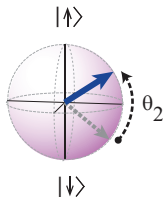
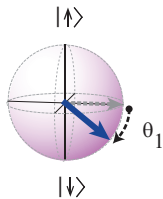
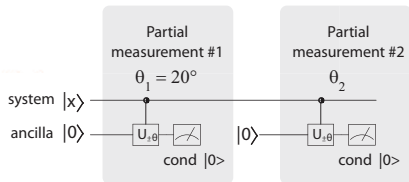
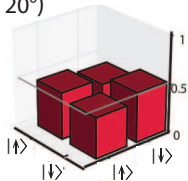


# heralded sequential measurements



## uncollapse

$$(\theta_2 = \theta_1 = 20^\circ)$$



## steering

$$(\theta_2 = 39^\circ)$$

