Machine Listening for Music and Sound Analysis

Lecture 2 – Machine Learning/Deep Learning

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https://www.machinelistening.de



Learning Objectives

- Introduction
- Learning paradigms
- Machine learning (ML) project pipeline
- Deep learning



Introduction

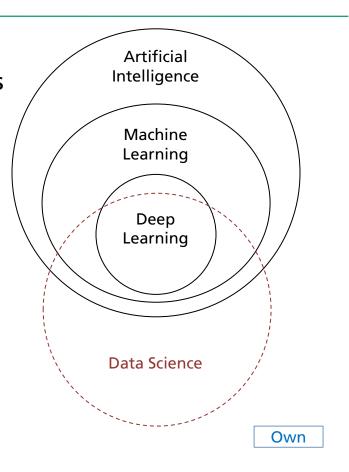
Goals

- "...give computers the ability to learn without being explicitly programmed" [Samuels, 1959]
- Learning structures in given (un)labeled data to make predictions on new / unseen data
- Paradigm change
 - Before: manually designed / general-purpose features
 - Now: joint representation learning (features) & data modeling (classification)
- Related disciplines
 - Statistics, data science, optimization



Introduction Terminology

- Artificial Intelligence (AI)
 - "an agent's ability to achieve goals in a wide range of environments" [Legg & Hutter, 2007]
- Machine Learning (ML)
 - Pattern recognition, data modeling, learning, prediction
- Deep Learning (DL)
 - (Brain-inspired) artificial neural networks (ANN)
- Data Science
 - Knowledge extraction from data





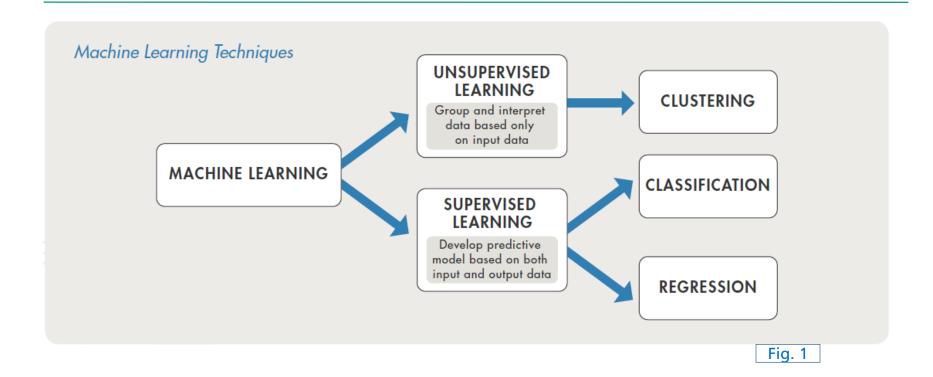
Introduction

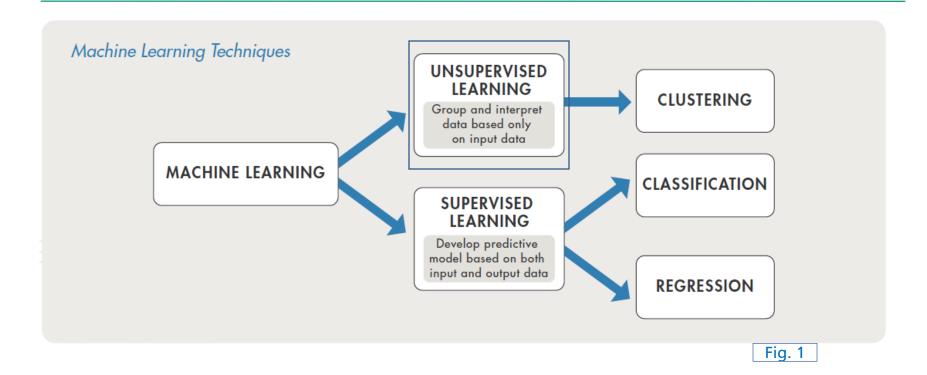
Application Scenarios

- Computational finance (credit scoring, algorithmic trading)
- Computer vision (face & object recognition, motion detection)
- Computational biology (tumor detection, drug discovery, DNA sequencing)
- Energy (price & load forecasting)
- Predictive maintenance (automotive, aerospace, manufacturing)
- Natural language processing (sentiment classification, text search, translation)
- Machine listening (music transcription, instrument recognition, sound event detection, acoustic scene classification)



