



1. La distancia media entre dos señales periódicas  $x_1(t) \in \mathbb{R}, \mathbb{C}$  y  $x_2(t) \in \mathbb{R}, \mathbb{C}$ ; se puede expresar a partir de la potencia media de la diferencia entre ellas:

$$d^2(x_1, x_2) = \bar{P}_{x_1 - x_2} = \lim_{T \rightarrow \infty} \frac{1}{T} \int_T |x_1(t) - x_2(t)|^2 dt.$$

Sea  $x_1(t)$  y  $x_2(t)$  dos señales definidas como:

$$x_1(t) = Ae^{-jn\omega_0 t}$$

$$x_2(t) = Be^{jm\omega_0 t}$$

con  $\omega_0 = \frac{2\pi}{T}$ ;  $T, A, B \in \mathbb{R}^+$  y  $n, m \in \mathbb{Z}$ . Determine la distancia entre las dos señales. Compruebe sus resultados con Python.

$$\begin{aligned} \bar{P}_{x_1} &= \frac{1}{T} \int_T x_1(t) x_1^*(t) dt = \frac{1}{T} \int_0^T Ae^{-jn\omega_0 t} (Ae^{-jn\omega_0 t})^* dt = \frac{1}{T} \int_0^T Ae^{-jn\omega_0 t} Ae^{jn\omega_0 t} dt \\ &= \frac{A^2}{T} \int_0^T e^{(n-n)\omega_0 t} dt = \frac{A^2}{T} \int_0^T 1 dt = \frac{A^2}{T} (T-0) = \frac{A^2}{T} \cdot T = A^2 \end{aligned}$$

$$\begin{aligned} \bar{P}_{x_2} &= \frac{1}{T} \int_T x_2(t) x_2^*(t) dt = \frac{1}{T} \int_0^T Be^{jm\omega_0 t} (Be^{jm\omega_0 t})^* dt = \frac{1}{T} \int_0^T Be^{jm\omega_0 t} Be^{-jm\omega_0 t} dt \\ &= \frac{B^2}{T} \int_0^T e^{(m-m)\omega_0 t} dt = \frac{B^2}{T} \int_0^T 1 dt = \frac{B^2}{T} (T-0) = \frac{B^2}{T} \cdot T = B^2 \end{aligned}$$

El cruzado tiene dos casos:

$$\begin{aligned} \textcircled{1} \text{ Si } n \neq -m \rightarrow x &= -\frac{2}{T} \int_T x_1(t) x_2^*(t) dt = -\frac{2}{T} \int_0^T Ae^{-jn\omega_0 t} (Be^{jm\omega_0 t})^* dt \\ &= -\frac{2}{T} \int_0^T Ae^{-jn\omega_0 t} Be^{jmb\omega_0 t} dt = -\frac{2AB}{T} \int_0^T e^{j(m-n)\omega_0 t} dt \rightarrow \text{Si } n, m \in \mathbb{Z} \rightarrow n+m = r \in \mathbb{Z} \\ &= -\frac{2AB}{T} \int_0^T e^{jr\omega_0 t} dt = -\frac{2AB}{T} \left[ \frac{e^{jr\omega_0 t}}{jr\omega_0} \right]_0^T = -\frac{2AB}{T} \frac{1}{r\frac{2\pi}{T}} \left( e^{jr\frac{2\pi}{T}T} - e^{jr\frac{2\pi}{T}0} \right) \\ &= -\frac{2AB}{T} \frac{1}{r\frac{2\pi}{T}} (e^{jr2\pi} - 1) = -\frac{2AB}{T} \frac{1}{r\frac{2\pi}{T}} (\cos(2\pi r) - j\sin(2\pi r) - 1) \\ &= \frac{2AB}{T} \frac{1}{r\frac{2\pi}{T}} (1 - 0 - 1) = \frac{2AB}{T} \frac{1}{r\frac{2\pi}{T}} = 0 \end{aligned}$$

$$\begin{aligned} \textcircled{2} \text{ Si } n = -m \rightarrow x &= -\frac{2}{T} \int_T x_1(t) x_2^*(t) dt = -\frac{2}{T} \int_0^T Ae^{-jn\omega_0 t} (Be^{jm\omega_0 t})^* dt = -\frac{2}{T} \int_0^T Ae^{-jn\omega_0 t} Be^{jmb\omega_0 t} dt \\ &= -\frac{2}{T} \int_0^T Ae^{-jn\omega_0 t} Be^{jmb\omega_0 t} dt = -\frac{2AB}{T} \int_0^T e^{j(m-n)\omega_0 t} dt = -\frac{2AB}{T} \int_0^T 1 dt \\ &= -\frac{2AB}{T} (T-0) = -\frac{2AB}{T} \cdot T = -2AB \end{aligned}$$

$$\bar{P}_{x_1 - x_2} = \begin{cases} A^2 + B^2 & ; n \neq -m \\ A^2 + B^2 - 2AB & ; n = -m \end{cases}$$

$$d(x_1, x_2) = \begin{cases} \sqrt{A^2 + B^2} & ; n \neq -m \\ \sqrt{A^2 + B^2 - 2AB} & ; n = -m \end{cases}$$



$$x_1(t) = Ae^{-jn\omega_0 t}, \quad x_2(t) = Be^{jm\omega_0 t}; \quad \omega_0 = \frac{2\pi}{T}$$

$$d^2(x_1, x_2) = \bar{P}_{x_1 - x_2} = \lim_{T \rightarrow \infty} \frac{1}{T} \int_T |x_1(t) - x_2(t)|^2 dt$$

$$\begin{aligned} \bar{P}_{x_1 - x_2} &= \frac{1}{T} \int_T |x_1(t) - x_2(t)|^2 dt \\ &= \frac{1}{T} \left( \int_T (x_1(t) - x_2(t))(x_1(t) - x_2(t))^* dt \right) \\ &= \frac{1}{T} \left( \int_T (x_1(t) - x_2(t))(x_1^*(t) - x_2^*(t)) dt \right) \\ &= \frac{1}{T} \left( \int_T x_1(t)x_1^*(t) dt - \int_T x_1(t)x_2^*(t) dt - \int_T x_2(t)x_1^*(t) dt + \int_T x_2(t)x_2^*(t) dt \right) \\ &= \underbrace{\frac{1}{T} \int_T |x_1(t)|^2 dt}_{\bar{P}_{x_1}} - \underbrace{\frac{2}{T} \int_T x_1(t)x_2^*(t) dt}_{C_{x_1 x_2}} + \underbrace{\frac{1}{T} \int_T |x_2(t)|^2 dt}_{\bar{P}_{x_2}} \end{aligned}$$

2. Encuentre la señal en tiempo discreto al utilizar un conversor análogo digital con frecuencia de muestreo de  $5\text{kHz}$  y 4 bits de capacidad de representación, aplicado a la señal continua:

$$x(t) = 3 \cos(1000\pi t) + 5 \sin(3000\pi t) + 10 \cos(11000\pi t).$$

Realizar la simulación del proceso de discretización (incluyendo al menos tres periodos de  $x(t)$ ). En caso de que la discretización no sea apropiada, diseñe e implemente un conversor adecuado para la señal estudiada.

$$X(t) = 3 \cos(1000\pi t) + 5 \sin(3000\pi t) + 10 \cos(11000\pi t)$$

$$F_s = 5\text{kHz}, \quad \# \text{ de estados} = 2^{4\text{bits}} = 16$$

$$t = nT_s \rightarrow F_s = \frac{1}{T_s}; \quad F = \frac{1}{T} \rightarrow T = \frac{2\pi}{\omega}$$

$$\frac{A \cos(\omega_c n)}{A \cos(2\pi f n)} \rightarrow \omega_c = 2\pi f \rightarrow f = \frac{T_s}{T} = \frac{F}{F_s}$$

$$X(t) = X_1(t) + X_2(t) + X_3(t) \rightarrow$$

Para  $X_1(t) = 3 \cos(1000\pi t)$

$$\omega_1 = 1000\pi \rightarrow T_1 = \frac{2\pi}{\omega_1} = \frac{2\pi}{1000\pi} = \frac{1}{500} \rightarrow F_1 = \frac{1}{T_1} = \frac{1}{\frac{1}{500}} = 500\text{Hz} \rightarrow X_1[n] = A \cos(2\pi n \cdot \frac{F}{F_s}) = 3 \cos(2\pi n \cdot \frac{500}{5000}) = 3 \cos(\frac{\pi n}{5})$$

