

1. La distancia media entre dos señales periódicas $x_1(t) \in \mathbb{R}, \mathbb{C}$ y $x_2(t) \in \mathbb{R}, \mathbb{C}$; se puede expresar a partir de la potencia media de la diferencia entre ellas:

$$d^2(x_1, x_2) = \bar{P}_{x_1 - x_2} = \lim_{T \rightarrow \infty} \frac{1}{T} \int_T |x_1(t) - x_2(t)|^2 dt.$$

Sea $x_1(t)$ y $x_2(t)$ dos señales definidas como:

$$x_1(t) = Ae^{-jn\omega_0 t}$$

$$x_2(t) = Be^{jm\omega_0 t}$$

con $\omega_0 = \frac{2\pi}{T}$; $T, A, B \in \mathbb{R}^+$ y $n, m \in \mathbb{Z}$. Determine la distancia entre las dos señales. Compruebe sus resultados con Python.

$$\begin{aligned} \bar{P}_{x_1} &= \frac{1}{T} \int_T x_1(t) x_1^*(t) dt = \frac{1}{T} \int_0^T Ae^{-jn\omega_0 t} (Ae^{-jn\omega_0 t})^* dt = \frac{1}{T} \int_0^T Ae^{-jn\omega_0 t} Ae^{jn\omega_0 t} dt \\ &= \frac{A^2}{T} \int_0^T e^{(n-n)\omega_0 t} dt = \frac{A^2}{T} \int_0^T 1 dt = \frac{A^2}{T} (T-0) = \frac{A^2}{T} \cdot T = A^2 \end{aligned}$$

$$\begin{aligned} \bar{P}_{x_2} &= \frac{1}{T} \int_T x_2(t) x_2^*(t) dt = \frac{1}{T} \int_0^T Be^{jm\omega_0 t} (Be^{jm\omega_0 t})^* dt = \frac{1}{T} \int_0^T Be^{jm\omega_0 t} Be^{-jm\omega_0 t} dt \\ &= \frac{B^2}{T} \int_0^T e^{(m-m)\omega_0 t} dt = \frac{B^2}{T} \int_0^T 1 dt = \frac{B^2}{T} (T-0) = \frac{B^2}{T} \cdot T = B^2 \end{aligned}$$

El cruzado tiene dos casos:

$$\begin{aligned} \textcircled{1} \text{ Si } n \neq -m \rightarrow \bar{C}_x &= -\frac{2}{T} \int_T x_1(t) x_2^*(t) dt = -\frac{2}{T} \int_0^T Ae^{-jn\omega_0 t} (Be^{jm\omega_0 t})^* dt \\ &= -\frac{2}{T} \int_0^T Ae^{-jn\omega_0 t} Be^{jmb\omega_0 t} dt = -\frac{2AB}{T} \int_0^T e^{j(n-m)\omega_0 t} dt \rightarrow \text{Si } n, m \in \mathbb{Z} \rightarrow n+m = r \in \mathbb{Z} \\ &= -\frac{2AB}{T} \int_0^T e^{-jr\omega_0 t} dt = -\frac{2AB}{T} \left[\frac{e^{-jr\omega_0 t}}{-jr\omega_0} \right]_0^T = -\frac{2AB}{T} \left(\frac{e^{-jr\omega_0 T}}{-jr\omega_0} - \frac{e^{-jr\omega_0 \cdot 0}}{-jr\omega_0} \right) \\ &= -\frac{2AB}{T} \left(\frac{e^{-jr\omega_0 T} - 1}{-jr\omega_0} \right) = -\frac{2AB}{T} \left(\frac{\cos(jr\omega_0 T) - j\sin(jr\omega_0 T) - 1}{-jr\omega_0} \right) \\ &= -\frac{2AB}{T} \left(\frac{1 - 0 - 1}{-jr\omega_0} \right) = -\frac{2AB}{T} \left(\frac{0}{-jr\omega_0} \right) = 0 \end{aligned}$$

$$\begin{aligned} \textcircled{2} \text{ Si } n = -m \rightarrow \bar{C}_x &= -\frac{2}{T} \int_T x_1(t) x_2^*(t) dt = -\frac{2}{T} \int_0^T Ae^{-jn\omega_0 t} (Be^{jm\omega_0 t})^* dt = -\frac{2}{T} \int_0^T Ae^{-jn\omega_0 t} Be^{jmb\omega_0 t} dt \\ &= -\frac{2}{T} \int_0^T Ae^{-jn\omega_0 t} Be^{-jn\omega_0 t} dt = -\frac{2AB}{T} \int_0^T e^{-2jn\omega_0 t} dt = -\frac{2AB}{T} \int_0^T 1 dt \\ &= -\frac{2AB}{T} (T-0) = -\frac{2AB}{T} \cdot T = -2AB \end{aligned}$$

$$\bar{P}_{x_1 - x_2} = \begin{cases} A^2 + B^2 & ; n \neq -m \\ A^2 + B^2 - 2AB & ; n = -m \end{cases}$$

