

Enabling Ambient Backscatter Using Low-cost Software-defined-radio

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Abstract—Backscatter communication is attractive for energy-constrained devices due to its very low power requirements. Ambient backscatter takes this aspect to the limit by leveraging existing radio frequency signals for the purpose of communication without the need for generating energy expensive carrier signal. In this paper we investigate the use of ambient television broadcast signals for communication. As opposed to state-of-the-art restricted to operations under conditions of strong signal strength, we demonstrate a low cost software defined radio as receiver enables operations even in conditions when ambient signals are weak in strength. We build the system using low-cost off-the-shelf microcontroller, and RTLSDR software-defined radio receiver. We also conduct survey of signal strength of TV broadcast in a mid-sized swedish city, and observe that our system can operate in most parts of the city.

I. INTRODUCTION

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II. BACKGROUND

A. RTL2832U

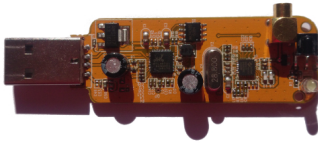


Fig. 1. RTL-SDR hardware with the DVB-T I/Q demodulator *Raeltek RTL2832U* (left IC) and the tuner with integrated LNA *Rafael Micro R820T/2* (right IC).

The Raeltek RTL2832U is a terrestrial digital video broadcast (DVB-T) chip, which is the basis of a very low-cost software defined radio: The RTL-SDR. One feature of this chip is, that it supports USB 2.0. Ham radio enthusiasts combined their efforts to enable accessing the raw I/Q data. With their software driver (basically the *librtlsdr*, cf. [1]) DVB-T sticks, which are based on the RTL2832, can be converted into a wideband SDR. This sort of hardware has been in the range of a few thousands USD a few years ago. An RTL2832U based DVB-T receiver can be bought with antenna for less than 10

USD. What is a software defined radio? Traditionally basic radio components like mixers or filters have been realized in hardware. Nowadays as soon as one works in the baseband frequency the computational resources of a personal computer are sufficient to realize these components with signal processing done in software. An RTL-SDR does not only consist of the RTL2832U. The second essential component is the tuner, which mixes down the radio frequency (RF) to a intermediate frequency (IF). In the case of the used hardware this tuner component was represented by a *Rafael Micro R820T/2*. It subsumes a low-noise amplifier (LNA) and filters. The image frequency is rejected automatically with 65 dBc and the noise figure is with 3.5 dB quite low. It allows a frequency range from 42 to 1002 MHz (cf. [2]). The I/Q demodulator, also shown in figure 3, is the most important part of the *RTL2832U* for our work. The received signal can be interpreted as

$$s_{IF}(t) = I(t) \cdot \cos(\omega_0 t) + Q(t) \cdot \sin(\omega_0 t) \quad (1)$$

This is multiplied with a cosine (and a sine as well) from a local oscillator.

$$s_{IF}(t) \cdot s_L(t) = I(t) \cdot \cos(\omega_0 t) \cdot \cos(\omega_0 t) + Q(t) \cdot \sin(\omega_0 t) \cdot \cos(\omega_0 t) \quad (2)$$

With $2 \cos(a) \cos(b) = \cos(a - b) + \cos(a + b)$ and $2 \sin(a) \cos(b) = \sin(a + b) + \sin(a - b)$ follows

$$2 \cdot s_{IF}(t) \cdot s_L(t) = I(t) \cdot [1 + \cos(2\omega_0 t)] + Q(t) \cdot [\sin(2\omega_0 t) + \sin(0)]. \quad (3)$$

One can see, that the interesting inphase part in this case is represented by a DC value after mixing. With a low-pass filter this DC value can be separated from the undesired rest. Similar things are happening with the quadrature part when mixing with a sine, which is indeed done to get the quadrature part.

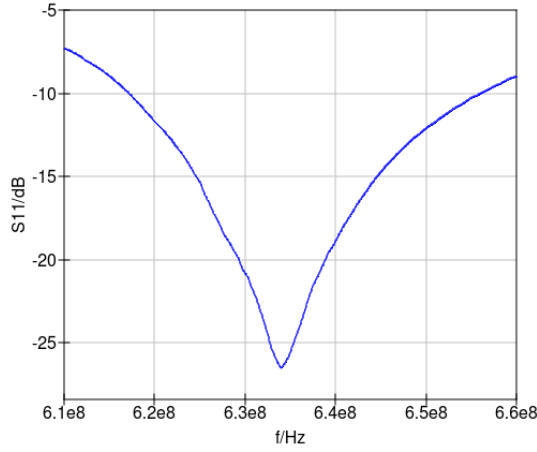


Fig. 2. Input reflection coefficient Γ_{in} also known as S_{11} of the selfmade backscattering ground plane antenna in dB.

