The Laplace Transform

The haplace transform of the signal X(t) is defined as

$$X(s) = \int_{-\infty}^{\infty} \chi(t) e^{-st} dt \qquad - D$$

X(S) is a function of the complex variable $S = \sigma + jw$. The range of values of S for which the integral in eqn. D converges is referred to as the region of convergence (ROC) of the Leplace transform.

This is the Fourier transform of $\chi(t)$. $\left| \chi(s) \right|_{s=j\omega} = \Im \left\{ \chi(t) \right\} - 2$

$$X(s) = \int_{0}^{\infty} g^{-(s+a)t} dt$$

with s= o+jw

$$X(\sigma+j\omega) = \int_{0}^{\infty} e^{-(\sigma+a)t} e^{-j\omega t} dt$$

which corresponds to the Fourier transform of $e^{-(\sigma+a)t}\mu(t)$.

$$X(\sigma+j\omega) = \frac{1}{(\sigma+a)+j\omega}$$
, $\sigma+a>0$

Since $S = \sigma + j\omega$ and $\sigma = Re\{s\}$ we have

$$X(s) = \frac{1}{5+a}$$
, $Re\{s\} > -a$.

If a >0 then X(S) converges for 0 =0.

$$\times (0+j\omega) = \frac{1}{a+j\omega}$$

with $\sigma=0$, the haplace transform is equal to the Fourier transform. If $\alpha \leq 0$, the haplace

transform seists but the Fourier transform does not.

Example 2
$$X(t) = -at \mu(-t)$$

$$X(s) = -\int_{-\infty}^{\infty} e^{-at} \mu(-t) e^{-st} dt$$

$$= -\int_{-\infty}^{\infty} e^{-(s+a)t} dt$$

$$X(s) = \frac{1}{s+a}, Re\{s\} < -a.$$

Note that the algebraic expression for the haplace transform of 2 at 11(t) is also \$\frac{1}{5+a}\$. However the ROC for the haplace transform of 2-at 11(t) is different. To specify the haplace transform of a signal both the algebraic expression and the ROC are required.

Example 3
$$X(t) = e^{-t} u(t) + e^{-3t} u(t)$$

$$X(s) = \int_{-\infty}^{\infty} \left[e^{-t} u(t) + e^{-3t} u(t) \right] e^{-st} dt$$

$$= \int_{0}^{\infty} e^{-(s+1)t} dt + \int_{0}^{\infty} e^{-(s+3)t} dt$$

$$= \frac{1}{s+1} + \frac{1}{s+3}, Re\{s\} > -1$$

$$= \frac{s+3+s+1}{(s+1)(s+3)}, Re\{s\} > -1.$$

$$\chi(s) = \frac{2(s+2)}{(s+1)(s+3)}$$
, Re $\{s\} > -1$.

Pole / Zero Diegram

In examples 1, 2, and 3 the Laplace transform is a ratio of polynomials in the complex variable S. that is $X(s) = \frac{N(s)}{D(s)}$, for S in ROC.

$$X(s) = \frac{N(s)}{D(s)}$$
, for s in ROC

The roots of the numerator polynomial N(S) are
called the zero of the haplace transform
because $\chi(s) = 0$ for those values of s .
The roots of the denominator polynomial D(S)
are called the poles of X(5) and for those
values of S, X(S) is infinite.
From example 3 we have
$\chi(s) = \frac{2(s+2)}{(s+1)(s+3)}, Re\{s\} > -1.$
The pole / zero plot of X(S) is shown below.
-3 -2 -1

The shooted region is the ROC.

ROC for rational Laplace transforms

Right - Sided Signals

a right - sided signal satisfies the condition X(t) = 0, t < t, for some finite value of t,

of X(s) exists the ROC is of the form

 $Re\{S\} > \sigma_{max}$

where mese is the massimum, part of the poles of X(5). X(5) converges to the right of the vertical line Re{S} = o more in the S-plane. The ROC is the region in the 5-plane to the right of the rightmost pole.

left - Sided Signals

a left - sided signal satisfies the condition $\chi(t) = 0$, $t > t_2$, for some finite value t_2 . of X(5) exists the ROC is of the form

Re $\{S\}$ < σ min

where σ_{min} is the minimum real part of the place of X(S) X(S) converges to the left of the vertical line $Re\{S\} = \sigma_{min}$ in the S-plane. The ROC is the region in the S-plane to the left of the left of the left of the left of the left.

Two-Sided Signals

a signal that is neither right-sided nor left-sided is called two-sided. If X(s) exists the ROC is of the form $\sigma_1 < Re\{s\} < \sigma_2$

where σ , and σ_2 are the real parts of two of the poles. The ROC is a vertical strip in the s-plane between the vertical lines $Re\{s\} = \sigma$, and $Re\{s\} = \sigma_2$.

