent of the owner,
- SC_ERR_UNAVAILABLE if clock/PLL not applicable to this resource,
- SC_ERR_LOCKED if rate locked (usually because shared clock/PLL)

Refer to the Clock List for valid clock/PLL values.

13.4.3.14 sc_pm_get_clock_rate()

This function gets the rate of a resource's clock/PLL.

Parameters

in	ipc	IPC handle
in	resource	ID of the resource
in	clk	clock/PLL to affect
out	rate	pointer to return rate

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC_ERR_PARM if invalid resource or clock/PLL,
- SC_ERR_NOACCESS if caller's partition is not the resource owner or parent of the owner,
- SC_ERR_UNAVAILABLE if clock/PLL not applicable to this resource

This function returns the actual clock rate of the hardware. This rate may be different from the original requested clock rate if the resource is set to a low power mode.

Refer to the Clock List for valid clock/PLL values.

13.4.3.15 sc_pm_clock_enable()

This function enables/disables a resource's clock.

Parameters

in	ipc	IPC handle	
in	resource	esource ID of the resource	
in	clk	clock to affect	
in	enable	enable if SC_TRUE; otherwise disabled	Reserved
in	autog	HW auto clock gating	

If resource is SC_R_ALL then all resources owned will be affected. No error will be returned.

If clk is SC_PM_CLK_ALL, then an error will be returned if any of the available clocks returns an error.

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- · SC ERR PARM if invalid resource or clock,
- · SC_ERR_NOACCESS if caller's partition is not the resource owner or parent (with grant) of the owner,
- SC_ERR_UNAVAILABLE if clock not applicable to this resource

Refer to the Clock List for valid clock values.

```
13.4.3.16 sc_pm_set_clock_parent()
```

This function sets the parent of a resource's clock.

This function should only be called when the clock is disabled.

Parameters

in	ipc	IPC handle
in	resource	ID of the resource
in	clk	clock to affect
in	parent	New parent of the clock

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- · SC ERR PARM if invalid resource or clock,
- SC_ERR_NOACCESS if caller's partition is not the resource owner or parent (with grant) of the owner,
- SC ERR UNAVAILABLE if clock not applicable to this resource
- SC_ERR_BUSY if clock is currently enabled.
- · SC_ERR_NOPOWER if resource not powered

Refer to the Clock List for valid clock values.

13.4.3.17 sc_pm_get_clock_parent()

This function gets the parent of a resource's clock.

Parameters

in	ipc	IPC handle
in	resource ID of the resource	
in	clk	clock to affect
out	parent	pointer to return parent of clock

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC_ERR_PARM if invalid resource or clock,
- SC_ERR_NOACCESS if caller's partition is not the resource owner or parent of the owner,
- SC_ERR_UNAVAILABLE if clock not applicable to this resource

Refer to the Clock List for valid clock values.

This function is used to reset the system.

Only the owner of the SC_R_SYSTEM resource or a partition with access permissions to SC_R_SYSTEM can do this.

Parameters

in	ipc	IPC handle
in	type	reset type

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC_ERR_PARM if invalid type,
- SC_ERR_NOACCESS if caller cannot access SC_R_SYSTEM

If this function returns, then the reset did not occur due to an invalid parameter.

```
13.4.3.19 sc_pm_reset_reason()
```

This function gets a caller's reset reason.

Parameters

in	ipc	IPC handle
out	reason	pointer to return the reset reason

This function returns the reason a partition was reset. If the reason is POR, then the system reset reason will be returned.

Note depending on the connection of the WDOG_OUT signal and the OTP programming of the PMIC, some resets may trigger a system POR and the original reason will be lost.

Returns

Returns an error code (SC_ERR_NONE = success).

13.4.3.20 sc_pm_get_reset_part()

This function gets the partition that caused a reset.

Parameters

in	ipc	IPC handle	
011†.	pt	pointer to return the resetting partition	
	1	NVD AII	Pighta Pagaryad
NXP - All/Rights Reserved			

If the reset reason obtained via sc_pm_reset_reason() is POR then the result from this function will be 0. Some SECO causes of reset will also return 0.

Note depending on the connection of the WDOG_OUT signal and the OTP programming of the PMIC, some resets may trigger a system POR and the partition info will be lost.

Returns

Returns an error code (SC_ERR_NONE = success).

13.4.3.21 sc_pm_boot()

This function is used to boot a partition.

Parameters

in	ipc	IPC handle
in	pt handle of partition to boot	
in	resource_cpu	ID of the CPU resource to start
in	boot_addr	64-bit boot address
in	resource_mu	ID of the MU that must be powered
in	resource_dev	ID of the boot device that must be powered

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC_ERR_PARM if invalid partition, resource, or addr,
- SC_ERR_NOACCESS if caller's partition is not the parent of the partition to boot

This must be used to boot a partition. Only a partition booted this way can be rebooted using the watchdog, sc_pm_boot() or sc_pm_reboot_partition().

Note the address is limited by the hardware implementation. See the CPU Start Address section in the Porting Guide.

13.4.3.22 sc_pm_set_boot_parm()

This function is used to change the boot parameters for a partition.

Parameters

in	ipc	IPC handle
in	resource_cpu	ID of the CPU resource to start
in	boot_addr	64-bit boot address
in	resource_mu	ID of the MU that must be powered (0=none)
in	resource_dev	ID of the boot device that must be powered (0=none)

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

· SC_ERR_PARM if invalid resource, or addr

This function can be used to change the boot parameters for a partition. This can be useful if a partitions reboots differently from the initial boot done via sc_pm_boot() or via ROM.

Note the address is limited by the hardware implementation. See the CPU Start Address section in the Porting Guide.

13.4.3.23 sc_pm_reboot()

This function is used to reboot the caller's partition.

Parameters

in	ipc	IPC handle
in	type	reset type

If type is SC_PM_RESET_TYPE_COLD, then most peripherals owned by the calling partition will be reset if possible.

SC state (partitions, power, clocks, etc.) is reset. The boot SW of the booting CPU must be able to handle peripherals that that are not reset.

If type is SC_PM_RESET_TYPE_WARM or SC_PM_RESET_TYPE_BOARD, then does nothing.

If this function returns, then the reset did not occur due to an invalid parameter.

13.4.3.24 sc_pm_reboot_partition()

This function is used to reboot a partition.

Parameters

in	ipc	IPC handle
in	pt	handle of partition to reboot
in	type	reset type

If *type* is SC_PM_RESET_TYPE_COLD, then most peripherals owned by the calling partition will be reset if possible. SC state (partitions, power, clocks, etc.) is reset. The boot SW of the booting CPU must be able to handle peripherals that that are not reset.

If *type* is SC_PM_RESET_TYPE_WARM or SC_PM_RESET_TYPE_BOARD, then returns SC_ERR_PARM as these are not supported.

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC_ERR_PARM if invalid partition or type
- SC_ERR_NOACCESS if caller's partition is not the parent of pt and the caller does not have access to SC_R_← SYSTEM

Most peripherals owned by the partition will be reset if possible. SC state (partitions, power, clocks, etc.) is reset. The boot SW of the booting CPU must be able to handle peripherals that that are not reset.

If board_reboot_part() returns a non-0 mask, then the reboot will be delayed until all partitions indicated in the mask have called sc_pm_reboot_continue() to continue the boot.

13.4.3.25 sc_pm_reboot_continue()

This function is used to continue the reboot a partition.

Parameters

in	ipc	IPC handle
in	pt	handle of partition to continue

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

· SC_ERR_PARM if invalid partition

13.4.3.26 sc_pm_cpu_start()

This function is used to start/stop a CPU.

Parameters

in	ipc	IPC handle
in	resource	ID of the CPU resource
in	enable	start if SC_TRUE; otherwise stop
in	address	64-bit boot address

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- · SC_ERR_PARM if invalid resource or address,
- SC_ERR_NOACCESS if caller's partition is not the parent of the resource (CPU) owner

This function is usually used to start a secondary CPU in the same partition as the caller. It is not used to start the first CPU in a dedicated partition. That would be started by calling sc_pm_boot().

A CPU started with sc_pm_cpu_start() will not restart as a result of a watchdog event or calling sc_pm_reboot() or sc_pm_reboot_partition(). Those will reboot that partition which will start the CPU started with sc_pm_boot().

Note the address is limited by the hardware implementation. See the CPU Start Address section in the Porting Guide.

13.4.3.27 sc_pm_cpu_reset()

This function is used to reset a CPU.

Parameters

in	ipc	IPC handle
in	resource	ID of the CPU resource
in	address	64-bit boot address

This function does not return anything as the calling core may have been reset. It can still fail if the resource or address is invalid. It can also fail if the caller's partition is not the owner of the CPU, not the parent of the CPU resource owner, or has access to SC_R_SYSTEM. Will also fail if the resource is not powered on. No indication of failure is returned.

Note this just resets the CPU. None of the peripherals or bus fabric used by the CPU is reset. State configured in the SCFW is not reset. The SW running on the core has to understand and deal with this.

The address is limited by the hardware implementation. See the CPU Start Address section in the Porting Guide.

13.4.3.28 sc_pm_resource_reset()

This function is used to reset a peripheral.

Parameters

in	ipc	IPC handle
in	resource	resource to reset

This function will reset a resource. Most resources cannot be reset unless the SoC design specifically allows it. In the case on MUs, the IPC/RPC protocol is also reset. Note a caller cannot reset an MU that this API call is sent on.

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC_ERR_PARM if invalid resource,
- SC ERR PARM if resource is the MU used to make the call,

- · SC_ERR_NOACCESS if caller's partition is not the resource owner or parent (with grant) of the owner,
- SC_ERR_BUSY if the resource cannot be reset due to power state of buses,
- SC_ERR_UNAVAILABLE if the resource cannot be reset due to hardware limitations

13.4.3.29 sc_pm_is_partition_started()

This function returns a bool indicating if a partition was started.

Parameters

in	ipc	IPC handle
in	pt	handle of partition to check

Returns

Returns a bool (SC_TRUE = started).

Note this indicates if a partition was started. It does not indicate if a partition is currently running or in a low power state.

13.5 RM: Resource Management Service

Module for the Resource Management (RM) service.

Typedefs

```
typedef uint8_t sc_rm_pt_t
```

This type is used to declare a resource partition.

typedef uint8_t sc_rm_mr_t

This type is used to declare a memory region.

typedef uint8_t sc_rm_did_t

This type is used to declare a resource domain ID used by the isolation HW.

typedef uint16_t sc_rm_sid_t

This type is used to declare an SMMU StreamID.

typedef uint8_t sc_rm_spa_t

This type is a used to declare master transaction attributes.

typedef uint8_t sc_rm_perm_t

This type is used to declare a resource/memory region access permission.

typedef uint8_t sc_rm_det_t

This type is used to indicate memory region transactions should detour to the IEE.

typedef uint8_t sc_rm_rmsg_t

This type is used to assign an RMSG value to a memory region.

Defines for type widths

```
    #define SC RM PARTITION W 5U
```

Width of sc_rm_pt_t.

• #define SC_RM_MEMREG_W 6U

Width of sc_rm_mr_t.

• #define SC RM DID W 4U

 ${\it Width\ of\ sc_rm_did_t}.$

#define SC_RM_SID_W 6U

Width of sc_rm_sid_t.

#define SC_RM_SPA_W 2U

Width of sc_rm_spa_t.

#define SC_RM_PERM_W 3U

Width of sc_rm_perm_t.

• #define SC_RM_DET_W 1U

Width of sc_rm_det_t.

#define SC_RM_RMSG_W 4U

Width of sc_rm_rmsg_t.

Defines for ALL parameters

```
• #define SC_RM_PT_ALL ((sc_rm_pt_t) UINT8_MAX)
```

All partitions.

#define SC_RM_MR_ALL ((sc_rm_mr_t) UINT8_MAX)

All memory regions.

Defines for sc_rm_spa_t

• #define SC RM SPA PASSTHRU 0U

Pass through (attribute driven by master)

#define SC_RM_SPA_PASSSID 1U

Pass through and output on SID.

#define SC_RM_SPA_ASSERT 2U

Assert (force to be secure/privileged)

• #define SC_RM_SPA_NEGATE 3U

Negate (force to be non-secure/user)

Defines for sc_rm_perm_t

#define SC RM PERM NONE 0U

No access.

#define SC_RM_PERM_SEC_R 1U

Secure RO.

#define SC_RM_PERM_SECPRIV_RW 2U

Secure privilege R/W.

#define SC RM PERM SEC RW 3U

Secure R/W.

#define SC_RM_PERM_NSPRIV_R 4U

Secure R/W, non-secure privilege RO.

#define SC_RM_PERM_NS_R 5U

Secure R/W, non-secure RO.

• #define SC RM PERM NSPRIV RW 6U

Secure R/W, non-secure privilege R/W.

• #define SC RM PERM FULL 7U

Full access.

Partition Functions

sc_err_t sc_rm_partition_alloc (sc_ipc_t ipc, sc_rm_pt_t *pt, sc_bool_t secure, sc_bool_t isolated, sc_bool_t restricted, sc_bool_t grant, sc_bool_t coherent)

This function requests that the SC create a new resource partition.

sc_err_t sc_rm_set_confidential (sc_ipc_t ipc, sc_rm_pt_t pt, sc_bool_t retro)

This function makes a partition confidential.

• sc_err_t sc_rm_partition_free (sc_ipc_t ipc, sc_rm_pt_t pt)

This function frees a partition and assigns all resources to the caller.

sc_rm_did_t sc_rm_get_did (sc_ipc_t ipc)

This function returns the DID of a partition.

sc_err_t sc_rm_partition_static (sc_ipc_t ipc, sc_rm_pt_t pt, sc_rm_did_t did)

This function forces a partition to use a specific static DID.

sc_err_t sc_rm_partition_lock (sc_ipc_t ipc, sc_rm_pt_t pt)

This function locks a partition.

sc_err_t sc_rm_get_partition (sc_ipc_t ipc, sc_rm_pt_t *pt)

This function gets the partition handle of the caller.

sc_err_t sc_rm_set_parent (sc_ipc_t ipc, sc_rm_pt_t pt, sc_rm_pt_t pt_parent)

This function sets a new parent for a partition.

sc_err_t sc_rm_move_all (sc_ipc_t ipc, sc_rm_pt_t pt_src, sc_rm_pt_t pt_dst, sc_bool_t move_rsrc, sc_bool_t move_pads)

This function moves all movable resources/pads owned by a source partition to a destination partition.

Resource Functions

sc_err_t sc_rm_assign_resource (sc_ipc_t ipc, sc_rm_pt_t pt, sc_rsrc_t resource)

This function assigns ownership of a resource to a partition.

sc_err_t sc_rm_set_resource_movable (sc_ipc_t ipc, sc_rsrc_t resource_fst, sc_rsrc_t resource_lst, sc_bool_t movable)

This function flags resources as movable or not.

sc_err_t sc_rm_set_subsys_rsrc_movable (sc_ipc_t ipc, sc_rsrc_t resource, sc_bool_t movable)

This function flags all of a subsystem's resources as movable or not.

• sc_err_t sc_rm_set_master_attributes (sc_ipc_t ipc, sc_rsrc_t resource, sc_rm_spa_t sa, sc_rm_spa_t pa, sc_bool_t smmu_bypass)

This function sets attributes for a resource which is a bus master (i.e.

• sc_err_t sc_rm_set_master_sid (sc_ipc_t ipc, sc_rsrc_t resource, sc_rm_sid_t sid)

This function sets the StreamID for a resource which is a bus master (i.e.

sc_err_t sc_rm_set_peripheral_permissions (sc_ipc_t ipc, sc_rsrc_t resource, sc_rm_pt_t pt, sc_rm_perm_t perm)

This function sets access permissions for a peripheral resource.

sc_bool_t sc_rm_is_resource_owned (sc_ipc_t ipc, sc_rsrc_t resource)

This function gets ownership status of a resource.

sc_err_t sc_rm_get_resource_owner (sc_ipc_t ipc, sc_rsrc_t resource, sc_rm_pt_t *pt)

This function is used to get the owner of a resource.

sc_bool_t sc_rm_is_resource_master (sc_ipc_t ipc, sc_rsrc_t resource)

This function is used to test if a resource is a bus master.

sc_bool_t sc_rm_is_resource_peripheral (sc_ipc_t ipc, sc_rsrc_t resource)

This function is used to test if a resource is a peripheral.

sc_err_t sc_rm_get_resource_info (sc_ipc_t ipc, sc_rsrc_t resource, sc_rm_sid_t *sid)

This function is used to obtain info about a resource.

Memory Region Functions

• sc_err_t sc_rm_memreg_alloc (sc_ipc_t ipc, sc_rm_mr_t *mr, sc_faddr_t addr_start, sc_faddr_t addr_end)

This function requests that the SC create a new memory region.

sc_err_t sc_rm_memreg_split (sc_ipc_t ipc, sc_rm_mr_t mr, sc_rm_mr_t *mr_ret, sc_faddr_t addr_start, sc_faddr_t addr_end)

This function requests that the SC split an existing memory region.

sc_err_t sc_rm_memreg_frag (sc_ipc_t ipc, sc_rm_mr_t *mr_ret, sc_faddr_t addr_start, sc_faddr_t addr_end)

This function requests that the SC fragment a memory region.

sc_err_t sc_rm_memreg_free (sc_ipc_t ipc, sc_rm_mr_t mr)

This function frees a memory region.

- sc_err_t sc_rm_find_memreg (sc_ipc_t ipc, sc_rm_mr_t *mr, sc_faddr_t addr_start, sc_faddr_t addr_end)
 Internal SC function to find a memory region.
- sc err t sc rm assign memreg (sc ipc t ipc, sc rm pt t pt, sc rm mr t mr)

This function assigns ownership of a memory region.

- sc_err_t sc_rm_set_memreg_permissions (sc_ipc_t ipc, sc_rm_mr_t mr, sc_rm_pt_t pt, sc_rm_perm_t perm)
 This function sets access permissions for a memory region.
- sc_err_t sc_rm_set_memreg_iee (sc_ipc_t ipc, sc_rm_mr_t mr, sc_rm_det_t det, sc_rm_rmsg_t rmsg)
 This function configures the IEE parameters for a memory region.
- sc_bool_t sc_rm_is_memreg_owned (sc_ipc_t ipc, sc_rm_mr_t mr)

This function gets ownership status of a memory region.

• sc_err_t sc_rm_get_memreg_info (sc_ipc_t ipc, sc_rm_mr_t mr, sc_faddr_t *addr_start, sc_faddr_t *addr_end)

This function is used to obtain info about a memory region.

Pad Functions

sc_err_t sc_rm_assign_pad (sc_ipc_t ipc, sc_rm_pt_t pt, sc_pad_t pad)

This function assigns ownership of a pad to a partition.

- sc_err_t sc_rm_set_pad_movable (sc_ipc_t ipc, sc_pad_t pad_fst, sc_pad_t pad_lst, sc_bool_t movable)
 This function flags pads as movable or not.
- sc_bool_t sc_rm_is_pad_owned (sc_ipc_t ipc, sc_pad_t pad)

This function gets ownership status of a pad.

Debug Functions

void sc_rm_dump (sc_ipc_t ipc)

This function dumps the RM state for debug.

13.5.1 Detailed Description

Module for the Resource Management (RM) service.

The following SCFW resource manager (RM) code is an example of how to create a partition for an M4 core and its resources. This could be run from another core, an SCD, or be embedded into board.c.

The ipc parameter most functions take is a handle to the IPC channel opened to communicate to the SC. It is implementation defined. Most API ports include an sc_ipc_open() and sc_ipc_close() function to manage this. The sc_ipc_open() takes an argument to identify the communication channel (usually the MU address) and returns the IPC handle that all API calls should then use.

Note all this configuration can be done with the M4 subsystem powered off. It will be loaded when the M4 is powered on.

```
1 sc_rm_pt_t pt_m4_0;
2 sc_rm_mr_t mr_ddr1, mr_ddr2, mr_m4_0;
3
4 //sc_rm_dump(ipc);
5
6 /* Mark all resources as not movable */
```

```
7 sc_rm_set_resource_movable(ipc, SC_R_ALL, SC_R_ALL, SC_FALSE);
8 sc_rm_set_pad_movable(ipc, SC_P_ALL, SC_P_ALL, SC_FALSE);
10 /* Allocate M4_0 partition */
11 sc_rm_partition_alloc(ipc, &pt_m4_0, SC_FALSE, SC_TRUE, SC_FALSE, SC_TRUE,
12
      SC FALSE);
14 /* Mark all M4_0 subsystem resources as movable */
15 sc_rm_set_subsys_rsrc_movable(ipc, SC_R_M4_0_PID0, SC_TRUE);
16 sc_rm_set_pad_movable(ipc,SC_P_ADC_IN3,SC_P_ADC_IN2, SC_TRUE);
18 /\star Keep some resources in the parent partition \star/
19 sc_rm_set_resource_movable(ipc, SC_R_M4_0_PID1, SC_R_M4_0_PID4,
21 sc_rm_set_resource_movable(ipc, SC_R_M4_0_MU_0A0, SC_R_M4_0_MU_0A3,
      SC_FALSE);
23
24 /* Move some resource not in the M4_0 subsystem */
25 sc_rm_set_resource_movable(ipc, SC_R_IRQSTR_M4_0, SC_R_IRQSTR_M4_0,
      SC TRUE);
27 sc rm set resource movable (ipc, SC R M4 1 MU 0A0, SC R M4 1 MU 0A0,
28
      SC TRUE);
30 /* Move everything flagged as movable */
31 sc_rm_move_all(ipc, pt, pt_m4_0, SC_TRUE, SC_TRUE);
33 /* Allow all to access the SEMA42 */
34 sc_rm_set_peripheral_permissions(ipc, pt_m4_0, SC_R_M4_0_SEMA42,
      SC_RM_PT_ALL, SC_RM_PERM_FULL);
3.5
36
37 /* Move M4 0 TCM */
38 sc_rm_find_memreg(ipc, &mr_m4_0, 0x034FE0000, 0x034FE0000);
39 sc_rm_assign_memreg(ipc, pt_m4_0, mr_m4_0);
40
41 /* Split DDR space, assign 0x88000000-0x8FFFFFFF to CM4 */
42 sc_rm_find_memreg(ipc, &mr_ddr1, 0x080000000, 0x080000000);
43 sc_rm_memreg_split(ipc, mr_ddr1, &mr_ddr2, 0x090000000, 0x0FFFFFFFF);
45 /* Reserve DDR for M4 0 */
46 sc_rm_memreg_split(ipc, mr_ddr1, &mr_m4_0, 0x088000000, 0x08FFFFFFF);
47 sc_rm_assign_memreg(ipc, pt_m4_0, mr_m4_0);
48
49 //sc_rm_dump(ipc);
```

First, variables are declared to hold return partition and memory region handles.

```
0 sc_rm_pt_t pt_m4_0;
1 sc_rm_mr_t mr_ddr1, mr_ddr2, mr_m4_0;
```

Optionally, call sc_rm_dump() to dump the state of the RM to the SCFW debug UART.

```
2 //sc_rm_dump(ipc);
```

Mark resources and pins as movable or not movable to the new partition. By default, all resources are marked as movable. Marking all as movable or not movable first depends on how many resources are to be moved and which is the most efficient. Marking does not move the resource yet. Note, that it is also possible to assign resources individually using sc rm assign resource().

```
4 /* Mark all resources as not movable */
6 sc_rm_set_resource_movable(ipc, SC_R_ALL, SC_R_ALL, SC_FALSE);
7 sc_rm_set_pad_movable(ipc, SC_P_ALL, SC_P_ALL, SC_FALSE);
```

The sc_rm_partition_alloc() function call requests that the SC create a new partition to contain the M4 system. This function does not access the hardware at all. It allocates a new partition and returns a partition handle (pt_m4_0). The partition is marked non-secure as secure=SC_FALSE. Marking as non-secure prevents subsequent functions from configuring masters in this partition to assert the TZPROT signal.

```
8 /* Allocate M4_0 partition */
10 sc_rm_partition_alloc(ipc, &pt_m4_0, SC_FALSE, SC_TRUE, SC_FALSE, SC_TRUE,
11 SC FALSE);
```

Now mark some resources as movable. sc_rm_set_subsys_rsrc_movable() can be used to mark all resources in a HW subsystem. sc_rm_set_pad_movable() is used to mark some pads (i.e. pins) as movable.

```
12 /* Mark all M4_0 subsystem resources as movable */
14 sc_rm_set_subsys_rsrc_movable(ipc, SC_R_M4_0_PID0, SC_TRUE);
15 sc_rm_set_pad_movable(ipc, SC_P_ADC_IN3, SC_P_ADC_IN2, SC_TRUE);
```

Then mark some resources in the M4_0 subsystem (all marked movable above) as not movable using sc_rm_set_resource_movable() In this case the process IDs used to access memory owned by other partitions as well as the MUs used for others to communicate with the M4 need to be left with the parent partition.

