

Frequency-Dynamic Attention Modulation for Dense Prediction

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Abstract

Vision Transformers (ViTs) have significantly advanced computer vision, demonstrating strong performance across various tasks. However, the attention mechanism in ViTs makes each layer function as a low-pass filter, and the stacked-layer architecture in existing transformers suffers from frequency vanishing. This leads to the loss of critical details and textures. We propose a novel, circuit-theory-inspired strategy called Frequency-Dynamic Attention Modulation (FDAM), which can be easily plugged into ViTs. FDAM directly modulates the overall frequency response of ViTs and consists of two techniques: Attention Inversion (AttInv) and Frequency Dynamic Scaling (FreqScale). Since circuit theory uses low-pass filters as fundamental elements, we introduce AttInv, a method that generates complementary high-pass filtering by inverting the low-pass filter in the attention matrix, and dynamically combining the two. We further design FreqScale to weight different frequency components for fine-grained adjustments to the target response function. Through feature similarity analysis and effective rank evaluation, we demonstrate that our approach avoids representation collapse, leading to consistent performance improvements across various models, including SegFormer, DeiT, and MaskDINO. These improvements are evident in tasks such as semantic segmentation, object detection, and instance segmentation. Additionally, we apply our method to remote sensing detection, achieving state-of-the-art results in single-scale settings. The code is available at <https://github.com/Linwei-Chen/FDAM>.

1. Introduction

In recent years, Vision Transformers (ViTs) have revolutionized computer vision, achieving state-of-the-art performance across various dense prediction tasks [22, 48, 56, 94].

However, when applying ViTs [22] to vision tasks, a critical issue emerges. The attention mechanism in ViTs exhibits a strong low-pass filtering characteristic [63, 85]. As shown in Figure 1(a), frequency analysis reveals that

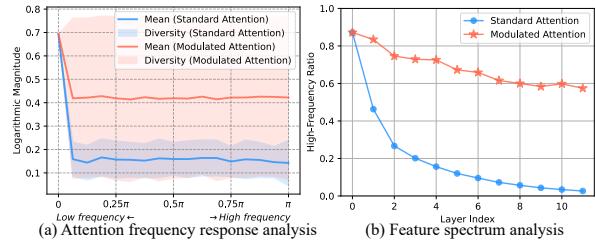


Figure 1. Frequency analysis. We stack a model with pure 12 attention layer. (a) Attention frequency response analysis reveals that our modulated attention maintains a higher mean magnitude across all frequency bands compared to standard attention, while also exhibiting greater diversity in high-frequency regions. (b) Feature spectrum analysis shows that our modulated attention maintains a stable high-frequency ratio and consistently preserves high-frequency information across layers, unlike standard attention, which rapidly loses it and results in representation collapse.

this low-pass filtering limits spectral diversity, severely restricting the frequency representation power. This limitation is exacerbated by the stacked-layer architecture. As illustrated in Figure 1(b), feature spectrum analysis shows that standard attention rapidly loses high-frequency information across layers, with the high-frequency ratio dropping sharply from the initial layers to the deeper layers (nearly 0). This leads to frequency vanishing and blurred feature representations, negatively impacting performance on tasks requiring fine-grained visual understanding.

To address this issue, we propose Frequency-Dynamic Attention Modulation (FDAM), a novel, circuit-theory-inspired strategy to modulate the overall frequency response of ViTs. FDAM consists of two techniques: Attention Inversion (AttInv) and Frequency Dynamic Scaling (FreqScale). Drawing on circuit theory [2, 75, 87], which treats low-pass filters as fundamental building blocks, we introduce our first technique, AttInv. In AttInv, we view attention matrix as a set of low-pass filters and invert them (analogous to s-domain inversion in circuit design) to derive complementary high-pass filters. At each layer, both low-pass and high-pass filters are dynamically weighted. By cascading these layers over L levels, the architecture forms 2^L unique combinations of filter weights, enabling it to learn complex frequency responses, as shown in Figure 2.

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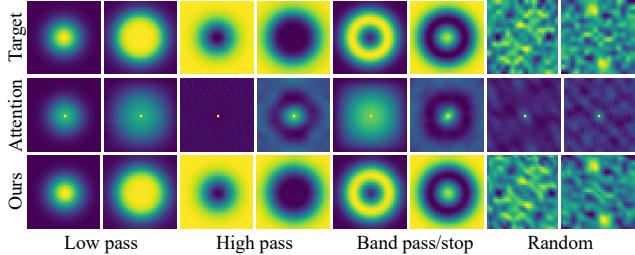


Figure 2. Analysis of frequency response fitting. From the center to the border are low- to high-frequency components. It is evident that the attention mechanism has strong low-pass characteristics, which makes it difficult to effectively fit high-pass, band pass/stop, and random filters. In contrast, our method, AttInv, demonstrates a superior capability in fitting these diverse frequency responses, indicating greater flexibility and effectiveness in handling a wide range of frequency characteristics.

The second technique, termed FreqScale, operates in a frequency-dynamic manner. It addresses the limitation of AttInv by providing fine-grained adjustments to the target response function. While AttInv effectively combines low-pass and high-pass filters, it lacks precise control over individual frequency components. FreqScale re-weights feature maps across separate frequency bands and dynamically amplifies high-frequency signals. This enables a more nuanced and adaptive adjustment of feature representations, enhancing the model’s ability to distinguish between different categories for dense prediction tasks such as segmentation.

These techniques are computationally efficient and can be *easily plugged into* existing ViT architectures. By incorporating these methods, we address the low-pass limitations in ViTs across various vision tasks, enabling full-spectrum feature representation. This results in significant performance improvements in dense prediction tasks, such as semantic segmentation (SegFormer +2.4 mIoU on ADE20K), object detection (Mask DINO +1.6 AP on COCO), and instance segmentation (Mask DINO +1.4 AP on COCO). Additionally, our method achieves 78.61 when applied to remote sensing object detection, surpassing previous state-of-the-art methods under single-scale training and testing settings. Furthermore, feature similarity analysis [63] and effective rank evaluation [38] confirm that our approach effectively prevents representation collapse.