Para  $X_2(t) = 5 \sin(3000\pi t)$

$$\omega_2 = 3000\pi \rightarrow T_2 = \frac{2\pi}{\omega_2} = \frac{2\pi}{3000\pi} = \frac{1}{1500} \rightarrow F_2 = \frac{1}{T_2} = \frac{1}{\frac{1}{1500}} = 1500\text{Hz} \rightarrow X_2[n] = A \sin(2\pi n \cdot \frac{F}{F_s}) = 5 \sin(2\pi n \cdot \frac{1500}{5000}) = 5 \sin(\frac{3\pi n}{5})$$

Para  $X_3(t) = 10 \cos(11000\pi t)$

$$\omega_3 = 11000\pi \rightarrow T_3 = \frac{2\pi}{\omega_3} = \frac{2\pi}{11000\pi} = \frac{1}{5500} \rightarrow F_3 = \frac{1}{T_3} = \frac{1}{\frac{1}{5500}} = 5500\text{Hz} \rightarrow X_3[n] = A \cos(2\pi n \cdot \frac{F}{F_s}) = 10 \cos(2\pi n \cdot \frac{5500}{5000}) = 10 \cos(\frac{11\pi n}{5})$$

$$X[n] = 3 \cos(\frac{\pi n}{5}) + 5 \sin(\frac{3\pi n}{5}) + 10 \cos(\frac{11\pi n}{5})$$

$$X[n] = 3 \cos(\frac{\pi}{5}n) + 5 \sin(\frac{3\pi}{5}n) + 10 \cos(\frac{11\pi}{5}n)$$

$$X[n] = 13 \cos(\frac{\pi}{5}n) + 5 \sin(\frac{3\pi}{5}n)$$

$$\frac{\omega_1}{\omega_2} = \frac{1000\pi}{3000\pi} = \frac{1}{3} \in \mathbb{Q}$$

$$\frac{\omega_1}{\omega_3} = \frac{1000\pi}{11000\pi} = \frac{1}{11} \in \mathbb{Q}$$

$$\frac{\omega_2}{\omega_3} = \frac{3000\pi}{11000\pi} = \frac{3}{11} \in \mathbb{Q}$$

Como todas son racionales la señal es cuasiperiódica.

$\int_i F_s \geq 2F_{\max} \rightarrow 2F_{\max} = 2 \cdot 5500\text{Hz} = 11000\text{Hz} \rightarrow F_s = 5000\text{Hz}$

No cumple Nyquist

Vamos a comparar con las originales.  $\rightarrow -\pi \leq \omega \leq \pi$

$$\omega_1 = \frac{1}{5}\pi \checkmark, \quad \omega_2 = \frac{3}{5}\pi \checkmark, \quad \omega_3 = \frac{11}{5}\pi \times \rightarrow F_s \text{ una copia / aliasing}$$

$$\omega_{3\text{original}} = \frac{11}{5}\pi - 2\pi = \frac{1}{5}\pi$$

Suponemos una frecuencia de muestreo mucho más grande

$$F_s = 4F_{\max} \rightarrow F_s = 4(5500)\text{Hz} = 22\text{kHz}$$

$$T_s = \frac{1}{22000}$$

Para  $X_1(t) = 3 \cos(1000\pi t)$

$$\omega_1 = 1000\pi \rightarrow T_1 = \frac{2\pi}{\omega_1} = \frac{2\pi}{1000\pi} = \frac{1}{500} \rightarrow F_1 = \frac{1}{T_1} = \frac{1}{\frac{1}{500}} = 500\text{Hz} \rightarrow X_1[n] = A \cos(2\pi n \cdot \frac{F}{F_s}) = 3 \cos(2\pi n \cdot \frac{500}{22000}) = 3 \cos(\frac{\pi n}{22})$$

Para  $X_2(t) = 5 \sin(3000\pi t)$

$$\omega_2 = 3000\pi \rightarrow T_2 = \frac{2\pi}{\omega_2} = \frac{2\pi}{3000\pi} = \frac{1}{1500} \rightarrow F_2 = \frac{1}{T_2} = \frac{1}{\frac{1}{1500}} = 1500\text{Hz} \rightarrow X_2[n] = A \sin(2\pi n \cdot \frac{F}{F_s}) = 5 \sin(2\pi n \cdot \frac{1500}{22000}) = 5 \sin(\frac{3\pi n}{22})$$

Para  $X_3(t) = 10 \cos(11000\pi t)$

$$\omega_3 = 11000\pi \rightarrow T_3 = \frac{2\pi}{\omega_3} = \frac{2\pi}{11000\pi} = \frac{1}{5500} \rightarrow F_3 = \frac{1}{T_3} = \frac{1}{\frac{1}{5500}} = 5500\text{Hz} \rightarrow X_3[n] = A \cos(2\pi n \cdot \frac{F}{F_s}) = 10 \cos(2\pi n \cdot \frac{5500}{22000}) = 10 \cos(\frac{\pi n}{2})$$

$$X[n] = 3 \cos(\frac{\pi n}{22}) + 5 \sin(\frac{3\pi n}{22}) + 10 \cos(\frac{\pi n}{2})$$

Vamos a comparar con las originales.  $\rightarrow -\pi \leq \omega \leq \pi$

$$\omega_1 = \frac{1}{22}\pi \checkmark, \quad \omega_2 = \frac{3}{22}\pi \checkmark, \quad \omega_3 = \frac{1}{22}\pi \checkmark \rightarrow \text{Las tres frecuencias digitales están en los originales.}$$

$$X[n] = 3 \cos(\frac{\pi n}{22}) + 5 \sin(\frac{3\pi n}{22}) + 10 \cos(\frac{\pi n}{2})$$



Para saber el periodo a graficar:

$$T = r \frac{2\pi}{\omega_1} = f \frac{2\pi}{\omega_2} = m \frac{2\pi}{\omega_3}$$

$$T = r \frac{2\pi}{1000\pi} = f \frac{2\pi}{3000\pi} = m \frac{2\pi}{11000\pi}$$

$$T = r \frac{1}{500} = f \frac{1}{1500} = m \frac{1}{5500}$$

$$5500T = r \frac{5500}{500} = f \frac{5500}{1500} = m \frac{5500}{5500}$$

$$5500T = r \cdot 11 = f \frac{11}{3} = m$$

$$3 \cdot 5500T = r \cdot 3 \cdot 11 = f \cdot 3 \cdot \frac{11}{3} = m \cdot 3$$

$$16500T = 33r = 11f = 3m \quad \text{mcm}\{33, 11, 3\} = 33$$

$$16500T = 33$$

$$T = \frac{33}{16500}$$

$$T = \frac{1}{500}$$



3. Sea  $x''(t)$  la segunda derivada de la señal  $x(t)$ , donde  $t \in [t_i, t_f]$ . Demuestre que los coeficientes de la serie exponencial de Fourier se pueden calcular según:

$$c_n = \frac{1}{(t_i - t_f)n^2\omega_0^2} \int_{t_i}^{t_f} x''(t) e^{-jn\omega_0 t} dt; \quad n \in \mathbb{Z}.$$

¿Cómo se pueden calcular los coeficientes  $a_n$  y  $b_n$  desde  $x''(t)$  en la serie trigonométrica de Fourier?