Learning Paradigms

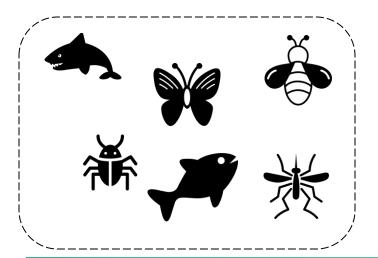




- Goal
- Find hidden **structure** and **patterns** in data
- No annotations available

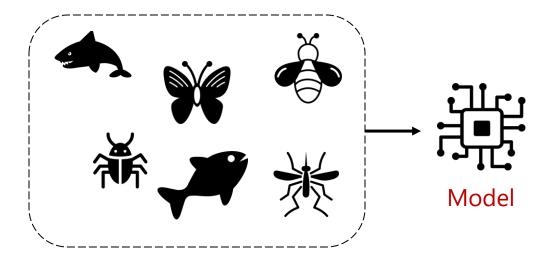


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- Clustering
 - **Grouping** of **similar** data instances



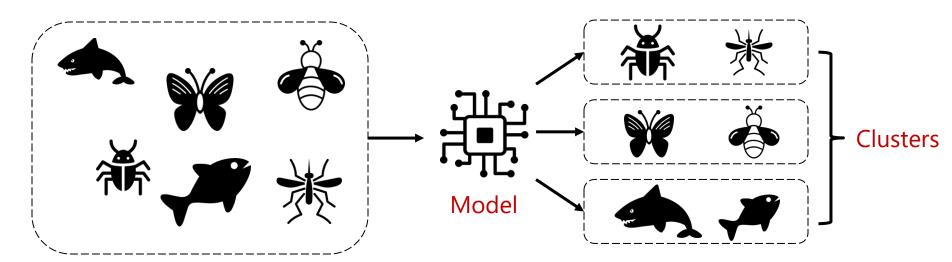


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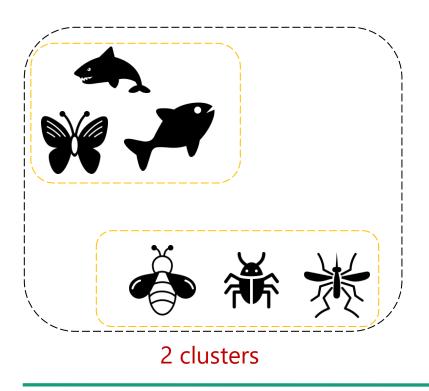


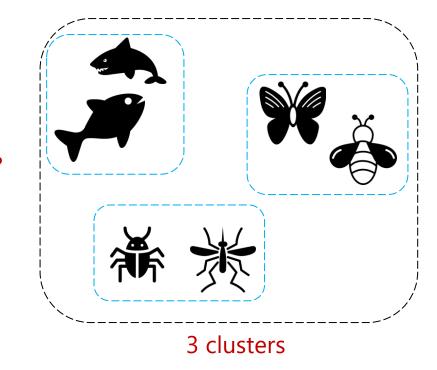
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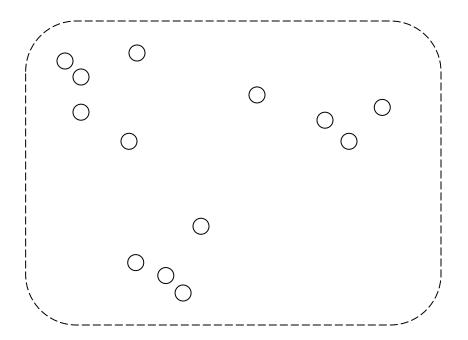
- Challenges
 - What is the **optimal number of clusters**?



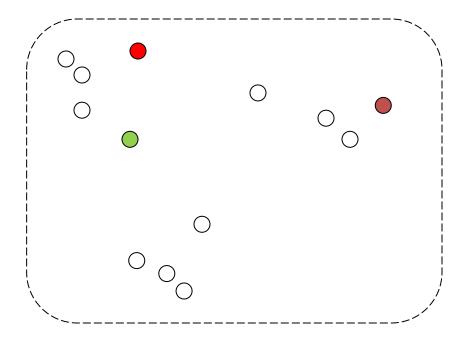




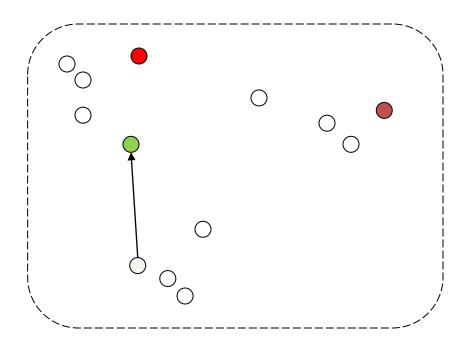
- K-means clustering
 - Initialize *K* "means" randomly (=cluster centroids)