Our contributions can be summarized as follows:

- We diagnose the low-pass filtering characteristic of ViTs’ attention mechanism through mathematical and spectral analysis. It reveals how this characteristic restricts frequency representation and leads to feature degradation, providing a clear understanding of the challenges faced by ViTs in fine-grained visual tasks.
- We introduce Frequency-Dynamic Attention Modulation (FDAM), comprising two techniques: AttInv and FreqScale. AttInv leverages the low-pass filtering characteristic to create a complementary high-pass fil-

ter, enabling full-spectrum feature representation. FreqScale provides fine-grained frequency adjustments by re-weighting and amplifying frequency signals. Together, these techniques effectively address the limitations of traditional attention mechanisms.

- Our methods are computationally efficient and can be easily integrated into existing ViT architectures. They achieve significant performance gains across diverse vision tasks. Extensive analysis, including effective rank evaluation [38], demonstrates that our approach avoids representation collapse.

2. Related Work

Vision Transformer. Following the success of attention-based architectures in neural machine translation [82], computer vision researchers explored Vision Transformers (ViT) [22]. These models tokenize image patches and process them using sequential attention mechanisms, achieving strong performance on classification benchmarks.

In recent years, various ViT variants have been proposed [25, 32, 43, 56, 72, 77, 79, 80, 97, 111, 112]. Hybrid architectures, such as [36, 88], combine convolutional inductive biases with attention mechanisms. Hierarchical designs like [86] use progressive resolution reduction for efficient multi-scale processing. To address quadratic complexity, windowed attention mechanisms [32, 56] and multi-granularity interactions [97] have been introduced. MetaFormer [103] demonstrated that the success of transformer stems from the residual MetaFormer framework rather than specific attention operators. TransNeXt [72] explores alternative spatial interaction paradigms inspired by biomimetic vision.

Beyond image classification, ViT variants have inspired the application of Transformers to other vision tasks, such as object detection [48, 116], semantic segmentation [74, 94, 108], and instance segmentation [16, 42].

Frequency-Domain Learning. Frequency-domain analysis has served as a foundational pillar in signal processing for decades [26, 67]. Recent advances have extended these principles to deep learning, where they enhance model optimization strategies [102] and improve the generalization capacity of deep neural networks (DNNs) [12, 83].

The integration of frequency-domain techniques into DNN architectures has demonstrated several advantages, such as capturing global contextual patterns through spectral operations [18, 28, 37, 50, 69], strengthening domain-generalizable representations through frequency-aware learning [10, 44, 51]. Researcher also utilize frequency-domain techniques in neural operations. For instance, FcaNet [68] enhances feature recalibration through frequency component analysis, while FreqFusion [8] optimizes multi-scale feature fusion using spectral properties. Subsequent work has further resolved aliasing arti-

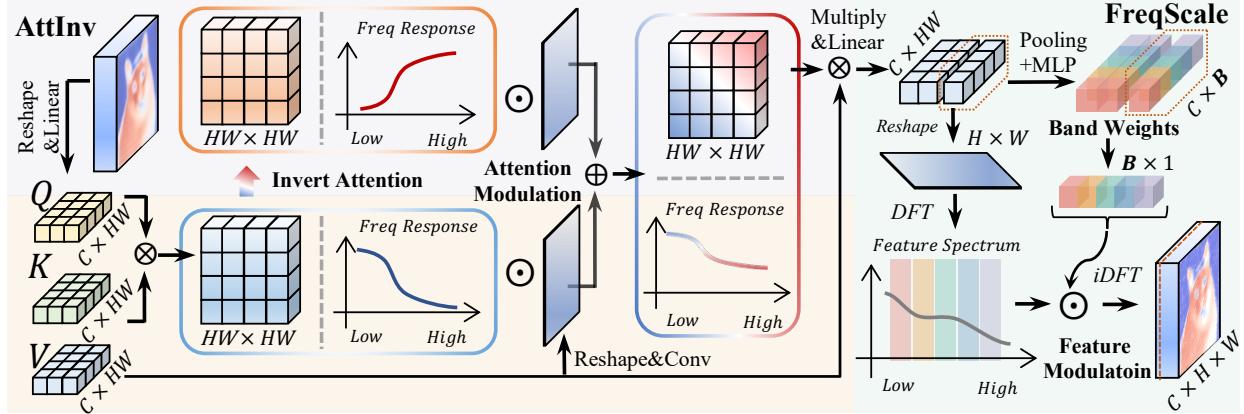


Figure 3. Illustration of Frequency Dynamic Attention Modulation (FDAM), comprising AttInv for attention modulation and FreqScale for feature modulation. The original attention mechanism is predominantly influenced by low-frequency components due to its inherent low-pass filtering characteristics. **i) AttInv** inverts the low-pass filter, represented by the attention weights, to derive a high-pass filter. By dynamically combining these filters using a predicted weight, we achieve a balanced representation that retains both low- and high-frequency information. **ii) FreqScale** adaptively reweights different frequency bands, enhancing suppressed high-frequency components (e.g., edges, textures) while preserving structural low-frequency information. This integrated approach alleviates attention collapse and patch uniformity issues in Vision Transformers, facilitating full-spectrum feature representation for improved discriminability.

facts in downsampling operations through high-frequency suppression [9, 11, 27], and FADC [13] adapts convolutional dilation rates based on feature frequency profiles. [1, 64–66, 76, 106] also explore improving ViTs from frequency perspective.

Anti-Oversmoothing for ViT. Recent works [21, 63, 64, 85] have conducted Fourier domain analyses of the oversmoothing phenomenon in ViTs, demonstrating that the self-attention mechanism acts as a low-pass filter. This causes feature maps to lose high-frequency information and converge to a Direct-Current (DC) component, leading to patch uniformity and rank collapse in deep ViTs [21].

Existing solutions, such as AttnScale and FeatScale [85], mitigate this effect by adaptively scaling high-frequency components, while NeuTRENO [63] incorporates a regularizer to preserve token fidelity. However, these methods primarily focus on static enhancement of high-frequency signals and neglect the broader spectral context. They fail to dynamically adapt to the varying frequency requirements of different layers and tasks, resulting in incomplete feature representations. Our method addresses these limitations by combining adaptive inverted high-pass filters with fine-grained frequency control. This enables the model to dynamically adjust its attention to capture a richer spectrum of features across layers, thereby capturing subtle visual differences that benefit complex vision tasks.

