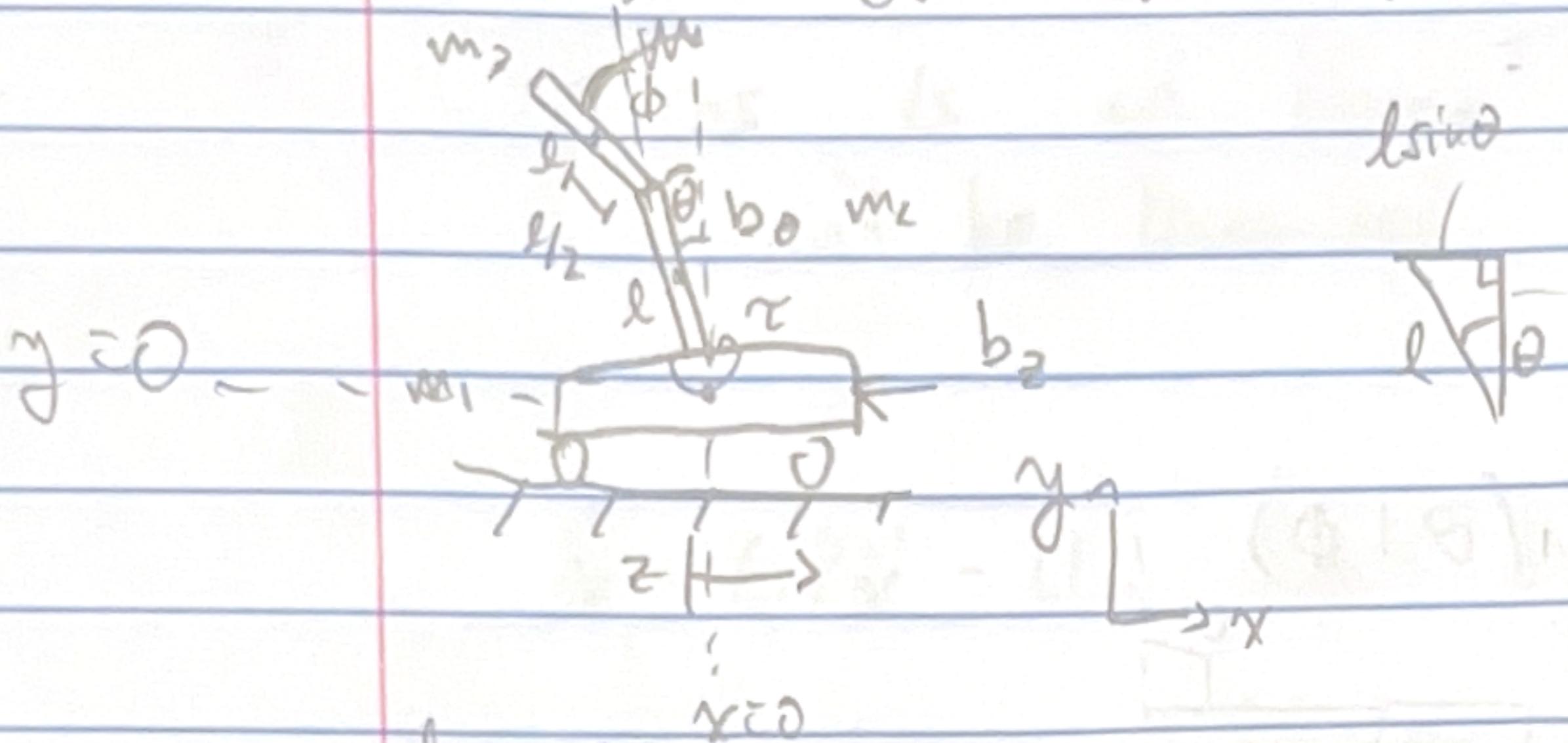


# Midterm

$l \sin \theta$   
 $\frac{l}{2} \sin \theta$



1.  $P_{\text{rel}}$

$$P_{3x} = z - l \sin \theta - l/2 \sin(\phi + \theta)$$

$$P_{3y} = l \cos \theta + l/2 \cos(\phi + \theta)$$

$$P_{2x} = z - l/2 \sin \theta$$

$$P_{2y} = l/2 \cos \theta$$

$$P_{1x} = z$$

$$P_{1y} = 0$$

3.  $K_{r1} = 0$

$\tau_1 = Y_2 \partial J \dot{\theta}$      $K_{r2} = Y_2 \dot{\phi}^T J \dot{\phi}$     only  $\dot{\phi}$  because angle change is relative to  $m_3$  &  $m_2$

