



Perturbation Theory	
★ $H = H_0 + \lambda V$ , with $H_0 \left  \phi_n \right\rangle = \epsilon_n \left  \phi_n \right\rangle$ known, $\lambda \in \mathbb{R}^+$ .	
★ $H \left  \psi_n \right\rangle = E_n \left  \psi_n \right\rangle$ eigenspectrum unknown. The solution in the limit of small $\lambda$ is $\left  \psi_n \right\rangle = \left  \phi_n \right\rangle + \lambda \left  \psi_n^{(1)} \right\rangle + \lambda^2 \left  \psi_n^{(2)} \right\rangle + \dots$ $E_n = \epsilon_n + \lambda E_n^{(1)} + \lambda^2 E_n^{(2)} + \dots$	
★ S.E.: $(H_0 + \lambda V)(\left  \phi_n \right\rangle + \lambda \left  \psi_n^{(1)} \right\rangle + \lambda^2 \left  \psi_n^{(2)} \right\rangle + \dots) = (\epsilon_n + \lambda E_n^{(1)} + \lambda^2 E_n^{(2)} + \dots)(\left  \phi_n \right\rangle + \lambda \left  \psi_n^{(1)} \right\rangle + \lambda^2 \left  \psi_n^{(2)} \right\rangle + \dots)$ must be satisfied at each order in $\lambda$	
Non-degenerate Time-Indepndent Perturbation Theory	p.2
★ <b>Zero-th order</b> $H_0 \left  \phi_n \right\rangle = \epsilon_n \left  \phi_n \right\rangle$ unperturbed eigenvalue problem	
★ <b>1st order</b> $E_n^{(1)} = \left\langle \phi_n \left  V \right  \phi_n \right\rangle$ ; $\left  \psi_n^1 \right\rangle = \sum_{m \neq n} \frac{\left\langle \phi_m \left  V \right  \phi_n \right\rangle}{\epsilon_n - \epsilon_m} \left  \phi_m \right\rangle$	
★ <b>2nd order</b> $E_n^{(2)} = \sum_{m \neq n} \frac{\left  \left\langle \phi_m \left  V \right  \phi_n \right\rangle \right ^2}{\epsilon_n - \epsilon_m}$ ; for approx. to be val. $\left  E_n^{(2)} \right  \ll \left  E_n^{(1)} \right $	
★ satisfied as long as $\frac{1}{\Delta} (\left\langle \phi_n \left  V^2 \right  \phi_n \right\rangle - \left\langle \phi_n \left  V \right  \phi_n \right\rangle^2) \ll \left\langle \phi_n \left  V \right  \phi_n \right\rangle$ , $\Delta = \min_m \left  \epsilon_n - \epsilon_m \right $ or more restrictive: $\left  \frac{\left\langle \phi_m \left  V \right  \phi_n \right\rangle}{\epsilon_n - \epsilon_m} \right  \ll 1$	
Degenerate Time-Indepndent Perturbation Theory	
★ $n$ th energy state has $N$ -fold degeneracy $\Rightarrow H_0$ has energy $\epsilon_n$ with $\phi_{n_i}, i = 1 \dots N$	
★ $\sum_j V_{ij} c_j = E_n^{(1)} c_i \iff \hat{V} \mathbf{c} = E_n^{(1)} \mathbf{c}$ $V_{ij} = \left\langle \phi_{n_i} \left  V \right  \phi_{n_j} \right\rangle$ eigenvalue problem, must diagonalise $V$ matrix (in the degenerate subspace only!)	
★ The eigenvectors are the corrected eigenstates (to 0th order), the eigenvalues are the 1st order correction to energy. If eigenvalues are the same, degeneracy is not lifted.	
★ E.g. $V = \begin{pmatrix} 0 & \alpha & 0 & 0 \\ \alpha & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \xrightarrow{\text{diag}} \alpha, \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \\ 0 \end{pmatrix}; -\alpha, \begin{pmatrix} -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \\ 0 \end{pmatrix}; 0, \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}; 0, \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}$ Thus $\left  0 \right\rangle \rightarrow \frac{1}{\sqrt{2}} (\left  0 \right\rangle + \left  1 \right\rangle)$ ; $\left  1 \right\rangle \rightarrow \frac{1}{\sqrt{2}} (\left  0 \right\rangle - \left  1 \right\rangle)$ ; $\left  2 \right\rangle, \left  3 \right\rangle$ unchanged The corrected eigenstates have an energy correction $E^{(1)}$ of $\alpha, -\alpha, 0, 0$ .	
Time-Dependent Hamiltonians	
★ $U(t, t_0) = \mathbb{I} + \sum_{n=1}^{\infty} \frac{(-1)^n}{n!} \int_{t_0}^t dt_1 \int_{t_0}^{t_1} dt_2 \dots \int_{t_0}^{t_{n-1}} dt_n T(H(t_1) \dots H(t_n))$ where $T[H(t_1)H(t_2) \dots H(t_n)] = H(t_1)H(t_{i_2}) \dots H(t_{i_n}), t_{i_1} \geq t_{i_2} \geq \dots$	
★ Alternatively: $U(t, t_0) \approx \sum_j \exp(iH(t_j)\delta t)$ with an error of $\left  \int_{t_0}^t ds H(s) - \delta t \sum_{r=1}^{n_t} H(t_0 + r\delta t) \right ^2$ (discretisation)	
Interaction picture	
★ Schrödinger picture: $i \frac{\partial}{\partial t} \left  \phi_S(t) \right\rangle = H(t) \left  \phi_S(t) \right\rangle, \quad O_S(t) = O_S$	
★ Heisenberg picture: $O_H(t) = U_S(t, t_0)^\dagger O_S U_S(t, t_0), \quad \left  \phi_H(t) \right\rangle = \left  \phi_S(t_0) \right\rangle$	
★ Interaction picture: $H(t) = H_H + V_S(t)$ ,	
★ $O_I(t) = e^{iH_0(t-t_0)} O_S(t) e^{-iH_0(t-t_0)}$	
★ $\left  \phi_I(t) \right\rangle = U_I(t, t_0) \left  \phi_I(t_0) \right\rangle, \quad U_I = e^{iH_0(t-t_0)} U_S(t, t_o)$	
★ $\frac{\partial U_I}{\partial t} = -iV_I(t)U_I(t, t_0)$	
Time-Dependent Perturbation Theory	
★ $U_I(t, t_0) \approx \mathbb{I} - i \int_{t_0}^t dt_1 V_I(t_1) + \dots$	
★ The exact transition probability between two states is $\left  \left\langle \psi \left  \phi \right\rangle \right ^2$	
★ $P_{i \rightarrow n}(t) = \left  \left\langle n \left  \phi_S(t) \right\rangle \right ^2 = \left  \left\langle n \left  U_I(t, t_0) \right  i \right\rangle \right ^2 = \left  -i \int_{t_0}^t dt_1 e^{i(E_n - E_i)(t-t_0)} \left\langle n \left  V(t_1, t_0) \right  i \right\rangle \right ^2$ general expression of <b>transition probabilities</b> between eigenstates $\left  i \right\rangle$ and $\left  n \right\rangle$ of $H_0$ . Note: if $V = 0$ then a system in an eigenstate stays in an aigenstate.	
★ For a constant potential $P_{i \rightarrow \bar{n}}(t) \stackrel{t \rightarrow \infty}{=} 2\omega t \left  \left\langle n \left  V \right  i \right\rangle \right ^2 \delta(E_n - E_i)$ $\frac{\partial}{\partial t} P_{i \rightarrow n}(t) = 2\pi \left  \left\langle n \left  V \right  i \right\rangle \right ^2 \delta(E_n - E_i)$	