3. Frequency-Dynamic Attention Modulation

In this section, we introduce our Frequency-Dynamic Attention Modulation (FDAM) mechanism, an approach designed to address the limitations of the low-pass filtering characteristic in Vision Transformers (ViTs). As shown

in Figure 3, our method consists of two key techniques, AttInv and FreqScale, which work together to enhance the frequency representation capabilities of ViTs.

3.1. Attention Inversion

Motivation. The self-attention mechanism is pivotal in ViTs [22], enabling the model to capture long-range dependencies and weigh the importance of different input elements. This mechanism is mathematically represented as:

$$\text{Attention}(\mathbf{Q}, \mathbf{K}, \mathbf{V}) = \text{softmax}\left(\frac{\mathbf{Q}\mathbf{K}^T}{\sqrt{C}}\right)\mathbf{V}, \quad (1)$$

where \mathbf{Q} , \mathbf{K} , and \mathbf{V} represent the query, key, and value matrices, respectively, each with a shape of (C, HW) . These matrices are derived from the input feature \mathbf{X} through a linear transformation. Here, c denotes the channel dimension of the vectors, and H and W represent the height and width.

The attention matrix $\mathbf{A} = \text{softmax}\left(\frac{\mathbf{Q}\mathbf{K}^T}{\sqrt{C}}\right)$ can be interpreted as a set of $H \times W$ linear filters [85], where each spatial location (p, q) has a corresponding filter $\mathbf{A}_{p,q} \in \mathbb{R}^{H \times W}$. It can be understood and mathematically proven to act as a low-pass filter due to its smoothing effect on feature maps [63, 85], which can be formulated as follows (see *supplementary material* for proof):

$$\begin{aligned} |\mathcal{F}(\mathbf{A}_{p,q})(u, v)| &= 1, \text{if } (u, v) = (0, 0), \\ |\mathcal{F}(\mathbf{A}_{p,q})(u, v)| &< 1, \text{if } (u, v) \neq (0, 0). \end{aligned} \quad (2)$$

where $\mathcal{F}(\cdot)$ denotes discrete Fourier transform (DFT), and (u, v) represents the frequency components. $|\mathcal{F}(\mathbf{A}_{p,q})(0, 0)| = 1$ ensures that the lowest direct current frequency is preserved, while $|\mathcal{F}(\mathbf{A}_{p,q})(u, v)| < 1$ for $(u, v) \neq (0, 0)$ indicates that higher frequency components are attenuated, thus confirming the low-pass filtering

effect. This limits its spectrum diversity and severely restricts its frequency representation power.

Now, consider a simple model with L layers of pure self-attention. Let $\mathcal{F}(\mathbf{X}^{(i)})$ denote the Fourier transformed spectrum of the feature map at layer i , and let $\mathcal{F}(\mathbf{A}^{(i)})$ denote the frequency response of the attention matrix at the same layer. The transformation across layers follows the recursive relation:

$$\mathcal{F}(\mathbf{X}^{(L)})(u, v) = \prod_{i=1}^L \mathcal{F}(\mathbf{A}^{(i)})(u, v) \cdot \mathcal{F}(\mathbf{X}^{(0)})(u, v). \quad (3)$$

Since $|\mathcal{F}(\mathbf{A}^{(i)})(u, v)| < 1$ for all nonzero frequencies $(u, v) \neq (0, 0)$, we observe that:

$$\lim_{L \rightarrow \infty} \prod_{i=1}^L |\mathcal{F}(\mathbf{A}^{(i)})(u, v)| = 0, \quad \forall (u, v) \neq (0, 0). \quad (4)$$

This means that, all high-frequency components are exponentially suppressed with layers, leaving only the lowest frequency component $(0, 0)$ dominant. Consequently, the model suffers from frequency vanishing, where fine-grained details and textures are lost, impairing the model to capture crucial information for dense prediction vision tasks.

To address the frequency representation limitations of the attention mechanism, we propose Attention Inversion (AttInv). The core idea is inspired by circuit theory [75, 87], which uses low-pass filters as fundamental elements to construct various filters, such as high-pass and band-pass filters. AttInv leverages the inherent low-pass filtering characteristic of the attention mechanism and inverts it to obtain a complementary high-pass filter. We then dynamically recombine these two types of filters in a spatially adaptive manner. This process enables us to capture high-frequency information that is typically lost in standard attention.

Overview of AttInv. AttInv involves two main steps: 1) *Attention Inversion*: Inverting filters in attention matrix $\mathbf{A}_{p,q}$ in the frequency domain to derive a complementary high-pass filter $\hat{\mathbf{A}}_{p,q}$. 2) *Dynamic Combination*: Predicting a spatial dynamic coefficient $\bar{\mathbf{S}}, \hat{\mathbf{S}} \in \mathbb{R}^{H \times W}$ for each attention head to combine complementary filters $\mathbf{A}_{p,q}, \hat{\mathbf{A}}_{p,q}$.

Attention Inversion. To obtain a complementary high-pass filter by inverting the low-pass filter, AttInv first computes the frequency response of \mathbf{A} and subtracts it from an all-pass filter \mathbf{I}_f . The resulting high-pass filter $\hat{\mathbf{A}}$ is then transformed back into the spatial domain:

$$\hat{\mathbf{A}}_{p,q} = \mathcal{F}^{-1}(\mathbf{I}_f - \mathcal{F}(\mathbf{A}_{p,q})), \quad (5)$$

where \mathcal{F} and \mathcal{F}^{-1} denote the Fourier Transform and its inverse, respectively. This ensures that $\hat{\mathbf{A}}_{p,q}$ captures high-frequency components complementary to $\mathbf{A}_{p,q}$.

