

No. 2

a)

We start with the two dimensional wave equation

$$\frac{\partial^2 u(x, y, t)}{\partial t^2} = c^2 \left(\frac{\partial^2 u(x, y, t)}{\partial x^2} + \frac{\partial^2 u(x, y, t)}{\partial y^2} \right)$$

we know we want a discretization of $u(x, y, t)$

$$u(x, y, t) \rightarrow u_{i,j}^n \equiv u(i\Delta x, j\Delta y, n\Delta t)$$

the second derivative is given as

$$\frac{\partial^2 u(x, y, t)}{\partial t^2} \rightarrow \frac{u_{i,j}^{n-1} - 2u_{i,j}^n + u_{i,j}^{n+1}}{\Delta t^2}$$

this leaves us with

$$\frac{u_{i,j}^{n-1} - 2u_{i,j}^n + u_{i,j}^{n+1}}{\Delta t^2} = c^2 \left(\frac{u_{i+1,j}^n - 2u_{i,j}^n + u_{i-1,j}^n}{\Delta x^2} + \frac{u_{i,j+1}^n - 2u_{i,j}^n + u_{i,j-1}^n}{\Delta y^2} \right)$$

$$\Leftrightarrow u_{i,j}^{n-1} - 2u_{i,j}^n + u_{i,j}^{n+1} = c^2 \Delta t^2 \left(\frac{u_{i+1,j}^n - 2u_{i,j}^n + u_{i-1,j}^n}{\Delta x^2} + \frac{u_{i,j+1}^n - 2u_{i,j}^n + u_{i,j-1}^n}{\Delta y^2} \right)$$

b)

Von Neumann Stability

the complex i is red.

$$\tilde{u}_{i,j}^n = \tilde{c}_{\omega, k_x, k_y} e^{i(k_x i \Delta x + k_y j \Delta y - \omega n \Delta t)}$$

Let's plug it into the wave equation

$$\tilde{u}_{\omega, k_x, k_y}^{n+1} e^{i(k_x i \Delta x + k_y j \Delta y - \omega(n+1) \Delta t)}$$

$$- 2 \tilde{u}_{\omega, k_x, k_y}^n e^{i(k_x i \Delta x + k_y j \Delta y - \omega n \Delta t)}$$

$$+ \tilde{u}_{\omega, k_x, k_y}^{n-1} e^{i(k_x i \Delta x + k_y j \Delta y - \omega(n-1) \Delta t)}$$

$$= c^2 \Delta t^2 \left(\frac{1}{\Delta x^2} \tilde{u}_{\omega, k_x, k_y}^n e^{i(k_x(i+1) \Delta x + k_y j \Delta y - \omega n \Delta t)} \right.$$

$$- 2 \tilde{c}_{\omega, k_x, k_y}^h e^{i(k_x i \Delta x + k_y j \Delta y - \omega n \Delta t)}$$

$$+ \tilde{c}_{\omega, k_x, k_y}^n e^{i(k_x (i-1) \Delta x + k_y j \Delta y - \omega n \Delta t)} \Bigg)$$

$$+ \frac{1}{\gamma^2} \left(\tilde{c}_{\omega, k_x, k_y}^n e^{i(k_x i \Delta x + k_y (j+1) \Delta y - \omega n \Delta t)} \right)$$

$$- 2 \tilde{c}_{\omega, k_x, k_y}^n e^{i(k_x i \Delta x + k_y j \Delta y - \omega n \Delta t)}$$

$$+ \tilde{c}_{\omega, k_x, k_y}^n e^{i(k_x i \Delta x + k_y (j-1) \Delta y - \omega n \Delta t)} \Bigg) \Bigg)$$

$$\Rightarrow \tilde{c}_{\omega, k_x, k_y} e^{i \omega \Delta t} - 2 + \tilde{c}_{\omega, k_x, k_y}^{-1} e^{-i \omega \Delta t}$$

$$= c^2 \Delta t^2 \left(\frac{1}{\Delta x^2} \left(e^{i \Delta x k_x} - 2 + e^{-i k_x \Delta x} \right) \right)$$

$$+ \frac{1}{\Delta y^2} \left(e^{i \Delta y k_y} - 2 + e^{-i k_y \Delta y} \right) \Bigg)$$

