

- 1.3 Encuentre la función de densidad espectral (transformada de Fourier) para las siguientes señales (sin aplicar propiedades):
 a) $e^{-a|t|}$, $a \in \mathbb{R}^+$; b) $\cos(w_c t)$, $w_c \in \mathbb{R}$; c) $\sin(w_s t)$, $w_s \in \mathbb{R}$
 d) $f(t) \cos(w_c t)$, $w_c \in \mathbb{R}$, $f(t) \in \mathbb{R}, \mathbb{C}$; e) $e^{-a|t|^2}$, $a \in \mathbb{R}^+$. f)
 $A \text{rect}_d(t)$, $A, d \in \mathbb{R}$.

$$X(\omega) = F\{x(t)\} = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$$

$$; F[e^{jw_0 t}] = 2\pi \delta(\omega - \omega_0)$$

a) $X(t) = e^{-a|t|}$, $a \in \mathbb{R}^+$ Para $|t|$ se puede expresar como $-t \in (-\infty, 0)$ y $t \in (0, \infty)$

$$\begin{aligned} F\{e^{-a|t|}\} &= \int_{-\infty}^{\infty} e^{-a|t|} e^{j\omega t} dt = \int_{-\infty}^0 e^{-a-t} e^{j\omega t} dt + \int_0^{\infty} e^{-a+t} e^{-j\omega t} dt = \int_{-\infty}^0 e^{(a-j\omega)t} dt + \int_0^{\infty} e^{-(a+j\omega)t} dt = \frac{e^{(a-j\omega)t}}{a-j\omega} \Big|_{-\infty}^0 + \frac{e^{-(a+j\omega)t}}{a+j\omega} \Big|_0^{\infty} \\ &= \frac{1}{a-j\omega} (e^0 - e^{\infty}) - \frac{1}{a+j\omega} (e^{-\infty} - e^0) = \frac{1}{a-j\omega} \left(1 - \frac{1}{e^{\infty}}\right) - \frac{1}{a+j\omega} \left(\frac{1}{e^{\infty}} - 1\right) = \frac{1}{a-j\omega} + \frac{1}{a+j\omega} = \frac{a+j\omega + a-j\omega}{a^2 - j^2 \omega^2} = \frac{2a}{a^2 + \omega^2} \end{aligned}$$

$$X(\omega) = \frac{2a}{a^2 + \omega^2}$$

b) $X(t) = \cos(w_c t)$; $w_c \in \mathbb{R}$ Si $\cos(w_c t) = \frac{e^{jw_c t} + e^{-jw_c t}}{2}$

$$\begin{aligned} F\{\cos(w_c t)\} &= \int_{-\infty}^{\infty} \cos(w_c t) e^{-j\omega t} dt = \int_{-\infty}^{\infty} \frac{e^{jw_c t} + e^{-jw_c t}}{2} e^{-j\omega t} dt = \frac{1}{2} \int_{-\infty}^{\infty} e^{jw_c t} e^{-j\omega t} dt + \frac{1}{2} \int_{-\infty}^{\infty} e^{-jw_c t} e^{-j\omega t} dt = \frac{1}{2} \int_{-\infty}^{\infty} e^{(w-w_c)t} dt + \frac{1}{2} \int_{-\infty}^{\infty} e^{(w+w_c)t} dt \\ &= \frac{1}{2} 2\pi \delta(\omega - w_c) + \frac{1}{2} 2\pi \delta(\omega + w_c) = \pi [\delta(\omega - w_c) + \delta(\omega + w_c)] \end{aligned}$$

$$X(\omega) = \pi [\delta(\omega - w_c) + \delta(\omega + w_c)]$$

$$\begin{aligned} \int_{-\infty}^{\infty} e^{j\omega t} dt &\stackrel{T \rightarrow \infty}{\rightarrow} \alpha \\ \int_{-\infty}^{\infty} e^{-j\omega t} dt &= \frac{e^{-j\omega T} - e^{j\omega T}}{-j\omega} = \frac{(e^{j\omega T} - e^{-j\omega T})}{j\omega} \cdot \frac{1}{2} \\ &= \frac{2 \operatorname{sen}(\omega T)}{\omega} \end{aligned}$$

$$\text{Si } \lim_{T \rightarrow \infty} \frac{\operatorname{sen}(\omega T)}{\omega T} = \delta(\omega) \rightarrow \lim_{T \rightarrow \infty} \frac{2 \operatorname{sen}(\omega T)}{\omega} = 2\pi \delta(\omega)$$

$$\text{Si } \alpha = \omega - w_c \rightarrow 2\pi \delta(\omega - w_c)$$

$$\text{Si } \alpha = \omega + w_c \rightarrow 2\pi \delta(\omega + w_c)$$

c) $X(t) = \operatorname{sen}(w_s t)$; $w_s \in \mathbb{R}$ Si $\operatorname{sen}(w_s t) = \frac{e^{jw_s t} - e^{-jw_s t}}{j2}$

