

Assignment 05

Solving Boundary Value Problem Using Finite Difference Method

Mayank Pathania
204103314

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1 Formulation

Boundary value problem is of the form

$$x'' = f(t, x, x')$$

$$\text{in } a \leq t \leq b \text{ with } x(a) = \alpha; x(b) = \beta$$

Central difference formula:

$$x'(t) = \frac{1}{2h}[x(t+h) - x(t-h)]$$

$$x''(t) = \frac{1}{h^2}[x(t+h) - 2x(t) + x(t-h)]$$

where h is spacing between consecutive data points. For equal spacing

$$h = \left(\frac{b-a}{n}\right)$$

where n is number of intervals.

Given Problem:

$$x'' = x \sin(t) + x' \cos(t) - e^t$$

$$x(0) = 0; x(1) = 1;$$

The problem can be written using central difference formulas as

$$\frac{1}{h^2}[x(t+h) - 2x(t) + x(t-h)] = x_i \sin(t_i) + \frac{1}{2h}[x(t+h) - x(t-h)] \cos(t_i) - e^{t_i}$$

$$\frac{1}{h^2}(x_{i+1} - 2x_i + x_{i-1}) = x_i \sin(t_i) + \frac{1}{2h}(x_{i+1} - x_{i-1}) \cos(t_i) - e^{t_i}$$

where

$$t_i = a + ih \quad i = 1, 2, \dots, n-1$$

$$x_i = x(t_i)$$

now collecting x_{i+1} , x_i , x_{i-1} terms on LHS and terms without x on RHS we get

$$\left(\frac{1}{h^2} - \frac{\cos(t_i)}{2h}\right)x_{i+1} - \left(\frac{2}{h^2} + \sin(t_i)\right)x_i + \left(\frac{1}{h^2} + \frac{\cos(t_i)}{2h}\right)x_{i-1} = -e^{t_i}$$

multiplying both side by h^2 we get

$$\left(1 - \frac{h\cos(t_i)}{2}\right)x_{i+1} - (2 + h^2\sin(t_i))x_i + \left(1 + \frac{h\cos(t_i)}{2}\right)x_{i-1} = -h^2e^{t_i}$$

Then we can write this above equation in the form

$$a_i x_{i-1} + d_i x_i + c_i x_{i+1} = b_i$$

where

$$a_i = \left(1 + \frac{h\cos(t_i)}{2}\right)$$

$$b_i = -h^2e^{t_i}$$

$$d_i = -(2 + h^2\sin(t_i))$$

$$c_i = \left(1 - \frac{h\cos(t_i)}{2}\right)$$

as $x_0 = \alpha$ and $x_n = \beta$ are known we can write the above equation as

$$d_1 x_1 + c_1 x_2 = b_1 - a_1 \alpha$$

$$a_2 x_1 + d_2 x_2 + c_2 x_3 = b_2$$

$$a_3 x_2 + d_3 x_3 + c_3 x_4 = b_3$$

$$\vdots$$

$$a_{n-1} x_{n-2} + d_{n-1} x_{n-1} = b_{n-1} - c_{n-1} \beta$$

Now these equations can be written in matrix form as

$$\begin{bmatrix} d_1 & c_1 & 0 & 0 & 0 & \dots & 0 & 0 \\ a_2 & d_2 & c_2 & 0 & 0 & \dots & 0 & 0 \\ 0 & a_3 & d_3 & c_3 & 0 & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \dots & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & \dots & a_{n-1} & d_{n-1} \end{bmatrix} \begin{Bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_{n-1} \end{Bmatrix} = \begin{Bmatrix} b_1 - a_1 \alpha \\ b_2 \\ b_3 \\ \vdots \\ b_{n-1} - c_{n-1} \beta \end{Bmatrix}$$

The matrix is tridiagonal matrix. And the problem is of the form $\mathbf{Ax} = \mathbf{B}$ and it can be solved using gauss elimination method.