Dynamic Combination. Since different locations on the feature map exhibit varying local frequencies, it is essential to adaptively extract different frequency components across regions. For instance, edges require high-frequency information for accurate boundary preservation, whereas smooth

regions do not. To achieve this, we employ a spatially dynamic approach to combine the low-pass filter \mathbf{A} and the high-pass filter $\hat{\mathbf{A}}$:

$$\tilde{\mathbf{A}}_{p,q} = \bar{\mathbf{S}}(p, q) \cdot \mathbf{A}_{p,q} + \hat{\mathbf{S}}(p, q) \cdot \hat{\mathbf{A}}_{p,q}, \quad (6)$$

where $\bar{\mathbf{S}}, \hat{\mathbf{S}}$ represent the combination weights obtained via a convolutional layer. This spatially adaptive combination dynamically balances low- and high-pass filtering, ensuring that each region retains the most relevant frequency components. When cascading L such layers, the frequency response across L layers can be expressed as:

$$\mathcal{F}(\mathbf{X}^{(L)}) = \prod_{i=1}^L [\bar{\mathbf{S}}^{(i)} \mathcal{F}(\mathbf{A}^{(i)}) + \hat{\mathbf{S}}^{(i)} \mathcal{F}(\hat{\mathbf{A}}^{(i)})] \cdot \mathcal{F}(\mathbf{X}^{(0)}). \quad (7)$$

This recursive composition of these hybrid filters expands into 2^L distinct weighted combinations of low- and high-pass operations, enabling flexible amplification or suppression of specific frequency bands. In contrast, stacking L standard attention layers monotonically attenuates high frequencies, leading to exponential vanishing as Equation (4) described. AttInv's quadratic complexity in frequency operations preserves both global structures (via low-pass) and fine details (via high-pass), overcoming the spectral limitations of conventional attention, as shown in Figure 1.

3.2. Frequency Dynamic Scaling

Motivation. AttInv effectively combines low-pass and high-pass filters but lacks precise control over individual frequency components. To address this, we propose Frequency Dynamic Scaling (FreqScale), which provides fine-grained adjustments to the target response function by reweighting feature maps across separate frequency bands and dynamically amplifying high-frequency signals.

Overview of FreqScale. FreqScale involves two main steps: 1) *Frequency Scaling Weight Generation*: Compute dynamic frequency band weights using a multi-layer perceptron (MLP) and combine them with learnable scaling weights to obtain final frequency scaling coefficients. 2) *Feature Frequency Modulation*: Transform features into the frequency domain, divide the spectrum into multiple bands, and modulate each band with frequency scaling weight.

Frequency Scaling Weight Generation. A straightforward approach to adjust frequency components within the feature map is to use static learnable parameters for each band. However, this static approach is suboptimal given the dynamic nature of attention mechanisms.

To address this, we propose a simple yet efficient method to generate dynamic frequency scaling weights based on the input. Specifically, as illustrated in Figure 4, we employ n learnable static scaling weights and use a multi-layer perceptron (MLP) with a tanh activation function to compute dynamic coefficients. These coefficients reassemble the static weights into dynamic frequency scaling weights of shape $C \times \mathbf{B}$, $\mathbf{B} \in \mathbb{R}^{b \times b}$ is number of frequency band.

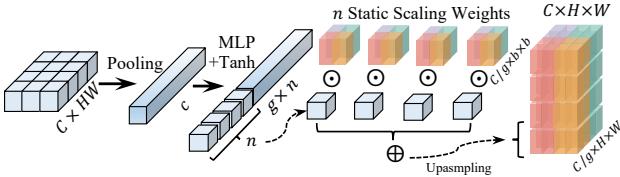


Figure 4. Illustration of frequency scaling weight generation. The input feature map of dimensions $C \times H \times W$ is first and then fed into an MLP with a Tanh activation function to generate dynamic coefficients of dimensions $g \times n$. These dynamic coefficients are multiplied with n learnable static scaling weights, which are upsampled to match the size of the feature map in the Fourier domain ($C \times H \times W$). This mechanism enables precise adjustment of various frequency components within the feature map dynamically.

Table 1. Quantitative comparisons using Vision Transformer [22] with *anti-oversmoothing* methods on the ADE20K *val* set [113].

Method <i>Segmentor</i> _[NeurIPS2021] [74]	Params	FLOPS	mIoU	
			SS	MS
DeiT-T _[ICML2021] [80]	6.7M	118G	35.7	36.7
+ AttScale _[ICLR2022] [85]	6.7M	118G	36.8 _{+1.1}	37.8 _{+1.1}
+ FeatScale _[ICLR2022] [85]	6.7M	118G	37.0 _{+1.3}	37.9 _{+1.2}
+ NeuTRENO _[NeurIPS2023] [63]	6.7M	118G	37.2 _{+1.5}	38.1 _{+1.4}
+ FDAM (Ours)	6.9M	120G	38.3 _{+2.6}	39.5 _{+2.8}

To reduce parameter cost and be parameter-efficient, we adopt a group-wise reassembly strategy. Each static scaling weight has a shape of $\frac{C}{g} \times b \times b$, and the dynamic coefficients have a shape of $g \times n$. The dynamic frequency scaling weights are generated via matrix multiplication:

$$\tilde{\mathbf{W}} = \mathbf{D} \cdot \text{stack}\{\mathbf{W}_1, \dots, \mathbf{W}_n\}, \quad (8)$$

where $\tilde{\mathbf{W}} \in \mathbb{R}^{C \times b \times b}$ represents the dynamic frequency scaling weights, $\mathbf{W}_i \in \mathbb{R}^{\frac{C}{g} \times b \times b}$ is the i -th static weight, and $\mathbf{D} \in \mathbb{R}^{g \times n}$ is the dynamic coefficient output by MLP.

Feature Frequency Modulation. With the frequency scaling weights obtained, we can modulate the feature as follows:

$$\mathbf{X} = \mathcal{F}^{-1}(\mathcal{F}(\mathbf{X}) \odot \text{upsample}(\tilde{\mathbf{W}})), \quad (9)$$

where $\mathbf{X} \in \mathbb{R}^{C \times H \times W}$ denotes the feature map. Note that we upsample the frequency scaling weights $\tilde{\mathbf{W}}$ to match the dimensions of \mathbf{X} , allowing us to effectively modulate the $B \in \mathbb{R}^{b \times b}$ frequency bands within \mathbf{X} . This approach facilitates precise manipulation of frequency information within the feature map, thereby enhancing the model’s capacity to capture intricate details and textures.

4. Experiments

Datasets and Metrics. We evaluate our methods on challenging datasets, including ADE20K [113], COCO [52], and DOTA [90]. For segmentation tasks, we use mean Intersection over Union (mIoU) as the evaluation metric [7, 11, 24, 54, 58]. For object detection and instance segmentation, we use Average Precision (AP) [33, 70]. For panoptic segmentation, we use Panoptic Quality (PQ) [40].

Table 2. *Semantic segmentation* comparison with SegFormer [94] and UPerNet [93] on the ADE20K *val* set. SS and MS indicate single- and multi-scale test time settings.