4.  $V_e?$

$$m_3 = m_3 g(P_{3y}) = m_3 g(l \cos \theta + l/2 \cos(\phi + \theta))$$

$$m_2 = m_2 g(P_{2y}) = m_2 g(l/2 \cos \theta)$$

$$m_1 = m_1 g(P_{1y}) = 0$$

need cos, not sin

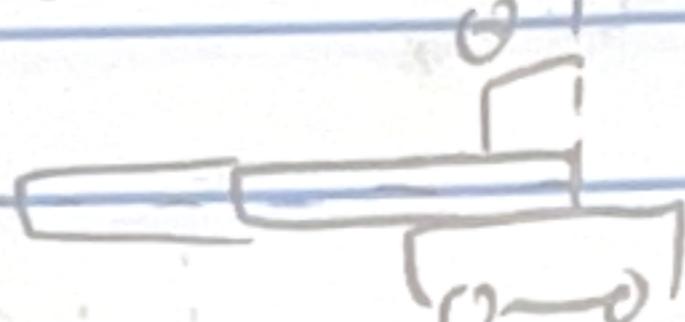
none

5. torque of  $M_3 =$

$$T_{qf}$$

$$T_3 = m_3 \frac{L}{2} \sin(\alpha + \phi)$$

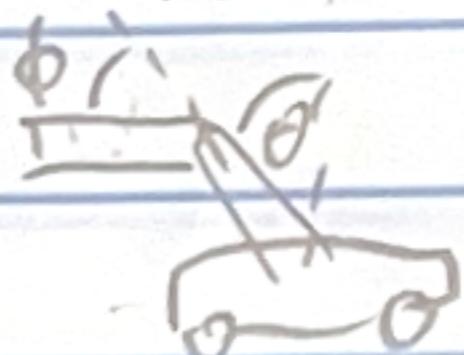
If  $\alpha = 90^\circ$ ,



max  $T_3$  only if  $\phi = 0$

or, if  $\alpha = 45^\circ$

max  $T_3$  iff  $\phi = 45^\circ$



none

6.  $b_2$ , given we have  $b_2 + b_3$

$$-n \begin{bmatrix} b_2 & 0 & 0 \\ 0 & b_3 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} \dot{z} \\ \dot{\theta} \\ \dot{\phi} \end{bmatrix}$$

$$\begin{bmatrix} b_2 \dot{z} \\ b_3 \dot{\theta} \\ 0 \end{bmatrix}$$

drawn as loop

cancel

7.  $\cos$  is not linear,  
can't be linearized

8.

$$\ddot{x} - 6.8\dot{x} - 11x + 3\phi = 4.2F_1 + 3.1F_2 - 5\phi$$

$$\dot{\phi} + 7.1\phi = 1.6\dot{x} - 2.9x - 9.9F_2$$

$$z = [x \ \dot{x} \ \ddot{x} \ \phi]^T \quad u = [F_1 \ F_2]^T \quad y = [6.4\dot{x} \ \phi + F_1]^T$$

(2x4)(4x1)

(2x2)(2x1)

2x1

(x + Du)

$$\begin{bmatrix} 0.64 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ \dot{x} \\ \ddot{x} \\ \phi \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} F_1 \\ F_2 \end{bmatrix}$$

b or d

9.

b or d again?

$$x = [z, \dot{z}, \ddot{z}]^T = [i, z, \dot{z}]^T$$

$$u = \int V(t)$$

$$10. \quad \dot{z} = z$$

$$\ddot{z} = \frac{k}{m} \left( \frac{1}{z} \right)^2 - g$$

$$v = L_i + R_i$$

$$\dot{i} = \frac{v - R_i}{L}$$

$$\begin{bmatrix} \vdots \\ z \\ \vdots \\ \ddot{z} \end{bmatrix} = \begin{bmatrix} \vdots \\ v \\ \vdots \\ \dot{i} \end{bmatrix} \begin{bmatrix} \ddot{z} \\ z \end{bmatrix}$$

