



| Perturbation Theory   |
|---|
| <div>★ <math>H = H_0 + \lambda V</math>, with <math>H_0 \left  \phi_n \right\rangle = \epsilon_n \left  \phi_n \right\rangle</math> known, <math>\lambda \in \mathbb{R}^+</math>.</div> <div>★ <math>H \left  \psi_n \right\rangle = E_n \left  \psi_n \right\rangle</math> eigenspectrum unknown. The solution in the limit of small <math>\lambda</math> is <math>\left  \psi_n \right\rangle = \left  \phi_n \right\rangle + \lambda \left  \psi_n^{(1)} \right\rangle + \lambda^2 \left  \psi_n^{(2)} \right\rangle + \dots</math><br/> <math>E_n = \epsilon_n + \lambda E_n^{(1)} + \lambda^2 E_n^{(2)} + \dots</math></div> <div>★ S.E.: <math>(H_0 + \lambda V)(\left  \phi_n \right\rangle + \lambda \left  \psi_n^{(1)} \right\rangle + \lambda^2 \left  \psi_n^{(2)} \right\rangle + \dots) = (\epsilon_n + \lambda E_n^{(1)} + \lambda^2 E_n^{(2)} + \dots)(\left  \phi_n \right\rangle + \lambda \left  \psi_n^{(1)} \right\rangle + \lambda^2 \left  \psi_n^{(2)} \right\rangle + \dots)</math> must be satisfied at each order in <math>\lambda</math></div>  |
| Non-degenerate Time-Independent Perturbation Theory   |
| <div>★ <b>Zero-th order</b> <math>H_0 \left  \phi_n \right\rangle = \epsilon_n \left  \phi_n \right\rangle</math> unperturbed eigenvalue problem</div> <div>★ <b>1st order</b> <math>E_n^{(1)} = \left\langle \phi_n \left  V \right  \phi_n \right\rangle</math>; <math>\left  \psi_n^1 \right\rangle = \sum_{m \neq n} \frac{\left\langle \phi_m \left  V \right  \phi_n \right\rangle}{\epsilon_n - \epsilon_m} \left  \phi_m \right\rangle</math></div> <div>★ <b>2nd order</b> <math>E_n^{(2)} = \sum_{m \neq n} \frac{\left  \left\langle \phi_m \left  V \right  \phi_n \right\rangle \right ^2}{\epsilon_n - \epsilon_m}</math>; for approx. to be val. <math>\left  E_n^{(2)} \right  \ll \left  E_n^{(1)} \right </math></div> <div>★ satisfied as long as <math>\frac{1}{\Delta} (\left\langle \phi_n \left  V^2 \right  \phi_n \right\rangle - \left\langle \phi_n \left  V \right  \phi_n \right\rangle^2) \ll \left\langle \phi_n \left  V \right  \phi_n \right\rangle</math>,<br/> <math>\Delta = \min_m \left  \epsilon_n - \epsilon_m \right </math> or more restrictive: <math>\left  \frac{\left\langle \phi_m \left  V \right  \phi_n \right\rangle}{\epsilon_n - \epsilon_m} \right  \ll 1</math></div> |
| Degenerate Time-Independent Perturbation Theory   |
| <div>★ <math>n</math>th energy state has <math>N</math>-fold degeneracy <math>\Rightarrow H_0</math> has energy <math>\epsilon_n</math> with <math>\phi_{n_i}, i = 1 \dots N</math></div> <div>★ <math>\sum_j V_{ij} c_j = E_n^{(1)} c_i \iff \hat{V} \mathbf{c} = E_n^{(1)} \mathbf{c}</math> <math>V_{ij} = \left\langle \phi_{n_i} \left  V \right  \phi_{n_j} \right\rangle</math><br/> eigenvalue problem, must diagonalise <math>V</math> matrix (in the degenerate subspace only!)</div> <div>★ The eigenvectors are the corrected eigenstates (to 0th order), the eigenvalues are the 1st order correction to energy. If eigenvalues are the same, degeneracy is not lifted.</div>  |
