

Volume-to-volume motion

.	Average abs. motion (mm)	1.19
.	Average rel. motion (mm)	0.76
.	Average x translation (mm)	0.45
.	Average y translation (mm)	0.04
.	Average z translation (mm)	-0.09
.	Average x rotation (deg)	0.61
.	Average y rotation (deg)	0.30
.	Average z rotation (deg)	0.68

Within-volume motion

.	Avg std x translation (mm)	0.03
.	Avg std y translation (mm)	0.14
.	Avg std z translation (mm)	0.04
.	Avg std x rotation (deg)	0.08
.	Avg std y rotation (deg)	0.05
.	Avg std z rotation (deg)	0.05

Outliers

.	Total outliers (%)	0.22
.	Outliers (b=1000 s/mm ²)	0.42
.	Outliers (b=2000 s/mm ²)	0.03
.	Outliers (PE dir=[0. 1. 0.])	0.00
.	Outliers (PE dir=[0. -1. 0.])	0.21

SNR/CNR

.	Average SNR (b=0 s/mm ²)	20.79
.	Average CNR (b=1000 s/mm ²)	1.80
.	Average CNR (b=2000 s/mm ²)	1.82

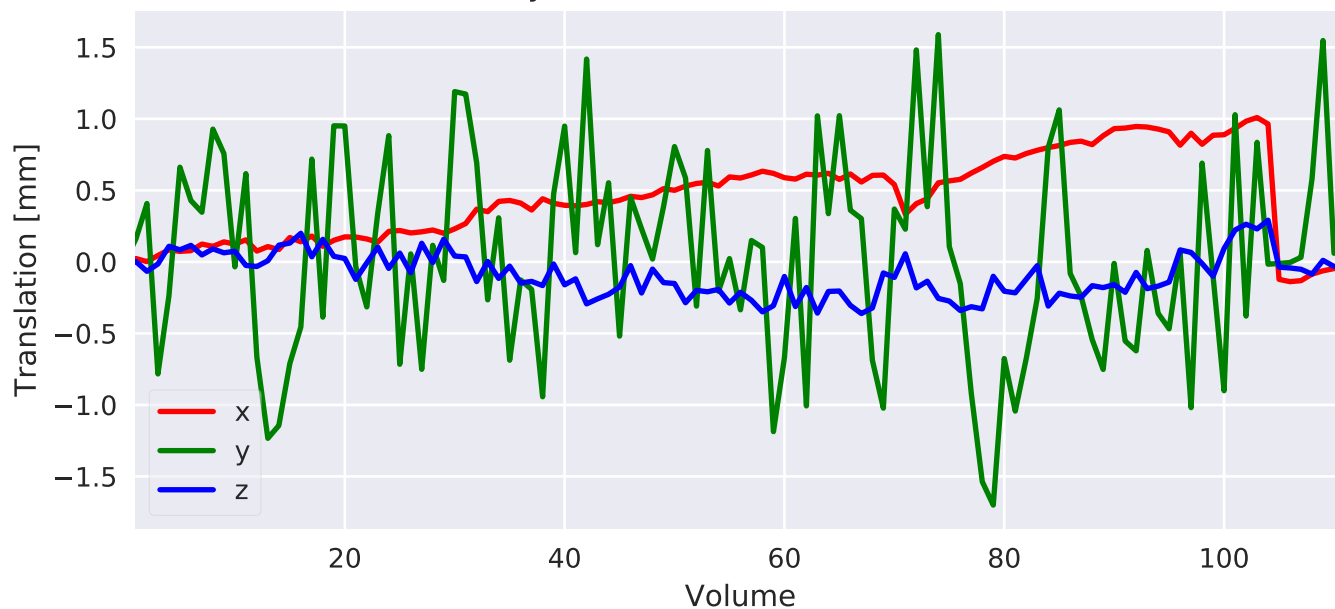
Eddy currents

.	Std Dev EC linear term (x)	0.06
.	Std Dev EC linear term (y)	0.05
.	Std Dev EC linear term (z)	0.09