$$x_1(t) = Ae^{-jn\omega_0 t}, \quad x_2(t) = Be^{jm\omega_0 t}; \quad \omega_0 = \frac{2\pi}{T}$$

$$\bar{d}^2(x_1, x_2) = \bar{P}_{x_1 - x_2} = \lim_{T \rightarrow \infty} \frac{1}{T} \int_T |x_1(t) - x_2(t)|^2 dt$$

$$\begin{aligned} \bar{P}_{x_1 - x_2} &= \frac{1}{T} \int_T |x_1(t) - x_2(t)|^2 dt \\ &= \frac{1}{T} \left(\int_T (x_1(t) - x_2(t))(x_1(t) - x_2(t))^* dt \right) \\ &= \frac{1}{T} \left(\int_T (x_1(t) - x_2(t))(x_1^*(t) - x_2^*(t)) dt \right) \\ &= \frac{1}{T} \left(\int_T x_1(t) x_1^*(t) dt - \int_T x_1(t) x_2^*(t) dt - \int_T x_2(t) x_1^*(t) dt + \int_T x_2(t) x_2^*(t) dt \right) \\ &= \underbrace{\frac{1}{T} \int_T |x_1(t)|^2 dt}_{\bar{P}_{x_1}} - \underbrace{\frac{2}{T} \int_T x_1(t) x_2^*(t) dt}_{\bar{C}_x} + \underbrace{\frac{1}{T} \int_T |x_2(t)|^2 dt}_{\bar{P}_{x_2}} \end{aligned}$$



2. Encuentre la señal en tiempo discreto al utilizar un conversor análogo digital con frecuencia de muestreo de 5kHz y 4 bits de capacidad de representación, aplicado a la señal continua:

$$x(t) = 3 \cos(1000\pi t) + 5 \sin(3000\pi t) + 10 \cos(11000\pi t).$$

Realizar la simulación del proceso de discretización (incluyendo al menos tres periodos de $x(t)$). En caso de que la discretización no sea apropiada, diseñe e implemente un conversor adecuado para la señal estudiada.

$$X(t) = 3 \cos(1000\pi t) + 5 \sin(3000\pi t) + 10 \cos(11000\pi t)$$

$$F_s = 5\text{kHz}, \quad \# \text{ de estados} = 2^{4\text{bits}} = 16$$

$$t = nT_s \rightarrow F_s = \frac{1}{T_s}; \quad F = \frac{1}{T} \rightarrow T = \frac{2\pi}{\omega}$$

$$A \cos(\omega_1 n) \rightarrow \omega_1 = 2\pi f \rightarrow f = \frac{T_s}{T} = \frac{f}{F_s}$$

$$X(t) = X_1(t) + X_2(t) + X_3(t) \rightarrow$$

Para $X_1(t) = 3 \cos(1000\pi t)$

$$\omega_1 = 1000\pi \rightarrow T_1 = \frac{2\pi}{\omega_1} = \frac{2\pi}{1000\pi} = \frac{1}{500} \rightarrow F_1 = \frac{1}{T_1} = \frac{1}{\frac{1}{500}} = 500\text{Hz} \rightarrow X_1[n] = A \cos\left(2\pi n \cdot \frac{f}{F_s}\right) = 3 \cos\left(2\pi n \cdot \frac{500}{5000}\right) = 3 \cos\left(\frac{\pi n}{5}\right)$$

Para $X_2(t) = 5 \sin(3000\pi t)$

$$\omega_2 = 3000\pi \rightarrow T_2 = \frac{2\pi}{\omega_2} = \frac{2\pi}{3000\pi} = \frac{1}{1500} \rightarrow F_2 = \frac{1}{T_2} = \frac{1}{\frac{1}{1500}} = 1500\text{Hz} \rightarrow X_2[n] = A \sin\left(2\pi n \cdot \frac{f}{F_s}\right) = 5 \sin\left(2\pi n \cdot \frac{1500}{5000}\right) = 5 \sin\left(\frac{3\pi n}{5}\right)$$

Para $X_3(t) = 10 \cos(11000\pi t)$

$$\omega_3 = 11000\pi \rightarrow T_3 = \frac{2\pi}{\omega_3} = \frac{2\pi}{11000\pi} = \frac{1}{5500} \rightarrow F_3 = \frac{1}{T_3} = \frac{1}{\frac{1}{5500}} = 5500\text{Hz} \rightarrow X_3[n] = A \cos\left(2\pi n \cdot \frac{f}{F_s}\right) = 10 \cos\left(2\pi n \cdot \frac{5500}{5000}\right) = 10 \cos\left(\frac{11\pi n}{5}\right)$$

$$X[n] = 3 \cos\left(\frac{\pi n}{5}\right) + 5 \sin\left(\frac{3\pi n}{5}\right) + 10 \cos\left(\frac{11\pi n}{5}\right)$$

$$X[n] = 3 \cos\left(\frac{\pi}{5}n\right) + 5 \sin\left(\frac{3\pi}{5}n\right) + 10 \cos\left(\frac{11\pi}{5}n\right)$$

$$X[n] = 13 \cos\left(\frac{\pi}{5}n\right) + 5 \sin\left(\frac{\pi}{5}n\right)$$

$$\frac{\omega_1}{\omega_2} = \frac{1000\pi}{3000\pi} = \frac{1}{3} \in \mathbb{Q}$$

$$\frac{\omega_1}{\omega_3} = \frac{1000\pi}{11000\pi} = \frac{1}{11} \in \mathbb{Q}$$

$$\frac{\omega_2}{\omega_3} = \frac{3000\pi}{11000\pi} = \frac{3}{11} \in \mathbb{Q}$$

Como todas son racionales la señal es cuasiperiódica.