Variational method	
★ $\frac{\left\langle \psi \left  H \right  \psi \right\rangle}{\left\langle \psi \left  \psi \right\rangle} \geq E_0$ <b>Variational principle</b>	
★ The idea is to come up with a parameterised guess for the state $\left  \psi \right\rangle$ , and then we use the variational principle to find the parameter values that minimize $\psi$ . It generalises to excited states orthogonal to the ground state $\phi_0$ (i.e. $\left\langle \phi_0 \left  \psi \right\rangle = 0\right)$ by replacing $E_0$ with $E_1$ . Limitation: the ground state should be known to ensure it is orthogonal to the excited state.	
★ Steps: compute $\frac{\left\langle \psi \left  H \right  \psi \right\rangle}{\left\langle \psi \left  \psi \right\rangle} = E(a)$ then minimise $E$ with respect to the parameter.	
Decoherence	
If $\left  \psi \right\rangle = \sum_j c_j \left  E_j \right\rangle_A \otimes \left  \phi \right\rangle_B$ and $H_{AB} = \sum_j \left  E_j \right\rangle \left\langle E_j \right _A \otimes H_B^{(j)}$ then $\rho_{AB} = \left  \psi \right\rangle \left\langle \psi \right  = \sum_j \sum_i c_j c_i^* \left  E_j \right\rangle \left\langle E_i \right _A \otimes \left  \phi \right\rangle \left\langle \phi \right _B$ $\rho_a(t) = \sum_j \sum_i c_j c_i^* \left  E_j \right\rangle \left\langle E_i \right  \left\langle \phi \right  e^{itH_B^{(i)}} e^{-itH_B^{(j)}} \left  \phi \right\rangle$ $\rho_B(t) = \sum_j \left  c_j \right ^2 e^{-itH_B^{(j)}} \left  \phi \right\rangle \left\langle \phi \right  e^{itH_B^{(j)}}$	
Measurement problem	
★ We start with following postulates: (i) Formalism, every physical quantity is represented by an operator $Q$ and every state of a physical system by a state vector $\left  \psi \right\rangle$ (ii) Measurement Kinematic Postulate: If a quantity Q is measured, the post measurement state of the system will be the eigenstate corresponding to the eigenvalue measured. (iii) Dynamical Postulate: Time evolution is a linear map from state to state.	
★ The linearity of quantum mechanics dynamics combined with quantum mechanical treatment of a basic conception of a measuring device leads to the conclusion that a system in a superposition remains in a superposition. According to dynamical postulate there is no way to get the system into an eigenstate of an observable if it is not already in one. However, this contradicts the Measurement Kinematic Postulate, which states that post measurement the system will be in an eigenstate of the observable being measured.	
★ The collapse postulate does not solve the measurement problem because the word measurement does not have precise enough meaning.	
★ There are two key ambiguities with the term measurement: (i) what processes count as measurements? (ii) measurement requires a divide between the system being measured and the part doing the measuring and there is no definite prescription for how this division is to be made	
★ A more modern way of solving in part the measurement problem is decoherence: the environment acts a good measurement device.	