$$\begin{aligned} F\{\operatorname{sen}(w_s t)\} &= \int_{-\infty}^{\infty} \operatorname{sen}(w_s t) e^{-j\omega t} dt = \int_{-\infty}^{\infty} \frac{e^{jw_s t} - e^{-jw_s t}}{j2} e^{-j\omega t} dt = \frac{1}{j2} \int_{-\infty}^{\infty} e^{jw_s t} e^{-j\omega t} dt - \frac{1}{j2} \int_{-\infty}^{\infty} e^{-jw_s t} e^{-j\omega t} dt = \frac{1}{j2} \int_{-\infty}^{\infty} e^{(w-w_s)t} dt - \frac{1}{j2} \int_{-\infty}^{\infty} e^{(w+w_s)t} dt \\ &= \frac{1}{j2} 2\pi \delta(\omega - w_s) - \frac{1}{j2} 2\pi \delta(\omega + w_s) = \frac{\pi}{j} [\delta(\omega - w_s) - \delta(\omega + w_s)] = \frac{j\pi}{j^2} [\delta(\omega - w_s) - \delta(\omega + w_s)] = \frac{j\pi}{j^2} [\delta(\omega - w_s) - \delta(\omega + w_s)] \\ &= -j\pi [\delta(\omega - w_s) - \delta(\omega + w_s)] \\ &= j\pi [\delta(\omega + w_s) - \delta(\omega - w_s)] \end{aligned}$$

$$X(\omega) = j\pi [\delta(\omega + w_s) - \delta(\omega - w_s)]$$

$$d) X(t) = f(t) \cos(\omega t); \omega \in \mathbb{R}, f(t) \in \mathbb{R}, \mathbb{C}$$

$$\begin{aligned} F\{f(t) \cos(\omega t)\} &= \int_{-\infty}^{\infty} f(t) \cos(\omega t) e^{-j\omega t} dt = \int_{-\infty}^{\infty} f(t) \frac{e^{j\omega t} + e^{-j\omega t}}{2} e^{-j\omega t} dt = \frac{1}{2} \int_{-\infty}^{\infty} f(t) (e^{j\omega t} + e^{-j\omega t}) e^{-j\omega t} dt = \frac{1}{2} \int_{-\infty}^{\infty} f(t) e^{j\omega t} e^{-j\omega t} dt + \frac{1}{2} \int_{-\infty}^{\infty} f(t) e^{-j\omega t} e^{-j\omega t} dt \\ &= \frac{1}{2} \int_{-\infty}^{\infty} f(t) e^{-(\omega - \omega_c)t} dt + \frac{1}{2} \int_{-\infty}^{\infty} f(t) e^{-(\omega + \omega_c)t} dt \end{aligned}$$

Si $\int_{-\infty}^{\infty} f(t) e^{j(\omega - \omega_c)t} dt = F(\omega - \omega_c)$ y $\int_{-\infty}^{\infty} f(t) e^{j(\omega + \omega_c)t} dt = F(\omega + \omega_c)$

Es la transformada de t desplazada.

$$\begin{aligned} &= \frac{1}{2} [F(\omega - \omega_c) + F(\omega + \omega_c)] \\ X(\omega) &= \frac{1}{2} (F(\omega - \omega_c) + F(\omega + \omega_c)) \end{aligned}$$

$$e) X(t) = e^{-|at|^2}; a \in \mathbb{R}^+ \quad \text{Para } a > 0$$

$$\begin{aligned} F\{e^{-at^2}\} &= \int_{-\infty}^{\infty} e^{-at^2} e^{-j\omega t} dt \end{aligned}$$

$-at^2 - j\omega t = -a(t^2 + \frac{j\omega}{a}t) \quad t^2 + \frac{j\omega}{a}t = (t + \frac{j\omega}{2a})^2 - (\frac{j\omega}{2a})^2$

$$\begin{aligned} &= -a \left((t + \frac{j\omega}{2a})^2 - (\frac{j\omega}{2a})^2 \right) \\ &= -a \left((t + \frac{j\omega}{2a})^2 - \frac{j\omega^2}{4a^2} \right) = -a \left((t + \frac{j\omega}{2a})^2 - \frac{-1\omega^2}{4a^2} \right) = -a \left(t + \frac{j\omega}{2a} \right)^2 + a \frac{-1\omega^2}{4a^2} = -a \left(t + \frac{j\omega}{2a} \right)^2 - \frac{\omega^2}{4a} \end{aligned}$$

$$\begin{aligned} &= \int_{-\infty}^{\infty} e^{-\frac{\omega^2}{4a}} e^{-a(t + \frac{j\omega}{2a})^2} dt \end{aligned}$$

Si $u = t + \frac{j\omega}{2a} \quad du = dt$

$$\begin{aligned} &= e^{\frac{\omega^2}{4a}} \int_{-\infty}^{\infty} e^{-au^2} du \end{aligned}$$

$I = \int_{-\infty}^{\infty} e^{-au^2} du$

$\text{En coordenadas polares } x = r \cos \theta, y = r \sin \theta, dx dy = r dr d\theta$

$$\begin{aligned} I^2 &= \left(\int_{-\infty}^{\infty} e^{-ax^2} dx \right) \left(\int_{-\infty}^{\infty} e^{-ay^2} dy \right) = \int_{0}^{\infty} \int_{0}^{\infty} e^{-a(x^2 + y^2)} dx dy \end{aligned}$$

$$\begin{aligned} I^2 &= \int_0^{2\pi} \int_0^{\infty} e^{-ar^2} r dr d\theta = 2\pi \int_0^{\infty} e^{-ar^2} r dr \end{aligned}$$

