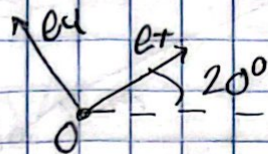


# PROBLEM SET #1

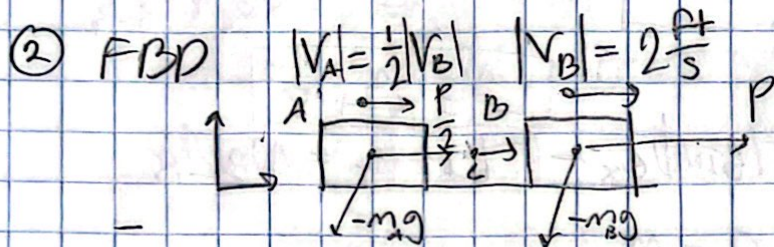
## QUESTION 1:

- ① KINEMATICS  
° CARTESIAN COORDS



$$\mathbf{r} = x\mathbf{e}_x + y\mathbf{e}_y \quad \mathbf{v} = \dot{\mathbf{r}} = \dot{x}\mathbf{e}_x + \dot{y}\mathbf{e}_y \quad \mathbf{a} = \dot{\mathbf{v}} = \ddot{x}\mathbf{e}_x + \ddot{y}\mathbf{e}_y$$

$$\dot{\varphi} = \ddot{\varphi} = \ddot{\varphi} = 0$$



$$g = 9.8 \frac{\text{m}}{\text{s}^2} \sin \theta \mathbf{e}_x$$

③  $\sum \mathbf{F}_B = m_B \mathbf{A}_B \rightarrow -m_B g + P = m_B A_B \quad m_B = ? \quad A_B = 3 \frac{\text{ft}}{\text{s}^2}$

$$\sum \mathbf{F}_C = m_C \mathbf{A}_C \rightarrow -m_C g + c_1 P = m_C A_C \quad c_1 c_2 = \text{CONST.}$$

$$\sum \mathbf{F}_A = m_A \mathbf{A}_A \rightarrow -m_A g + c_2 P = m_A A_A$$

$$P = m_B A_B + m_B g = \frac{1}{c_1} (m_C A_C + m_C g) = \frac{1}{c_2} (m_A A_A + m_A g)$$

$$2R_A = R_B \rightarrow 2V_A = V_B \rightarrow 2A_A = A_B$$

$$V_C = \frac{V_A + V_B}{2} = \frac{V_B/2 + V_B}{2} = \frac{3V_B}{4} \quad A_C = \frac{3A_B}{4}$$

$$V_A = \frac{2}{2} \frac{\text{ft}}{\text{s}} = 1 \frac{\text{ft}}{\text{s}} \quad A_A = \frac{3}{2} \frac{\text{ft}}{\text{s}^2}$$

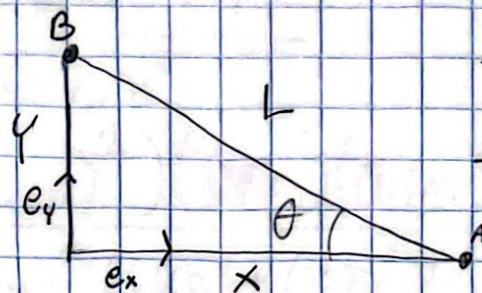
$$V_C = \frac{3 \cdot 2}{4} \frac{\text{ft}}{\text{s}} = \frac{3}{2} \frac{\text{ft}}{\text{s}}$$



# PROBLEM SET #1

## QUESTION 2

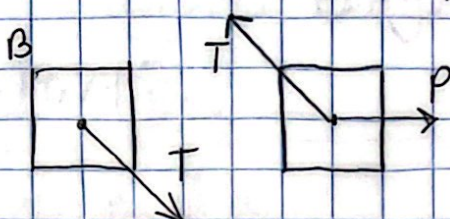
① KINEMATICS  
• CARTESIAN



$$\begin{aligned} \underline{r} &= x\mathbf{e}_x + y\mathbf{e}_y \\ \underline{v} &= \dot{x}\mathbf{e}_x + \dot{y}\mathbf{e}_y \\ \underline{a} &= \ddot{x}\mathbf{e}_x + \ddot{y}\mathbf{e}_y \end{aligned}$$

