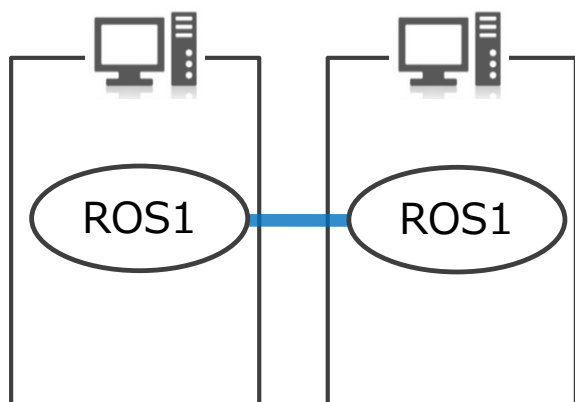
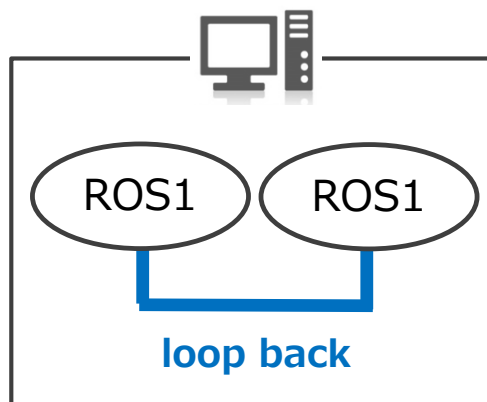


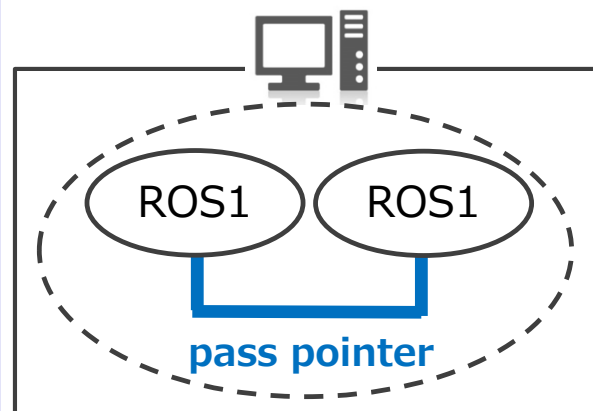
(1-a): ROS1 remote



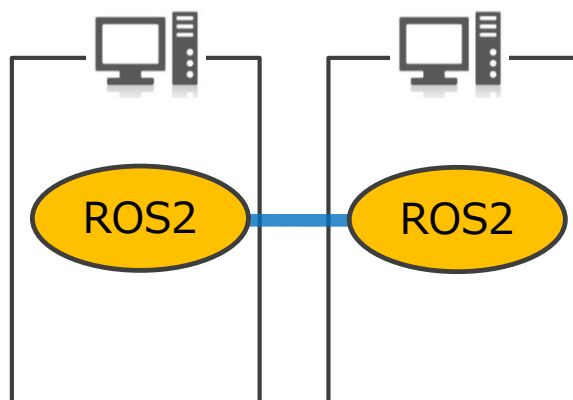
(1-b): ROS1 local



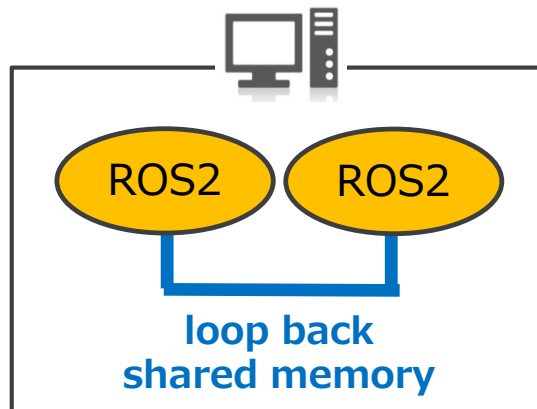
(1-c): ROS1 nodelet



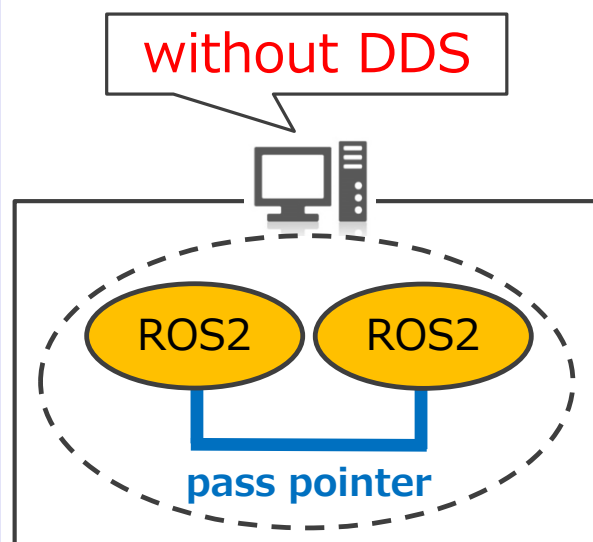
(2-a): ROS2 remote



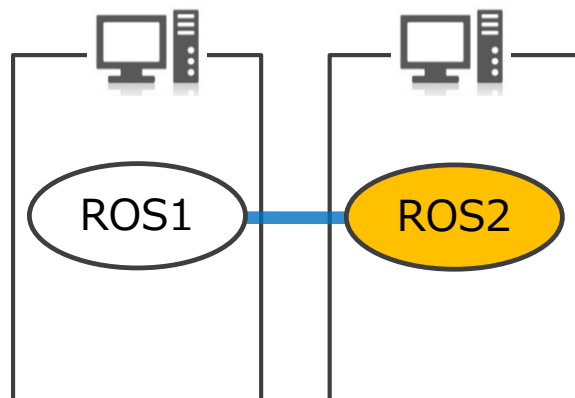
(2-b): ROS2 local



(2-c): ROS2 intra-process



(3-a): ROS bridge remote



(3-b): ROS bridge local