$r \in [0, \infty), \theta \in [0, 2\pi]$

$s = ar^2 \quad ds = 2ar dr \rightarrow r dr = \frac{ds}{2a}$

$\text{Cuando } r: 0 \rightarrow \infty \quad s: 0 \rightarrow \infty$

$$\begin{aligned} I^2 &= 2\pi \int_0^{\infty} e^{-\frac{s}{2a}} \frac{ds}{2a} = \frac{2\pi}{2a} \int_0^{\infty} e^{-\frac{s}{2a}} ds = \frac{\pi}{a} \cdot \left(-\frac{1}{2} e^{-\frac{s}{2a}} \right) \Big|_0^{\infty} = \frac{\pi}{a} \cdot (-1) = \frac{\pi}{a} \end{aligned}$$

$$\therefore I = \sqrt{\frac{\pi}{a}}$$

$$X(\omega) = e^{\frac{\omega^2}{4a}} \sqrt{\frac{\pi}{a}}$$

$$f) X(t) = A \text{rect}_d(t); A, d \in \mathbb{R} \quad \text{Con } \text{rect}_d(t) = \begin{cases} 1 & |t| \leq d/2 \\ 0 & |t| > d/2 \end{cases}$$

$\Rightarrow \text{Si } \text{rect}_d(t) = 1 \text{ Solo en } [-d/2, d/2]$

$$\begin{aligned} F\{A \text{rect}_d(t)\} &= \int_{-\infty}^{\infty} A \text{rect}_d(t) e^{-j\omega t} dt \\ &= \int_{-d/2}^{d/2} A \cdot 1 e^{-j\omega t} dt = A \left(\frac{e^{-j\omega t}}{-j\omega} \right) \Big|_{-d/2}^{d/2} = -\frac{A}{j\omega} (e^{-j\omega \cdot d/2} - e^{j\omega \cdot d/2}) = \frac{A}{j\omega} \frac{2(e^{j\omega \cdot d/2} - e^{-j\omega \cdot d/2})}{2 \cdot j} = \frac{2A}{\omega} \text{Sen}(\omega d/2) \end{aligned}$$

$$X(\omega) = \frac{2A}{\omega} \text{Sen}(\omega d/2)$$

- 1.4 Aplique las propiedades de la transformada de Fourier para resolver:
- $\mathcal{F}\{e^{-jw_1 t} \cos(w_c t)\}$, $w_1, w_c \in \mathbb{R}$
 - $\mathcal{F}\{u(t) \cos^2(w_c t)\}$, $w_c \in \mathbb{R}$
 - $\mathcal{F}^{-1}\left\{\frac{7}{w^2+6w+45}\right\} * \left\{\frac{10}{(8+jw/3)^2}\right\}$, $w \in \mathbb{R}$
 - $\mathcal{F}\{3t^3\}$
 - $\sum_{n=-\infty}^{+\infty} \left(\frac{1}{a^2 + (w - n\omega_o)^2} + \frac{1}{a+j(w - n\omega_o)} \right)$, donde $n \in \{0, \pm 1, \pm 2, \dots\}$, $\omega_o = 2\pi/T$ y $B, T \in \mathbb{R}^+$. Ver Tablas de propiedades y Tablas transformada de Fourier.

$$F[X(t)] = X(\omega) = \int_{-\infty}^{\infty} X(t) e^{-j\omega t} dt$$

$$F^{-1}[X(\omega)] = X(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) e^{j\omega t} d\omega$$

a) $F[e^{j\omega t} \cos(w_c t)] : w, w_c \in \mathbb{R}$ Si $\cos(w_c t) = \frac{e^{jw_c t} + e^{-jw_c t}}{2}$

$$e^{j\omega t} \cos(w_c t) = \frac{e^{j\omega t} + e^{-j\omega t}}{2} \cdot e^{-jw_c t} dt = \frac{1}{2} (e^{j(\omega-w_c)t} + e^{j(\omega+w_c)t} + e^{-j(\omega-w_c)t} + e^{-j(\omega+w_c)t}) = \frac{1}{2} (e^{j\omega t} (\delta(\omega - w_c) + \delta(\omega + w_c)))$$

$$\text{Si } F[e^{j\omega t}] = 2\pi \delta(\omega - \omega_0)$$

$$F\left[\frac{1}{2}(e^{j\omega(\omega_1-w_c)} + e^{j\omega(\omega_1+w_c)})\right] = \frac{1}{2} \left(F[e^{j\omega(\omega_1-w_c)}] + F[e^{j\omega(\omega_1+w_c)}] \right) = \frac{1}{2} (2\pi \delta(\omega - (\omega_1 - w_c)) + 2\pi \delta(\omega - (\omega_1 + w_c))) \\ = \frac{2\pi}{2} (\delta(\omega + \omega_1 - w_c) + \delta(\omega + \omega_1 + w_c)) = \pi (\delta(\omega + \omega_1 - w_c) + \delta(\omega + \omega_1 + w_c))$$

$$X(\omega) = \pi (\delta(\omega + \omega_1 - w_c) + \delta(\omega + \omega_1 + w_c))$$

b) $F[u(t) \cos^2(w_c t)] : w_c \in \mathbb{R}^+$ Si $u(t) = 1$ de $[0, \infty)$

$$\cos^2(w_c t) = \frac{1 + \cos(2w_c t)}{2} ; u(t) \cos^2(w_c t) = \frac{1}{2} u(t) + \frac{1}{2} u(t) \cos(2w_c t)$$

$$F[u(t)] = F[\text{source}] + F[\frac{1}{2}] = \frac{1}{j\omega} + \pi \delta(\omega)$$

$$F[u(t) \cos(w_c t)] = \frac{\pi}{2} (\delta(\omega - w_c) + \delta(\omega + w_c)) + \frac{j\omega}{(2w_c)^2 - \omega^2}$$