$$\sin\theta = y/L$$

② FBD



$$\begin{aligned} \textcircled{3} \quad \Sigma \underline{F} &= m \underline{a} \quad \textcircled{1} \quad T = m_B a_B \Rightarrow \left| T \frac{y}{L} = m_B \ddot{y} \right| \\ \textcircled{2} \quad &\left| -T \frac{x}{L} + P = m_A \ddot{x} \right| \end{aligned}$$

$$\textcircled{3} \quad \left| L^2 = y^2 + x^2 \right| \xrightarrow{\frac{d}{dt}} \quad 0 = 2x\dot{x} + 2y\dot{y} \Rightarrow \left| x\dot{x} + y\dot{y} = 0 \right| \quad \textcircled{4}$$

$$\xrightarrow{\frac{d}{dt}} \quad \left| \dot{x}^2 + x\ddot{x} + \dot{y}^2 + y\ddot{y} = 0 \right| \quad \textcircled{5}$$

$$\textcircled{3} \quad (0.5\text{m})^2 = y^2 + (0.4\text{m})^2 \quad y = 0.3\text{m}$$

$$\textcircled{4} \quad (0.4\text{m})(2\text{m/s}) + (0.3\text{m})\dot{y} = 0 \quad \dot{y} = -8/3 \text{ m/s}$$

$$T = \frac{L m_B \ddot{y}}{y} \quad T = \frac{L (P - m_A \ddot{x})}{x}$$

$$-m_B \frac{\ddot{y}}{y} = \frac{P - m_A \ddot{x}}{x} \quad \ddot{y} = \frac{y(m_A \ddot{x} - P)}{m_B x}$$

$$\dot{x}^2 + x\ddot{x} + \dot{y}^2 + y^2(m_A \ddot{x} - P) / m_B x = 0$$

$$\frac{y^2(m_A \ddot{x} - P)}{m_B x} + x\ddot{x} = -\dot{x}^2 - \dot{y}^2$$

$$y^2 m_A \ddot{x} + m_B x^2 \ddot{x} = (-\dot{x}^2 - \dot{y}^2) m_B x + y^2 P$$

$$\ddot{x} (y^2 m_A + m_B x^2) = (-\dot{x}^2 - \dot{y}^2) m_B x + y^2 P$$

$$\begin{aligned} x &= 0.4\text{m} \\ L &= 0.5\text{m} \\ y &= 0.3\text{m} \\ \dot{x} &= 2\text{m/s} \\ \dot{y} &= -8/3 \text{ m/s} \\ m_A &= 2\text{kg} \\ m_B &= 3\text{kg} \end{aligned}$$



$$\ddot{X} = \frac{(-\dot{x}^2 - \dot{y}^2) M_B X + Y^2 P}{Y^2 M_A + M_B X^2}$$

$$\ddot{X} = \frac{(-(2\frac{m}{s})^2 - (8/3\frac{m}{s})^2)(3\text{kg})(0.4\text{m}) + (0.3\text{m})^2(40\text{N})}{(0.3\text{m})^2(2\text{kg}) + (3\text{kg})(0.4\text{m})^2}$$

$$\ddot{X} = -14.74 \frac{m}{s^2}$$

$$M_A \ddot{X} = P + \frac{M_B \ddot{Y} X}{Y}$$

$$11.11 + 0.4\ddot{X} + 0.3\ddot{Y} = 0$$

$$40 + \frac{3\ddot{Y} \cdot 0.4}{0.3} = 2\ddot{X}$$

$$20 + 2\ddot{Y} = \ddot{X}$$

$$\ddot{Y} = \frac{\ddot{X} - 20}{2} = \frac{-14.74 - 20}{2}$$

$$= -17.37 \frac{m}{s^2}$$

$$T = \frac{-(0.5\text{m})(3\text{kg})(-17.37\frac{m}{s^2})}{0.3\text{m}}$$

$$T = 86.85 \text{ kg} \frac{m}{s^2}$$

↑  
acc of block B



# PROBLEM SET #1

## QUESTION 3

① KINEMATICS  
• CYLINDRICAL

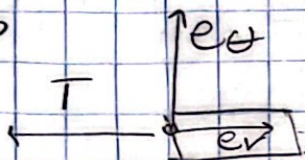
$$\mathbf{r} = r\mathbf{e}_r + z\mathbf{e}_z$$

