System Step Response Using Convolution

Lab 4

Spring 2021

1 Purpose

Become familiar with using convolution to compute a system's step response.

2 Deliverables Overview

2.1 Part 1

• Plots from Task 2.

2.2 Part 2

- Plots for **Task 1**.
- Hand calculated convolution integrals from Task 2.
- Plots from Task 2.

As usual, plots and equations need to be thoroughly discussed in your report.

3 Part 1

3.1 Purpose

Use the step function you coded previously to write transfer functions to use in this lab.

3.2 Deliverables

1. Plots from **Task 1** in a single figure, to be included in the **Results** section of your report.

3.3 Tasks

1. Create the following signals as user-defined functions:

$$h_1(t) = e^{-2t}[u(t) - u(t-3)]$$

$$h_2(t) = u(t-2) - u(t-6)$$

$$h_3(t) = cos(\omega_0 t)u(t)$$

for,
$$f_0 = 0.25$$
 Hz.

2. Plot the three functions in a single figure (separate subplots) from $-10 \le t \le 10$ with time steps small enough to achieve appropriate resolution.

4 Part 2

4.1 Purpose

Find and plot the step response of the three transfer functions defined in **Part 1** using Python and hand calculations.

4.2 Deliverables

- 1. Plots from Task 1 to be included in the Results section of your report.
- 2. Typed equations and solutions from hand calculations in **Task 2** to be included in the **Equations** and **Results** sections of your reports, respectively.
- 3. Plots from **Task 2** to be included in the **Results** section of your report. *Note: These plots should match the plots from Part 1*.

4.3 Tasks

Perform the following tasks for each of the three transfer functions defined in **Part 1**. Plot each response from $-10 \le t \le 10$ with an appropriate time step.

- 1. Plot the step response using the convolution function you created in Lab 3.
- 2. By hand, calculate the step response of each transfer function by solving the convolution integral. Plot the results and ensure they match the plots from **Task 1**.

5 Questions

1. Leave any feedback on the clarity of lab tasks, expectations, and deliverables.

$$h_{1} * v(t) = \int_{0}^{t} e^{-2^{t}} (v(t-t) - v(t-3-t)) dt$$

$$\int_{0}^{t} e^{-2^{t}} dt = \frac{1}{2} [e^{-2t} - 1]$$

$$= \sum_{0}^{t} h_{1} * v(t)$$

$$= \frac{1}{2} [e^{-2(t-3)} - 1] v(t-3) - \frac{1}{2} [e^{-2^{t}} - 1] w_{0}$$

$$h_{2} * v(t) = \int_{-\infty}^{\infty} [v(t-2) - v(t-6)] \cdot v(t-t) dt$$

$$= \int_{2}^{t} v(t-2) dt - \int_{0}^{t} v(t-6) dt$$

$$h_{2} * v(t) = \int_{0}^{\infty} cos(w_{0}t) \cdot v(t) \cdot v(t-6)$$

$$h_{3} * v(t) = \int_{0}^{\infty} cos(w_{0}t) \cdot v(t) \cdot v(t-t) dt$$

$$= \int_{0}^{t} cos(w_{0}t) dt = \int_{0}^{\infty} cos(w_{0}t) \cdot v(t-t) dt$$

$$h_3 * U(t) = \int_{-\infty}^{\infty} \cos(\omega_0 t) \cdot U(t) \cdot U(t-t) dt$$

$$= \int_{0}^{t} \cos(\omega_0 t) dt = \int_{\omega_0}^{t} \sin(\omega_0 t) \cdot U(t) dt$$