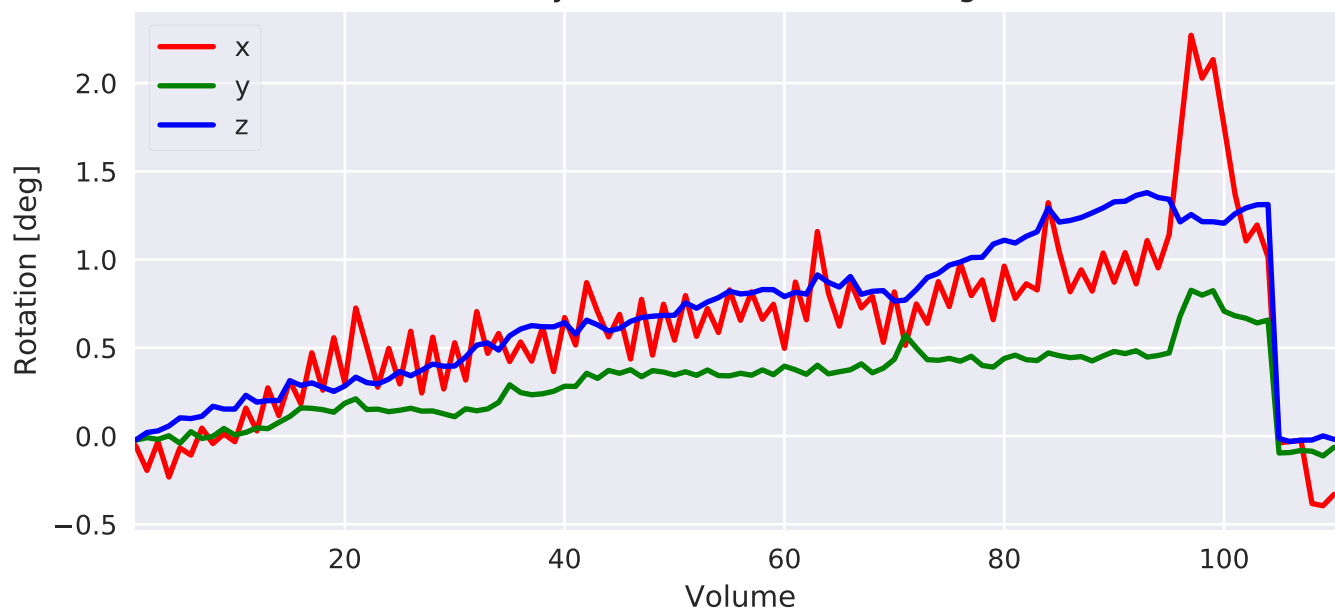
Susceptibility distortions

.	Std Dev voxel displacement	1.70
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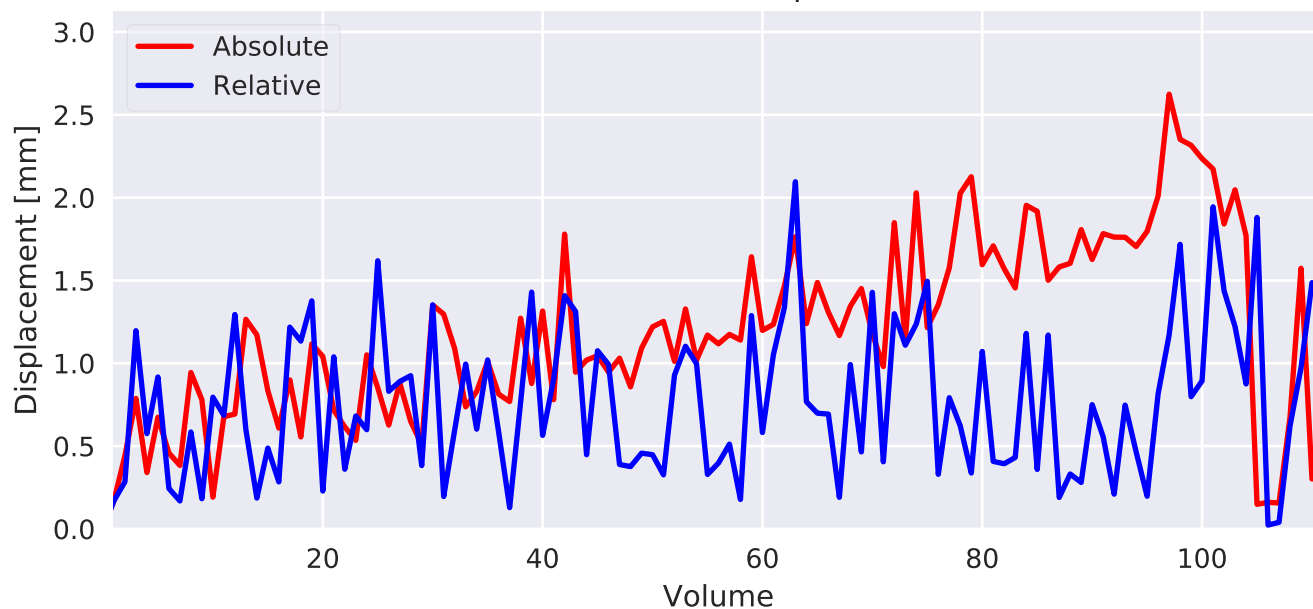
Eddy estimated translations (mm)



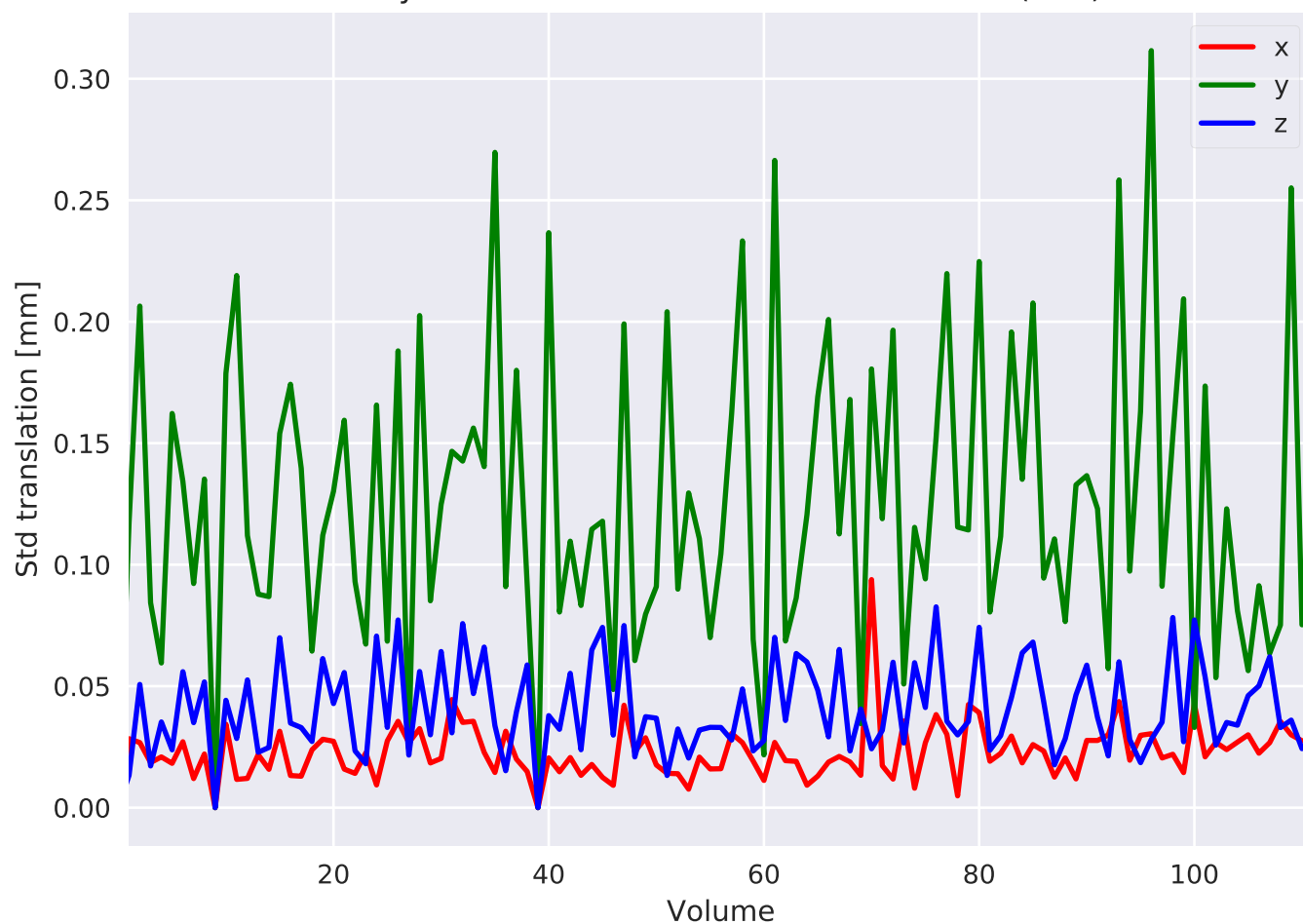
Eddy estimated rotations (deg)