Con  $X(t)$  para  $t \in [t_i, t_f]$   
 Demostrar:  $C_n = \frac{1}{(t_i - t_f)n^2\omega_0^2} \int_{t_i}^{t_f} x''(t) e^{-jn\omega_0 t} dt$  con  $n \in \mathbb{Z}$

Tenemos:  $X(t) = \sum_n C_n e^{jn\omega_0 t}$

$$X'(t) = \frac{\partial}{\partial t} \sum_n C_n e^{jn\omega_0 t} = \sum_n C_n \frac{\partial}{\partial t} e^{jn\omega_0 t}$$

$$X''(t) = \frac{\partial}{\partial t} X'(t) = \frac{\partial}{\partial t} \sum_n C_n \frac{\partial}{\partial t} e^{jn\omega_0 t} = \sum_n C_n \frac{\partial^2}{\partial t^2} e^{jn\omega_0 t}$$

$$\frac{\partial}{\partial t} e^{jn\omega_0 t} = jn\omega_0 e^{jn\omega_0 t}; \quad \frac{\partial^2}{\partial t^2} e^{jn\omega_0 t} = \frac{\partial}{\partial t} (jn\omega_0 e^{jn\omega_0 t}) = jn\omega_0 \cdot jn\omega_0 e^{jn\omega_0 t} = -n^2\omega_0^2 e^{jn\omega_0 t}$$

$$X''(t) = \sum_n C_n \frac{\partial^2}{\partial t^2} e^{jn\omega_0 t} = \sum_n C_n n^2 \omega_0^2 e^{jn\omega_0 t} = \sum_n C_{-n} e^{jn\omega_0 t}; \quad \text{con } C_{-n} = -C_n n^2 \omega_0^2$$

Si  $C_n = \frac{1}{t_f - t_i} \int_{t_i}^{t_f} X(t) e^{-jn\omega_0 t} dt$  y  $C_{-n} = \frac{1}{t_f - t_i} \int_{t_i}^{t_f} X'(t) e^{-jn\omega_0 t} dt \rightarrow$  Reemplazamos el  $C_{-n} \rightarrow -C_n n^2 \omega_0^2 = \frac{1}{t_f - t_i} \int_{t_i}^{t_f} X''(t) e^{-jn\omega_0 t} dt$

$$C_n = \frac{1}{-(t_f - t_i)n^2\omega_0^2} \int_{t_i}^{t_f} X''(t) e^{-jn\omega_0 t} dt$$

$$C_n = \frac{1}{(t_i - t_f)n^2\omega_0^2} \int_{t_i}^{t_f} X''(t) e^{-jn\omega_0 t} dt$$

$$C_n = \frac{1}{(t_i - t_f)n^2\omega_0^2} \int_{t_i}^{t_f} X''(t) e^{-jn\omega_0 t} dt = \frac{1}{(t_i - t_f)n^2\omega_0^2} \int_{t_i}^{t_f} X''(t) (\cos(n\omega_0 t) - j\sin(n\omega_0 t)) dt$$

$$= \frac{1}{(t_i - t_f)n^2\omega_0^2} \int_{t_i}^{t_f} X''(t) \cos(n\omega_0 t) dt - j \frac{1}{(t_i - t_f)n^2\omega_0^2} \int_{t_i}^{t_f} X''(t) \sin(n\omega_0 t) dt$$

Sabiendo que:  $A_n = \frac{2}{T} \int_{t_i}^{t_f} X(t) \cos(n\omega_0 t) dt$ ;  $b_n = \frac{2}{T} \int_{t_i}^{t_f} X(t) \sin(n\omega_0 t) dt$  y  $A_n = 2 \operatorname{Re}\{c_n\}$ ;  $b_n = -2 \operatorname{Im}\{c_n\}$

$$A_n = 2 \operatorname{Re}\{c_n\} = 2 \frac{1}{(t_i - t_f)n^2\omega_0^2} \int_{t_i}^{t_f} X''(t) \cos(n\omega_0 t) dt$$

$$b_n = -2 \operatorname{Im}\{c_n\} = -2 \cdot \frac{1}{(t_i - t_f)n^2\omega_0^2} \int_{t_i}^{t_f} X''(t) \sin(n\omega_0 t) dt = 2 \frac{1}{(t_i - t_f)n^2\omega_0^2} \int_{t_i}^{t_f} X''(t) \sin(n\omega_0 t) dt$$

También se pueden calcular con:  $X(t) = \sum_n A_n \cos(n\omega_0 t) + b_n \sin(n\omega_0 t)$

$$X(t) = \sum_n A_n \cos(n\omega_0 t) + b_n \sin(n\omega_0 t)$$

$$X'(t) = \sum_n A_n \sin(n\omega_0 t) n\omega_0 + b_n \cos(n\omega_0 t) n\omega_0$$

$$X''(t) = \sum_n A_n \cos(n\omega_0 t) n\omega_0 \cdot n\omega_0 - b_n \sin(n\omega_0 t) n\omega_0 \cdot n\omega_0 = \sum_n \underbrace{A_n n^2 \omega_0^2}_{a_n} \cos(n\omega_0 t) - \underbrace{b_n n^2 \omega_0^2}_{b_n} \sin(n\omega_0 t)$$

$$a_n = -A_n n^2 \omega_0^2, \quad b_n = -b_n n^2 \omega_0^2$$

$$A_n = \frac{2}{T} \int_{t_i}^{t_f} X(t) \cos(n\omega_0 t) dt \rightarrow a_n = \frac{2}{T} \int_{t_i}^{t_f} X''(t) \cos(n\omega_0 t) dt$$

$$-A_n n^2 \omega_0^2 = \frac{2}{T} \int_{t_i}^{t_f} X''(t) \cos(n\omega_0 t) dt$$

$$A_n = \frac{2}{-(t_f - t_i)n^2\omega_0^2} \int_{t_i}^{t_f} X''(t) \cos(n\omega_0 t) dt$$

$$A_n = \frac{2}{(t_i - t_f)n^2\omega_0^2} \int_{t_i}^{t_f} X''(t) \cos(n\omega_0 t) dt$$

$$b_n = \frac{2}{T} \int_{t_i}^{t_f} X(t) \sin(n\omega_0 t) dt \rightarrow b_n = \frac{2}{T} \int_{t_i}^{t_f} X''(t) \sin(n\omega_0 t) dt$$

$$-b_n n^2 \omega_0^2 = \frac{2}{T} \int_{t_i}^{t_f} X''(t) \sin(n\omega_0 t) dt$$

$$b_n = \frac{2}{-(t_f - t_i)n^2\omega_0^2} \int_{t_i}^{t_f} X''(t) \sin(n\omega_0 t) dt$$

$$b_n = \frac{2}{(t_i - t_f)n^2\omega_0^2} \int_{t_i}^{t_f} X''(t) \sin(n\omega_0 t) dt$$



4. Encuentre el espectro de Fourier, su parte real, imaginaria, magnitud, fase y el error relativo para  $n \in \{0, \pm 1, \pm 2, \pm 3, \pm 4, \pm 5\}$ , a partir de  $x''(t)$  para la señal  $x(t)$  en la Figura 1. Compruebe el espectro obtenido con la estimación a partir de  $x(t)$ . Presente las simulaciones de Python respectivas.

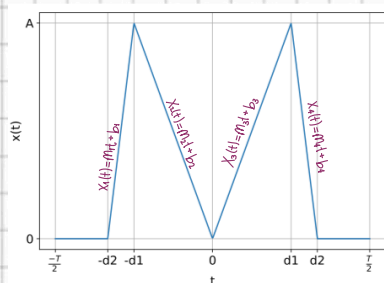


Figura 1:  $x(t)$  para el ejercicio 1.4

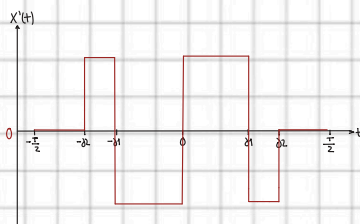
Para  $x_1(t) = m_1 t + b_1$   $\rightarrow m_1 = \frac{A-0}{-d1 - (-d2)} = \frac{A}{d2-d1}$  ;  $t_n = -d2 \rightarrow X(-d2) = \frac{A}{d2-d1} \cdot -d2 + b_1$   
 $0 = \frac{-d2 \cdot A}{d2-d1} + b_1$   
 $b_1 = \frac{d2}{d2-d1} A$   
 $x_1(t) = \frac{A}{d2-d1} t + \frac{d2}{d2-d1} A$

Para  $x_2(t) = m_2 t + b_2$   $\rightarrow m_2 = \frac{0-A}{0 - (-d1)} = -\frac{A}{d1}$  ;  $t_n = -d1 \rightarrow X(-d1) = -\frac{A}{d1} \cdot -d1 + b_2$   
 $A = A + b_2$   
 $b_2 = A - A = 0$   
 $x_2(t) = -\frac{A}{d1} t$