- K-means clustering
 - K = 3

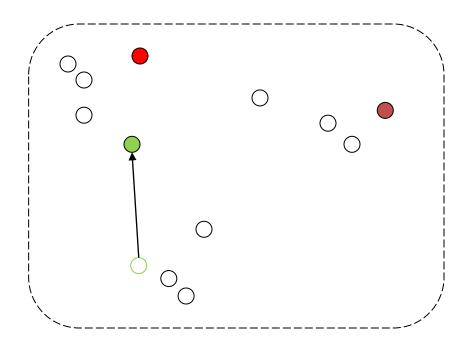


- K-means clustering
 - Assignment: assign each data point to its closest mean



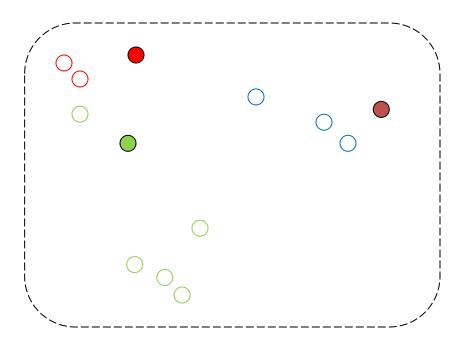


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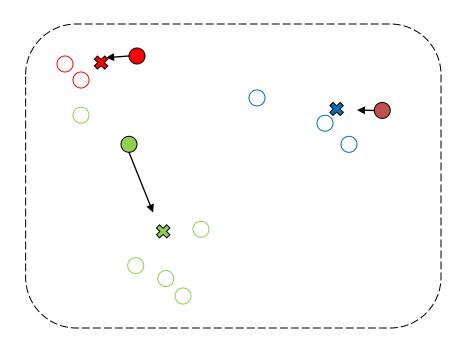


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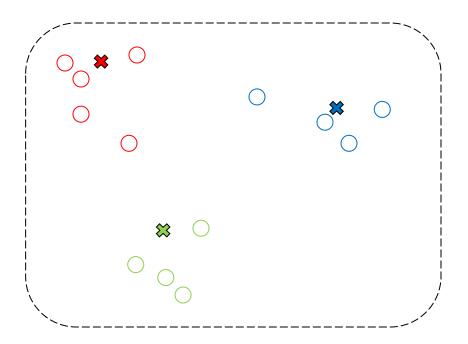


- K-means clustering
 - Update: update mean by average over all assigned data points

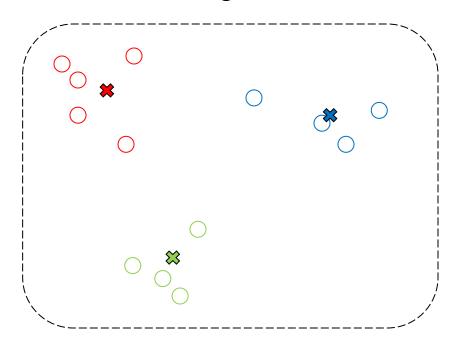


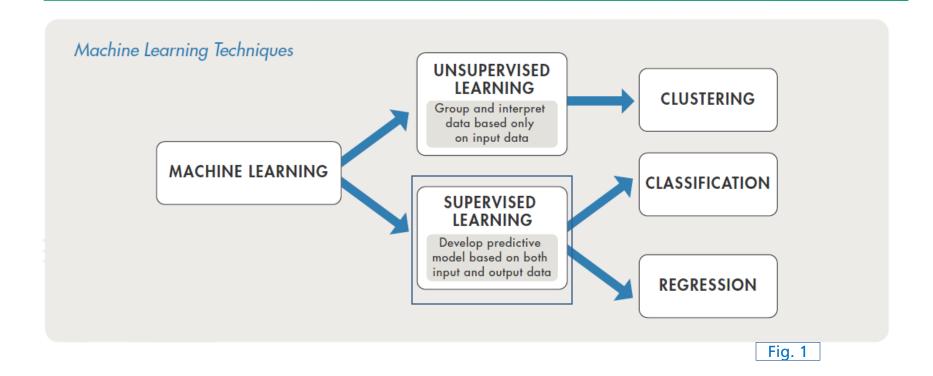


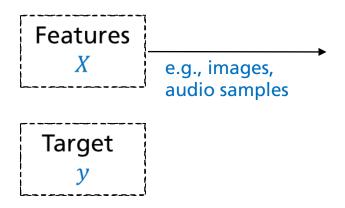
- K-means clustering
 - Assignment: re-assign data points to closest mean