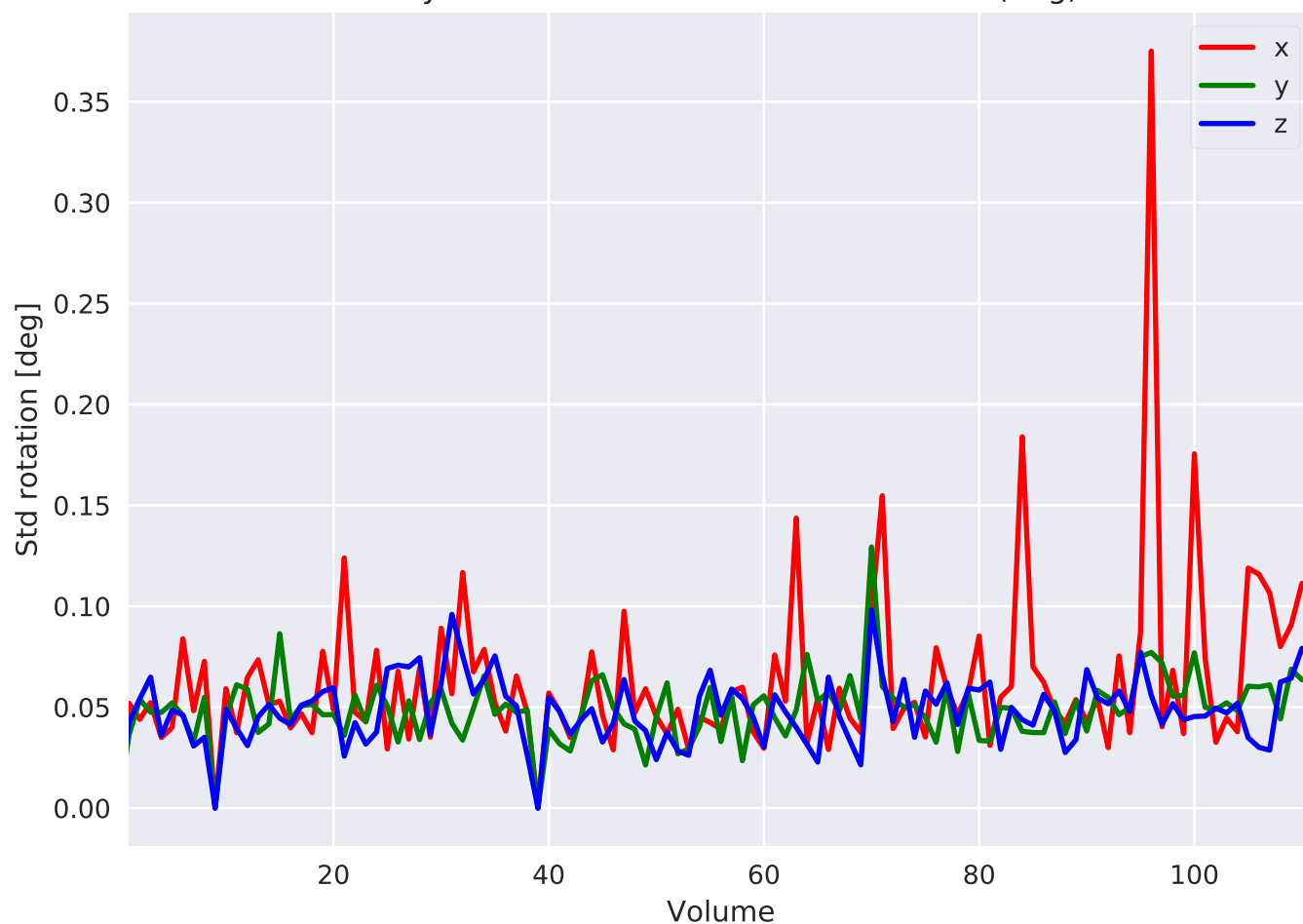
Estimated mean displacement



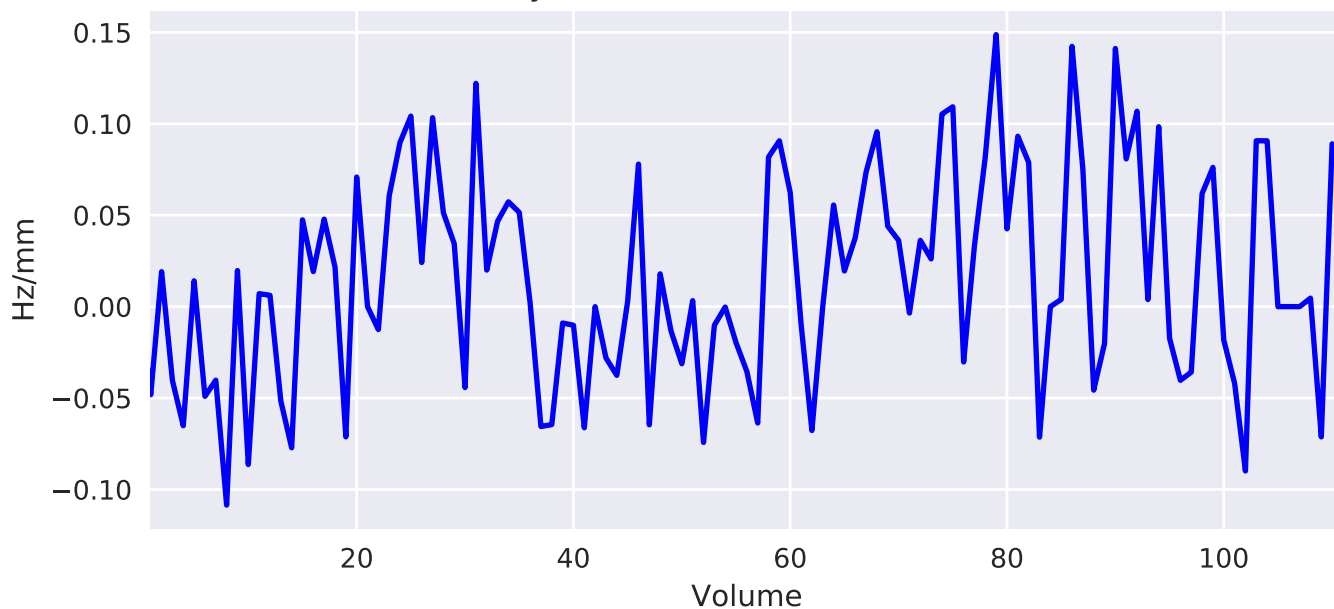
Eddy estimated within volume translations (mm)



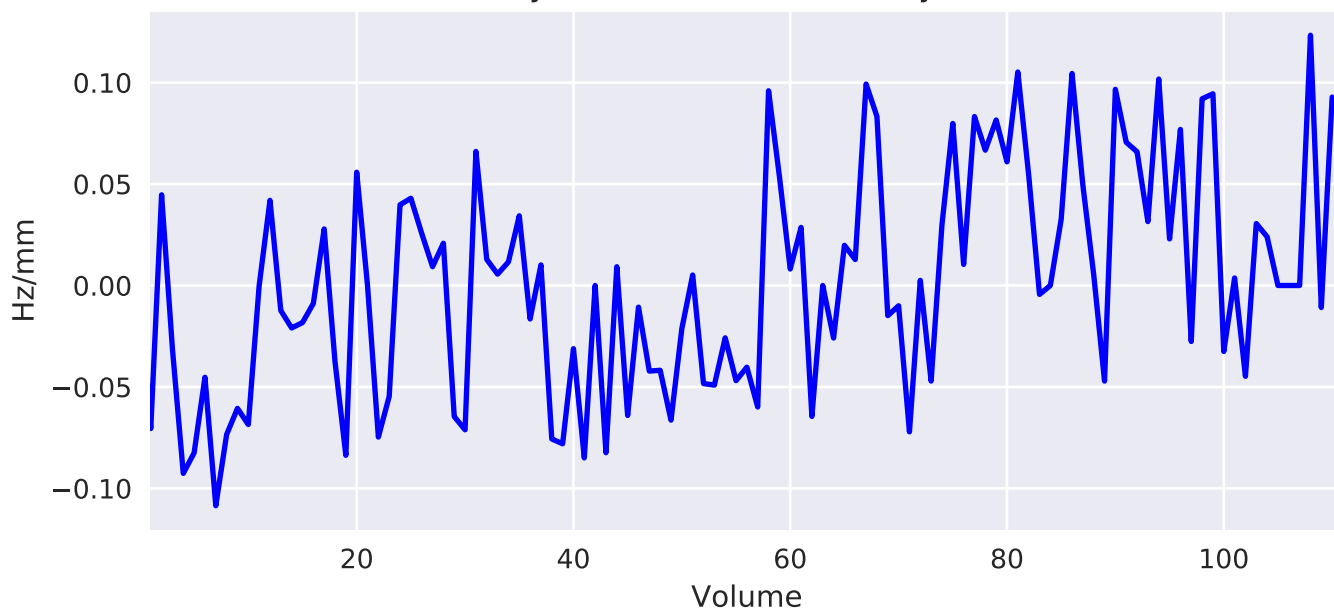
Eddy estimated within volume rotations (deg)



