

# Tree sort

A **tree sort** is a sort algorithm that builds a binary search tree from the elements to be sorted, and then traverses the tree (in-order) so that the elements come out in sorted order. Its typical use is sorting elements online: after each insertion, the set of elements seen so far is available in sorted order.

## Efficiency

Adding one item to a binary search tree is on average an  $O(\log n)$  process (in big O notation). Adding  $n$  items is an  $O(n \log n)$  process, making tree sorting a 'fast sort' process. Adding an item to an unbalanced binary tree requires  $O(n)$  time in the worst-case: When the tree resembles a linked list (degenerate tree). This results in a worst case of  $O(n^2)$  time for this sorting algorithm. This worst case occurs when the algorithm operates on an already sorted set, or one that is nearly sorted, reversed or nearly reversed. Expected  $O(n \log n)$  time can however be achieved by shuffling the array, but this does not help for equal items.

The worst-case behaviour can be improved by using a self-balancing binary search tree. Using such a tree, the algorithm has an  $O(n \log n)$  worst-case performance, thus being degree-optimal for a comparison sort. However, trees require memory to be allocated on the heap, which is a significant performance hit when compared to quicksort and heapsort. When using a splay tree as the binary search tree, the resulting algorithm (called splaysort) has the additional property that it is an adaptive sort, meaning that its running time is faster than  $O(n \log n)$  for inputs that are nearly sorted.

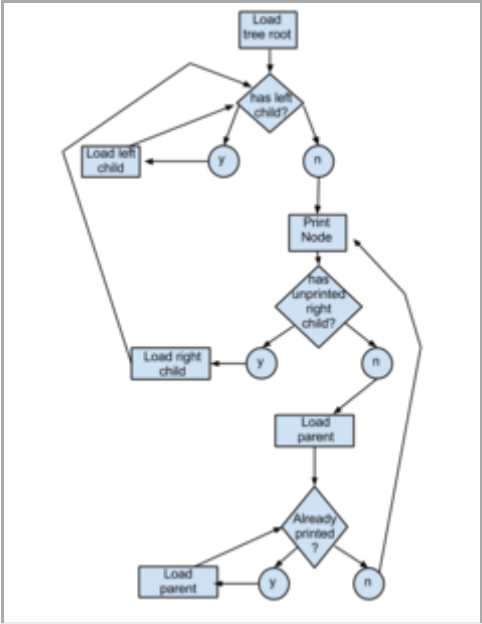
## Example

The following tree sort algorithm in pseudocode accepts a collection of comparable items and outputs the items in ascending order:

```
STRUCTURE BinaryTree
  BinaryTree:LeftSubTree
  Object:Node
  BinaryTree:RightSubTree

PROCEDURE Insert(BinaryTree:searchTree, Object:item)
  IF searchTree.Node IS NULL THEN
    SET searchTree.Node TO item
  ELSE
    IF item IS LESS THAN searchTree.Node THEN
      Insert(searchTree.LeftSubTree, item)
    ELSE
```

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<b>Class</b>	Sorting algorithm
<b>Data structure</b>	Array
<b>Worst-case performance</b>	$O(n^2)$ (unbalanced) $O(n \log n)$ (balanced)
<b>Best-case performance</b>	$O(n \log n)$
<b>Average performance</b>	$O(n \log n)$
<b>Worst-case space complexity</b>	$\Theta(n)$

```

        Insert(searchTree.RightSubTree, item)

PROCEDURE InOrder(BinaryTree:searchTree)
  IF searchTree.Node IS NULL THEN
    EXIT PROCEDURE
  ELSE
    InOrder(searchTree.LeftSubTree)
    EMIT searchTree.Node
    InOrder(searchTree.RightSubTree)

PROCEDURE TreeSort(Collection:items)
  BinaryTree:searchTree

  FOR EACH individualItem IN items
    Insert(searchTree, individualItem)

  InOrder(searchTree)

```

In a simple functional programming form, the algorithm (in Haskell) would look something like this:

```

data Tree a = Leaf | Node (Tree a) a (Tree a)

insert :: Ord a => a -> Tree a -> Tree a
insert x Leaf = Node Leaf x Leaf
insert x (Node t y s)
  | x <= y = Node (insert x t) y s
  | x > y  = Node t y (insert x s)

flatten :: Tree a -> [a]
flatten Leaf = []
flatten (Node t x s) = flatten t ++ [x] ++ flatten s

treesort :: Ord a => [a] -> [a]
treesort = flatten . foldr insert Leaf

```

In the above implementation, both the insertion algorithm and the retrieval algorithm have  $O(n^2)$  worst-case scenarios.

## External links

- [Binary Tree Java Applet and Explanation \(https://web.archive.org/web/20161129234513/http://qmatica.com/DataStructures/Trees/BST.html\)](https://web.archive.org/web/20161129234513/http://qmatica.com/DataStructures/Trees/BST.html) at the [Wayback Machine](#) (archived 29 November 2016)
- [Tree Sort of a Linked List \(http://www.martinbroadhurst.com/articles/sorting-a-linked-list-by-turning-it-into-a-binary-tree.html\)](http://www.martinbroadhurst.com/articles/sorting-a-linked-list-by-turning-it-into-a-binary-tree.html)
- [Tree Sort in C++ \(http://www.martinbroadhurst.com/cpp-sorting.html#tree-sort\)](http://www.martinbroadhurst.com/cpp-sorting.html#tree-sort)

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