$$F[u(t) \cos^2(w_c t)] = \frac{1}{2} F[u(t)] + \frac{1}{2} F[u(t) \cos(2w_c t)] \\ = \frac{1}{2} \left(\frac{1}{j\omega} + \pi \delta(\omega) + \frac{\pi}{2} (\delta(\omega - 2w_c) + \delta(\omega + 2w_c)) + \frac{j\omega}{(2w_c)^2 - \omega^2} \right)$$

$$X(\omega) = \frac{1}{2} \left(\frac{1}{j\omega} + \pi \delta(\omega) + \frac{\pi}{2} (\delta(\omega - 2w_c) + \delta(\omega + 2w_c)) + \frac{j\omega}{(2w_c)^2 - \omega^2} \right)$$

c) $F^{-1}\left[\frac{7}{w^2+6w+45} * \frac{10}{(8+jw/3)^2}\right]$ Producto en frecuencia \rightarrow convolución en t

$$F^{-1}[G(\omega)H(\omega)](t) = \frac{1}{2\pi} (g * h)(t)$$

$$g(t) = F^{-1}\{G(\omega)\} \quad \text{y} \quad h(t) = F^{-1}\{H(\omega)\}$$

$$G(\omega) = \frac{7}{w^2 + 6w + 45} \rightarrow w^2 + 6w + 45 = (w+3)^2 + 36 = (w+3)^2 + 6^2$$

$$G(\omega) = \frac{7}{(w+3)^2 + 6^2} \quad \text{Si } e^{j\omega t} \leftrightarrow \frac{2\omega}{\omega^2 + \omega^2} = \frac{1}{(w-w_0)^2 + \omega^2} \leftrightarrow \frac{1}{2\omega} e^{j\omega t} e^{j\omega_0 t}$$

$$(w+3)^2 + 6^2 = (w-(-3))^2 + 6^2$$

$$G(\omega) = \frac{7}{(w-(-3))^2 + 6^2}$$

$$g(t) = F^{-1}\left[\frac{7}{w-(-3))^2 + 6^2}\right] = \frac{7}{2\cdot 6} e^{-6|t|} e^{-j3t} = \frac{7}{12} e^{-6|t|} e^{-j3t}$$

$$H(\omega) = \frac{10}{(8+j\omega/3)^2} \quad \text{circled}$$

$$H(\omega) = \frac{10}{q(24+j\omega)^2}$$

$$H(\omega) = 90 \cdot \frac{1}{(24+j\omega)^2} \rightarrow \text{Sí } F[t e^{at} u(t)] = \frac{1}{(a+j\omega)^2} \text{ para } a > 0$$

$$h(t) = F^{-1}\left[90 \frac{1}{(24+j\omega)^2}\right] = 90t e^{-24t} u(t)$$

$$X(t) = F^{-1}\{G \cdot H\} = \frac{1}{2\pi} (g * h) = \frac{1}{2\pi} \int_{-\infty}^{\infty} g(\tau) h(t-\tau) d\tau$$

$$X(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{1}{12} e^{-6|\tau|} e^{-j3\tau} 90(t-\tau) e^{-24(t-\tau)} u(t-\tau) d\tau$$

$$X(t) = \frac{1}{2\pi} \cdot \frac{1}{12} \int_{-\infty}^{\infty} e^{-6|\tau|} e^{-j3\tau} (t-\tau) e^{-24(t-\tau)} u(t-\tau) d\tau$$

$$X(t) = \frac{105}{4\pi} \int_{-\infty}^{\infty} e^{-6|\tau|} e^{-j3\tau} (t-\tau) e^{-24(t-\tau)} u(t-\tau) d\tau \rightarrow \text{Sí } u(t-\tau) = 1 \text{ en } (-\infty, t]$$

$$X(t) = \frac{105}{4\pi} \int_{-\infty}^t e^{-6|\tau|} e^{-j3\tau} (t-\tau) e^{-24(t-\tau)} d\tau$$

$$X(t) = \frac{105}{4\pi} \left(\int_{-\infty}^0 e^{6\tau} e^{-j3\tau} (t-\tau) e^{-24(t-\tau)} d\tau + \int_0^t e^{6\tau} e^{-j3\tau} (t-\tau) e^{-24(t-\tau)} d\tau \right)$$

$$X(t) = \frac{105}{4\pi} \left(\int_{-\infty}^0 e^{6\tau} e^{-j3\tau} (t-\tau) e^{-24(t-\tau)} d\tau + \int_0^t e^{6\tau} e^{-j3\tau} (t-\tau) e^{-24(t-\tau)} d\tau \right)$$

$$X(t) = \frac{105}{4\pi} e^{-24t} \left(\int_{-\infty}^0 e^{6\tau} e^{-j3\tau} (t-\tau) e^{24\tau} d\tau + \int_0^t e^{6\tau} e^{-j3\tau} (t-\tau) e^{24\tau} d\tau \right)$$

$$X(t) = \frac{105}{4\pi} e^{-24t} \left(\int_{-\infty}^0 (t-\tau) e^{\tau(30-j3)} d\tau + \int_0^t (t-\tau) e^{\tau(-30+j3)} d\tau \right)$$

