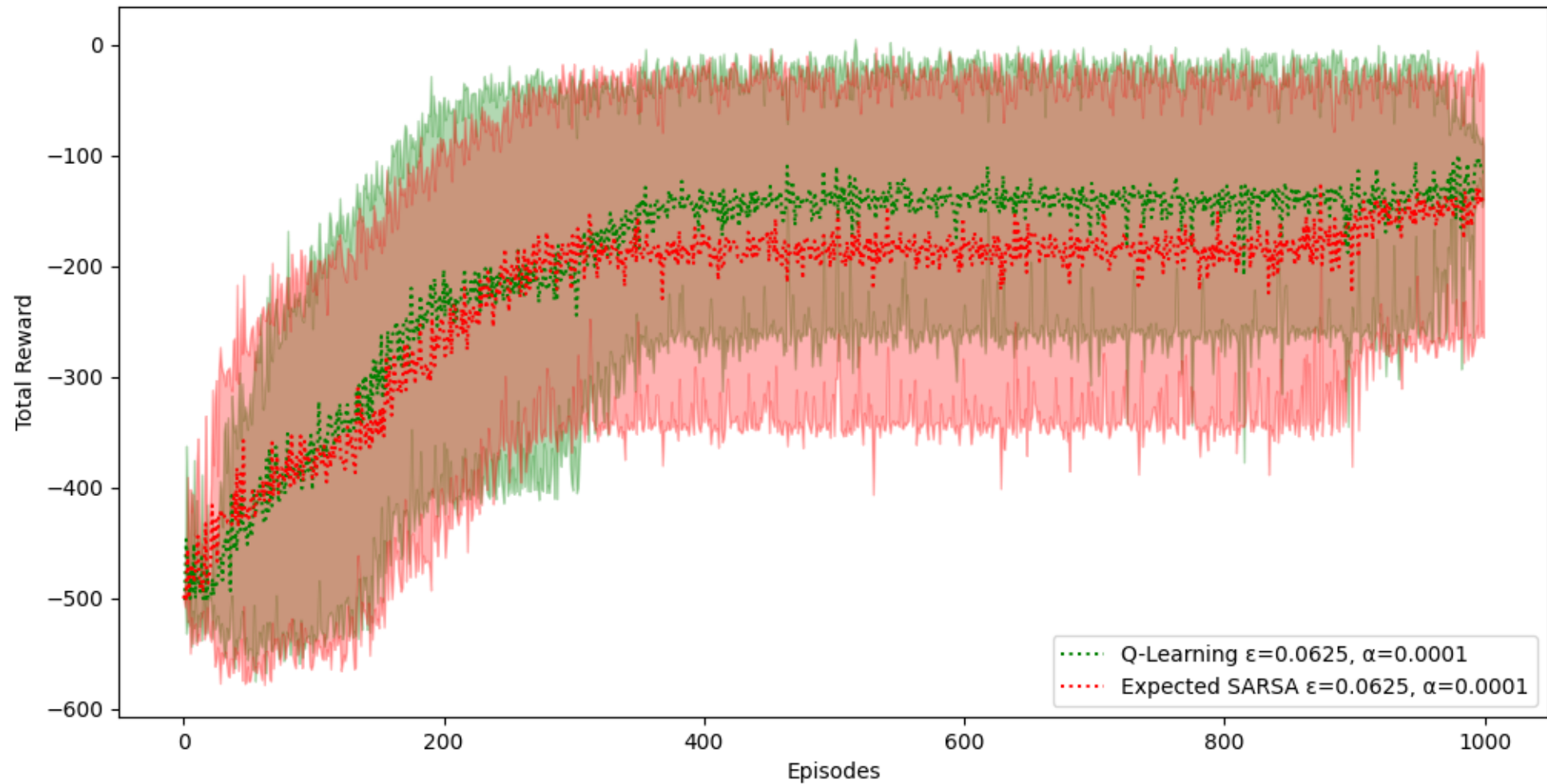
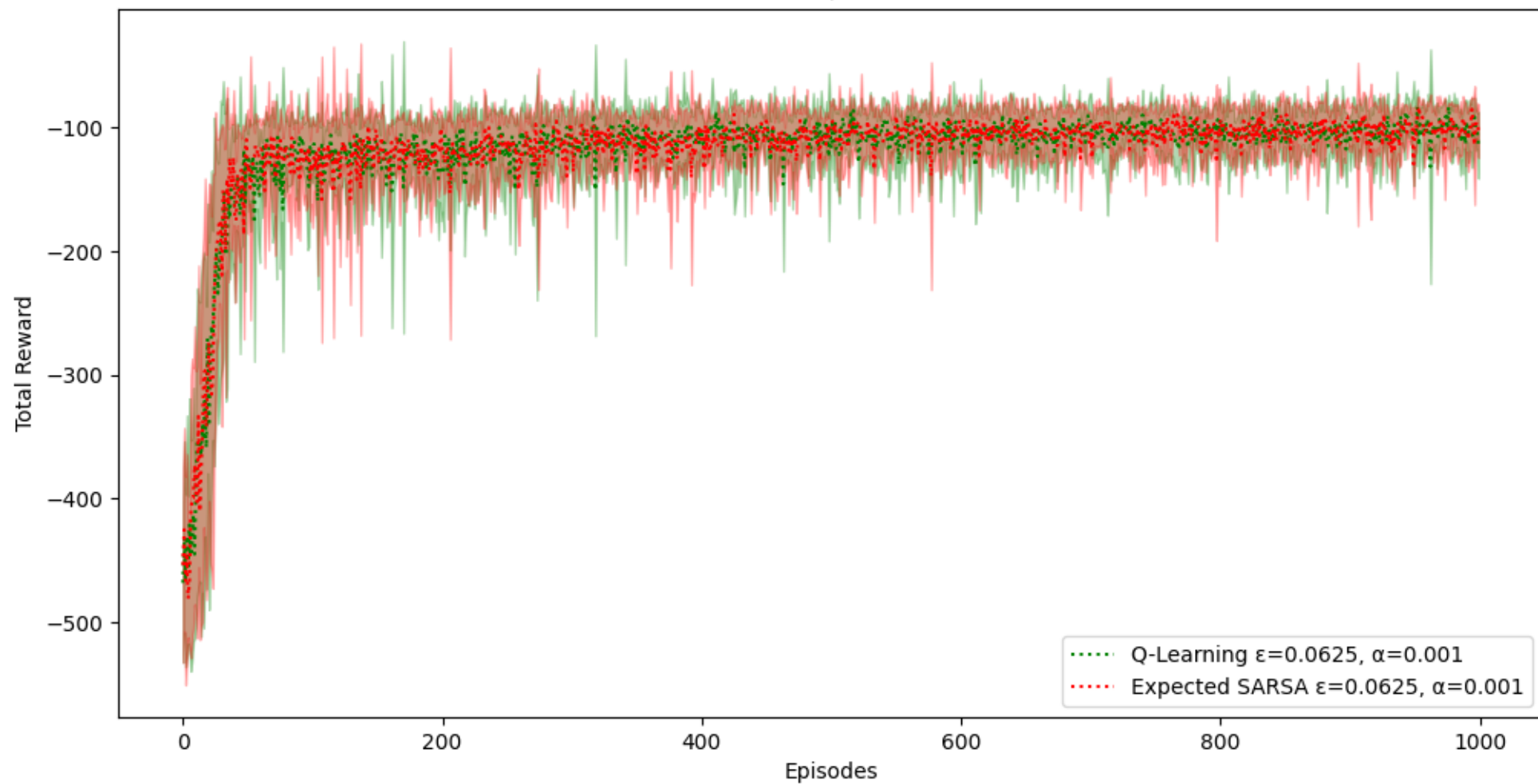


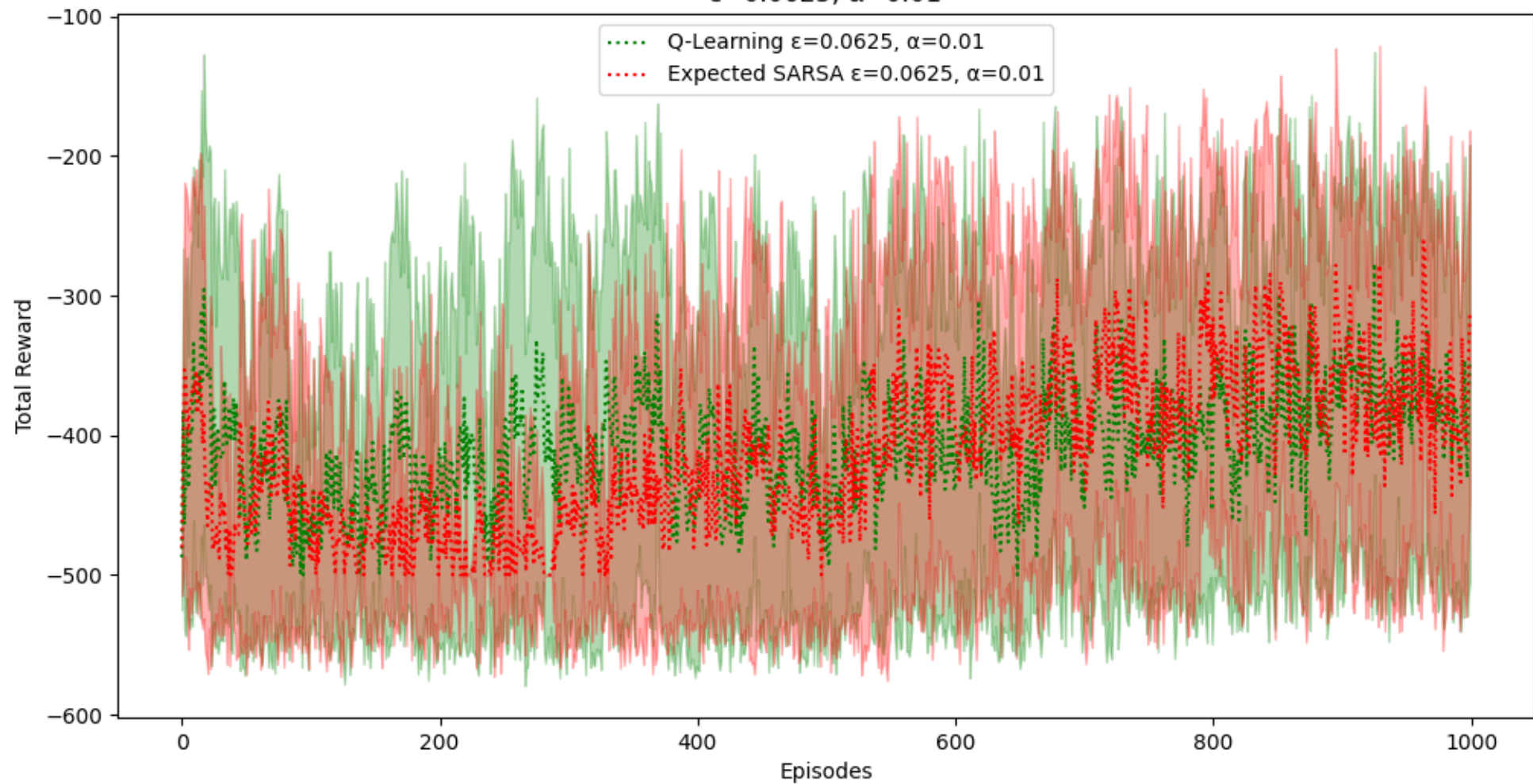
