

Design a Non-blocking LCD and Keypad

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Firstly: Project Description:

- 1. Hardware Requirements
 - 1. character LCD
 - 2. KEPAD
- 2. Software Requirements
 - 1. Use non-blocking delay functions



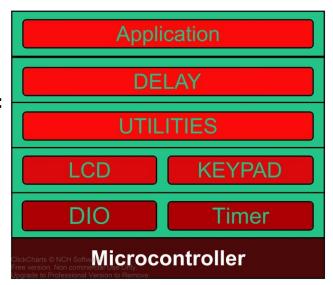
Secondly: Layered architecture:

- 1- Microcontroller
- 2- MCAL
- 3- ECUAL
- 4- UTILITIES
- 5- SERVICES

Application
SERVICES
UTILITIES
ECUAL
MCAL
ClickCharts © NCH Softw Microcontroller Free version. Non commercial Use Only, Upgrade to Professional Version to Remove.

Thirdly: System modules:

- 1- Specify system modules/drivers:
 - DIO, TIMER, LCD, KEYPAD, DELAY
- 2- Assign each module to its related layer:
 - By drawing



Forthly: APIs:

1- DIO APIs:



2-TIMER APIs:

```
void TIMER_init (uint8_t Mode,uint8_t intial_value);
void TIMER_start (uint8_t prescaler_value);
void TIMER_set(uint8_t intial_value);
void TIMER_getStatus(uint8_t *value);
void TIMER_Stop (void);
```

3-LCD APIs:

```
void LCD_init (void);
void LCD_sendcommand (uint8_t cmnd);
void LCD_sendcommand (uint8_t char_data);
```

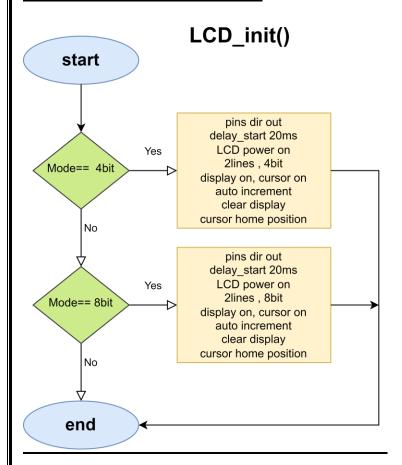
4- KEYPAD APIs:

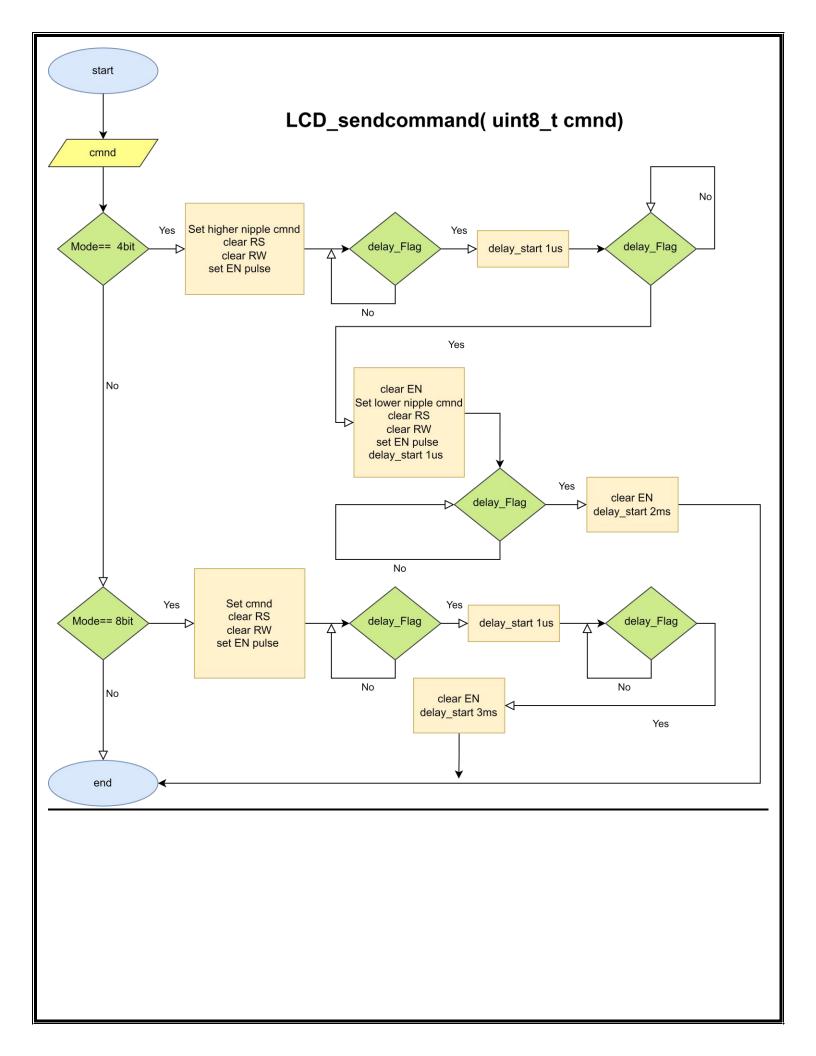
```
void KEYPAD_init (uint8_t port);
uint8_t KEYPAD_getkey (void);
```