Particle in a box	
★ $V(x) = \begin{cases} 0 & \text{if }  x  \leq L/2 \\ \infty & \text{else} \end{cases} \quad \phi_n(x) = \begin{cases} \sqrt{\frac{2}{L}} \cos(\frac{n\pi}{L}x) & n \text{ odd} \\ \sqrt{\frac{2}{L}} \sin(\frac{n\pi}{L}x) & n \text{ even} \end{cases}$	
★ $E_n = n^2 \frac{\pi^2 \hbar^2}{2mL^2}$	
Harmonic oscillator	
★ $H = \frac{1}{2m} \hat{p}^2 + \frac{1}{2} m \omega^2 \hat{x}^2 = \hbar \omega (\hat{N} + \frac{1}{2}), \quad \hat{N} = \hat{a}^\dagger \hat{a} \quad \star \frac{1}{2m} \hat{p}^2 = -\frac{\hbar^2}{2m} \frac{d^2}{dx^2}$	
★ $\hat{a} = \sqrt{\frac{m\omega}{2\hbar}} \left( \hat{x} + \frac{i\hat{p}}{m\omega} \right) \quad \hat{a}^\dagger = \sqrt{\frac{m\omega}{2\hbar}} \left( \hat{x} - \frac{i\hat{p}}{m\omega} \right)$	
★ $\hat{x} = \sqrt{\frac{\hbar}{2m\omega}} (\hat{a} + \hat{a}^\dagger) \quad \hat{p} = i\sqrt{\frac{m\omega\hbar}{2}} (\hat{a}^\dagger - \hat{a})$	
★ $[\hat{x}, \hat{p}] = i\hbar, \quad [\hat{a}, \hat{a}^\dagger] = 1, \quad [\hat{N}, \hat{a}] = -\hat{a}, \quad [\hat{N}, \hat{a}^\dagger] = \hat{a}^\dagger$	
★ $\phi_0(x) = \left( \frac{m\omega}{\phi\hbar} \right)^{1/4} \exp\left(-\frac{m\omega}{2\hbar} x^2\right)$	
★ $\phi_n = \frac{1}{\sqrt{n!}} (a^\dagger)^n \phi_0 = \frac{1}{\sqrt{2^n n!}} \left( \frac{m\omega}{\pi\hbar} \right)^{1/4} e^{-\frac{m\omega x^2}{2\hbar}} H_n \left( \sqrt{\frac{m\omega}{\hbar}} x \right)$ with $H_n(z) = (-1)^n e^{z^2} \frac{d^n}{dz^n} (e^{-z^2})$	
★ $\hat{H} \phi_n = E_n \phi_n = \hbar \omega (n + \frac{1}{2}) \phi_n$	
★ $\hat{a}^\dagger \phi_n = \sqrt{n+1} \phi_{n+1} \quad \hat{a} \phi_n = \sqrt{n} \phi_{n-1}$	
Hermitian and unitary operators	
★ Hermitian operator: $M = M^\dagger \longrightarrow$ diagonalisable with real eigenvalues, linear	
★ Unitary operators: $UU^\dagger = U^\dagger U = \mathbb{I} \longrightarrow \left\langle \psi \left  U^\dagger U \right  \psi \right\rangle = \mathbb{I}$ and linear	
Tensor product	
★ $\begin{pmatrix} a \\ b \end{pmatrix} \otimes \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \begin{pmatrix} a\alpha & a\beta & b\alpha & b\beta \end{pmatrix}^T$	
★ $A \otimes B = \begin{pmatrix} A_{11}B & A_{12}B \\ A_{21}B & A_{22}B \end{pmatrix} \quad \star A \oplus B = \begin{pmatrix} A & 0 \\ 0 & B \end{pmatrix}$	
★ $R(g)^{\otimes k} = R(g) \otimes \dots \otimes R(g) \quad \star \bigoplus_k R(g) = (R \oplus \dots \oplus R)(g)$	
★ $f(\hat{A} \otimes \hat{B}) \left  a \right\rangle \left  \phi \right\rangle = \left  a \right\rangle \otimes f(a\hat{B}) \left  \phi \right\rangle$	
★ $[A \otimes \mathbb{I}, \mathbb{I} \otimes B] = 0 \quad \star \{A \otimes \mathbb{I}, \mathbb{I} \otimes B\} = 2A \otimes B$	
★ $e^{A+B} = e^A e^B$ if $[A, B] = 0 \implies e^{A \otimes \mathbb{I} + \mathbb{I} \otimes B} = e^A \otimes e^B$	
Trigonometry	
★ $\cos(a+b) = \cos(a)\cos(b) - \sin(a)\sin(b) \quad \star \sin(2a) = 2\sin a \cos a$	
★ $\sin(a+b) = \sin(a)\cos(b) + \cos(a)\sin(b) \quad \star \cos(2a) = \cos^2 a - \sin^2 a$	
★ $2\sin(a)\sin(b) = \cos(a-b) - \cos(a+b) \quad \star \sin(a/2) = \pm \sqrt{(1 - \cos(a))/2}$	
★ $2\cos(a)\cos(b) = \cos(a+b) + \cos(a-b) \quad \star \cos(a/2) = \pm \sqrt{(1 + \cos(a))/2}$	
★ $2\cos(a)\sin(b) = \sin(a+b) - \sin(a-b) \quad \star \sin^2 a = (1 - \cos 2a)/2$	
★ $\cos(a) + \cos(b) = 2\cos((a+b)/2)\cos((a-b)/2) \quad \star \cos^2 a = (1 + \cos 2a)/2$	
★ $\sin(a) + \sin(b) = 2\sin((a+b)/2)\cos((a-b)/2)$	
★ $\cos(a) - \cos(b) = -2\sin((a+b)/2)\sin((a-b)/2)$	
Some useful integrals	
★ $\int_{-\infty}^{+\infty} dx e^{-\alpha^2(x+\beta)^2+Bx} = \frac{\sqrt{\pi}}{\alpha} e^{\frac{B^2}{4\alpha^2}-B\beta}$ with $\text{Re}(\alpha^2) \geq 0, B, \beta \in \mathbb{C}$	
★ $\int_{-\infty}^{+\infty} dx x^n e^{-\frac{1}{2}Ax^2} = \begin{cases} (n-1)!!\sqrt{2\pi} A^{-\frac{n+1}{2}} & \text{If n is even} \\ 0 & \text{If n is odd} \end{cases}$	
★ $\int_0^T \sin^2(\frac{x\pi}{T})dx = \frac{T}{2}$ and same with $\cos^2$	