Move some resources in other subsystems. The new partition will require access to the IRQ Steer module which routes interrupts to this M4's NVIC. In this example, it also needs access to one of the M4 1 MUs.

```
22 /* Move some resource not in the M4_0 subsystem */
24 sc_rm_set_resource_movable(ipc, SC_R_IRQSTR_M4_0, SC_R_IRQSTR_M4_0,
```

Now assign (i.e. move) everything marked as movable. At this point, all these resources are in the new partition and HW will enforce isolation.

```
25 /* Move everything flagged as movable */
30 sc_rm_move_all(ipc, pt, pt_m4_0, SC_TRUE, SC_TRUE);
```

Allow others to access some of the new partitions resources. In this case, the SEMA42 IP works by allowing multiple CPUs to access and acquire the semaphore.

```
31 /* Allow all to access the SEMA42 */
33 sc_rm_set_peripheral_permissions(ipc, pt_m4_0, SC_R_M4_0_SEMA42,
34 SC_RM_PT_ALL, SC_RM_PERM_FULL);
```

Now assign the M4_0 TCM to the M4 partition. Note the M4 can always access its TCM. This action prevents the parent (current owner of the M4 TCM) from accessing. This should only be done after code for the M4 has been loaded into the TCM. Code loading will require the M4 subsystem already be powered on.

```
35 /* Move M4 0 TCM */
37 sc_rm_find_memreg(ipc, &mr_m4_0, 0x034FE0000, 0x034FE0000);
38 sc_rm_assign_memreg(ipc, pt_m4_0, mr_m4_0);
```

Next is to carve out some DDR for the M4. In this case, the memory is in the middle of the DDR so the DDR has to be split into three regions. First is to split off the end portion and keep this with the parent. Next is then to split off the end of the remaining part and assign this to the M4.

```
39 /* Split DDR space, assign 0x88000000-0x8FFFFFFF to CM4 */
41 sc_rm_find_memreg(ipc, &mr_ddr1, 0x080000000, 0x080000000);
42 sc_rm_memreg_split(ipc, mr_ddr1, &mr_ddr2, 0x090000000, 0x0FFFFFFFF);
43
44 /* Reserve DDR for M4_0 */
45 sc_rm_memreg_split(ipc, mr_ddr1, &mr_m4_0, 0x088000000, 0x08FFFFFFF);
46 sc_rm_assign_memreg(ipc, pt_m4_0, mr_m4_0);
```

Optionally, call sc_rm_dump() to dump the state of the RM to the SCFW debug UART. 47 //sc_rm_dump(ipc);

At this point, the M4 can be powered on (if not already) and the M4 can be started using sc_pm_boot(). Do NOT start the CPU using sc_pm_cpu_start() as that function is for starting a secondary CPU in the calling core's partition. In this

case, the core is in another partition that needs to be booted.

Refer to the SoC-specific Resource List for a list of resources.

13.5.2 Typedef Documentation

```
13.5.2.1 sc_rm_perm_t

typedef uint8_t sc_rm_perm_t
```

This type is used to declare a resource/memory region access permission.

Refer to the XRDC2 Block Guide for more information.

```
13.5.2.2 sc_rm_rmsg_t
typedef uint8_t sc_rm_rmsg_t
```

This type is used to assign an RMSG value to a memory region.

This value is sent to the IEE.

13.5.3 Function Documentation

13.5.3.1 sc_rm_partition_alloc()

This function requests that the SC create a new resource partition.

Parameters

in	ipc	IPC handle
out	pt	return handle for partition; used for subsequent function calls associated with this partition
in	secure	boolean indicating if this partition should be secure; only valid if caller is secure
in	isolated	boolean indicating if this partition should be HW isolated via XRDC; set SC_TRUE if new DID is desired
in	restricted	boolean indicating if this partition should be restricted; set SC_TRUE if masters in this partition cannot create new partitions
in	grant	boolean indicating if this partition should always grant access and control to the parent
in	coherent	boolean indicating if this partition is conferent, set SC_TRUE if only this partition will contain both AP clusters and they will be coherent via the CCI

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- · SC_ERR_NOACCESS if caller's partition is restricted,
- · SC ERR PARM if caller's partition is not secure but a new secure partition is requested,
- · SC_ERR_LOCKED if caller's partition is locked,
- SC_ERR_UNAVAILABLE if partition table is full (no more allocation space)

Marking as non-secure prevents subsequent functions from configuring masters in this partition to assert the secure signal. Basically, if TrustZone SW is used, the Cortex-A cores and peripherals the TZ SW will use should be in a secure partition. Almost all other partitions (for a non-secure OS or M4 cores) should be in non-secure partitions.

Isolated should be true for almost all partitions. The exception is the non-secure partition for a Cortex-A core used to run a non-secure OS. This isn't isolated by domain but is instead isolated by the TZ security hardware.

If restricted then the new partition is limited in what functions it can call, especially those associated with managing partitions.

The grant option is usually used to isolate a bus master's traffic to specific memory without isolating the peripheral interface of the master or the API controls of that master. This is only used when creating a sub-partition with no CPU. It's useful to separate out a master and the memory it uses.

13.5.3.2 sc_rm_set_confidential()

This function makes a partition confidential.

Parameters

in	ipc	IPC handle
in	pt	handle of partition that is granting
in	retro	retroactive

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

SC PARM if pt out of range,

- SC_ERR_NOACCESS if caller's not allowed to change pt
- SC ERR LOCKED if partition pt is locked

Call to make a partition confidential. Confidential means only this partition should be able to grant access permissions to this partition.

If retroactive, then all resources owned by other partitions will have access rights for this partition removed, even if locked.

13.5.3.3 sc_rm_partition_free()

This function frees a partition and assigns all resources to the caller.

Parameters

in	ipc	IPC handle
in	pt	handle of partition to free

Returns

Returns an error code (SC ERR NONE = success).

Return errors:

- · SC_ERR_NOACCESS if caller's partition is restricted,
- SC PARM if pt out of range or invalid,
- SC ERR NOACCESS if pt is the SC partition,
- SC_ERR_NOACCESS if caller's partition is not the parent of pt,
- SC_ERR_LOCKED if pt or caller's partition is locked

All resources, memory regions, and pads are assigned to the caller/parent. The partition watchdog is disabled (even if locked). DID is freed.

13.5.3.4 sc_rm_get_did()

This function returns the DID of a partition.

Parameters

in <i>ipc</i>	IPC handle
---------------	------------

Returns

Returns the domain ID (DID) of the caller's partition.

The DID is a SoC-specific internal ID used by the HW resource protection mechanism. It is only required by clients when using the SEMA42 module as the DID is sometimes connected to the master ID.

13.5.3.5 sc_rm_partition_static()

This function forces a partition to use a specific static DID.

Parameters

in	ipc	IPC handle
in	pt	handle of partition to assign did
in	did	static DID to assign

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC_ERR_NOACCESS if caller's partition is restricted,
- SC_PARM if pt or did out of range,
- SC_ERR_NOACCESS if caller's partition is not the parent of pt,
- SC_ERR_LOCKED if pt is locked

Assumes no assigned resources or memory regions yet! The number of static DID is fixed by the SC at boot.

13.5.3.6 sc_rm_partition_lock()

This function locks a partition.

Parameters

in	ipc	IPC handle
in	pt	handle of partition to lock

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC_PARM if pt out of range,
- SC_ERR_NOACCESS if caller's partition is not the parent of pt

If a partition is locked it cannot be freed, have resources/pads assigned to/from it, memory regions created/assigned, DID changed, or parent changed.

13.5.3.7 sc_rm_get_partition()

This function gets the partition handle of the caller.

Parameters

in	ipc	IPC handle
out	pt	return handle for caller's partition

Returns

Returns an error code (SC_ERR_NONE = success).

13.5.3.8 sc_rm_set_parent()

This function sets a new parent for a partition.

Parameters

in	ipc	IPC handle
in	pt	handle of partition for which parent is to be changed
in	pt_parent	handle of partition to set as parent

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- · SC_ERR_NOACCESS if caller's partition is restricted,
- SC_PARM if arguments out of range or invalid,
- SC_ERR_NOACCESS if caller's partition is not the parent of pt,
- · SC_ERR_LOCKED if either partition is locked

13.5.3.9 sc_rm_move_all()

This function moves all movable resources/pads owned by a source partition to a destination partition.

It can be used to more quickly set up a new partition if a majority of the caller's resources are to be moved to a new partition.

Parameters

in	ipc	IPC handle
in	pt_src	handle of partition from which resources should be moved from
in	pt_dst	handle of partition to which resources should be moved to
in	move_rsrc	boolean to indicate if resources should be moved
in	move_pads	boolean to indicate if pads should be moved

Returns

Returns an error code (SC_ERR_NONE = success).

By default, all resources are movable. This can be changed using the sc_rm_set_resource_movable() function. Note all masters defaulted to SMMU bypass.

Return errors:

- · SC_ERR_NOACCESS if caller's partition is restricted,
- · SC PARM if arguments out of range or invalid,
- SC_ERR_NOACCESS if caller's partition is not pt_src or the parent of pt_src,
- SC_ERR_LOCKED if either partition is locked

13.5.3.10 sc_rm_assign_resource()

This function assigns ownership of a resource to a partition.

Parameters

in	ipc	IPC handle
in	pt	handle of partition to which resource should be assigned
in	resource	resource to assign

This function assigned a resource to a partition. This partition is then the owner. All resources always have an owner (one owner). The owner has various rights to make API calls affecting the resource. Ownership does not imply access to the peripheral itself (that is based on access rights).

Returns

Returns an error code (SC_ERR_NONE = success).

This action resets the resource's master and peripheral attributes. Privilege attribute will be PASSTHRU, security attribute will be ASSERT if the partition is secure and NEGATE if it is not, and masters will defaulted to SMMU bypass. Access permissions will reset to SEC_RW for the owning partition only for secure partitions, FULL for non-secure. Default is no access by other partitions.

Return errors:

SC ERR NOACCESS if caller's partition is restricted,

- SC_PARM if arguments out of range or invalid,
- SC_ERR_NOACCESS if caller's partition is not the resource owner or parent of the owner,
- SC_ERR_LOCKED if the owning partition or pt is locked

13.5.3.11 sc_rm_set_resource_movable()

This function flags resources as movable or not.

Parameters

in	ipc	IPC handle
in	resource_fst	first resource for which flag should be set
in	resource_lst	last resource for which flag should be set
in	movable	movable flag (SC_TRUE is movable)

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- · SC_PARM if resources are out of range,
- SC_ERR_NOACCESS if caller's partition is not a parent of a resource owner,
- · SC_ERR_LOCKED if the owning partition is locked

This function is used to determine the set of resources that will be moved using the sc_rm_move_all() function. All resources are movable by default so this function is normally used to prevent a set of resources from moving.

13.5.3.12 sc_rm_set_subsys_rsrc_movable()

This function flags all of a subsystem's resources as movable or not.

Parameters

in	ipc	IPC handle
in	resource	resource to use to identify subsystem
in	movable	movable flag (SC_TRUE is movable)

A subsystem is a physical grouping within the chip of related resources; this is SoC specific. This function is used to optimize moving resource for these groupings, for instance, an M4 core and its associated resources. The list of subsystems and associated resources can be found in the SoC-specific API document Resources chapter.

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

· SC_ERR_PARM if a function argument is out of range

Note resource is used to find the associated subsystem. Only resources owned by the caller are set.

13.5.3.13 sc_rm_set_master_attributes()

This function sets attributes for a resource which is a bus master (i.e.

capable of DMA).

Parameters

in	ipc	IPC handle
in	resource	master resource for which attributes should apply
in	sa	security attribute
in	ра	privilege attribute
in	smmu_bypass	SMMU bypass mode

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- · SC_ERR_NOACCESS if caller's partition is restricted,
- · SC_PARM if arguments out of range or invalid,
- SC_ERR_NOACCESS if caller's partition is not a parent of the resource owner,
- · SC_ERR_LOCKED if the owning partition is locked

Masters are IP blocks that generate bus transactions. This function configures how the isolation HW will define these bus transactions from the specified master. Note the security attribute will only be changed if the caller's partition is secure.

Note an IP block can be both a master and peripheral (have both a programming model and generate bus transactions).

13.5.3.14 sc_rm_set_master_sid()

This function sets the StreamID for a resource which is a bus master (i.e.

capable of DMA).

Parameters

in	ipc	IPC handle
in	resource	master resource for which attributes should apply
in	sid	StreamID

Returns

Returns an error code (SC ERR NONE = success).

Return errors:

- · SC_ERR_NOACCESS if caller's partition is restricted,
- SC_PARM if arguments out of range or invalid,
- SC_ERR_NOACCESS if caller's partition is not the resource owner or parent of the owner,
- · SC_ERR_LOCKED if the owning partition is locked

This function configures the SID attribute associated with all bus transactions from this master. Note 0 is not a valid SID as it is reserved to indicate bypass.

13.5.3.15 sc_rm_set_peripheral_permissions()

This function sets access permissions for a peripheral resource.

Parameters

in	ipc	IPC handle
in	resource	peripheral resource for which permissions should apply
in	pt	handle of partition <i>perm</i> should by applied for
in	perm	permissions to apply to resource for pt

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- · SC_PARM if arguments out of range or invalid,
- SC_ERR_NOACCESS if caller's partition is not the resource owner or parent of the owner,
- SC_ERR_LOCKED if the owning partition is locked
- SC_ERR_LOCKED if the pt is confidential and the caller isn't pt

Peripherals are IP blocks that have a programming model that can be accessed.

This function configures how the isolation HW will restrict access to a peripheral based on the attributes of a transaction from bus master. It also allows the access permissions of SC_R_SYSTEM to be set.

Note an IP block can be both a master and peripheral (have both a programming model and generate bus transactions).

13.5.3.16 sc_rm_is_resource_owned()

This function gets ownership status of a resource.

Parameters

in	ipc	IPC handle
in	resource	resource to check

Returns

Returns a boolean (SC_TRUE if caller's partition owns the resource).

If resource is out of range then SC_FALSE is returned.

```
13.5.3.17 sc_rm_get_resource_owner()
```

This function is used to get the owner of a resource.

Parameters

in	ipc	IPC handle
in	resource	resource to check
out	pt	pointer to return owning partition

Returns

Returns a boolean (SC_TRUE if the resource is a bus master).

Return errors:

· SC_PARM if arguments out of range or invalid

If resource is out of range then SC_ERR_PARM is returned.

13.5.3.18 sc_rm_is_resource_master()

This function is used to test if a resource is a bus master.

Parameters

in	ipc	IPC handle
in	resource	resource to check

Masters are IP blocks that generate bus transactions. Note an IP block can be both a master and peripheral (have both a programming model and generate bus transactions).

Returns

Returns a boolean (SC_TRUE if the resource is a bus master).

If resource is out of range then SC FALSE is returned.

13.5.3.19 sc_rm_is_resource_peripheral()

This function is used to test if a resource is a peripheral.

Parameters

in	ipc	IPC handle
in	resource	resource to check

Peripherals are IP blocks that have a programming model that can be accessed. Note an IP block can be both a master and peripheral (have both a programming model and generate bus transactions)

Returns

Returns a boolean (SC_TRUE if the resource is a peripheral).

If resource is out of range then SC_FALSE is returned.

13.5.3.20 sc_rm_get_resource_info()

This function is used to obtain info about a resource.

Parameters

in	ipc	IPC handle
in	resource	resource to inquire about
out	sid	pointer to return StreamID

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

• SC_PARM if resource is out of range

13.5.3.21 sc_rm_memreg_alloc()

This function requests that the SC create a new memory region.

Parameters

in	ipc	IPC handle
out	mr	return handle for region; used for subsequent function calls associated with this region
in	addr_start	start address of region (physical)
in	addr_end	end address of region (physical)

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC_ERR_PARM if the new memory region is misaligned,
- SC_ERR_LOCKED if caller's partition is locked,
- SC_ERR_PARM if the new memory region spans multiple existing regions,
- SC_ERR_NOACCESS if caller's partition does not own the memory containing the new region,
- SC_ERR_UNAVAILABLE if memory region table is full (no more allocation space)

This function will create a new memory region. The area covered by the new region must already exist in a memory region owned by the caller. The result will be two memory regions, the new one overlapping the existing one. The new region has higher priority. See the XRDC2 MRC documentation for how it resolves access permissions in this case. By default, permissions will mirror the parent region.

13.5.3.22 sc_rm_memreg_split()

This function requests that the SC split an existing memory region.

Parameters

in	ipc	IPC handle	
in	mr	handle of memory region to split	
out	mr_ret	return handle for new region; used for subsequent function calls associated with this region	
in	addr_start	start address of region (physical)	
in	addr_end	end address of region (physical)	

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC ERR PARM if the new memory region is not start/end part of mr,
- SC_ERR_LOCKED if caller's partition is locked,
- SC_ERR_PARM if the new memory region spans multiple existing regions,
- SC ERR NOACCESS if caller's partition does not own the memory containing the new region,
- SC ERR BUSY if the region is coincident with another region,
- SC_ERR_UNAVAILABLE if memory region table is full (no more allocation space)

This function will take an existing region and split it into two, non-overlapping regions. Note the new region must start or end on the split region. Permissions will mirror the parent region.

13.5.3.23 sc_rm_memreg_frag()

This function requests that the SC fragment a memory region.

Parameters

in	ipc	IPC handle	
out	mr_ret	return handle for new region; used for subsequent function calls associated with this region	
in	addr_start	start address of region (physical)	
in	addr_end	end address of region (physical)	

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- · SC_ERR_LOCKED if caller's partition is locked,
- SC_ERR_PARM if the new memory region spans multiple existing regions,
- SC_ERR_NOACCESS if caller's partition does not own the memory containing the new region,
- SC_ERR_BUSY if the region is coincident with another region,
- SC ERR UNAVAILABLE if memory region table is full (no more allocation space)

This function finds the memory region containing the address range. It then splits it as required and returns the extracted region. The result is 2-3 non-overlapping regions, depending on how the new region aligns with existing regions. Permissions will mirror the parent region.

13.5.3.24 sc_rm_memreg_free()

This function frees a memory region.

Parameters

in	ipc	IPC handle	
in	mr	handle of memory region to free	

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

• SC PARM if mr out of range or invalid,

- SC_ERR_NOACCESS if caller's partition is not a parent of mr,
- SC_ERR_LOCKED if the owning partition of mr is locked

13.5.3.25 sc_rm_find_memreg()

Internal SC function to find a memory region.

See also

```
sc_rm_find_memreg().
```

This function finds a memory region.

Parameters

in	ipc	IPC handle	
out	mr	return handle for region; used for subsequent function calls associated with this region	
in	addr_start	start address of region to search for	
in	addr_end	end address of region to search for	

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

· SC_ERR_NOTFOUND if region not found,

Searches only for regions owned by the caller. Finds first region containing the range specified.

13.5.3.26 sc_rm_assign_memreg()

This function assigns ownership of a memory region.

Parameters

in	ipc	IPC handle
in	pt	handle of partition to which memory region should be assigned
in	mr	handle of memory region to assign

Returns

Returns an error code (SC_ERR_NONE = success).

This function assigns a memory region to a partition. This partition is then the owner. All regions always have an owner (one owner). The owner has various rights to make API calls affecting the region. Ownership does not imply access to the memory itself (that is based on access rights).

Return errors:

- SC_PARM if arguments out of range or invalid,
- SC_ERR_NOACCESS if caller's partition is not the mr owner or parent of the owner,
- SC_ERR_LOCKED if the owning partition or pt is locked

13.5.3.27 sc_rm_set_memreg_permissions()

This function sets access permissions for a memory region.

Parameters

in	ipc	IPC handle
in	mr	handle of memory region for which permissions should apply
in	pt	handle of partition perm should by applied for
in	perm	permissions to apply to <i>mr</i> for <i>pt</i>

This operates on the memory region specified. If SC_RM_PT_ALL is specified then it operates on all the regions owned by the caller that exist at the time of the call.

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- · SC_PARM if arguments out of range or invalid,
- SC_ERR_NOACCESS if caller's partition is not the region owner or parent of the owner,
- · SC_ERR_LOCKED if the owning partition is locked
- SC_ERR_LOCKED if the pt is confidential and the caller isn't pt

This function configures how the HW isolation will restrict access to a memory region based on the attributes of a transaction from bus master.

13.5.3.28 sc_rm_set_memreg_iee()

This function configures the IEE parameters for a memory region.

Parameters

in	ipc	IPC handle	
	'		
in	mr	handle of memory region to check	
in	det	0 = normal, 1 = encrypted	
in	rmsg	IEE region (0-7)	

Caller must own SC_R_IEE_Rn where n is rmsg.

Returns

Returns an error code (SC ERR NONE = success).

Return errors:

- · SC_PARM if arguments out of range or invalid,
- · SC ERR LOCKED if the owning partition is locked
- SC_ERR_NOACCESS if caller's partition is not the region owner or parent of the owner
- SC_ERR_UNAVAILABLE if caller's partition is not the IEE region resource owner

13.5.3.29 sc_rm_is_memreg_owned()

This function gets ownership status of a memory region.

Parameters

in	ipc	IPC handle	
in	mr	handle of memory region to check	

Returns

Returns a boolean (SC_TRUE if caller's partition owns the memory region).

If mr is out of range then SC_FALSE is returned.

13.5.3.30 sc_rm_get_memreg_info()

This function is used to obtain info about a memory region.

Parameters

in	ipc	IPC handle	
in	mr	handle of memory region to inquire about	
out	addr_start	pointer to return start address	
out	addr_end	pointer to return end address	

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

• SC_PARM if mr is out of range

13.5.3.31 sc_rm_assign_pad()

This function assigns ownership of a pad to a partition.

Parameters

	in	ipc	IPC handle
Ī	in	pt	handle of partition to which pad should be assigned
Ī	in	pad	pad to assign

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- · SC_ERR_NOACCESS if caller's partition is restricted,
- · SC_PARM if arguments out of range or invalid,
- SC_ERR_NOACCESS if caller's partition is not the pad owner or parent of the owner,
- SC_ERR_LOCKED if the owning partition or pt is locked

13.5.3.32 sc_rm_set_pad_movable()

This function flags pads as movable or not.

Parameters

in	ipc	IPC handle	
in <i>pad_fst</i>		first pad for which flag should be set	
in <i>pad_lst</i>		last pad for which flag should be set	
in	movable	movable flag (SC_TRUE is movable)	

This function assigned a pad to a partition. This partition is then the owner. All pads always have an owner (one owner). The owner has various rights to make API calls affecting the pad.

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- SC_PARM if pads are out of range,
- · SC_ERR_NOACCESS if caller's partition is not a parent of a pad owner,
- · SC ERR LOCKED if the owning partition is locked

This function is used to determine the set of pads that will be moved using the sc_rm_move_all() function. All pads are movable by default so this function is normally used to prevent a set of pads from moving.

```
13.5.3.33 sc_rm_is_pad_owned()
```

This function gets ownership status of a pad.

Parameters

in	ipc	IPC handle
in	pad	pad to check

Returns

Returns a boolean (SC_TRUE if caller's partition owns the pad).

If pad is out of range then SC_FALSE is returned.

```
13.5.3.34 sc_rm_dump()
```

```
void sc_rm_dump (
sc_ipc_t ipc )
```

This function dumps the RM state for debug.

Parameters

in	ipc	IPC handle

13.6 SECO: Security Service

Module for the Security (SECO) service.

Typedefs

typedef uint8_t sc_seco_auth_cmd_t

This type is used to issue SECO authenticate commands.

typedef uint32_t sc_seco_rng_stat_t

This type is used to return the RNG initialization status.

Defines for sc_seco_auth_cmd_t

#define SC_SECO_AUTH_CONTAINER 0U

Authenticate container.

#define SC_SECO_VERIFY_IMAGE 1U

Verify image.

#define SC_SECO_REL_CONTAINER 2U

Release container.

#define SC_SECO_AUTH_SECO_FW 3U

SECO Firmware.

#define SC_SECO_AUTH_HDMI_TX_FW 4U

HDMI TX Firmware.

#define SC_SECO_AUTH_HDMI_RX_FW 5U

HDMI RX Firmware.

#define SC_SECO_EVERIFY_IMAGE 6U

Enhanced verify image.

Defines for seco_rng_stat_t

- #define SC_SECO_RNG_STAT_UNAVAILABLE 0U
 - Unable to initialize the RNG.
- #define SC_SECO_RNG_STAT_INPROGRESS 1U

Initialization is on-going.

• #define SC_SECO_RNG_STAT_READY 2U

Initialized.

Image Functions

- sc_err_t sc_seco_image_load (sc_ipc_t ipc, sc_faddr_t addr_src, sc_faddr_t addr_dst, uint32_t len, sc_bool_t fw)

 This function loads a SECO image.
- sc_err_t sc_seco_authenticate (sc_ipc_t ipc, sc_seco_auth_cmd_t cmd, sc_faddr_t addr)

This function is used to authenticate a SECO image or command.

sc_err_t sc_seco_enh_authenticate (sc_ipc_t ipc, sc_seco_auth_cmd_t cmd, sc_faddr_t addr, uint32_t mask1, uint32_t mask2)

This function is used to authenticate a SECO image or command.

Lifecycle Functions

sc err t sc seco forward lifecycle (sc ipc t ipc, uint32 t change)

This function updates the lifecycle of the device.

sc_err_t sc_seco_return_lifecycle (sc_ipc_t ipc, sc_faddr_t addr)

This function updates the lifecycle to one of the return lifecycles.

sc_err_t sc_seco_commit (sc_ipc_t ipc, uint32_t *info)

This function is used to commit into the fuses any new SRK revocation and FW version information that have been found in the primary and secondary containers.

Attestation Functions

sc_err_t sc_seco_attest_mode (sc_ipc_t ipc, uint32_t mode)

This function is used to set the attestation mode.

sc_err_t sc_seco_attest (sc_ipc_t ipc, uint64_t nonce)

This function is used to request attestation.

sc_err_t sc_seco_get_attest_pkey (sc_ipc_t ipc, sc_faddr_t addr)

This function is used to retrieve the attestation public key.

sc_err_t sc_seco_get_attest_sign (sc_ipc_t ipc, sc_faddr_t addr)

This function is used to retrieve attestation signature and parameters.

sc_err_t sc_seco_attest_verify (sc_ipc_t ipc, sc_faddr_t addr)

This function is used to verify attestation.

Key Functions

sc_err_t sc_seco_gen_key_blob (sc_ipc_t ipc, uint32_t id, sc_faddr_t load_addr, sc_faddr_t export_addr, uint16_t max_size)

This function is used to generate a SECO key blob.

sc_err_t sc_seco_load_key (sc_ipc_t ipc, uint32_t id, sc_faddr_t addr)

This function is used to load a SECO key.

Manufacturing Protection Functions

sc_err_t sc_seco_get_mp_key (sc_ipc_t ipc, sc_faddr_t dst_addr, uint16_t dst_size)

This function is used to get the manufacturing protection public key.

• sc_err_t sc_seco_update_mpmr (sc_ipc_t ipc, sc_faddr_t addr, uint8_t size, uint8_t lock)

This function is used to update the manufacturing protection message register.

 sc_err_t sc_seco_get_mp_sign (sc_ipc_t ipc, sc_faddr_t msg_addr, uint16_t msg_size, sc_faddr_t dst_addr, uint16_t dst_size)

This function is used to get the manufacturing protection signature.