$\therefore F_s \geq 2F_{\max} \rightarrow 2F_{\max} = 2 \cdot 5500\text{Hz} = 11000\text{Hz} \rightarrow F_s = 5000\text{Hz}$

No cumple Nyquist

Vamos a comparar con las originales. $\rightarrow -\pi \leq \omega \leq \pi$

$\omega_1 = \frac{1}{5}\pi \checkmark, \quad \omega_2 = \frac{3}{5}\pi \checkmark, \quad \omega_3 = \frac{11}{5}\pi \times \rightarrow F_s \text{ una copia / aliasing}$

$\omega_{3\text{original}} = \frac{11}{5}\pi - 2\pi = \frac{1}{5}\pi$

Suponemos una frecuencia de muestreo mucho más grande

$F_s = 4F_{\max} \rightarrow F_s = 4(5500)\text{Hz} = 22\text{kHz}$

$T_s = \frac{1}{22000}$

Para $X_1(t) = 3 \cos(1000\pi t)$

$$\omega_1 = 1000\pi \rightarrow T_1 = \frac{2\pi}{\omega_1} = \frac{2\pi}{1000\pi} = \frac{1}{500} \rightarrow F_1 = \frac{1}{T_1} = \frac{1}{\frac{1}{500}} = 500\text{Hz} \rightarrow X_1[n] = A \cos\left(2\pi n \cdot \frac{f}{F_s}\right) = 3 \cos\left(2\pi n \cdot \frac{500}{22000}\right) = 3 \cos\left(\frac{\pi n}{22}\right)$$

Para $X_2(t) = 5 \sin(3000\pi t)$

$$\omega_2 = 3000\pi \rightarrow T_2 = \frac{2\pi}{\omega_2} = \frac{2\pi}{3000\pi} = \frac{1}{1500} \rightarrow F_2 = \frac{1}{T_2} = \frac{1}{\frac{1}{1500}} = 1500\text{Hz} \rightarrow X_2[n] = A \sin\left(2\pi n \cdot \frac{f}{F_s}\right) = 5 \sin\left(2\pi n \cdot \frac{1500}{22000}\right) = 5 \sin\left(\frac{3\pi n}{22}\right)$$

Para $X_3(t) = 10 \cos(11000\pi t)$

$$\omega_3 = 11000\pi \rightarrow T_3 = \frac{2\pi}{\omega_3} = \frac{2\pi}{11000\pi} = \frac{1}{5500} \rightarrow F_3 = \frac{1}{T_3} = \frac{1}{\frac{1}{5500}} = 5500\text{Hz} \rightarrow X_3[n] = A \cos\left(2\pi n \cdot \frac{f}{F_s}\right) = 10 \cos\left(2\pi n \cdot \frac{5500}{22000}\right) = 10 \cos\left(\frac{\pi n}{2}\right)$$

$$X[n] = 3 \cos\left(\frac{\pi n}{22}\right) + 5 \sin\left(\frac{3\pi n}{22}\right) + 10 \cos\left(\frac{\pi n}{2}\right)$$

Vamos a comparar con las originales. $\rightarrow -\pi \leq \omega \leq \pi$

$\omega_1 = \frac{1}{22}\pi \checkmark, \quad \omega_2 = \frac{3}{22}\pi \checkmark, \quad \omega_3 = \frac{1}{22}\pi \checkmark \rightarrow \text{Las tres frecuencias digitales están en los originales.}$

$$X[n] = 3 \cos\left(\frac{\pi n}{22}\right) + 5 \sin\left(\frac{3\pi n}{22}\right) + 10 \cos\left(\frac{\pi n}{2}\right)$$



3. Sea $x''(t)$ la segunda derivada de la señal $x(t)$, donde $t \in [t_i, t_f]$. Demuestre que los coeficientes de la serie exponencial de Fourier se pueden calcular según:

$$c_n = \frac{1}{(t_i - t_f)n^2\omega_0^2} \int_{t_i}^{t_f} x''(t) e^{-jn\omega_0 t} dt; \quad n \in \mathbb{Z}.$$

¿Cómo se pueden calcular los coeficientes a_n y b_n desde $x''(t)$ en la serie trigonométrica de Fourier?