Let X,(t)=X(t) U(t-to) and Xz(t) = X(t) U(-t+to) for any value of to where an impulse does not occur. X,(t) is a right-sided signal and $X_1(S)$ converges for Re $\{S\} > 0$, X2(t) is a left-sided signal and X2(5) converges for Re $\{s\}$ $< \sigma_2$. $X(s) = X_1(s) + X_2(s)$ converges if $\sigma_2 > \sigma_1$. He ROC is $\sigma_1 < Re\{s\} < \sigma_2$. The Inverse haplace Transform $X(\sigma+j\omega) = \int_{-\infty}^{\infty} \left[\chi(t) e^{-\sigma t} \right] e^{-j\omega t} dt$ $\exists \exists \{\chi(t) e^{-\sigma t}\}$ $X(t)2^{-\sigma t} = \exists^{-1} \{ \chi(\sigma + j\omega) \}$ $=\frac{1}{2\pi}\int_{-\infty}^{\infty}X(\sigma+j\omega)e^{j\omega t}d\omega$

multiplying both sides by 2°t, we obtain $X(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\sigma + j\omega) e^{(\sigma + j\omega)t} d\omega$ Make the substitution $5 = \sigma + j\omega$ and $dS = jd\omega$. $\chi(t) = \frac{1}{2\pi i} \int_{\sigma - j\infty}^{\sigma + j\infty} \chi(s) e^{St} ds$ This is a contour integral in the 5-plane. The contour of integration is a vertical line from o -jos to o +jos. This vertical line must be in the ROC of X(5). For rational haplace transforms we do not need to sistuate this integral. Instead we will obtain a partial fraction for X(5) and determine the inverse haplace transform of each

of the lower order terms.

Example 4

Invert each of the following

haplace transforms:

(a)
$$X_{1}(s) = \frac{1}{s^{2}+3s+2}$$
, Re $\{s\}>-1$

(b)
$$X_2(s) = \frac{1}{5^2 + 3S + 2}, -2 < Re\{s\} < -1$$

(c)
$$X_3(s) = \frac{1}{s^2 + 3s + 2}$$
, Re{s} < -2.

(a)
$$\chi_1(s) = \frac{1}{(s+1)(s+2)}$$
, $Re\{s\} > -1$

$$X_1(s) = \frac{A}{s+1} + \frac{B}{s+2}$$
, Re{s} >-1

where
$$A = [(S+1)X_1(S)]_{S=-1} = 1$$

and
$$B = [(s+2)X,(s)]_{s=-2} = -1$$

$$X_{1}(s) = \frac{1}{s+1} - \frac{1}{s+2}, Re\{s\} > -1$$

$$X_{1}(t) \iff X_{1}(s)$$

$$X_{1}(t) \text{ is a right-sided signal.}$$

$$From \text{ Example } 1 \text{ we have}$$

$$e^{-t} \text{ wit}) \iff \frac{1}{s+1}, Re\{s\} > -1$$

$$e^{-2t} \text{ wit}) \iff \frac{1}{s+2}, Re\{s\} > -2$$

$$X_{1}(t) = \left[e^{-t} - e^{-2t}\right] \text{ wit}$$

$$X_{2}(s) = \frac{1}{s+1} - \frac{1}{s+2}, -2 < Re\{s\} < -1$$

$$X_{2}(t) \iff X_{2}(s)$$

$$X_{2}(t) \text{ is a two-sided signal.}$$

$$-e^{-2t} \text{ wit}) \iff -\frac{1}{s+2}, Re\{s\} > -2$$

From Example 2 we have
$$-\ell^{-t} \mathcal{U}(-t) \iff \frac{1}{S+1}, Re\{s\} < -1$$

$$\chi_{2}(t) = -\ell^{-2t} \mathcal{U}(t) - \ell^{-t} \mathcal{U}(-t)$$

$$(c) \quad \chi_{3}(s) = \frac{1}{S+1} - \frac{1}{S+2}, \quad Re\{s\} < -2$$

$$\chi_{3}(t) \iff \chi_{3}(s)$$

$$\chi_{3}(t) \text{ is a left-sided signal.}$$

$$-\ell^{-t} \mathcal{U}(-t) \iff \frac{1}{S+1}, Re\{s\} < -1$$

$$\ell^{-2t} \mathcal{U}(-t) \iff -\frac{1}{S+1}, Re\{s\} < -2$$

$$-\ell^{-1}\mu(-t) \iff \frac{1}{S+1}, Re\{S\} < -1$$

$$\ell^{-2t}\mu(-t) \iff -\frac{1}{S+2}, Re\{S\} < -2$$

$$\chi_3(t) = \left[\ell^{-2t} - \ell^{-t}\right]\mu(-t)$$

Properties of the haplace Transform

$$X(t) \iff X(s) \text{ with } ROC = R$$

$$X_1(t) \iff X_1(s) \text{ with } ROC = R_1$$

$$X_2(t) \iff X_2(s) \text{ with } ROC = R_2$$

dinearity

$$a \times_{1}(t) + b \times_{2}(t) \iff a \times_{1}(s) + b \times_{2}(s)$$

with ROC containing R, NR₂.

Jime Shift $\chi(t-t_0) \iff \ell^{-st_0} \chi(s) \text{ with } ROC = R$

June Scaling $\chi(at) \longleftrightarrow \frac{1}{|a|} \times \left(\frac{s}{a}\right) \text{ with } Roc = aR$

Convolution of Signals $X_{1}(t) * X_{2}(t) \iff X_{1}(s) X_{2}(s) \text{ with ROC}$ $\text{containing R, NR}_{2}$

Modulation

$$e^{sot} \chi(t) \iff \chi(s-s_0) \text{ with ROC} = R+Re\{s_0\}$$

Differentiation

$$\frac{dX(t)}{dt} \implies SX(S) \text{ with ROC containing R.}$$

Integration

$$\int_{-\infty}^{t} \chi(z) dz \iff \int_{S} \chi(s) \text{ with } Roc$$
 containing $R \cap \{Re\{s\}>0\}$

Initial - and Final - Value Theorems

If X(t) = 0 for t < 0 and X(t) contains no impulses or higher - order singularities at t = 0, then

$$\lim_{t\to 0^+} \chi(t) = \lim_{s\to \infty} s\chi(s)$$

$$\lim_{t\to\infty} x(t) = \lim_{s\to 0} s \times (s)$$