

$$\begin{aligned}
 h(t) &= r j \sin\left(\frac{\omega}{r}t\right) + \cos\left(t - \frac{\pi}{r}\right) + r \\
 &= e^{\frac{j\omega}{r}t} - e^{-\frac{j\omega}{r}t} + \frac{1}{r}(e^{j(t-\frac{\pi}{r})} + e^{-j(t-\frac{\pi}{r})}) + r \\
 &= e^{\frac{j\omega}{r}t} - e^{-\frac{j\omega}{r}t} + \frac{1}{r}e^{-\frac{j\pi}{r}}(e^{jt}) + \frac{1}{r}e^{\frac{j\pi}{r}}(e^{-jt}) + r
 \end{aligned}
 : \text{J}$$

$$\text{لوره تاب اهل سنت} \rightarrow T_0 = \frac{4\pi}{1} \quad , \quad T_r = 4\pi \quad \xrightarrow{\text{ر.م.ك}} \quad T_i = \frac{4\pi}{\frac{r}{R}} = \frac{4\pi}{\rho}$$

$$W_o = \frac{P_{IR}}{E_n} = \frac{1}{f}$$

$$\frac{\kappa}{\mu} = \mu \Rightarrow \alpha_\mu = 1$$

$$\frac{1}{r} = r \Rightarrow a_r = \frac{1}{r} e^{-\frac{\pi i}{r}}$$

$$\frac{r}{-r} = -1 \Rightarrow a_{-r} = -1$$

$$-\frac{1}{r} = -1 \Rightarrow a_{-r} = \frac{1}{r} e^{\frac{\pi i}{n} j}$$

$$a_0 = r$$

$$(K = 1 \text{--} 1 \mid K \mid >^* \Rightarrow a_{k=0})$$

$$A_K = \frac{1}{T_0} \int_{T_0} x(t) e^{-jKw_0 t} dt$$

$$T_0 = f \Rightarrow W_0 = \frac{Pf}{\epsilon} = F_p$$

$$a_K = \frac{1}{\varepsilon} \int_{-1}^{\varepsilon} \delta(t+1) e^{-jk(\frac{t}{\varepsilon})} dt = \frac{1}{\varepsilon} e^{-jk\frac{1}{\varepsilon}} = \frac{1}{\varepsilon} e^{-jk\pi} = \frac{1}{\varepsilon} (-1)^K$$

a) $x(t - t_0) + x(t + t_0)$

$$\begin{array}{ccc} \downarrow b_{iK} & & \downarrow b_{rK} \\ \end{array}$$

$$b_{iK} = a_K e^{-jKw_0 t} = a_K e^{-jK\left(\frac{\pi}{T}\right)t_0} : \text{(وقرگزىش زمان)} \text{ timeshifting}$$

$$b_{rK} = a_K e^{jKw_0 t} = a_K e^{jK\left(\frac{\pi}{T}\right)t_0}$$

$$b_K = b_{iK} + b_{rK} = a_K \left(e^{-jK\left(\frac{\pi}{T}\right)t_0} + e^{jK\left(\frac{\pi}{T}\right)t_0} \right) : \text{(خطىچىز خطي)} \text{ linearity}$$

$$x(t) \xrightarrow{FS} a_K$$

$$x(t-t_0) + x(t+t_0) \xrightarrow{FS} a_K \left(e^{-jK\left(\frac{\pi}{T}\right)t_0} + e^{jK\left(\frac{\pi}{T}\right)t_0} \right) : \text{منابى سرى فورىه}$$

$$T_1 = T, T_r = T \xrightarrow{\text{P.P.S}} T_0 = T : \text{دوره تناوب}$$

b) $\text{Even}\{x(t)\} = \frac{1}{2}(x(t) + x(-t))$

$$\begin{array}{ccc} \downarrow b_{iK} & & \downarrow b_{rK} \\ \end{array}$$

$$b_{rK} = a_{-K} : \text{وقرگزىش زىزىي زىزمان} \text{ time-reversal}$$

$$b_K = \frac{1}{2}(b_{iK} + b_{rK}) = \frac{1}{2}(a_K + a_{-K}) : \text{خطىچىز خطي} \text{ linearity}$$

$$x(t) \xrightarrow{FS} a_K$$

$$\text{Even}\{x(t)\} \xrightarrow{FS} \frac{1}{2}(a_K + a_{-K}) : \text{منابى سرى فورىه}$$