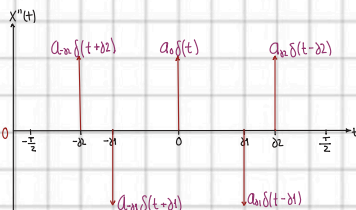
Para  $x_3(t) = m_3 t + b_3$   $\rightarrow m_3 = \frac{A-0}{d1-0} = \frac{A}{d1}$  ;  $t_n = 0 \rightarrow X(0) = \frac{A}{d1} \cdot 0 + b_3$   
 $0 = 0 + b_3$   
 $b_3 = 0$   
 $x_3(t) = \frac{A}{d1} t$

Para  $x_4(t) = m_4 t + b_4$   $\rightarrow m_4 = \frac{0-A}{d2-d1} = -\frac{A}{d2-d1}$  ;  $t_n = d2 \rightarrow X(d2) = -\frac{A}{d2-d1} \cdot d2 + b_4$   
 $0 = -\frac{A}{d2-d1} \cdot d2 + b_4$   
 $b_4 = \frac{A \cdot d2}{d2-d1}$   
 $x_4(t) = -\frac{A}{d2-d1} (t - d2)$

$$X(t) = \begin{cases} 0 & -\frac{T}{2} \leq t < -d2 \\ \frac{A}{d2-d1} (t + d2) & -d2 \leq t < -d1 \\ -\frac{A}{d1} t & -d1 \leq t < 0 \\ \frac{A}{d1} t & 0 \leq t < d1 \\ -\frac{A}{d2-d1} (t - d2) & d1 \leq t < d2 \\ 0 & d2 \leq t < \frac{T}{2} \end{cases}$$



$$x'(t) = \begin{cases} 0 & -\frac{T}{2} \leq t < -d2 \\ \frac{A}{d2-d1} & -d2 \leq t < -d1 \\ -\frac{A}{d1} & -d1 \leq t < 0 \\ \frac{A}{d1} & 0 \leq t < d1 \\ -\frac{A}{d2-d1} & d1 \leq t < d2 \\ 0 & d2 \leq t < \frac{T}{2} \end{cases}$$



$x''(t) = 0$  en cada tramo y en los puntos donde hay cambios tiende a  $\pm \infty$  y estos cambios los podemos representar como  $a_n \delta(t \pm t_n)$  donde  $a_n$  es la diferencia de la derivada por la derecha y la derivada por la izquierda y  $t_n$  donde ocurre el salto (cambio instantáneo)





$$A_{-1} = X'(-\partial_2^+) - X'(-\partial_2^-) = m_1 - 0 = \frac{A}{\partial_2 - \partial_1}$$

$$A_{-1} = X'(-\partial_1^+) - X'(-\partial_1^-) = m_2 - m_1 = -\frac{A}{\partial_1} - \frac{A}{\partial_2 - \partial_1} = -A \left( \frac{1}{\partial_1} + \frac{1}{\partial_2 - \partial_1} \right)$$

$$A_0 = X'(0^+) - X'(0^-) = m_3 - m_2 = \frac{A}{\partial_1} - \frac{A}{\partial_1} = \frac{A}{\partial_1} (1+1) = \frac{2A}{\partial_1}$$

$$A_{\partial_1} = X'(\partial_1^+) - X'(\partial_1^-) = m_4 - m_3 = -\frac{A}{\partial_2 - \partial_1} - \frac{A}{\partial_1} = -A \left( \frac{1}{\partial_2 - \partial_1} + \frac{1}{\partial_1} \right)$$

$$A_{\partial_2} = X'(\partial_2^+) - X'(\partial_2^-) = 0 - m_4 = 0 - \frac{A}{\partial_2 - \partial_1} = \frac{A}{\partial_2 - \partial_1}$$

$$X''(t) = A_{-1} \delta(t + \partial_2) + A_{-1} \delta(t + \partial_1) + A_0 \delta(t) + A_{\partial_1} \delta(t - \partial_1) + A_{\partial_2} \delta(t - \partial_2)$$

$$X''(t) = \frac{A}{\partial_2 - \partial_1} \delta(t + \partial_2) - A \left( \frac{1}{\partial_1} + \frac{1}{\partial_2 - \partial_1} \right) \delta(t + \partial_1) + \frac{2A}{\partial_1} \delta(t) - A \left( \frac{1}{\partial_2 - \partial_1} + \frac{1}{\partial_1} \right) \delta(t - \partial_1) + \frac{A}{\partial_2 - \partial_1} \delta(t - \partial_2)$$

$$X''(t) = \frac{A}{\partial_2 - \partial_1} (\delta(t + \partial_2) + \delta(t - \partial_2)) - A \left( \frac{1}{\partial_1} + \frac{1}{\partial_2 - \partial_1} \right) (\delta(t + \partial_1) + \delta(t - \partial_1)) + \frac{2A}{\partial_1} \delta(t)$$

$$C_n = \frac{1}{(t_i - t_f) \hbar^2 \omega^2} \int_{-T/2}^{T/2} X''(t) e^{-j\omega t} dt \quad \text{con } T = t_f - t_i = \frac{T}{2} - (-\frac{T}{2}) = T \quad \omega_0 = \frac{2\pi}{T}$$

$$C_n = \frac{1}{(t_i - t_f) \hbar^2 \omega^2} \int_{-T/2}^{T/2} \left( \frac{A}{\partial_2 - \partial_1} (\delta(t + \partial_2) + \delta(t - \partial_2)) - A \left( \frac{1}{\partial_1} + \frac{1}{\partial_2 - \partial_1} \right) (\delta(t + \partial_1) + \delta(t - \partial_1)) + \frac{2A}{\partial_1} \delta(t) \right) e^{-j\omega t} dt$$

$$C_n = \frac{1}{(t_i - t_f) \hbar^2 \omega^2} \left( \int_{-T/2}^{T/2} \frac{A}{\partial_2 - \partial_1} (\delta(t + \partial_2) + \delta(t - \partial_2)) e^{-j\omega t} dt - \int_{-T/2}^{T/2} A \left( \frac{1}{\partial_1} + \frac{1}{\partial_2 - \partial_1} \right) (\delta(t + \partial_1) + \delta(t - \partial_1)) e^{-j\omega t} dt + \int_{-T/2}^{T/2} \frac{2A}{\partial_1} \delta(t) e^{-j\omega t} dt \right)$$

$$C_n = \frac{1}{(t_i - t_f) \hbar^2 \omega^2} \left( \int_{-T/2}^{T/2} \frac{A}{\partial_2 - \partial_1} \delta(t + \partial_2) e^{-j\omega t} dt + \int_{-T/2}^{T/2} \frac{A}{\partial_2 - \partial_1} \delta(t - \partial_2) e^{-j\omega t} dt - \int_{-T/2}^{T/2} A \left( \frac{1}{\partial_1} + \frac{1}{\partial_2 - \partial_1} \right) \delta(t + \partial_1) e^{-j\omega t} dt - \int_{-T/2}^{T/2} A \left( \frac{1}{\partial_1} + \frac{1}{\partial_2 - \partial_1} \right) \delta(t - \partial_1) e^{-j\omega t} dt + \int_{-T/2}^{T/2} \frac{2A}{\partial_1} \delta(t) e^{-j\omega t} dt \right)$$

$$C_n = \frac{1}{(t_i - t_f) \hbar^2 \omega^2} \left( \frac{A}{\partial_2 - \partial_1} e^{-j\omega_0 \partial_2} + \frac{A}{\partial_2 - \partial_1} e^{-j\omega_0 \partial_2} - A \left( \frac{1}{\partial_1} + \frac{1}{\partial_2 - \partial_1} \right) e^{-j\omega_0 \partial_1} - A \left( \frac{1}{\partial_1} + \frac{1}{\partial_2 - \partial_1} \right) e^{-j\omega_0 \partial_1} + \frac{2A}{\partial_1} e^{0} \right)$$