$$11. \quad V_{ls}$$

$$V = (G_2 + G_3)E$$

$$V = (G_2 + G_3)(Y_r - G_4 Y)$$

$$0 = (G_2 + G_3)(Y_r - G_4(G_1, V))$$

$$= G_2 Y_r + G_3 Y_r - (G_4 G_3 V - G_4 G_2 V) G_1$$

$$V(1 + G_4 G_3 + G_4 G_2) = Y_r (G_2 + G_3)$$

$$\frac{V}{Y_r} = \frac{G_2 + G_3}{1 + G_4(G_3 + G_2)G_1}$$

13

sys 1

$$\dot{x} = -4x + 1.2\dot{x} + 0$$

$$\ddot{x} = -7(\dot{x}) + .2u$$

=

$$\ddot{x} = m .28x - .84\dot{x} + .2u$$

$$s^2X = .28X - .84sX + .2u$$

$$s^2X + .84sX - .28X = .2u$$

$$X(s^2 + .84s - .28) = .2u$$

$$\frac{X}{u} = \frac{.2}{s^2 + .84s - .28}$$

$$\frac{X}{u} = X \cdot \left( \frac{\Theta}{u} \right)^{-1}$$

sys 2

$$\dot{\theta} = -.5\theta - 1\dot{\theta} + 0$$

$$\ddot{\theta} = .4\dot{\theta} + 1.8\theta + u$$

$$= .4\dot{\theta} - .9\theta - 1.8\theta + u$$

$$\ddot{\theta} = -.5\dot{\theta} - 1.8\theta + u$$

$$s^2\theta = -\dot{\theta} - 1.8s\theta + u$$

$$s^2\theta + 1.8s\theta + .5\dot{\theta} = u$$

$$\frac{\theta}{u} = \frac{1}{s^2 + 1.8s + .5}$$

$$\frac{.2}{s^2 + .84s - .28}$$

inspire time!

$$\frac{1}{s^2 + 1.8s + .5}$$

14.

$$OL =$$

$$Y = P \bar{U} \\ = P(k_p E) - k_d s Y$$

$$Y = P(k_p(Y_r - Y) - k_d s Y)$$

$$Y = Pk_p Y_r - (Pk_p + Pk_d s) Y$$

$$Y - Pk_p Y + Pk_d s Y = Pk_p Y_r$$

$$Y_r = \frac{P k_p}{1 - P k_p / P k_d s}$$

$$Y_r = \frac{P k_p}{1 - P k_p / P k_d s}$$

$$P(s) = \frac{87s - 3.3}{s^2 - 7.6s + 13.95}$$

$$s = \frac{7.6 \pm \sqrt{7.6^2 - 4(1)(13.95)}}{2 \cdot 6.95 - 5P - 3A}$$

$$\therefore \frac{7.6 \pm 1.4}{2} = \boxed{4.5, 3.1}$$

15.

$$Y = MPV$$

$$= P(k_p E - k_d \varsigma Y)$$

$$= P(k_p(Y_r - Y) - k_d \varsigma Y)$$

$$= Pk_p Y_r - Pk_p Y - k_d \varsigma Y$$

$$Y + Pk_p Y + Ak_d \varsigma Y = Pk_p Y_r$$

$$Y(1 + Pk_p + k_d \varsigma) = Y_r(Pk_p)$$

$$\frac{Y}{Y_r} = \frac{Pk_p}{1 + Pk_p + k_d \varsigma}$$

16.

$$t_r = 1.5$$

$$\varsigma = .6$$

$$w_d = 2.2 \sqrt{1.6^2 - 1}$$

$$1.76?$$

$$\frac{k_p}{k_d} =$$

assuming  $k=1$

$$\omega_m = 2\pi f$$

$$= 2\pi \left(\frac{1}{5}\right)$$

$$\approx 4\pi?$$

$$1.76$$

$$\frac{1}{s^2 + 2\zeta\omega_n s + \omega_n^2}$$

w.

$$1.2\omega_n$$

$$\omega_n^2$$

17.

7.1

$$s^2 + -8.5s + 16.24$$

$$\alpha_0 = -8.5$$

$$\alpha_1 = 16.24$$

$$k_p = \frac{\alpha_0 - a_0}{b_0}$$

$$7.1 k_p$$

$$(7.1 k_p) = 27.1 b_0$$

$$\alpha_1 = a_1 + b_0 k_d$$

$$b_0 = 7.1$$

$$k_d = \frac{\alpha_1 - a_1}{b_0}$$

$$\alpha_1 = 10.8$$

$$\alpha_0 = 27.1 k_p + q_0$$

$$\alpha_0 = 27.47$$

$$q_1 = 1.2$$

$$q_2 = 2$$

$$k_p = \frac{\alpha_0 - a_0}{b_0}$$

$$7.1 = b_0 k_p$$

18.

$P_{kp}$

$$(\downarrow P_{kp} + k_d \downarrow)$$

3,763

$$(2,46s+1)(s^2+8,5s+16,24)+3,763$$

$\lim_{s \rightarrow 0}$

$$(0+1)(0-0+16,24)$$

$$16,24 + 3,763$$

3,763

$$= 16,24 + 3,763$$