$$\begin{aligned} \int_{-\infty}^0 (t-\tau) e^{\tau(30-j3)} d\tau &= \int_{-\infty}^0 t e^{\tau(30-j3)} d\tau - \int_{-\infty}^0 \tau e^{\tau(30-j3)} d\tau \\ &= t \cdot \frac{e^{\tau(30-j3)}}{30-j3} \Big|_{-\infty}^0 - \left(\frac{\tau e^{\tau(30-j3)}}{30-j3} - \frac{e^{\tau(30-j3)}}{(30-j3)^2} \right) \Big|_{-\infty}^0 \\ &= \frac{t}{30-j3} \left(e^{0^+} - e^{-\infty} \right) - \left(\frac{0 e^{0^+}}{30-j3} - \frac{e^{0^+}}{(30-j3)^2} - \left(\frac{1}{(30-j3)} e^{-\infty} - \frac{1}{(30-j3)^2} e^{-\infty} \right) \right) \\ &= \frac{t}{30-j3} + \frac{1}{(30-j3)^2} \end{aligned}$$

$$\begin{aligned} \int_0^t (t-\tau) e^{\tau(-30+j3)} d\tau &= \int_0^t t e^{\tau(-30+j3)} d\tau - \int_0^t \tau e^{\tau(-30+j3)} d\tau \\ &= t \cdot \frac{e^{\tau(-30+j3)}}{-30+j3} \Big|_0^t - \left(\frac{\tau e^{\tau(-30+j3)}}{-30+j3} - \frac{e^{\tau(-30+j3)}}{(-30+j3)^2} \right) \Big|_0^t \\ &= \frac{t}{-30+j3} \left(e^{0^-} - e^{0^+} \right) - \left(\frac{0 e^{0^-}}{-30+j3} - \frac{e^{0^+}}{(-30+j3)^2} - \left(\frac{1}{(-30+j3)} e^{0^-} - \frac{1}{(-30+j3)^2} e^{0^-} \right) \right) \\ &= \frac{t e^{(-30+j3)t}}{-30+j3} - \frac{t}{-30+j3} - \frac{t e^{(-30+j3)t}}{-30+j3} + \frac{1}{(-30+j3)^2} - \frac{1}{(-30+j3)^2} \\ &= \frac{e^{(-30+j3)t} - 1}{(-30+j3)^2} + \frac{t}{30+j3} \end{aligned}$$

$$X(t) = \frac{105}{4\pi} e^{-24t} \left(\frac{t}{30-j3} + \frac{1}{(30-j3)^2} + \frac{e^{(30-j3)t} - 1}{(30+j3)^2} + \frac{t}{30+j3} \right)$$

$$X(t) = \frac{105}{4\pi} e^{-24t} \left(t \left(\frac{1}{30-j3} + \frac{1}{30+j3} \right) + \left(\frac{1}{(30-j3)^2} - \frac{1}{(30+j3)^2} \right) + \frac{e^{(30-j3)t}}{(30+j3)^2} \right)$$

$$X(t) = \frac{105}{4\pi} e^{-24t} \left(t \frac{60}{30^2+3^2} + \frac{360j}{909^2} + \frac{e^{(30-j3)t}}{(30+j3)^2} \right)$$

d) $\mathcal{F}\{3t^3\} \rightarrow \delta; \mathcal{F}\{t^n X(t)\} = j^n \frac{\partial^n}{\partial w^n} X(w); X(t)=1 \rightarrow \mathcal{F}\{1\}=2\pi \delta(w)$

$$\mathcal{F}\{3t^3\} = 3j^3 \frac{\partial^3}{\partial w^3} (2\pi \delta(w)) = j^3 \cdot j \cdot 6\pi \delta^{(3)}(w) = -j6\pi \delta^{(3)}(w) \xrightarrow{\text{tercera derivada}}$$

e) $\frac{B}{T} \sum_{n=-\infty}^{+\infty} \left(\frac{1}{a^2 + (w-n\omega_0)^2} + \frac{1}{a+j(w-n\omega_0)} \right)$ donde $n \in \{0, \pm 1, \pm 2, \dots\}$, $\omega_0 = 2\pi/T$ y $B, T \in \mathbb{R}^+$

$$X(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{B}{T} \sum_{n=-\infty}^{+\infty} \left(\frac{1}{a^2 + (w-n\omega_0)^2} + \frac{1}{a+j(w-n\omega_0)} \right) e^{j\omega t} d\omega = \frac{B}{T2\pi} \sum_{n=-\infty}^{+\infty} \int_{-\infty}^{\infty} \left(\frac{1}{a^2 + (w-n\omega_0)^2} + \frac{1}{a+j(w-n\omega_0)} \right) e^{j\omega t} d\omega \xrightarrow{w=V+n\omega_0} V=w-n\omega_0 \quad dw=dV$$

$$= \frac{B}{T2\pi} \sum_{n=-\infty}^{+\infty} \left(\int_{-\infty}^{\infty} \frac{1}{a^2 + V^2} e^{j(V+n\omega_0)t} dV + \int_{-\infty}^{\infty} \frac{1}{a+jV} e^{j(V+n\omega_0)t} dV \right)$$

$$= \frac{B}{T2\pi} \sum_{n=-\infty}^{+\infty} \left(e^{\int_{-\infty}^{\infty} \frac{1}{a^2 + V^2} dV} \int_{-\infty}^{\infty} e^{j(V+n\omega_0)t} dV + e^{\int_{-\infty}^{\infty} \frac{1}{a+jV} dV} \int_{-\infty}^{\infty} e^{j(V+n\omega_0)t} dV \right)$$

$$= \frac{B}{T2\pi} \sum_{n=-\infty}^{+\infty} e^{\int_{-\infty}^{\infty} \frac{1}{a^2 + V^2} dV} \left(\int_{-\infty}^{\infty} \frac{1}{a^2 + V^2} e^{j(V+n\omega_0)t} dV + \int_{-\infty}^{\infty} \frac{1}{a+jV} e^{j(V+n\omega_0)t} dV \right) \xrightarrow{\text{Si } A(V) = \frac{1}{a^2 + V^2} \rightarrow A(t) = \mathcal{F}[A(V)] = \frac{1}{2a} e^{-|at|} \text{ para } a > 0}$$