| <div>★ E.g. <math>V = \begin{pmatrix} 0 &amp; \alpha &amp; 0 &amp; 0 \\ \alpha &amp; 0 &amp; 0 &amp; 0 \\ 0 &amp; 0 &amp; 0 &amp; 0 \\ 0 &amp; 0 &amp; 0 &amp; 0 \end{pmatrix} \xrightarrow{\text{diag}} \alpha, \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \\ 0 \end{pmatrix}; -\alpha, \begin{pmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \\ 0 \\ 0 \end{pmatrix}; 0, \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}; 0, \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}</math></div> <div>Thus <math>\left  0 \right\rangle \rightarrow \frac{1}{\sqrt{2}} (\left  0 \right\rangle + \left  1 \right\rangle)</math>; <math>\left  1 \right\rangle \rightarrow \frac{1}{\sqrt{2}} (\left  0 \right\rangle - \left  1 \right\rangle)</math>; <math>\left  2 \right\rangle, \left  3 \right\rangle</math> unchanged</div> <div>The corrected eigenstates have an energy correction <math>E^{(1)}</math> of <math>\alpha, -\alpha, 0, 0</math>.</div>   |
| Time-Dependent Hamiltonians   |
| <div>★ <math>U(t, t_0) = \mathbb{I} + \sum_{n=1}^{\infty} \frac{(-1)^n}{n!} \int_{t_0}^t dt_1 \int_{t_0}^{t_1} dt_2 \dots \int_{t_0}^{t_{n-1}} dt_n T(H(t_1) \dots H(t_n))</math><br/> where <math>T[H(t_1)H(t_2) \dots H(t_n)] = H(t_{i_1})H(t_{i_2}) \dots H(t_{i_n}), t_{i_1} \geq t_{i_2} \geq \dots</math></div> <div>★ Alternatively: <math>U(t, t_0) \approx \sum_j \exp(iH(t_j)\delta t)</math> with an error of <math>\left  \int_{t_0}^t ds H(s) - \delta t \sum_{r=1}^{n_t} H(t_0 + r\delta t) \right ^2</math> (discretisation)</div>   |
| Interaction picture   |
| <div>★ Schrödinger picture: <math>i \frac{\partial}{\partial t} \left  \phi_S(t) \right\rangle = H(t) \left  \phi_S(t) \right\rangle, \quad O_S(t) = O_S</math></div> <div>★ Heisenberg picture: <math>O_H(t) = U_S(t, t_0)^\dagger O_S U_S(t, t_0), \quad \left  \phi_H(t) \right\rangle = \left  \phi_S(t_0) \right\rangle</math></div> <div>★ Interaction picture: <math>H(t) = H_H + V_S(t)</math>,</div> <div>★ <math>O_I(t) = e^{iH_0(t-t_0)} O_S(t) e^{-iH_0(t-t_0)}</math></div> <div>★ <math>\left  \phi_I(t) \right\rangle = U_I(t, t_0) \left  \phi_I(t_0) \right\rangle, \quad U_I = e^{iH_0(t-t_0)} U_S(t, t_o)</math></div> <div>★ <math>\frac{\partial U_I}{\partial t} = -iV_I(t)U_I(t, t_0)</math></div>   |
| Time-Dependent Perturbation Theory  |
| <div>★ <math>U_I(t, t_0) \approx \mathbb{I} - i \int_{t_0}^t dt_1 V_I(t_1) + \dots</math></div> <div>★ The exact transition probability between two states is <math>\left  \left\langle \psi \left  \phi \right\rangle \right ^2</math></div> <div>★ <math>P_{i \rightarrow n}(t) = \left  \left\langle n \left  \phi_S(t) \right\rangle \right ^2 = \left  \left\langle n \left  U_I(t, t_0) \right  i \right\rangle \right ^2 = \left  -i \int_{t_0}^t dt_1 e^{i(E_n - E_i)(t-t_0)} \left\langle n \left  V(t_1, t_0) \right  i \right\rangle \right ^2</math> general expression of <b>transition probabilities</b> between eigenstates <math>\left  i \right\rangle</math> and <math>\left  n \right\rangle</math> of <math>H_0</math>. Note: if <math>V = 0</math> then a system in an eigenstate stays in an aigenstate.</div> <div>★ For a constant potential <math>P_{i \rightarrow n}(t) \xrightarrow{t \rightarrow \infty} 2\omega t \left  \left\langle n \left  V \right  i \right\rangle \right ^2 \delta(E_n - E_i)</math><br/> <math>\frac{\partial}{\partial t} P_{i \rightarrow n}(t) = 2\pi \left  \left\langle n \left  V \right  i \right\rangle \right ^2 \delta(E_n - E_i)</math></div>                 |