$$\dot{\mathbf{r}} = \dot{r}\mathbf{e}_r + r\dot{\theta}\mathbf{e}_\theta + \dot{z}\mathbf{e}_z$$

$$\ddot{\mathbf{r}} = (\ddot{r} - r\dot{\theta}^2)\mathbf{e}_r + (r\ddot{\theta} + 2\dot{r}\dot{\theta})\mathbf{e}_\theta + \ddot{z}\mathbf{e}_z$$

$$\dot{z} = \ddot{z} = \ddot{z} = 0$$

② FBD



$$F_c = m\omega^2 r(t)$$

③  $\sum F_r = m A_r$   $A_{cr} = (\ddot{r} - r\dot{\theta}^2)\mathbf{e}_r$

$$-T = m(\ddot{r} - r\dot{\theta}^2) \rightarrow T = (0.2)(2 - 1(4)^2)$$

$$T = 2.8 \text{ N} \quad \text{--- STRING TENSION}$$

$$\sum F_\theta = m A_\theta \quad A_{\theta} = (r\ddot{\theta} + 2\dot{r}\dot{\theta})\mathbf{e}_\theta$$

$$F_\theta = m(r\ddot{\theta} + 2\dot{r}\dot{\theta}) = (0.2)(-2 + 2(-3)(4))$$

$$F_\theta = 5.2 \text{ N} \quad \text{--- FORCE EXERTED BY TUBE}$$



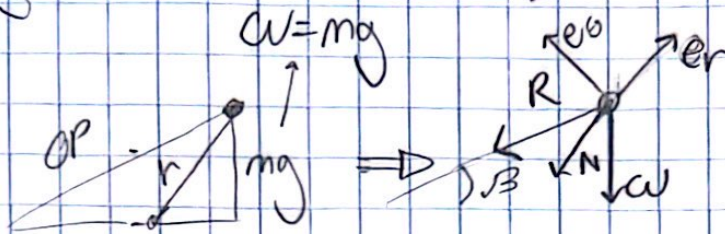
# PROBLEM SET #1

## QUESTION 4

- ① KINEMATICS  
• CYLINDRICAL  
 $\{e_r, e_\theta\}$

$$\begin{aligned} \underline{r} &= r e_r \\ \underline{v} &= \dot{r} e_r + r \dot{\theta} e_\theta \\ \underline{a} &= (\ddot{r} - r \dot{\theta}^2) e_r + (r \ddot{\theta} + 2 \dot{r} \dot{\theta}) e_\theta \end{aligned}$$

- ② FBD



- ③

$$\sum F_r = m A_{er} \quad A_{er} = (\ddot{r} - r \dot{\theta}^2) e_r = -r \Omega^2$$

$$-N - R \cos \beta - W \cos \beta = -mr \Omega^2 \quad \ddot{\theta} = 0 \quad \dot{r} = 0$$

$$\sum F_\theta = m A_{e\theta} \quad A_{e\theta} = (r \ddot{\theta} + 2 \dot{r} \dot{\theta}) e_\theta = 0$$

$$R \sin \beta - W \sin \beta = 0 \rightarrow R = W$$

$$-N - 2W \cos \beta = -mr \Omega^2$$

$$-N = -mr \Omega^2 - 2mg \cos \beta = -(0.2 \text{ kg})(1 \text{ m})(2 \frac{\text{rad}}{\text{s}})^2$$

$$N = 4.434 \text{ N}$$

$$-2(0.2 \text{ kg})(9.8 \frac{\text{m}}{\text{s}^2})(0.92)$$

$$R = mg = (0.2 \text{ kg})(9.8 \frac{\text{m}}{\text{s}^2}) = 1.96 \text{ N}$$