Acrobot-v1 with Replay Buffer
 $\epsilon=0.0625$, $\alpha=0.0001$



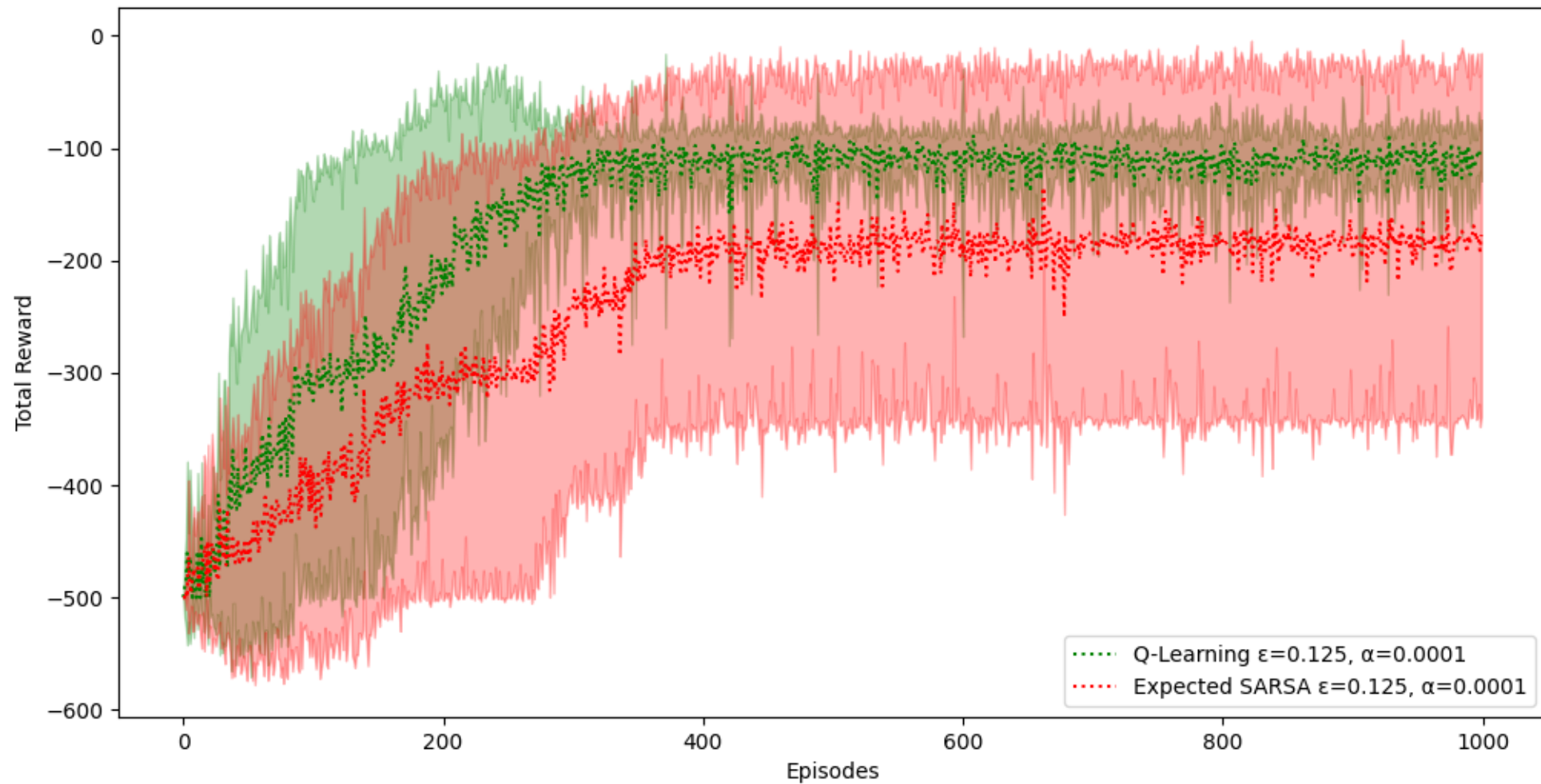