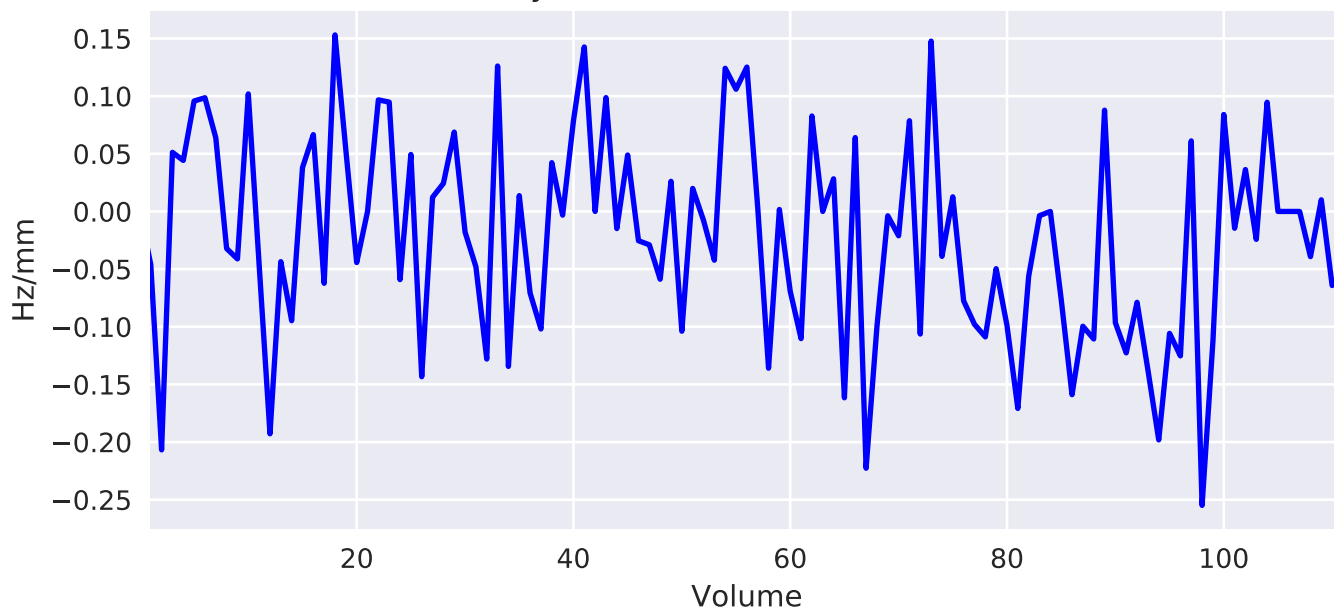
Eddy currents linear terms (x-axis)



Eddy currents linear terms (y-axis)



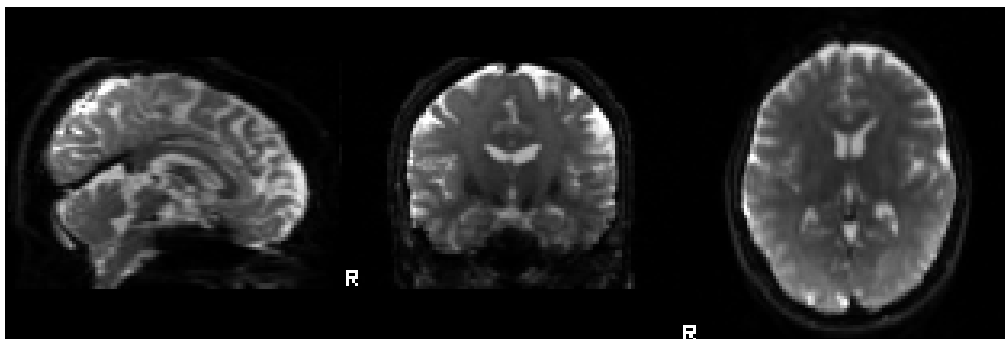
Eddy currents linear terms (z-axis)



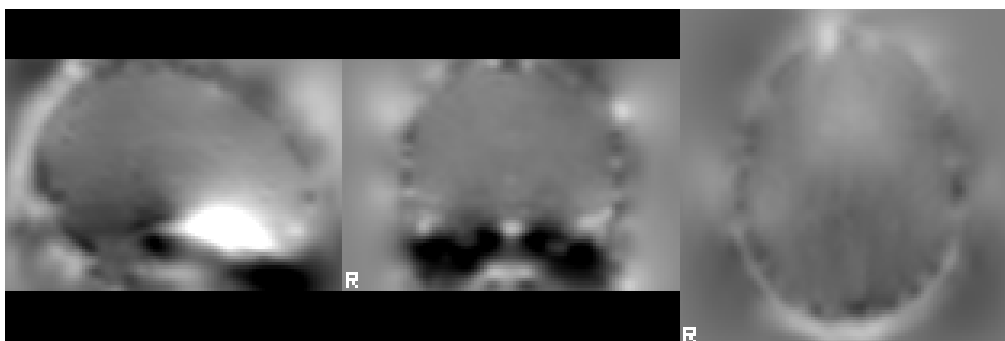
Average b0 signal (PE=[[0. 1. 0.]])



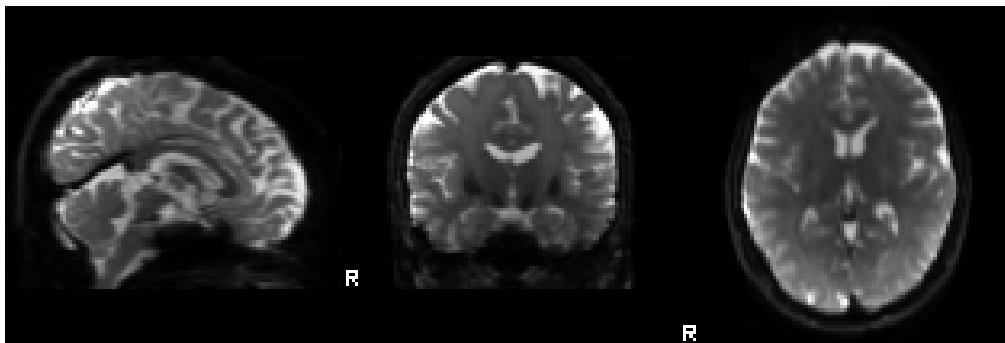
Average b0 signal (PE=[[0. -1. 0.]])



Voxel displacement map



Average DW signal (b=0)