| Variational method  |
|---|
| <div>★ <math>\frac{\left\langle \psi \left  H \right  \psi \right\rangle}{\left\langle \psi \left  \psi \right\rangle} \geq E_0</math> <b>Variational principle</b></div> <div>★ The idea is to come up with a parameterised guess for the state <math>\left  \psi \right\rangle</math>, and then we use the variational principle to find the parameter values that minimize <math>\psi</math>. It generalises to excited states orthogonal to the ground state <math>\phi_0</math> (i.e. <math>\left\langle \phi_0 \left  \psi \right\rangle = 0</math>) by replacing <math>E_0</math> with <math>E_1</math>. Limitation: the ground state should be known to ensure it is orthogonal to the excited state.</div> <div>★ Steps: compute <math>\frac{\left\langle \psi \left  H \right  \psi \right\rangle}{\left\langle \psi \left  \psi \right\rangle} = E(a)</math> then minimise <math>E</math> with respect to the parameter.</div> |

| Particle in a box  |
|--|
| <div>★ <math>V(x) = \begin{cases} 0 &amp; \text{if }  x  \leq L/2 \\ \infty &amp; \text{else} \end{cases} \quad \phi_n(x) = \begin{cases} \sqrt{\frac{2}{L}} \cos(\frac{n\pi}{L}x) &amp; n \text{ odd} \\ \sqrt{\frac{2}{L}} \sin(\frac{n\pi}{L}x) &amp; n \text{ even} \end{cases}</math></div> <div>★ <math>E_n = n^2 \frac{\pi^2 \hbar^2}{2mL^2}</math></div>   |
| Harmonic oscillator  |
| <div>★ <math>H = \frac{1}{2m} \hat{p}^2 + \frac{1}{2} m \omega^2 \hat{x}^2 = \hbar \omega (\hat{N} + \frac{1}{2}), \quad \hat{N} = \hat{a}^\dagger \hat{a} \quad \star \hat{p}^2 = -\frac{\hbar^2}{2m} \frac{d^2}{dx^2}</math></div> <div>★ <math>\hat{a} = \sqrt{\frac{m\omega}{2\hbar}} \left( \hat{x} + \frac{i\hat{p}}{m\omega} \right) \quad \hat{a}^\dagger = \sqrt{\frac{m\omega}{2\hbar}} \left( \hat{x} - \frac{i\hat{p}}{m\omega} \right)</math></div> <div>★ <math>\hat{x} = \sqrt{\frac{\hbar}{2m\omega}} (\hat{a} + \hat{a}^\dagger) \quad \hat{p} = i\sqrt{\frac{m\omega\hbar}{2}} (\hat{a}^\dagger - \hat{a})</math></div> <div>★ <math>[\hat{x}, \hat{p}] = i\hbar, \quad [\hat{a}, \hat{a}^\dagger] = 1, \quad [\hat{N}, \hat{a}] = -\hat{a}, \quad [\hat{N}, \hat{a}^\dagger] = \hat{a}^\dagger</math></div> <div>★ <math>\phi_0(x) = \left( \frac{m\omega}{\phi\hbar} \right)^{1/4} \exp\left(-\frac{m\omega}{2\hbar} x^2\right)</math></div> <div>★ <math>\phi_n = \frac{1}{\sqrt{n!}} (a^\dagger)^n \phi_0 = \frac{1}{\sqrt{2^n n!}} \left( \frac{m\omega}{\pi\hbar} \right)^{1/4} e^{-\frac{m\omega x^2}{2\hbar}} H_n\left(\sqrt{\frac{m\omega}{\hbar}} x\right)</math><br/> with <math>H_n(z) = (-1)^n e^{z^2} \frac{d^n}{dz^n} (e^{-z^2})</math></div> <div>★ <math>\hat{H} \phi_n = E_n \phi_n = \hbar \omega (n + \frac{1}{2}) \phi_n</math></div> <div>★ <math>\hat{a}^\dagger \phi_n = \sqrt{n+1} \phi_{n+1} \quad \hat{a} \phi_n = \sqrt{n} \phi_{n-1}</math></div> |
| Hermitian and unitary operators  |
| <div>★ Hermitian operator: <math>M = M^\dagger \longrightarrow</math> diagonalisable with real eigenvalues, linear</div> <div>★ Unitary operators: <math>UU^\dagger = U^\dagger U = \mathbb{I} \longrightarrow \left\langle \psi \left  U^\dagger U \right  \psi \right\rangle = \mathbb{I}</math> and linear</div>  |
| Tensor product   |
| <div>★ <math>\begin{pmatrix} a \\ b \end{pmatrix} \otimes \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \begin{pmatrix} a\alpha &amp; a\beta &amp; b\alpha &amp; b\beta \end{pmatrix}^T</math></div> <div>★ <math>A \otimes B = \begin{pmatrix} A_{11}B &amp; A_{12}B \\ A_{21}B &amp; A_{22}B \end{pmatrix} \quad \star A \oplus B = \begin{pmatrix} A &amp; 0 \\ 0 &amp; B \end{pmatrix}</math></div> <div>★ <math>R(g)^{\otimes k} = R(g) \otimes \dots \otimes R(g) \quad \star \bigoplus_k R(g) = (R \oplus \dots \oplus R)(g)</math></div> <div>★ <math>f(\hat{A} \otimes \hat{B}) \left  a \right\rangle \left  \phi \right\rangle = \left  a \right\rangle \otimes f(a\hat{B}) \left  \phi \right\rangle</math></div> <div>★ <math>[A \otimes \mathbb{I}, \mathbb{I} \otimes B] = 0 \quad \star \{A \otimes \mathbb{I}, \mathbb{I} \otimes B\} = 2A \otimes B</math></div> <div>★ <math>e^{A+B} = e^A e^B</math> if <math>[A, B] = 0 \implies e^{A \otimes \mathbb{I} + \mathbb{I} \otimes B} = e^A \otimes e^B</math></div>   |
| Trigonometry   |
| <div>★ <math>\cos(a+b) = \cos(a)\cos(b) - \sin(a)\sin(b) \quad \star \sin(2a) = 2\sin a \cos a</math></div> <div>★ <math>\sin(a+b) = \sin(a)\cos(b) + \cos(a)\sin(b) \quad \star \cos(2a) = \cos^2 a - \sin^2 a</math></div> <div>★ <math>2\sin(a)\sin(b) = \cos(a-b) - \cos(a+b) \quad \star \sin(a/2) = \pm \sqrt{(1 - \cos(a))/2}</math></div> <div>★ <math>2\cos(a)\cos(b) = \cos(a+b) + \cos(a-b) \quad \star \cos(a/2) = \pm \sqrt{(1 + \cos(a))/2}</math></div> <div>★ <math>2\cos(a)\sin(b) = \sin(a+b) - \sin(a-b) \quad \star \sin^2 a = (1 - \cos 2a)/2</math></div> <div>★ <math>\cos(a) + \cos(b) = 2\cos((a+b)/2)\cos((a-b)/2) \quad \star \cos^2 a = (1 + \cos 2a)/2</math></div> <div>★ <math>\sin(a) + \sin(b) = 2\sin((a+b)/2)\cos((a-b)/2)</math></div> <div>★ <math>\cos(a) - \cos(b) = -2\sin((a+b)/2)\sin((a-b)/2)</math></div>  |
| Some useful integrals  |
| <div>★ <math>\int_{-\infty}^{+\infty} dx e^{-\alpha^2(x+\beta)^2+Bx} = \frac{\sqrt{\pi}}{\alpha} e^{\frac{B^2}{4\alpha^2}-B\beta}</math> with <math>\text{Re}(\alpha^2) \geq 0, B, \beta \in \mathbb{C}</math></div> <div>★ <math>\int_{-\infty}^{+\infty} dx x^n e^{-\frac{1}{2}Ax^2} = \begin{cases} (n-1)!!\sqrt{2\pi} A^{-\frac{n+1}{2}} &amp; \text{If n is even} \\ 0 &amp; \text{If n is odd} \end{cases}</math></div> <div>★ <math>\int_0^T \sin^2(\frac{x\pi}{T}) dx = \frac{T}{2}</math> and same with <math>\cos^2</math></div>   |