Group Theory

- ★ **Group:** Set  $G$  equipped with operation  $*$  such that
  - $G$  closed under  $*$ , i.e. if  $a, b \in G$  then  $a * b \in G$
  - Associative:  $\forall a, b, c \in G$  one has  $(a * b) * c = a * (b * c)$
  - Has identity, i.e an element  $e$  such that  $e * a = a \forall a \in G$
  - Has inverse, i.e.  $\forall a \in G$  it exists  $b \in G$  such that  $b * a = a * b = e$ . ( $b = a^{-1}$ )

★ Any unitary that leaves a property invariant forms a group with  $*$  matrix multiplicative.

★ **Finite group:** A group that contains a finite number of elements (the group order).

★ Order 1 group (the only one, trivial group):

*	e
e	e
*	e a
e	e a
a	a e
*	e a b
e	e a b
a	a b e
b	b e a

★ Order 2: parity group

★ The unique order 3 group is the cyclic  $\mathbb{Z}_3$  group

★ Order 4 has cyclic and symmetry of a rectangle (check Miscellanea)

*	e	a	a <sup>2</sup>	b	c	d
e	e	a	a <sup>2</sup>	b	c	d
a	a	a <sup>2</sup>	e	c	d	b
a <sup>2</sup>	a <sup>2</sup>	e	a	d	b	c
b	b	d	c	e	a <sup>2</sup>	a
c	c	b	d	a	e	a <sup>2</sup>
d	d	c	b	a	a <sup>2</sup>	e

★ Order 6 has cyclic group  $\mathbb{Z}_6$  and the C3v group (on the right)

*	e	a <sup>1</sup>	a <sup>2</sup>	...	a <sup>n-1</sup>
*	e	a <sup>1</sup>	a <sup>2</sup>	...	a <sup>n-1</sup>
a <sup>1</sup>	a <sup>1</sup>	a <sup>2</sup>	a <sup>3</sup>	...	e
a <sup>2</sup>	a <sup>2</sup>	a <sup>3</sup>	a <sup>4</sup>	...	a <sup>1</sup>
⋮					
a <sup>n-1</sup>	a <sup>n-1</sup>	e	a <sup>1</sup>	...	a <sup>n-2</sup>

★ Symmetric permutation group  $S_n$  (all possible permutations of  $n$  objects)  
e.g.  $S_3 = \{I, \text{SWAP}_{12}, \text{SWAP}_{13}, \text{SWAP}_{23}, \text{CYCLE}_{123}, \text{CYCLE}_{321}\}$  isomorphic to C3v

★ **Lie group:** a continuous group that depends analytically on some continuous parameters  $\lambda$ . Examples: Real  $d$ -dimensional rotations  $SO(d)$ , the orthogonal group  $O(d)$ , the unitary group  $U(d)$ , the special unitary group  $SU(d)$

★ **Abelian group:**  $a * b = b * a \forall a, b \in G$

★ **Subgroup:** a subset  $H$  of the group  $G$  is a subgroup of  $G$  if and only if it is nonempty and itself forms a group. If it is neither the identity or  $G$  itself then it is a *proper* subgroup. **Lagrange Theorem:** the order of  $H$  divides the order of  $G$ . Thus if the order of a group is prime there is only one possible group

★ **Group homomorphism:** an application from  $(G, *)$  to  $(G, **)$  such that  $\forall x, y \in G \quad f(x * y) = f(x) ** f(y)$ . An isomorphism sets a one-to-one correspondence.