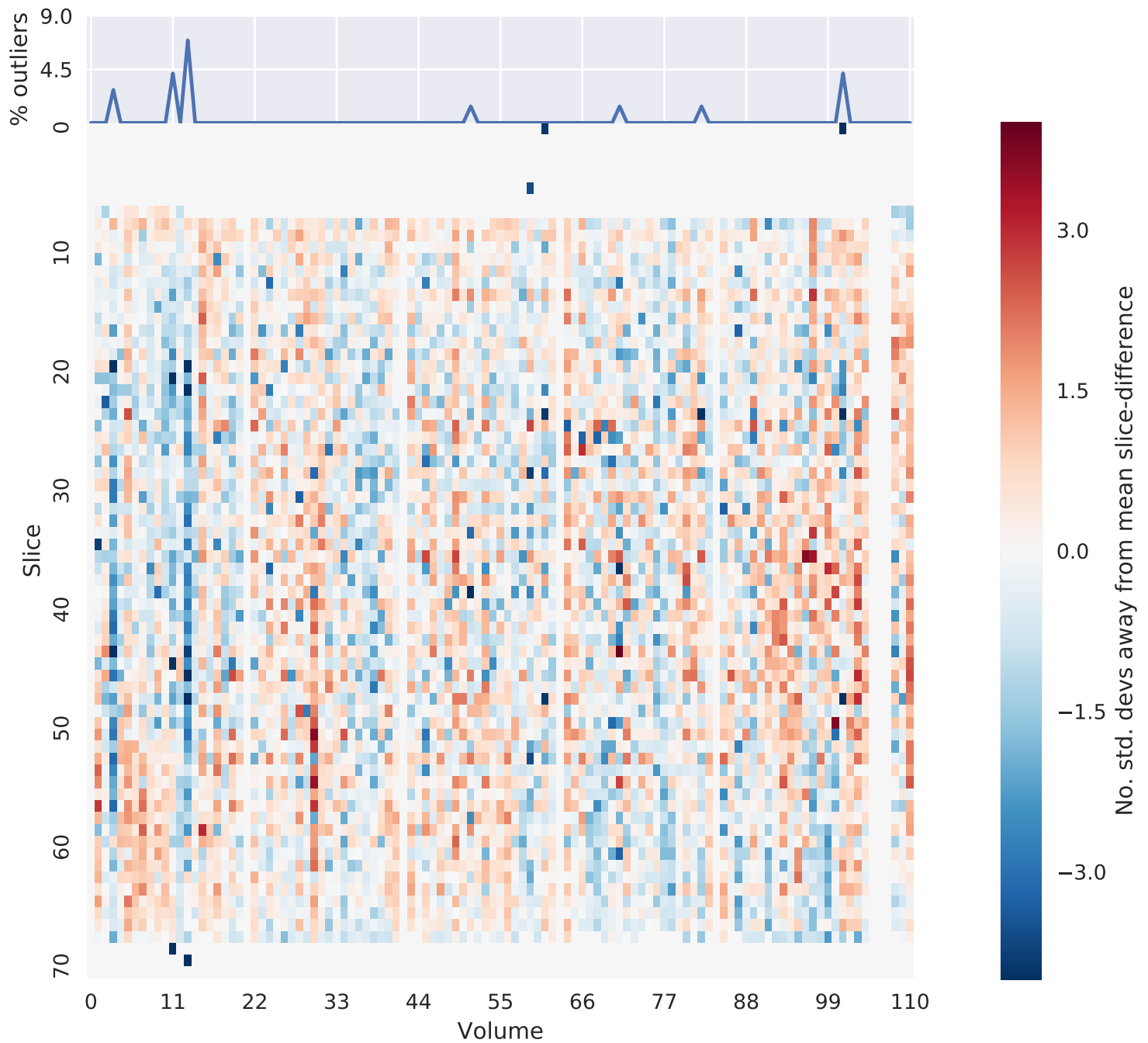
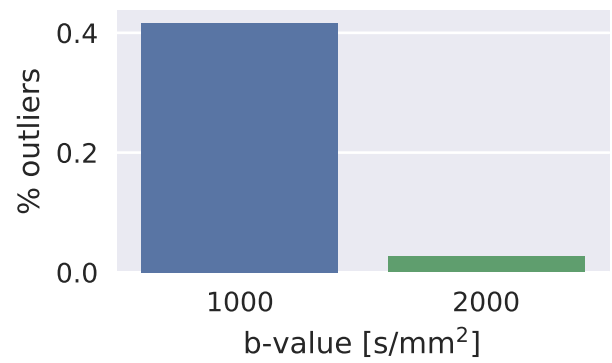
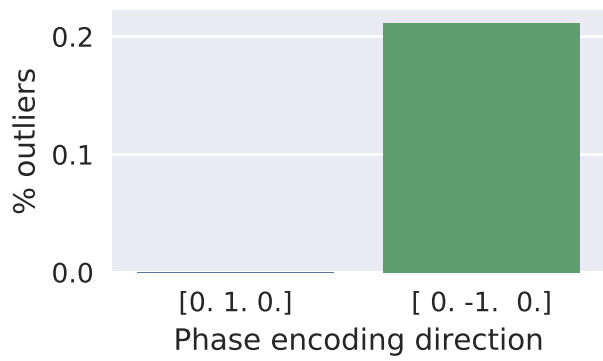


Average DW signal (b=1000)

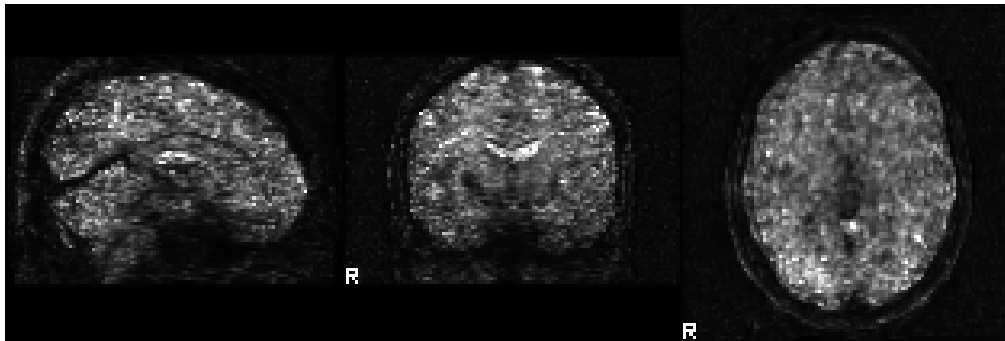


Average DW signal (b=2000)

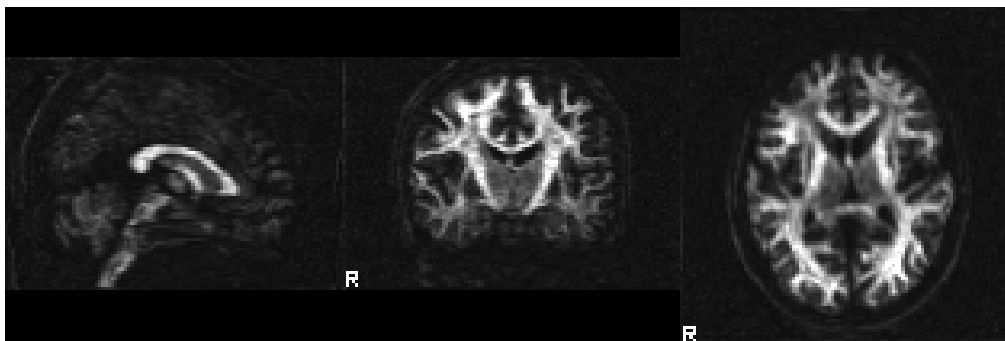




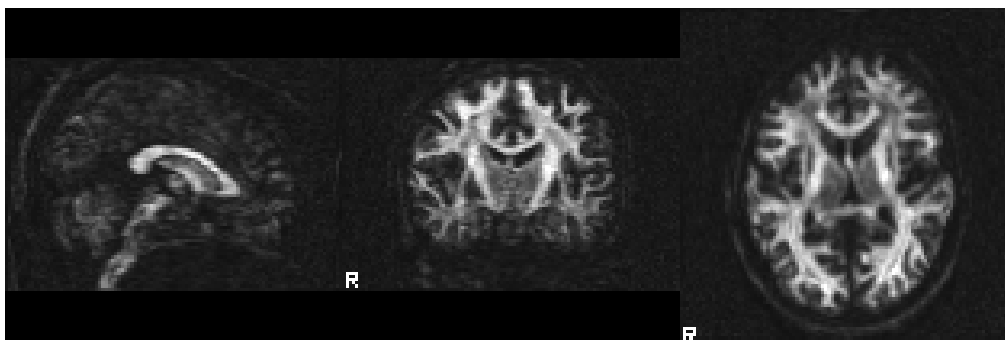
tSNR map (b=0)