Group Theory

- ★ **Group:** Set  $G$  equipped with operation  $*$  such that
  - $G$  closed under  $*$ , i.e. if  $a, b \in G$  then  $a * b \in G$
  - Associative:  $\forall a, b, c \in G$  one has  $(a * b) * c = a * (b * c)$
  - Has identity, i.e an element  $e$  such that  $e * a = a \forall a \in G$
  - Has inverse, i.e.  $\forall a \in G$  it exists  $b \in G$  such that  $b * a = a * b = e$ . ( $b = a^{-1}$ )

★ Any unitary that leaves a property invariant forms a group with  $*$  matrix multiplicative.

★ **Finite group:** A group that contains a finite number of elements (the group order).

★ Order 1 group (the only one, trivial group):

|   |       |
|---|-------|
| * | e     |
| e | e     |
| * | e a   |
| e | e a   |
| a | a e   |
| * | e a b |
| e | e a b |
| a | a b e |
| b | b e a |

★ Order 2: parity group

★ The unique order 3 group is the cyclic  $\mathbb{Z}_3$  group

★ Order 4 has cyclic and symmetry of a rectangle

|                |                |                |                |                |                |                |
|----------------|----------------|----------------|----------------|----------------|----------------|----------------|
| *              | e              | a              | a <sup>2</sup> | b              | c              | d              |
| e              | e              | a              | a <sup>2</sup> | b              | c              | d              |
| a              | a              | a <sup>2</sup> | e              | c              | d              | b              |
| a <sup>2</sup> | a <sup>2</sup> | e              | a              | d              | b              | c              |
| b              | b              | d              | c              | e              | a <sup>2</sup> | a              |
| c              | c              | b              | d              | a              | e              | a <sup>2</sup> |
| d              | d              | c              | b              | a <sup>2</sup> | a              | e              |