$$T_1 = T, T_r = T \xrightarrow{\text{P.P.S}} T_0 = T : \text{دوره تناوب}$$

c) $\frac{d^k x(t)}{dt^k}$

$$x(t) \xrightarrow{FS} a_K$$

$$\frac{dx}{dt} \xrightarrow{FS} jKw_0 a_K = jK\left(\frac{\pi}{T}\right) a_K : \text{وقرگزىش (ستق)} \text{ Differentiation}$$

$$\frac{d^k x}{dt^k} \xrightarrow{FS} jK\left(\frac{\pi}{T}\right) \times jK\left(\frac{\pi}{T}\right)^{k-1} a_K = -K^k \left(\frac{\pi}{T}\right)^k a_K : \text{منابى سرى فورىه}$$

$$T_0 = T : \text{دوره تناوب}$$

d) $x(t+1)$

$$x(t+1) \xrightarrow{FS} a_K \left(e^{-jK\left(\frac{\pi}{T}\right)t_0} \right) = a_K \left(e^{jK\left(\frac{\pi}{T}\right)} \right) : \text{(استال زىزمان)} \text{ time-shifting}$$

$$x(t+1) \xrightarrow{FS} a_K \left(e^{+jK\left(\frac{\pi}{T}\right)} \right) : \text{(عىقايس زىزمان)} \text{ time-scaling}$$

Date:

Subject:

$$x(t+1) \xleftarrow{FS} a_k (e^{jK\frac{(k+1)\pi}{T}})$$

متغير سرى خورى: دورة تناوب: ζ

$$T_0 = \frac{T}{v}$$

$$x(t) \xrightarrow{FS} a_k \quad T = v \Rightarrow \omega_0 = \frac{\pi v}{T}$$

$$\frac{dx(t)}{dt} \xleftarrow{FS} b_k = jK\omega_0 a_k$$

$$b_k = \frac{1}{v} \int_{-r}^1 \frac{dx(t)}{dt} e^{-jK\omega_0 t} dt$$

$$= \frac{1}{v} \left(\int_{-r}^0 1 \times e^{-jK\omega_0 t} dt + \int_0^1 -r \times e^{-jK\omega_0 t} dt \right)$$

$$= \frac{1}{v} \left(\frac{1}{-jK\omega_0} e^{-jK\omega_0 t} \Big|_{-r}^0 + \frac{r}{jK\omega_0} e^{-jK\omega_0 t} \Big|_0^1 \right)$$

$$= \frac{1}{v} \left(\frac{1}{-jK\omega_0} (1 - e^{rjK\omega_0}) + \frac{r}{jK\omega_0} (e^{-jK\omega_0} - 1) \right)$$

$$= \frac{1}{v} \left(\frac{-r}{jK\omega_0} + \frac{rjK\omega_0}{jK\omega_0} + \frac{re^{-jK\omega_0}}{jK\omega_0} \right)$$

$$a_k = \frac{b_k}{jK\omega_0} \Rightarrow a_k = \frac{1}{v} \left(\frac{-r}{-K^v \omega_0^v} + \frac{rjK\omega_0}{-K^v \omega_0^v} + \frac{re^{-jK\omega_0}}{-K^v \omega_0^v} \right)$$

$$= \frac{1}{rK^v \omega_0^v} (r - e^{rjK\omega_0} - re^{-jK\omega_0})$$

$$= \frac{1}{rK^v \omega_0^v} (r - e^{-rjK(\frac{K\pi}{v})} - e^{-jK(\frac{r\pi}{v})})$$

$$= \frac{r}{rK^v \omega_0^v} (r - e^{-\frac{r}{v}jK\pi} - r e^{\frac{r}{v}jK\pi}) ; (K \neq 0)$$

$$K=0 \Rightarrow a_0 = \frac{1}{v} \int x(t) dt = \frac{1}{v} \left(\frac{r \times r}{v} \right) = 1$$

Kian King

Date: Subject:

$$x(t) = r e^{j\omega t} + \cos(\omega t) + e^{j\omega t}$$

$$= r e^{j\omega t} + \frac{1}{2}(e^{j\omega t} + e^{-j\omega t}) + e^{j\omega t}$$

لـ ω_0 : $\frac{\pi}{T}$, $\frac{\pi}{2T}$, $\frac{\pi}{4T}$ $\Rightarrow T_0 = 2\pi/\omega_0$

$$\omega_0 = \frac{2\pi}{T_0} = 1$$

$$\frac{\omega}{\omega_0} = r \Rightarrow a_r = r$$

$$\frac{\omega}{\omega_0} = 1 \Rightarrow a_1 = 1$$

$$\frac{\omega}{\omega_0} = -1 \Rightarrow a_{-1} = 1$$

$$\frac{\omega}{\omega_0} = \infty \Rightarrow a_\infty = 1$$

$$(K > f, K < \omega_0, K \neq -1) \Rightarrow a_K = 0$$

$$P = \frac{1}{T} \int_{-\infty}^{\infty} |x(t)|^2 dt = \sum_{K=-\infty}^{\infty} |a_K|^2$$

