

Lee Mracek

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OBJECTIVE

To build on my production environment software experience through larger scale projects or further development on embedded systems through a 2017 summer internship.

EDUCATION

GEORGIA INST OF TECH

BS COMPUTER SCIENCE

BS ELECTRICAL ENGINEERING

Expected 2020 | Atlanta, GA

MONTA VISTA HIGH SCHOOL DE ANZA COLLEGE

August 2012–June 2016

Final two years of high school were at college.

LINKS

Facebook:// [leemracek](#)

Github:// [m3rcuriel](#)

LinkedIn:// [leemracek](#)

COURSEWORK

UNDERGRADUATE

Adv. Programming in C++

Linear Algebra

Differential Equations

Multivariable Calculus

SKILLS

PROGRAMMING

Proficient:

Java • Shell • Python • C++

C • Matlab • Simulink • \LaTeX

Familiar:

Real-time Linux • Android

TOOLS & INFRASTRUCTURE

AWS • Docker • Vagrant

ControlDesk • dSPACE

gdb • Bazel • CMake • Gradle • ant

Jenkins • Travis CI • Gerrit

EXPERIENCE

GEORGIA TECH ECOCAR 3 | CONTROLS & MODELING

Aug 2016 - Present | Atlanta, GA

- Wrote HIL simulation code for dSPACE using Simulink.
- Used AutomationDesk to write Python unit-test cases for controls.

VALKYRIE ROBOTICS | HEAD MENTOR & SOFTWARE ENGINEER

Mar 2016 - Present | Cupertino, CA

- Founded and am assisting a robotics team consisting of high schoolers in the community to enrich their STEM educations.
- Both founding head mentor as well as in charge of all technical work.
- Real-time programming for embedded systems and abstract Python libraries (see 'Mass' in Projects section).
- Manage back-end system including AWS, Google Apps, Confluence, Jenkins, and Gerrit.

DIAMOND SYSTEMS | SOFTWARE ENGINEERING INTERN

June 2015 – Sep 2015 | Mountain View, CA

- Managed full software stack as sole software engineer.
- Produced and tested Linux kernel modules for custom hardware.
- Worked with the CEO of Rocket EMS to evaluate hardware and software system and eliminated software as root cause after working with them for several weeks designing newest revision of a PC board.

MONTA VISTA HIGH SCHOOL

FIRST ROBOTICS TEAM | SOFTWARE ENGINEERING

Aug 2012 - Mar 2016 | Cupertino, CA

- Led and trained groups of freshmen to design and construct our robot code.
- Implemented control theory, stochastic modeling and state-space representation which were used for machine learning and controls code on the robot.
- Developed overarching framework for writing code for math utilities, hardware abstractions and timing methods.

PROJECTS

MASS | PRIVATE REPOSITORY

With Valkyrie Robotics

Real-time C++ framework for FIRST Robotics. Led and designed code structure and implementation. Achieves 5 ms control loops on real-time hardware with 10 μ s standard deviation. Allows effective PID and full state control, Kalman filtering, DMA, and motion profiling.

JARVIS SCHEDULER | [GITHUB.COM/JARVIS/JARVIS-SCHEDULER](https://github.com/Jarvis/Jarvis-Scheduler)

May 2015 – June 2016

Built backend Python for a webapp to help De Anza College students schedule their classes.