

Progress Report 3:

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Subsystem: Coding

Date of Submission: 18/01/2021

Reporting progress from: 10/01/2021 – 17/01/2021

Progress:

- **Course Completed:**
 1. MATLAB OnRamp
- **GitHub:**
 1. Learnt about Markdown Language
 2. Added an organized read me file in the repository
- **Researched About:**
 1. Holonomic drive for 3 and 4 wheeled bots
 2. The general formula in terms of velocity of each wheel and their angle from the axis.
 3. Motor Driver L293D
 4. H-bridge circuit
 5. Motor Driver MDD 10A
 6. Bluetooth sensor HC-05
- **Arduino UNO R3**
 1. Blinking and fading an LED
 2. Using a Potentiometer to control the angle of the servo motor
 3. Light input based buzzer using a photoresistor
 4. Tilt switch to light up the LEDs on either sides.
- **TinkerCad Circuits:**
 1. L293D Motor Driver to run a DC motor