$$C_n = \frac{1}{(t_i - t_f) \hbar^2 \omega^2} \left( \frac{A}{\partial_2 - \partial_1} (\cos(n\omega_0 \partial_2) + j\sin(n\omega_0 \partial_2) + \cos(n\omega_0 \partial_2) - j\sin(n\omega_0 \partial_2)) - A \left( \frac{1}{\partial_1} + \frac{1}{\partial_2 - \partial_1} \right) (\cos(n\omega_0 \partial_1) + j\sin(n\omega_0 \partial_1) + \cos(n\omega_0 \partial_1) - j\sin(n\omega_0 \partial_1)) + \frac{2A}{\partial_1} \right)$$

$$C_n = \frac{1}{(t_i - t_f) \hbar^2 \omega^2} \left( \frac{A}{\partial_2 - \partial_1} \cdot 2 \cos(n\omega_0 \partial_2) - A \left( \frac{1}{\partial_1} + \frac{1}{\partial_2 - \partial_1} \right) \cdot 2 \cos(n\omega_0 \partial_1) + \frac{2A}{\partial_1} \right)$$

$$C_n = \frac{2A}{(t_i - t_f) \hbar^2 \omega^2} \left( \frac{1}{\partial_2 - \partial_1} \cdot \cos(n\omega_0 \partial_2) - \left( \frac{1}{\partial_1} + \frac{1}{\partial_2 - \partial_1} \right) \cdot \cos(n\omega_0 \partial_1) + \frac{1}{\partial_1} \right)$$

$$C_n = \frac{2A}{(-\frac{T}{2} - \frac{T}{2}) \hbar^2 \frac{2\pi}{T}} \left( \frac{1}{\partial_2 - \partial_1} \cdot \cos(n\omega_0 \partial_2) - \left( \frac{1}{\partial_1} + \frac{1}{\partial_2 - \partial_1} \right) \cdot \cos(n\omega_0 \partial_1) + \frac{1}{\partial_1} \right)$$

$$C_n = \frac{-AT}{2 \hbar^2 \pi} \left( \frac{1}{\partial_2 - \partial_1} \cdot \cos(n\omega_0 \partial_2) - \left( \frac{1}{\partial_1} + \frac{1}{\partial_2 - \partial_1} \right) \cdot \cos(n\omega_0 \partial_1) + \frac{1}{\partial_1} \right)$$



Ahora Confirmamos con  $x(t)$

$$C_n = \frac{1}{T} \int_T x(t) e^{-jn\omega t} dt \quad ; \quad T = t_f - t_i = \frac{T}{2} - (-\frac{T}{2}) = \frac{T}{2}(1+1) = T \quad ; \quad \omega_0 = \frac{2\pi}{T}$$

$$C_n = \frac{1}{\cancel{\frac{1}{2}}} \left( \int_{-\frac{\delta_1}{2}}^{\frac{\delta_2}{2}} \frac{A}{\delta_2 - \delta_1} e^{-j\omega t} dt + \int_{-\frac{\delta_1}{2}}^{\frac{\delta_1}{2}} \frac{A}{\delta_2 - \delta_1} (t + \delta_2) e^{-j\omega t} dt + \int_{-\frac{\delta_1}{2}}^0 \frac{A}{\delta_1} t e^{-j\omega t} dt + \int_0^{\frac{\delta_1}{2}} \frac{A}{\delta_1} t e^{-j\omega t} dt + \int_{\frac{\delta_1}{2}}^{\frac{\delta_2}{2}} \frac{A}{\delta_2 - \delta_1} (t + \delta_2) e^{-j\omega t} dt + \int_{\frac{\delta_2}{2}}^{\frac{\delta_2}{2}} \frac{A}{\delta_2 - \delta_1} e^{-j\omega t} dt \right)$$

$$C_n = \frac{1}{T} \left( \frac{A}{2\pi\beta_1} \int_{-\beta_1}^{-\beta_2} (t+\beta_2) e^{-j\omega_0 t} dt - \frac{A}{\beta_1} \int_{-\beta_1}^0 t e^{-j\omega_0 t} dt + \frac{A}{\beta_1} \int_0^{\beta_1} t e^{-j\omega_0 t} dt - \frac{A}{2\pi\beta_1} \int_{\beta_1}^{\beta_2} (t+\beta_2) e^{-j\omega_0 t} dt \right)$$

$$C_1 = \frac{1}{T} \left( \frac{A}{\partial t - \partial_1} \left( \int_{-\partial_1}^{-\partial_1} \text{te}^{-\text{hu} \partial t} \partial t + \partial_2 \int_{-\partial_1}^{-\partial_1} \text{te}^{-\text{hu} \partial t} \partial t \right) - \frac{A}{\partial_1} \left( \int_{-\partial_1}^0 \text{te}^{-\text{hu} \partial t} \partial t + \frac{A}{\partial_1} \int_0^{\partial_1} \text{te}^{-\text{hu} \partial t} \partial t - \frac{A}{\partial_2 - \partial_1} \left( \int_{\partial_1}^{\partial_2} \text{te}^{-\text{hu} \partial t} \partial t + \partial_2 \int_{\partial_1}^{\partial_2} \text{te}^{-\text{hu} \partial t} \partial t \right) \right) \right)$$

$$\textcircled{1} \int_{-\frac{\pi}{2}}^{-\frac{\pi}{4}} t e^{-j\omega t} dt \rightarrow \begin{matrix} u=t & \rightarrow & du=dt \\ dv=e^{-j\omega t} & \rightarrow & v=\int e^{-j\omega t} dt = \frac{e^{-j\omega t}}{-j\omega} \end{matrix} \rightarrow uv - \int v du$$

$$= t \cdot e^{-\frac{v_{\text{rel}}}{c} \cdot \frac{\delta t}{\delta \tau}} \cdot \left[ \frac{e^{-\frac{v_{\text{rel}}}{c} \cdot \frac{\delta t}{\delta \tau}}}{\gamma_{\text{rel}}} \cdot \delta t = t \cdot e^{-\frac{v_{\text{rel}}}{c} \cdot \frac{\delta t}{\delta \tau}} \cdot \frac{e^{-\frac{v_{\text{rel}}}{c} \cdot \frac{\delta t}{\delta \tau}}}{\gamma_{\text{rel}} \cdot n^2 \cdot \omega^2} \right] = \left( -\delta t \cdot \frac{e^{-\frac{v_{\text{rel}}}{c} \cdot \frac{\delta t}{\delta \tau}}}{\gamma_{\text{rel}}} - \left( \frac{e^{-\frac{v_{\text{rel}}}{c} \cdot \frac{\delta t}{\delta \tau}}}{\gamma_{\text{rel}}} \right) \cdot \left( \frac{e^{-\frac{v_{\text{rel}}}{c} \cdot \frac{\delta t}{\delta \tau}}}{n^2 \cdot \omega^2} \right) \right)$$

$$= \delta t \cdot \frac{e^{-\frac{v_{\text{rel}}}{c} \cdot \frac{\delta t}{\delta \tau}}}{\gamma_{\text{rel}}} - \frac{e^{-\frac{v_{\text{rel}}}{c} \cdot \frac{\delta t}{\delta \tau}}}{\gamma_{\text{rel}}} \cdot \frac{e^{-\frac{v_{\text{rel}}}{c} \cdot \frac{\delta t}{\delta \tau}}}{n^2 \cdot \omega^2} + \frac{e^{-\frac{v_{\text{rel}}}{c} \cdot \frac{\delta t}{\delta \tau}}}{n^2 \cdot \omega^2} = e^{-\frac{v_{\text{rel}}}{c} \cdot \frac{\delta t}{\delta \tau}} \left( \frac{\delta t}{\gamma_{\text{rel}}} - \frac{1}{n^2 \cdot \omega^2} \right) + e^{-\frac{v_{\text{rel}}}{c} \cdot \frac{\delta t}{\delta \tau}} \left( \frac{1}{n^2 \cdot \omega^2} - \frac{\delta t}{\gamma_{\text{rel}}} \right)$$