Debug Functions

```
    void sc_seco_build_info (sc_ipc_t ipc, uint32_t *version, uint32_t *commit)
```

This function is used to return the SECO FW build info.

• sc_err_t sc_seco_chip_info (sc_ipc_t ipc, uint16_t *lc, uint16_t *monotonic, uint32_t *uid_l, uint32_t *uid_h)

This function is used to return SECO chip info.

sc_err_t sc_seco_enable_debug (sc_ipc_t ipc, sc_faddr_t addr)

This function securely enables debug.

• sc_err_t sc_seco_get_event (sc_ipc_t ipc, uint8_t idx, uint32_t *event)

This function is used to return an event from the SECO error log.

Miscellaneous Functions

sc err t sc seco fuse write (sc ipc t ipc, sc faddr t addr)

This function securely writes a group of fuse words.

sc_err_t sc_seco_patch (sc_ipc_t ipc, sc_faddr_t addr)

This function applies a patch.

sc_err_t sc_seco_set_mono_counter_partition (sc_ipc_t ipc, uint16_t *she)

This function partitions the monotonic counter.

sc err t sc seco set fips mode (sc ipc t ipc, uint8 t mode, uint32 t *reason)

This function configures the SECO in FIPS mode.

sc_err_t sc_seco_start_rng (sc_ipc_t ipc, sc_seco_rng_stat_t *status)

This function starts the random number generator.

• sc_err_t sc_seco_sab_msg (sc_ipc_t ipc, sc_faddr_t addr)

This function sends a generic signed message to the SECO SHE/HSM components.

sc_err_t sc_seco_secvio_enable (sc_ipc_t ipc)

This function is used to enable security violation and tamper interrupts.

sc_err_t sc_seco_secvio_config (sc_ipc_t ipc, uint8_t id, uint8_t access, uint32_t *data0, uint32_t *data1, uint32_t *data2, uint32_t *data3, uint32_t *data4, uint8_t size)

This function is used to read/write SNVS security violation and tamper registers.

sc_err_t sc_seco_secvio_dgo_config (sc_ipc_t ipc, uint8_t id, uint8_t access, uint32_t *data)

This function is used to read/write SNVS security violation and tamper DGO registers.

13.6.1 Detailed Description

Module for the Security (SECO) service.

SECO functions in the SCFW API communicate via a messaging protocol to the Security Controller (SECO). This messaging protocol is documented in the SECO API Reference Guide. There is also a Security Reference Manual (SRM) that documents many of the SECO features.

SECO messages contain error codes defined in the SECO API Reference Guide. These have to be mapped to SC FW error codes. sc_seco_get_event() can be used to obtain SECO-specific error codes recorded in the SECO event log.

SCFW Error Mapping to SECO Errors

SC ERR NOACCESS

- AHAB_INVALID_LIFECYCLE
- AHAB_PERMISSION_DENIED_IND
- · SC ERR IPC
 - AHAB INVALID MESSAGE IND
 - AHAB_CRC_ERROR
 - AHAB_INVALID_OPERATION_IND
- SC_ERR_VERSION
 - AHAB BAD VERSION IND
- SC_ERR_PARM
 - AHAB_BAD_HASH_IND
 - AHAB BAD VALUE IND
 - AHAB_BAD_FUSE_ID_IND
 - AHAB_BAD_CONTAINER_IND
 - AHAB_BAD_KEY_HASH_IND
 - AHAB_NO_VALID_CONTAINER_IND
 - AHAB_MUST_SIGNED_IND
 - AHAB_NO_BID_MATCHING_IND
 - AHAB_UNKNOWN_BID_IND
 - AHAB_UNALIGNED_PAYLOAD_IND
 - AHAB_WRONG_SIZE_IND
 - AHAB_OTP_INVALID_IDX_IND
 - AHAB_ADM_WRONG_LC_IND
 - AHAB_OTP_DED_IND
 - AHAB_BAD_PAYLOAD_IND
 - AHAB_WRONG_ADDRESS_IND
 - AHAB_DMA_FAILURE_IND
 - AHAB_BAD_UID_IND
 - AHAB_INCONSISTENT_PAR_IND
 - AHAB_BAD_MONOTONIC_COUNTER_IND
 - AHAB_BAD_SRK_SET_IND
 - AHAB_BAD_ID_IND
- · SC_ERR_LOCKED
 - AHAB_OTP_LOCKED_IND
 - AHAB_LOCKED_REG_IND
- SC_ERR_UNAVAILABLE
 - AHAB_BID_COLLISION_IND
 - AHAB_OOM_FOR_BLOB_IND
 - AHAB_OOM_FOR_BLOB_EXPORT_IND
 - AHAB_HDCP_DISABLED_IND

- AHAB_NON_SECURE_STATE_IND
- AHAB_DISABLED_FEATURE_IND
- · SC ERR BUSY
 - AHAB_ADM_NOT_READY_IND
 - AHAB TIME OUT IND
- SC_ERR_FAIL
 - AHAB BAD BLOB IND
 - AHAB ENCRYPTION FAILURE IND
 - AHAB DECRYPTION FAILURE IND
 - AHAB BAD CERTIFICATE IND
 - AHAB_OTP_PROGFAIL_IND
 - AHAB_KMEK_GENERATION_FAIL_IND
 - AHAB_BAD_SIGNATURE_IND
 - AHAB_INVALID_KEY_IND
 - AHAB_MUST_ATTEST_IND
 - AHAB_RNG_NOT_STARTED_IND
 - AHAB_SECO_FATAL_FAILURE_IND
 - AHAB_RNG_INST_FAILURE_IND
 - AHAB_NO_AUTHENTICATION_IND
 - AHAB_AUTH_SKIPPED_OR_FAILED_IND
- If no mapping exists, SC_ERR_FAIL will be returned

13.6.2 Function Documentation

13.6.2.1 sc_seco_image_load()

This function loads a SECO image.

Parameters

in	ipc	IPC handle
in	addr_src	address of image source
in	addr_dst	address of image destination
in	len	length of image to load
in	fw/	SC_TRUE = firmware load

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors codes:

- SC_ERR_PARM if word fuse index param out of range or invalid,
- SC_ERR_UNAVAILABLE if SECO not available,
- SC_ERR_IPC if SECO response has bad header tag or size,
- SC_ERR_VERSION if SECO response has bad version,
- Others, see the Security Service Detailed Description section

This is used to load images via the SECO. Examples include SECO Firmware and IVT/CSF data used for authentication. These are usually loaded into SECO TCM. *addr_src* is in secure memory.

See the SECO API Reference Guide for more info.

13.6.2.2 sc_seco_authenticate()

This function is used to authenticate a SECO image or command.

Parameters

in	ipc	IPC handle
in	cmd authenticate command	
in	addr	address of/or metadata

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors codes:

- · SC_ERR_PARM if word fuse index param out of range or invalid,
- SC_ERR_UNAVAILABLE if SECO not available,
- · SC ERR BUSY if SECO is busy with another authentication request,
- SC_ERR_FAIL if SECO response is bad,
- SC ERR IPC if SECO response has bad header tag or size,

- · SC_ERR_VERSION if SECO response has bad version,
- · Others, see the Security Service Detailed Description section

This is used to authenticate a SECO image or issue a security command. *addr* often points to an container. It is also just data (or even unused) for some commands.

Implementation of this command depends on the underlying security architecture of the device. For example, on devices with SECO FW, the following options apply:

- cmd=SC_SECO_AUTH_CONTAINER, addr=container address (sends AHAB_AUTH_CONTAINER_REQ to S← ECO)
- cmd=SC_SECO_VERIFY_IMAGE, addr=image mask (sends AHAB_VERIFY_IMAGE_REQ to SECO)
- cmd=SC_SECO_REL_CONTAINER, addr unused (sends AHAB_RELEASE_CONTAINER_REQ to SECO)
- cmd=SC_SECO_AUTH_HDMI_TX_FW, addr unused (sends AHAB_ENABLE_HDMI_X_REQ with Subsystem=0 to SECO)
- cmd=SC_SECO_AUTH_HDMI_RX_FW, addr unused (sends AHAB_ENABLE_HDMI_X_REQ with Subsystem=1 to SECO)

See the SECO API Reference Guide for more info.

13.6.2.3 sc_seco_enh_authenticate()

This function is used to authenticate a SECO image or command.

This is an enhanced version that has additional mask arguments.

Parameters

in	ipc	IPC handle
in	cmd	authenticate command
in	addr	address of/or metadata
in	mask1	metadata
in	mask2	metadata

Return errors codes:

SC ERR PARM if word fuse index param out of range or invalid,

- SC_ERR_UNAVAILABLE if SECO not available,
- · SC_ERR_BUSY if SECO is busy with another authentication request,
- · SC_ERR_FAIL if SECO response is bad,
- SC_ERR_IPC if SECO response has bad header tag or size,
- SC_ERR_VERSION if SECO response has bad version,
- Others, see the Security Service Detailed Description section

This supports all the commands found in sc_seco_authenticate(). Those commands should set both masks to 0 (except SC_SECO_VERIFY_IMAGE).

New commands are as follows:

- cmd=SC_SECO_VERIFY_IMAGE, addr unused, mask1=image mask, mask2 unused (sends AHAB_VERIFY
 — IMAGE_REQ to SECO)
- cmd=SC_SECO_EVERIFY_IMAGE, addr=container address, mask1=image mask, mask2=move mask (sends AHAB_EVERIFY_IMAGE_REQ to SECO)

See the SECO API Reference Guide for more info.

```
13.6.2.4 sc_seco_forward_lifecycle()
```

This function updates the lifecycle of the device.

Parameters

in	ipc	IPC handle
in	change	desired lifecycle transition

Returns

Returns and error code (SC_ERR_NONE = success).

Return errors codes:

- SC_ERR_UNAVAILABLE if SECO not available,
- SC_ERR_IPC if SECO response has bad header tag or size,
- SC_ERR_VERSION if SECO response has bad version,
- Others, see the Security Service Detailed Description section

This function is used for going from Open to NXP Closed to OEM Closed. Note *change* is NOT the new desired lifecycle. It is a lifecycle transition as documented in the *SECO API Reference Guide*.

If any SECO request fails or only succeeds because the part is in an "OEM open" lifecycle, then a request to transition from "NXP closed" to "OEM closed" will also fail. For example, booting a signed container when the OEM SRK is not fused will succeed, but as it is an abnormal situation, a subsequent request to transition the lifecycle will return an error.

13.6.2.5 sc_seco_return_lifecycle()

This function updates the lifecycle to one of the return lifecycles.

Parameters

in	ipc	IPC handle
in	addr	address of message block

Returns

Returns and error code (SC_ERR_NONE = success).

Return errors codes:

- SC ERR UNAVAILABLE if SECO not available,
- SC_ERR_IPC if SECO response has bad header tag or size,
- SC ERR VERSION if SECO response has bad version,
- · Others, see the Security Service Detailed Description section

Note addr must be a pointer to a signed message block.

To switch back to NXP states (Full Field Return), message must be signed by NXP SRK. For OEM States (Partial Field Return), must be signed by OEM SRK.

See the SECO API Reference Guide for more info.

13.6.2.6 sc_seco_commit()

This function is used to commit into the fuses any new SRK revocation and FW version information that have been found in the primary and secondary containers.

Parameters

in	ipc	IPC handle	
in,out	info	pointer to information type to be committed	

The return info will contain what was actually committed.

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors codes:

- SC_ERR_PARM if info is invalid,
- SC_ERR_UNAVAILABLE if SECO not available,
- SC_ERR_IPC if SECO response has bad header tag or size,
- SC_ERR_VERSION if SECO response has bad version,
- Others, see the Security Service Detailed Description section

13.6.2.7 sc_seco_attest_mode()

This function is used to set the attestation mode.

Only the owner of the SC_R_ATTESTATION resource may make this call.

Parameters

in	ipc	IPC handle
in	mode	mode

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors codes:

- SC_ERR_PARM if mode is invalid,
- SC_ERR_NOACCESS if SC_R_ATTESTATON not owned by caller,

- · SC_ERR_UNAVAILABLE if SECO not available,
- SC_ERR_IPC if SECO response has bad header tag or size,
- SC_ERR_VERSION if SECO response has bad version,
- Others, see the Security Service Detailed Description section

This is used to set the SECO attestation mode. This can be prover or verifier. See the SECO API Reference Guide for more on the supported modes, mode values, and mode behavior.

13.6.2.8 sc_seco_attest()

This function is used to request attestation.

Only the owner of the SC_R_ATTESTATION resource may make this call.

Parameters

in	ipc	IPC handle
in	nonce	unique value

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors codes:

- SC_ERR_NOACCESS if SC_R_ATTESTATON not owned by caller,
- · SC ERR UNAVAILABLE if SECO not available,
- SC_ERR_IPC if SECO response has bad header tag or size,
- · SC ERR VERSION if SECO response has bad version,
- Others, see the Security Service Detailed Description section

This is used to ask SECO to perform an attestation. The result depends on the attestation mode. After this call, the signature can be requested or a verify can be requested.

See the SECO API Reference Guide for more info.

13.6.2.9 sc_seco_get_attest_pkey()

This function is used to retrieve the attestation public key.

Mode must be verifier. Only the owner of the SC_R_ATTESTATION resource may make this call.

Parameters

in	ipc	IPC handle
in	addr	address to write response

Result will be written to *addr*. The *addr* parameter must point to an address SECO can access. It must be 64-bit aligned. There should be 96 bytes of space.

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors codes:

- SC ERR PARM if addr bad or attestation has not been requested,
- SC_ERR_NOACCESS if SC_R_ATTESTATON not owned by caller,
- SC_ERR_UNAVAILABLE if SECO not available,
- SC_ERR_IPC if SECO response has bad header tag or size,
- SC_ERR_VERSION if SECO response has bad version,
- Others, see the Security Service Detailed Description section

See the SECO API Reference Guide for more info.

13.6.2.10 sc_seco_get_attest_sign()

This function is used to retrieve attestation signature and parameters.

Mode must be provider. Only the owner of the SC_R_ATTESTATION resource may make this call.

Parameters

in	ipc	IPC handle
in	addr	address to write response

Result will be written to *addr*. The *addr* parameter must point to an address SECO can access. It must be 64-bit aligned. There should be 120 bytes of space.

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors codes:

- SC_ERR_PARM if addr bad or attestation has not been requested,
- SC_ERR_NOACCESS if SC_R_ATTESTATON not owned by caller,
- SC_ERR_UNAVAILABLE if SECO not available,
- SC_ERR_IPC if SECO response has bad header tag or size,
- SC_ERR_VERSION if SECO response has bad version,
- Others, see the Security Service Detailed Description section

See the SECO API Reference Guide for more info.

```
13.6.2.11 sc seco attest verify()
```

This function is used to verify attestation.

Mode must be verifier. Only the owner of the SC R ATTESTATION resource may make this call.

Parameters

in	ipc	IPC handle
in	addr	address of signature

The addr parameter must point to an address SECO can access. It must be 64-bit aligned.

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors codes:

- SC_ERR_PARM if addr bad or attestation has not been requested,
- SC_ERR_NOACCESS if SC_R_ATTESTATON not owned by caller,
- · SC_ERR_UNAVAILABLE if SECO not available,
- SC ERR FAIL if signature doesn't match,

- · SC_ERR_IPC if SECO response has bad header tag or size,
- SC_ERR_VERSION if SECO response has bad version,
- Others, see the Security Service Detailed Description section

See the SECO API Reference Guide for more info.

```
13.6.2.12 sc_seco_gen_key_blob()
```

This function is used to generate a SECO key blob.

Parameters

in	ipc	IPC handle
in	id	key identifier
in	load_addr	load address
in	export_addr	export address
in	max_size	max export size

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors codes:

- · SC_ERR_PARM if word fuse index param out of range or invalid,
- SC_ERR_UNAVAILABLE if SECO not available,
- SC_ERR_IPC if SECO response has bad header tag or size,
- · SC ERR VERSION if SECO response has bad version,
- Others, see the Security Service Detailed Description section

This function is used to encapsulate sensitive keys in a specific structure called a blob, which provides both confidentiality and integrity protection.

See the SECO API Reference Guide for more info.

13.6.2.13 sc_seco_load_key()

This function is used to load a SECO key.

Parameters

in	ipc	IPC handle
in	id	key identifier
in	addr	key address

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors codes:

- · SC ERR PARM if word fuse index param out of range or invalid,
- SC_ERR_UNAVAILABLE if SECO not available,
- · SC ERR IPC if SECO response has bad header tag or size,
- SC_ERR_VERSION if SECO response has bad version,
- Others, see the Security Service Detailed Description section

This function is used to install private cryptographic keys encapsulated in a blob previously generated by SECO. The controller can be either the IEE or the VPU. The blob header carries the controller type and the key size, as provided by the user when generating the key blob.

See the SECO API Reference Guide for more info.

```
13.6.2.14 sc_seco_get_mp_key()
```

This function is used to get the manufacturing protection public key.

Parameters

in	ipc	IPC handle
in	dst_addr	destination address
in	dst size	destination size

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors codes:

- SC_ERR_PARM if word fuse index param out of range or invalid,
- SC_ERR_UNAVAILABLE if SECO not available,
- SC_ERR_IPC if SECO response has bad header tag or size,
- SC_ERR_VERSION if SECO response has bad version,
- Others, see the Security Service Detailed Description section

This function is supported only in OEM-closed lifecycle. It generates the mfg public key and stores it in a specific location in the secure memory.

See the SECO API Reference Guide for more info.

13.6.2.15 sc_seco_update_mpmr()

This function is used to update the manufacturing protection message register.

Parameters

in	ipc	IPC handle
in	addr	data address
in	size	size
in	lock	lock_reg

Returns

Returns an error code (SC ERR NONE = success).

Return errors codes:

- · SC_ERR_PARM if word fuse index param out of range or invalid,
- · SC_ERR_UNAVAILABLE if SECO not available,
- SC_ERR_IPC if SECO response has bad header tag or size,
- SC ERR VERSION if SECO response has bad version,

• Others, see the Security Service Detailed Description section

This function is supported only in OEM-closed lifecycle. It updates the content of the MPMR (Manufacturing Protection Message register of 256 bits). This register will be appended to the input-data message when generating the signature. Please refer to the CAAM block guide for details.

See the SECO API Reference Guide for more info.

```
13.6.2.16 sc_seco_get_mp_sign()
```

This function is used to get the manufacturing protection signature.

Parameters

in	ipc	IPC handle
in	msg_addr	message address
in	msg_size	message size
in	dst_addr	destination address
in	dst_size	destination size

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors codes:

- SC_ERR_PARM if word fuse index param out of range or invalid,
- SC_ERR_UNAVAILABLE if SECO not available,
- · SC ERR IPC if SECO response has bad header tag or size,
- SC_ERR_VERSION if SECO response has bad version,
- Others, see the Security Service Detailed Description section

This function is used to generate an ECDSA signature for an input-data message and to store it in a specific location in the secure memory. It is only supported in OEM-closed lifecycle. In order to get the ECDSA signature, the RNG must be initialized. In case it has not been started an error will be returned.

See the SECO API Reference Guide for more info.

13.6.2.17 sc_seco_build_info()

This function is used to return the SECO FW build info.

Parameters

in	ipc	IPC handle
out	version	pointer to return build number
out	commit	pointer to return commit ID (git SHA-1)

13.6.2.18 sc_seco_chip_info()

This function is used to return SECO chip info.

Parameters

in	ipc	IPC handle
out	lc	pointer to return lifecycle
out	monotonic	pointer to return monotonic counter
out	uid_l	pointer to return UID (lower 32 bits)
out	uid_h	pointer to return UID (upper 32 bits)

Returns

Returns and error code (SC_ERR_NONE = success).

Return errors codes:

- SC_ERR_UNAVAILABLE if SECO not available,
- SC_ERR_IPC if SECO response has bad header tag or size,
- SC_ERR_VERSION if SECO response has bad version,
- Others, see the Security Service Detailed Description section

13.6.2.19 sc_seco_enable_debug()

This function securely enables debug.

Parameters

in	ipc	IPC handle
in	addr	address of message block

Returns

Returns and error code (SC_ERR_NONE = success).

Return errors codes:

- SC_ERR_UNAVAILABLE if SECO not available,
- SC_ERR_IPC if SECO response has bad header tag or size,
- SC_ERR_VERSION if SECO response has bad version,
- Others, see the Security Service Detailed Description section

Note addr must be a pointer to a signed message block.

See the SECO API Reference Guide for more info.

```
13.6.2.20 sc_seco_get_event()
```

This function is used to return an event from the SECO error log.

Parameters

in	ipc	IPC handle
out	idx	index of event to return
out	event	pointer to return event

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors codes:

- SC_ERR_UNAVAILABLE if SECO not available,
- SC_ERR_IPC if SECO response has bad header tag or size,
- · SC_ERR_VERSION if SECO response has bad version,
- Others, see the Security Service Detailed Description section

Read of idx 0 captures events from SECO. Loop starting with 0 until an error is returned to dump all events.

```
13.6.2.21 sc_seco_fuse_write()
```

This function securely writes a group of fuse words.

Parameters

in	ipc	IPC handle
in	addr	address of message block

Returns

Returns and error code (SC_ERR_NONE = success).

Return errors codes:

- · SC_ERR_UNAVAILABLE if SECO not available,
- SC_ERR_IPC if SECO response has bad header tag or size,
- SC_ERR_VERSION if SECO response has bad version,
- Others, see the Security Service Detailed Description section

Note addr must be a pointer to a signed message block.

See the SECO API Reference Guide for more info.

13.6.2.22 sc_seco_patch()

This function applies a patch.

Parameters

in	ipc	IPC handle
in	addr	address of message block

Returns

Returns and error code (SC_ERR_NONE = success).

Return errors codes:

- · SC ERR UNAVAILABLE if SECO not available,
- · SC_ERR_IPC if SECO response has bad header tag or size,
- SC_ERR_VERSION if SECO response has bad version,
- Others, see the Security Service Detailed Description section

Note *addr* must be a pointer to a signed message block.

See the SECO API Reference Guide for more info.

13.6.2.23 sc_seco_set_mono_counter_partition()

This function partitions the monotonic counter.

Only the owner of the SC R SYSTEM resource or a partition with access permissions to SC R SYSTEM can do this.

Parameters

in	ipc	IPC handle
in,out	she	pointer to number of SHE bits

SECO uses an OTP monotonic counter to protect the SHE and HSM key-stores from roll-back attack. This function is used to define the number of monotonic counter bits allocated to SHE use. Two monotonic counter bits are used to store this information while the remaining bits are allocated to the HSM user. This function must be called before any SHE or HSM key stores are created in the system, otherwise the default configuration is applied. Returns the actual number of SHE bits.

If the partition has been already configured, any attempt to re-configure the SHE partition to a different value will result in a failure response.

Returns

Returns and error code (SC_ERR_NONE = success).

Return errors codes:

- SC_ERR_UNAVAILABLE if SECO not available,
- SC_ERR_NOACCESS if caller does not have SC_R_SYSTEM access
- · SC_ERR_IPC if SECO response has bad header tag or size,
- SC_ERR_VERSION if SECO response has bad version,
- Others, see the Security Service Detailed Description section

See the SECO API Reference Guide for more info.

```
13.6.2.24 sc_seco_set_fips_mode()
```

This function configures the SECO in FIPS mode.

Only the owner of the SC_R_SYSTEM resource or a partition with access permissions to SC_R_SYSTEM can do this.

Parameters

in	ipc	IPC handle
in	mode	FIPS mode
out	reason	pointer to return failure reason

This function permanently configures the SECO in FIPS approved mode. When in FIPS approved mode the following services will be disabled and receive a failure response:

- · Encrypted boot is not supported
- · Attestation is not supported
- · Manufacturing protection is not supported
- DTCP load
- · SHE services are not supported
- Assign JR is not supported (all JRs owned by SECO)

Return errors codes:

- SC_ERR_UNAVAILABLE if SECO not available,
- SC_ERR_NOACCESS if caller does not have SC_R_SYSTEM access
- SC_ERR_IPC if SECO response has bad header tag or size,
- SC_ERR_VERSION if SECO response has bad version,
- Others, see the Security Service Detailed Description section

See the SECO API Reference Guide for more info.

This function starts the random number generator.

Parameters

in	ipc	IPC handle
out	status	pointer to return state of RNG

Returns

Returns and error code (SC_ERR_NONE = success).

sc_seco_rng_stat_t * status)

Return errors codes:

- SC_ERR_UNAVAILABLE if SECO not available,
- · SC_ERR_IPC if SECO response has bad header tag or size,
- SC_ERR_VERSION if SECO response has bad version,
- Others, see the Security Service Detailed Description section

The RNG is started automatically after all CPUs are booted. This function can be used to start earlier and to check the status.

See the SECO API Reference Guide for more info.

This function sends a generic signed message to the SECO SHE/HSM components.

Parameters

in	ipc	IPC handle
in	addr	address of message block

Returns

Returns and error code (SC_ERR_NONE = success).

Return errors codes:

- SC_ERR_UNAVAILABLE if SECO not available,
- · SC_ERR_IPC if SECO response has bad header tag or size,
- SC_ERR_VERSION if SECO response has bad version,
- · Others, see the Security Service Detailed Description section

Note addr must be a pointer to a signed message block.

See the SECO API Reference Guide for more info.

13.6.2.27 sc_seco_secvio_enable()

This function is used to enable security violation and tamper interrupts.

These are then reported using the IRQ service via the SC_IRQ_SECVIO interrupt. Note it is automatically enabled at boot.

Parameters

in	ipc	IPC handle
----	-----	------------

Returns

Returns and error code (SC_ERR_NONE = success).

Return errors codes:

- SC_ERR_NOACCESS if caller does not own SC_R_SECVIO,
- SC_ERR_UNAVAILABLE if SECO not available,
- SC ERR IPC if SECO response has bad header tag or size,

- · SC_ERR_VERSION if SECO response has bad version,
- Others, see the Security Service Detailed Description section

The security violation interrupt is self-masking. Once it is cleared in the SNVS it must be re-enabled using this function.