★ Order 6 has cyclic group  $\mathbb{Z}_6$  and the C3v group (on the right)

|                  |                  |                |                |     |                  |
|------------------|------------------|----------------|----------------|-----|------------------|
| *                | e                | a <sup>1</sup> | a <sup>2</sup> | ... | a <sup>n-1</sup> |
| *                | e                | a <sup>1</sup> | a <sup>2</sup> | ... | a <sup>n-1</sup> |
| a <sup>1</sup>   | a <sup>1</sup>   | a <sup>2</sup> | a <sup>3</sup> | ... | e                |
| a <sup>2</sup>   | a <sup>2</sup>   | a <sup>3</sup> | a <sup>4</sup> | ... | a <sup>1</sup>   |
| ⋮                |                  |                |                |     |                  |
| a <sup>n-1</sup> | a <sup>n-1</sup> | e              | a <sup>1</sup> | ... | a <sup>n-2</sup> |

- ★ Symmetric permutation group  $S_n$  (all possible permutations of  $n$  objects)  
e.g.  $S_3 = \{I, \text{SWAP}_{12}, \text{SWAP}_{13}, \text{SWAP}_{23}, \text{CYCLE}_{123}, \text{CYCLE}_{321}\}$  isomorphic to C3v
- ★ **Lie group:** a continuous group that depends analytically on some continuous parameters  $\lambda$ . Examples: Real  $d$ -dimensional rotations  $SO(d)$ , the orthogonal group  $O(d)$ , the unitary group  $U(d)$ , the special unitary group  $SU(d)$

★ **Abelian group:**  $a * b = b * a \forall a, b \in G$

★ **Subgroup:** a subset  $H$  of the group  $G$  is a subgroup of  $G$  if and only if it is nonempty and itself forms a group. If it is neither the identity or  $G$  itself then it is a *proper* subgroup. **Lagrange Theorem:** the order of  $H$  divides the order of  $G$ . Thus if the order of a group is prime there is only one possible group

★ **Group homomorphism:** an application from  $(G, *)$  to  $(G, **)$  such that  $\forall x, y \in G \quad f(x * y) = f(x) ** f(y)$ . An isomorphism sets a one-to-one correspondence.

Representations

★ A **representation**  $R$  of a group  $G$  on a vector space  $V$  is a group homomorphism from  $G$  to a set of matrices that act on a vector space  $V$ . The dimension of a representation  $R$  is defined to be the dimension of the vector space  $V$ , i.e.,  $\dim(R) = \dim(V)$ .

★ All groups allow **trivial representation**  $\forall g \in G, R(g) = \mathbb{I}$

★ The **regular representation** is obtained by reordering the Cayley table so that only  $e$  fills the diagonal, then to every element assign the matrix obtained by replacing 1 in the positions where the element is in the table and 0 everywhere else.

★ **Equivalent** reps are related by a similarity transformation  $R'(g) = SR(g)S^{-1}$

★ If  $R_1$  and  $R_2$  are two representations for  $G$ , then  $R_1(g) \otimes R_2(g)$  is also a rep

★ The direct sum  $R_1 \oplus R_2$  is a rep of  $G$  acting on  $V_1 \oplus V_2$

$$(R_1 \oplus R_2)(g) = \begin{pmatrix} R_1(g) & 0 \\ 0 & R_2(g) \end{pmatrix}$$

★ Let  $U_g$  be a rep of  $G$  and  $H$  an Hermitian operator such that  $[U_g, H] = 0 \forall g$ . Then  $H$  and  $U_g$  are simultaneously block diagonalised (in the same basis).  
E.g.  $U_g \otimes U_g$ , the tensor product representation of  $SU(2)$ , commutes with SWAP and has therefore a symmetric ( $d = 3$ ) and an asymmetric ( $d = 1$ ) invariant subspace.

★ **Reducible representation:** a rep  $R(g)$  of  $G$  over a vector space  $V$  is reducible if there exists an invariant subspace, i.e. if there exists a non-trivial subspace  $W$  of  $V$  such that for all  $|w\rangle \in W$  we have  $R(g)|w\rangle \in W$  for any  $g$ .

★ **Completely reducible rep:** if it splits into a direct sum of irreducible reps

★ **Schur's 1st lemma:** Let  $R_1(g)$  and  $R_l(g)$  be two non-equivalent irreducible reps of  $G$ , acting on vector spaces  $V_1, V_2$ . If there is a matrix  $A$  such that  $AR_1(g) = R_2(g)A \forall g$  then  $A = 0$ .  
Equivalently, if you can find  $A$  different than 0 that satisfies the eq., then the reps are reducible.

★ **Schur's 2nd lemma:** Let  $R$  be an irreducible rep of  $G$ . If  $AR(g) = R(g)A \forall g \in G$  then  $A = \lambda \mathbb{I}$  for some  $\lambda \in \mathbb{C}$ .  
Equivalent to: if  $[A, R(g)] = 0$  i.e. if they can be diagonalised in the same base.

★ **Burnside's lemma:** for a finite group of order  $h$  there are only a finite number  $n$  of irreducible representations  $a = 1 \dots n$  of dimension  $l_a$  and  $\sum_{a=1}^n l_a^2 = h$

★ In a group  $G$ , two elements  $g$  and  $g'$  are **equivalent** if there exists another element  $f$  such that  $g' = f^{-1}gf$ . This divides  $G$  in conjugacy classes.