Con $X(t)$ para $t \in [t_i, t_f]$
 Demostrar: $C_n = \frac{1}{(t_i - t_f)n^2\omega_0^2} \int_{t_i}^{t_f} x''(t) e^{-jn\omega_0 t} dt$ con $n \in \mathbb{Z}$

Tenemos: $X(t) = \sum_n C_n e^{jn\omega_0 t}$

$$X'(t) = \frac{\partial}{\partial t} \sum_n C_n e^{jn\omega_0 t} = \sum_n C_n \frac{\partial}{\partial t} e^{jn\omega_0 t}$$

$$X''(t) = \frac{\partial}{\partial t} X'(t) = \frac{\partial}{\partial t} \sum_n C_n \frac{\partial}{\partial t} e^{jn\omega_0 t} = \sum_n C_n \frac{\partial^2}{\partial t^2} e^{jn\omega_0 t}$$

$$\frac{\partial}{\partial t} e^{jn\omega_0 t} = jn\omega_0 e^{jn\omega_0 t}; \quad \frac{\partial^2}{\partial t^2} e^{jn\omega_0 t} = \frac{\partial}{\partial t} (jn\omega_0 e^{jn\omega_0 t}) = jn\omega_0 \cdot jn\omega_0 e^{jn\omega_0 t} = -n^2\omega_0^2 e^{jn\omega_0 t}$$

$$X''(t) = \sum_n C_n \frac{\partial^2}{\partial t^2} e^{jn\omega_0 t} = \sum_n C_n n^2 \omega_0^2 e^{jn\omega_0 t} = \sum_n C_{-n} e^{jn\omega_0 t}; \quad \text{con } C_{-n} = -C_n n^2 \omega_0^2$$

Si $C_n = \frac{1}{t_f - t_i} \int_{t_i}^{t_f} X(t) e^{-jn\omega_0 t} dt$ y $C_{-n} = \frac{1}{t_f - t_i} \int_{t_i}^{t_f} X'(t) e^{-jn\omega_0 t} dt \rightarrow$ Reemplazamos el $C_{-n} \rightarrow -C_n n^2 \omega_0^2 = \frac{1}{t_f - t_i} \int_{t_i}^{t_f} X''(t) e^{-jn\omega_0 t} dt$

$$C_n = \frac{1}{-(t_f - t_i)n^2\omega_0^2} \int_{t_i}^{t_f} X''(t) e^{-jn\omega_0 t} dt$$

$$C_n = \frac{1}{(t_i - t_f)n^2\omega_0^2} \int_{t_i}^{t_f} X''(t) e^{-jn\omega_0 t} dt$$

$$C_n = \frac{1}{(t_i - t_f)n^2\omega_0^2} \int_{t_i}^{t_f} X''(t) e^{-jn\omega_0 t} dt = \frac{1}{(t_i - t_f)n^2\omega_0^2} \int_{t_i}^{t_f} X''(t) (\cos(n\omega_0 t) - j\sin(n\omega_0 t)) dt$$

$$= \frac{1}{(t_i - t_f)n^2\omega_0^2} \int_{t_i}^{t_f} X''(t) \cos(n\omega_0 t) dt - j \frac{1}{(t_i - t_f)n^2\omega_0^2} \int_{t_i}^{t_f} X''(t) \sin(n\omega_0 t) dt$$

Sabiendo que: $A_n = \frac{2}{T} \int_{t_i}^{t_f} X(t) \cos(n\omega_0 t) dt$; $b_n = \frac{2}{T} \int_{t_i}^{t_f} X(t) \sin(n\omega_0 t) dt$ y $A_n = 2 \operatorname{Re}\{c_n\}$; $b_n = -2 \operatorname{Im}\{c_n\}$

$$A_n = 2 \operatorname{Re}\{c_n\} = 2 \frac{1}{(t_i - t_f)n^2\omega_0^2} \int_{t_i}^{t_f} X''(t) \cos(n\omega_0 t) dt$$

$$b_n = -2 \operatorname{Im}\{c_n\} = -2 \cdot \frac{1}{(t_i - t_f)n^2\omega_0^2} \int_{t_i}^{t_f} X''(t) \sin(n\omega_0 t) dt = 2 \frac{1}{(t_i - t_f)n^2\omega_0^2} \int_{t_i}^{t_f} X''(t) \sin(n\omega_0 t) dt$$

También se pueden calcular con: $X(t) = \sum_n A_n \cos(n\omega_0 t) + b_n \sin(n\omega_0 t)$

$$X(t) = \sum_n A_n \cos(n\omega_0 t) + b_n \sin(n\omega_0 t)$$

$$X'(t) = \sum_n A_n \sin(n\omega_0 t) n\omega_0 + b_n \cos(n\omega_0 t) n\omega_0$$

$$X''(t) = \sum_n A_n \cos(n\omega_0 t) n\omega_0 \cdot n\omega_0 - b_n \sin(n\omega_0 t) n\omega_0 \cdot n\omega_0 = \sum_n \underbrace{A_n n^2 \omega_0^2}_{a_n} \cos(n\omega_0 t) - \underbrace{b_n n^2 \omega_0^2}_{b_n} \sin(n\omega_0 t)$$