Acrobot-v1 with Replay Buffer
 $\epsilon=0.0625$, $\alpha=0.001$



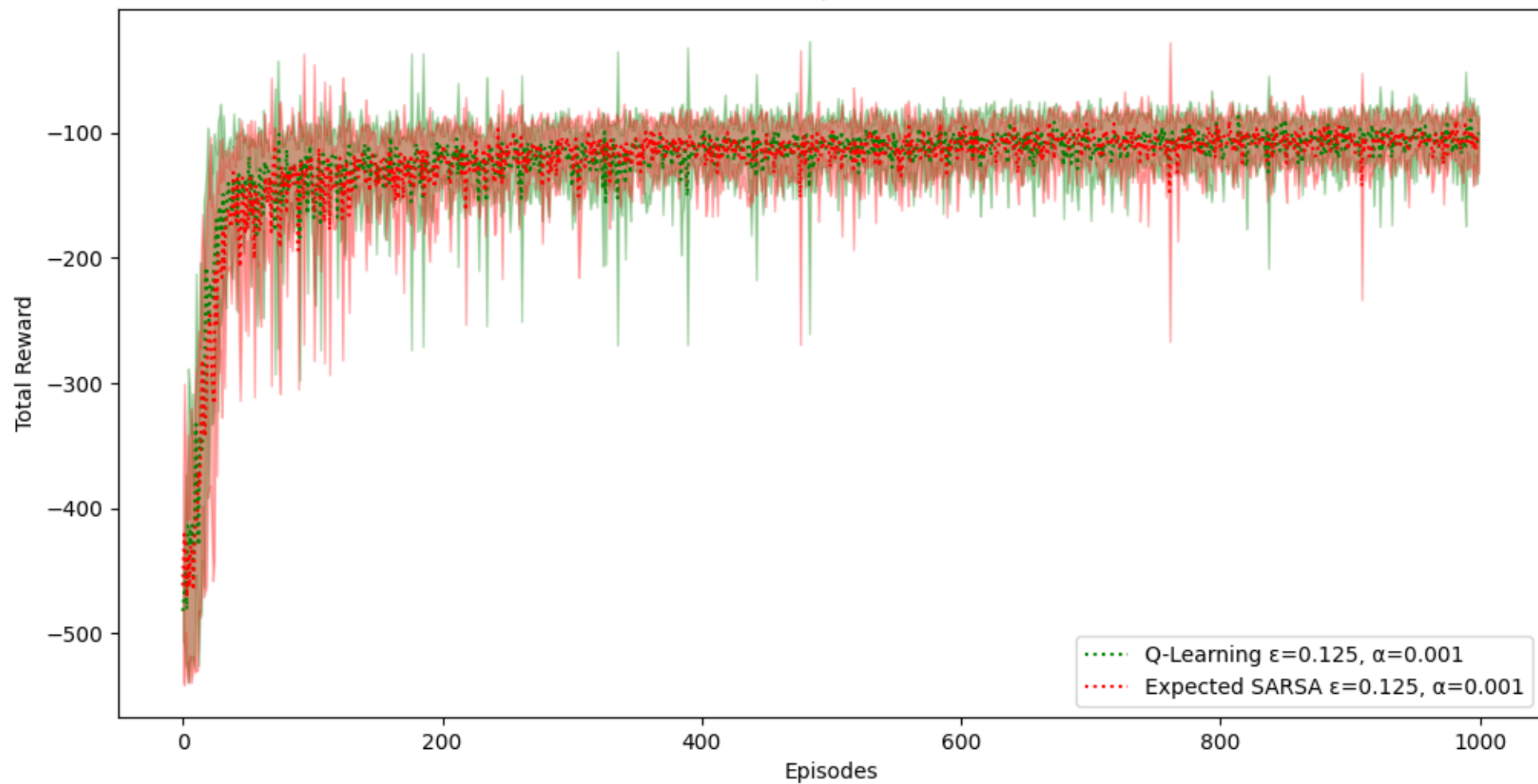