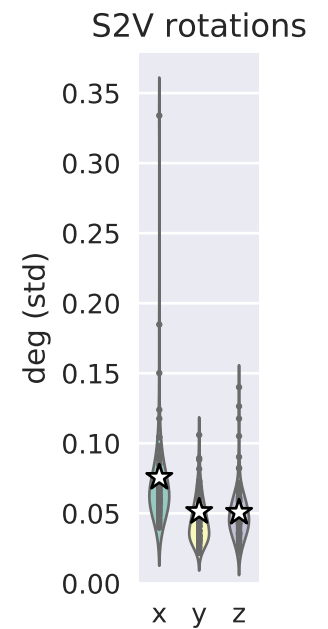
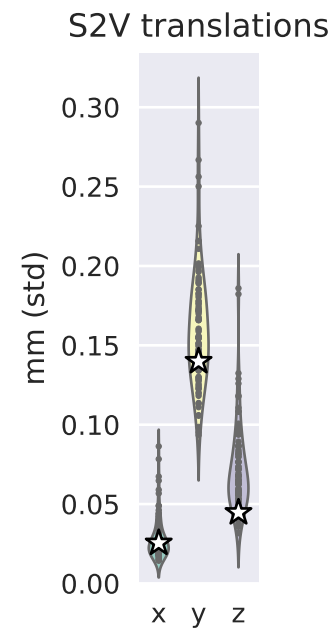
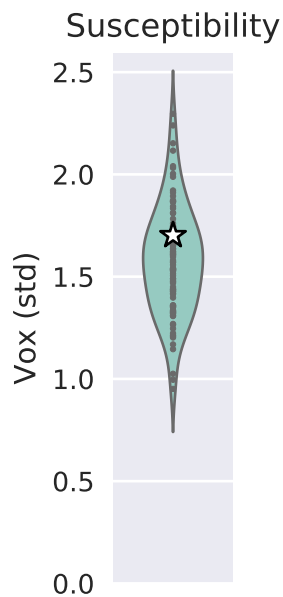
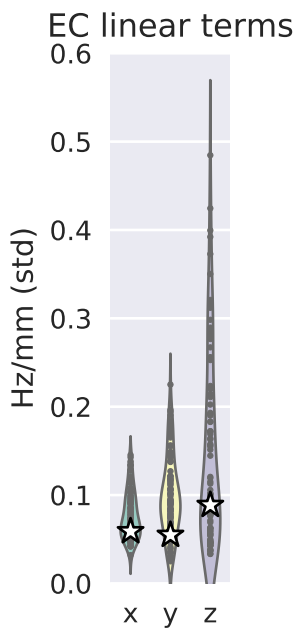
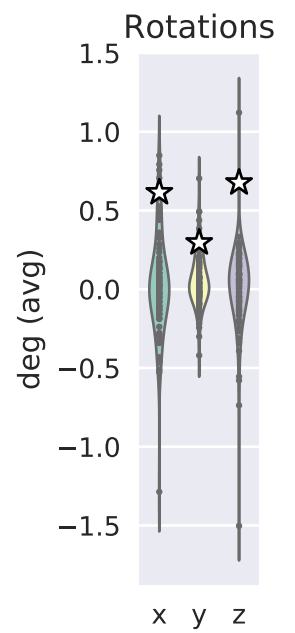
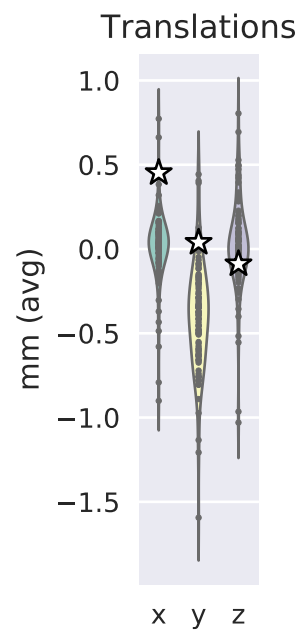
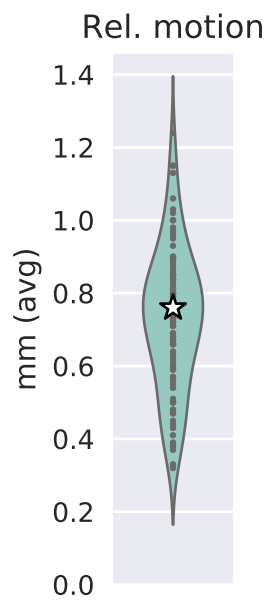
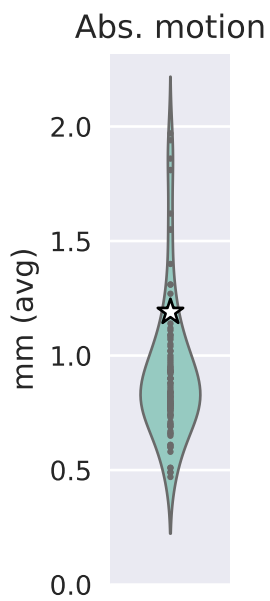
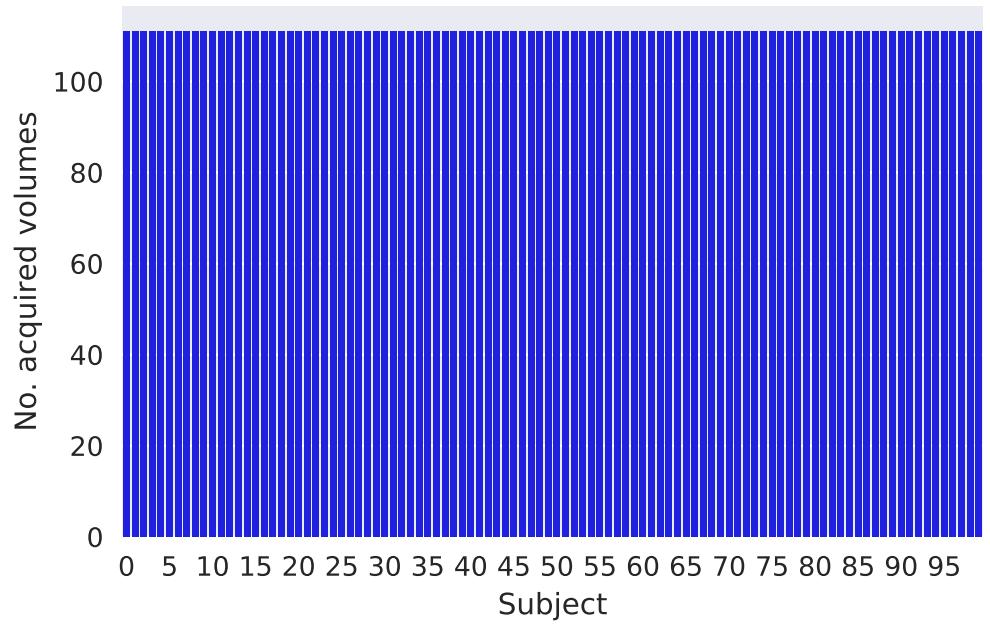
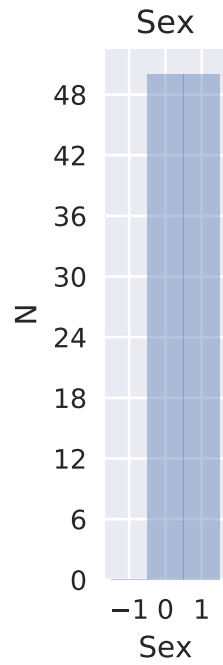
CNR map (b=1000)