$$\textcircled{2} \quad \partial_2 \int_{-\partial_2}^{-\partial_1} e^{-j\omega_0 t} dt = -\partial_2 \left. \frac{e^{-j\omega_0 t}}{-j\omega_0} \right|_{-\partial_2}^{-\partial_1} = -\partial_2 \frac{e^{-j\omega_0 \partial_1}}{-j\omega_0} - (-\partial_2) \frac{e^{-j\omega_0 \partial_2}}{-j\omega_0} = \partial_2 \frac{e^{-j\omega_0 \partial_2}}{j\omega_0} - \partial_2 \frac{e^{-j\omega_0 \partial_1}}{j\omega_0} = \frac{\partial_2}{j\omega_0} (e^{-j\omega_0 \partial_2} - e^{-j\omega_0 \partial_1})$$

$$\textcircled{3} \int_{-\frac{\pi}{2}}^0 t e^{j\omega t} dt = t \cdot \frac{e^{-j\omega t}}{-j\omega} \Big|_{-\frac{\pi}{2}}^0 - \int_{-\frac{\pi}{2}}^0 \frac{e^{-j\omega t}}{-j\omega} dt = t \cdot \frac{e^{-j\omega t}}{-j\omega} \Big|_{-\frac{\pi}{2}}^0 - \frac{e^{-j\omega t}}{n^2 \omega^2} \Big|_{-\frac{\pi}{2}}^0 = \left( 0 \cdot \frac{e^{-j\omega \cdot 0}}{-j\omega} - \left( -\frac{\pi}{2} \right) \frac{e^{-j\omega \cdot (-\frac{\pi}{2})}}{-j\omega} \right) - \left( \frac{e^{-j\omega \cdot 0}}{n^2 \omega^2} - \frac{e^{-j\omega \cdot (-\frac{\pi}{2})}}{n^2 \omega^2} \right)$$

$$\begin{aligned} \textcircled{+} \int_0^{\delta t} t e^{-j\omega_0 t} dt &= t \cdot \frac{e^{-j\omega_0 t}}{-j\omega_0} \bigg|_0^{\delta t} - \int_0^{\delta t} \frac{e^{-j\omega_0 t}}{-j\omega_0} dt = t \cdot \frac{e^{-j\omega_0 t}}{-j\omega_0} \bigg|_0^{\delta t} - \frac{e^{-j\omega_0 t}}{n^2 \omega_0^2} \bigg|_0^{\delta t} \\ &= \left( \delta t \cdot \frac{e^{-j\omega_0 \delta t}}{-j\omega_0} - 0 \cdot \frac{e^{-j\omega_0 \cdot 0}}{-j\omega_0} \right) - \left( \frac{e^{-j\omega_0 \delta t}}{n^2 \omega_0^2} - \frac{e^{-j\omega_0 \cdot 0}}{n^2 \omega_0^2} \right) \\ &= -\delta t \frac{e^{-j\omega_0 \delta t}}{j\omega_0} - \left( \frac{e^{-j\omega_0 \delta t}}{n^2 \omega_0^2} - \frac{1}{n^2 \omega_0^2} \right) \end{aligned}$$

$$\begin{aligned} \textcircled{5} \quad \int_{\partial_1}^{\partial_2} t e^{\frac{j\omega_0 t}{u_0}} dt &= t \cdot \frac{e^{\frac{j\omega_0 t}{u_0}}}{\frac{j\omega_0}{u_0}} \Big|_{\partial_1}^{\partial_2} - \int_{\partial_1}^{\partial_2} \frac{e^{\frac{j\omega_0 t}{u_0}}}{\frac{j\omega_0}{u_0}} dt = t \cdot \frac{e^{\frac{j\omega_0 t}{u_0}}}{\frac{j\omega_0}{u_0}} \Big|_{\partial_1}^{\partial_2} - \frac{e^{\frac{j\omega_0 t}{u_0}}}{\frac{j\omega_0}{u_0}} \Big|_{\partial_1}^{\partial_2} \\ &= \left( \partial_1 \frac{e^{\frac{j\omega_0 t}{u_0}}}{\frac{j\omega_0}{u_0}} - \partial_2 \frac{e^{\frac{j\omega_0 t}{u_0}}}{\frac{j\omega_0}{u_0}} \right) - \left( \frac{e^{\frac{j\omega_0 t}{u_0}}}{\frac{j\omega_0}{u_0}} \Big|_{\partial_1}^{\partial_2} - \frac{e^{\frac{j\omega_0 t}{u_0}}}{\frac{j\omega_0}{u_0}} \Big|_{\partial_1}^{\partial_2} \right) \end{aligned}$$

$$\textcircled{6} \quad \omega \int_{\omega_1}^{\omega_2} e^{-j\omega_0 t} dt = \omega \left. \frac{e^{-j\omega_0 t}}{-j\omega_0} \right|_{\omega_1}^{\omega_2} = \omega \frac{e^{-j\omega_0 \omega_2}}{-j\omega_0} - \omega \frac{e^{-j\omega_0 \omega_1}}{-j\omega_0} = \omega \frac{e^{-j\omega_0 \omega_2}}{j\omega_0} - \omega \frac{e^{-j\omega_0 \omega_1}}{j\omega_0}$$

$$C_1 = \frac{1}{T} \left( \frac{A}{\partial z - \delta_1} \left( \delta_1 \frac{e^{-j\omega t}}{j\omega U_0} - \delta_2 \frac{e^{-j\omega t}}{j\omega U_0} \right) - \frac{e^{-j\omega t}}{n^2 U_0^2} - \frac{e^{-j\omega t}}{n^2 U_0^2} \right) + \delta_2 \frac{e^{-j\omega t}}{j\omega U_0} - \delta_2 \frac{e^{-j\omega t}}{j\omega U_0} - \frac{A}{\delta_1} \left( -\delta_1 \frac{e^{-j\omega t}}{j\omega U_0} - \left( \frac{1}{n^2 U_0^2} - \frac{e^{-j\omega t}}{n^2 U_0^2} \right) \right)$$
  
 $+ \frac{A}{\delta_1} \left( -\delta_1 \frac{e^{-j\omega t}}{j\omega U_0} - \left( \frac{e^{-j\omega t}}{n^2 U_0^2} - \frac{1}{n^2 U_0^2} \right) \right) - \frac{A}{\partial z - \delta_1} \left( \delta_1 \frac{e^{-j\omega t}}{j\omega U_0} - \delta_2 \frac{e^{-j\omega t}}{j\omega U_0} \right) - \left( \frac{e^{-j\omega t}}{n^2 U_0^2} - \frac{e^{-j\omega t}}{n^2 U_0^2} \right) + \delta_2 \frac{e^{-j\omega t}}{j\omega U_0} - \delta_2 \frac{e^{-j\omega t}}{j\omega U_0}$   
 $= \frac{1}{T} \left( \frac{A}{\partial z - \delta_1} \delta_1 \frac{e^{-j\omega t}}{j\omega U_0} - \frac{A}{\partial z - \delta_1} \delta_2 \frac{e^{-j\omega t}}{j\omega U_0} - \frac{A}{\partial z - \delta_1} \frac{e^{-j\omega t}}{n^2 U_0^2} + \frac{A}{\partial z - \delta_1} \frac{e^{-j\omega t}}{n^2 U_0^2} + \frac{A}{\partial z - \delta_1} \delta_2 \frac{e^{-j\omega t}}{j\omega U_0} - \frac{A}{\partial z - \delta_1} \delta_2 \frac{e^{-j\omega t}}{j\omega U_0} \right.$   
 $\left. + \frac{A}{\delta_1} \delta_1 \frac{e^{-j\omega t}}{j\omega U_0} - \frac{A}{\delta_1} \frac{1}{n^2 U_0^2} - \frac{A}{\delta_1} \frac{e^{-j\omega t}}{n^2 U_0^2} - \frac{A}{\delta_1} \delta_1 \frac{e^{-j\omega t}}{j\omega U_0} - \frac{A}{\delta_1} \frac{e^{-j\omega t}}{n^2 U_0^2} + \frac{A}{\delta_1} \frac{1}{n^2 U_0^2} \right.$   
 $\left. - \frac{A}{\partial z - \delta_1} \delta_1 \frac{e^{-j\omega t}}{j\omega U_0} + \frac{A}{\partial z - \delta_1} \delta_2 \frac{e^{-j\omega t}}{j\omega U_0} + \frac{A}{\partial z - \delta_1} \frac{e^{-j\omega t}}{n^2 U_0^2} - \frac{A}{\partial z - \delta_1} \frac{e^{-j\omega t}}{n^2 U_0^2} - \frac{A}{\partial z - \delta_1} \delta_2 \frac{e^{-j\omega t}}{j\omega U_0} + \frac{A}{\partial z - \delta_1} \delta_2 \frac{e^{-j\omega t}}{j\omega U_0} \right)$