Acrobot-v1 with Replay Buffer
 $\epsilon=0.0625$, $\alpha=0.01$



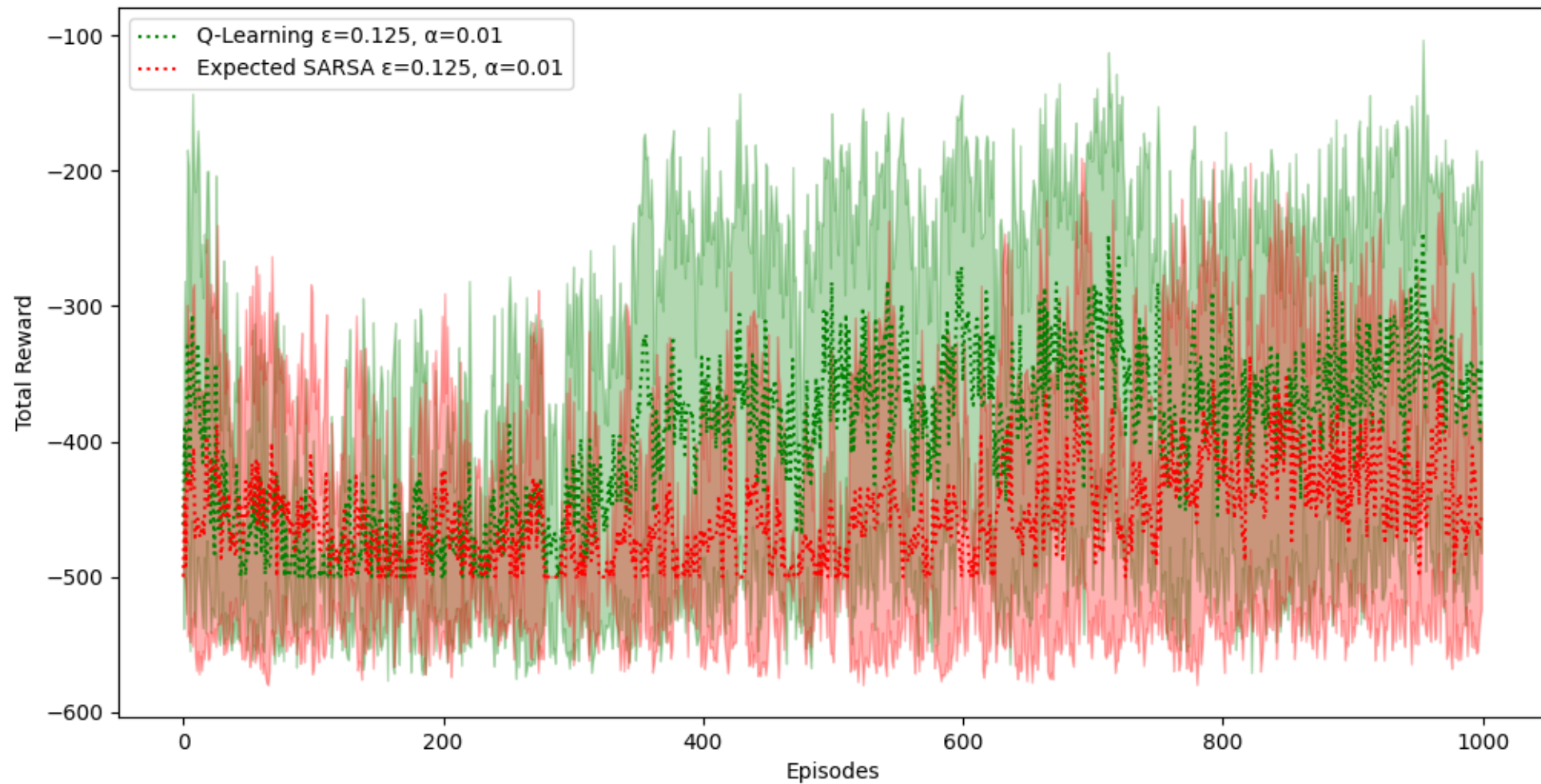