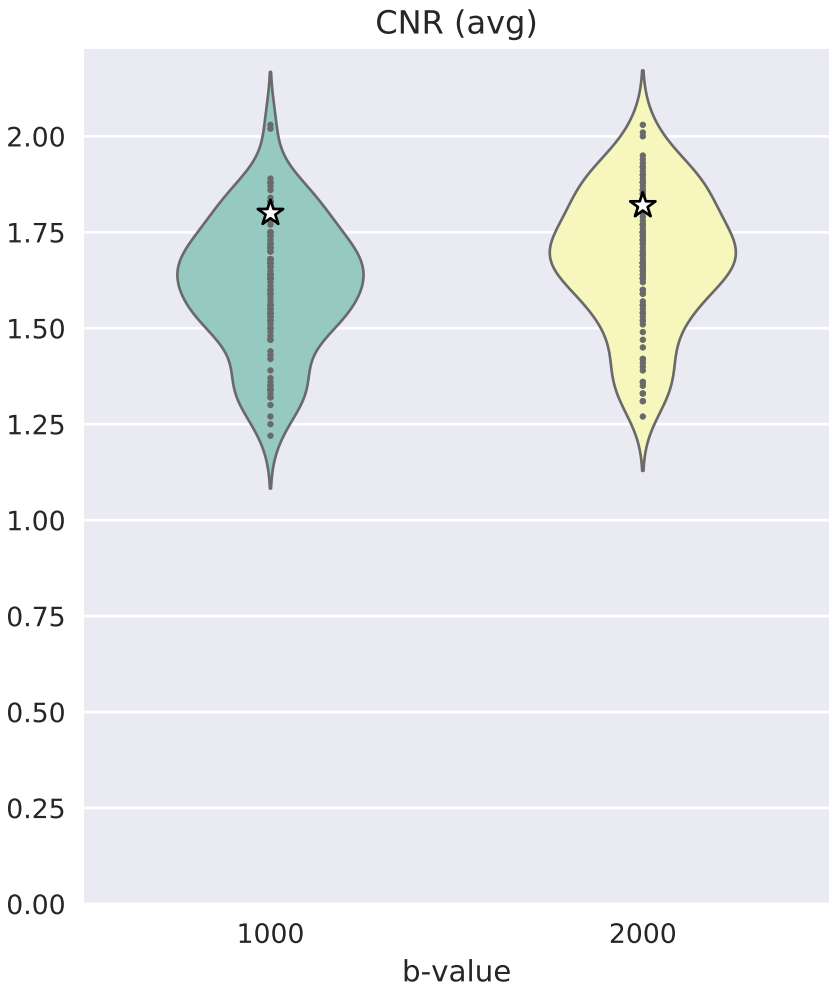
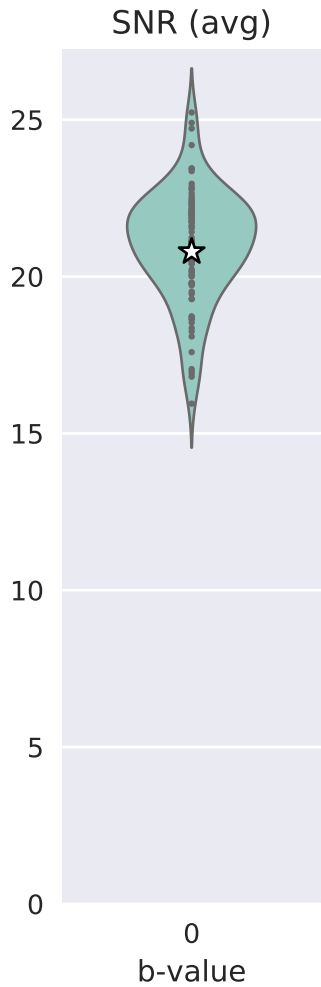
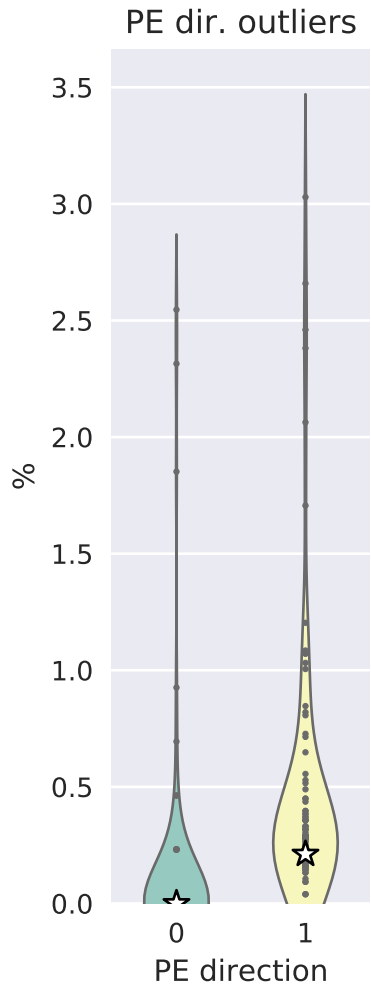
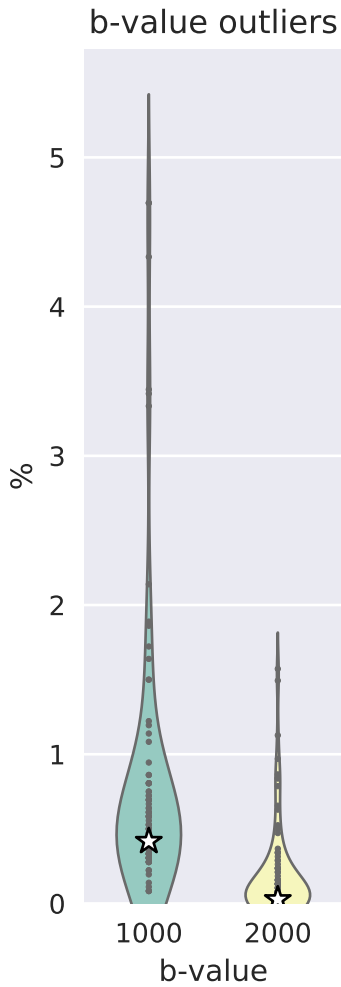
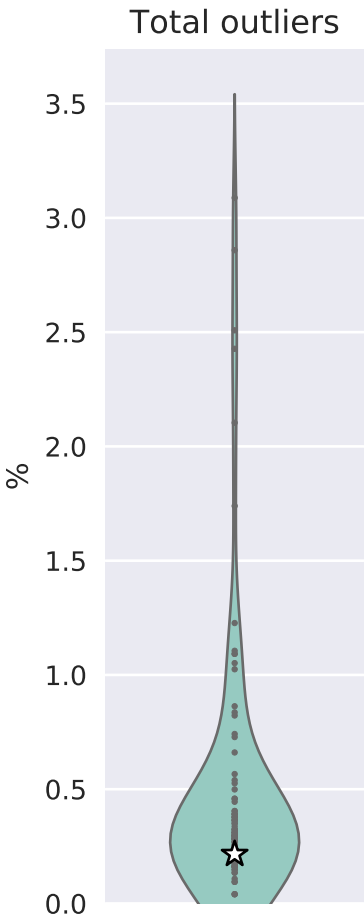
CNR map (b=2000)