$$= \frac{1}{T} \left( \frac{\partial A e^{jn\omega t}}{j\omega (2-\delta t)} - \frac{\partial A e^{jn\omega t}}{j\omega (2-\delta t)} - \frac{A e^{jn\omega t}}{n^2 \omega^2 (2-\delta t)} + \frac{A e^{jn\omega t}}{n^2 \omega^2 (2-\delta t)} + \frac{\partial A e^{jn\omega t}}{j\omega (2-\delta t)} - \frac{\partial A e^{jn\omega t}}{j\omega (2-\delta t)} \right. \\ \left. + \frac{A e^{jn\omega t}}{j\omega (2-\delta t)} + \frac{A}{\delta n^2 \omega^2} - \frac{A e^{jn\omega t}}{\delta n^2 \omega^2} - \frac{A e^{jn\omega t}}{j\omega (2-\delta t)} - \frac{A e^{jn\omega t}}{\delta n^2 \omega^2} + \frac{A}{\delta n^2 \omega^2} \right. \\ \left. - \frac{\partial A e^{jn\omega t}}{j\omega (2-\delta t)} + \frac{\partial A e^{jn\omega t}}{j\omega (2-\delta t)} + \frac{A e^{jn\omega t}}{n^2 \omega^2 (2-\delta t)} - \frac{A e^{jn\omega t}}{n^2 \omega^2 (2-\delta t)} - \frac{\partial A e^{jn\omega t}}{j\omega (2-\delta t)} + \frac{\partial A e^{jn\omega t}}{j\omega (2-\delta t)} \right)$$

Acomodamos los terminos por aparte

$$\begin{aligned} \frac{\partial A e^{jn\omega t}}{j\omega (2-\delta t)} - \frac{\partial A e^{jn\omega t}}{j\omega (2-\delta t)} &\rightarrow \frac{\partial A}{j\omega (2-\delta t)} (e^{jn\omega t} - e^{jn\omega t}) \\ - \frac{\partial A e^{jn\omega t}}{j\omega (2-\delta t)} + \frac{\partial A e^{jn\omega t}}{j\omega (2-\delta t)} + \frac{\partial A e^{jn\omega t}}{j\omega (2-\delta t)} + \frac{\partial A e^{jn\omega t}}{j\omega (2-\delta t)} &\rightarrow \frac{2 \partial A e^{jn\omega t}}{j\omega (2-\delta t)} \\ - \frac{\partial A e^{jn\omega t}}{j\omega (2-\delta t)} - \frac{\partial A e^{jn\omega t}}{j\omega (2-\delta t)} &\rightarrow \frac{-\partial A}{j\omega (2-\delta t)} (e^{jn\omega t} + e^{jn\omega t}) \\ - \frac{A e^{jn\omega t}}{n^2 \omega^2 (2-\delta t)} - \frac{A e^{jn\omega t}}{n^2 \omega^2 (2-\delta t)} &\rightarrow \frac{-A}{n^2 \omega^2 (2-\delta t)} (e^{jn\omega t} + e^{jn\omega t}) \\ + \frac{A}{\delta n^2 \omega^2} + \frac{A}{\delta n^2 \omega^2} &\rightarrow \frac{2A}{\delta n^2 \omega^2} \\ + \frac{A e^{jn\omega t}}{n^2 \omega^2 (2-\delta t)} + \frac{A e^{jn\omega t}}{n^2 \omega^2 (2-\delta t)} &\rightarrow \frac{A}{n^2 \omega^2 (2-\delta t)} (e^{jn\omega t} + e^{jn\omega t}) \\ + \frac{A e^{jn\omega t}}{j\omega (2-\delta t)} - \frac{A e^{jn\omega t}}{j\omega (2-\delta t)} &\rightarrow \frac{A}{j\omega (2-\delta t)} (e^{jn\omega t} - e^{jn\omega t}) \\ - \frac{A e^{jn\omega t}}{\delta n^2 \omega^2} - \frac{A e^{jn\omega t}}{\delta n^2 \omega^2} &\rightarrow \frac{-A}{\delta n^2 \omega^2} (e^{jn\omega t} + e^{jn\omega t}) \end{aligned}$$

$$\begin{aligned} \frac{\partial A}{j\omega (2-\delta t)} (e^{jn\omega t} - e^{jn\omega t}) &= \frac{\partial A (\cos(n\omega \delta t) + j \sin(n\omega \delta t) - \cos(n\omega \delta t) - j \sin(n\omega \delta t))}{j\omega (2-\delta t)} = \frac{\partial A}{j\omega (2-\delta t)} 2 j \sin(n\omega \delta t) \\ \frac{2 \partial A e^{jn\omega t}}{j\omega (2-\delta t)} &= \frac{2 \partial A \cos(n\omega \delta t)}{j\omega (2-\delta t)} - \frac{2 \partial A j \sin(n\omega \delta t)}{j\omega (2-\delta t)} \\ \frac{-\partial A}{j\omega (2-\delta t)} (e^{jn\omega t} + e^{jn\omega t}) &= \frac{-\partial A (\cos(n\omega \delta t) + j \sin(n\omega \delta t) + \cos(n\omega \delta t) - j \sin(n\omega \delta t))}{j\omega (2-\delta t)} = \frac{-\partial A \cdot 2 \cos(n\omega \delta t)}{j\omega (2-\delta t)} \\ \frac{-A}{n^2 \omega^2 (2-\delta t)} (e^{jn\omega t} + e^{jn\omega t}) &= \frac{-A (\cos(n\omega \delta t) + j \sin(n\omega \delta t) + \cos(n\omega \delta t) - j \sin(n\omega \delta t))}{n^2 \omega^2 (2-\delta t)} = \frac{-A \cdot 2 \cos(n\omega \delta t)}{n^2 \omega^2 (2-\delta t)} \\ \frac{2A}{\delta n^2 \omega^2} &= \frac{A (\cos(n\omega \delta t) + j \sin(n\omega \delta t) + \cos(n\omega \delta t) - j \sin(n\omega \delta t))}{n^2 \omega^2 (2-\delta t)} = \frac{A \cdot 2 \cos(n\omega \delta t)}{n^2 \omega^2 (2-\delta t)} \\ \frac{A}{j\omega (2-\delta t)} (e^{jn\omega t} - e^{jn\omega t}) &= \frac{A (\cos(n\omega \delta t) + j \sin(n\omega \delta t) - \cos(n\omega \delta t) - j \sin(n\omega \delta t))}{j\omega (2-\delta t)} = \frac{A \cdot 2 j \sin(n\omega \delta t)}{j\omega (2-\delta t)} \\ - \frac{A}{\delta n^2 \omega^2} (e^{jn\omega t} + e^{jn\omega t}) &= \frac{-A (\cos(n\omega \delta t) + j \sin(n\omega \delta t) + \cos(n\omega \delta t) - j \sin(n\omega \delta t))}{\delta n^2 \omega^2} = \frac{-A \cdot 2 \cos(n\omega \delta t)}{\delta n^2 \omega^2} \end{aligned}$$