Method ($\frac{\text{SegFormer}}{\text{UPerNet}}$)	Params	FLOPS	mIoU	
			SS	MS
SegFormer-B0 _[NeurIPS2021] [94]	3.8M	8.6G	37.4	38.0
SegFormer-B0 + FDAM (Ours)	3.9M	8.9G	39.8 _{+2.4}	40.2 _{+2.2}
ResNet-50 _[CVPR2016] [34]	66M	947G	40.7	41.8
ResNet-101 _[CVPR2016] [34]	85M	1029G	42.9	44.0
DeiT-S _[ICML2021] [80]	52.1M	360G	42.9	43.8
DeiT-S + FDAM (Ours)	52.6M	363G	44.3 _{+1.4}	45.0 _{+1.2}
DeiT-B _[ICML2021] [80]	122M	787G	45.4	47.2
ViT-B-MLN _[ECCV2020] [22, 73]	144M	2007G	46.8	48.5
Swin-B _[ECCV2021] [56]	121M	1188G	48.1	49.7
NAT-B _[CVPR2023] [32]	123M	1137G	48.5	49.7
ConvNeXt-B _[CVPR2022] [57]	122M	1170G	49.1	49.9
ConvNeXt-B-dcls _[ICLR2023] [39]	122M	1170G	49.3	-
Swin-B-HAT _[ECCV2022] [1]	121M	1188G	48.9	50.3
DiNAT-B _[arXiv2022] [31]	123M	1137G	49.6	50.4
Focal-B _[NeurIPS2022] [97]	126M	1354G	49.0	50.5
DAT-B _[CVPR2022] [91]	121M	1212G	49.4	50.6
InceptionNeXt-B _[CVPR2024] [105]	115M	1159G	-	50.6
PeLK-B _[CVPR2024] [5]	126M	1237G	50.4	-
MogaNet-L _[ICLR2024] [45]	113M	1176G	50.9	-
ConvFormer-M36 _[TPAMI2024] [103]	85M	1113G	51.3	-
OverLoC-B _[CVPR2025] [60]	124M	1202G	51.7	52.3
DeiT3-B _[ECCV2022] [81]	144M	1283G	51.8	52.8
DeiT-B + FDAM (Ours)	124M	795G	46.5 _{+1.1}	48.2 _{+1.0}
ViT-B-MLN + FDAM (Ours)	146M	2015G	48.0 _{+1.2}	49.5 _{+1.0}
DeiT3-B + FDAM (Ours)	123M	1290G	52.6 _{+0.8}	53.4 _{+0.6}
MambaOut-B _[arXiv2024] [104]	112M	1178G	49.6	51.0
VMamba-B _[arXiv2024] [114]	122M	1170G	51.0	51.6
S.Mamba-B _[ICLR2025] [92]	127M	1176G	51.8	52.6
S.Mamba-B + FDAM (Ours)	129M	1180G	52.3 _{+0.5}	53.0 _{+0.4}
Swin-L _[ECCV2021] [56]	234M	3230G	52.1	53.5
ConvNeXt-XL _[CVPR2022] [57]	245M	2458G	53.2	53.7
MogaNet-XL _[ICLR2024] [45]	214M	2451G	54.0	-
DeiT3-L _{*[ECCV2022]} [81]	354M	2231G	53.5	54.3
DeiT3-L + FDAM (Ours)	358M	2246G	54.1 _{+0.6}	54.8 _{+0.5}

Implementation Details. We follow the settings from the original papers for UPerNet [93], MaskDINO [42], and ViT [81]. On ADE20K [113], we train models for 160k iterations, following previous practice [56, 94]. On COCO [53] and DOTA [90], we adhere to standard practices [33, 47], training models for 12 epochs (1× schedule). More details are provided in the *supplementary material*.

5. Main Results

In this section, we evaluate our method on a range of tasks, including object detection, instance segmentation, and semantic segmentation, using standard benchmarks such as COCO [52], ADE20K [113], and DOTA [90].

We first compare our method with recent anti-oversmoothing approaches [63, 85], followed by a comparison with state-of-the-art Vision Transformer (ViT [22], Swin [56], DAT [91], DeiT3 [81], DiNAT [31]), convolutional networks (ConvNeXt-B [57], Focal-B [97], ConvFormer [103], PeLK-B [5], InceptionNeXt [105],

Table 3. *Object detection and instance segmentation* comparison on the COCO validation set [52]. * indicates reproduced results.

Model (Backbone: $\frac{R50}{ViT}$)	Epochs	Params	FLOPs	AP^{box}	AP^{mask}
DETR _{ECCV2020} [4]	500	41M	86G	42.0	-
Deform. DETR _{ICLR2021} [115]	50	40M	173G	43.8	-
DAB-DETR _{ICLR2022} [55]	50	44M	94G	42.2	-
Mask-RCNN _{ECCV2017} [33]	36	40M	207G	40.9	37.1
HTC _{ECCV2019} [6]	36	80M	441G	44.9	39.7
QueryInst _{ECCV2021} [23]	36	-	-	45.6	40.6
Mask2Former _{CVPR2022} [16]	12	44M	226G	-	38.7
DDQ R-CNN _{CVPR2023} [110]	12	-	249G	44.6	41.2
Mask DINO* _{CVPR2023} [42]	12	52M	286G	45.5	41.2
Swin-T _{ECCV2021} [56]	12	48M	267G	42.7	39.3
ViTDet-B _{ECCV2022} [48]	12	90M	463G	43.8	39.9
ViTDet-L _{ECCV2022} [48]	12	308M	1542G	46.8	42.5
ViT-Adapter-B _{ICLR2023} [15]	12	120M	-	47.0	41.8
AdaptFormer-B _{NeurIPS2023} [14]	12	119M	733G	44.5	40.3
LoSA-B _{CVPR2024} [62]	12	117M	722G	45.1	41.8
META-B _{ICLR2025} [109]	12	115M	720G	45.4	42.3
ViT-CoMer-S _{CVPR2024} [89]	12	50M	-	45.8	40.5
PIIP-SBL _{NeurIPS2024} [116]	12	493M	727G	46.7	40.8
Mask DINO + FDAM (Ours)	12	53M	289G	47.1_{+1.6}	42.6_{+1.4}

Table 4. *Panoptic segmentation* comparison on the COCO validation set [52]. * indicates reproduced results.