Acrobot-v1 with Replay Buffer
 $\epsilon=0.125$, $\alpha=0.0001$



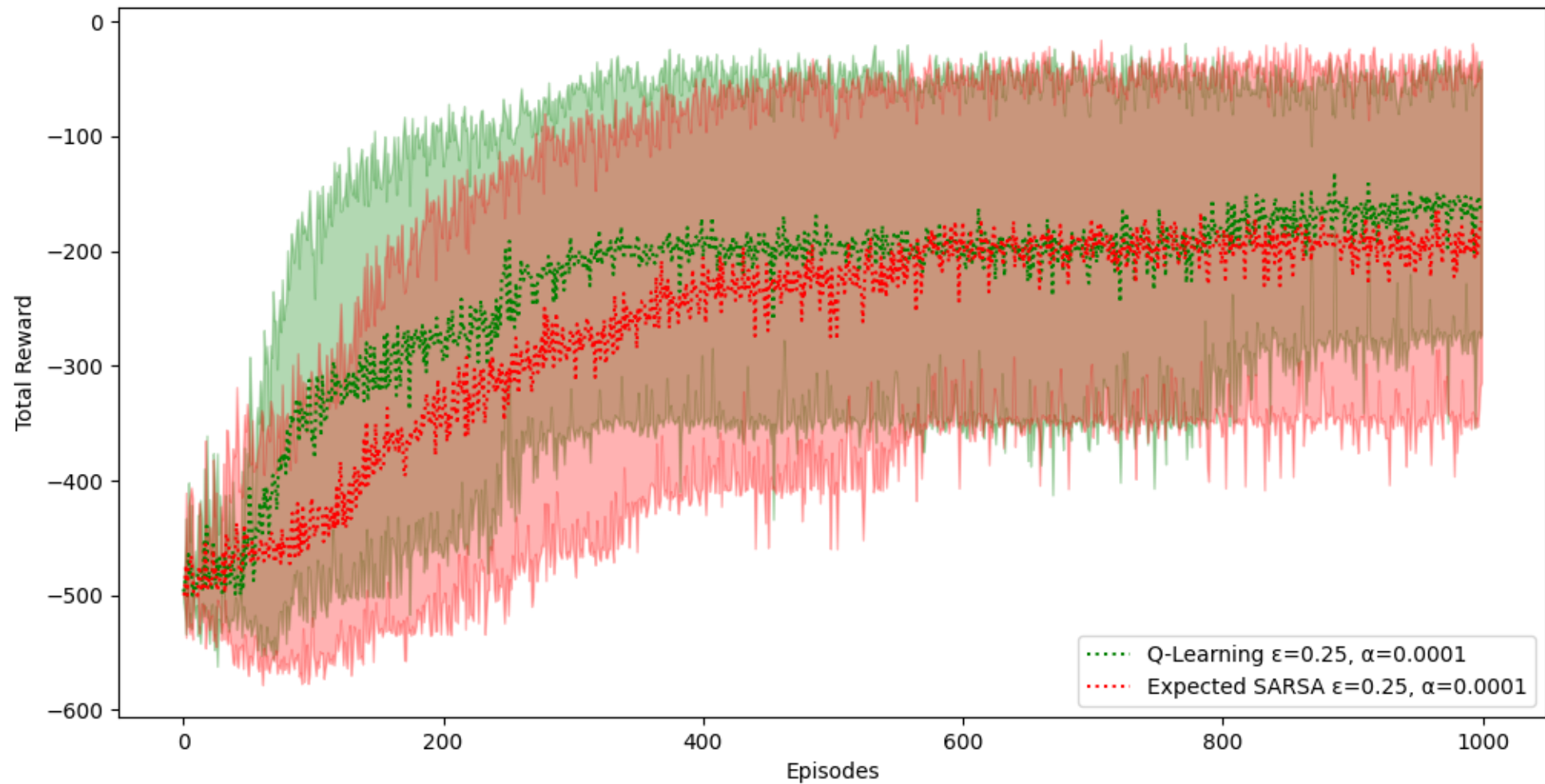
Acrobot-v1 with Replay Buffer