$$B(V) = \frac{1}{a+jV} \text{ para } a > 0 \rightarrow B(t) = \mathcal{F}[B(V)] = e^{-at} U(t)$$

$$= \frac{B}{T2\pi} \sum_{n=-\infty}^{+\infty} e^{\int_{-\infty}^{\infty} \frac{1}{a^2 + V^2} dV} \left(2\pi \frac{1}{2a} e^{-|at|} + 2\pi e^{-at} U(t) \right)$$

$$= \frac{B2\pi}{T2\pi} \left(\frac{1}{2a} e^{-|at|} + e^{-at} U(t) \right) \sum_{n=-\infty}^{+\infty} e^{\int_{-\infty}^{\infty} \frac{1}{a^2 + V^2} dV}$$

$$= \frac{B}{T} \left(\frac{1}{2a} e^{-|at|} + e^{-at} U(t) \right) \sum_{n=-\infty}^{+\infty} e^{\int_{-\infty}^{\infty} \frac{1}{a^2 + V^2} dV} \xrightarrow{\sum_{n=-\infty}^{+\infty} e^{\int_{-\infty}^{\infty} \frac{1}{a^2 + V^2} dV} = 2\pi \sum_{k=-\infty}^{+\infty} \delta(wb - 2\pi k)} = 2\pi \sum_{k=-\infty}^{+\infty} \frac{1}{w_0} \delta(t - 2\pi k); w_0 = \frac{2\pi}{T} \rightarrow T = \frac{2\pi}{w_0}$$

$$= \frac{2\pi}{w_0} \sum_{k=-\infty}^{+\infty} \delta(t - \pi k) = T \sum_{k=-\infty}^{+\infty} \delta(t - \pi k)$$

$$= B \left(\frac{1}{2a} e^{-|at|} + e^{-at} U(t) \right) \sum_{k=-\infty}^{+\infty} \delta(t - \pi k)$$

$$= B \left(\frac{1}{2a} e^{-|at|} + e^{-at} U(t) \right) \sum_{k=-\infty}^{+\infty} \delta(t - \pi k)$$

2.3 Demuestre si los siguientes sistemas de la forma $y = \mathcal{H}\{x\}$, son sistemas lineales e invariantes en el tiempo (SLIT) (simule los sistemas en Python):

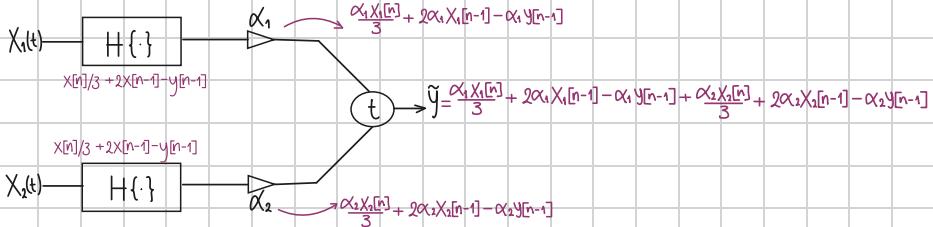
- $y[n] = x[n]/3 + 2x[n-1] - y[n-1]$.
- $y[n] = \sum_{k=-\infty}^n x^2[k]$.
- $y[n] = \text{median}(x[n])$; donde median es la función mediana sobre una ventana de tamaño 3.
- $y(t) = Ax(t) + B$; $A, B \in \mathbb{R}$.

$$1. y[n] = x[n]/3 + 2x[n-1] - y[n-1]$$

Siempre se asume linealidad a la entrada $x[n] = \alpha_1 x_1[n] + \alpha_2 x_2[n]$

$$\mathcal{H}\{x[n]\} = y[n] = x[n]/3 + 2x[n-1] - y[n-1] = \frac{\alpha_1 x_1[n] + \alpha_2 x_2[n]}{3} + 2(\alpha_1 x_1[n-1] + \alpha_2 x_2[n-1]) - y[n-1]$$

$$= \frac{\alpha_1 x_1[n]}{3} + \frac{\alpha_2 x_2[n]}{3} + 2\alpha_1 x_1[n-1] + 2\alpha_2 x_2[n-1] - \alpha_1 y_1[n-1] - \alpha_2 y_2[n-1]$$



$y[n] = \tilde{y}[n]$ El sistema es lineal si consideramos la dependencia de $y[n-1]$ y condiciones iniciales nulas

Si $y[n] = \mathcal{H}\{x[n]\}$, $x_1[n] = x[n-n_0]$, $y_1[n] = \mathcal{H}\{x_1[n]\}$, Si $y_1[n] = y[n-n_0]$

$$y_{d[n]} = \frac{x[n-n_0]}{3} + 2x[n-n_0-1] - y_1[n-1]$$

$$y_1[n-n_0] = \frac{x[n-n_0]}{3} + 2x[n-n_0-1] - y[n-n_0-1]$$

Si $y[n] = 0$; $n < 0 \rightarrow y_d[n] = y[n-n_0]$ para todo n .