(Parseval) ابتداء برسالة

$$P = |a_x|^2 + |a_H|^2 + |a_R|^2 + |a_d|^2 = (\frac{r}{2})^2 + (\frac{1}{2})^2 + 1^2 + 1^2 = \frac{1}{4} + \frac{1}{4} + 1 + 1 = 10 + \frac{1}{4} = 10.25$$

$$b_K = (-1)^K a_K + (-1)^{-K} a_{-K} = e^{j\pi K} a_K + e^{-j\pi K} a_{-K}$$

$$T_0 = \frac{2\pi}{\omega_0} = \frac{2\pi}{f} \Rightarrow b_K = e^{j\frac{2\pi}{f} K} (a_K + a_{-K}) = e^{-j\frac{2\pi}{f} K} (a_K + a_{-K})$$

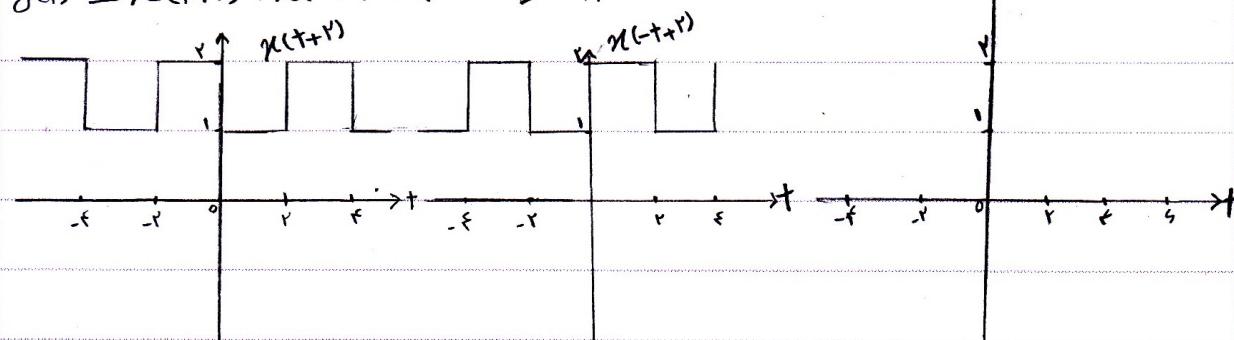
$$b_K = e^{-j\frac{2\pi}{f} K} a_K + e^{-j\frac{2\pi}{f} K} a_{-K} = b_{1K} + b_{-1K}$$

$$b_{1K} = e^{-j\frac{2\pi}{f} K} a_K \xrightarrow{FS} x(t+r)$$

$$b_{-1K} = e^{-j\frac{2\pi}{f} K} a_{-K} \xleftarrow{FS} x(-t+r)$$

$$x(t) \xleftarrow{FS} a_K$$

$$y(t) = x(t+r) + x(-t+r) \xrightarrow{FS} b_K$$



Date:

Subject:

$$T_r = \gamma \Rightarrow W_r = \frac{\gamma \pi}{\nu}$$

$$a_0, a_{|K|>r} = 0 \quad a_1, a_{-1}, a_r, a_{-r} = ?$$

$$x(t) \xrightarrow{FS} a_K$$

$$x(t-\tau) \xrightarrow{FS} -e^{-j\omega_0 K t_0} a_K = -e^{-j(\frac{\pi}{\nu}) K (\frac{r}{\nu})} a_K = -e^{-\frac{\pi r j K}{\nu}} a_K = -(-1)^K a_K \stackrel{?}{=} a_K$$

$$K=1 \Rightarrow a_1 = a_1, K=-1 \Rightarrow a_{-1} = a_{-1}, K=r \Rightarrow -a_r = a_r \Rightarrow a_r = 0$$

$$K=1 \Rightarrow -a_{-r} = a_{-r} \Rightarrow a_{-r} = 0$$

$$\Rightarrow x(t) = a_1 e^{j(\frac{\pi}{\nu})t} + a_{-1} e^{j(-\frac{\pi}{\nu})t} = a_1 e^{\frac{\pi r j t}{\nu}} + a_r e^{-\frac{\pi r j t}{\nu}}$$

$$a_K = a_{-K}^*$$

$$K=-1 \Rightarrow a_{-1} = a_1^* \xrightarrow{\text{تحقق } a_1} a_1 \Rightarrow a_{-1} = a_1$$