13.6.2.28 sc_seco_secvio_config()

This function is used to read/write SNVS security violation and tamper registers.

Parameters

in	ipc	IPC handle
in	id	register ID
in	access	0=read, 1=write
in	data0	pointer to data to read or write
in	data1	pointer to data to read or write
in	data2	pointer to data to read or write
in	data3	pointer to data to read or write
in	data4	pointer to data to read or write
in	size	number of valid data words

Returns

Returns and error code (SC_ERR_NONE = success).

Return errors codes:

- SC_ERR_NOACCESS if caller does not own SC_R_SECVIO,
- SC_ERR_UNAVAILABLE if SECO not available,
- SC_ERR_IPC if SECO response has bad header tag or size,
- SC_ERR_VERSION if SECO response has bad version,
- Others, see the Security Service Detailed Description section

Unused data words can be passed a NULL pointer.

See AHAB_MANAGE_SNVS_REQ in the SECO API Reference Guide for more info.

13.6.2.29 sc_seco_secvio_dgo_config()

This function is used to read/write SNVS security violation and tamper DGO registers.

Parameters

in	ipc	IPC handle
in	id	regsiter ID
in	access	0=read, 1=write
in	data	pointer to data to read or write

Returns

Returns and error code (SC_ERR_NONE = success).

Return errors codes:

- SC_ERR_NOACCESS if caller does not own SC_R_SECVIO,
- SC_ERR_UNAVAILABLE if SECO not available,
- SC_ERR_IPC if SECO response has bad header tag or size,
- SC_ERR_VERSION if SECO response has bad version,
- Others, see the Security Service Detailed Description section

See AHAB_MANAGE_SNVS_DGO_REQ in the SECO API Reference Guide for more info.

13.7 TIMER: Timer Service

Module for the Timer service.

Typedefs

typedef uint8_t sc_timer_wdog_action_t

This type is used to configure the watchdog action.

• typedef uint32_t sc_timer_wdog_time_t

This type is used to declare a watchdog time value in milliseconds.

Defines for type widths

#define SC_TIMER_ACTION_W 3U
 Width of sc_timer_wdog_action_t.

Defines for sc_timer_wdog_action_t

 #define SC_TIMER_WDOG_ACTION_PARTITION 0U Reset partition.

• #define SC TIMER WDOG ACTION WARM 1U

Warm reset system.

• #define SC TIMER WDOG ACTION COLD 2U

Cold reset system.

• #define SC_TIMER_WDOG_ACTION_BOARD 3U

Reset board.

#define SC_TIMER_WDOG_ACTION_IRQ 4U

Only generate IRQs.

Watchdog Functions

sc_err_t sc_timer_set_wdog_timeout (sc_ipc_t ipc, sc_timer_wdog_time_t timeout)

This function sets the watchdog timeout in milliseconds.

sc_err_t sc_timer_set_wdog_pre_timeout (sc_ipc_t ipc, sc_timer_wdog_time_t pre_timeout)

This function sets the watchdog pre-timeout in milliseconds.

sc_err_t sc_timer_set_wdog_window (sc_ipc_t ipc, sc_timer_wdog_time_t window)

This function sets the watchdog window in milliseconds.

• sc_err_t sc_timer_start_wdog (sc_ipc_t ipc, sc_bool_t lock)

This function starts the watchdog.

sc_err_t sc_timer_stop_wdog (sc_ipc_t ipc)

This function stops the watchdog if it is not locked.

sc_err_t sc_timer_ping_wdog (sc_ipc_t ipc)

This function pings (services, kicks) the watchdog resetting the time before expiration back to the timeout.

sc_err_t sc_timer_get_wdog_status (sc_ipc_t ipc, sc_timer_wdog_time_t *timeout, sc_timer_wdog_time_t *max_timeout, sc_timer_wdog_time_t *remaining_time)

This function gets the status of the watchdog.

sc_err_t sc_timer_pt_get_wdog_status (sc_ipc_t ipc, sc_rm_pt_t pt, sc_bool_t *enb, sc_timer_wdog_time_t *timeout, sc_timer_wdog_time_t t*remaining_time)

This function gets the status of the watchdog of a partition.

sc_err_t sc_timer_set_wdog_action (sc_ipc_t ipc, sc_rm_pt_t pt, sc_timer_wdog_action_t action)

This function configures the action to be taken when a watchdog expires.

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Real-Time Clock (RTC) Functions

sc_err_t sc_timer_set_rtc_time (sc_ipc_t ipc, uint16_t year, uint8_t mon, uint8_t day, uint8_t hour, uint8_t min, uint8 t sec)

This function sets the RTC time.

sc_err_t sc_timer_get_rtc_time (sc_ipc_t ipc, uint16_t *year, uint8_t *mon, uint8_t *day, uint8_t *hour, uint8_t *min, uint8_t *sec)

This function gets the RTC time.

• sc_err_t sc_timer_get_rtc_sec1970 (sc_ipc_t ipc, uint32_t *sec)

This function gets the RTC time in seconds since 1/1/1970.

sc_err_t sc_timer_set_rtc_alarm (sc_ipc_t ipc, uint16_t year, uint8_t mon, uint8_t day, uint8_t hour, uint8_t min, uint8_t sec)

This function sets the RTC alarm.

sc_err_t sc_timer_set_rtc_periodic_alarm (sc_ipc_t ipc, uint32_t sec)

This function sets the RTC alarm (periodic mode).

sc_err_t sc_timer_cancel_rtc_alarm (sc_ipc_t ipc)

This function cancels the RTC alarm.

sc_err_t sc_timer_set_rtc_calb (sc_ipc_t ipc, int8_t count)

This function sets the RTC calibration value.

System Counter (SYSCTR) Functions

• sc_err_t sc_timer_set_sysctr_alarm (sc_ipc_t ipc, uint64_t ticks)

This function sets the SYSCTR alarm.

• sc err t sc timer set sysctr periodic alarm (sc ipc t ipc, uint64 t ticks)

This function sets the SYSCTR alarm (periodic mode).

• sc err t sc timer cancel sysctr alarm (sc ipc t ipc)

This function cancels the SYSCTR alarm.

13.7.1 Detailed Description

Module for the Timer service.

This includes support for the watchdog, RTC, and system counter. Note every resource partition has a watchdog it can use.

13.7.2 Function Documentation

13.7.2.1 sc_timer_set_wdog_timeout()

This function sets the watchdog timeout in milliseconds.

If not set then the timeout defaults to the max. Once locked this value cannot be changed.

Parameters

in	ipc	IPC handle
in	timeout	timeout period for the watchdog

Returns

Returns an error code (SC_ERR_NONE = success, SC_ERR_LOCKED = locked).

13.7.2.2 sc_timer_set_wdog_pre_timeout()

This function sets the watchdog pre-timeout in milliseconds.

If not set then the pre-timeout defaults to the max. Once locked this value cannot be changed.

Parameters

	in	ipc	IPC handle
ſ	in	pre_timeout	pre-timeout period for the watchdog

When the pre-timout expires an IRQ will be generated. Note this timeout clears when the IRQ is triggered. An IRQ is generated for the failing partition and all of its child partitions.

Returns

Returns an error code (SC_ERR_NONE = success).

13.7.2.3 sc_timer_set_wdog_window()

This function sets the watchdog window in milliseconds.

If not set then the window defaults to the 0. Once locked this value cannot be changed.

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Parameters

in	ipc	IPC handle
in	window	window period for the watchdog

Returns

Returns an error code (SC_ERR_NONE = success, SC_ERR_LOCKED = locked).

Calling sc timer ping wdog() before the window time has expired will result in the watchdog action being taken.

13.7.2.4 sc_timer_start_wdog()

This function starts the watchdog.

Parameters

in	ipc	IPC handle
in	lock	boolean indicating the lock status

Returns

Returns an error code (SC ERR NONE = success).

Return errors:

- · SC_ERR_NOACCESS if caller's partition is not isolated,
- · SC_ERR_BUSY if already started

If *lock* is set then the watchdog cannot be stopped or the timeout period changed.

If the calling partition is not isolated then the wdog cannot be used. This is always the case if a non-secure partition is running on the same CPU as a secure partition (e.g. Linux under TZ). See sc_rm_partition_alloc().

13.7.2.5 sc_timer_stop_wdog()

This function stops the watchdog if it is not locked.

Parameters

in <i>ipc</i>	IPC handle
---------------	------------

Returns

Returns an error code (SC_ERR_NONE = success, SC_ERR_LOCKED = locked).

13.7.2.6 sc_timer_ping_wdog()

This function pings (services, kicks) the watchdog resetting the time before expiration back to the timeout.

Parameters

in <i>ipc</i>	IPC handle
---------------	------------

Returns

Returns an error code (SC_ERR_NONE = success).

13.7.2.7 sc_timer_get_wdog_status()

This function gets the status of the watchdog.

All arguments are in milliseconds.

Parameters

in	ipc	IPC handle
out	timeout	pointer to return the timeout
out	max_timeout	pointer to return the max timeout
out	remaining_time	pointer to return the time remaining until trigger

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Returns

Returns an error code (SC_ERR_NONE = success).

13.7.2.8 sc_timer_pt_get_wdog_status()

This function gets the status of the watchdog of a partition.

All arguments are in milliseconds.

Parameters

in	ipc	IPC handle
in	pt	partition to query
out	enb	pointer to return enable status
out	timeout	pointer to return the timeout
out	remaining_time	pointer to return the time remaining until trigger

Returns

Returns an error code (SC_ERR_NONE = success).

13.7.2.9 sc_timer_set_wdog_action()

This function configures the action to be taken when a watchdog expires.

Parameters

in	ipc	IPC handle
in	pt	partition to affect
in	action	action to take

Default action is inherited from the parent.

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

- · SC_ERR_PARM if invalid parameters,
- SC_ERR_NOACCESS if caller's partition is not the SYSTEM owner,
- · SC_ERR_LOCKED if the watchdog is locked

13.7.2.10 sc_timer_set_rtc_time()

This function sets the RTC time.

Only the owner of the SC_R_SYSTEM resource or a partition with access permissions to SC_R_SYSTEM can set the time.

Parameters

in	ipc	IPC handle
in	year	year (min 1970)
in	mon	month (1-12)
in	day	day of the month (1-31)
in	hour	hour (0-23)
in	min	minute (0-59)
in	sec	second (0-59)

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

SC_ERR_PARM if invalid time/date parameters,

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• SC_ERR_NOACCESS if caller's partition cannot access SC_R_SYSTEM

13.7.2.11 sc_timer_get_rtc_time()

This function gets the RTC time.

Parameters

in	ipc	IPC handle
out	year	pointer to return year (min 1970)
out	mon	pointer to return month (1-12)
out	day	pointer to return day of the month (1-31)
out	hour	pointer to return hour (0-23)
out	min	pointer to return minute (0-59)
out	sec	pointer to return second (0-59)

Returns

Returns an error code (SC_ERR_NONE = success).

13.7.2.12 sc_timer_get_rtc_sec1970()

This function gets the RTC time in seconds since 1/1/1970.

Parameters

in	ipc	IPC handle
out	sec	pointer to return seconds

Returns

Returns an error code (SC_ERR_NONE = success).

13.7.2.13 sc_timer_set_rtc_alarm()

```
sc_err_t sc_timer_set_rtc_alarm (
    sc_ipc_t ipc,
    uint16_t year,
    uint8_t mon,
    uint8_t day,
    uint8_t hour,
    uint8_t min,
    uint8_t sec )
```

This function sets the RTC alarm.

Parameters

in	ipc	IPC handle
in	year	year (min 1970)
in	mon	month (1-12)
in	day	day of the month (1-31)
in	hour	hour (0-23)
in	min	minute (0-59)
in	sec	second (0-59)

Note this alarm setting clears when the alarm is triggered. This is an absolute time.

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

• SC_ERR_PARM if invalid time/date parameters

13.7.2.14 sc_timer_set_rtc_periodic_alarm()

This function sets the RTC alarm (periodic mode).

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Parameters

in	ipc	IPC handle
in	sec	period in seconds

Returns

Returns an error code (SC_ERR_NONE = success).

Note this is a relative time.

Return errors:

• SC_ERR_PARM if invalid time/date parameters

```
13.7.2.15 sc_timer_cancel_rtc_alarm()
```

This function cancels the RTC alarm.

Parameters

in	ipc	IPC handle

Note this alarm setting clears when the alarm is triggered.

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

• SC_ERR_PARM if invalid time/date parameters

13.7.2.16 sc_timer_set_rtc_calb()

This function sets the RTC calibration value.

Only the owner of the SC_R_SYSTEM resource or a partition with access permissions to SC_R_SYSTEM can set the calibration.

Parameters

in	ipc	IPC handle
in	count	calibration count (-16 to 15)

The calibration value is a 5-bit value including the sign bit, which is implemented in 2's complement. It is added or subtracted from the RTC on a periodic basis, once per 32768 cycles of the RTC clock.

Returns

Returns an error code (SC_ERR_NONE = success).

13.7.2.17 sc_timer_set_sysctr_alarm()

This function sets the SYSCTR alarm.

Parameters

in	ipc	IPC handle
in	ticks	number of 8MHz cycles

Note the ticks parameter is an absolute time. This alarm setting clears when the alarm is triggered.

Returns

Returns an error code (SC ERR NONE = success).

Return errors:

• SC_ERR_PARM if invalid time/date parameters

13.7.2.18 sc_timer_set_sysctr_periodic_alarm()

This function sets the SYSCTR alarm (periodic mode).

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Parameters

in	ipc	IPC handle
in	ticks	number of 8MHz cycles

Note the *ticks* parameter is a relative time.

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

• SC_ERR_PARM if invalid time/date parameters

13.7.2.19 sc_timer_cancel_sysctr_alarm()

This function cancels the SYSCTR alarm.

Parameters

in <i>ipc</i>	IPC handle
---------------	------------

Note this alarm setting clears when the alarm is triggered.

Returns

Returns an error code (SC_ERR_NONE = success).

Return errors:

• SC_ERR_PARM if invalid time/date parameters

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Chapter 14

File Documentation

14.1 platform/config/mx8dxl/pads.h File Reference

Header file used to configure SoC pad list.

Macros

Pad Definitions

```
    #define SC P PCIE CTRL0 PERST B 0

     HSIO.PCIE0.PERST_B, LSIO.GPIO4.IO00, LSIO.GPIO7.IO00.

    #define SC_P_PCIE_CTRL0_CLKREQ_B 1

     HSIO.PCIE0.CLKREQ_B, LSIO.GPIO4.IO01, LSIO.GPIO7.IO01.

    #define SC_P_PCIE_CTRL0_WAKE_B 2

     HSIO.PCIE0.WAKE_B, LSIO.GPIO4.IO02, LSIO.GPIO7.IO02.
• #define SC_P_COMP_CTL_GPIO_1V8_3V3_PCIESEP 3

    #define SC_P_USB_SS3_TC0 4

     ADMA.I2C1.SCL, CONN.USB_OTG1.PWR, CONN.USB_OTG2.PWR, LSIO.GPIO4.IO03, LSIO.GPIO7.IO03.

    #define SC P USB SS3 TC1 5

     ADMA.I2C1.SCL, CONN.USB_OTG2.PWR, LSIO.GPIO4.IO04, LSIO.GPIO7.IO04.

    #define SC_P_USB_SS3_TC2 6

     ADMA.I2C1.SDA, CONN.USB_OTG1.OC, CONN.USB_OTG2.OC, LSIO.GPIO4.IO05, LSIO.GPIO7.IO05.

    #define SC_P_USB_SS3_TC3 7

     ADMA.I2C1.SDA, CONN.USB_OTG2.OC, LSIO.GPIO4.IO06, LSIO.GPIO7.IO06.

    #define SC_P_COMP_CTL_GPIO_3V3_USB3IO 8

• #define SC P EMMC0 CLK 9
     CONN.EMMCO.CLK, CONN.NAND.READY_B, LSIO.GPIO4.IO07.

    #define SC_P_EMMC0_CMD 10

     CONN.EMMCO.CMD, CONN.NAND.DQS, LSIO.GPIO4.IO08.

    #define SC_P_EMMC0_DATA0 11

     CONN.EMMCO.DATAO, CONN.NAND.DATAOO, LSIO.GPIO4.IO09.

    #define SC_P_EMMC0_DATA1 12
```

CONN.EMMC0.DATA1, CONN.NAND.DATA01, LSIO.GPIO4.IO10.

CONN.EMMCO.DATA2, CONN.NAND.DATA02, LSIO.GPIO4.IO11.

#define SC P EMMC0 DATA2 13

#define SC_P_EMMC0_DATA3 14

CONN.EMMC0.DATA3, CONN.NAND.DATA03, LSIO.GPIO4.IO12.

#define SC_P_EMMC0_DATA4 15

CONN.EMMC0.DATA4, CONN.NAND.DATA04, LSIO.GPIO4.IO13.

#define SC P EMMC0 DATA5 16

CONN.EMMC0.DATA5, CONN.NAND.DATA05, LSIO.GPIO4.IO14.

#define SC P EMMC0 DATA6 17

CONN.EMMC0.DATA6, CONN.NAND.DATA06, LSIO.GPIO4.IO15.

#define SC_P_EMMC0_DATA7 18

CONN.EMMCO.DATA7, CONN.NAND.DATA07, LSIO.GPIO4.IO16.

#define SC_P_EMMC0_STROBE 19

CONN.EMMC0.STROBE. CONN.NAND.CLE. LSIO.GPIO4.IO17.

#define SC P EMMC0 RESET B 20

CONN.EMMC0.RESET_B, CONN.NAND.WP_B, LSIO.GPIO4.IO18.

- #define SC_P_COMP_CTL_GPIO_1V8_3V3_SD1FIX0 21
- #define SC_P_USDHC1_RESET_B 22

CONN.USDHC1.RESET_B, CONN.NAND.RE_N, ADMA.SPI2.SCK, CONN.NAND.WE_B, LSIO.GPIO4.IO19, LSIO.← GPIO7.IO08.

#define SC_P_USDHC1_VSELECT 23

 $CONN.USDHC1.VSELECT,\ CONN.NAND.RE_P,\ ADMA.SPI2.SDO,\ CONN.NAND.RE_B,\ LSIO.GPIO4.IO20,\ LSIO. \leftarrow GPIO7.IO09.$

- #define SC P CTL NAND RE P N 24
- #define SC P USDHC1 WP 25

 $CONN.USDHC1.WP, CONN.NAND.DQS_N, ADMA.SPI2.SDI, CONN.NAND.ALE, LSIO.GPIO4.IO21, LSIO.GPIO7. \leftarrow IO10.$

• #define SC P USDHC1 CD B 26

CONN.USDHC1.CD_B, CONN.NAND.DQS_P, ADMA.SPI2.CS0, CONN.NAND.DQS, LSIO.GPI04.I022, LSIO.GPI \sim 07.I011.

- #define SC P CTL NAND DQS P N 27
- #define SC P COMP CTL GPIO 1V8 3V3 VSELSEP 28
- #define SC P ENET0 RGMII TXC 29

 $CONN.ENET0.RGMII_TXC, CONN.ENET0.RCLK50M_OUT, CONN.ENET0.RCLK50M_IN, CONN.NAND.CE1_B, L \leftarrow SIO.GPIO4.IO29, CONN.USDHC2.CLK.$

#define SC P ENETO RGMII TX CTL 30

CONN.ENETO.RGMII TX CTL, CONN.USDHC1.RESET B, LSIO.GPIO4.IO30, CONN.USDHC2.CMD.

#define SC_P_ENET0_RGMII_TXD0 31

CONN.ENETO.RGMII_TXD0, CONN.USDHC1.VSELECT, LSIO.GPIO4.IO31, CONN.USDHC2.DATA0.

#define SC_P_ENET0_RGMII_TXD1 32

CONN.ENET0.RGMII_TXD1, CONN.USDHC1.WP, LSIO.GPIO5.IO00, CONN.USDHC2.DATA1.

#define SC P ENET0 RGMII TXD2 33

CONN.ENET0.RGMII_TXD2, CONN.NAND.CE0_B, CONN.USDHC1.CD_B, LSIO.GPI05.I001, CONN.USDHC2.D \leftarrow ATA2.

#define SC P ENETO RGMII TXD3 34

CONN.ENETO.RGMII TXD3, CONN.NAND.RE B, LSIO.GPIO5.IO02, CONN.USDHC2.DATA3.

- #define SC_P_COMP_CTL_GPIO_1V8_3V3_ENET_ENETB0 35
- #define SC P ENETO RGMII RXC 36

CONN.ENET0.RGMII_RXC, CONN.NAND.WE_B, CONN.USDHC1.CLK, LSIO.GPIO5.IO03.

#define SC P ENETO RGMII RX CTL 37

CONN.ENET0.RGMII_RX_CTL, CONN.USDHC1.CMD, LSIO.GPIO5.IO04.

#define SC_P_ENET0_RGMII_RXD0 38

CONN.ENETO.RGMII_RXD0, CONN.USDHC1.DATA0, LSIO.GPIO5.IO05.

• #define SC P ENETO RGMII RXD1 39

CONN.ENET0.RGMII RXD1, CONN.USDHC1.DATA1, LSIO.GPIO5.IO06.

#define SC P ENET0 RGMII RXD2 40

CONN.ENETO.RGMII_RXD2, CONN.ENETO.RMII_RX_ER, CONN.USDHC1.DATA2, LSIO.GPIO5.IO07.

• #define SC_P_ENET0_RGMII_RXD3 41

CONN.ENETO.RGMII_RXD3, CONN.NAND.ALE, CONN.USDHC1.DATA3, LSIO.GPIO5.IO08.

- #define SC_P_COMP_CTL_GPIO_1V8_3V3_ENET_ENETB1 42
- #define SC_P_ENET0_REFCLK_125M_25M 43

CONN.ENET0.REFCLK_125M_25M, CONN.ENET0.PPS, CONN.EQOS.PPS_IN, CONN.EQOS.PPS_OUT, LSIO. ← GPIO5.IO09.

#define SC P ENETO MDIO 44

CONN.ENETO.MDIO, ADMA.I2C3.SDA, CONN.EQOS.MDIO, LSIO.GPIO5.IO10, LSIO.GPIO7.IO16.

#define SC P ENETO MDC 45

CONN.ENETO.MDC, ADMA.I2C3.SCL, CONN.EQOS.MDC, LSIO.GPIO5.IO11, LSIO.GPIO7.IO17.

- #define SC_P_COMP_CTL_GPIO_1V8_3V3_GPIOCT 46
- #define SC P ENET1 RGMII TXC 47

LSIO.GPIO0.IO00, CONN.EQOS.RCLK50M_OUT, ADMA.LCDIF.D00, CONN.EQOS.RGMII_TXC, CONN.EQOS.R← CLK50M_IN.

#define SC P ENET1 RGMII TXD2 48

, ADMA.LCDIF.D01, CONN.EQOS.RGMII_TXD2, LSIO.GPIO0.IO01

#define SC P ENET1 RGMII TX CTL 49

, ADMA.LCDIF.D02, CONN.EQOS.RGMII_TX_CTL, LSIO.GPIO0.IO02

#define SC_P_ENET1_RGMII_TXD3 50

, ADMA.LCDIF.D03, CONN.EQOS.RGMII_TXD3, LSIO.GPIO0.IO03

#define SC_P_ENET1_RGMII_RXC 51

, ADMA.LCDIF.D04, CONN.EQOS.RGMII_RXC, LSIO.GPIO0.IO04

#define SC_P_ENET1_RGMII_RXD3 52

, ADMA.LCDIF.D05, CONN.EQOS.RGMII_RXD3, LSIO.GPIO0.IO05

#define SC_P_ENET1_RGMII_RXD2 53

, ADMA.LCDIF.D06, CONN.EQOS.RGMII_RXD2, LSIO.GPIO0.IO06, LSIO.GPIO6.IO00

#define SC_P_ENET1_RGMII_RXD1 54

, ADMA.LCDIF.D07, CONN.EQOS.RGMII_RXD1, LSIO.GPIO0.IO07, LSIO.GPIO6.IO01

#define SC P ENET1 RGMII TXD0 55

, ADMA.LCDIF.D08, CONN.EQOS.RGMII TXD0, LSIO.GPIO0.IO08, LSIO.GPIO6.IO02

#define SC_P_ENET1_RGMII_TXD1 56

, ADMA.LCDIF.D09, CONN.EQOS.RGMII TXD1, LSIO.GPIO0.IO09, LSIO.GPIO6.IO03

#define SC P ENET1 RGMII RXD0 57

ADMA.SPDIF0.RX, ADMA.MQS.R, ADMA.LCDIF.D10, CONN.EQOS.RGMII_RXD0, LSIO.GPIO0.IO10, LSIO.GPI← O6.IO04.

• #define SC P ENET1 RGMII RX CTL 58

ADMA.SPDIF0.TX, ADMA.MQS.L, ADMA.LCDIF.D11, CONN.EQOS.RGMII_RX_CTL, LSIO.GPIO0.IO11, LSIO.GP ← IO6.IO05.

#define SC_P_ENET1_REFCLK_125M_25M 59

ADMA.SPDIF0.EXT_CLK, ADMA.LCDIF.D12, CONN.EQOS.REFCLK_125M_25M, LSIO.GPI00.IO12, LSIO.GPI← O6.IO16

- #define SC_P_COMP_CTL_GPIO_1V8_3V3_GPIORHB 60
- #define SC_P_SPI3_SCK 61

ADMA.SPI3.SCK, ADMA.LCDIF.D13, LSIO.GPIO0.IO13, ADMA.LCDIF.D00.

#define SC_P_SPI3_SDO 62

ADMA.SPI3.SDO, ADMA.LCDIF.D14, LSIO.GPIO0.IO14, ADMA.LCDIF.D01.

• #define SC_P_SPI3_SDI 63

ADMA.SPI3.SDI, ADMA.LCDIF.D15, LSIO.GPIO0.IO15, ADMA.LCDIF.D02.

#define SC_P_SPI3_CS0 64

ADMA.SPI3.CS0, ADMA.ACM.MCLK OUT1, ADMA.LCDIF.HSYNC, LSIO.GPI00.IO16, ADMA.LCDIF.CS.