$$a_n = -A_n n^2 \omega_0^2, \quad b_n = -b_n n^2 \omega_0^2$$

$$A_n = \frac{2}{T} \int_{t_i}^{t_f} X(t) \cos(n\omega_0 t) dt \rightarrow a_n = \frac{2}{T} \int_{t_i}^{t_f} X''(t) \cos(n\omega_0 t) dt$$

$$-A_n n^2 \omega_0^2 = \frac{2}{T} \int_{t_i}^{t_f} X''(t) \cos(n\omega_0 t) dt$$

$$A_n = \frac{2}{-(t_f - t_i)n^2\omega_0^2} \int_{t_i}^{t_f} X''(t) \cos(n\omega_0 t) dt$$

$$A_n = \frac{2}{(t_i - t_f)n^2\omega_0^2} \int_{t_i}^{t_f} X''(t) \cos(n\omega_0 t) dt$$

$$b_n = \frac{2}{T} \int_{t_i}^{t_f} X(t) \sin(n\omega_0 t) dt \rightarrow b_n = \frac{2}{T} \int_{t_i}^{t_f} X''(t) \sin(n\omega_0 t) dt$$

$$-b_n n^2 \omega_0^2 = \frac{2}{T} \int_{t_i}^{t_f} X''(t) \sin(n\omega_0 t) dt$$

$$b_n = \frac{2}{-(t_f - t_i)n^2\omega_0^2} \int_{t_i}^{t_f} X''(t) \sin(n\omega_0 t) dt$$

$$b_n = \frac{2}{(t_i - t_f)n^2\omega_0^2} \int_{t_i}^{t_f} X''(t) \sin(n\omega_0 t) dt$$



4. Encuentre el espectro de Fourier, su parte real, imaginaria, magnitud, fase y el error relativo para $n \in \{0, \pm 1, \pm 2, \pm 3, \pm 4, \pm 5\}$, a partir de $x''(t)$ para la señal $x(t)$ en la Figura 1. Compruebe el espectro obtenido con la estimación a partir de $x(t)$. Presente las simulaciones de Python respectivas.

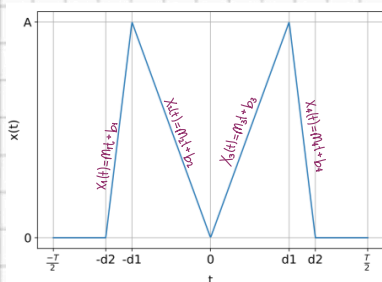


Figura 1: $x(t)$ para el ejercicio 1.4

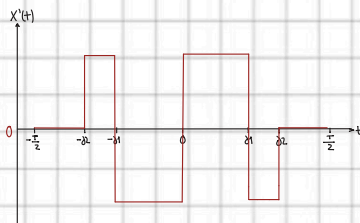
Para $x_1(t) = m_1 t + b_1$ $\rightarrow m_1 = \frac{A-0}{-d1 - (-d2)} = \frac{A}{d2-d1}$; $\text{En } t = -d2 \rightarrow X(-d2) = \frac{A}{d2-d1} \cdot (-d2) + b_1$
 $X_1(t) = \frac{A}{d2-d1} t + \frac{d2}{d2-d1} A$
 $X_1(t) = \frac{A}{d2-d1} (t + d2)$

Para $x_2(t) = m_2 t + b_2$ $\rightarrow m_2 = \frac{0-A}{0 - (-d1)} = \frac{-A}{d1}$; $\text{En } t = -d1 \rightarrow X(-d1) = \frac{-A}{d1} \cdot (-d1) + b_2$
 $X_2(t) = \frac{-A}{d1} t$
 $A = A + b_2$
 $b_2 = A - A = 0$

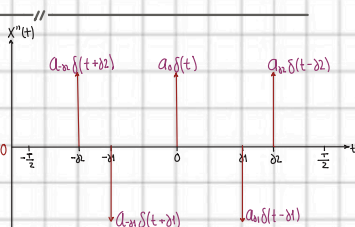
Para $x_3(t) = m_3 t + b_3$ $\rightarrow m_3 = \frac{A-0}{d1-0} = \frac{A}{d1}$; $\text{En } t = 0 \rightarrow X(0) = \frac{A}{d1} \cdot 0 + b_3$
 $X_3(t) = \frac{A}{d1} t$
 $0 = 0 + b_3$
 $b_3 = 0$

Para $x_4(t) = m_4 t + b_4$ $\rightarrow m_4 = \frac{0-A}{d2-d1} = \frac{-A}{d2-d1}$; $\text{En } t = d2 \rightarrow X(d2) = \frac{-A}{d2-d1} \cdot d2 + b_4$
 $X_4(t) = \frac{-A}{d2-d1} t + \frac{-Ad2}{d2-d1}$
 $X_4(t) = -\frac{A}{d2-d1} (t + d2)$
 $0 = \frac{-A}{d2-d1} \cdot d2 + b_4$
 $b_4 = \frac{-Ad2}{d2-d1}$

$$X(t) = \begin{cases} 0 & -\frac{T}{2} \leq t < -d2 \\ \frac{A}{d2-d1} (t + d2) & -d2 \leq t < -d1 \\ -\frac{A}{d1} t & -d1 \leq t < 0 \\ \frac{A}{d1} t & 0 \leq t < d1 \\ -\frac{A}{d2-d1} (t + d2) & d1 \leq t < d2 \\ 0 & d2 \leq t < \frac{T}{2} \end{cases}$$



$$X'(t) = \begin{cases} 0 & -\frac{T}{2} \leq t < -d2 \\ \frac{A}{d2-d1} & -d2 \leq t < -d1 \\ -\frac{A}{d1} & -d1 \leq t < 0 \\ \frac{A}{d1} & 0 \leq t < d1 \\ -\frac{A}{d2-d1} & d1 \leq t < d2 \\ 0 & d2 \leq t < \frac{T}{2} \end{cases}$$