Representations p.3

★ A **representation**  $R$  of a group  $G$  on a vector space  $V$  is a group homomorphism from  $G$  to a set of matrices that act on a vector space  $V$ . The dimension of a representation  $R$  is defined to be the dimension of the vector space  $V$ , i.e.,  $\dim(R) = \dim(V)$ .

★ All groups allow **trivial representation**  $\forall g \in G, R(g) = \mathbb{I}$

★ The **regular representation** is obtained by reordering the Cayley table so that only  $e$  fills the diagonal, then to every element assign the matrix obtained by replacing 1 in the positions where the element is in the table and 0 everywhere else.

★ **Equivalent** reps are related by a similarity transformation  $R'(g) = SR(g)S^{-1}$

★ If  $R_1$  and  $R_2$  are two representations for  $G$ , then  $R_1(g) \otimes R_2(g)$  is also a rep

★ The direct sum  $R_1 \oplus R_2$  is a rep of  $G$  acting on  $V_1 \oplus V_2$

$$(R_1 \oplus R_2)(g) = \begin{pmatrix} R_1(g) & 0 \\ 0 & R_2(g) \end{pmatrix}$$

★ Let  $U_g$  be a rep of  $G$  and  $H$  an Hermitian operator such that  $[U_g, H] = 0 \forall g$ . Then  $H$  and  $U_g$  are simultaneously block diagonalised (in the same basis).  
E.g.  $U_g \otimes U_g$ , the tensor product representation of  $SU(2)$ , commutes with SWAP and has therefore a symmetric ( $d = 3$ ) and an asymmetric ( $d = 1$ ) invariant subspace.

★ **Reducible representation:** a rep  $R(g)$  of  $G$  over a vector space  $V$  is reducible if there exists an invariant subspace, i.e. if there exists a non-trivial subspace  $W$  of  $V$  such that for all  $|w\rangle \in W$  we have  $R(g)|w\rangle \in W$  for any  $g$ .

★ **Completely reducible rep:** if it splits into a direct sum of irreducible reps

★ **Schur's 1st lemma:** Let  $R_1(g)$  and  $R_l(g)$  be two non-equivalent irreducible reps of  $G$ , acting on vector spaces  $V_1, V_2$ . If there is a matrix  $A$  such that  $AR_1(g) = R_2(g)A \forall g$  then  $A = 0$ .  
Equivalently, if you can find  $A$  different than 0 that satisfies the eq., then the reps are reducible.

★ **Schur's 2nd lemma:** Let  $R$  be an irreducible rep of  $G$ . If  $AR(g) = R(g)A \forall g \in G$  then  $A = \lambda \mathbb{I}$  for some  $\lambda \in \mathbb{C}$ .  
Equivalent to: if  $[A, R(g)] = 0$  i.e. if they can be diagonalised in the same base.

★ **Burnside's lemma:** for a finite group of order  $h$  there are only a finite number  $n$  of irreducible representations  $a = 1 \dots n$  of dimension  $l_a$  and  $\sum_{a=1}^n l_a^2 = h$

★ In a group  $G$ , two elements  $g$  and  $g'$  are **equivalent** if there exists another element  $f$  such that  $g' = f^{-1}gf$ . This divides  $G$  in conjugacy classes.

★ For a finite group, the number of (non-equiv.) irreps is equal to the number of conjugacy classes

★ All irreducible reps of Abelian groups are scalar ( $d = 1$ ). An Abelian group of order  $n$  has  $n$  conjugacy classes and thus  $n$  irreducible reps.

★ **Grand Orthogonality Theorem:** Let  $R_a$  and  $R_b$  be two non-equiv. unitary irreducible reps of a finite group  $G$  of order  $N$ . Let  $n_a$  and  $n_b$  be the dimensions of the vector space for  $R_a$  and  $R_b$ . Then

$$\sum_{g \in G} \frac{n_a}{N} [R_a(g)^\dagger]_{jk} [R_b(g)]_{lm} = \delta_{ab} \delta_{jm} \delta_{lk}$$

• if  $a \neq b$  then  $\sum_{g \in G} [R_a(g)^\dagger]_{jk} [R_b(g)]_{lm} = 0$  for all  $i, j, k, l$

• if  $a = b$  then  $\sum_{g \in G} [R_a(g)^\dagger]_{jk} [R_a(g)]_{lm} = 0$  if  $j \neq m$  and/or  $l \neq k$

• if  $a = b$  and  $j = m$  and  $l = k$  then  $\sum_{g \in G} [R_a(g)^\dagger]_{jk} [R_a(g)]_{jk} = \frac{N}{n_a}$

★ A finite group can only have a finite number of inequivalent irreducible representations. Specifically, the **maximum number of possible irreps** is given by the order of the group. Proof: irreps give us 'vectors of matrices' in a vector space of dimension  $|G|$  and the theorem says they must be orthogonal. But there are at most  $|G|$  orthogonal vectors in a vector space of dimension  $|G|$