QUAD: Group report



QUAD: Group report



QUAD: Group report

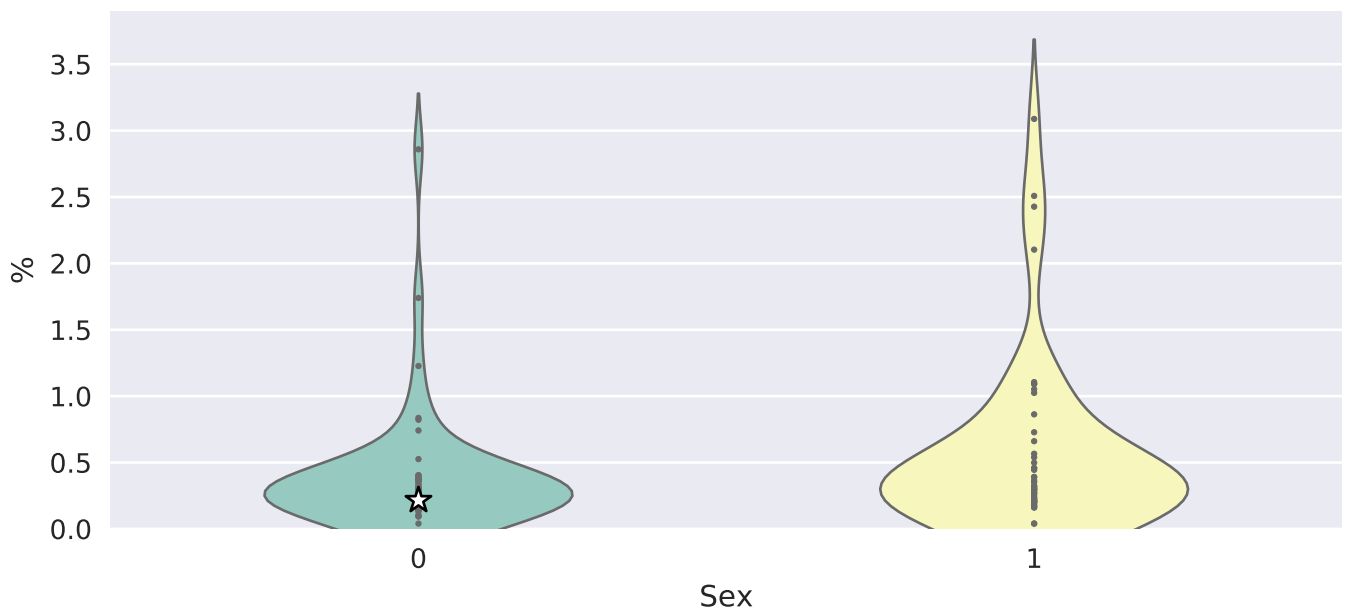
Average absolute motion



Average relative motion

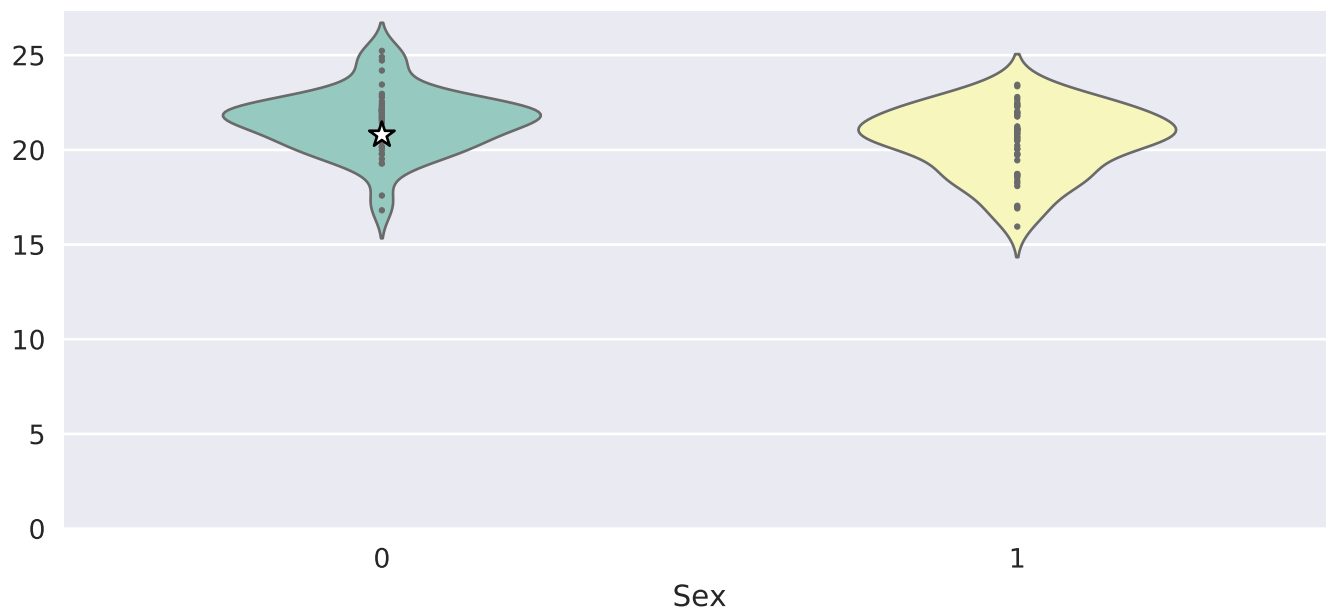


Total outliers

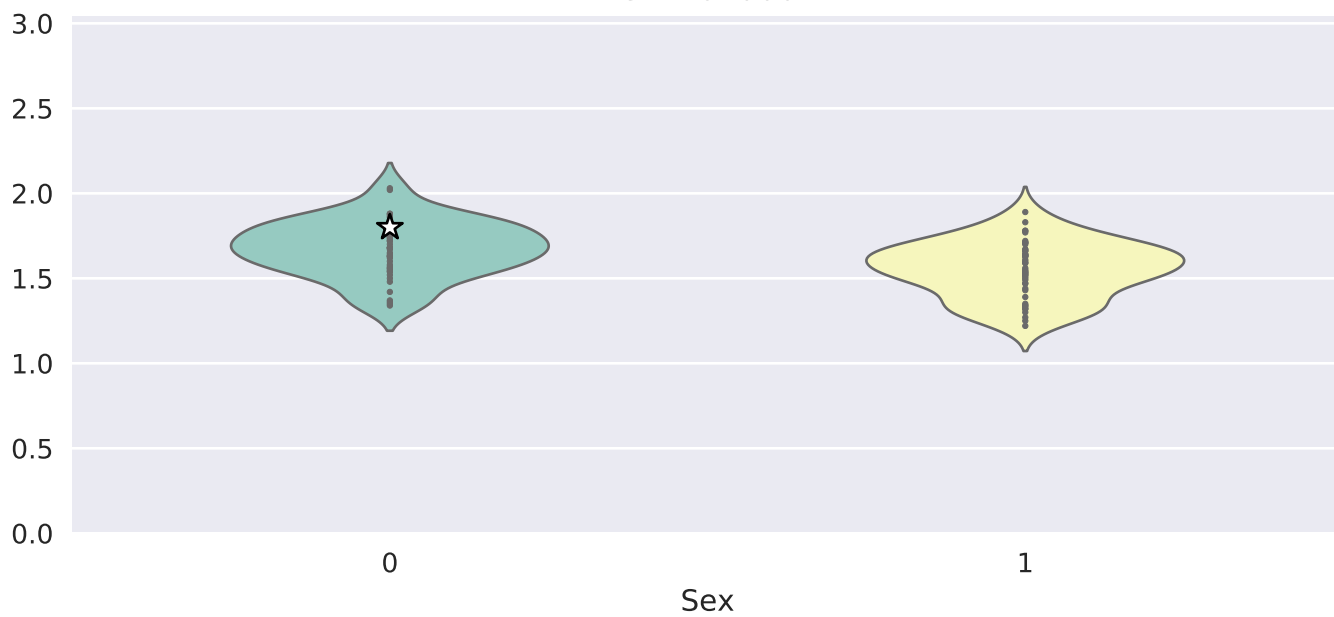


QUAD: Group report

b0 SNR



CNR b1000



CNR b2000