$X''(t) = 0$ en cada tramo y en los puntos donde hay cambios tiende a $\pm \infty$ y estos cambios los podemos representar como $a_n \delta(t \pm t_n)$ donde a_n es la diferencia de la derivada por la derecha y la derivada por la izquierda y t_n donde ocurre el salto (cambio instantáneo)



$$A_{-1} = X'(-\partial_2^+) - X'(-\partial_2^-) = m_1 - 0 = \frac{A}{\partial_2 - \partial_1}$$

$$A_{-2} = X'(-\partial_1^+) - X'(-\partial_1^-) = m_2 - m_1 = -\frac{A}{\partial_1} - \frac{A}{\partial_2 - \partial_1} = -A \left(\frac{1}{\partial_1} + \frac{1}{\partial_2 - \partial_1} \right)$$

$$A_0 = X'(0^+) - X'(0^-) = m_3 - m_2 = \frac{A}{\partial_1} - \frac{A}{\partial_1} = \frac{A}{\partial_1} (1+1) = \frac{2A}{\partial_1}$$

$$A_{\partial_1} = X'(\partial_1^+) - X'(\partial_1^-) = m_4 - m_3 = -\frac{A}{\partial_2 - \partial_1} - \frac{A}{\partial_1} = -A \left(\frac{1}{\partial_2 - \partial_1} + \frac{1}{\partial_1} \right)$$

$$A_{\partial_2} = X'(\partial_2^+) - X'(\partial_2^-) = 0 - m_4 = 0 - \frac{A}{\partial_2 - \partial_1} = \frac{A}{\partial_2 - \partial_1}$$

$$X''(t) = A_{-2} \delta(t + \partial_2) + A_{-1} \delta(t + \partial_1) + A_0 \delta(t) + A_{\partial_1} \delta(t - \partial_1) + A_{\partial_2} \delta(t - \partial_2)$$

$$X''(t) = \frac{A}{\partial_2 - \partial_1} \delta(t + \partial_2) - A \left(\frac{1}{\partial_1} + \frac{1}{\partial_2 - \partial_1} \right) \delta(t + \partial_1) + \frac{2A}{\partial_1} \delta(t) - A \left(\frac{1}{\partial_2 - \partial_1} + \frac{1}{\partial_1} \right) \delta(t - \partial_1) + \frac{A}{\partial_2 - \partial_1} \delta(t - \partial_2)$$

$$X''(t) = \frac{A}{\partial_2 - \partial_1} (\delta(t + \partial_2) + \delta(t - \partial_2)) - A \left(\frac{1}{\partial_1} + \frac{1}{\partial_2 - \partial_1} \right) (\delta(t + \partial_1) + \delta(t - \partial_1)) + \frac{2A}{\partial_1} \delta(t)$$

$$C_n = \frac{1}{(t_i - t_f) \hbar^2 \omega^2} \int_{-T/2}^{T/2} X''(t) e^{-j\omega t} dt \quad \text{con } T = t_f - t_i = \frac{T}{2} - (-\frac{T}{2}) = T \quad \omega_0 = \frac{2\pi}{T}$$

$$C_n = \frac{1}{(t_i - t_f) \hbar^2 \omega^2} \int_{-T/2}^{T/2} \left(\frac{A}{\partial_2 - \partial_1} (\delta(t + \partial_2) + \delta(t - \partial_2)) - A \left(\frac{1}{\partial_1} + \frac{1}{\partial_2 - \partial_1} \right) (\delta(t + \partial_1) + \delta(t - \partial_1)) + \frac{2A}{\partial_1} \delta(t) \right) e^{-j\omega t} dt$$

$$C_n = \frac{1}{(t_i - t_f) \hbar^2 \omega^2} \left(\int_{-T/2}^{T/2} \frac{A}{\partial_2 - \partial_1} (\delta(t + \partial_2) + \delta(t - \partial_2)) e^{-j\omega t} dt - \int_{-T/2}^{T/2} A \left(\frac{1}{\partial_1} + \frac{1}{\partial_2 - \partial_1} \right) (\delta(t + \partial_1) + \delta(t - \partial_1)) e^{-j\omega t} dt + \int_{-T/2}^{T/2} \frac{2A}{\partial_1} \delta(t) e^{-j\omega t} dt \right)$$