#define SC_P_SPI3_CS1 65

ADMA.SPI3.CS1, ADMA.I2C3.SCL, ADMA.LCDIF.RESET, ADMA.SPI2.CS0, ADMA.LCDIF.D16, ADMA.LCDIF.RD_E.

• #define SC P MCLK IN1 66

ADMA.ACM.MCLK_IN1, ADMA.I2C3.SDA, ADMA.LCDIF.EN, ADMA.SPI2.SCK, ADMA.LCDIF.D17, ADMA.LCDIF.← D03.

• #define SC P MCLK IN0 67

ADMA.ACM.MCLK INO, ADMA.LCDIF.VSYNC, ADMA.SPI2.SDI, LSIO.GPI00.IO19, ADMA.LCDIF.RS.

#define SC P MCLK OUT0 68

ADMA.ACM.MCLK_OUT0, ADMA.LCDIF.CLK, ADMA.SPI2.SDO, LSIO.GPI00.IO20, ADMA.LCDIF.WR_RWN.

#define SC_P_UART1_TX 69

ADMA.UART1.TX, LSIO.PWM0.OUT, LSIO.GPT0.CAPTURE, LSIO.GPIO0.IO21, ADMA.LCDIF.D04.

#define SC P UART1 RX 70

ADMA.UART1.RX, LSIO.PWM1.OUT, LSIO.GPT0.COMPARE, LSIO.GPT1.CLK, LSIO.GPI00.IO22, ADMA.LCDIF. \leftarrow D05.

#define SC P UART1 RTS B 71

ADMA.UART1.RTS_B, LSIO.PWM2.OUT, ADMA.LCDIF.D16, LSIO.GPT1.CAPTURE, LSIO.GPT0.CLK, ADMA.LC \leftarrow DIF.D06.

#define SC P UART1 CTS B 72

ADMA.UART1.CTS_B, LSIO.PWM3.OUT, ADMA.LCDIF.D17, LSIO.GPT1.COMPARE, LSIO.GPIO0.IO24, ADMA.L \leftarrow CDIF.D07

- #define SC P COMP CTL GPIO 1V8 3V3 GPIORHK 73
- #define SC P SPI0 SCK 74

ADMA.SPIO.SCK, ADMA.SAIO.TXC, M40.I2CO.SCL, M40.GPIO0.IO00, LSIO.GPIO1.IO04, ADMA.LCDIF.D08.

#define SC P SPI0 SDI 75

ADMA.SPIO.SDI, ADMA.SAIO.TXD, M40.TPMO.CHO, M40.GPIO0.IO02, LSIO.GPIO1.IO05, ADMA.LCDIF.D09.

#define SC P SPI0 SDO 76

ADMA.SPIO.SDO, ADMA.SAIO.TXFS, M40.I2CO.SDA, M40.GPIO0.IO01, LSIO.GPIO1.IO06, ADMA.LCDIF.D10.

#define SC P SPI0 CS1 77

ADMA.SPI0.CS1, ADMA.SAI0.RXC, ADMA.SAI1.TXD, ADMA.LCD_PWM0.OUT, LSIO.GPIO1.IO07, ADMA.LCDIF.←
D11

#define SC P SPI0 CS0 78

ADMA.SPIO.CSO, ADMA.SAIO.RXD, M40.TPM0.CH1, M40.GPIO0.IO03, LSIO.GPIO1.IO08, ADMA.LCDIF.D12.

- #define SC P COMP CTL GPIO 1V8 3V3 GPIORHT 79
- #define SC P ADC IN1 80

ADMA.ADC.IN1, M40.I2C0.SDA, M40.GPIO0.IO01, ADMA.I2C0.SDA, LSIO.GPIO1.IO09, ADMA.LCDIF.D13.

• #define SC P ADC IN0 81

ADMA.ADC.INO, M40.I2C0.SCL, M40.GPIO0.IO00, ADMA.I2C0.SCL, LSIO.GPIO1.IO10, ADMA.LCDIF.D14.

#define SC P ADC IN3 82

ADMA.ADC.IN3, M40.UART0.TX, M40.GPIO0.IO03, ADMA.ACM.MCLK_OUT0, LSIO.GPIO1.IO11, ADMA.LCDIF.← D15.

• #define SC P ADC IN2 83

ADMA.ADC.IN2, M40.UART0.RX, M40.GPIO0.IO02, ADMA.ACM.MCLK_IN0, LSIO.GPIO1.IO12, ADMA.LCDIF.D16.

#define SC P ADC IN5 84

ADMA.ADC.IN5, M40.TPM0.CH1, M40.GPIO0.IO05, ADMA.LCDIF.LCDBUSY, LSIO.GPIO1.IO13, ADMA.LCDIF.D17.

#define SC_P_ADC_IN4 85

ADMA.ADC.IN4, M40.TPM0.CH0, M40.GPIO0.IO04, ADMA.LCDIF.LCDRESET, LSIO.GPIO1.IO14.

#define SC_P_FLEXCAN0_RX 86

ADMA.FLEXCANO.RX, ADMA.SAI2.RXC, ADMA.UARTO.RTS_B, ADMA.SAI1.TXC, LSIO.GPIO1.IO15, LSIO.GPI← O6.IO08.

• #define SC P FLEXCAN0 TX 87

ADMA.FLEXCANO.TX, ADMA.SAI2.RXD, ADMA.UARTO.CTS_B, ADMA.SAI1.TXFS, LSIO.GPIO1.IO16, LSIO.GPI← O6.IO09.

#define SC_P_FLEXCAN1_RX 88

ADMA.FLEXCAN1.RX, ADMA.SAI2.RXFS, ADMA.FTM.CH2, ADMA.SAI1.TXD, LSIO.GPIO1.IO17, LSIO.GPIO6.I← O10.

#define SC P FLEXCAN1 TX 89

ADMA.FLEXCAN1.TX, ADMA.SAI3.RXC, ADMA.DMA0.REQ_INO, ADMA.SAI1.RXD, LSIO.GPIO1.IO18, LSIO.GPI← O6.IO11.

#define SC P FLEXCAN2 RX 90

ADMA.FLEXCAN2.RX, ADMA.SAI3.RXD, ADMA.UART3.RX, ADMA.SAI1.RXFS, LSIO.GPIO1.IO19, LSIO.GPIO6.I← 012.

• #define SC P FLEXCAN2 TX 91

ADMA.FLEXCAN2.TX, ADMA.SAI3.RXFS, ADMA.UART3.TX, ADMA.SAI1.RXC, LSIO.GPIO1.IO20, LSIO.GPIO6.I← 013.

```
    #define SC_P_UART0_RX 92

     ADMA.UARTO.RX, ADMA.MQS.R, ADMA.FLEXCANO.RX, SCU.UARTO.RX, LSIO.GPIO1.IO21, LSIO.GPIO6.IO14.

    #define SC P UART0 TX 93

     ADMA.UARTO.TX, ADMA.MQS.L, ADMA.FLEXCANO.TX, SCU.UARTO.TX, LSIO.GPIO1.IO22, LSIO.GPIO6.IO15.

    #define SC_P_UART2_TX 94

     ADMA.UART2.TX, ADMA.FTM.CH1, ADMA.FLEXCAN1.TX, LSIO.GPIO1.IO23, LSIO.GPIO6.IO16.

    #define SC_P_UART2_RX 95

     ADMA.UART2.RX, ADMA.FTM.CH0, ADMA.FLEXCAN1.RX, LSIO.GPIO1.IO24, LSIO.GPIO6.IO17.

    #define SC P COMP CTL GPIO 1V8 3V3 GPIOLH 96

    #define SC_P_JTAG_TRST_B 97

     SCU.JTAG.TRST_B, SCU.WDOG0.WDOG_OUT.

    #define SC P PMIC I2C SCL 98

     SCU.PMIC_I2C.SCL, SCU.GPIO0.IOXX_PMIC_A35_ON, LSIO.GPIO2.IO01.

    #define SC P PMIC I2C SDA 99

     SCU.PMIC 12C.SDA, SCU.GPIO0.IOXX PMIC GPU ON, LSIO.GPIO2.IO02.

    #define SC P PMIC INT B 100

     SCU.DSC.PMIC_INT_B.
#define SC_P_SCU_GPIO0_00 101
     SCU.GPIO0.IO00, SCU.UARTO.RX, M40.UARTO.RX, ADMA.UART3.RX, LSIO.GPIO2.IO03.

    #define SC_P_SCU_GPIO0_01 102

     SCU.GPIO0.IO01, SCU.UART0.TX, M40.UART0.TX, ADMA.UART3.TX, SCU.WDOG0.WDOG OUT.

    #define SC P SCU PMIC STANDBY 103

     SCU.DSC.PMIC_STANDBY.

    #define SC P SCU BOOT MODE1 104

     SCU.DSC.BOOT_MODE1.

    #define SC_P_SCU_BOOT_MODE0 105

     SCU.DSC.BOOT MODEO.

    #define SC P SCU BOOT MODE2 106

     SCU.DSC.BOOT MODE2, SCU.DSC.RTC CLOCK OUTPUT 32K.

    #define SC P SNVS TAMPER OUT1 107

     , LSIO.GPIO2.IO05_IN, LSIO.GPIO6.IO19_IN

    #define SC_P_SNVS_TAMPER_OUT2 108

     , LSIO.GPIO2.IO06_IN, LSIO.GPIO6.IO20_IN

    #define SC P SNVS TAMPER OUT3 109

     , ADMA.SAI2.RXC, LSIO.GPIO2.IO07 IN, LSIO.GPIO6.IO21 IN

    #define SC P SNVS TAMPER OUT4 110

     , ADMA.SAI2.RXD, LSIO.GPIO2.IO08_IN, LSIO.GPIO6.IO22_IN

    #define SC_P_SNVS_TAMPER_IN0 111

     , ADMA.SAI2.RXFS, LSIO.GPIO2.IO09 IN, LSIO.GPIO6.IO23 IN

    #define SC P SNVS TAMPER IN1 112

     , ADMA.SAI3.RXC, LSIO.GPIO2.IO10 IN, LSIO.GPIO6.IO24 IN

    #define SC P SNVS TAMPER IN2 113

     , ADMA.SAI3.RXD, LSIO.GPIO2.IO11_IN, LSIO.GPIO6.IO25_IN

    #define SC P SNVS TAMPER IN3 114

     , ADMA.SAI3.RXFS, LSIO.GPIO2.IO12_IN, LSIO.GPIO6.IO26_IN

    #define SC P SPI1 SCK 115

     , ADMA.I2C2.SDA, ADMA.SPI1.SCK, LSIO.GPIO3.IO00

    #define SC P SPI1 SDO 116

     , ADMA.I2C2.SCL, ADMA.SPI1.SDO, LSIO.GPIO3.IO01

    #define SC P SPI1 SDI 117

     , ADMA.I2C3.SCL, ADMA.SPI1.SDI, LSIO.GPIO3.IO02

    #define SC P SPI1 CS0 118

     , ADMA.I2C3.SDA, ADMA.SPI1.CS0, LSIO.GPIO3.IO03

    #define SC P COMP CTL GPIO 1V8 3V3 GPIORHD 119
```

#define SC P QSPI0A DATA1 120

LSIO.QSPI0A.DATA1, LSIO.GPI03.IO10.

#define SC P QSPI0A DATA0 121

LSIO.QSPIOA.DATA0, LSIO.GPIO3.IO09.

#define SC P QSPI0A DATA3 122

LSIO.QSPI0A.DATA3, LSIO.GPI03.IO12.

#define SC_P_QSPI0A_DATA2 123

LSIO.QSPI0A.DATA2, LSIO.GPI03.IO11.

#define SC_P_QSPI0A_SS0_B 124

LSIO.QSPI0A.SS0_B, LSIO.GPI03.IO14.

#define SC_P_QSPI0A_DQS 125

LSIO.QSPI0A.DQS, LSIO.GPI03.IO13.

#define SC P QSPI0A SCLK 126

LSIO.QSPI0A.SCLK, LSIO.GPI03.IO16.

- #define SC P COMP CTL GPIO 1V8 3V3 QSPI0A 127
- #define SC_P_QSPI0B_SCLK 128

LSIO.QSPI0B.SCLK, LSIO.GPIO3.IO17.

#define SC_P_QSPI0B_DQS 129

LSIO.QSPI0B.DQS, LSIO.GPI03.I022.

#define SC_P_QSPI0B_DATA1 130

LSIO.QSPI0B.DATA1, LSIO.GPI03.IO19.

#define SC_P_QSPI0B_DATA0 131

LSIO.QSPI0B.DATA0, LSIO.GPIO3.IO18.

#define SC_P_QSPI0B_DATA3 132

LSIO.QSPI0B.DATA3, LSIO.GPI03.I021.

#define SC P QSPI0B DATA2 133

LSIO.QSPI0B.DATA2, LSIO.GPI03.IO20.

#define SC_P_QSPI0B_SS0_B 134

LSIO.QSPI0B.SS0 B, LSIO.GPI03.IO23, LSIO.QSPI0A.SS1 B.

#define SC_P_COMP_CTL_GPIO_1V8_3V3_QSPI0B 135

14.1.1 Detailed Description

Header file used to configure SoC pad list.

14.2 platform/main/ipc.h File Reference

Header file for the IPC implementation.

Functions

sc_err_t sc_ipc_open (sc_ipc_t *ipc, sc_ipc_id_t id)

This function opens an IPC channel.

void sc_ipc_close (sc_ipc_t ipc)

This function closes an IPC channel.

void sc_ipc_read (sc_ipc_t ipc, void *data)

This function reads a message from an IPC channel.

• void sc_ipc_write (sc_ipc_t ipc, const void *data)

This function writes a message to an IPC channel.

14.2.1 Detailed Description

Header file for the IPC implementation.

14.2.2 Function Documentation

14.2.2.1 sc_ipc_open()

This function opens an IPC channel.

Parameters

out	ipc	return pointer for ipc handle
in	id	id of channel to open

Returns

Returns an error code (SC_ERR_NONE = success, SC_ERR_IPC otherwise).

The id parameter is implementation specific. Could be an MU address, pointer to a driver path, channel index, etc.

14.2.2.2 sc_ipc_close()

This function closes an IPC channel.

Parameters

in	ipc	id of channel to close

14.2.2.3 sc_ipc_read()

This function reads a message from an IPC channel.

Parameters

in	ipc	id of channel read from
out	data	pointer to message buffer to read

This function will block if no message is available to be read.

```
14.2.2.4 sc_ipc_write()
```

This function writes a message to an IPC channel.

Parameters

in	ipc	id of channel to write to
in	data	pointer to message buffer to write

This function will block if the outgoing buffer is full.

14.3 platform/main/types.h File Reference

Header file containing types used across multiple service APIs.

Macros

- #define SC_R_NONE 0xFFF0U
 - Define for ATF/Linux.
- #define SC_C_TEMP 0U
 - Defines for sc_ctrl_t.
- #define SC_C_TEMP_HI 1U
- #define SC_C_TEMP_LOW 2U
- #define SC_C_PXL_LINK_MST1_ADDR 3U
- #define SC_C_PXL_LINK_MST2_ADDR 4U
- #define SC_C_PXL_LINK_MST_ENB 5U
- #define SC_C_PXL_LINK_MST1_ENB 6U
- #define SC_C_PXL_LINK_MST2_ENB 7U
- #define SC_C_PXL_LINK_SLV1_ADDR 8U
- #define SC C PXL LINK SLV2 ADDR 9U
- #define SC_C_PXL_LINK_MST_VLD 10U
- #define SC_C_PXL_LINK_MST1_VLD 11U
- #define SC_C_PXL_LINK_MST2_VLD 12U
- #define **SC_C_SINGLE_MODE** 13U
- #define SC C ID 14U
- #define SC_C_PXL_CLK_POLARITY 15U

- #define SC_C_LINESTATE 16U
- #define SC_C_PCIE_G_RST 17U
- #define SC_C_PCIE_BUTTON_RST 18U
- #define SC_C_PCIE_PERST 19U
- #define SC C PHY RESET 20U
- #define SC_C_PXL_LINK_RATE_CORRECTION 21U
- #define SC_C_PANIC 22U
- #define SC C PRIORITY GROUP 23U
- #define SC_C_TXCLK 24U
- #define SC_C_CLKDIV 25U
- #define SC C DISABLE 50 26U
- #define SC C DISABLE 125 27U
- #define SC_C_SEL_125 28U
- #define SC C MODE 29U
- #define SC_C_SYNC_CTRL0 30U
- #define SC_C_KACHUNK_CNT 31U
- #define SC_C_KACHUNK_SEL 32U
- #define SC C SYNC CTRL1 33U
- #define SC_C_DPI_RESET 34U
- #define SC_C_MIPI_RESET 35U
- #define SC C DUAL MODE 36U
- #define SC_C_VOLTAGE 37U
- #define SC_C_PXL_LINK_SEL 38U
- #define SC C OFS SEL 39U
- #define SC C OFS AUDIO 40U
- #define SC C OFS PERIPH 41U
- #define SC C OFS IRQ 42U
- #define SC_C_RST0 43U
- #define SC_C_RST1 44U
- #define SC_C_SEL0 45U
- #define SC C CALIBO 46U
- #define SC C CALIB1 47U
- #define SC_C_CALIB2 48U
- #define SC_C_IPG_DEBUG 49U
- #define SC C IPG DOZE 50U
- #define SC_C_IPG_WAIT 51U
- #define SC_C_IPG_STOP 52U
- #define SC C IPG STOP MODE 53U
- #define SC C IPG STOP ACK 54U
- #define SC_C_SYNC_CTRL 55U
- #define SC_C_OFS_AUDIO_ALT 56U
- #define SC_C_DSP_BYP 57U
- #define SC_C_CLK_GEN_EN 58U
- #define SC_C_INTF_SEL 59U
- #define SC C RXC DLY 60U
- #define SC_C_TIMER_SEL 61U
- #define SC C MISC0 62U
- #define SC C MISC1 63U
- #define SC_C_MISC2 64U
- #define SC_C_MISC3 65U
- #define SC_C_LAST 66U

#define SC_P_ALL ((sc_pad_t) UINT16_MAX)
 Define for used to specify all pads.

Defines for chip IDs

- #define CHIP_ID_QM 0x1U
 i.MX8QM
- #define CHIP_ID_QX 0x2U
 i.MX8QX
- #define CHIP_ID_DXL 0xEU
 i.MX8DXL

Defines for common frequencies

- #define SC_32KHZ 32768U
 - 32KHz
- #define SC_1MHZ 1000000U
 1MHz
- #define SC_10MHZ 10000000U
 - 10MHz
- #define SC_16MHZ 16000000U
 16MHz
- #define SC_20MHZ 20000000U 20MHz
- #define SC_25MHZ 25000000U
 25MHz
- #define SC_27MHZ 27000000U 27MHz
- #define SC_40MHZ 40000000U 40MHz
- #define SC_45MHZ 45000000U 45MHz
- #define SC_50MHZ 50000000U 50MHz
- #define SC_60MHZ 60000000U 60MHz
- #define SC_66MHZ 6666666U
 66MHz
- #define SC_74MHZ 74250000U 74.25MHz
- #define SC_80MHZ 80000000U 80MHz
- #define SC_83MHZ 83333333U 83MHz
- #define SC_84MHZ 84375000U
- 84.37MHz
 #define SC_100MHZ 10000000U
- #define SC_114MHZ 114000000U
- 114MHz
 #define SC_125MHZ 125000000U
 125MHz

- #define SC_128MHZ 128000000U
 128MHz
- #define SC_133MHZ 133333333U
 133MHz
- #define SC_135MHZ 135000000U
 135MHz
- #define SC_150MHZ 150000000U
 150MHz
- #define SC_160MHZ 160000000U
 160MHz
- #define SC_166MHZ 166666666U
 166MHz
- #define SC_175MHZ 175000000U 175MHz
- #define SC_180MHZ 180000000U 180MHz
- #define SC_200MHZ 200000000U 200MHz
- #define SC_250MHZ 250000000U 250MHz
- #define SC_266MHZ 266666666U
 266MHz
- #define SC_300MHZ 300000000U 300MHz
- #define SC_312MHZ 312500000U 312.5MHZ
- #define SC_320MHZ 320000000U 320MHz
- #define SC_325MHZ 325000000U 325MHz
- #define SC_333MHZ 3333333333U
 333MHz
- #define SC_350MHZ 350000000U 350MHz
- #define SC_372MHZ 372000000U 372MHz
- #define SC_375MHZ 375000000U 375MHz
- #define SC_400MHZ 400000000U 400MHz
- #define SC_465MHZ 465000000U
 465MHz
- #define SC_500MHZ 500000000U 500MHz
- #define SC_594MHZ 594000000U 594MHz
- #define SC_625MHZ 625000000U 625MHz
- #define SC_640MHZ 640000000U 640MHz
- #define SC_648MHZ 648000000U 648MHz
- #define SC_650MHZ 650000000U 650MHz
- #define SC_667MHZ 66666667U

667MHz • #define SC_675MHZ 675000000U 675MHz #define SC_700MHZ 700000000U 700MHz #define SC_720MHZ 720000000U 720MHz #define SC_750MHZ 750000000U 750MHz #define SC 753MHZ 753000000U 753MHz #define SC_793MHZ 793000000U 793MHz #define SC_800MHZ 800000000U 800MHz #define SC 850MHZ 850000000U 850MHz #define SC_858MHZ 858000000U 858MHz #define SC_900MHZ 900000000U 900MHz • #define SC_953MHZ 953000000U 953MHz #define SC_963MHZ 963000000U 963MHz #define SC_1000MHZ 1000000000U 1GHz #define SC_1060MHZ 1060000000U 1.06GHz #define SC_1068MHZ 1068000000U 1.068GHz • #define SC_1121MHZ 1121000000U 1.121GHz #define SC_1173MHZ 1173000000U 1.173GHz #define SC_1188MHZ 1188000000U 1.188GHz #define SC_1260MHZ 1260000000U 1.26GHz #define SC_1278MHZ 1278000000U 1.278GHz #define SC_1280MHZ 1280000000U 1.28GHz #define SC_1300MHZ 1300000000U 1.3GHz #define SC_1313MHZ 1313000000U 1.313GHz #define SC_1345MHZ 1345000000U 1.345GHz #define SC_1400MHZ 1400000000U #define SC_1500MHZ 1500000000U 1.5GHz #define SC_1600MHZ 1600000000U 1.6GHz

- #define SC_1800MHZ 1800000000U
 1.8GHz
- #define SC_1860MHZ 1860000000U
 1.86GHz
- #define SC_2000MHZ 200000000U 2.0GHz
- #define SC_2112MHZ 2112000000U 2.12GHz

Defines for 24M related frequencies

- #define SC_8MHZ 8000000U 8MHz
- #define SC_12MHZ 12000000U
- 12MHz
 #define SC_19MHZ 19800000U
- 19.8MHz
 #define SC_24MHZ 24000000U
- 24MHz
 #define SC_48MHZ 48000000U
 48MHz
- #define SC_120MHZ 120000000U 120MHz
- #define SC_132MHZ 132000000U
 132MHz
- #define SC_144MHZ 144000000U 144MHz
- #define SC_192MHZ 192000000U
 192MHz
- #define SC_211MHZ 211200000U
 211.2MHz
- #define SC_228MHZ 228000000U 233MHz
- #define SC_240MHZ 240000000U 240MHz
- #define SC_264MHZ 264000000U 264MHz
- #define SC_352MHZ 352000000U 352MHz
- #define SC_360MHZ 36000000U
- #define SC_384MHZ 384000000U 384MHz
- #define SC_396MHZ 396000000U 396MHz
- #define SC_432MHZ 432000000U 432MHz
- #define SC_456MHZ 456000000U
- #define SC_480MHZ 480000000U 480MHz
- #define SC_600MHZ 600000000U 600MHz
- #define SC_744MHZ 744000000U

```
744MHz

    #define SC 792MHZ 792000000U

     792MHz

    #define SC_864MHZ 864000000U

     864MHz

    #define SC_912MHZ 912000000U

     912MHz
 #define SC_960MHZ 960000000U
     960MHz
• #define SC_1056MHZ 1056000000U
     1056MHz

    #define SC_1104MHZ 1104000000U

     1104MHz

    #define SC_1200MHZ 1200000000U

     1.2GHz

    #define SC_1464MHZ 1464000000U

     1.464GHz

    #define SC_2400MHZ 2400000000U

     2.4GHz
```

Defines for A/V related frequencies

- #define SC_62MHZ 62937500U 62.9375MHz
- #define SC_755MHZ 755250000U 755.25MHz

Defines for type widths

#define SC_BOOL_W 1U
 Width of sc_bool_t.
 #define SC_ERR_W 4U
 Width of sc_err_t.
 #define SC_RSRC_W 10U
 Width of sc_rsrc_t.
 #define SC_CTRL_W 7U
 Width of sc_ctrl_t.

Defines for sc_bool_t

#define SC_FALSE ((sc_bool_t) 0U)
 False.
 #define SC_TRUE ((sc_bool_t) 1U)
 True.

Defines for sc_err_t

#define SC_ERR_NONE 0U
 Success.
 #define SC_ERR_VERSION 1U
 Incompatible API version.
 #define SC_ERR_CONFIG 2U

Configuration error.

• #define SC ERR PARM 3U

Bad parameter.

#define SC ERR NOACCESS 4U

Permission error (no access)

#define SC ERR LOCKED 5U

Permission error (locked)

#define SC_ERR_UNAVAILABLE 6U

Unavailable (out of resources)

• #define SC_ERR_NOTFOUND 7U

Not found.

#define SC_ERR_NOPOWER 8U

No power.

#define SC_ERR_IPC 9U

Generic IPC error.

#define SC ERR BUSY 10U

Resource is currently busy/active.

#define SC_ERR_FAIL 11U

General I/O failure.