\Rightarrow

$$\tilde{c}_{\omega, k_x, k_y} = c^2 \Delta t^2 \left(\frac{2 \cos(k_x \Delta x) - 2}{\Delta x^2} - \frac{2 \cos(k_y \Delta y) - 2}{\Delta y^2} \right) e^{\tilde{\omega} \Delta t} - 2e^{\omega \Delta t} - \frac{e^{2\omega \Delta t}}{\tilde{c}_{\omega, k_x, k_y}}$$

$$c) \quad u_{i,j}^1 = c^2 \Delta t^2 \left(\frac{u_{i+1,j}^0 - 2u_{i,j}^0 + u_{i-1,j}^0}{\Delta x^2} + \frac{u_{i,j+1}^0 - 2u_{i,j}^0 + u_{i,j-1}^0}{\Delta y^2} \right) + 2u_{i,j}^0 - u_{i,j}^{-1}$$

$$u_{i,j}^{-1} = -2 \Delta t \left. \frac{\partial u(x,y,t)}{\partial t} \right|_{t=0} + u_{i,j}^0 \quad (3.2) \text{ Kierfeld}$$

$$f'(x) = \frac{f(x+h) - f(x-h)}{2h}$$

$$\Rightarrow u_{i,j}^1 = c^2 \Delta t^2 \left(\frac{u_{i+1,j}^0 - 2u_{i,j}^0 + u_{i-1,j}^0}{\Delta x^2} + \frac{u_{i,j+1}^0 - 2u_{i,j}^0 + u_{i,j-1}^0}{\Delta y^2} \right) + 2u_{i,j}^0 - 4\Delta t u_{i,j}^0 \left. \frac{\partial u(x,y,t)}{\partial t} \right|_{t=0} =$$

d)

$$\tilde{x} = \frac{x}{l} \quad \tilde{y} = \frac{y}{l} \quad \tilde{t} = \frac{t}{\tau} \quad \tilde{c} = \frac{c}{v} \quad v = \frac{l}{\tau}$$

$$\tilde{c} \stackrel{!}{=} 1 \rightarrow v = c$$

$$\frac{\partial^2 u(\tilde{x}, \tilde{y}, \tilde{t})}{\cancel{\tau^2} \partial \tilde{t}^2} =$$

$$\sqrt{\frac{\tau^2}{\tau^2}} \cdot \left(\frac{\partial^2 u(\tilde{x}, \tilde{y}, \tilde{t})}{\cancel{\tau^2} \partial \tilde{x}^2} + \frac{\partial^2 u(\tilde{x}, \tilde{y}, \tilde{t})}{\cancel{\tau^2} \partial \tilde{y}^2} \right)$$

$$\Rightarrow \frac{\partial^2 u(\tilde{x}, \tilde{y}, \tilde{t})}{\partial \tilde{t}^2} = \tilde{c}^2 \left(\frac{\partial^2 u(\tilde{x}, \tilde{y}, \tilde{t})}{\partial \tilde{x}^2} + \frac{\partial^2 u(\tilde{x}, \tilde{y}, \tilde{t})}{\partial \tilde{y}^2} \right) =$$

$$\Rightarrow \tilde{c}_{\omega, k_x, k_y} e^{i \omega \Delta t} = 2 + \tilde{c}_{\omega, k_x, k_y}^{-1} e^{-i \omega \Delta t}$$

$$= c^2 \Delta t^2 \left(\frac{1}{\Delta x^2} \left(e^{i \Delta x k_x} - 2 + e^{-i k_x \Delta x} \right) + \frac{1}{\Delta y^2} \left(e^{i \Delta y k_y} - 2 + e^{-i k_y \Delta y} \right) \right)$$

$$-2 + ab + \frac{1}{ab} = c(d + e)$$

$$-2ab + (ab)^2 = abc(d + e)$$

$$0 = ab(-ab + 2 + c(d + e)) \quad ab = 2 + c(d + e)$$

$$\tilde{c}_{\omega, k_x, k_y} e^{i \omega \Delta t} = 2 + c^2 \Delta t^2$$

$$\cdot \left(\frac{2 \cos(k_x \Delta x) - 2}{\Delta x^2} - \frac{2 \cos(k_y \Delta y) - 2}{\Delta y^2} \right)$$

$$\tilde{c}_{\omega, k_x, k_y} = e^{-i \omega \Delta t} \left(2 + c^2 \Delta t^2 \left(\frac{\cos(k_x \Delta x) - 1}{\Delta x^2} - \frac{\cos(k_y \Delta y) - 1}{\Delta y^2} \right) \right)$$

This is probably wrong because it would mean that it is stable for every Δt as long as ω is real. And also that higher values of $\Delta x, \Delta y$ make it more stable.