Model (Backbone: $R50$)	Epochs	#Query	PQ	PQ^{Th}	PQ^{St}
DETR _{ECCV2020} [4]	500+25	100	43.4	48.2	36.0
PanopticFPN _{CVPR2019} [41]	36	-	42.5	50.3	30.7
PanopticFCN _{CVPR2021} [49]	36	-	44.3	53.0	36.5
MaskFormer _{NeurIPS2021} [17]	300	100	46.5	51.0	39.8
Mask2Former _{CVPR2022} [16]	12	100	46.9	52.5	38.4
Mask DINO* _{CVPR2023} [42]	12	300	48.7	54.6	40.0
Mask DINO + FDAM (Ours)	12	300	49.6_{+0.9}	55.5_{+0.9}	40.7_{+0.7}

MogaNet [45], OverLoCK [60]), and Mamba (MambaOut [104], Vision Mamba [114], Spatial Mamba [81]).

Our method achieves considerable improvements in dense prediction tasks, including object detection, semantic segmentation, instance segmentation, panoptic segmentation, and remote sensing object detection, by addressing the limitations of vision transformers. It does so with minimal additional parameters and FLOPS overhead. Our method is highly versatile, integrating seamlessly with state-of-the-art architectures such as ViT [22] and MaskDINO [42], as well as with Mamba models like Spatial Mamba [92]. Experiments demonstrate that our method consistently outperforms recent state-of-the-art baselines.

Comparing with Anti-Oversmoothing Methods. Table 1 compares various anti-oversmoothing methods for ViT [80]. Our proposed FDAM achieves the highest performance, with an mIoU of 38.3 for single-scale (SS) evaluation and 39.5 for multi-scale (MS) evaluation. This outperforms existing methods such as AttScale [85], FeatScale [85], and NeuTRENO [63]. Specifically, FDAM improves SS mIoU by 2.6 and MS mIoU by 2.8 compared to vanilla DeiT-T [80]. These results demonstrate the effectiveness of FDAM in addressing the oversmoothing problem and enhancing segmentation performance.

Semantic Segmentation. Table 2 shows that FDAM con-

sistently enhances performance across architectures and scales, with minimal computational overhead (0.5M/0.3G for SegFormer-B0, 0.5M/3G for DeiT-S). For SegFormer-B0, FDAM improves mIoU by +2.4 in single-scale (SS) (37.4→39.8) and +2.2 in multi-scale (MS) (38.0→40.2). Similar gains are observed for DeiT-S, with +1.4 mIoU (42.9→44.3) in SS and +1.2 (43.8→45.0) in MS.

Object Detection and Instance Segmentation. We evaluate FDAM’s effectiveness on object detection and instance segmentation tasks using the COCO validation set [52]. As shown in Table 3, FDAM is integrated into the state-of-the-art Mask DINO framework [42], achieving notable performance gains with minimal computational overhead.

Specifically, FDAM enhances the AP^{box} by +1.6 (45.5→47.1) and the AP^{mask} by +1.4 (41.2→42.6), while adding only 1M parameters and 3G FLOPs to the baseline. These highlight FDAM’s effectiveness and efficiency.

Compared to other state-of-the-art methods, FDAM consistently delivers better or comparable performance with significantly fewer parameters and FLOPs. For example, ViTDet-L [48] achieves an AP^{box} of 46.8 with 308M parameters and 1542G FLOPs, whereas FDAM-enhanced Mask DINO achieves an AP^{box} of 47.1 with just 53M parameters and 289G FLOPs. This demonstrates FDAM’s effectiveness as a lightweight yet powerful enhancement to unlock the potential of transformers.

Panoptic Segmentation. On more challenging panoptic segmentation, our proposed Mask DINO + FDAM achieves superior performance compared to existing state-of-the-art methods, as shown in Table 4. Specifically, it attains a PQ score of 49.6, outperforming Mask DINO (48.7) and Mask2Former (46.9). The improvements are also evident in the PQ^{Th} and PQ^{St} metrics, with values of 55.5 and 40.7, respectively. These results demonstrate the effectiveness of FDAM in enhancing panoptic segmentation performance.

Remote Sensing Object Detection. Table 2 shows that applying FDAM to the LSKNet-S model improves the mAP by +1.12, from 77.49 to 78.61, with a minimal increase in model parameters (0.3M) and negligible additional computational cost, demonstrating FDAM’s efficiency.

Combination with Heavy Models. As shown in Table 2, FDAM also benefits larger models, achieving notable improvements on DeiT-B [80] (+1.1) and ViT-B [22] (+1.2). Specifically, DeiT3-Large with FDAM shows considerable mIoU improvements, with the single-scale (SS) mIoU increasing by +0.6 (53.5→54.1) and the multi-scale (MS) mIoU improving by +0.5 (54.3→54.8). It demonstrates that FDAM remains effective even when scaling up.

Combination with Mamba. Though not designed for Mamba, when combined with the recent Spatial Mamba-B [92], an improvement of +0.5 is observed (51.8→52.3), as shown in Table 2. These results confirm FDAM’s adaptability and effectiveness across various architectures.

Table 5. Remote sensing object detection results on the DOTA-v1.0 dataset [90] under a single-scale training and testing setting.