#define SC_ERR_LAST 12U

Defines for sc_rsrc_t

- #define SC_R_A53 0U
- #define SC R A53 0 1U
- #define SC_R_A53_1 2U
- #define SC_R_A53_2 3U
- #define SC_R_A53_3 4U
- #define SC_R_A72 5U
- #define **SC_R_A72_0** 6U
- #define **SC_R_A72_1** 7U
- #define **SC R A72 2** 8U
- #define SC R A72 3 9U
- #define SC R CCI 10U
- #define SC R DB 11U
- #define SC R DRC 0 12U
- #define SC_R_DRC_1 13U
- #define SC R GIC SMMU 14U #define SC_R_IRQSTR_M4_0 15U
- #define SC R IRQSTR M4_1 16U
- #define SC_R_SMMU 17U
- #define SC_R_GIC 18U
- #define **SC_R_DC_0_BLIT0** 19U
- #define SC_R_DC_0_BLIT1 20U
- #define SC_R_DC_0_BLIT2 21U
- #define SC_R_DC_0_BLIT_OUT 22U
- #define SC_R_PERF 23U
- #define SC R USB 1 PHY 24U
- #define SC R DC 0 WARP 25U
- #define SC R V2X MU 0 26U
- #define SC R V2X MU 1 27U
- #define SC_R_DC_0_VIDEO0 28U
- #define SC_R_DC_0_VIDEO1 29U #define SC R DC 0 FRAC0 30U
- #define SC R V2X MU 2 31U
- #define SC R DC 0 32U
- #define SC_R_GPU_2_PID0 33U

- #define SC_R_DC_0_PLL_0 34U
- #define SC_R_DC_0_PLL_1 35U
- #define SC R DC 1 BLIT0 36U
- #define SC R DC 1 BLIT1 37U
- #define SC R DC 1 BLIT2 38U
- #define SC_R_DC_1_BLIT_OUT 39U
- #define SC_R_V2X_MU_3 40U
- #define SC_R_V2X_MU_4 41U
- #define SC_R_DC_1_WARP 42U
- #define SC_R_UNUSED1 43U
- #define SC_R_SECVIO 44U
- #define SC_R_DC_1_VIDEO0 45U
- #define SC R DC 1 VIDEO1 46U
- #define SC R DC 1 FRAC0 47U
- #define SC R UNUSED13 48U
- #define SC_R_DC_1 49U
- #define SC R UNUSED14 50U
- #define SC_R_DC_1_PLL_0 51U
- #define SC_R_DC_1_PLL_1 52U
- #define SC_R_SPI_0 53U
- #define SC_R_SPI_1 54U
- #define SC_R_SPI_2 55U
- #define SC R SPI 3 56U
- #define SC_R_UART_0 57U
- #define SC_R_UART_1 58U
- #define SC_R_UART_2 59U
- #define SC_R_UART_3 60U
- #define SC R UART 461U
- #define SC_R_EMVSIM_0 62U
- #define SC_R_EMVSIM_1 63U
- #define SC R DMA 0 CH0 64U
- #define SC R DMA 0 CH1 65U
- #define SC_R_DMA_0_CH2 66U
- #define SC R DMA 0 CH3 67U
- #define SC_R_DMA_0_CH4 68U
- #define SC_R_DMA_0_CH5 69U
 #define SC_R_DMA_0_CH6 70U
- #define SC_R_DMA_0_CH7 71U
- #define SC R DMA 0 CH8 72U
- #define SC_R_DMA_0_CH9 73U
- #define SC R DMA 0 CH10 74U
- #define SC_R_DMA_0_CH11 75U
- #define SC_R_DMA_0_CH12 76U
- #define SC_R_DMA_0_CH13 77U
- #define SC_R_DMA_0_CH14 78U
- #define SC_R_DMA_0_CH15 79U
- #define SC_R_DMA_0_CH16 80U
- #define SC_R_DMA_0_CH17 81U
- #define SC R DMA 0 CH18 82U
- #define SC R DMA 0 CH19 83U
- #define SC_R_DMA_0_CH20 84U
- #define SC R DMA 0 CH21 85U
- #define SC_R_DMA_0_CH22 86U
- #define SC R DMA 0 CH23 87U
- #define SC_R_DMA_0_CH24 88U
- #define SC_R_DMA_0_CH25 89U
 #define SC_R_DMA_0_CH26 90U
- #define SC R DMA 0 CH27 91U
- #define SC R DMA 0 CH28 92U
- #define SC R DMA 0 CH29 93U

- #define SC_R_DMA_0_CH30 94U
- #define SC_R_DMA_0_CH31 95U
- #define SC R I2C 0 96U
- #define SC_R_I2C_1 97U
- #define SC R I2C 2 98U
- #define SC_R_I2C_3 99U
- #define SC_R_I2C_4 100U
- #define SC_R_ADC_0 101U
- #define SC_R_ADC_1 102U
- #define SC_R_FTM_0 103U
- #define **SC_R_FTM_1** 104U
- #define **SC_R_CAN_0** 105U
- #define SC R CAN 1 106U
- #define SC R CAN 2 107U
- #define SC_R_DMA_1_CH0 108U
- #define SC R DMA 1 CH1 109U
- #define SC_R_DMA_1_CH2 110U
- #define SC_R_DMA_1_CH3 111U
- #define SC_R_DMA_1_CH4 112U
- #define SC R DMA 1 CH5 113U
- #define SC R DMA 1 CH6 114U
- #define SC R DMA 1 CH7 115U
- #define SC R DMA 1 CH8 116U
- #define SC_R_DMA_1_CH9 117U
- #define SC_R_DMA_1_CH10 118U
- #define SC_R_DMA_1_CH11 119U
- #define SC_R_DMA_1_CH12 120U
- #define SC_R_DMA_1_CH13 121U
- #define SC_R_DMA_1_CH14 122U
- #define SC R DMA 1 CH15 123U
- #define SC R DMA 1 CH16 124U
- #define SC R DMA 1 CH17 125U
- #define SC_R_DMA_1_CH18 126U
- #define SC_R_DMA_1_CH19 127U
- #define SC_R_DMA_1_CH20 128U
 #define SC_R_DMA_1_CH21 129U
- #define **SC R DMA 1 CH22** 130U
- #define SC_R_DMA_1_CH23 131U
- #define SC R DMA 1 CH24 132U
- #define SC_R_DMA_1_CH25 133U
- #define SC_R_DMA_1_CH26 134U
- #define SC_R_DMA_1_CH27 135U
- #define SC_R_DMA_1_CH28 136U
- #define SC_R_DMA_1_CH29 137U
- #define SC_R_DMA_1_CH30 138U
- #define SC_R_DMA_1_CH31 139U
- #define SC_R_V2X_PID0 140U
- #define SC_R_V2X_PID1 141U
- #define SC_R_V2X_PID2 142U
- #define SC R V2X PID3 143U
- #define SC_R_GPU_0_PID0 144U
- #define SC_R_GPU_0_PID1 145U
- #define SC_R_GPU_0_PID2 146U
 #define SC_R_GPU_0_PID3 147U
- #define SC R GPU 1 PID0 148U
- #define SC R GPU 1 PID1 149U
- #define SC R GPU 1 PID2 150U
- #define SC R GPU 1 PID3 151U
- #define SC R PCIE A 152U
- #define SC R SERDES 0 153U

- #define SC_R_MATCH_0 154U
- #define SC_R_MATCH_1 155U
- #define SC R MATCH 2 156U
- #define SC_R_MATCH_3 157U
- #define SC R MATCH 4 158U
- #define SC_R_MATCH_5 159U
- #define SC_R_MATCH_6 160U
- #define SC_R_MATCH_7 161U
- #define SC_R_MATCH_8 162U
- #define SC_R_MATCH_9 163U
- #define SC_R_MATCH_10 164U
- #define SC_R_MATCH_11 165U
- #define SC_R_MATCH_12 166U
 #define SC_R_MATCH_12 166U
- #define SC_R_MATCH_13 167U
- #define SC R MATCH 14 168U
- #define SC R PCIE B 169U
- #define SC R SATA 0 170U
- #define SC_R_SERDES_1 171U
- #define SC_R_HSIO_GPIO 172U
- #define SC_R_MATCH_15 173U
- #define SC_R_MATCH_16 174U
- #define SC_R_MATCH_17 175U
- #define SC_R_MATCH_18 176U
- #define SC_R_MATCH_19 177U
- #define SC_R_MATCH_20 178U
- #define SC_R_MATCH_21 179U
- #define SC_R_MATCH_22 180U
- #define SC_R_MATCH_23 181U
- #define SC_R_MATCH_24 182U
- #define SC_R_MATCH_25 183U
- #define SC_R_MATCH_26 184U
- #define SC_R_MATCH_27 185U
- #define SC_R_MATCH_28 186U
- #define SC R LCD 0 187U
- #define SC_R_LCD_0_PWM_0 188U
- #define SC_R_LCD_0_I2C_0 189U
- #define SC_R_LCD_0_I2C_1 190U
- #define SC_R_PWM_0 191U
- #define SC_R_PWM_1 192U
- #define SC_R_PWM_2 193U
- #define SC_R_PWM_3 194U
- #define SC_R_PWM_4 195U
- #define SC_R_PWM_5 196U
- #define SC_R_PWM_6 197U#define SC_R_PWM_7 198U
- #define SC_R_GPIO_0 199U
- #define SC_R_GPIO_1 200U
- #define SC_R_GPIO_1 2000
 #define SC_R_GPIO_2 201U
- #define SC R GPIO 3 202U
- #define SC R GPIO 4 203U
- #define SC R GPIO 5 204U
- #define SC R GPIO 6 205U
- #define SC R GPIO 7 206U
- #define SC R GPT 0 207U
- #define SC R GPT 1 208U
- #define SC R GPT 2 209U
- #define SC R GPT 3 210U
- #define SC R GPT 4 211U
- #define SC R KPP 212U
- #define SC R MU 0A 213U

- #define SC_R_MU_1A 214U
- #define SC_R_MU_2A 215U
- #define SC R MU 3A 216U
- #define SC_R_MU_4A 217U
- #define SC R MU 5A 218U
- #define SC_R_MU_6A 219U
- #define SC_R_MU_7A 220U
- #define SC_R_MU_8A 221U
- #define SC_R_MU_9A 222U
- #define SC_R_MU_10A 223U
- #define SC_R_MU_11A 224U
- #define SC_R_MU_12A 225U
- #define SC R MU 13A 226U
- #define SC R MU 5B 227U
- #define SC_R_MU_6B 228U
- #define SC_R_MU_7B 229U
- #define SC R MU 8B 230U
- #define SC R MU 9B 231U
- #define SC_R_MU_10B 232U
- #define SC_R_MU_11B 233U
- #define SC R MU 12B 234U
- #define SC_R_MU_13B 235U
- #define SC R ROM 0 236U
- #define SC R FSPI 0 237U
- #define SC_R_FSPI_1 238U
- #define SC_R_IEE 239U
- #define SC_R_IEE_R0 240U
- #define SC_R_IEE_R1 241U
- #define SC_R_IEE_R2 242U
- #define SC_R_IEE_R3 243U
- #define SC_R_IEE_R4 244U
 #define SC R IEE R5 245U
- #define SC R IEE R6 246U
- #define SC R IEE R7 247U
- #define SC R SDHC 0 248U
- #define SC_R_SDHC_1 249U
- #define SC_R_SDHC_2 250U
- #define SC_R_ENET_0 251U
- #define SC_R_ENET_1 252U
- #define **SC_R_MLB_0** 253U
- #define SC_R_DMA_2_CH0 254U
- #define SC_R_DMA_2_CH1 255U
- #define SC_R_DMA_2_CH2 256U
- #define SC_R_DMA_2_CH3 257U
- #define SC_R_DMA_2_CH4 258U
- #define SC_R_USB_0 259U#define SC_R_USB_1 260U
- #define SC_R_USB_0_PHY 261U
- #define SC R USB 2 262U
- #define SC R USB 2 PHY 263U
- #define SC R DTCP 264U
- #define SC R NAND 265U
- #define SC R LVDS 0 266U
- #define SC R LVDS 0 PWM 0 267U
- #define SC_R_LVDS_0_I2C_0 268U
- #define SC R LVDS 0 I2C 1 269U
- #define SC R LVDS 1 270U
- #define SC R LVDS 1 PWM 0 271U
- #define SC R LVDS 1 I2C 0 272U
- #define SC R LVDS 1 I2C 1 273U

- #define SC_R_LVDS_2 274U
- #define SC_R_LVDS_2_PWM_0 275U
- #define SC R LVDS 2 I2C 0 276U
- #define SC_R_LVDS_2_I2C_1 277U
- #define SC R M4 0 PID0 278U
- #define SC_R_M4_0_PID1 279U
- #define SC_R_M4_0_PID2 280U
- #define SC_R_M4_0_PID3 281U
- #define SC_R_M4_0_PID4 282U
- #define SC_R_M4_0_RGPIO 283U
- #define SC_R_M4_0_SEMA42 284U
- #define SC_R_M4_0_TPM 285U
- #define SC R M4 0 PIT 286U
- #define SC_R_M4_0_UART 287U
- #define SC R M4 0 I2C 288U
- #define SC R M4 0 INTMUX 289U
- #define SC R ENET 0 A0 290U
- #define SC_R_ENET_0_A1 291U
- #define SC_R_M4_0_MU_0B 292U
- #define SC_R_M4_0_MU_0A0 293U
- #define SC_R_M4_0_MU_0A1 294U
- #define SC_R_M4_0_MU_0A2 295U
- #define SC_R_M4_0_MU_0A3 296U
- #define SC_R_M4_0_MU_1A 297U
- #define SC_R_M4_1_PID0 298U
 #define SC_R_M4_1_PID1 299U
- #define SC_R_M4_1_PID2 300U
- #define SC R M4 1 PID3 301U
- #define SC R M4 1 PID4 302U
- #define SC R M4 1 RGPIO 303U
- #define SC R M4 1 SEMA42 304U
- #define SC R M4 1 TPM 305U
- #define SC R M4 1 PIT 306U
- #define SC R M4 1 UART 307U
- #define SC_R_M4_1_I2C 308U
- #define SC_R_M4_1_INTMUX 309U
- #define SC_R_UNUSED17 310U
- #define SC_R_UNUSED18 311U
- #define SC_R_M4_1_MU_0B 312U
 #define SC_R_M4_1_MU_0A0 313U
- #define SC R M4 1 MU 0A1 314U
- #define SC_R_M4_1_MU_0A2 315U
- #define SC_R_M4_1_MU_0A3 316U
- #define SC_R_M4_1_MU_1A 317U
- #define SC_R_SAI_0 318U
- #define SC_R_SAI_1 319U
- #define SC_R_SAI_2 320U
- #define SC_R_IRQSTR_SCU2 321U
- #define SC_R_IRQSTR_DSP 322U
- #define SC R ELCDIF PLL 323U
- #define SC R OCRAM 324U
- #define SC R AUDIO PLL 0 325U
- #define SC R PI 0 326U
- #define SC R PI 0 PWM 0 327U
- #define SC_R_PI_0_PWM_1 328U
- #define SC_R_PI_0_I2C_0 329U
- #define SC_R_PI_0_PLL 330U
- #define SC_R_PI_1 331U
- #define SC R PI 1 PWM 0 332U
- #define SC R PI 1 PWM 1 333U

- #define SC_R_PI_1_I2C_0 334U
- #define SC_R_PI_1_PLL 335U
- #define SC R SC PID0 336U
- #define SC R SC PID1 337U
- #define SC R SC PID2 338U
- #define SC_R_SC_PID3 339U
- #define SC_R_SC_PID4 340U
- #define SC_R_SC_SEMA42 341U
- #define SC_R_SC_TPM 342U
- #define SC_R_SC_PIT 343U
- #define SC_R_SC_UART 344U
- #define SC_R_SC_I2C 345U
- #define SC R SC MU 0B 346U
- #define SC_R_SC_MU_0A0 347U
- #define SC R SC MU 0A1 348U
- #define SC_R_SC_MU_0A2 349U
- #define SC R SC MU 0A3 350U
- #define SC R SC MU 1A 351U
- #define SC_R_SYSCNT_RD 352U
- #define SC_R_SYSCNT_CMP 353U
- #define SC R DEBUG 354U
- #define SC_R_SYSTEM 355U
- #define SC R SNVS 356U
- #define SC R OTP 357U
- #define SC_R_VPU_PID0 358U
- #define SC R VPU PID1 359U
- #define SC_R_VPU_PID2 360U
- #define SC R VPU PID3 361U
- #define SC_R_VPU_PID4 362U
- #define SC R VPU PID5 363U
- #define SC R VPU PID6 364U
- #define SC R VPU PID7 365U
- #define SC_R_ENET_0_A2 366U
- #define SC_R_ENET_1_A0 367U
- #define SC_R_ENET_1_A1 368U#define SC_R_ENET_1_A2 369U
- #define SC R ENET 1 A3 370U
- #define SC_R_ENET_1_A4 371U
- #define SC R DMA 4 CH0 372U
- #define SC_R_DMA_4_CH1 373U
- #define SC R DMA 4 CH2 374U
- #define SC_R_DMA_4_CH3 375U
- #define SC_R_DMA_4 CH4 376U
- #define SC_R_ISI_CH0 377U
- #define SC_R_ISI_CH1 378U
- #define SC_R_ISI_CH2 379U
- #define SC_R_ISI_CH3 380U
- #define SC_R_ISI_CH4 381U
- #define SC R ISI CH5 382U
- #define SC R ISI CH6 383U
- #define SC R ISI CH7 384U
- #define SC R MJPEG DEC S0 385U
- #define SC_R_MJPEG_DEC_S1 386U
- #define SC R MJPEG DEC S2 387U
- #define SC_R_MJPEG_DEC_S3 388U
- #define SC_R_MJPEG_ENC_S0 389U
 #define SC R MJPEG ENC S1 390U
- #define SC R MJPEG ENC S2 391U
- #define SC R MJPEG ENC S3 392U
- #define SC R MIPI 0 393U

- #define SC_R_MIPI_0_PWM_0 394U
- #define SC_R_MIPI_0_I2C_0 395U
- #define SC R MIPI 0 I2C 1 396U
- #define SC R MIPI 1 397U
- #define SC R MIPI 1 PWM 0 398U
- #define SC_R_MIPI_1_I2C_0 399U
- #define SC_R_MIPI_1_I2C_1 400U
- #define SC_R_CSI_0 401U
- #define SC_R_CSI_0_PWM_0 402U
- #define SC_R_CSI_0_I2C_0 403U
- #define SC_R_CSI_1 404U
- #define SC_R_CSI_1_PWM_0 405U
- #define SC R CSI 1 I2C 0 406U
- #define SC R HDMI 407U
- #define SC R HDMI I2S 408U
- #define SC R_HDMI_I2C_0 409U
- #define SC R HDMI PLL 0 410U
- #define SC R HDMI RX 411U
- #define SC_R_HDMI_RX_BYPASS 412U
- #define SC R HDMI RX I2C 0 413U
- #define SC R ASRC 0 414U
- #define SC R ESAI 0 415U
- #define SC R SPDIF 0 416U
- #define SC R SPDIF 1 417U
- #define SC_R_SAI_3 418U
- #define SC_R_SAI_4 419U
- #define SC_R_SAI_5 420U
- #define SC R GPT 5 421U
- #define SC_R_GPT_6 422U
- #define SC R GPT 7 423U
- #define SC R GPT 8 424U
- #define SC R GPT 9 425U
- #define SC R GPT 10 426U
- #define SC R DMA 2 CH5 427U
- #define SC R DMA 2 CH6 428U #define SC R DMA 2 CH7 429U
- #define SC R DMA 2 CH8 430U
- #define SC_R_DMA_2_CH9 431U
- #define SC R DMA 2 CH10 432U
- #define SC_R_DMA_2_CH11 433U
- #define SC R DMA 2 CH12 434U
- #define SC_R_DMA_2_CH13 435U
- #define SC_R_DMA_2_CH14 436U
- #define SC_R_DMA_2_CH15 437U
- #define SC_R_DMA_2_CH16 438U
- #define SC_R_DMA_2_CH17 439U
- #define SC_R_DMA_2_CH18 440U
- #define SC_R_DMA_2_CH19 441U #define SC R DMA 2 CH20 442U
- #define SC R DMA 2 CH21 443U
- #define SC R DMA 2 CH22 444U
- #define SC R DMA 2 CH23 445U
- #define SC R DMA 2 CH24 446U
- #define SC R DMA 2 CH25 447U
- #define SC_R_DMA_2_CH26 448U
- #define SC R DMA 2 CH27 449U
- #define SC R DMA 2 CH28 450U
- #define SC R DMA 2 CH29 451U
- #define SC R DMA 2 CH30 452U
- #define SC R DMA 2 CH31 453U

- #define SC_R_ASRC_1 454U
- #define SC_R_ESAI_1 455U
- #define SC R SAI 6 456U
- #define SC_R_SAI_7 457U
- #define SC R AMIX 458U
- #define SC_R_MQS_0 459U
- #define SC_R_DMA_3_CH0 460U
- #define SC_R_DMA_3_CH1 461U
- #define SC_R_DMA_3_CH2 462U
- #define SC_R_DMA_3_CH3 463U
- #define SC_R_DMA_3_CH4 464U
- #define SC_R_DMA_3_CH5 465U
- #define SC R DMA 3 CH6 466U
- #define SC R DMA 3 CH7 467U
- #define SC R DMA 3 CH8 468U
- #define SC R DMA 3 CH9 469U
- #define SC R DMA 3 CH10 470U
- #define SC R DMA 3 CH11 471U
- #define SC_R_DMA_3_CH12 472U
- #define SC R DMA 3 CH13 473U
- #define SC R DMA 3 CH14 474U
- #define SC R DMA 3 CH15 475U
- #define SC R DMA 3 CH16 476U
- #define SC_R_DMA_3_CH17 477U
- #define SC_R_DMA_3_CH18 478U
- #define SC_R_DMA_3_CH19 479U
- #define SC_R_DMA_3_CH20 480U
- #dcfinc 00_11_DMA_0_01120 4000
- #define SC_R_DMA_3_CH21 481U
- #define SC_R_DMA_3_CH22 482U
- #define SC_R_DMA_3_CH23 483U
- #define SC_R_DMA_3_CH24 484U
- #define SC_R_DMA_3_CH25 485U
- #define SC_R_DMA_3_CH26 486U
 #define SC_R_DMA_3_CH27 487U
- #define SC R DMA 3 CH28 488U
- #define SC_R_DMA_3_CH29 489U
- #define **SC_R_DMA_3_CH30** 490U
- #define SC_R_DMA_3_CH31 491U
- #define SC_R_AUDIO_PLL_1 492U
- #define SC_R_AUDIO_CLK_0 493U
- #define SC_R_AUDIO_CLK_1 494U
- #define SC_R_MCLK_OUT_0 495U
- #define SC_R_MCLK_OUT_1 496U
- #define SC_R_PMIC_0 497U
- #define SC_R_PMIC_1 498U
- #define SC_R_SECO 499U
- #define SC_R_CAAM_JR1 500U
- #define SC_R_CAAM_JR2 501U
- #define SC_R_SECO_MU_2 503U
 #define SC_R_SECO_MU_3 504U
- #define SC R SECO MU 4 505U
- #define SC_R_HDMI_RX_PWM_0 506U
- #define SC R A35 507U
- #define SC_R_A35_0 508U
- #define SC R A35 1 509U
- #define SC_R_A35_2 510U
- #define SC_R_A35_3 511U
- #define SC R DSP 512U
- #define SC_R_DSP_RAM 513U

- #define SC_R_CAAM_JR1_OUT 514U
- #define SC_R_CAAM_JR2_OUT 515U
- #define SC_R_CAAM_JR3_OUT 516U
- #define SC_R_VPU_DEC_0 517U
- #define SC R VPU ENC 0 518U
- #define SC R CAAM JR0 519U
- #define SC_R_CAAM_JR0_OUT 520U
- #define SC R PMIC 2 521U
- #define SC_R_DBLOGIC 522U
- #define SC_R_HDMI_PLL_1 523U
- #define SC_R_BOARD_R0 524U
- #define SC_R_BOARD_R1 525U
- #define SC_R_BOARD_R2 526U
- #define SC_R_BOARD_R3 527U
- #define SC_R_BOARD_R4 528U
- #define SC R BOARD R5 529U
- #define SC R BOARD R6 530U
- #define SC R BOARD R7 531U
- #define SC R MJPEG DEC MP 532U
- #define SC R MJPEG ENC MP 533U
- #define SC R VPU TS 0 534U
- #define SC R VPU MU 0 535U
- #define SC R VPU MU 1 536U
- #define SC R VPU MU 2 537U
- #define SC R VPU MU 3 538U
- #define SC_R_VPU_ENC_1 539U
- #define SC R VPU 540U
- #define SC_R_DMA_5_CH0 541U
- #define SC R DMA 5 CH1 542U
- #define SC_R_DMA_5_CH2 543U
- #define SC_R_DMA_5_CH3 544U
- #define SC_R_ATTESTATION 545U
- #define SC_R_LAST 546U
- #define SC_R_ALL ((sc_rsrc_t) UINT16_MAX)

All resources.

Typedefs

typedef uint8_t sc_bool_t

This type is used to store a boolean.

typedef uint64 t sc faddr t

This type is used to store a system (full-size) address.

• typedef uint8_t sc_err_t

This type is used to indicate error response for most functions.

typedef uint16_t sc_rsrc_t

This type is used to indicate a resource.

typedef uint32_t sc_ctrl_t

This type is used to indicate a control.

typedef uint16_t sc_pad_t

This type is used to indicate a pad.

typedef __INT8_TYPE__ int8_t

Type used to declare an 8-bit integer.

typedef __INT16_TYPE__ int16_t

Type used to declare a 16-bit integer.

```
typedef __INT32_TYPE__ int32_t
      Type used to declare a 32-bit integer.

    typedef __INT64_TYPE__ int64_t

      Type used to declare a 64-bit integer.
• typedef __UINT8_TYPE__ uint8_t
      Type used to declare an 8-bit unsigned integer.
• typedef __UINT16_TYPE__ uint16_t
      Type used to declare a 16-bit unsigned integer.
• typedef __UINT32_TYPE__ uint32_t
      Type used to declare a 32-bit unsigned integer.

    typedef __UINT64_TYPE__ uint64_t

      Type used to declare a 64-bit unsigned integer.
```

14.3.1 **Detailed Description**

Header file containing types used across multiple service APIs.