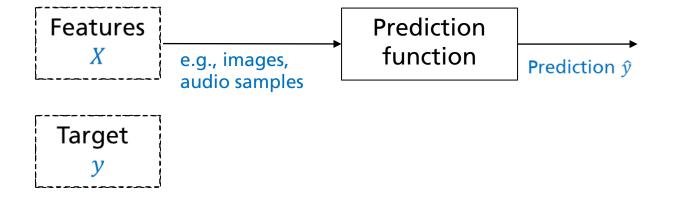
- K-means clustering
 - Update: re-assign data points to closest mean (repeat until convergence)



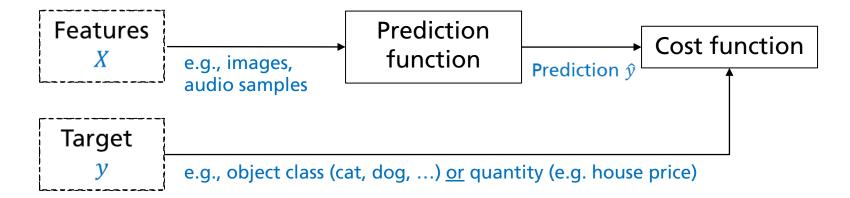




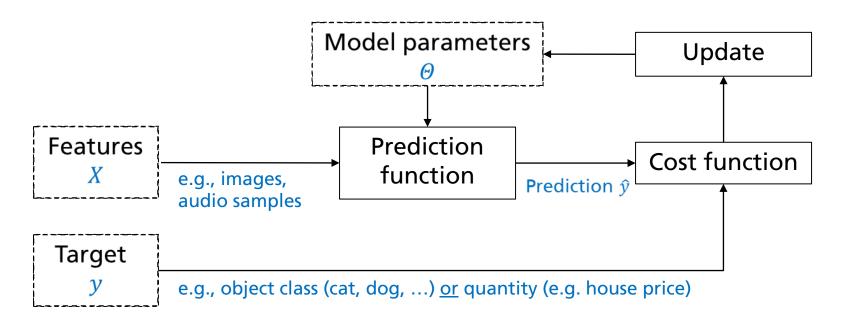








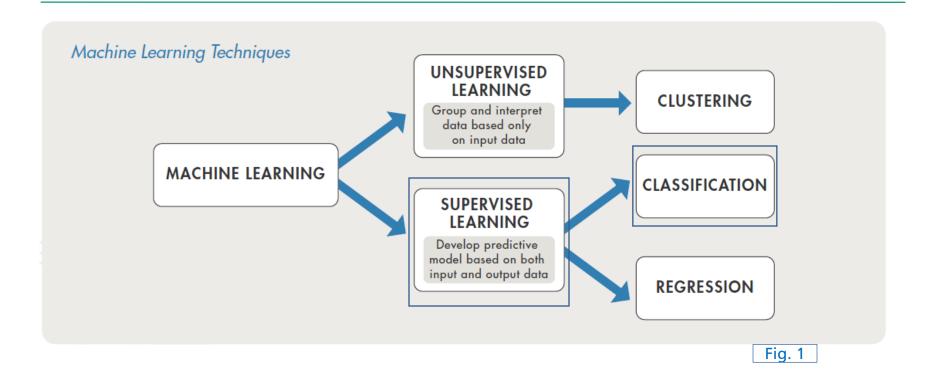






Learning Paradigms

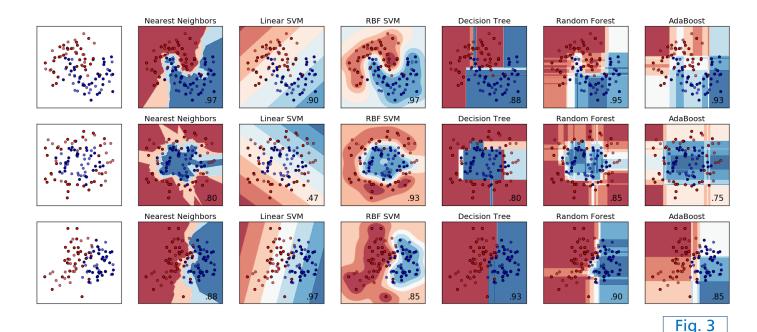
Supervised Learning - Classification



- Predict one or multiple categorical labels from features
 - Examples → music genre, instrument(s), key



