

MOHIT KULKARNI

Sophomore Undergraduate
Department of Mathematics and Statistics
Indian Institute of Technology, Kanpur

mohitmk@iitk.ac.in ✉
m2kulkarni | m2kulkarni in
m2kulkarni.github.io 🏠
+91-9405602576 📞

EDUCATIONAL QUALIFICATIONS

Year	Degree	Institution(Board)	CGPA/%
July'19 – June'23 (expected)	B.S., Mathematics	Indian Institute of Technology, Kanpur	8.2/10.0
2019	SSC – XII	Vidyadham Junior, Aurangabad	87.8%
2017	ICSE – X	Podar International School, Aurangabad	95.6%

INTERESTS

Open Source, Computational Neuroscience, Robotics, Image Processing, Machine Learning, AGI

SKILLS

Prog. Language: C, C++, Python, Java, Bash
Utilities: OpenCV, ROS, Brian2, PyTorch, Tensorflow, Gazebo, Makefile, Git, MATLAB, \LaTeX

ACHIEVEMENTS

- AIR 615, JEE Advanced - 2019, amongst 200,000 candidates
- AIR 637, JEE Main - 2019, amongst 1.2 million candidates
- Awarded INSPIRE scholarship by Department of Science and Technology, Government of India,

WORK EXPERIENCE

Svoboda Lab, Janelia Research Campus

Remote Undergraduate Intern Sep'20 - Present

- Working on learning and plasticity in the Somatosensory cortex.
- Involved in analysing Calcium Imaging data gathered from rodents and finding suitable correlations and learning mechanisms that allow such correlations.
- Experimented with more biologically plausible learning algorithms such as Feedback Alignment, localised hebbian learning etc.

POSITIONS OF RESPONSIBILITY

Robotics Club, IIT Kanpur

Secretary April'20 - Present

- Part of team responsible to suggest and execute ideas to increase participation in robotics related activities.

Brain and Cognitive Society, IIT Kanpur

Secretary August'20 - Present

- Responsible for conduction of journal clubs, contacting professors, and raising awareness about the club activities

Counselling Service, IIT Kanpur

Student Guide November'20 - Present

- Responsible for mentoring and guiding 6 freshman as they adjust to the new environment.

CAMPS AND WORKSHOPS

Neuromatch Academy 2020

An online school for Computational Neuroscience July'20

Vijyoshi Camp 2019

IISER, Kolkata Dec'19

RELEVANT COURSES

Fundamentals of Computing(ESC101)
Introduction to Electronics(ESC201)¹
Linear Algebra and ODE(MTH102)

Real Analysis(MTH101)
Set Theory and Mathematical Logic(MTH302)¹
Electrodynamics(PHY103)

Neurobiology(BSE656)¹
Deep Learning Specialization*
Fluid Mechanics(ESO204)¹

(¹): Ongoing Courses (*): Coursera course

PROJECTS

The Omniglot Project

Github ✍

Brain and Cognitive Society, IIT Kanpur

May'20 - July'20

- This project was aimed at understanding and solving the problem of one-shot learning.
- Implemented SOTA meta-learning models to solve one-shot classification and generative problem.
- Used architectures like GANs, VAEs, LSTMs and bayesian statistics to develop models in PyTorch.

Autonomous Humanoid(AUTOMI)

Github ✍

Team Humanoid, IIT Kanpur

Sep'19 - Present

- Involved in the development of a complete, highly optimised software stack for AUTOMI.
- AUTOMI v1 is designed for autonomous navigation in a static environment using techniques like depth estimation, SLAM, object recognition, avoidance, lane detection etc.
- The software stack is based on ROS, with image processing using OpenCV.

DumE

Github ✍

Robotics Club, IIT Kanpur

May'20 - July'20

- The aim was to create a Robotic arm that mimicks human arm, particularly useful in high precision environments.
- The simulation was based on ROS and Gazebo, with arm detection using custom joint detection algorithms.
- Secured the Best Innovation Award from amongst 50 summer projects under Science and Technology Council, IITK .

Following Sub-Population Signals

Github ✍

Mentor: Prof. James Murray, University of Oregon

July'20

- The goal was to reveal more insights about the connection between different brain areas and how the sub-populations communicate, like order of firing of specific neuronal type, and the correlation between order of firing between different brain regions.
- This analysis was performed on Steinmetz dataset, as a part of Neuromatch Academy 2020.
- Techniques such as Granger Causality, PCA, dPCA, Markov Models were used.

PETcat

Github ✍

Robotics Club, IIT Kanpur

April'20 - Present

- Aimed at developing a biologically inspired robotic cat.
- Simultaneous Localization and Planning Algorithms like orb-SLAM, gmapping, roVIO were implemented and benchmarked.
- Currently involved in optimization of software stack using storage optimization, multi-threading etc.