14.3.2 Macro Definition Documentation

```
14.3.2.1 SC_R_NONE
#define SC_R_NONE 0xFFF0U
Define for ATF/Linux.
Not used by SCFW. Not a valid parameter for any SCFW API calls!
```

```
#define SC_P_ALL ((sc_pad_t) UINT16_MAX)
```

Define for used to specify all pads.

All pads

14.3.2.2 SC_P_ALL

14.3.3 Typedef Documentation

```
14.3.3.1 sc_rsrc_t
typedef uint16_t sc_rsrc_t
```

This type is used to indicate a resource.

Resources include peripherals and bus masters (but not memory regions). Note items from list should never be changed or removed (only added to at the end of the list).

```
14.3.3.2 sc_pad_t
typedef uint16_t sc_pad_t
```

This type is used to indicate a pad.

Valid values are SoC specific.

Refer to the SoC Pad List for valid pad values.

14.4 platform/svc/irq/api.h File Reference

Header file containing the public API for the System Controller (SC) Interrupt (IRQ) function.

Macros

 #define SC_IRQ_NUM_GROUP 7U Number of groups.

Defines for sc_irq_group_t

- #define SC_IRQ_GROUP_TEMP 0U
 Temp interrupts.
- #define SC_IRQ_GROUP_WDOG 1U

Watchdog interrupts.

• #define SC IRQ GROUP RTC 2U

RTC interrupts.

• #define SC IRQ GROUP WAKE 3U

Wakeup interrupts.

• #define SC IRQ GROUP SYSCTR 4U

System counter interrupts.

#define SC_IRQ_GROUP_REBOOTED 5U

Partition reboot complete.

#define SC IRQ GROUP REBOOT 6U

Partition reboot starting.

Defines for sc_irq_temp_t

```
    #define SC_IRQ_TEMP_HIGH (1UL << 0U)</li>
```

Temp alarm interrupt.

#define SC_IRQ_TEMP_CPU0_HIGH (1UL << 1U)

CPU0 temp alarm interrupt.

#define SC_IRQ_TEMP_CPU1_HIGH (1UL << 2U)

CPU1 temp alarm interrupt.

#define SC_IRQ_TEMP_GPU0_HIGH (1UL << 3U)

GPU0 temp alarm interrupt.

• #define SC_IRQ_TEMP_GPU1_HIGH (1UL << 4U)

GPU1 temp alarm interrupt.

 #define SC_IRQ_TEMP_DRC0_HIGH (1UL << 5U) DRC0 temp alarm interrupt. #define SC_IRQ_TEMP_DRC1_HIGH (1UL << 6U) DRC1 temp alarm interrupt. #define SC_IRQ_TEMP_VPU_HIGH (1UL << 7U) DRC1 temp alarm interrupt. #define SC_IRQ_TEMP_PMIC0_HIGH (1UL << 8U) PMIC0 temp alarm interrupt. #define SC_IRQ_TEMP_PMIC1_HIGH (1UL << 9U) PMIC1 temp alarm interrupt. #define SC_IRQ_TEMP_LOW (1UL << 10U) Temp alarm interrupt. #define SC_IRQ_TEMP_CPU0_LOW (1UL << 11U) CPU0 temp alarm interrupt. #define SC_IRQ_TEMP_CPU1_LOW (1UL << 12U) CPU1 temp alarm interrupt. #define SC_IRQ_TEMP_GPU0_LOW (1UL << 13U) GPU0 temp alarm interrupt. #define SC_IRQ_TEMP_GPU1_LOW (1UL << 14U) GPU1 temp alarm interrupt. #define SC_IRQ_TEMP_DRC0_LOW (1UL << 15U) DRC0 temp alarm interrupt. #define SC_IRQ_TEMP_DRC1_LOW (1UL << 16U) DRC1 temp alarm interrupt. #define SC_IRQ_TEMP_VPU_LOW (1UL << 17U) DRC1 temp alarm interrupt. #define SC_IRQ_TEMP_PMIC0_LOW (1UL << 18U) PMIC0 temp alarm interrupt. #define SC_IRQ_TEMP_PMIC1_LOW (1UL << 19U) PMIC1 temp alarm interrupt. #define SC_IRQ_TEMP_PMIC2_HIGH (1UL << 20U)

Defines for sc_irq_wdog_t

#define SC_IRQ_WDOG (1U << 0U)
 Watchdog interrupt.

PMIC2 temp alarm interrupt.

PMIC2 temp alarm interrupt.

#define SC_IRQ_TEMP_PMIC2_LOW (1UL << 21U)

Defines for sc_irq_rtc_t

#define SC_IRQ_RTC (1U << 0U)
 RTC interrupt.

Defines for sc_irq_wake_t

#define SC_IRQ_BUTTON (1U << 0U)

Button interrupt.
#define SC_IRQ_PAD (1U << 1U)

Pad wakeup.
#define SC_IRQ_USR1 (1U << 2U)

User defined 1.

```
#define SC_IRQ_USR2 (1U << 3U)

User defined 2.</li>
#define SC_IRQ_BC_PAD (1U << 4U)

Pad wakeup (broadcast to all partitions)</li>
#define SC_IRQ_SW_WAKE (1U << 5U)

Software requested wake.</li>
#define SC_IRQ_SECVIO (1U << 6U)</li>
```

Defines for sc_irq_sysctr_t

Security violation.

 #define SC_IRQ_SYSCTR (1U << 0U) SYSCTR interrupt.

Typedefs

```
    typedef uint8_t sc_irq_group_t
    This type is used to declare an interrupt group.
```

typedef uint8_t sc_irq_temp_t

This type is used to declare a bit mask of temp interrupts.

typedef uint8_t sc_irq_wdog_t

This type is used to declare a bit mask of watchdog interrupts.

typedef uint8_t sc_irq_rtc_t

This type is used to declare a bit mask of RTC interrupts.

• typedef uint8_t sc_irq_wake_t

This type is used to declare a bit mask of wakeup interrupts.

Functions

- sc_err_t sc_irq_enable (sc_ipc_t ipc, sc_rsrc_t resource, sc_irq_group_t group, uint32_t mask, sc_bool_t enable)
 This function enables/disables interrupts.
- sc_err_t sc_irq_status (sc_ipc_t ipc, sc_rsrc_t resource, sc_irq_group_t group, uint32_t *status)

 This function returns the current interrupt status (regardless if masked).

14.4.1 Detailed Description

Header file containing the public API for the System Controller (SC) Interrupt (IRQ) function.

14.5 platform/svc/misc/api.h File Reference

Header file containing the public API for the System Controller (SC) Miscellaneous (MISC) function.

Macros

#define SC MISC DMA GRP MAX 31U

Max DMA channel priority group.

Defines for type widths

#define SC_MISC_DMA_GRP_W 5U
 Width of sc_misc_dma_group_t.

Defines for sc misc boot status t

- #define SC_MISC_BOOT_STATUS_SUCCESS 0U Success.
- #define SC_MISC_BOOT_STATUS_SECURITY 1U Security violation.

Defines for sc_misc_temp_t

• #define SC_MISC_TEMP 0U

Temp sensor.

• #define SC_MISC_TEMP_HIGH 1U

Temp high alarm.

#define SC_MISC_TEMP_LOW 2U

Temp low alarm.

Defines for $sc_misc_bt_t$

- #define SC_MISC_BT_PRIMARY 0U
 - Primary boot.
- #define SC_MISC_BT_SECONDARY 1U

Secondary boot.

#define SC_MISC_BT_RECOVERY 2U

Recovery boot.

• #define SC_MISC_BT_MANUFACTURE 3U

Manufacture boot.

• #define SC_MISC_BT_SERIAL 4U

Serial boot.

Typedefs

typedef uint8_t sc_misc_dma_group_t

This type is used to store a DMA channel priority group.

typedef uint8_t sc_misc_boot_status_t

This type is used report boot status.

typedef uint8_t sc_misc_temp_t

This type is used report boot status.

typedef uint8_t sc_misc_bt_t

This type is used report the boot type.

Functions

Control Functions

sc_err_t sc_misc_set_control (sc_ipc_t ipc, sc_rsrc_t resource, sc_ctrl_t ctrl, uint32_t val)

This function sets a miscellaneous control value.

sc_err_t sc_misc_get_control (sc_ipc_t ipc, sc_rsrc_t resource, sc_ctrl_t ctrl, uint32_t *val)

This function gets a miscellaneous control value.

DMA Functions

sc_err_t sc_misc_set_max_dma_group (sc_ipc_t ipc, sc_rm_pt_t pt, sc_misc_dma_group_t max)

This function configures the max DMA channel priority group for a partition.

sc_err_t sc_misc_set_dma_group (sc_ipc_t ipc, sc_rsrc_t resource, sc_misc_dma_group_t group)

This function configures the priority group for a DMA channel.

Debug Functions

void sc_misc_debug_out (sc_ipc_t ipc, uint8_t ch)

This function is used output a debug character from the SCU UART.

sc_err_t sc_misc_waveform_capture (sc_ipc_t ipc, sc_bool_t enable)

This function starts/stops emulation waveform capture.

void sc_misc_build_info (sc_ipc_t ipc, uint32_t *build, uint32_t *commit)

This function is used to return the SCFW build info.

void sc_misc_api_ver (sc_ipc_t ipc, uint16_t *cl_maj, uint16_t *cl_min, uint16_t *sv_maj, uint16_t *sv_min)

This function is used to return the SCFW API versions.

void sc_misc_unique_id (sc_ipc_t ipc, uint32_t *id_l, uint32_t *id_h)

This function is used to return the device's unique ID.

Other Functions

sc_err_t sc_misc_set_ari (sc_ipc_t ipc, sc_rsrc_t resource, sc_rsrc_t resource_mst, uint16_t ari, sc_bool_t enable)

This function configures the ARI match value for PCIe/SATA resources.

void sc_misc_boot_status (sc_ipc_t ipc, sc_misc_boot_status_t status)

This function reports boot status.

• sc err t sc misc boot done (sc ipc t ipc, sc rsrc t cpu)

This function tells the SCFW that a CPU is done booting.

sc_err_t sc_misc_otp_fuse_read (sc_ipc_t ipc, uint32_t word, uint32_t *val)

This function reads a given fuse word index.

sc_err_t sc_misc_otp_fuse_write (sc_ipc_t ipc, uint32_t word, uint32_t val)

This function writes a given fuse word index.

sc_err_t sc_misc_set_temp (sc_ipc_t ipc, sc_rsrc_t resource, sc_misc_temp_t temp, int16_t celsius, int8_t tenths)

This function sets a temp sensor alarm.

sc_err_t sc_misc_get_temp (sc_ipc_t ipc, sc_rsrc_t resource, sc_misc_temp_t temp, int16_t *celsius, int8_t *tenths)

This function gets a temp sensor value.

void sc_misc_get_boot_dev (sc_ipc_t ipc, sc_rsrc_t *dev)

This function returns the boot device.

sc_err_t sc_misc_get_boot_type (sc_ipc_t ipc, sc_misc_bt_t *type)

This function returns the boot type.

sc_err_t sc_misc_get_boot_container (sc_ipc_t ipc, uint8_t *idx)

This function returns the boot container index.

void sc misc get button status (sc ipc t ipc, sc bool t *status)

This function returns the current status of the ON/OFF button.

sc_err_t sc_misc_rompatch_checksum (sc_ipc_t ipc, uint32_t *checksum)

This function returns the ROM patch checksum.

• sc err t sc misc board ioctl (sc ipc t ipc, uint32 t *parm1, uint32 t *parm2, uint32 t *parm3)

This function calls the board IOCTL function.

14.5.1 Detailed Description

Header file containing the public API for the System Controller (SC) Miscellaneous (MISC) function.

14.6 platform/svc/pad/api.h File Reference

Header file containing the public API for the System Controller (SC) Pad Control (PAD) function.

Macros

Defines for type widths

#define SC_PAD_MUX_W 3U
 Width of mux parameter.

Defines for sc_pad_config_t

- #define SC_PAD_CONFIG_NORMAL 0U Normal.
- #define SC_PAD_CONFIG_OD 1U
- Open Drain.
 #define SC_PAD_CONFIG_OD_IN 2U

Open Drain and input.

#define SC_PAD_CONFIG_OUT_IN 3U
 Output and input.

Defines for sc_pad_iso_t

- #define SC_PAD_ISO_OFF 0U
 - ISO latch is transparent.
- #define SC_PAD_ISO_EARLY 1U

Follow EARLY_ISO.

#define SC_PAD_ISO_LATE 2U

Follow LATE ISO.

#define SC_PAD_ISO_ON 3U

ISO latched data is held.

Defines for sc_pad_28fdsoi_dse_t

#define SC PAD 28FDSOI DSE 18V 1MA 0U

Drive strength of 1mA for 1.8v.

#define SC_PAD_28FDSOI_DSE_18V_2MA 1U

Drive strength of 2mA for 1.8v.

#define SC_PAD_28FDSOI_DSE_18V_4MA 2U

Drive strength of 4mA for 1.8v.

#define SC PAD 28FDSOI DSE 18V 6MA 3U

Drive strength of 6mA for 1.8v.

#define SC_PAD_28FDSOI_DSE_18V_8MA 4U

Drive strength of 8mA for 1.8v.

#define SC_PAD_28FDSOI_DSE_18V_10MA 5U

Drive strength of 10mA for 1.8v.

- #define SC_PAD_28FDSOI_DSE_18V_12MA 6U
 Drive strength of 12mA for 1.8v.
- #define SC_PAD_28FDSOI_DSE_18V_HS 7U

High-speed drive strength for 1.8v.

#define SC_PAD_28FDSOI_DSE_33V_2MA 0U

Drive strength of 2mA for 3.3v.

#define SC_PAD_28FDSOI_DSE_33V_4MA 1U

Drive strength of 4mA for 3.3v.

#define SC_PAD_28FDSOI_DSE_33V_8MA 2U

Drive strength of 8mA for 3.3v.

#define SC_PAD_28FDSOI_DSE_33V_12MA 3U

Drive strength of 12mA for 3.3v.

#define SC_PAD_28FDSOI_DSE_DV_HIGH 0U

High drive strength for dual volt.

#define SC PAD 28FDSOI DSE DV LOW 1U

Low drive strength for dual volt.

Defines for sc_pad_28fdsoi_ps_t

• #define SC_PAD_28FDSOI_PS_KEEPER 0U

Bus-keeper (only valid for 1.8v)

• #define SC_PAD_28FDSOI_PS_PU 1U

Pull-up.

• #define SC_PAD_28FDSOI_PS_PD 2U

Pull-down.

#define SC_PAD_28FDSOI_PS_NONE 3U

No pull (disabled)

Defines for sc_pad_28fdsoi_pus_t

- #define SC_PAD_28FDSOI_PUS_30K_PD 0U 30K pull-down
- #define SC_PAD_28FDSOI_PUS_100K_PU 1U 100K pull-up
- #define SC_PAD_28FDSOI_PUS_3K_PU 2U 3K pull-up
- #define SC_PAD_28FDSOI_PUS_30K_PU 3U 30K pull-up

Defines for sc_pad_wakeup_t

- #define SC_PAD_WAKEUP_OFF 0U Off.
- #define SC_PAD_WAKEUP_CLEAR 1U
 Clears pending flag.
- #define SC_PAD_WAKEUP_LOW_LVL 4U

Low level.

- #define SC_PAD_WAKEUP_FALL_EDGE 5U Falling edge.
- #define SC_PAD_WAKEUP_RISE_EDGE 6U
 - Rising edge. define SC PAD WAKEUP HIGH LVL 7U
- #define SC_PAD_WAKEUP_HIGH_LVL 7U
 High-level.

Typedefs

```
    typedef uint8_t sc_pad_config_t
```

This type is used to declare a pad config.

typedef uint8_t sc_pad_iso_t

This type is used to declare a pad low-power isolation config.

typedef uint8_t sc_pad_28fdsoi_dse_t

This type is used to declare a drive strength.

typedef uint8 t sc pad 28fdsoi ps t

This type is used to declare a pull select.

typedef uint8_t sc_pad_28fdsoi_pus_t

This type is used to declare a pull-up select.

typedef uint8 t sc pad wakeup t

This type is used to declare a wakeup mode of a pad.

Functions

Generic Functions

- sc_err_t sc_pad_set_mux (sc_ipc_t ipc, sc_pad_t pad, uint8_t mux, sc_pad_config_t config, sc_pad_iso_t iso)
 This function configures the mux settings for a pad.
- sc_err_t sc_pad_get_mux (sc_ipc_t ipc, sc_pad_t pad, uint8_t *mux, sc_pad_config_t *config, sc_pad_iso_t *iso)

This function gets the mux settings for a pad.

sc_err_t sc_pad_set_gp (sc_ipc_t ipc, sc_pad_t pad, uint32_t ctrl)

This function configures the general purpose pad control.

sc_err_t sc_pad_get_gp (sc_ipc_t ipc, sc_pad_t pad, uint32_t *ctrl)

This function gets the general purpose pad control.

• sc_err_t sc_pad_set_wakeup (sc_ipc_t ipc, sc_pad_t pad, sc_pad_wakeup_t wakeup)

This function configures the wakeup mode of the pad.

sc err t sc pad get wakeup (sc ipc t ipc, sc pad t pad, sc pad wakeup t *wakeup)

This function gets the wakeup mode of a pad.

 sc_err_t sc_pad_set_all (sc_ipc_t ipc, sc_pad_t pad, uint8_t mux, sc_pad_config_t config, sc_pad_iso_t iso, uint32_t ctrl, sc_pad_wakeup_t wakeup)

This function configures a pad.

sc_err_t sc_pad_get_all (sc_ipc_t ipc, sc_pad_t pad, uint8_t *mux, sc_pad_config_t *config, sc_pad_iso_t *iso, uint32 t *ctrl, sc_pad_wakeup t *wakeup)

This function gets a pad's config.

SoC Specific Functions

```
    sc_err_t sc_pad_set (sc_ipc_t ipc, sc_pad_t pad, uint32_t val)
```

This function configures the settings for a pad.

sc_err_t sc_pad_get (sc_ipc_t ipc, sc_pad_t pad, uint32_t *val)

This function gets the settings for a pad.

sc_err_t sc_pad_config (sc_ipc_t ipc, sc_pad_t pad, uint32_t val)

This function writes a configuration register.

Technology Specific Functions

sc_err_t sc_pad_set_gp_28fdsoi (sc_ipc_t ipc, sc_pad_t pad, sc_pad_28fdsoi_dse_t dse, sc_pad_28fdsoi_ps_t ps)

This function configures the pad control specific to 28FDSOI.

sc_err_t sc_pad_get_gp_28fdsoi (sc_ipc_t ipc, sc_pad_t pad, sc_pad_28fdsoi_dse_t *dse, sc_pad_28fdsoi_ps_t *ps)

This function gets the pad control specific to 28FDSOI.

 sc_err_t sc_pad_set_gp_28fdsoi_hsic (sc_ipc_t ipc, sc_pad_t pad, sc_pad_28fdsoi_dse_t dse, sc_bool_t hys, sc_pad_28fdsoi_pus_t pus, sc_bool_t pke, sc_bool_t pue)

This function configures the pad control specific to 28FDSOI.

sc_err_t sc_pad_get_gp_28fdsoi_hsic (sc_ipc_t ipc, sc_pad_t pad, sc_pad_28fdsoi_dse_t *dse, sc_bool_t *hys, sc_pad_28fdsoi_pus_t *pus, sc_bool_t *pke, sc_bool_t *pue)

This function gets the pad control specific to 28FDSOI.

sc_err_t sc_pad_set_gp_28fdsoi_comp (sc_ipc_t ipc, sc_pad_t pad, uint8_t compen, sc_bool_t fastfrz, uint8_t rasrcp, uint8_t rasrcp, uint8_t rasrcp, sc_bool_t psw_ovr)

This function configures the compensation control specific to 28FDSOI.

sc_err_t sc_pad_get_gp_28fdsoi_comp (sc_ipc_t ipc, sc_pad_t pad, uint8_t *compen, sc_bool_t *fastfrz, uint8_t *rasrcp, uint8_t *rasrcp, sc_bool_t *nasrc_sel, sc_bool_t *compok, uint8_t *nasrc, sc_bool_t *psw
_ovr)

This function gets the compensation control specific to 28FDSOI.

14.6.1 Detailed Description

Header file containing the public API for the System Controller (SC) Pad Control (PAD) function.

14.7 platform/svc/pm/api.h File Reference

Header file containing the public API for the System Controller (SC) Power Management (PM) function.

Macros

Defines for type widths

• #define SC_PM_POWER_MODE_W 2U

Width of sc_pm_power_mode_t.

#define SC PM CLOCK MODE W 3U

Width of sc pm clock mode t.

• #define SC PM RESET TYPE W 2U

Width of sc_pm_reset_type_t.

• #define SC PM RESET REASON W 4U

Width of sc_pm_reset_reason_t.

Defines for ALL parameters

#define SC_PM_CLK_ALL ((sc_pm_clk_t) UINT8_MAX)
 All clocks.

Defines for sc pm power mode t

 #define SC_PM_PW_MODE_OFF 0U Power off.

- #define SC_PM_PW_MODE_STBY 1U
 - Power in standby.
- #define SC PM PW MODE LP 2U
 - Power in low-power.
- #define SC_PM_PW_MODE_ON 3U

Power on.

Defines for sc_pm_clk_t

- #define SC_PM_CLK_SLV_BUS 0U
 - Slave bus clock.
- #define SC_PM_CLK_MST_BUS 1U
 - Master bus clock.
- #define SC PM CLK PER 2U
 - Peripheral clock.
- #define SC_PM_CLK_PHY 3U
 - Phy clock.
- #define SC PM CLK MISC 4U
 - Misc clock.
- #define SC_PM_CLK_MISC0 0U
 - Misc 0 clock.
- #define SC_PM_CLK_MISC1 1U
 - Misc 1 clock.
- #define SC_PM_CLK_MISC2 2U
 - Misc 2 clock.
- #define SC_PM_CLK_MISC3 3U
 - Misc 3 clock.
- #define SC_PM_CLK_MISC4 4U
 - Misc 4 clock.
- #define SC_PM_CLK_CPU 2U
 - CPU clock.
- #define SC_PM_CLK_PLL 4U
 - PLL
- #define SC_PM_CLK_BYPASS 4U
 - Bypass clock.

Defines for sc_pm_clk_parent_t

- #define SC_PM_PARENT_XTAL 0U
 - Parent is XTAL.
- #define SC_PM_PARENT_PLL0 1U
 - Parent is PLL0.
- #define SC_PM_PARENT_PLL1 2U
 - Parent is PLL1 or PLL0/2.
- #define SC_PM_PARENT_PLL2 3U
 - Parent in PLL2 or PLL0/4.
- #define SC_PM_PARENT_BYPS 4U
 - Parent is a bypass clock.

Defines for sc pm reset type t

#define SC_PM_RESET_TYPE_COLD 0U

Cold reset.

#define SC_PM_RESET_TYPE_WARM 1U
 Warm reset.
 #define SC_PM_RESET_TYPE_BOARD 2U
 Board reset.

Defines for sc_pm_reset_reason_t

#define SC_PM_RESET_REASON_POR 0U

Power on reset.

#define SC_PM_RESET_REASON_JTAG 1U

JTAG reset.

#define SC_PM_RESET_REASON_SW 2U

Software reset.

• #define SC PM RESET REASON WDOG 3U

Partition watchdog reset.

#define SC_PM_RESET_REASON_LOCKUP 4U

SCU lockup reset.

#define SC_PM_RESET_REASON_SNVS 5U

SNVS reset.

#define SC PM RESET REASON TEMP 6U

Temp panic reset.

• #define SC PM RESET REASON MSI 7U

MSI reset.

#define SC_PM_RESET_REASON_UECC 8U

ECC reset.

• #define SC PM RESET REASON SCFW WDOG 9U

SCFW watchdog reset.

#define SC_PM_RESET_REASON_ROM_WDOG 10U

SCU ROM watchdog reset.

#define SC PM RESET REASON SECO 11U

SECO reset.

#define SC_PM_RESET_REASON_SCFW_FAULT 12U

SCFW fault reset.

#define SC_PM_RESET_REASON_V2X_DEBUG 13U

V2X debug switch.

Defines for sc pm sys if t

• #define SC PM SYS IF INTERCONNECT 0U

System interconnect.

#define SC_PM_SYS_IF_MU 1U

AP -> SCU message units.

#define SC_PM_SYS_IF_OCMEM 2U

On-chip memory (ROM/OCRAM)

#define SC_PM_SYS_IF_DDR 3U

DDR memory.

Defines for sc_pm_wake_src_t

• #define SC PM WAKE SRC NONE 0U

No wake source, used for self-kill.

#define SC_PM_WAKE_SRC_SCU 1U

Wakeup from SCU to resume CPU (IRQSTEER & GIC powered down)

#define SC PM WAKE SRC IRQSTEER 2U

Wakeup from IRQSTEER to resume CPU (GIC powered down)

#define SC_PM_WAKE_SRC_IRQSTEER_GIC 3U

Wakeup from IRQSTEER+GIC to wake CPU (GIC clock gated)

#define SC_PM_WAKE_SRC_GIC 4U

Wakeup from GIC to wake CPU.

Typedefs

typedef uint8_t sc_pm_power_mode_t

This type is used to declare a power mode.

typedef uint8 t sc pm clk t

This type is used to declare a clock.

typedef uint8 t sc pm clk parent t

This type is used to declare the clock parent.

typedef uint32 t sc pm clock rate t

This type is used to declare clock rates.

typedef uint8_t sc_pm_reset_type_t

This type is used to declare a desired reset type.

typedef uint8_t sc_pm_reset_reason_t

This type is used to declare a reason for a reset.

typedef uint8_t sc_pm_sys_if_t

This type is used to specify a system-level interface to be power managed.

typedef uint8_t sc_pm_wake_src_t

This type is used to specify a wake source for CPU resources.