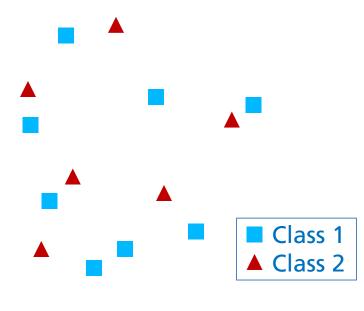
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 - Examples → music genre, instrument(s), key
- Feature space modeling (Example: 2 classes)



- Example: k-Nearest Neighbors
 - Training → Store all examples



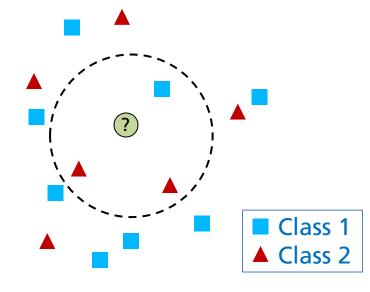
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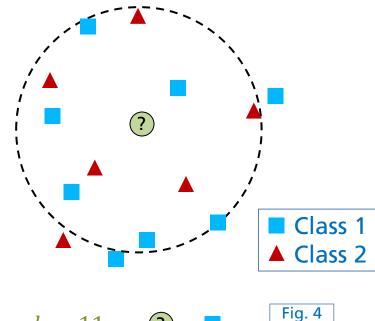


$$k = 3 \rightarrow ? = \blacktriangle$$





- Example: k-Nearest Neighbors
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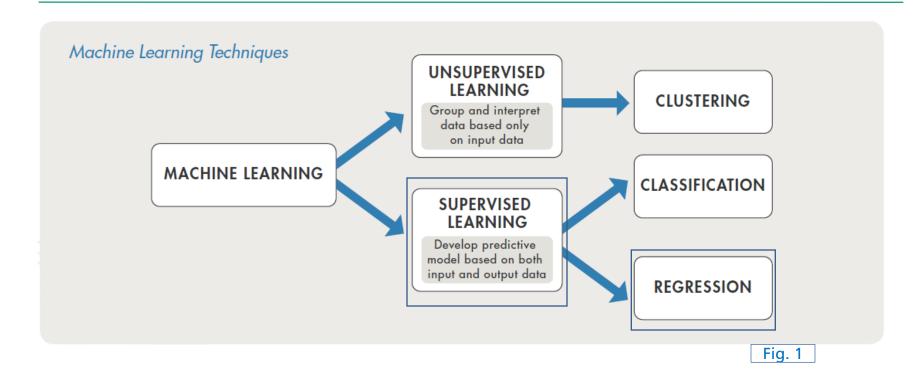
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- Example: k-Nearest Neighbors
 - Training → Store all examples
 - Test → Assign test item to dominant class label of the k clostest training data items
- Distance measures
 - Euclidean distance, Manhatten distance, cosine distance, ...





Learning Paradigms Supervised Learning - Regression

- Goal
- Predict a dependent (response) variable given one or multiple independent variables (features)
- Continuous quantities
- Examples
 - Univariate (linear) regression:
 - - $\blacksquare \beta_0 \rightarrow \text{bias}$
 - $\blacksquare \beta_1 \rightarrow \text{weight}$