★ For a finite group, the number of (non-equiv.) irreps is equal to the number of conjugacy classes

★ All irreducible reps of Abelian groups are scalar ( $d = 1$ ). An Abelian group of order  $n$  has  $n$  conjugacy classes and thus  $n$  irreducible reps.

★ **Grand Orthogonality Theorem:** Let  $R_a$  and  $R_b$  be two non-equiv. unitary irreducible reps of a finite group  $G$  of order  $N$ . Let  $n_a$  and  $n_b$  be the dimensions of the vector space for  $R_a$  and  $R_b$ . Then

$$\sum_{g \in G} \frac{n_a}{N} [R_a(g)^\dagger]_{jk} [R_b(g)]_{lm} = \delta_{ab} \delta_{jm} \delta_{lk}$$

• if  $a \neq b$  then  $\sum_{g \in G} [R_a(g)^\dagger]_{jk} [R_b(g)]_{lm} = 0$  for all  $i, j, k, l$

• if  $a = b$  then  $\sum_{g \in G} [R_a(g)^\dagger]_{jk} [R_a(g)]_{lm} = 0$  if  $j \neq m$  and/or  $l \neq k$

• if  $a = b$  and  $j = m$  and  $l = k$  then  $\sum_{g \in G} [R_a(g)^\dagger]_{jk} [R_a(g)]_{jk} = \frac{N}{n_a}$

★ A finite group can only have a finite number of inequivalent irreducible representations. Specifically, the **maximum number of possible irreps** is given by the order of the group. Proof: irreps give us 'vectors of matrices' in a vector space of dimension  $|G|$  and the theorem says they must be orthogonal. But there are at most  $|G|$  orthogonal vectors in a vector space of dimension  $|G|$

★ **Group averaging:** if  $d$  is the dim. of vector space of rep and  $U_g$  is an irreducible representation then  $\langle X \rangle_G = \frac{1}{N} \sum_g U_g X U_g^\dagger = \frac{1}{d} \text{Tr}[X] \mathbb{I}$

★ Proof:  $\frac{1}{N} \sum_g U_g X U_g^\dagger = \frac{1}{N} \sum_g \left( \sum_{l,m} [U_g]_{lm} |l\rangle \langle m| \right) X \left( \sum_{k,j} [U_g^\dagger]_{kj} |k\rangle \langle j| \right)$   
 $= \frac{1}{N} \sum_g \sum_{lmkj} [U_g]_{lm} X_{mk} [U^\dagger]_{kj} |l\rangle \langle j|$  then apply orthogonality  
 $= \frac{1}{n_a} \sum_{lmkj} \delta_{lj} \delta_{mk} X_{mk} |l\rangle \langle j|$

★  $\langle X \rangle_G = \int_G d\mu(g) U_x(g) X U_x(g)^\dagger = \frac{1}{d} \text{Tr}[X] \mathbb{I}$  for continuous groups

★ For reducible representations  $U_g$  we have

$$\langle X \rangle_G = \frac{1}{N} \sum_g U_g X U_g^\dagger = \sum_x \frac{\text{Tr}[\Pi_x X]}{d_x} \Pi_x = \bigoplus_x \frac{\text{Tr}[\Pi_x X]}{d_x} \mathbb{I}_x$$

★ Proof: any reducible unitary can be written as  $U(g) = \bigoplus_x U_x(g) = \sum_x U_x(g) \otimes I_{\bar{x}}$  where  $\bar{x}$  is the subspace  $U_x$  does not act on.  
 $\langle X \rangle_G = \frac{1}{N} \sum_g U_g X U_g^\dagger = \frac{1}{N} \sum_g \sum_{x,x'} (U_x(g) \otimes I_{\bar{x}}) X (U_{x'}(g)^\dagger \otimes I_{\bar{x}}) = \frac{1}{N} \sum_g \sum_x (U_x(g) \otimes I_{\bar{x}}) X (U_x(g)^\dagger \otimes I_{\bar{x}}) = \frac{1}{d_x} \sum_x \text{Tr}[X \Pi_x] \Pi_x \otimes I_{\bar{x}} = \frac{1}{d_x} \bigoplus_x \text{Tr}[X \Pi_x] \Pi_x$

★ In a representation  $R$ , all elements which are in the same conjugacy class have the same trace. Proof:  $\text{Tr}(R(u^{-1}yu)) = \text{Tr}(R(u)R(u^{-1})R(y)) = \text{Tr}(R(y))$

★ **Petit Orthogonality Theorem:** Let  $R_a$  and  $R_b$  be two non-equiv. unitary irreducible reps of a finite group of order  $N$ , then  $\sum_{g \in G} \chi_a^*(g) \chi_b(g) = N \delta_{a,b}$  where  $\chi_R(g) = \text{Tr}[R(g)]$ , or equiv.  $\sum_{\mu=1}^{N_c} \eta_\mu \chi_a^*(g) \chi_b(g) = N \delta_{a,b}$  with  $\eta_\mu$  the nb of elements in class  $\mu$  and  $N_c$  total nb of conjugacy classes

★ The set of all traces  $\{\chi_R(g)\}$  is the **character** of representation  $R$ . Two irreps are equivalent iff they have the same character. Proof by contradiction with Petit.