El sistema es invariante en t

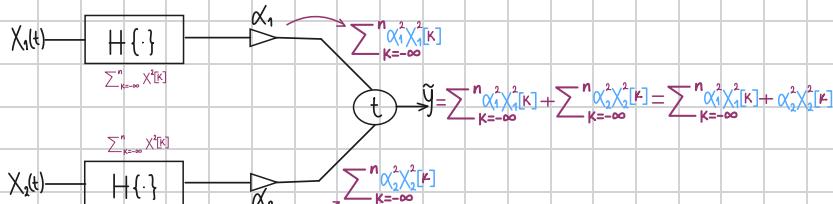
En conclusión el sistema es SLIT para condiciones iniciales = 0

$$2. y[n] = \sum_{k=-\infty}^n x^2[k]$$

Siempre se asume linealidad a la entrada $x[n] = \alpha_1 x_1[n] + \alpha_2 x_2[n]$

$$\mathcal{H}\{x[n]\} = y[n] = \sum_{k=-\infty}^n x^2[k] = \sum_{k=-\infty}^n (\alpha_1 x_1[k] + \alpha_2 x_2[k])^2$$

$$= \sum_{k=-\infty}^n \alpha_1^2 x_1^2[k] + 2\alpha_1 \alpha_2 x_1[k] x_2[k] + \alpha_2^2 x_2^2[k]$$



$$y[n] \neq \tilde{y}[n]$$

Si $y[n] = h[x[n]]$, $x_d[n] = x[n-n_0]$, $y_d[n] = h[x_d[n]]$, Si $y_d[n] = y[n-n_0]$

$$y_d[n] = \sum_{k=-\infty}^n (x[k-n_0])^2$$

$$y[n-n_0] = \sum_{m=-\infty}^{n-n_0} (x[m])^2 \text{ Si } m=k-n_0 \rightarrow k=m+n_0; k \rightarrow -\infty \rightarrow n: m=k-n_0 \rightarrow n-n_0$$

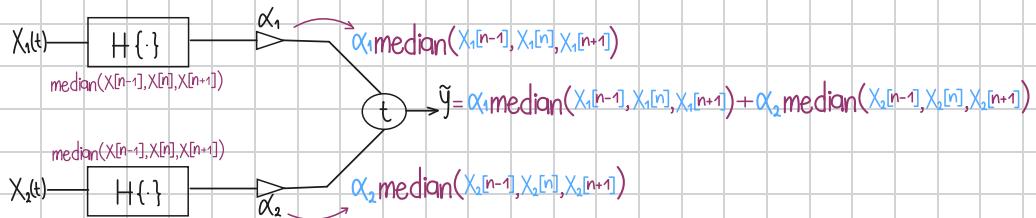
$$y[n-n_0] = \sum_{k=-\infty}^n (x[k-n_0])^2 \rightarrow y_d[n] = y[n-n_0]$$

En conclusión el sistema no es SUT porque aunque es invariante en el tiempo, no es lineal.

3. $y[n] = \text{median}(X[n])$; donde median es la función mediana sobre una ventana de tamaño 3

Siempre se asume linealidad a la entrada $X[n] = \alpha_1 X_1[n] + \alpha_2 X_2[n]$

$$h[x[n]] = y[n] = \text{median}(X[n-1], X[n], X[n+1]) = \text{median}(\alpha_1 X_1[n-1] + \alpha_2 X_2[n-1], \alpha_1 X_1[n] + \alpha_2 X_2[n], \alpha_1 X_1[n+1] + \alpha_2 X_2[n+1])$$



$$y[n] \neq \hat{y}[n]$$

Si $y[n] = h[x[n]]$, $x_d[n] = x[n-n_0]$, $y_d[n] = h[x_d[n]]$, Si $y_d[n] = y[n-n_0]$

$$y_d[n] = \text{median}(x_d[n-n_0-1], x_d[n-n_0], x_d[n-n_0+1])$$

$$y[n-n_0] = \text{median}(x_d[n-n_0-1], x_d[n-n_0], x_d[n-n_0+1])$$

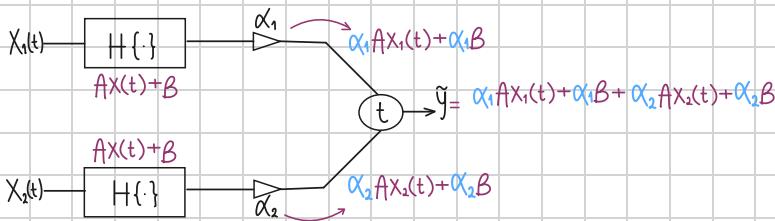
$$y_d[n] = y[n-n_0]$$

En conclusión el sistema no es SUT porque aunque es invariante en el tiempo, no es lineal.

4. $y(t) = Ax(t) + B$; $A, B \in \mathbb{R}$

Siempre se asume linealidad a la entrada $X(t) = \alpha_1 X_1(t) + \alpha_2 X_2(t)$

$$h[x[n]] = y[n] = Ax(t) + B = A(\alpha_1 X_1(t) + \alpha_2 X_2(t)) + B = A\alpha_1 X_1(t) + A\alpha_2 X_2(t) + B$$



$$y[n] \neq \hat{y}[n] \rightarrow \text{Para } B \neq 0$$

$$y[n] = \hat{y}[n] \rightarrow \text{Sólo es lineal si } B=0 \text{ o } \alpha_1 = \alpha_2 = \frac{1}{2}$$

Si $y(t) = H\{x(t)\}$, $x_d(t) = x(t-t_0)$, $y_d(t) = H\{x_d(t)\}$, Si $y_d(t) = y(t-t_0)$

$$y_d(t) = A(X(t-t_0)) + B$$

$$y(t-t_0) = A(X(t-t_0)) + B$$

$$y_d(t) = y(t-t_0)$$

En conclusión el sistema es invariante en el tiempo y es SUT solo cuando $B=0$ o $\alpha_1=\alpha_2=\frac{1}{2}$ porque de otra forma no es lineal.