★ **Group averaging:** if  $d$  is the dim. of vector space of rep and  $U_g$  is an irreducible representation then  $\langle X \rangle_G = \frac{1}{N} \sum_g U_g X U_g^\dagger = \frac{1}{d} \text{Tr}[X] \mathbb{I}$

★ Proof:  $\frac{1}{N} \sum_g U_g X U_g^\dagger = \frac{1}{N} \sum_g \left( \sum_{l,m} [U_g]_{lm} |l\rangle \langle m| \right) X \left( \sum_{k,j} [U_g^\dagger]_{kj} |k\rangle \langle j| \right)$   
 $= \frac{1}{N} \sum_g \sum_{lmkj} [U_g]_{lm} X_{mk} [U^\dagger]_{kj} |l\rangle \langle j|$  then apply orthogonality  
 $= \frac{1}{n_a} \sum_{lmkj} \delta_{lj} \delta_{mk} X_{mk} |l\rangle \langle j|$

★  $\langle X \rangle_G = \int_G d\mu(g) U_x(g) X U_x(g)^\dagger = \frac{1}{d} \text{Tr}[X] \mathbb{I}$  for continuous groups

★ For reducible representations  $U_g$  we have

$$\langle X \rangle_G = \frac{1}{N} \sum_g U_g X U_g^\dagger = \sum_x \frac{\text{Tr}[\Pi_x X]}{d_x} \Pi_x = \bigoplus_x \frac{\text{Tr}[\Pi_x X]}{d_x} \mathbb{I}_x$$

★ Proof: any reducible unitary can be written as  $U(g) = \bigoplus_x U_x(g) = \sum_x U_x(g) \otimes I_{\bar{x}}$  where  $\bar{x}$  is the subspace  $U_{\bar{x}}$  does not act on.  
 $\langle X \rangle_G = \frac{1}{N} \sum_g U_g X U_g^\dagger = \frac{1}{N} \sum_g \sum_{x,x'} (U_x(g) \otimes I_{\bar{x}}) X (U_{x'}(g)^\dagger \otimes I_{\bar{x}}) = \frac{1}{N} \sum_g \sum_x (U_x(g) \otimes I_{\bar{x}}) X (U_x(g)^\dagger \otimes I_{\bar{x}}) = \frac{1}{d_x} \sum_x \text{Tr}[X \Pi_x] \Pi_x \otimes I_{\bar{x}} = \frac{1}{d_x} \bigoplus_x \text{Tr}[X \Pi_x] \Pi_x$

★ In a representation  $R$ , all elements which are in the same conjugacy class have the same trace. Proof:  $\text{Tr}(R(u^{-1}yu)) = \text{Tr}(R(u)R(u^{-1})R(y)) = \text{Tr}R(y)$

★ **Petit Orthogonality Theorem:** Let  $R_a$  and  $R_b$  be two non-equiv. unitary irreducible reps of a finite group of order  $N$ , then  $\sum_{g \in G} \chi_a^*(g) \chi_b(g) = N \delta_{a,b}$  where  $\chi_R(g) = \text{Tr}[R(g)]$ , or equiv.  $\sum_{\mu=1}^{N_c} \eta_\mu \chi_a^*(g) \chi_b(g) = N \delta_{a,b}$  with  $\eta_\mu$  the nb of elements in class  $\mu$  and  $N_c$  total nb of conjugacy classes

★ The set of all traces  $\{\chi_R(g)\}$  is the **character** of representation  $R$ . Two irreps are equivalent iff they have the same character. Proof by contradiction with Petit.

★ Trace of all reps within a conj. class are the same  $\rightarrow \chi_R(C_\mu) = \sum_a b_a \chi_a(C_\mu)$

★ Assuming a decomposition in irreps  $R(g) = \bigoplus_{a,x} R_{a,x}(g)$  for  $x = 1 \dots b_a$ , the number of irreps composing  $R_a$  is  $b_a = \frac{1}{N} \sum_\mu \eta_\mu \chi_a^*(C_\mu) \chi_R(C_\mu)$

★ A necessary and sufficient condition for a representation  $R$  to be an irrep is that  $\sum_{\mu=1}^{N_c} \eta_\mu |\chi(C_\mu)|^2 = N$ . Proof: decompose trace and use Petit.