$$\begin{aligned} C_n &= \frac{1}{T} \left( \frac{\partial A}{j\omega (2-\delta t)} 2 j \sin(n\omega \delta t) + \frac{2 \partial A \cos(n\omega \delta t)}{j\omega (2-\delta t)} - \frac{2 \partial A j \sin(n\omega \delta t)}{j\omega (2-\delta t)} - \frac{\partial A \cdot 2 \cos(n\omega \delta t)}{j\omega (2-\delta t)} + \frac{2A}{\delta n^2 \omega^2} + \frac{A \cdot 2 \cos(n\omega \delta t)}{n^2 \omega^2 (2-\delta t)} \right. \\ &\quad \left. + \frac{A \cdot 2 j \sin(n\omega \delta t)}{j\omega (2-\delta t)} - \frac{A \cdot 2 \cos(n\omega \delta t)}{\delta n^2 \omega^2} \right) \\ &= \frac{1}{T} \left( \frac{2 \partial A}{n\omega (2-\delta t)} \sin(n\omega \delta t) + \frac{2 \partial A \cdot 2 \cos(n\omega \delta t)}{j\omega (2-\delta t)} - \frac{2 \partial A}{n\omega (2-\delta t)} \sin(n\omega \delta t) - \frac{2 \partial A}{j\omega (2-\delta t)} \cos(n\omega \delta t) + \frac{2A}{\delta n^2 \omega^2} \right. \\ &\quad \left. + \frac{A \cdot 2 \cos(n\omega \delta t)}{n^2 \omega^2 (2-\delta t)} + \frac{2A}{n\omega} \sin(n\omega \delta t) - \frac{2A}{\delta n^2 \omega^2} \cos(n\omega \delta t) \right) \\ &= \frac{1}{T} \left( \frac{2A \sin(n\omega \delta t)}{n\omega} \left( \frac{\delta t}{2-\delta t} + 1 \right) + \frac{2A \cos(n\omega \delta t)}{n\omega (2-\delta t)} \left( \frac{\delta t}{j} + \frac{1}{n\omega} \right) \right. \\ &\quad \left. - \frac{2A \cos(n\omega \delta t)}{n\omega} \left( \frac{1}{\delta n\omega} + \frac{\delta t}{2-\delta t} \right) - \frac{2 \partial A}{n\omega (2-\delta t)} \sin(n\omega \delta t) + \frac{2A}{\delta n^2 \omega^2} \right) \end{aligned}$$



$$P_e\{C_n\} = -\frac{AT}{2 \cdot n^2 \pi^2} \left( \frac{1}{\delta_2 - \delta_1} \cdot \cos(n\omega_0 \delta_2) - \left( \frac{1}{\delta_1} + \frac{1}{\delta_2 - \delta_1} \right) \cdot \cos(n\omega_0 \delta_1) + \frac{1}{\delta_1} \right) \quad y \quad \text{Im}\{C_n\} = 0 \longrightarrow \text{Simetría por}$$

$$|C_n| = \sqrt{P_e\{C_n\} + \text{Im}\{C_n\}^2} = \sqrt{\left( -\frac{AT}{2 \cdot n^2 \pi^2} \left( \frac{1}{\delta_2 - \delta_1} \cdot \cos(n\omega_0 \delta_2) - \left( \frac{1}{\delta_1} + \frac{1}{\delta_2 - \delta_1} \right) \cdot \cos(n\omega_0 \delta_1) + \frac{1}{\delta_1} \right) \right)^2}$$

$$\Theta_{C_n} = \tan^{-1} \left\{ \frac{\text{Im}\{C_n\}}{P_e\{C_n\}} \right\} = \tan^{-1} \left( \frac{0}{-\frac{AT}{2 \cdot n^2 \pi^2} \left( \frac{1}{\delta_2 - \delta_1} \cdot \cos(n\omega_0 \delta_2) - \left( \frac{1}{\delta_1} + \frac{1}{\delta_2 - \delta_1} \right) \cdot \cos(n\omega_0 \delta_1) + \frac{1}{\delta_1} \right)} \right) = 0$$

$$P_r\{x\} = \left( 1 - \sum |C_n|^2 \frac{P_n}{P_x} \right) \cdot 100\% ; P_n = \frac{1}{T} E_n = \frac{1}{T} \int_0^T e^{j n \omega_0 t} dt = \frac{1}{T} \cdot T = 1$$

Como la señal es par solo vamos a integrar de 0 a  $\delta_2$  ( $x(-t) = x(t)$ )

$$P_x = \frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} |x(t)|^2 dt = \frac{2}{T} \int_0^{\frac{T}{2}} |x(t)|^2 dt \rightarrow \text{Pero de } \delta_2 \text{ a } \frac{T}{2} \text{ es } 0 \rightarrow P_x = \frac{2}{T} \int_0^{\delta_2} |x(t)|^2 dt = \frac{2}{T} \left( \int_0^{\delta_1} \left( \frac{A}{\delta_1} t \right)^2 dt + \int_{\delta_1}^{\delta_2} \frac{A}{\delta_2 - \delta_1} (t + \delta_2)^2 dt \right)$$

$$P_x = \frac{2}{T} \left( \int_0^{\delta_1} \left( \frac{A}{\delta_1} t \right)^2 dt + \int_{\delta_1}^{\delta_2} \frac{A}{\delta_2 - \delta_1} (t + \delta_2)^2 dt \right) = \frac{2}{T} \left( \frac{A^2}{\delta_1^3} \int_0^{\delta_1} t^2 dt + \frac{A^2}{(\delta_2 - \delta_1)^2} \int_{\delta_1}^{\delta_2} (t + \delta_2)^2 dt \right)$$

$$\int_0^{\delta_1} t^2 dt = \frac{t^3}{3} \Big|_0^{\delta_1} = \frac{\delta_1^3}{3} ; \int_{\delta_1}^{\delta_2} (t + \delta_2)^2 dt = \int_{\delta_1 + \delta_2}^{2\delta_2} u^2 du = \frac{u^3}{3} \Big|_{\delta_1 + \delta_2}^{2\delta_2} = \frac{(2\delta_2)^3}{3} - \frac{(\delta_1 + \delta_2)^3}{3} = \frac{1}{3} (8\delta_2^3 - (\delta_1 + \delta_2)^3)$$

$$\begin{aligned} u &= t + \delta_2 \\ du &= dt \end{aligned}$$

$$\text{Si } t = \delta_1 \rightarrow u = \delta_1 + \delta_2$$

$$\text{Si } t = \delta_2 \rightarrow u = 2\delta_2$$

$$u \in [\delta_1 + \delta_2, 2\delta_2]$$

$$P_x = \frac{2}{T} \left( \frac{A^2}{\delta_1^3} \frac{\delta_1^3}{3} + \frac{A^2}{3(\delta_2 - \delta_1)^2} (8\delta_2^3 - (\delta_1 + \delta_2)^3) \right) \quad |C_n|^2 = \sqrt{\left( -\frac{AT}{2 \cdot n^2 \pi^2} \left( \frac{1}{\delta_2 - \delta_1} \cdot \cos(n\omega_0 \delta_2) - \left( \frac{1}{\delta_1} + \frac{1}{\delta_2 - \delta_1} \right) \cdot \cos(n\omega_0 \delta_1) + \frac{1}{\delta_1} \right) \right)^2}$$

$$P_x = \frac{2}{T} \left( \frac{A^2}{\delta_1^3} \frac{\delta_1^3}{3} + \frac{A^2}{3(\delta_2 - \delta_1)^2} (8\delta_2^3 - (\delta_1 + \delta_2)^3) \right)$$

$$P_x = \frac{2}{T} \left( \frac{A^2}{\delta_1^3} \frac{\delta_1^3}{3} + \frac{A^2}{3(\delta_2 - \delta_1)^2} (8\delta_2^3 - (\delta_1 + \delta_2)^3) \right)$$

$$P_x = \frac{2A^2 \delta_1}{3T} + \frac{2A^2}{3T(\delta_2 - \delta_1)^2} (8\delta_2^3 - (\delta_1 + \delta_2)^3)$$

$$P_r(\%) = \left( 1 - \sum_n \frac{\left( -\frac{AT}{2 \cdot n^2 \pi^2} \left( \frac{1}{\delta_2 - \delta_1} \cdot \cos(n\omega_0 \delta_2) - \left( \frac{1}{\delta_1} + \frac{1}{\delta_2 - \delta_1} \right) \cdot \cos(n\omega_0 \delta_1) + \frac{1}{\delta_1} \right) \right)^2}{\frac{2A^2 \delta_1}{3T} + \frac{2A^2}{3T(\delta_2 - \delta_1)^2} (8\delta_2^3 - (\delta_1 + \delta_2)^3)} \right) \cdot 100(\%)$$