- 2.5 Sea la señal Gaussiana $x(t) = e^{-at^2}$ con $a \in \mathbb{R}^+$, el sistema A con relación entrada-salida $y_A(t) = x^2(t)$, y el sistema lineal e invariante con el tiempo B con respuesta al impulso $h_B(t) = Be^{-bt^2}$: a) Encuentre la salida del sistema en serie $x(t) \rightarrow h_B(t) \rightarrow y_A(t) \rightarrow y(t)$ b) Encuentre la salida del sistema en serie $x(t) \rightarrow y_A(t) \rightarrow h_B(t) \rightarrow y(t)$.

$$X(t) * h(t) = \int_{-\infty}^{\infty} X(\tau) h(t-\tau) d\tau$$

Fase respuesta al impulso desplazado

$$y(t) = \int_{-\infty}^{\infty} X(\tau) h(t-\tau) d\tau$$

$$y(t) = X(t) * h(t)$$

$$h_B = Be^{-bt^2}$$

$$X(t) = e^{-at^2}$$

$$Y_A(t) = X^2(t)$$

$$a) X(t) \xrightarrow{h_B} U(t) \xrightarrow{A} Y(t)$$

$$U(t) = X(t) * h_B = \int_{-\infty}^{\infty} e^{-at^2} Be^{-b(\tau-t)^2} d\tau = B \int_{-\infty}^{\infty} e^{-(a\tau^2 + b(\tau-t)^2)} d\tau$$

$$\begin{aligned} a\tau^2 + b(\tau-t)^2 &= a\tau^2 + b(\tau^2 - 2t\tau + t^2) \\ &= a\tau^2 + bt^2 - 2bt\tau + b\tau^2 \\ &= (a+b)\tau^2 - 2bt\tau + bt^2 \end{aligned}$$

$$\begin{aligned} &= B \int_{-\infty}^{\infty} e^{-(a+b)(\tau - \frac{bt}{a+b})^2} d\tau = B \bar{e}^{\frac{ab}{a+b}t^2} \int_{-\infty}^{\infty} e^{-(a+b)(\tau - \frac{bt}{a+b})^2} d\tau \\ &\quad \text{Integral gaussiana:} \end{aligned}$$

$$(a+b)\left(\tau - \frac{2bt}{a+b}\right) = (a+b)\left[\left(\tau - \frac{bt}{a+b}\right)^2 - \left(\frac{bt}{a+b}\right)^2\right]$$

$$a\tau^2 + b(\tau-t)^2 = (a+b)\left(\tau - \frac{bt}{a+b}\right)^2 - (a+b)\left(\frac{bt}{a+b}\right)^2$$

$$bt^2 - (a+b)\frac{bt^2}{(a+b)^2} = bt^2 - \frac{b^2t^2}{a+b} = \frac{b(a+b)-b^2}{a+b}t^2 = \frac{ab}{a+b}t^2$$

$$a\tau^2 + b(\tau-t)^2 = (a+b)\left(\tau - \frac{bt}{a+b}\right)^2 + \frac{ab}{a+b}t^2$$

$$Y(t) = X^2(t) = \left(B \bar{e}^{\frac{ab}{a+b}t^2} \sqrt{\frac{\pi}{a+b}}\right)^2 = \frac{\pi}{a+b} B^2 \bar{e}^{\frac{2ab}{a+b}t^2}$$

$$a) \rightarrow Y(t) = \frac{B^2 \pi}{a+b} \bar{e}^{\frac{2ab}{a+b}t^2}$$

$$b) X(t) \xrightarrow{A} U(t) = Y_A(t) \xrightarrow{h_B} Y(t)$$

$$U(t) = X^2(t) = e^{-2at^2}$$

$$Y(t) = U(t) * h_B(t) = \int_{-\infty}^{\infty} e^{-2a\tau^2} Be^{-b(\tau-t)^2} d\tau = B \int_{-\infty}^{\infty} e^{-(2a\tau^2 + b(\tau-t)^2)} d\tau$$

$$\begin{aligned} 2a\tau^2 + b(\tau-t)^2 &= (2a+b)\tau^2 - 2bt + bt^2 \\ (2a+b)\left(\tau - \frac{bt}{2a+b}\right)^2 + \frac{bt^2}{2a+b} &= (2a+b)\left(\tau - \frac{bt}{2a+b}\right)^2 + \frac{b(2a+b)-b^2}{2a+b}t^2 \end{aligned}$$

$$= B \bar{e}^{\frac{(2a+b)(\tau - \frac{bt}{2a+b})^2}{2a+b} + \frac{b(2a+b)-b^2}{2a+b}t^2} \int_{-\infty}^{\infty} e^{-(2a+b)(\tau - \frac{bt}{2a+b})^2} d\tau$$

$$\frac{bt^2}{2a+b} = \frac{b(2a+b)-b^2}{2a+b}t^2 = \frac{2ab}{2a+b}t^2$$

$$= B \bar{e}^{\frac{2ab}{2a+b}t^2} \sqrt{\frac{\pi}{2a+b}}$$

$$(2a+b)\left(\tau - \frac{bt}{2a+b}\right)^2 + \frac{2ab}{2a+b}t^2$$