 $\epsilon=0.125, \alpha=0.001$



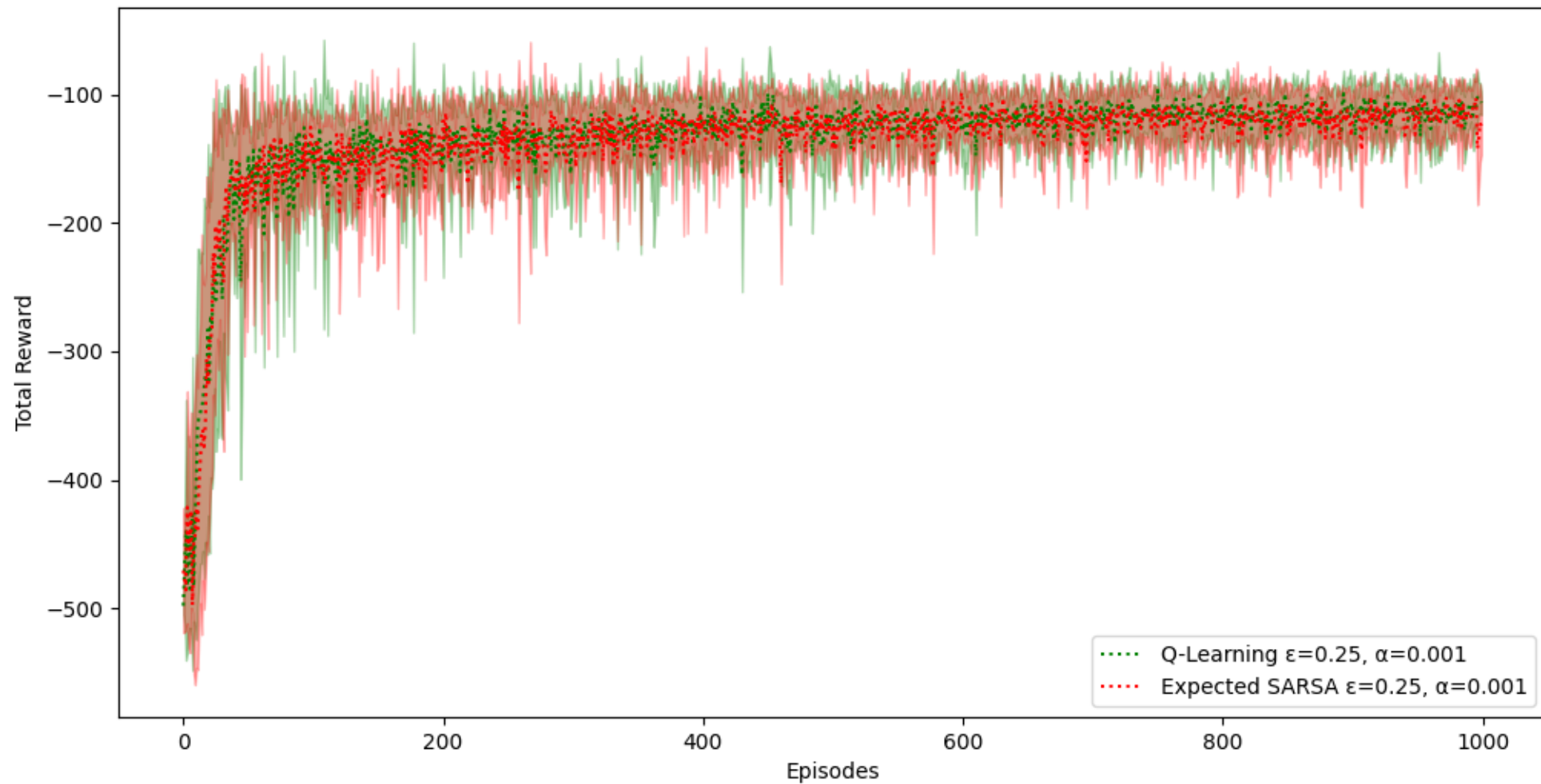
Acrobot-v1 with Replay Buffer
 $\epsilon=0.125$, $\alpha=0.01$



Acrobot-v1 with Replay Buffer
 $\epsilon=0.25, \alpha=0.0001$



Acrobot-v1 with Replay Buffer
 $\epsilon=0.25, \alpha=0.001$



Acrobot-v1 with Replay Buffer
 $\epsilon=0.25, \alpha=0.01$