Method	#Params	PL	BD	BR	GTF	SV	LV	SH	TC	BC	ST	SBF	RA	HA	SP	HC	mAP
DETR-based																	
AO ² -DETR _[TCSVT2022] [19]	40.8M	87.99	79.46	45.74	66.64	78.90	73.90	73.30	90.40	80.55	85.89	55.19	63.62	51.83	70.15	60.04	70.91
O ² -DETR _[arxiv2021] [61]	-	86.01	75.92	46.02	66.65	79.70	79.93	89.17	90.44	81.19	76.00	56.91	62.45	64.22	65.80	58.96	72.15
ARS-DETR _[arxiv2023] [107]	41.6M	86.61	77.26	48.84	66.76	78.38	78.96	87.40	90.61	82.76	82.19	54.02	62.61	72.64	72.80	64.96	73.79
One-stage																	
SASM _[AAAI2022] [35]	36.6M	86.42	78.97	52.47	69.84	77.30	75.99	86.72	90.89	82.63	85.66	60.13	68.25	73.98	72.22	62.37	74.92
R3Det-GWD _[ICML2021] [99]	41.9M	88.82	82.94	55.63	72.75	78.52	83.10	87.46	90.21	86.36	85.44	64.70	61.41	73.46	76.94	57.38	76.34
R3Det-KLD _[NeurIPS] [101]	41.9M	88.90	84.17	55.80	69.35	78.72	84.08	87.00	89.75	84.32	85.73	64.74	61.80	76.62	78.49	70.89	77.36
O-RepPoints _[CVPR2022] [46]	36.6M	87.02	83.17	54.13	71.16	80.18	78.40	87.28	90.90	85.97	86.25	59.90	70.49	73.53	72.27	58.97	75.97
R. FCOS _[ICCV2019] [78]	31.9M	88.52	77.54	47.06	63.78	80.42	80.50	87.34	90.39	77.83	84.13	55.45	65.84	66.02	72.77	49.17	72.45
R3Det _[AAAI2021] [98]	41.9M	89.00	75.60	46.64	67.09	76.18	73.40	79.02	90.88	78.62	84.88	59.00	61.16	63.65	62.39	37.94	69.70
S2ANet _[TGRS2021] [29]	38.5M	89.11	82.84	48.37	71.11	78.11	78.39	87.25	90.83	84.90	85.64	60.36	62.60	65.26	69.13	57.94	74.12
Two-stage																	
SCRDet _[ICCV2019] [100]	41.9M	89.98	80.65	52.09	68.36	68.36	60.32	72.41	90.85	87.94	86.86	65.02	66.68	66.25	68.24	65.21	72.61
G.V. _[TPAMI2020] [96]	41.1M	89.64	85.00	52.26	77.34	73.01	73.14	86.82	90.74	79.02	86.81	59.55	70.91	72.94	70.86	57.32	75.02
CenterMap [59]	41.1M	89.02	80.56	49.41	61.98	77.99	74.19	83.74	89.44	78.01	83.52	47.64	65.93	63.68	67.07	61.59	71.59
ReDet _[CVPR2021] [30]	31.6M	88.79	82.64	53.97	74.00	78.13	84.06	88.04	90.89	87.78	85.75	61.76	60.39	75.96	68.07	63.59	76.25
Roi Trans _[CVPR2019] [20]	55.1M	89.01	77.48	51.64	72.07	74.43	77.55	87.76	90.81	79.71	85.27	58.36	64.11	76.50	71.99	54.06	74.05
R. F. R-CNN _[TPAMI2016] [71]	41.1M	89.40	81.81	47.28	67.44	73.96	73.12	85.03	90.90	85.15	84.90	56.60	64.77	64.70	70.28	62.22	73.17
O-CNN _[ICCV2024] [95]	74.4M	89.40	82.48	55.33	73.88	79.37	84.05	88.06	90.90	86.44	84.83	63.63	70.32	74.29	71.91	65.43	77.35
LSKNet-S _[ICCV2024] [95]	31.0M	89.66	85.52	57.72	75.70	74.95	78.69	88.24	90.88	86.79	86.38	66.92	63.77	77.77	74.47	64.82	77.49
GRA _[ICCV2024] [84]	41.7M	89.27	81.71	53.44	74.18	80.02	85.08	87.97	90.90	86.08	85.52	66.93	68.37	74.20	72.58	68.48	77.65
PKINet-S _[CVPR2024] [3]	30.8M	89.72	84.20	55.81	77.63	80.25	84.45	88.12	90.88	87.57	86.07	66.86	70.23	77.47	73.62	62.94	78.39
LSKNet-S + FDAM (Ours)	31.3M	89.85	83.86	55.12	78.84	79.71	85.10	88.35	90.88	88.77	86.12	68.31	66.57	76.77	72.49	68.36	78.61_{+1.12}

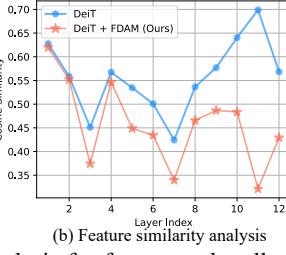
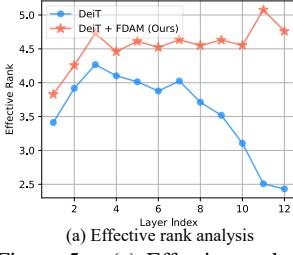


Figure 5. (a) Effective rank analysis for feature rank collapse. Higher *effective rank* [38] indicates a greater ability to capture complex patterns and nuanced details from the input data. FDAM maintains a consistently higher effective rank across all layers compared to the DeiT model using standard attention, demonstrating enhanced expressiveness of the attention mechanisms. (b) Feature similarity analysis. The cosine similarity increases with depth in the baseline DeiT model, indicating a loss of diversity in patch representations [63, 85]. The proposed FDAM method largely reduces this similarity, promoting more diverse features.

6. Analyses and Discussion

Here, we analyze effectiveness of the proposed method. More analyses are provided in *supplementary material*.

Rank Collapse Analysis. The inherent low-pass filtering characteristic of the attention mechanism lead to rank collapse [21], which degrades the model’s representational capacity. To analyze this, we employ the concept of *effective rank*, defined as the Shannon entropy of the normalized singular values of a matrix [38]. This measure provides a continuous and informative alternative to the traditional binary rank metric by capturing the distribution of singular values.

As shown in Figure 5(a), the effective rank of DeiT [80] model decreases rapidly with increasing depth, indicating a loss of feature anisotropy and hindering the model’s ability to capture complex patterns. In contrast, our FDAM main-

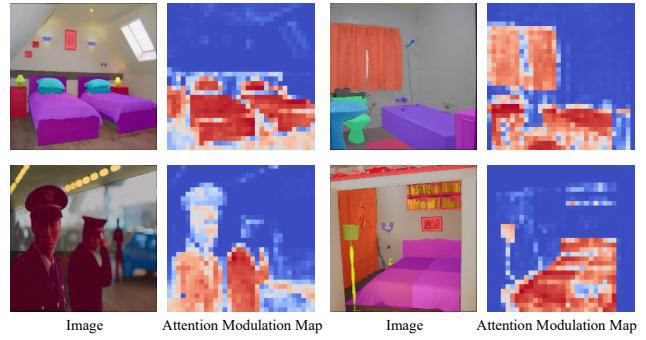


Figure 6. Visualization of attention modulation learned by AttInv. Warmer colors indicate higher values for high-pass filters. AttInv tends to assign higher values to foreground regions and semantic edges, emphasizing the focus on salient objects and boundaries.

tains a consistently higher effective rank across all layers, demonstrating that FDAM mitigates rank collapse and enhances expressiveness of attention mechanism.