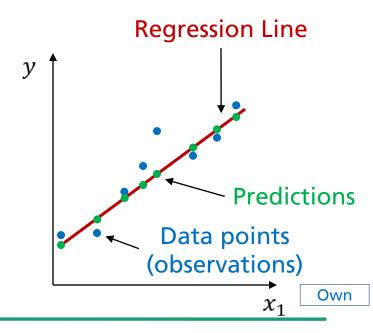


Learning Paradigms

Supervised Learning - Regression

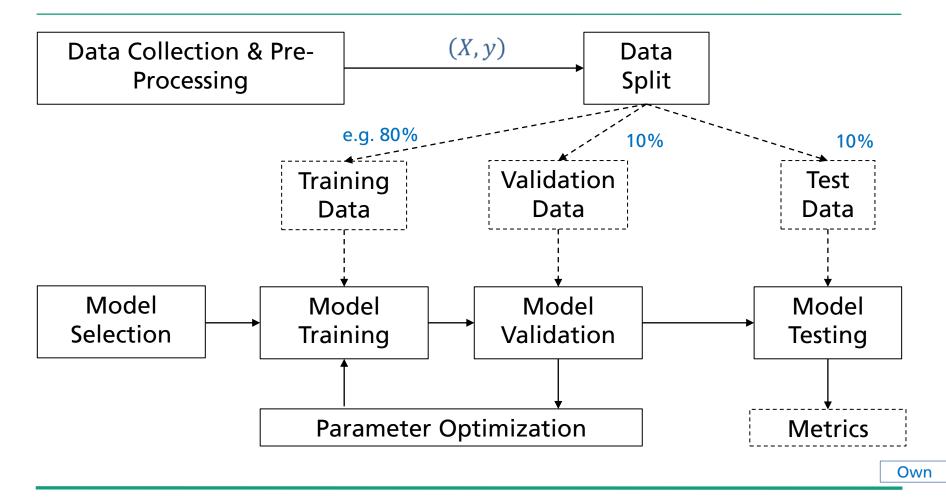
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ML Project Pipeline



- Training Set
 - Model learns from this data



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- Validation / Development Set
 - Used to fine-tune the model (hyper)parameters
 - Model occasionally sees but does not learn from this data



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 - Only used once after the model training & tuning is completed
 - Should reflect the targeted real-world use case for the model
- Common split ratios
 - 80/10/10% or even 98/1/1% (for large datasets)



ML Project Pipeline Data Collection & Pre-Processing

- Data collection
 - Check for available data resources for given (or related) task
 - Collect / record / annotate new data
 - Ensure data variability
 - Example (from acoustic condition monitoring) → include different motor engine types & conditions, recording locations, microphones, ...



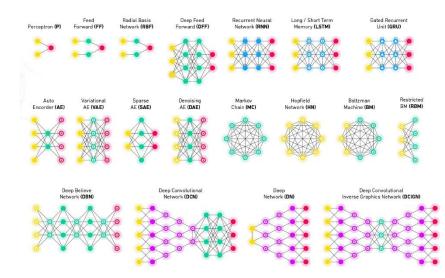
ML Project Pipeline Data Collection & Pre-Processing

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 - Example (from acoustic condition monitoring) → include different motor engine types & conditions, recording locations, microphones, ...
- Data cleanup / pre-processing
 - Remove errors, silence, empty files, ...
 - Balance dataset (proportions among class examples)
 - Normalize (depends on the model)



ML Project Pipeline Model Selection

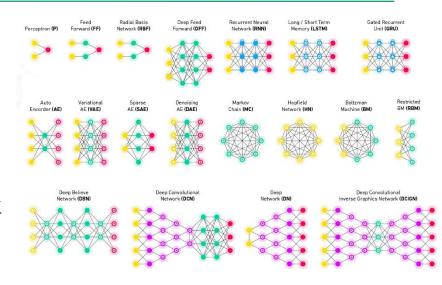
- Many models and approaches exist
 - Types (SVM, GMM, logistic regression, DNNs)
 - Hyperparameters (SVM kernel functions, DNN layer types)





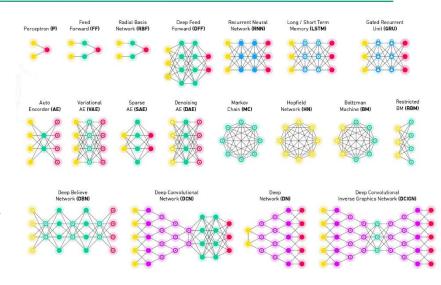
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ML Project Pipeline Model Selection

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 - Hyperparameters (SVM kernel functions, DNN layer types)
- Often constrained by the use-case / task
 - Model complexity (memory, training time, training data amount)
- Feature pre-processing depends on model type
- Use simple models for simple tasks





- Iterative process
 - Typically: start with random parameter initialization



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 - Use (batches of) training data to iteratively improve model predictions (optimization)
 - Learn from examples



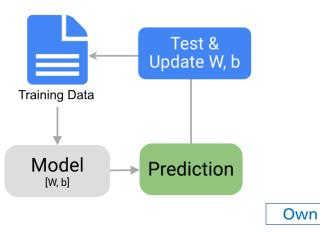
- Iterative process
 - Typically: start with random parameter initialization
 - Use (batches of) training data to iteratively improve model predictions (optimization)
 - Learn from examples
 - Update model parameters according to loss function



