The textured plane

In an earlier assignment you wrote a program which loaded a *ppm* image and then mapped it onto a rectangular plane. Such an image is commonly called a *texture* and the process of mapping it onto a planar surface is called *texture mapping*.

We can incorporate this approach into the raytracer. The *textured plane* is simply a *finite plane* onto which a texture has been mapped. Both *tiled* and *fit* mode may be employed as shown in the following example entitled: "Philosophers at Dinner".



The image above includes 4 textured planes. For the curtains, the marble floor, the frame on which the photograph is mounted and the photograph. The texture is mapped in *tiled* mode for the frame and the floor. The curtains and the photograph itself are mapped in *fit* mode. Note specular refection of the wall and photograph show in the marble floor.

The textured plane definition

The textured plane definition requires two items of information beyond that of the finite rectangular plane: the name of the file containing the texture and the mapping mode. Mapping mode *I* means stretch the texture to *fit* the plane. Mapping mode *2* means repeatedly *tile* the texture.

```
17
                  textured plane
6.0 6.0 6.0
4.0 4.0 4.0
0.0 0.0 0.0
                  amb, diffuse, spec
                 amb, diffuse, spec
amb, diffuse, spec
                  normal
0 0 1
-8 -6 -4.2
                  point
1 0 0
                  xdir
24 18
                  width height
                 name of the texture file
marble.ppm
2
                  tile mode (1 means fit mode)
```

The tex plane inheritance structure

```
typedef struct obj type{
   void
           *priv;
} obj t;
typedef struct plane type{
   double normal[3];
  double double ndotq;
*priv;
   double point[3];
                          /* Used multiple times
                                                           */
                         /* Data for specialized types */
} plane t;
typedef struct fplane type {
   double xdir[3];
   double size[2];
   double lasthit[2];
                            /* data for specialized types */
   void
           priv;
} fplane t;
typedef struct texplane_type {
  int texmode; /* 1 -> fit and 2-> tile
                                                           */
   char
               texname[40]; /* name of .ppm file
                                                           */
   texture t *texture; /* pointer to texture struct */
} texplane t;
```

Loading a textured plane

The textured plane management functions *texplane_load*, *texplane_dump*, *texplane_amb*, *texplane_diff*, and *texplane_spec* should reside in a new module called *texplane.c*

```
obj t *texplane load(FILE *in, list t *lst, int objtype) {
   texplane t *texp;
   fplane t
                *fp;
   plane t
                *p;
   obj t
                *obj;
   int
                pcount;
                buf[256];
   char
/* Create fplane t, plane t, and obj t structures */
   obj = fplane load(in, lst, objtype);
   if (obj == NULL)
      return(NULL);
   recover pointer to fplane t structure
   malloc new texplane t and link it to fplane t
   set obj->hits to fplane hits
   set obj->getamb/getdiff to texplane getamb/getdiff
  read in texture file name and texture file mode.
   if (texture load(texp))
       return(NULL);
   return(obj);
}
```

Loading the texture

Determining the diffuse pixel color of the textured plane.

As was the case with the *tiled* plane, the real action occurs in *getamb/getdiff*. We will describe the action of the *getdiff()* function *texplane diff()*.

The basic idea is that the intensity returned will be the *product* of the object's reflectivity with the texel that maps to the hit point. The *texture_map()* function in *texture.c* is responsible for determining what *texel* maps to the hit point.

```
/**/
void texplane_diff(obj_t *obj, double *value){
   plane_t *pln = (plane_t *)obj->priv;
   fplane_t *fp = (fplane_t *)pln->priv;

   double texel[3];

   texture_map(fp, texel);
   compute product of reflectivity and texel
}
```

The texture map function

This mission of this function is to determine the *texel* which maps to the most recent hit point on the object. In general this would appear to be a difficult thing to do but, as with the finite plane, its not so hard if the textured plane is based at (0, 0, 0), has x direction (1, 0, 0), and normal (0, 0, 1).

Thus, to simulate this condition, we can simply use the "newhit" data that was computed in *fplane hits* and stored in *fp->lasthit[]* at the time the *hit* was found:

```
fp->lasthit[0] = newhit[0];
fp->lasthit[1] = newhit[1];
```

Acquiring the value of a texel is easy when the x and y offsets of the hit are expressed as a fractional percentage of the x and y dimensions of the texture. This is the main mission of the texture map() function.

```
int texture map(fplane t *fp, double *texel){
    recover pointers to the texplane t and the texture t
    if the texture mode is TEX FIT {
      compute the fractional x-offset, xfrac, of the texel as fp->lasthit[0] / fp->size[0]
      pass xfrac and yfrac to texel get()
   else /* mode is TEX TILE */{
       This mode is slightly more complicated because the size of the texture must be considered.
       There are two possible ways to do this: (1) convert the size of the texture to world
       coordinates or (2) map the fp->lasthit to pixel coordinates.
       Since we already have a map pix to world() function it might seem easier to use approach
       (1) but I recommend using approach (2) because it corresponds better to the approach
       suggested in you modern art maker. To do this you will need to build a
       map world to pix() function.
       Assuming you have done map world to pix(fp->lasthit, pixhit);
       Then xfrac = (double)(pixhit[0] \% texture -> size[0]) / texture size[0];
      pass xfrac and yfrac to texel get()
```

The texel get() function

This functions mission is to copy the contents of the texel at fractional position (xrel, yrel) into the texel passed as a parameter.

```
/*
     xrel- relative offset of [0.0, 1.0)
*
     yrel – within the texture
*/
void texel get(texture t *tex, double xrel, double yrel,
                 double texel[3]){
   unsigned char *texloc;
   int xtex;
                   /* x coordinate of the texel */
                    /* y coordinate of the texel */
   iny ytex;
   multiply x rel and y rel by respective texture dimensions getting xtex and ytex;
  compute offset, texloc, of the (ytex, xtex) in texture in the usual way
   texel[0] = *texloc / 255.0;
   texel[1] = *(texloc+1) / 255.0;
texel[2] = *(texloc+2) / 255.0;
}
```

Mapping world to pixel coordinates

You will note that information in the *proj_t* is required to map between pixel and world coordinates. Furthermore the *proj_t* structure is not passed down the diffuse and ambient lighting paths.

There are several ways (all somewhat ugly) to work around this:

- (1) pass a pointer to the *proj_t* from *mk_image()* through *raytrace()* through *diffuse illumination()*....
- (2) in module *proj.c* where the mapping functions should reside (I am aware some have wandered off into other files) create a *static proj_t* *p; that is *not* in the body of any function. Initialize it to point to the *proj_t* structure in *projection_init()*. Then use this pointer to access the *proj_t* structure in *map world to pix()*.
- (3) Add *pix_x_size* and *pix_y_size* elements to the *fplane_t* structure. Then hack a patch into *model_load()* (which does hold a reference to the *proj_t*), Each time a *texplane_t* is loaded, the patch can compute the values of *pix_x_size* and *pix_y_size*.

The third method is the one I used in my C++ version since I already had to have the *case* structure in place anyway.

```
83 case TEX_PLANE:

84 /* fprintf(stderr, "Loading finite pln\n"); */

85 texplane = new texplane_t(in, out, objtype, objid);

86 texplane->set_pixsize(proj->pix_x_size, proj->pix_y_size);

87 list->add(texplane);

88 break;
```

In my C version I decided that option (2) was the easiest and least intrusive.