★ Trace of all reps within a conjugacy class are the same  $\rightarrow \chi_R(C_\mu) = \sum_a b_a \chi_a(C_\mu)$

★ Assuming a decomposition in irreps  $R(g) = \bigoplus_{a,x} R_{a,x}(g)$  for  $x = 1 \dots b_a$ , the degeneracy of conjugacy class  $a$  is  $b_a = \frac{1}{N} \sum_\mu \eta_\mu \chi_a^*(C_\mu) \chi_R(C_\mu)$  NOT CLEAR

★ A necessary and sufficient condition for a representation  $R$  to be an irrep is that  $|\sum_{\mu=1}^{N_c} \eta_\mu |\chi(C_\mu)|^2 = N$ . Proof: decompose trace and use Petit.

Lie Algebras

p.3

★ Rotation through infinitesimal angle  $R(\theta) = \mathbb{I} + A$  and as  $R^T R = \mathbb{I}$  we must have  $A^T = -A \implies$  e.g. in 2D  $A = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \theta = J\theta$

★ Then  $R(\theta) = \lim_{N \rightarrow \infty} \left( R\left(\frac{\theta}{N}\right) \right)^N = e^{\theta J}$

★ What about 3D? 3 basis antisymmetric matrices:

$$J_x = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix} J_y = \begin{pmatrix} 0 & 0 & -1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix} J_z = \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

and any 3x3 antisymmetric matrix can be written as  $A = \theta_x J_x + \theta_y J_y + \theta_z J_z$  so that  $R(\theta) = e^{\theta_x J_x + \theta_y J_y + \theta_z J_z}$

★ Arbitrary dimension:  $R(\theta) = e^{\sum_i \theta_i J_i}$  or  $R(\theta) = e^{i \sum_i \theta_i \tilde{J}_i}$  with  $\tilde{J} = -iJ$

★ **Structure constants:** let  $R = \mathbb{I} + A, R' = \mathbb{I} + B$ . Then  $RR'R^{-1} = \mathbb{I} + B + [A, B]$ .  $[A, B] = i^2 \sum_{i,j} \theta_i \theta'_j [J_i, J_j]$  measures how much they don't commute. Generally we have  $[T_a, T_b] = i f_{abc} T_c$  where  $f_{abc}$  are the structure constants of the algebra.

★ **Lie algebra:** a linear space spanned by linear combinations  $\sum_i \theta_i J_i$  of the generators of the associated Lie group  $G$

★ As Lie groups are differentiable, it is always possible to write an element  $g$  of a Lie group  $G$  as the exponential of an element  $J$  of the corresponding Lie algebra  $\mathfrak{g}$  i.e.  $g = \{J|e^{iJ} \in G\}$

★ The commutation relations of the generators  $J_j$  (i.e., a basis for  $\mathfrak{g}$ ) are the structure constants of the group and can be used to identify the Lie algebra  $\mathfrak{g}$  (and thereby the corresponding Lie group  $G$ ).

★ What does it mean to represent an algebra? It means to find a set of matrices such that the defining commutation relations are satisfied.

★ Let  $G$  be a matrix Lie group with Lie algebra  $\mathfrak{g}$ . If  $R$  is a representation of  $G$  on  $V$ , then there exists a unique representation  $r$  of  $\mathfrak{g}$  on  $V$  given by  $r(X) = \left. \frac{d}{d\theta} (R(e^{\theta X})) \right|_{\theta=0}$  for all  $X \in \mathfrak{g}$ . We call  $r$  the rep of  $\mathfrak{g}$  induced by  $R$ .