$$C_n = \frac{1}{(t_i - t_f) \hbar^2 \omega^2} \left(\int_{-T/2}^{T/2} \frac{A}{\partial_2 - \partial_1} \delta(t + \partial_2) e^{-j\omega t} dt + \int_{-T/2}^{T/2} \frac{A}{\partial_2 - \partial_1} \delta(t - \partial_2) e^{-j\omega t} dt - \int_{-T/2}^{T/2} A \left(\frac{1}{\partial_1} + \frac{1}{\partial_2 - \partial_1} \right) \delta(t + \partial_1) e^{-j\omega t} dt - \int_{-T/2}^{T/2} A \left(\frac{1}{\partial_1} + \frac{1}{\partial_2 - \partial_1} \right) \delta(t - \partial_1) e^{-j\omega t} dt + \int_{-T/2}^{T/2} \frac{2A}{\partial_1} \delta(t) e^{-j\omega t} dt \right) \quad \text{Usando } \rightarrow \int_{-\infty}^{\infty} X(t) \delta(t - t_0) dt = X(t_0)$$

$$C_n = \frac{1}{(t_i - t_f) \hbar^2 \omega^2} \left(\frac{A}{\partial_2 - \partial_1} e^{-j\omega_0 \partial_2} + \frac{A}{\partial_2 - \partial_1} e^{-j\omega_0 \partial_2} - A \left(\frac{1}{\partial_1} + \frac{1}{\partial_2 - \partial_1} \right) e^{-j\omega_0 \partial_1} - A \left(\frac{1}{\partial_1} + \frac{1}{\partial_2 - \partial_1} \right) e^{-j\omega_0 \partial_1} + \frac{2A}{\partial_1} e^{0} \right)$$

$$C_n = \frac{1}{(t_i - t_f) \hbar^2 \omega^2} \left(\frac{A}{\partial_2 - \partial_1} (\cos(n\omega_0 \partial_2) + j\sin(n\omega_0 \partial_2) + \cos(n\omega_0 \partial_2) - j\sin(n\omega_0 \partial_2)) - A \left(\frac{1}{\partial_1} + \frac{1}{\partial_2 - \partial_1} \right) (\cos(n\omega_0 \partial_1) + j\sin(n\omega_0 \partial_1) + \cos(n\omega_0 \partial_1) - j\sin(n\omega_0 \partial_1)) + \frac{2A}{\partial_1} \right)$$

$$C_n = \frac{1}{(t_i - t_f) \hbar^2 \omega^2} \left(\frac{A}{\partial_2 - \partial_1} \cdot 2 \cos(n\omega_0 \partial_2) - A \left(\frac{1}{\partial_1} + \frac{1}{\partial_2 - \partial_1} \right) \cdot 2 \cos(n\omega_0 \partial_1) + \frac{2A}{\partial_1} \right)$$

$$C_n = \frac{2A}{(t_i - t_f) \hbar^2 \omega^2} \left(\frac{1}{\partial_2 - \partial_1} \cdot \cos(n\omega_0 \partial_2) - \left(\frac{1}{\partial_1} + \frac{1}{\partial_2 - \partial_1} \right) \cdot \cos(n\omega_0 \partial_1) + \frac{1}{\partial_1} \right)$$

$$C_n = \frac{2A}{(-\frac{T}{2} - \frac{T}{2}) \hbar^2 \frac{2\pi}{T}} \left(\frac{1}{\partial_2 - \partial_1} \cdot \cos(n\omega_0 \partial_2) - \left(\frac{1}{\partial_1} + \frac{1}{\partial_2 - \partial_1} \right) \cdot \cos(n\omega_0 \partial_1) + \frac{1}{\partial_1} \right)$$

$$C_n = \frac{-AT}{2 \hbar^2 \pi} \left(\frac{1}{\partial_2 - \partial_1} \cdot \cos(n\omega_0 \partial_2) - \left(\frac{1}{\partial_1} + \frac{1}{\partial_2 - \partial_1} \right) \cdot \cos(n\omega_0 \partial_1) + \frac{1}{\partial_1} \right)$$



$$P_e\{C_n\} = -\frac{AT}{2 \cdot n^2 \pi^2} \left(\frac{1}{\delta 2 - \delta 1} \cdot \cos(n\omega \delta 2) - \left(\frac{1}{\delta 1} + \frac{1}{\delta 2 - \delta 1} \right) \cdot \cos(n\omega \delta 1) + \frac{1}{\delta 1} \right) \quad y \quad \text{Im}\{C_n\} = 0 \longrightarrow \text{Simetría por}$$

$$|C_n| = \sqrt{P_e\{C_n\} + \text{Im}\{C_n\}^2} = \sqrt{\left(-\frac{AT}{2 \cdot n^2 \pi^2} \left(\frac{1}{\delta 2 - \delta 1} \cdot \cos(n\omega \delta 2) - \left(\frac{1}{\delta 1} + \frac{1}{\delta 2 - \delta 1} \right) \cdot \cos(n\omega \delta 1) + \frac{1}{\delta 1} \right) \right)^2}$$