Feature Similarity Analysis. We assess our model’s feature similarity using cosine similarity across layers in Figure 5(b). The DeiT shows a sharp rise in patch-wise cosine similarity with depth, hitting 0.70 by layer 11, signaling feature homogenization from repeated self-attention operations that erode discriminative spatial information. Our FDAM reduces late-layer similarity by up to 35%, enhancing robustness and task performance through more diverse representations. This analysis shows our methods curb over-smoothing, promote diversity, improve representational capacity, and boost performance on vision tasks.

Visualization of AttInv. Figure 6 shows that AttInv assigns higher high-pass filter values to foreground and semantic edges. This highlights the model’s focus on salient objects

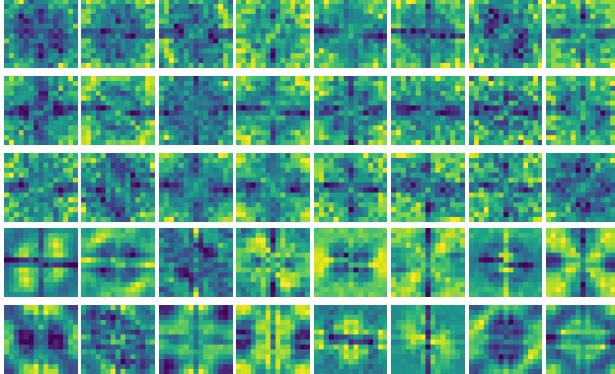


Figure 7. Visualization of frequency modulation map learned by FreqScale. From the center to the border are low- to high-frequency components. Brighter colors highlight amplified frequency components. This demonstrates that FreqScale tends to enhance high-frequency components in the feature maps, effectively preventing over-smoothing caused by the attention mechanism.

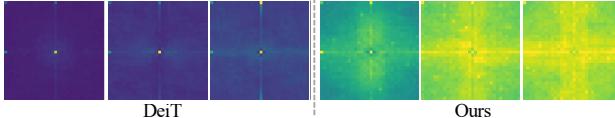


Figure 8. Frequency response visualization for the *last three attention layers*. Warmer colors denote higher response. DeiT shows a strong response for the lowest direct current frequency. Our approach shows a balanced distribution across frequency bands, with a stronger emphasis on high-frequency components. This correlates with higher accuracy in downstream dense prediction tasks requiring fine-grained discriminative spatial details.

and boundaries, emphasizing the importance of these areas in capturing discriminative details and textures.

Visualization of FreqScale. Figure 7 demonstrates that FreqScale tends to amplify the high-frequency components in the feature maps, effectively preventing over-smoothing caused by the attention mechanism.

Feature Response Visualization. To further illustrate FDAM’s effectiveness, we visualize the frequency responses in Figure 8. The left spectrum of DeiT shows a strong concentration in low-frequency regions, indicating a bias toward coarse features. In contrast, FDAM (right) exhibits enhanced activation in mid-to-high frequencies, preserving fine-grained details and localized structures. This improved frequency response aligns with the higher accuracy observed in dense prediction tasks, where fine-grained spatial information is crucial.

Feature Visualization. As shown in Figure 9, DeiT features show a tendency to blur details and textures due to the model’s inherent low-pass filtering characteristic. This results in a loss of fine-grained details crucial for tasks requiring precise visual understanding. In contrast, our method generates feature maps with sharper, more discriminative details, effectively highlighting object structures. The feature spectrum of DeiT demonstrates a strong bias toward

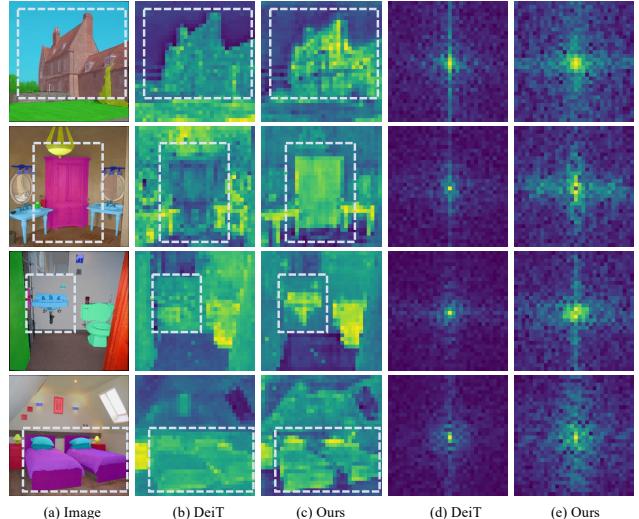


Figure 9. Feature and spectrum visualization. (a) Input image. (b), (c) feature maps. (d), (e) feature spectrum. Our approach generates semantically focused activations (c). Compared to DeiT’s feature maps (b), our feature maps (c) capture sharper, more discriminative details, emphasizing object structures. The spectrum (d) shows DeiT’s dominance in low-frequency components, whereas our method exhibits stronger high-frequency components, indicating better edge and detail preservation.

low-frequency components. However, our feature spectrum shows a more balanced distribution across frequency bands, suggesting better preservation of fine-grained details and localized features critical for precise spatial discrimination.

7. Conclusion

We identified and addressed a key limitation of ViTs: their inherent low-pass filtering, which causes frequency vanishing and loss of fine-grained details, hindering dense prediction tasks. To overcome this, we proposed Frequency-Dynamic Attention Modulation (FDAM), which comprises Attention Inversion (AttInv) and Frequency Dynamic Scaling (FreqScale). AttInv restructures self-attention into a dynamic mix of high- and low-pass filters, enhancing frequency flexibility, while FreqScale further refines frequency response function by adaptively re-weighting frequency bands to preserve crucial frequency information. It can be *easily plugged into* existing ViT architectures.

Extensive experiments demonstrate that FDAM effectively avoids representation collapse and boosts performance in semantic segmentation, object detection, and instance segmentation with minimal cost. Additionally, FDAM achieves state-of-the-art results when applied to remote sensing object detection, showcasing its potential for real-world applications. Beyond its empirical success, FDAM offers new theoretical insights into self-attention’s spectral properties, paving the way for frequency-adaptive transformers and more robust vision architectures.

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