2 Algorithms

2.1 Initialization

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1: procedure FILL_AB(m, a, b,  $\alpha$ ,  $\beta$ )
                                 $\triangleright$  m = number of intervals - 1
                                 $\triangleright$   $x(a) = \alpha$ ;  $x(b) = \beta$ 
                                 $\triangleright$  Only tridiagonal elements are stored
2:   A  $\leftarrow$  initialize matrix of size  $m \times 3$ 
3:   B  $\leftarrow$  initialize vector of size m
4:   for i  $\leftarrow$  1:1:m do
5:
6:       if i > 1 then
7:           A[i][1]  $\leftarrow$   $a_i$ 
8:       end if
9:       A[i][2]  $\leftarrow$   $d_i$ 
10:      if i < m then
11:          A[i][3]  $\leftarrow$   $c_i$ 
12:      end if
13:      B[i]  $\leftarrow$   $b_i$ 
14:  end for
15:  B[0]  $\leftarrow$  B[0] -  $a_1 * \alpha$ 
16:  B[m]  $\leftarrow$  B[m] -  $c_m * \beta$ 
17:  return A,B
18: end procedure

```

$\triangleright a_i, b_i, c_i, d_i$ are from formulation

2.2 Solving $Ax = B$

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1: procedure SOLVE(A[[[]], B[])
                                 $\triangleright$  A[[[]]] is matrix of size  $m \times 3$ 