Lie Algebras

★ Rotation through infinitesimal angle  $R(\theta) = \mathbb{I} + A$  and as  $R^T R = \mathbb{I}$  we must have  $A^T = -A \implies$  e.g. in 2D  $A = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \theta = J \theta$

★ Then  $R(\theta) = \lim_{N \rightarrow \infty} \left( R\left(\frac{\theta}{N}\right) \right)^N = e^{\theta J}$

★ What about 3D? 3 basis antisymmetric matrices:

$$J_x = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix} J_y = \begin{pmatrix} 0 & 0 & -1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix} J_z = \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

and any 3x3 antisymmetric matrix can be written as  $A = \theta_x J_x + \theta_y J_y + \theta_z J_z$  so that  $R(\theta) = e^{\theta_x J_x + \theta_y J_y + \theta_z J_z}$

★ Arbitrary dimension:  $R(\theta) = e^{\sum_i \theta_i J_i}$  or  $R(\theta) = e^{i \sum_i \theta_i \tilde{J}_i}$  with  $\tilde{J} = -iJ$

★ **Structure constants:** let  $R = \mathbb{I} + A, R' = \mathbb{I} + B$ . Then  $RR'R^{-1} = \mathbb{I} + B + [A, B]$ .  $[A, B] = i^2 \sum_{i,j} \theta_i \theta'_j [J_i, J_j]$  measures how much they don't commute. Generally we have  $[T_a, T_b] = i f_{abc} T_c$  where  $f_{abc}$  are the structure constants of the algebra.

★ **Lie algebra:** a linear space spanned by linear combinations  $\sum_i \theta_i J_i$  of the generators of the associated Lie group  $G$

★ As Lie groups are differentiable, it is always possible to write an element  $g$  of a Lie group  $G$  as the exponential of an element  $J$  of the corresponding Lie Algebra  $\mathfrak{g}$  i.e.  $\mathfrak{g} = \{J|e^{iJ} \in G\}$

★ The commutation relations of the generators  $J_j$  (i.e., a basis for  $\mathfrak{g}$ ) are the structure constants of the group and can be used to identify the Lie Algebra  $\mathfrak{g}$  (and thereby the corresponding Lie group  $G$ ).

★ What does it mean to represent an algebra? It means to find a set of matrices such that the defining commutation relations are satisfied.

★ Let  $G$  be a matrix Lie group with Lie algebra  $\mathfrak{g}$ . If  $R$  is a representation of  $G$  on  $V$ , then there exists a unique representation  $r$  of  $\mathfrak{g}$  on  $V$  given by  $r(X) = \left. \frac{d}{d\theta} (R(e^{\theta X})) \right|_{\theta=0}$  for all  $X \in \mathfrak{g}$ . We call  $r$  the rep of  $\mathfrak{g}$  induced by  $R$ .

Ladder operators

$$\star S_{\pm} = S_x \pm i S_y \quad \star S_x = \frac{1}{2} (S_+ + S_-) \quad \star S_y = \frac{1}{2i} (S_+ - S_-)$$

$$\star S_+ |s, m\rangle = \sqrt{s(s+1) - m(m+1)} |s, m+1\rangle$$

$$\star S_- |s, m\rangle = \sqrt{s(s+1) - m(m-1)} |s, m-1\rangle$$

★ For a composite system the ladder operators are  $S_{\pm} = j_{\pm} \otimes \mathbb{I} + \mathbb{I} \otimes j_{\pm}$

★ Obtaining **Clebsch-Gordan** coefficients: Start by the highest spin state (e.g. for two spin-1 states  $|s=1, m=1\rangle |s=1, m=1\rangle = |S=2, m=2\rangle$ ), then apply lowering operator on both sides until you get 0. To find the other sectors, we must first find the set of states which are orthogonal to the previous ones, and find the highest weight among those.

**Irreducible representations of C3v**

(i) Trivial      (ii) 2D irrep ↓

$$R(e) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} R(c_+) = \begin{pmatrix} -\frac{1}{2} & -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & -\frac{1}{2} \end{pmatrix} R(c_-) = \begin{pmatrix} -\frac{1}{2} & \frac{\sqrt{3}}{2} \\ -\frac{\sqrt{3}}{2} & -\frac{1}{2} \end{pmatrix}$$

$$R(\sigma) = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} R(\sigma') = \begin{pmatrix} \frac{1}{2} & \frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & -\frac{1}{2} \end{pmatrix} R(\sigma'') = \begin{pmatrix} \frac{1}{2} & -\frac{\sqrt{3}}{2} \\ -\frac{\sqrt{3}}{2} & -\frac{1}{2} \end{pmatrix}$$

(iii)  $R(e) = 1, R(c_+) = 1, R(c_-) = 1, R(\sigma) = -1, R(\sigma') = -1, R(\sigma'') = -1$

	$e$	$2C_3$	$3\sigma_v$
$R_{(i)}$	1	1	1
$R_{(ii)}$	2	-1	0
$R_{(iii)}$	1	1	-1

★ Character table:

**3D representation of C3v (reducible)** p.4

Triangle in a 3D space with vertex at positions (1; 0; 0), (0; 1; 0) and (0; 0; 1)

$$R(e) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} R(c_+) = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} R(c_-) = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$

$$R(\sigma) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} R(\sigma') = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} R(\sigma'') = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

**Other groups**

★  $SU(2)$ : single qubit rotations  $\rightarrow e^{-i\sigma_x\theta_1}e^{-i\sigma_z\theta_2}e^{-i\sigma_x\theta_3}$   
 2D irreducible representation: Pauli matrices  
 3D irreducible representation: same as for  $SO(3)$ , obtain  $L_x, L_y, L_z$  from ladder operators acting on the basis  $|l, m\rangle$