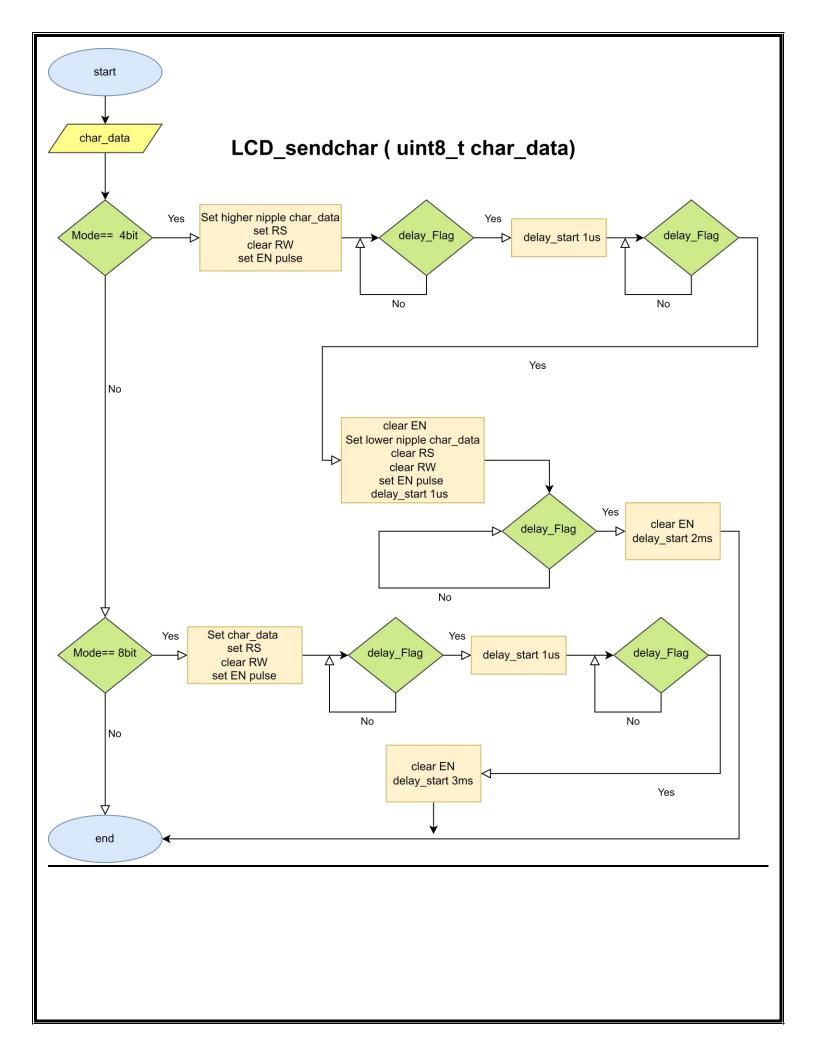
5- DELAY APIs:

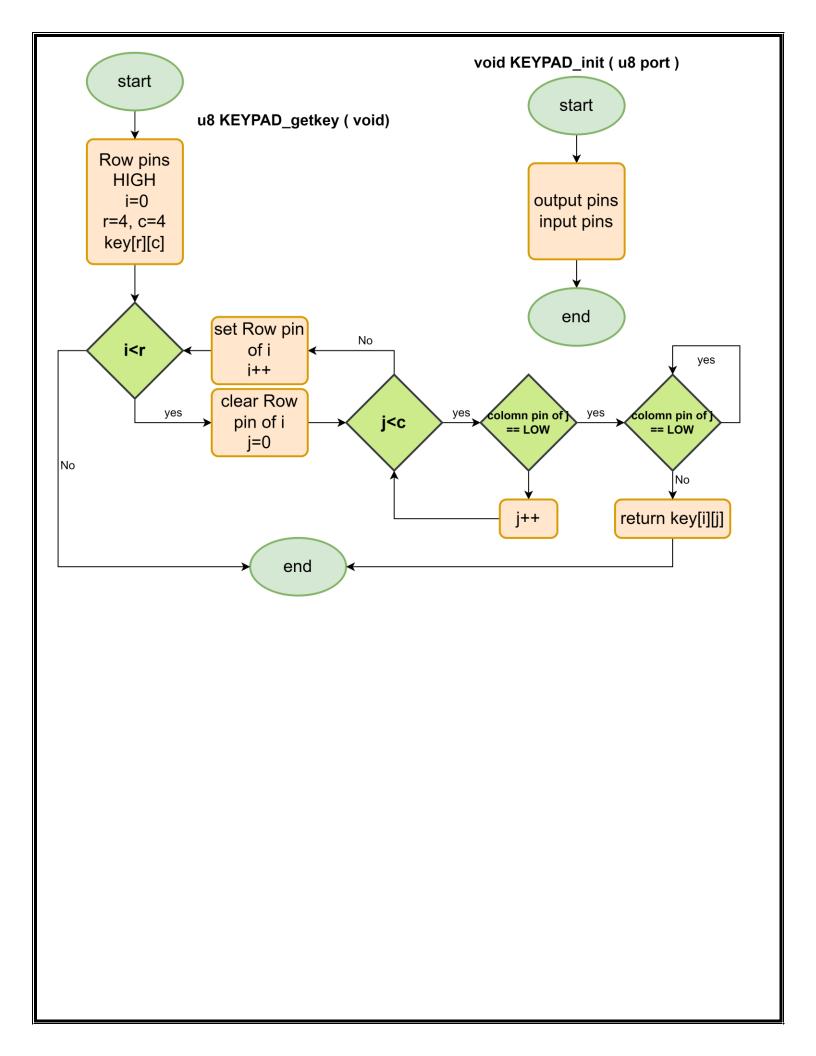
```
void delay_start_ms (uint32_t ms);
void delay_start_us (uint32_t us);
```

Fifthly: Flowcharts APIs:









void delay_start_us (u8 us) void delay_start_ms (u8 ms) start start TIMER ISR us Count++ Set pin direction output (DDR) Set pin direction output (DDR) choose timer mode (TCCR0) choose timer mode (TCCR0) enable global interrup (SREG) enable global interrup (SREG) enable timer0 ovflow interrup (TIMSK) enable timer0 ovflow interrup (TIMSK) Count == Timer0_Ovf_CALLBACK (TIMER_ISR) Timer0_Ovf_CALLBACK (TIMER_ISR) TIME_OUT Flag = 1; Flag = 1; Count=0; Count=0; TIME OUT =ms*4; TIME OUT =us; timer start count timer start count set intial value timer to 0x06 start start Flag = 0 timer stop disable int. timer ovf disable global int. return from interrupt