Ladder operators

$$S_{\pm} = S_x \pm i S_y \quad S_x = \frac{1}{2} (S_+ + S_-) \quad S_y = \frac{1}{2i} (S_+ - S_-)$$

$$S_+ |s, m\rangle = \sqrt{s(s+1) - m(m+1)} |s, m+1\rangle$$

$$S_- |s, m\rangle = \sqrt{s(s+1) - m(m-1)} |s, m-1\rangle$$

★ Clebsch-Gordan stuff

**Irreducible representations of C3v**

(i) Trivial      (ii) 2D irrep ↓

$$R(e) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} R(c_+) = \begin{pmatrix} -\frac{1}{2} & -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & -\frac{1}{2} \end{pmatrix} R(c_-) = \begin{pmatrix} -\frac{1}{2} & \frac{\sqrt{3}}{2} \\ -\frac{\sqrt{3}}{2} & -\frac{1}{2} \end{pmatrix}$$
$$R(\sigma) = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} R(\sigma') = \begin{pmatrix} \frac{1}{2} & \frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & -\frac{1}{2} \end{pmatrix} R(\sigma'') = \begin{pmatrix} \frac{1}{2} & -\frac{\sqrt{3}}{2} \\ -\frac{\sqrt{3}}{2} & -\frac{1}{2} \end{pmatrix}$$

(iii)  $R(e) = 1, R(c_+) = 1, R(c_-) = 1, R(\sigma) = -1, R(\sigma') = -1, R(\sigma'') = -1$

★ Character table:

|             | $e$ | $2C_3$ | $3\sigma_v$ |
|-------------|-----|--------|-------------|
| $R_{(i)}$   | 1   | 1      | 1           |
| $R_{(ii)}$  | 2   | -1     | 0           |
| $R_{(iii)}$ | 1   | 1      | -1          |

**3D representation of C3v (reducible)** p.4

Triangle in a 3D space with vertex at positions (1; 0; 0), (0; 1; 0) and (0; 0; 1)

$$R(e) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} R(c_+) = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} R(c_-) = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$
$$R(\sigma) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} R(\sigma') = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} R(\sigma'') = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

**Other groups**

★  $SU(2)$ : single qubit rotations  $\rightarrow e^{-i\sigma_x\theta_1} e^{-i\sigma_z\theta_2} e^{-i\sigma_x\theta_3}$

2D irreducible representation: Pauli matrices

3D irreducible representation: same as for  $SO(3)$ , obtain  $L_x, L_y, L_z$  from ladder operators acting on the basis  $|l, m\rangle$

★  $U(1)$ : symmetry group of rotations around one axis (e.g.  $x$ ), such as phase of a laser. The associated representation is the set of rotations by an angle  $\theta \in [0, 2\pi)$  about the axis  $U(\theta) = e^{-i\theta\sigma_x/2}$ . The representation is reducible in 1D reps  $\{1\}$  and  $\{e^{-i\theta}\}$ . For example for  $\sigma_x$   $U_g = \begin{pmatrix} 1 & 0 \\ 0 & e^{-i\theta} \end{pmatrix} = |+\rangle\langle+| + e^{-i\theta}|-\rangle\langle-|$

Averaging a state  $\rho$ :  $\langle\rho\rangle_G = \langle+|\rho|+\rangle|+\rangle\langle+| + \langle-|\rho|-\rangle|-\rangle\langle-|$  which is a projection onto the  $x$ -axis

★  $U(2)$ : light polarisation  $\rightarrow e^{-i\phi} e^{-i\sigma_x\theta_1} e^{-i\sigma_z\theta_2} e^{-i\sigma_x\theta_3}$

★ Possible dimensions of  $SO(3)$  are odd

★ Any representation of  $SO(3)$  is also a representation of  $SU(2)$ . The converse is not true. For each representation in  $SO(3)$  there are two in  $SU(2)$  ( $SU(2)$  is a double cover of  $SO(3)$ )

| Bayes' theorem                                  |  |
|---|--|
|   | $P(A B) = \frac{P(B A)P(A)}{P(B)}$   |
| Eigenspectrum of generic 2 x 2 hermitian matrix |  |
| ★ Matrix of form                                | $\begin{pmatrix} V_{11} & V_{12} \\ V_{12}^* & V_{22} \end{pmatrix}$   |
| ★ Eigenvalues $E_{\pm}$                         | $= \frac{1}{2}(V_{11} + V_{22} \pm \Delta E)$ where $\Delta E = \sqrt{(V_{11} - V_{22})^2 + 4 V_{12} ^2}$  |
| ★ The normalised eigenvectors are               | $\begin{pmatrix} \frac{V_{12}}{\sqrt{\Delta E \left( \frac{\Delta E}{2} \pm \frac{(V_{22} - V_{11})}{2} \right)}} e^{i\phi_{\pm}} \\ \pm \sqrt{\frac{\frac{\Delta E}{2} \pm \frac{(V_{22} - V_{11})}{2}}{\Delta E}} e^{i\phi_{\pm}} \end{pmatrix}$ |
| valid for any phase $\phi_{\pm}$                |  |
| Eigenvectors of Pauli matrices                  |  |
|   | $\psi_{x+} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \psi_{x-} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$  |
|   | $\psi_{y+} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ i \end{pmatrix}, \psi_{y-} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -i \end{pmatrix}$  |
|   | $\psi_{z+} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \psi_{z-} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}.$  |