1. Let r(t) and u(t) denote the unit-ramp and unit-step signals respectively. Sketch and label each of the following signals:

(a)
$$x_1(t) = r(-t)$$

(b)
$$x_2(t) = 3r(2-t)$$

(c)
$$x_3(t) = 2u(t-1) - u(t-2)$$

(d)
$$x_4(t) = \frac{dx_3(t)}{dt}$$

(e)
$$x_5(t) = t [u(t+1) - u(t-3)]$$

(f)
$$x_6(t) = \frac{dx_5(t)}{dt}$$

(g)
$$x_7(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT)$$

2. Determine whether each of the following systems is (i) linear and (ii) time-invariant:

(a)
$$y(t) = t x(t)$$

(b)
$$y(t) = x^2(t)$$

(c)
$$y(t) = x(t) + 1$$

3. The following are impulse responses of continuous-time LTI systems. Determine whether each system is (i) causal and (ii) stable. Justify your answers.

(a)
$$h(t) = e^{-2t} u(t-1)$$

(b)
$$h(t) = e^t u(-1 - t)$$

(c)
$$h(t) = u(t)$$

4. Consider an LTI system whose input x(t) and output y(t) are related by

$$y(t) = x(t - t_0),$$

where t_0 is a constant. Determine the impulse response of the system.

5. Consider an LTI system with impulse response $h(t) = \delta(t-1) - \delta(t-3)$. Determine and sketch the step-response, s(t), of the system.