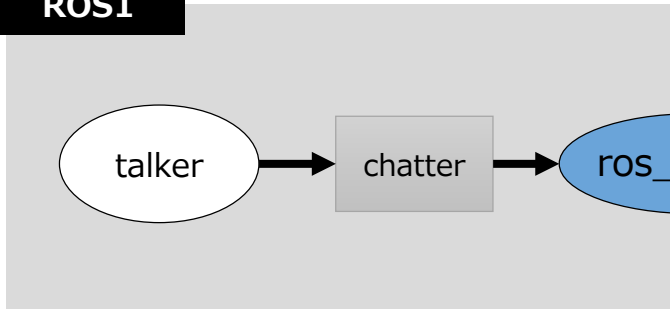


ROS1



ROS2