                                 $\triangleright$  B[] is vector of size  $m \times 1$ 
                                 $\triangleright$  Elimination Steps
2:   for i  $\leftarrow$  1:1:m-1 do
3:       ratio  $\leftarrow$   $\frac{A[i+1][1]}{A[i][2]}$ 
4:       A[i + 1][2]  $\leftarrow$  A[i + 1][2] - (ratio  $\times$  A[i][3])
5:       B[i + 1]  $\leftarrow$  B[i + 1] - (ratio  $\times$  B[i])
6:   end for
                                 $\triangleright$  Backsubstitution
7:   x  $\leftarrow$  initialize vector of size  $m \times 1$ 
8:   x[m]  $\leftarrow$   $\frac{B[m]}{A[m][2]}$ 
9:   for i  $\leftarrow$  m - 1:-1:1 do
10:      x[i]  $\leftarrow$   $\frac{B[i] - (A[i][3] \times x[i+1])}{A[i][2]}$ 
11:   end for
12:   return x
13: end procedure

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3 Results

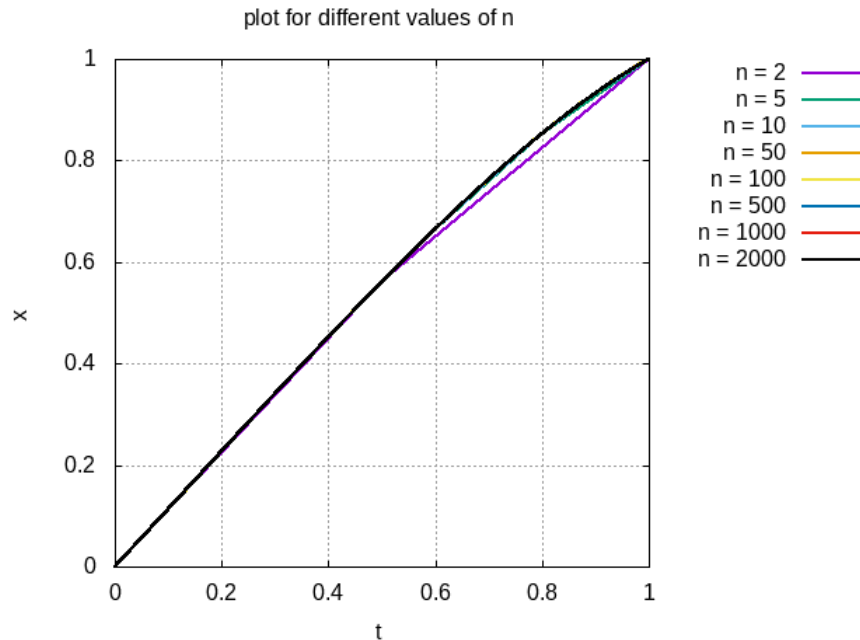
3.1 Solution

t	n = 2	n = 10	n = 100	n == 1000
0	0	0	0	0
0.1	-	0.113591	0.113569	0.113568
0.2	-	0.227566	0.227526	0.227526
0.3	-	0.34091	0.340868	0.340867
0.4	-	0.45252	0.45247	0.452469
0.5	0.562672	0.56111	0.561062	0.561061
0.6	-	0.66524	0.665196	0.665195