III. DESIGN

A. Transmitter

A backscattering antenna is the most important part of backscattering sender. Our antenna is optimized for usage with the television signal, which has its center frequency at 626 MHz. It is a ground plane antenna, which has been built up on a big PCB. This rectangular PCB, with dimensions of 200 mm x 300 mm, is covered with a copper layer on one side and left blank on the other. A hole in the middle of the PCB serves for connecting a thicker wire to a 50 Ω microstrip transmission line. The wire is the vertical antenna element has a length of 350 mm, which is roughly 0.73λ . It is soldered to the transmission line. The transmission line has been calculated for 626 MHz using FR4 substrate with a thickness of 1.6 mm. According to microstrip line theory the length of the line changes the phase and the width of the line changes the impedance (cf. chapter 3 in [3]). The design equations given in [?] are implemented in various programs e.g. KiCAD, which has been used for solving the design equations. The given parameters lead to a microstrip line width of 3 mm. An open-stub, attached directly at the puncture where the vertical antenna element is attached to the transmission line, is used for fine tuning of the input impedance. The stub length has been adjusted manually (shortened) while measuring the reflection coefficient with a vector network analyzer (VNA). Open-stub matching is discussed in chapter 5 in [3]. Furthermore the resonance frequency has been tuned by cutting the vertical antenna element piece by piece while measuring with the VNA. At some point the S_{11} had the minimum quite close to where we wanted to have it (cf. 2). In the plot one can also see, that the antenna is quite narrowband. For backscattering this is not necessarily a disadvantage, since everything, which is within the operating frequency of the antenna is backscattered. So with a narrowband antenna the effect, that signals are backscattered, which are not targeted, is reduced. This statement has to be qualified as the antenna

also has multiple resonance frequencies in multiple bands. With our approach we were able to achieve a input resistance at 634 MHz of $Z_{in} = (52.2 + j4.3)\Omega$. At 626 MHz S_{11} is still approximately -17 dB. Besides the antenna the transmitter consists out of a *MSP430*, which acts as subscriber, that sends data to the receiver. This transmitter is connected with one I/O pin and ground to a rf switch. The switch can change between matched (50 Ω) and open. The software now steers this switch with a two 2 MHz rectangular timer signal for a 1 and is just leaves it open for a 0. Therefore the result is a shift of the television signal by 2 MHz for a 1 and no shift for a 0. Hence a classical binary amplitude shift keying is the implemented modulation technique.

B. Receiver

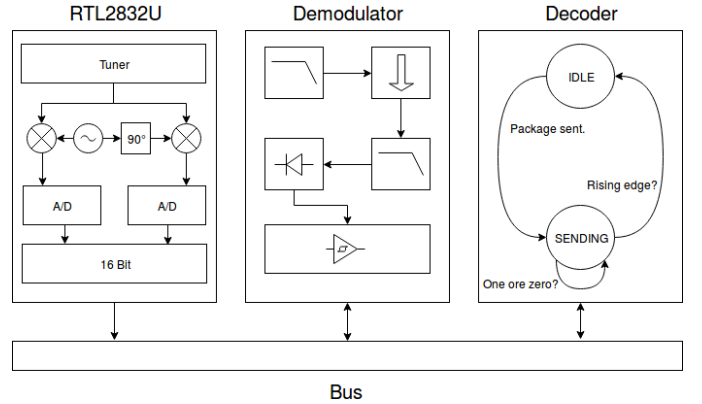


Fig. 3. Receiver architecture from a system point of view. Signal flow is from the left to the right.

The receiver was the most work intensive part of the design. C++ has been used to implement the receiver. We provide the code publicly available under <https://github.com/s3xm3x/backscatterBASKReceiver>. In figure 3 one can see the architecture of the receiver from an abstract point of view. A highly sophisticated bus system has been developed to exchange data between the different components of the system. The signal flow is from the left to the right. *Librtlsdr* (cf. [1]), which is based on *libusb*, is used to transfer the data from the TV stick into our program. As described under II-A, the RTL2832 mixes down the high frequency to a intermediate frequency (both values are in SW adjustable). Subsequently the data is mixed with sine and cosine, low-pass filtered and finally transferred in the digital world. This data is available as two 8 Bit values. It is a well-known fact, that this technique, which is commonly known as I/Q demodulation, results in a real and an imaginary part. With this two values phase and absolute value of the data can be determined for every sample. So every sample consists out of a real and an imaginary part. And can be seen as:

$$I + jQ = \text{abs}(I, Q) \cdot e^{ang(I, Q)} \quad (4)$$

So the first block, which is entitled with RTL2832U, provides the interface to the TV dongle. This block is represented as

one object. It can set the frequency f_{tuned} , where the receiver is listening. Also it can set the sampling frequency f_{samp} and the analog gain of the tuner. The raw samples are pushed to the bus. Demodulator is the block called, which is responsible to convert the sampled signals into something, which looks like ones and zeroes. Therefore the real and imaginary values first have to be deinterleaved out of the sample message. Now they are represented as integer values between 0 and 255 (8 bit). So one converts them to floats, whereas 127.5 equals 0. After that the values have to be downsampled. Usually we were sampling with 250 kHz. This is still much more than we need assuming an additive white gaussian noise (AWGN) channel with a $S/N = 10 \text{ dB}$ (cf. equation 5). So we decided to reduce the sampling frequency to 25 kHz.

$$C = B \cdot \log_2(1 + \frac{S}{N}) = 25 \text{ kHz} \cdot \log_2(11) \approx 86.5 \text{ kbit/s} \quad (5)$$

To do this it is important to use an anti-aliasing filter, as the Shannon-Nyquist theorem has to be satisfied:

$$f_{samp} \geq 2 \cdot f_a \quad (6)$$

f_a is the highest frequency in the signal. A FIR filter naively implemented with floats has been used to achieve this. 10 kHz is the cut-off frequency of the first filter. All filters have been constructed with the internal filter design tool of GNU radio. After downsampling another filter is used to suppress noise. This filter has a cut-off frequency of 3 kHz. The last demodulation step is to take the signal, rectify it (cf. equation 7) and decide with a software-defined Schmitt trigger whether a sample is a 1 or a 0.

$$abs(I, Q) = \sqrt{I^2 + Q^2} \quad (7)$$

These samples are broadcasted on the bus. A registered listener receives the processed samples. This registered listener is the decoder, which is represented as an object as well. After the decoder received the samples it decides when a frame is sent or when the channel is idle. On the basis of a defined threshold the decoder determines whether a certain sample pattern of ones and zeros is a 1 bit or a 0 bit. The baudrate and the sampling rate lead to a certain length of one bit. For example a sample rate $f_{sampling}$ of 25 kHz combined with a baudrate of 1 kbit/s leads to 25 samples/bit. The decoder also includes a function to correlate the received bitstream with an expected pattern. Hence it is able to determine the bit error ratio (BER). Furthermore the code we have written so far subsumes a simulator to simulate ideal data coming out of the demodulator to test the algorithms behind the decoder. Also a simulator for the RTL2832U has been written to replay recorded samples, which facilitates debugging as well. Another handy utility, which has been written in Octave, is a tool (an oscilloscope) to look at the data, which is written into files by the demodulator. An example of a recorded data stream with 25 kS/s can be seen in figure 4.

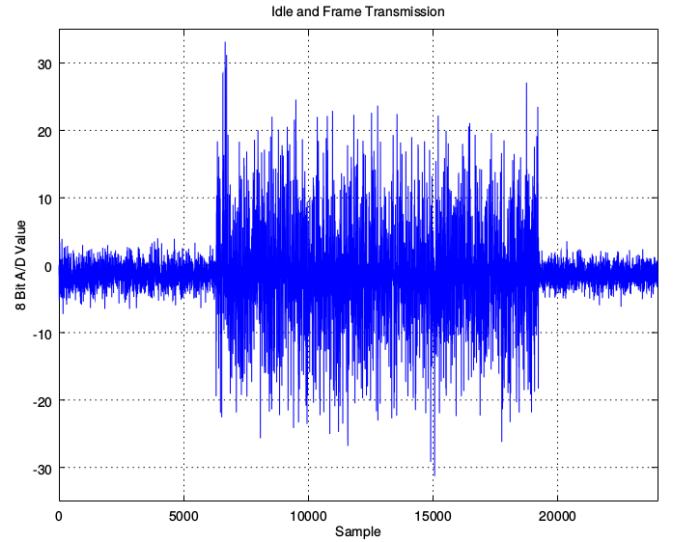


Fig. 4. Transmission of 101010.. with 1 kbit/s and idle state. Data from the Octave oscilloscope. Amplitude is quite low with an average of 12 % of the maximum, which is 127.5.

IV. EVALUATION

- A. Signal Strength Variation within the City
- B. Signal Strength Variation over Time
- C. Communication Performance

V. DISCUSSION

ACKNOWLEDGMENT

The authors would like to thank...

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