Functions

Power Functions

- sc_err_t sc_pm_set_sys_power_mode (sc_ipc_t ipc, sc_pm_power_mode_t mode)
 - This function sets the system power mode.
- sc_err_t sc_pm_set_partition_power_mode (sc_ipc_t ipc, sc_rm_pt_t pt, sc_pm_power_mode_t mode)

This function sets the power mode of a partition.

sc_err_t sc_pm_get_sys_power_mode (sc_ipc_t ipc, sc_rm_pt_t pt, sc_pm_power_mode_t *mode)

This function gets the power mode of a partition.

• sc_err_t sc_pm_partition_wake (sc_ipc_t ipc, sc_rm_pt_t pt)

This function sends a wake interrupt to a partition.

- sc_err_t sc_pm_set_resource_power_mode (sc_ipc_t ipc, sc_rsrc_t resource, sc_pm_power_mode_t mode)

 This function sets the power mode of a resource.
- sc_err_t sc_pm_set_resource_power_mode_all (sc_ipc_t ipc, sc_rm_pt_t pt, sc_pm_power_mode_t mode, sc_rsrc_t exclude)

This function sets the power mode for all the resources owned by a child partition.

- sc_err_t sc_pm_get_resource_power_mode (sc_ipc_t ipc, sc_rsrc_t resource, sc_pm_power_mode_t *mode)

 This function gets the power mode of a resource.
- sc_err_t sc_pm_req_low_power_mode (sc_ipc_t ipc, sc_rsrc_t resource, sc_pm_power_mode_t mode)

This function specifies the low power mode some of the resources can enter based on their state.

 sc_err_t sc_pm_req_cpu_low_power_mode (sc_ipc_t ipc, sc_rsrc_t resource, sc_pm_power_mode_t mode, sc_pm_wake_src_t wake_src)

This function requests low-power mode entry for CPU/cluster resources.

sc_err_t sc_pm_set_cpu_resume_addr (sc_ipc_t ipc, sc_rsrc_t resource, sc_faddr_t address)

This function is used to set the resume address of a CPU.

- sc_err_t sc_pm_set_cpu_resume (sc_ipc_t ipc, sc_rsrc_t resource, sc_bool_t isPrimary, sc_faddr_t address)

 This function is used to set parameters for CPU resume from low-power mode.
- sc_err_t sc_pm_req_sys_if_power_mode (sc_ipc_t ipc, sc_rsrc_t resource, sc_pm_sys_if_t sys_
 if, sc_pm_power_mode_t hpm, sc_pm_power_mode_t lpm)

This function requests the power mode configuration for system-level interfaces including messaging units, interconnect, and memories.

Clock/PLL Functions

• sc_err_t sc_pm_set_clock_rate (sc_ipc_t ipc, sc_rsrc_t resource, sc_pm_clk_t clk, sc_pm_clock_rate_t *rate)

This function sets the rate of a resource's clock/PLL.

• sc_err_t sc_pm_get_clock_rate (sc_ipc_t ipc, sc_rsrc_t resource, sc_pm_clk_t clk, sc_pm_clock_rate_t *rate)

This function gets the rate of a resource's clock/PLL.

sc_err_t sc_pm_clock_enable (sc_ipc_t ipc, sc_rsrc_t resource, sc_pm_clk_t clk, sc_bool_t enable, sc_bool_t autog)

This function enables/disables a resource's clock.

sc_err_t sc_pm_set_clock_parent (sc_ipc_t ipc, sc_rsrc_t resource, sc_pm_clk_t clk, sc_pm_clk_parent_t parent)

This function sets the parent of a resource's clock.

sc_err_t sc_pm_get_clock_parent (sc_ipc_t ipc, sc_rsrc_t resource, sc_pm_clk_t clk, sc_pm_clk_parent_t *parent)

This function gets the parent of a resource's clock.

Reset Functions

sc_err_t sc_pm_reset (sc_ipc_t ipc, sc_pm_reset_type_t type)

This function is used to reset the system.

sc_err_t sc_pm_reset_reason (sc_ipc_t ipc, sc_pm_reset_reason_t *reason)

This function gets a caller's reset reason.

sc_err_t sc_pm_get_reset_part (sc_ipc_t ipc, sc_rm_pt_t *pt)

This function gets the partition that caused a reset.

• sc_err_t sc_pm_boot (sc_ipc_t ipc, sc_rm_pt_t pt, sc_rsrc_t resource_cpu, sc_faddr_t boot_addr, sc_rsrc_t resource_mu, sc_rsrc_t resource_dev)

This function is used to boot a partition.

• sc_err_t sc_pm_set_boot_parm (sc_ipc_t ipc, sc_rsrc_t resource_cpu, sc_faddr_t boot_addr, sc_rsrc_t resource_mu, sc_rsrc_t resource_dev)

This function is used to change the boot parameters for a partition.

void sc_pm_reboot (sc_ipc_t ipc, sc_pm_reset_type_t type)

This function is used to reboot the caller's partition.

sc_err_t sc_pm_reboot_partition (sc_ipc_t ipc, sc_rm_pt_t pt, sc_pm_reset_type_t type)

This function is used to reboot a partition.

sc_err_t sc_pm_reboot_continue (sc_ipc_t ipc, sc_rm_pt_t pt)

This function is used to continue the reboot a partition.

sc_err_t sc_pm_cpu_start (sc_ipc_t ipc, sc_rsrc_t resource, sc_bool_t enable, sc_faddr_t address)

This function is used to start/stop a CPU.

void sc_pm_cpu_reset (sc_ipc_t ipc, sc_rsrc_t resource, sc_faddr_t address)

This function is used to reset a CPU.

sc_err_t sc_pm_resource_reset (sc_ipc_t ipc, sc_rsrc_t resource)

This function is used to reset a peripheral.

sc_bool_t sc_pm_is_partition_started (sc_ipc_t ipc, sc_rm_pt_t pt)

This function returns a bool indicating if a partition was started.

14.7.1 Detailed Description

Header file containing the public API for the System Controller (SC) Power Management (PM) function.

This includes functions for power state control, clock control, reset control, and wake-up event control.

14.8 platform/svc/rm/api.h File Reference

Header file containing the public API for the System Controller (SC) Resource Management (RM) function.

Macros

Defines for type widths

```
• #define SC_RM_PARTITION_W 5U
```

Width of sc_rm_pt_t.

#define SC_RM_MEMREG_W 6U

Width of sc_rm_mr_t.

• #define SC_RM_DID_W 4U

Width of sc rm did t.

#define SC RM SID W 6U

Width of sc_rm_sid_t.

• #define SC_RM_SPA_W 2U

Width of sc_rm_spa_t.

#define SC_RM_PERM_W 3U

Width of sc_rm_perm_t.

• #define SC_RM_DET_W 1U

Width of sc_rm_det_t.

• #define SC_RM_RMSG_W 4U

Width of sc_rm_rmsg_t.

Defines for ALL parameters

#define SC_RM_PT_ALL ((sc_rm_pt_t) UINT8_MAX)

All partitions.

#define SC_RM_MR_ALL ((sc_rm_mr_t) UINT8_MAX)

All memory regions.

Defines for sc_rm_spa_t

• #define SC_RM_SPA_PASSTHRU 0U

Pass through (attribute driven by master)

#define SC_RM_SPA_PASSSID 1U

Pass through and output on SID.

#define SC_RM_SPA_ASSERT 2U

Assert (force to be secure/privileged)

#define SC_RM_SPA_NEGATE 3U

Negate (force to be non-secure/user)

Defines for sc_rm_perm_t

#define SC_RM_PERM_NONE 0U

No access.

• #define SC_RM_PERM_SEC_R 1U

Secure RO.

• #define SC_RM_PERM_SECPRIV_RW 2U

Secure privilege R/W.

#define SC_RM_PERM_SEC_RW 3U

Secure R/W.

• #define SC RM PERM NSPRIV R 4U

Secure R/W, non-secure privilege RO.

#define SC RM PERM NS R 5U

Secure R/W, non-secure RO.

#define SC_RM_PERM_NSPRIV_RW 6U

Secure R/W, non-secure privilege R/W.

• #define SC_RM_PERM_FULL 7U

Full access.

Typedefs

typedef uint8 t sc rm pt t

This type is used to declare a resource partition.

typedef uint8_t sc_rm_mr_t

This type is used to declare a memory region.

typedef uint8 t sc rm did t

This type is used to declare a resource domain ID used by the isolation HW.

• typedef uint16_t sc_rm_sid_t

This type is used to declare an SMMU StreamID.

• typedef uint8_t sc_rm_spa_t

This type is a used to declare master transaction attributes.

typedef uint8_t sc_rm_perm_t

This type is used to declare a resource/memory region access permission.

typedef uint8_t sc_rm_det_t

This type is used to indicate memory region transactions should detour to the IEE.

typedef uint8_t sc_rm_rmsg_t

This type is used to assign an RMSG value to a memory region.

Functions

Partition Functions

sc_err_t sc_rm_partition_alloc (sc_ipc_t ipc, sc_rm_pt_t *pt, sc_bool_t secure, sc_bool_t isolated, sc_bool_t restricted, sc_bool_t grant, sc_bool_t coherent)

This function requests that the SC create a new resource partition.

sc_err_t sc_rm_set_confidential (sc_ipc_t ipc, sc_rm_pt_t pt, sc_bool_t retro)

This function makes a partition confidential.

• sc_err_t sc_rm_partition_free (sc_ipc_t ipc, sc_rm_pt_t pt)

This function frees a partition and assigns all resources to the caller.

• sc_rm_did_t sc_rm_get_did (sc_ipc_t ipc)

This function returns the DID of a partition.

sc_err_t sc_rm_partition_static (sc_ipc_t ipc, sc_rm_pt_t pt, sc_rm_did_t did)

This function forces a partition to use a specific static DID.

sc_err_t sc_rm_partition_lock (sc_ipc_t ipc, sc_rm_pt_t pt)

This function locks a partition.

• sc err t sc rm get partition (sc ipc t ipc, sc rm pt t *pt)

This function gets the partition handle of the caller.

sc_err_t sc_rm_set_parent (sc_ipc_t ipc, sc_rm_pt_t pt, sc_rm_pt_t pt_parent)

This function sets a new parent for a partition.

sc_err_t sc_rm_move_all (sc_ipc_t ipc, sc_rm_pt_t pt_src, sc_rm_pt_t pt_dst, sc_bool_t move_rsrc, sc_bool_t move pads)

This function moves all movable resources/pads owned by a source partition to a destination partition.

Resource Functions

sc_err_t sc_rm_assign_resource (sc_ipc_t ipc, sc_rm_pt_t pt, sc_rsrc_t resource)

This function assigns ownership of a resource to a partition.

sc_err_t sc_rm_set_resource_movable (sc_ipc_t ipc, sc_rsrc_t resource_fst, sc_rsrc_t resource_lst, sc_bool_t movable)

This function flags resources as movable or not.

sc_err_t sc_rm_set_subsys_rsrc_movable (sc_ipc_t ipc, sc_rsrc_t resource, sc_bool_t movable)

This function flags all of a subsystem's resources as movable or not.

 sc_err_t sc_rm_set_master_attributes (sc_ipc_t ipc, sc_rsrc_t resource, sc_rm_spa_t sa, sc_rm_spa_t pa, sc bool t smmu bypass)

This function sets attributes for a resource which is a bus master (i.e.

sc_err_t sc_rm_set_master_sid (sc_ipc_t ipc, sc_rsrc_t resource, sc_rm_sid_t sid)

This function sets the StreamID for a resource which is a bus master (i.e.

sc_err_t sc_rm_set_peripheral_permissions (sc_ipc_t ipc, sc_rsrc_t resource, sc_rm_pt_t pt, sc_rm_perm_t perm)

This function sets access permissions for a peripheral resource.

sc_bool_t sc_rm_is_resource_owned (sc_ipc_t ipc, sc_rsrc_t resource)

This function gets ownership status of a resource.

sc_err_t sc_rm_get_resource_owner (sc_ipc_t ipc, sc_rsrc_t resource, sc_rm_pt_t *pt)

This function is used to get the owner of a resource.

• sc bool t sc rm is resource master (sc ipc t ipc, sc rsrc t resource)

This function is used to test if a resource is a bus master.

• sc_bool_t sc_rm_is_resource_peripheral (sc_ipc_t ipc, sc_rsrc_t resource)

This function is used to test if a resource is a peripheral.

sc_err_t sc_rm_get_resource_info (sc_ipc_t ipc, sc_rsrc_t resource, sc_rm_sid_t *sid)

This function is used to obtain info about a resource.

Memory Region Functions

- sc_err_t sc_rm_memreg_alloc (sc_ipc_t ipc, sc_rm_mr_t *mr, sc_faddr_t addr_start, sc_faddr_t addr_end)

 This function requests that the SC create a new memory region.
- sc_err_t sc_rm_memreg_split (sc_ipc_t ipc, sc_rm_mr_t mr, sc_rm_mr_t *mr_ret, sc_faddr_t addr_start, sc_faddr_t addr_end)

This function requests that the SC split an existing memory region.

- sc_err_t sc_rm_memreg_frag (sc_ipc_t ipc, sc_rm_mr_t *mr_ret, sc_faddr_t addr_start, sc_faddr_t addr_end)

 This function requests that the SC fragment a memory region.
- sc_err_t sc_rm_memreg_free (sc_ipc_t ipc, sc_rm_mr_t mr)

This function frees a memory region.

- sc_err_t sc_rm_find_memreg (sc_ipc_t ipc, sc_rm_mr_t *mr, sc_faddr_t addr_start, sc_faddr_t addr_end)

 Internal SC function to find a memory region.
- sc_err_t sc_rm_assign_memreg (sc_ipc_t ipc, sc_rm_pt_t pt, sc_rm_mr_t mr)

This function assigns ownership of a memory region.

- sc_err_t sc_rm_set_memreg_permissions (sc_ipc_t ipc, sc_rm_mr_t mr, sc_rm_pt_t pt, sc_rm_perm_t perm)

 This function sets access permissions for a memory region.
- sc_err_t sc_rm_set_memreg_iee (sc_ipc_t ipc, sc_rm_mr_t mr, sc_rm_det_t det, sc_rm_rmsg_t rmsg)

This function configures the IEE parameters for a memory region.

sc_bool_t sc_rm_is_memreg_owned (sc_ipc_t ipc, sc_rm_mr_t mr)

This function gets ownership status of a memory region.

sc_err_t sc_rm_get_memreg_info (sc_ipc_t ipc, sc_rm_mr_t mr, sc_faddr_t *addr_start, sc_faddr_t *addr_← end)

This function is used to obtain info about a memory region.

Pad Functions

- sc_err_t sc_rm_assign_pad (sc_ipc_t ipc, sc_rm_pt_t pt, sc_pad_t pad)
 - This function assigns ownership of a pad to a partition.
- sc_err_t sc_rm_set_pad_movable (sc_ipc_t ipc, sc_pad_t pad_fst, sc_pad_t pad_lst, sc_bool_t movable)
 This function flags pads as movable or not.
- sc_bool_t sc_rm_is_pad_owned (sc_ipc_t ipc, sc_pad_t pad)

This function gets ownership status of a pad.

Debug Functions

• void sc rm dump (sc ipc t ipc)

This function dumps the RM state for debug.

14.8.1 Detailed Description

Header file containing the public API for the System Controller (SC) Resource Management (RM) function.

This includes functions for partitioning resources, pads, and memory regions.

14.9 platform/svc/seco/api.h File Reference

Header file containing the public API for the System Controller (SC) Security (SECO) function.

Macros

Defines for sc_seco_auth_cmd_t

- #define SC_SECO_AUTH_CONTAINER 0U
 - Authenticate container.
- #define SC_SECO_VERIFY_IMAGE 1U
 - Verify image.
- #define SC_SECO_REL_CONTAINER 2U
 - Release container.
- #define SC SECO AUTH SECO FW 3U
 - SECO Firmware.
- #define SC_SECO_AUTH_HDMI_TX_FW 4U
 - HDMI TX Firmware.
- #define SC_SECO_AUTH_HDMI_RX_FW 5U
 - HDMI RX Firmware.
- #define SC_SECO_EVERIFY_IMAGE 6U

Enhanced verify image.

Defines for seco rng stat t

- #define SC_SECO_RNG_STAT_UNAVAILABLE 0U
 - Unable to initialize the RNG.
- #define SC_SECO_RNG_STAT_INPROGRESS 1U
 - Initialization is on-going.
- #define SC_SECO_RNG_STAT_READY 2U

Initialized.

Typedefs

typedef uint8 t sc seco auth cmd t

This type is used to issue SECO authenticate commands.

typedef uint32_t sc_seco_rng_stat_t

This type is used to return the RNG initialization status.

Functions

Image Functions

sc_err_t sc_seco_image_load (sc_ipc_t ipc, sc_faddr_t addr_src, sc_faddr_t addr_dst, uint32_t len, sc_bool_t fw)

This function loads a SECO image.

sc_err_t sc_seco_authenticate (sc_ipc_t ipc, sc_seco_auth_cmd_t cmd, sc_faddr_t addr)

This function is used to authenticate a SECO image or command.

sc_err_t sc_seco_enh_authenticate (sc_ipc_t ipc, sc_seco_auth_cmd_t cmd, sc_faddr_t addr, uint32_t mask1, uint32_t mask2)

This function is used to authenticate a SECO image or command.

Lifecycle Functions

sc_err_t sc_seco_forward_lifecycle (sc_ipc_t ipc, uint32_t change)

This function updates the lifecycle of the device.

sc_err_t sc_seco_return_lifecycle (sc_ipc_t ipc, sc_faddr_t addr)

This function updates the lifecycle to one of the return lifecycles.

sc_err_t sc_seco_commit (sc_ipc_t ipc, uint32_t *info)

This function is used to commit into the fuses any new SRK revocation and FW version information that have been found in the primary and secondary containers.

Attestation Functions

sc_err_t sc_seco_attest_mode (sc_ipc_t ipc, uint32_t mode)

This function is used to set the attestation mode.

sc_err_t sc_seco_attest (sc_ipc_t ipc, uint64_t nonce)

This function is used to request attestation.

sc_err_t sc_seco_get_attest_pkey (sc_ipc_t ipc, sc_faddr_t addr)

This function is used to retrieve the attestation public key.

sc_err_t sc_seco_get_attest_sign (sc_ipc_t ipc, sc_faddr_t addr)

This function is used to retrieve attestation signature and parameters.

sc_err_t sc_seco_attest_verify (sc_ipc_t ipc, sc_faddr_t addr)

This function is used to verify attestation.

Key Functions

 sc_err_t sc_seco_gen_key_blob (sc_ipc_t ipc, uint32_t id, sc_faddr_t load_addr, sc_faddr_t export_addr, uint16 t max size)

This function is used to generate a SECO key blob.

sc_err_t sc_seco_load_key (sc_ipc_t ipc, uint32_t id, sc_faddr_t addr)

This function is used to load a SECO key.

Manufacturing Protection Functions

```
• sc_err_t sc_seco_get_mp_key (sc_ipc_t ipc, sc_faddr_t dst_addr, uint16_t dst_size)
```

This function is used to get the manufacturing protection public key.

sc_err_t sc_seco_update_mpmr (sc_ipc_t ipc, sc_faddr_t addr, uint8_t size, uint8_t lock)

This function is used to update the manufacturing protection message register.

sc_err_t sc_seco_get_mp_sign (sc_ipc_t ipc, sc_faddr_t msg_addr, uint16_t msg_size, sc_faddr_t dst_addr, uint16_t dst_size)

This function is used to get the manufacturing protection signature.

Debug Functions

• void sc_seco_build_info (sc_ipc_t ipc, uint32_t *version, uint32_t *commit)

This function is used to return the SECO FW build info.

• sc_err_t sc_seco_chip_info (sc_ipc_t ipc, uint16_t *lc, uint16_t *monotonic, uint32_t *uid_l, uint32_t *uid_h)

This function is used to return SECO chip info.

sc_err_t sc_seco_enable_debug (sc_ipc_t ipc, sc_faddr_t addr)

This function securely enables debug.

sc_err_t sc_seco_get_event (sc_ipc_t ipc, uint8_t idx, uint32_t *event)

This function is used to return an event from the SECO error log.

Miscellaneous Functions

• sc err t sc seco fuse write (sc ipc t ipc, sc faddr t addr)

This function securely writes a group of fuse words.

sc_err_t sc_seco_patch (sc_ipc_t ipc, sc_faddr_t addr)

This function applies a patch.

sc_err_t sc_seco_set_mono_counter_partition (sc_ipc_t ipc, uint16_t *she)

This function partitions the monotonic counter.

sc_err_t sc_seco_set_fips_mode (sc_ipc_t ipc, uint8_t mode, uint32_t *reason)

This function configures the SECO in FIPS mode.

• sc_err_t sc_seco_start_rng (sc_ipc_t ipc, sc_seco_rng_stat_t *status)

This function starts the random number generator.

sc_err_t sc_seco_sab_msg (sc_ipc_t ipc, sc_faddr_t addr)

This function sends a generic signed message to the SECO SHE/HSM components.

sc_err_t sc_seco_secvio_enable (sc_ipc_t ipc)

This function is used to enable security violation and tamper interrupts.

sc_err_t sc_seco_secvio_config (sc_ipc_t ipc, uint8_t id, uint8_t access, uint32_t *data0, uint32_t *data1, uint32_t *data2, uint32_t *data3, uint32_t *data4, uint8_t size)

This function is used to read/write SNVS security violation and tamper registers.

• sc_err_t sc_seco_secvio_dgo_config (sc_ipc_t ipc, uint8_t id, uint8_t access, uint32_t *data)

This function is used to read/write SNVS security violation and tamper DGO registers.

14.9.1 Detailed Description

Header file containing the public API for the System Controller (SC) Security (SECO) function.

14.10 platform/svc/timer/api.h File Reference

Header file containing the public API for the System Controller (SC) Timer function.

Macros

Defines for type widths

#define SC_TIMER_ACTION_W 3U
 Width of sc_timer_wdog_action_t.

Defines for sc_timer_wdog_action_t

- #define SC_TIMER_WDOG_ACTION_PARTITION 0U Reset partition.
- #define SC_TIMER_WDOG_ACTION_WARM 1U

Warm reset system.

#define SC TIMER WDOG ACTION COLD 2U

Cold reset system.

#define SC_TIMER_WDOG_ACTION_BOARD 3U

Reset board.

#define SC TIMER WDOG ACTION IRQ 4U

Only generate IRQs.

Typedefs

typedef uint8_t sc_timer_wdog_action_t

This type is used to configure the watchdog action.

typedef uint32_t sc_timer_wdog_time_t

This type is used to declare a watchdog time value in milliseconds.

Functions

Watchdog Functions

- sc_err_t sc_timer_set_wdog_timeout (sc_ipc_t ipc, sc_timer_wdog_time_t timeout)
 - This function sets the watchdog timeout in milliseconds.
- sc_err_t sc_timer_set_wdog_pre_timeout (sc_ipc_t ipc, sc_timer_wdog_time_t pre_timeout)

This function sets the watchdog pre-timeout in milliseconds.

sc_err_t sc_timer_set_wdog_window (sc_ipc_t ipc, sc_timer_wdog_time_t window)

This function sets the watchdog window in milliseconds.

sc_err_t sc_timer_start_wdog (sc_ipc_t ipc, sc_bool_t lock)

This function starts the watchdog.

sc err t sc timer stop wdog (sc ipc t ipc)

This function stops the watchdog if it is not locked.

sc_err_t sc_timer_ping_wdog (sc_ipc_t ipc)

This function pings (services, kicks) the watchdog resetting the time before expiration back to the timeout.

• sc_err_t sc_timer_get_wdog_status (sc_ipc_t ipc, sc_timer_wdog_time_t *timeout, sc_timer_wdog_time_t *max_timeout, sc_timer_wdog_time_t *remaining_time)

This function gets the status of the watchdog.

sc_err_t sc_timer_pt_get_wdog_status (sc_ipc_t ipc, sc_rm_pt_t pt, sc_bool_t *enb, sc_timer_wdog_time_t *timeout, sc_timer_wdog_time_t t*remaining_time)

This function gets the status of the watchdog of a partition.

sc_err_t sc_timer_set_wdog_action (sc_ipc_t ipc, sc_rm_pt_t pt, sc_timer_wdog_action_t action)

This function configures the action to be taken when a watchdog expires.

Real-Time Clock (RTC) Functions

sc_err_t sc_timer_set_rtc_time (sc_ipc_t ipc, uint16_t year, uint8_t mon, uint8_t day, uint8_t hour, uint8_t min, uint8_t sec)

This function sets the RTC time.

• sc_err_t sc_timer_get_rtc_time (sc_ipc_t ipc, uint16_t *year, uint8_t *mon, uint8_t *day, uint8_t *hour, uint8_t *min, uint8_t *sec)

This function gets the RTC time.

• sc err t sc timer get rtc sec1970 (sc ipc t ipc, uint32 t *sec)

This function gets the RTC time in seconds since 1/1/1970.

sc_err_t sc_timer_set_rtc_alarm (sc_ipc_t ipc, uint16_t year, uint8_t mon, uint8_t day, uint8_t hour, uint8_t min, uint8_t sec)

This function sets the RTC alarm.

• sc_err_t sc_timer_set_rtc_periodic_alarm (sc_ipc_t ipc, uint32_t sec)

This function sets the RTC alarm (periodic mode).

sc_err_t sc_timer_cancel_rtc_alarm (sc_ipc_t ipc)

This function cancels the RTC alarm.

• sc_err_t sc_timer_set_rtc_calb (sc_ipc_t ipc, int8_t count)

This function sets the RTC calibration value.

System Counter (SYSCTR) Functions

sc err t sc timer set sysctr alarm (sc ipc t ipc, uint64 t ticks)

This function sets the SYSCTR alarm.

sc_err_t sc_timer_set_sysctr_periodic_alarm (sc_ipc_t ipc, uint64_t ticks)

This function sets the SYSCTR alarm (periodic mode).

sc_err_t sc_timer_cancel_sysctr_alarm (sc_ipc_t ipc)

This function cancels the SYSCTR alarm.

14.10.1 Detailed Description

Header file containing the public API for the System Controller (SC) Timer function.

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