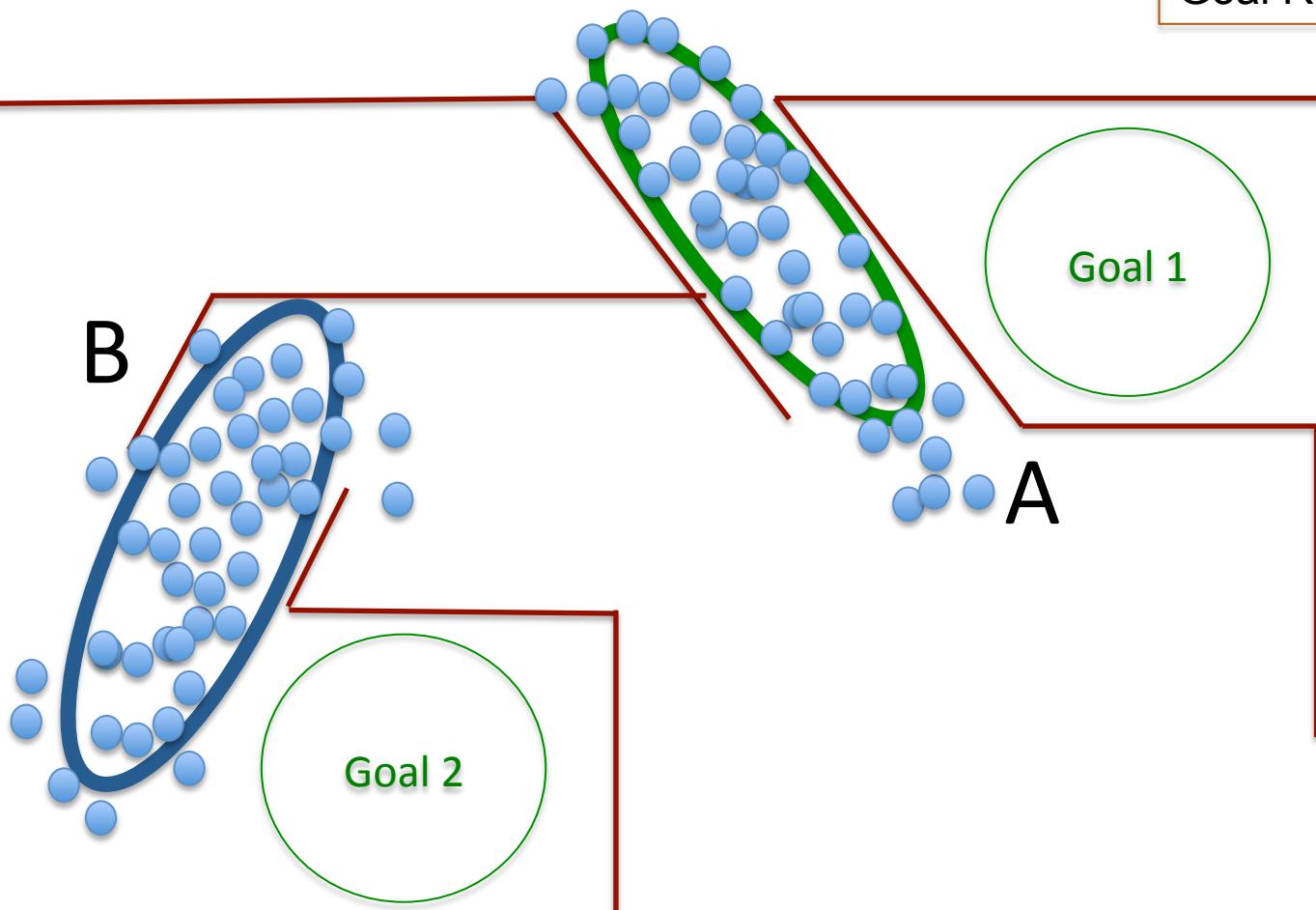
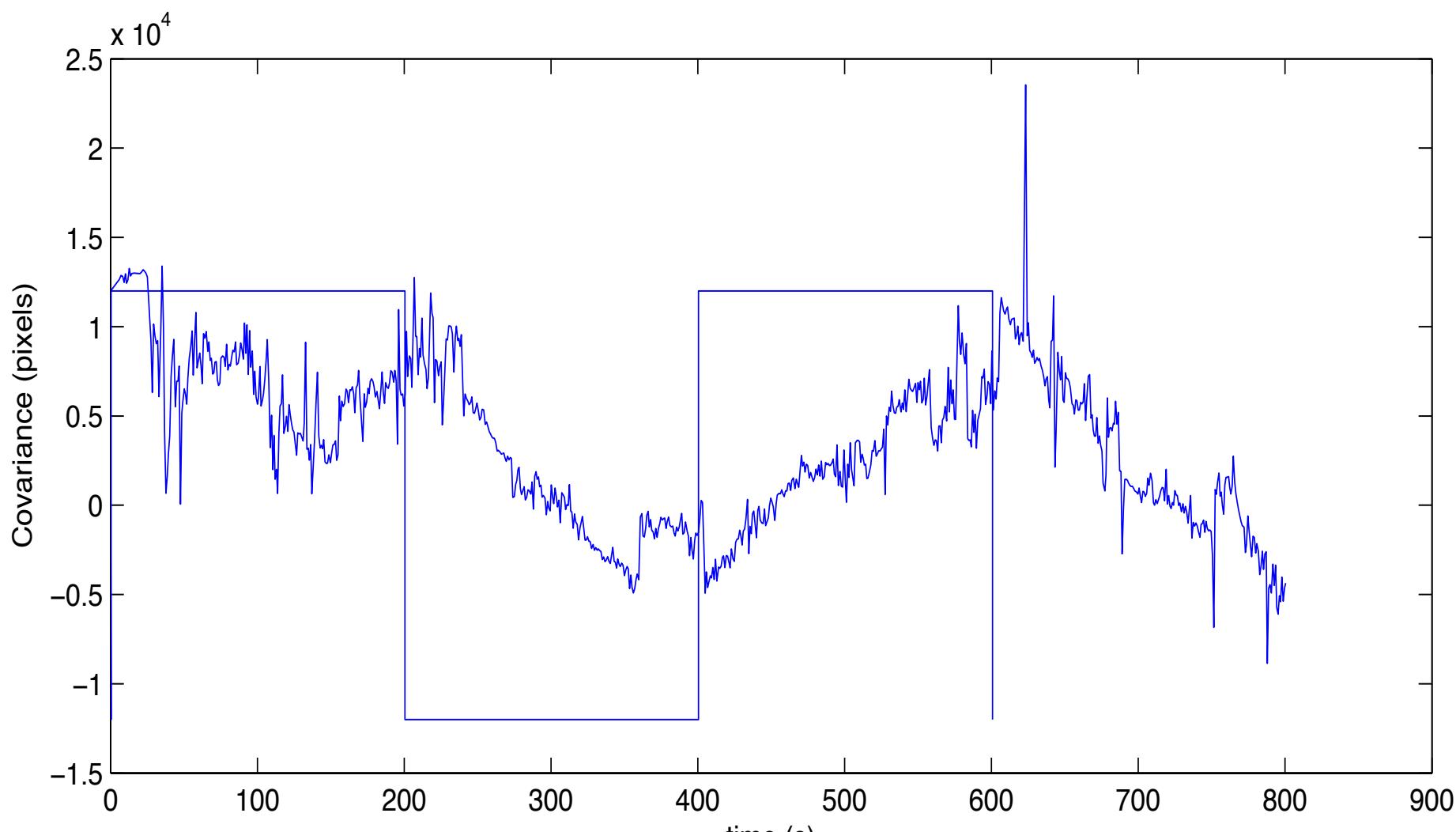


Robots	
Mean Position	
Covariance	
Desired Cov A	
Desired Cov B	
Goal Regions	







Robot
Bottom Path
Top Path
Goal Positions