$$\Rightarrow x(t) = a_1 (e^{\frac{\pi r j t}{\nu}} + e^{-\frac{\pi r j t}{\nu}})$$

$$\int_{-\nu}^{\nu} |x(t)| dt = 1 \nu \pi \quad \text{فرزن:}$$

$$|x(t)| = |a_1 (e^{\frac{\pi r j t}{\nu}} + e^{-\frac{\pi r j t}{\nu}})| = |a_1 (\cos(\frac{\pi r t}{\nu}) + j \sin(\frac{\pi r t}{\nu}) + \cos(\frac{\pi r t}{\nu}) - j \sin(\frac{\pi r t}{\nu}))| \\ = |a_1 (2 \cos(\frac{\pi r t}{\nu}))| \xrightarrow{\text{تحقق } a_1} |a_1| |\cos(\frac{\pi r t}{\nu})|$$

$$\Rightarrow \int_{-\nu}^{\nu} |x(t)| dt = \int_{-\nu}^{\nu} |a_1| |\cos(\frac{\pi r t}{\nu})| dt = |a_1| \int_{-\nu}^{\nu} |\cos(\frac{\pi r t}{\nu})| dt$$

$$= |a_1| \left(\int_{-\nu}^{\frac{\nu}{r}} -\cos(\frac{\pi r t}{\nu}) dt + \int_{\frac{\nu}{r}}^{\nu} \cos(\frac{\pi r t}{\nu}) dt + \int_{\nu}^{\frac{\nu}{r}} -\cos(\frac{\pi r t}{\nu}) dt \right)$$

$$= |a_1| \left(-\frac{\nu}{\pi r} \sin(\frac{\pi r t}{\nu}) \Big|_{-\nu}^{\frac{\nu}{r}} + \frac{\nu}{\pi r} \sin(\frac{\pi r t}{\nu}) \Big|_{\frac{\nu}{r}}^{\nu} + \frac{\nu}{\pi r} \sin(\frac{\pi r t}{\nu}) \Big|_{\nu}^{\frac{\nu}{r}} \right)$$

$$= |a_1| \left(-\frac{\nu}{\pi r} (-1 - 0) + \frac{\nu}{\pi r} (1 - (-1)) - \frac{\nu}{\pi r} (0 - 1) \right)$$

$$= |a_1| \left(\frac{\nu}{\pi r} + \frac{\nu}{\pi r} + \frac{\nu}{\pi r} \right) = |a_1| \left(\frac{3\nu}{\pi r} \right) = \frac{15 \nu a_1}{\pi r} \stackrel{1 \nu \pi}{=} 1 \nu \pi \Rightarrow a_1 = \frac{\pi r}{\nu}$$

$$\Rightarrow a_1 = a_{-1} = \frac{\pi r}{\nu}$$

$$\Rightarrow x(t) = \frac{\pi r}{\nu} (e^{\frac{\pi r j t}{\nu}} + e^{-\frac{\pi r j t}{\nu}}) = \frac{\pi r}{\nu} (2 \cos(\frac{\pi r t}{\nu})) = \pi r \cos(\frac{\pi r t}{\nu})$$

Kilian King

$$a_k = \frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} \delta(t) e^{-jk(\frac{2\pi t}{T})} dt = e^0 = 1 \quad : (1)$$

$$H(jkw_0) = \int_{-\infty}^{\infty} h(z) e^{-jkw_0 z} dz = \int_{-\infty}^{\infty} e^{-ftz} e^{-jkw_0 z} dz$$

$$= \int_{-\infty}^{0} e^{z(f-jkw_0)} dz + \int_{0}^{\infty} e^{-z(f+jkw_0)} dz$$

$$= \frac{1}{f-jkw_0} e^{z(f-jkw_0)/0} \Big|_{-\infty} + \frac{1}{f+jkw_0} e^{-z(f+jkw_0)/\infty} \Big|_0 = \frac{1}{f-jkw_0} - \frac{1}{f+jkw_0}$$

$$w_0 = \frac{\pi f}{K} \quad = \frac{+f + jkw_0 - f + jkw_0}{19 + K^2(\pi f)^2} = \frac{jK(\pi f)}{19 + f^2 K^2 \pi^2} = \frac{jK\pi}{f + K^2 \pi^2}$$

$$x(t) \xrightarrow{FS} a_k = 1$$

$$y(t) = x(t) \times H(jkw_0) \xrightarrow{FS} a_k \times H(jkw_0) = 1 \times \frac{jK\pi}{f + K^2 \pi^2} = \frac{jK\pi}{f + K^2 \pi^2}$$

Kian King

مزيج