Example: linear regression

$$y \approx \beta_0 + \beta_1 x_1$$

Training loop





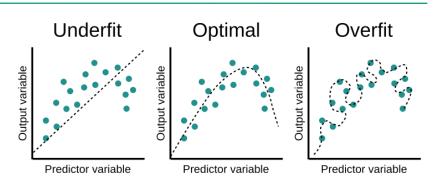
ML Project Pipeline Model Validation

 Regular model evaluation each or multiple training iteration



ML Project Pipeline Model Validation

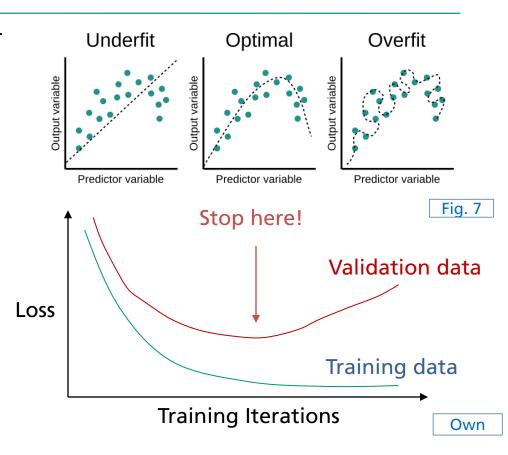
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ML Project Pipeline Model Validation

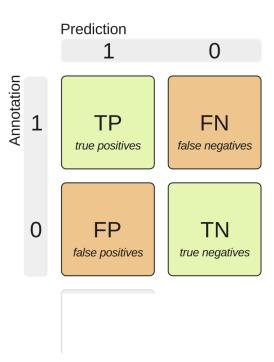
- Regular model evaluation each or multiple training iteration
- Helps to
 - optimize model (hyper)parameters
 - detect overfitting on training data
 - stop the training





ML Project Pipeline Model Testing

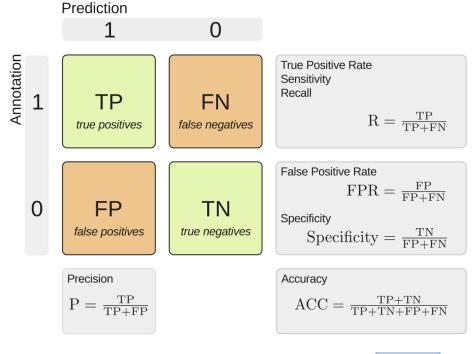
- Example: Binary classification evaluation
 - True/false positives (TP/FP)
 - True/false negatives (TN/FN)





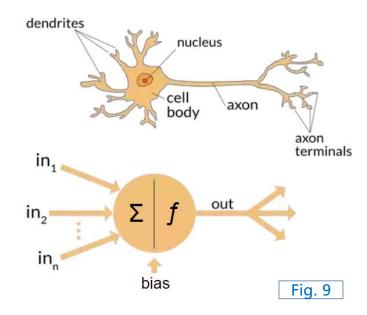
ML Project Pipeline Model Testing

- Example: Binary classification evaluation
 - True/false positives (TP/FP)
 - True/false negatives (TN/FN)
 - Metrics
 - Precision
 - Recall
 - Accuracy
 - F-score





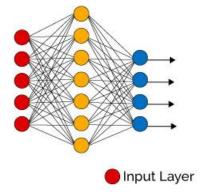
- Artificial neural networks → mimic brain processing
 - Connected neurons
 - Weighted input summation
 - Non-linear processing



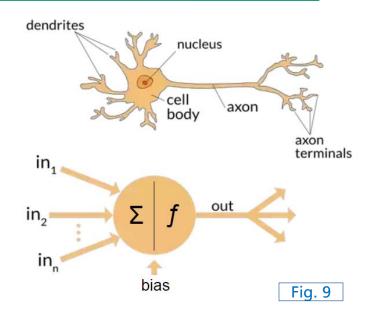


- Artificial neural networks → mimic brain processing
 - Connected neurons
 - Weighted input summation
 - Non-linear processing
- Shallow networks