0.7	-	0.763251	0.76321	0.76321
0.8	-	0.853224	0.853196	0.853196
0.9	-	0.932975	0.932961	0.932961
1	1	1	1	1

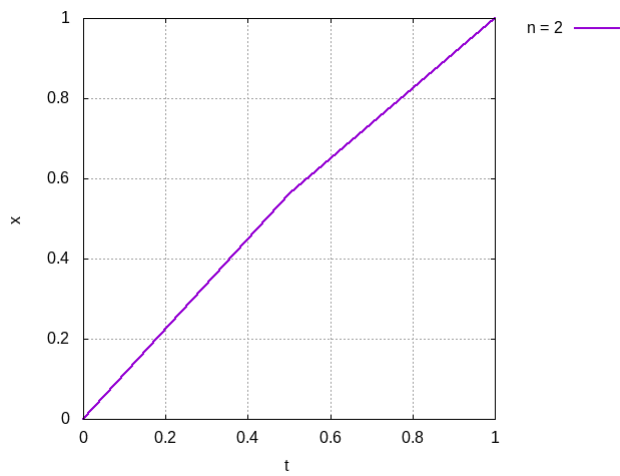
Table 1: Table showing value of $x(t)$ for various n i.e. number of intervals

3.2 Plots

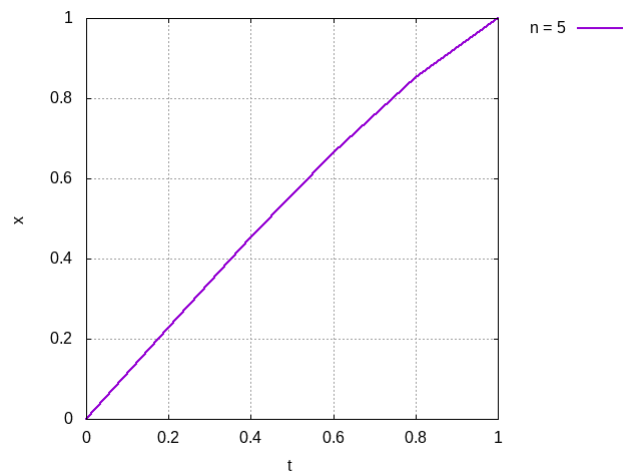
Following plot shows results obtained for different values of n .



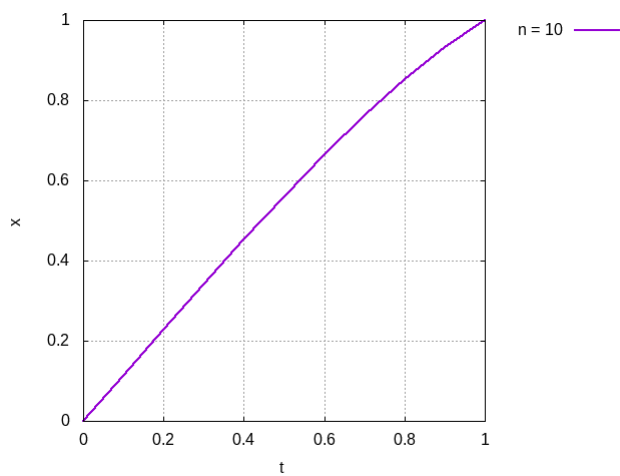
The curves are overlapping because the points obtained for different values of n had very same value up to 4 to 5 decimal places. For $n = 2$ the curve can be distinguished and for $n = 5$ the curve is almost overlapping and curves of $n = 10, 50, 100, 500, 1000, 2000$ are completely overlapping.



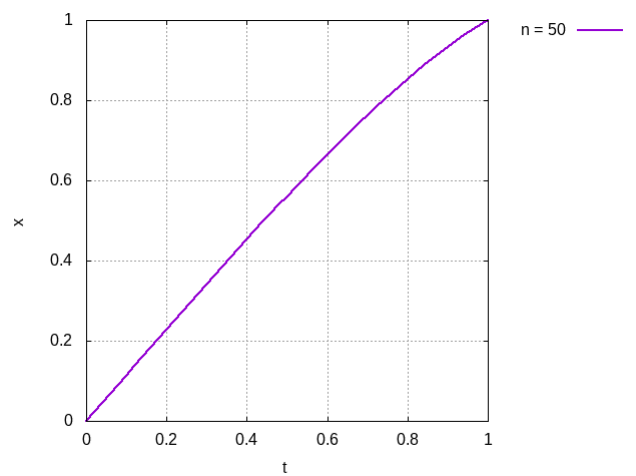
(a)



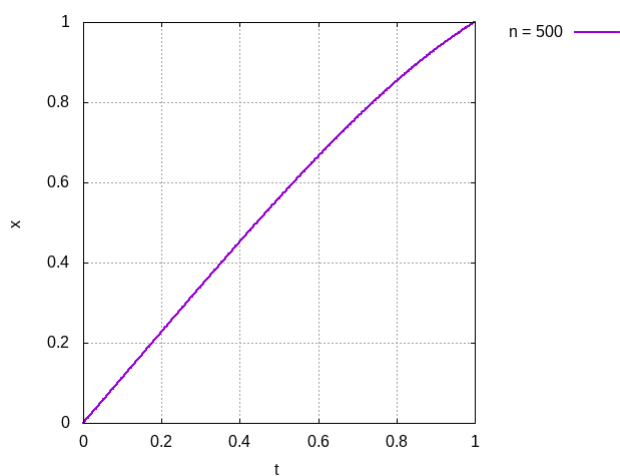
(b)



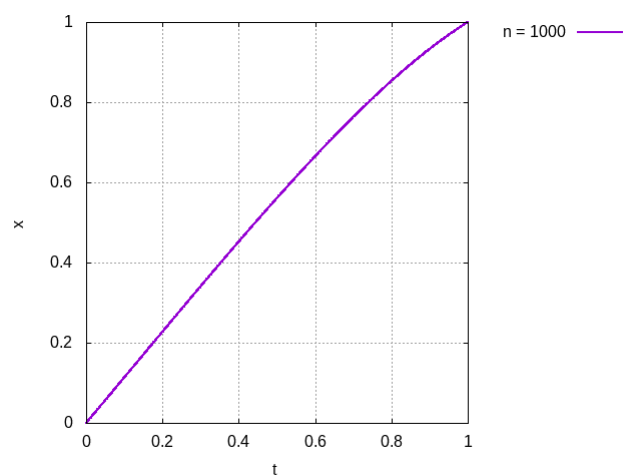
(c)



(d)



(e)



(f)

Table 2: Graphs for different values of n a) 2; b) 5; c) 10; d) 50; e) 500; f) 1000

4 Conclusion

- The given problem can be solved with 10 intervals.
- Time and Space complexity of solving tridiagonal matrix for given problem with gauss elimination is $\mathbf{O(n)}$ where n is number of intervals.