★  $U(1)$ : symmetry group of rotations around one axis (e.g.  $x$ ), such as phase of a laser. The associated representation is the set of rotations by an angle  $\theta \in [0, 2\pi)$  about the axis  $U(\theta) = e^{-i\theta\sigma_x/2}$ . The representation is reducible in 1D reps  $\{1\}$  and  $\{e^{-i\theta}\}$ . For example for  $\sigma_x$   $U_g = \begin{pmatrix} 1 & 0 \\ 0 & e^{-i\theta} \end{pmatrix} = |+\rangle\langle +| + e^{-i\theta} |-\rangle\langle -|$   
 Averaging a state  $\rho$ :  $\langle\rho\rangle_G = \langle +|\rho|+ \rangle |+\rangle\langle +| + \langle -|\rho|-\rangle |-\rangle\langle -|$  which is a projection onto the  $x$ -axis

★  $U(2)$ : light polarisation  $\rightarrow e^{-i\phi}e^{-i\sigma_x\theta_1}e^{-i\sigma_z\theta_2}e^{-i\sigma_x\theta_3}$

★ Possible dimensions of  $SO(3)$  are odd

★ Any representation of  $SO(3)$  is also a representation of  $SU(2)$ . The converse is not true. For each representation in  $SO(3)$  there are two in  $SU(2)$  ( $SU(2)$  is a double cover of  $SO(3)$ )

Bayes' theorem
$P(A B) = \frac{P(B A)P(A)}{P(B)}$
Eigenspectrum of generic 2 x 2 hermitian matrix
★ Matrix of form $\begin{pmatrix} V_{11} & V_{12} \\ V_{12}^* & V_{22} \end{pmatrix}$
★ Eigenvalues $E_{\pm} = \frac{1}{2}(V_{11}+V_{22}\pm\Delta E)$ where $\Delta E = \sqrt{(V_{11}-V_{22})^2+4 V_{12} ^2}$
★ The normalised eigenvectors are $\begin{pmatrix} \frac{V_{12}}{\sqrt{\Delta E\left(\frac{\Delta E}{2}\pm\frac{(V_{22}-V_{11})}{2}\right)}}e^{i\phi_{\pm}} \\ \pm\sqrt{\frac{\frac{\Delta E}{2}\pm\frac{(V_{22}-V_{11})}{2}}{\Delta E}}e^{i\phi_{\pm}} \end{pmatrix}$
valid for any phase $\phi_{\pm}$
Eigenvectors of Pauli matrices
$\psi_{x+} = \frac{1}{\sqrt{2}}\begin{pmatrix} 1 \\ 1 \end{pmatrix}, \psi_{x-} = \frac{1}{\sqrt{2}}\begin{pmatrix} 1 \\ -1 \end{pmatrix}$
$\psi_{y+} = \frac{1}{\sqrt{2}}\begin{pmatrix} 1 \\ i \end{pmatrix}, \psi_{y-} = \frac{1}{\sqrt{2}}\begin{pmatrix} 1 \\ -i \end{pmatrix}$
$\psi_{z+} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \psi_{z-} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}.$
Working with the symmetric and antisymmetric subspaces
★ The projectors onto the symmetric and antisymmetric subspaces are given by $\Pi_+ = \sum_{i=0}^2  \phi_i\rangle\langle\phi_i  = \frac{\mathbb{I}\otimes\mathbb{I} + \text{SWAP}}{2}$ $\Pi_- =  \phi_3\rangle\langle\phi_3  = \frac{\mathbb{I}\otimes\mathbb{I} - \text{SWAP}}{2}$
★ $\langle\rho\rangle = \frac{1}{3}\text{Tr}[\Pi_+\rho] + \text{Tr}[\Pi_-\rho]\Pi_- = \frac{\mathbb{I}\otimes\mathbb{I}}{6}(2 - \text{Tr}[\text{SWAP}\rho]) + \frac{\text{SWAP}}{6}(2\text{Tr}[\text{SWAP}\rho] - 1)$
★ If $\rho$ is in the symmetric subspace $\text{Tr}[\rho\text{SWAP}] = 1$ . $-1$ if in antisymmetric.
★ $\text{Tr}[(A\otimes B)\text{SWAP}] = \text{Tr}[AB]$
★ If we define Bloch vectors $\boldsymbol{r}_1$ and $\boldsymbol{r}_2$ corresponding to $\rho$ and $\sigma$ , then $\text{Tr}[\sigma\rho] = \frac{1 + \boldsymbol{r}_1\cdot\boldsymbol{r}_2}{2}$
★ $\text{SWAP} = \frac{1}{2}\sum_{\sigma\in\{1,\sigma_x,\sigma_y,\sigma_z\}}\sigma\otimes\sigma$

Miscellanea				
★ To diagonalise off-diagonal matrix $A$ take the square. $A^2$ will be diagonal and then from $\lambda^2$ you have candidates for $\lambda$	*	$e$	$a$	$b$
	$e$	$e$	$a$	$b$
★ Symmetry group of a rectangle	$a$	$a$	$e$	$b$
	$b$	$b$	$c$	$a$
	$c$	$c$	$b$	$e$
★ $\text{Tr}[R(e)] = \text{dim}(R)$				