$$\Theta_{C_n} = \tan^{-1} \left\{ \frac{\text{Im}\{C_n\}}{P_e\{C_n\}} \right\} = \tan^{-1} \left(\frac{0}{-\frac{AT}{2 \cdot n^2 \pi^2} \left(\frac{1}{\delta 2 - \delta 1} \cdot \cos(n\omega \delta 2) - \left(\frac{1}{\delta 1} + \frac{1}{\delta 2 - \delta 1} \right) \cdot \cos(n\omega \delta 1) + \frac{1}{\delta 1} \right)} \right) = 0$$

$$P_r\{x\} = (1 - \sum |C_n|^2 \frac{P_n}{P_r}) \cdot 100\% ; P_n = \frac{1}{T} E_n = \frac{1}{T} \int_0^T |e^{j\omega t} x|^2 dt = \frac{1}{T} \cdot T = 1$$

Como la señal es par solo vamos a integrar de 0 a $\delta 2$ ($X(-t) = X(t)$)

$$P_x = \frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} |X(t)|^2 dt = \frac{2}{T} \int_0^{\frac{T}{2}} |X(t)|^2 dt \rightarrow \text{Pero de } \delta 2 \text{ a } \frac{T}{2} \text{ es } 0 \rightarrow R_x = \frac{2}{T} \int_0^{\delta 2} |X(t)|^2 dt = \frac{2}{T} \left(\int_0^{\delta 1} \left(\frac{A}{\delta 1} t \right)^2 dt + \int_{\delta 1}^{\delta 2} \left(-\frac{A}{\delta 2 - \delta 1} (t + \delta 2) \right)^2 dt \right)$$

$$\begin{aligned} P_x &= \frac{2}{T} \left(\int_0^{\delta 1} \left(\frac{A}{\delta 1} t \right)^2 dt + \int_{\delta 1}^{\delta 2} \left(-\frac{A}{\delta 2 - \delta 1} (t + \delta 2) \right)^2 dt \right) = \frac{2}{T} \left(\frac{A^2}{\delta 1^3} \left[\frac{1}{3} t^3 \right]_0^{\delta 1} - \frac{A^2}{(\delta 2 - \delta 1)^3} \int_{\delta 1}^{\delta 2} (t + \delta 2)^2 dt \right) \\ &= \frac{2}{T} \left(\frac{A^2}{\delta 1^3} \left(\frac{\delta 1^3}{3} - 0 \right) - \frac{A^2}{(\delta 2 - \delta 1)^3} \left(\frac{t^3}{3} + \frac{2t^2\delta 2}{2} + \delta 2^2 t \right) \Big|_{\delta 1}^{\delta 2} \right) = \frac{2}{T} \left(\frac{A^2 \delta 1^3}{3 \delta 1^3} - \frac{A^2}{(\delta 2 - \delta 1)^3} \left(\frac{\delta 2^3}{3} + \frac{2\delta 2^2 \delta 2}{2} + \delta 2^2 \delta 2 - \left(\frac{\delta 1^3}{3} + \frac{2\delta 1^2 \delta 2}{2} + \delta 2^2 \delta 1 \right) \right) \right) \\ &= \frac{2}{T} \left(\frac{A^2 \delta 1}{3} - \frac{A^2}{(\delta 2 - \delta 1)^3} \left(\frac{\delta 2^3}{3} + \delta 2^2 + \delta 2^2 - \frac{\delta 1^3}{3} - \delta 1^2 \delta 2 - \delta 2^2 \delta 1 \right) \right) \end{aligned}$$

$$|C_n|^2 = \sqrt{\left(-\frac{AT}{2 \cdot n^2 \pi^2} \left(\frac{1}{\delta 2 - \delta 1} \cdot \cos(n\omega \delta 2) - \left(\frac{1}{\delta 1} + \frac{1}{\delta 2 - \delta 1} \right) \cdot \cos(n\omega \delta 1) + \frac{1}{\delta 1} \right) \right)^2}$$

$$= \left(\frac{AT}{2 \cdot n^2 \pi^2} \left(\frac{1}{\delta 2 - \delta 1} \cdot \cos(n\omega \delta 2) - \left(\frac{1}{\delta 1} + \frac{1}{\delta 2 - \delta 1} \right) \cdot \cos(n\omega \delta 1) + \frac{1}{\delta 1} \right) \right)^2$$

$$P_r(\%) = \left(1 - \frac{\left(\frac{AT}{2 \cdot n^2 \pi^2} \left(\frac{1}{\delta 2 - \delta 1} \cdot \cos(n\omega \delta 2) - \left(\frac{1}{\delta 1} + \frac{1}{\delta 2 - \delta 1} \right) \cdot \cos(n\omega \delta 1) + \frac{1}{\delta 1} \right) \right)^2}{\frac{2}{T} \left(\frac{A^2 \delta 1}{3} - \frac{A^2}{(\delta 2 - \delta 1)^3} \left(\frac{\delta 2^3}{3} + \delta 2^2 + \delta 2^2 - \frac{\delta 1^3}{3} - \delta 1^2 \delta 2 - \delta 2^2 \delta 1 \right) \right)} \right) \cdot 100(\%)$$