Simple Neural Network

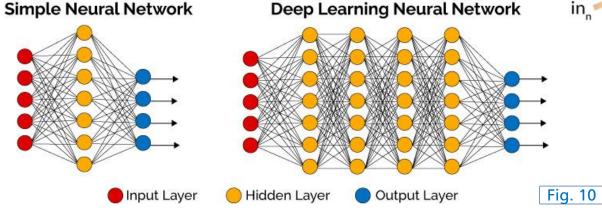


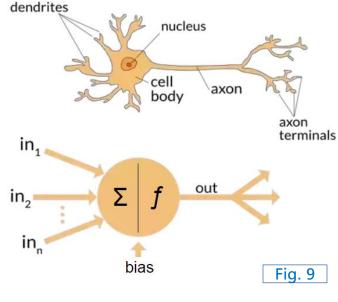






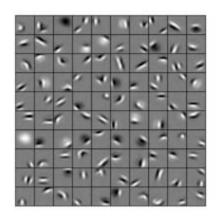
- Artificial neural networks → mimic brain processing
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- Shallow networks → deep networks







- Hierarchical feature learning
 - Example (face recognition)



Edges, curves

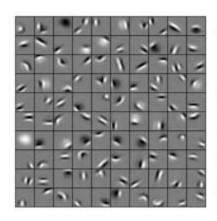
Fig. 11

First layers

Final layers



- Hierarchical feature learning
 - Example (face recognition)



Edges, curves

Shapes, object parts

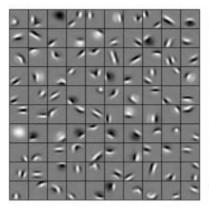
Fig. 11

First layers

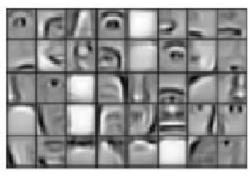
Final layers



- Hierarchical feature learning
 - Example (face recognition)



Edges, curves



Shapes, object parts



Objects (faces)

Fig. 11

First layers

Final layers



Input layer





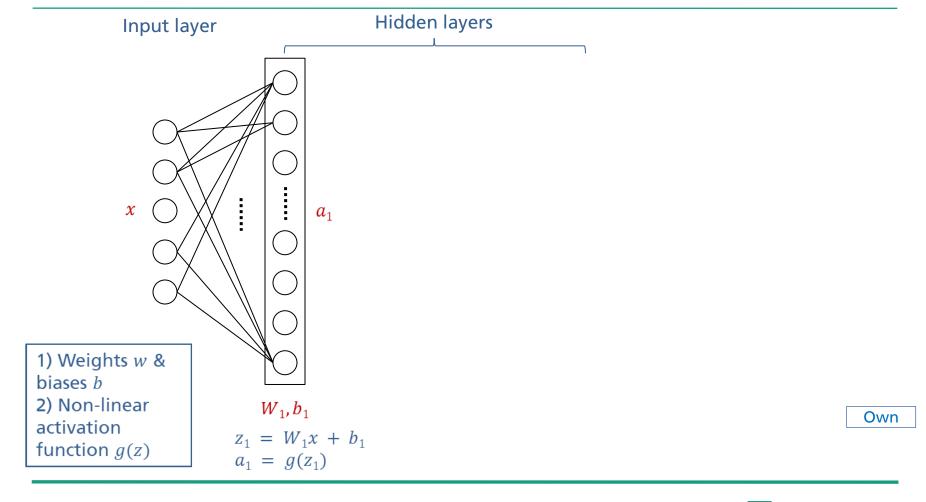
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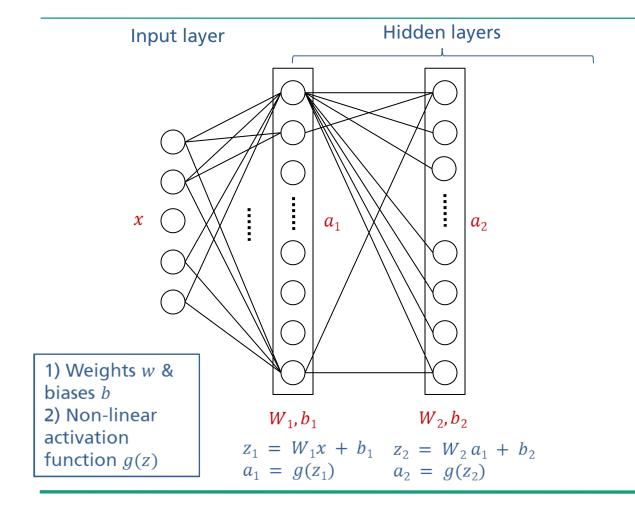


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Own

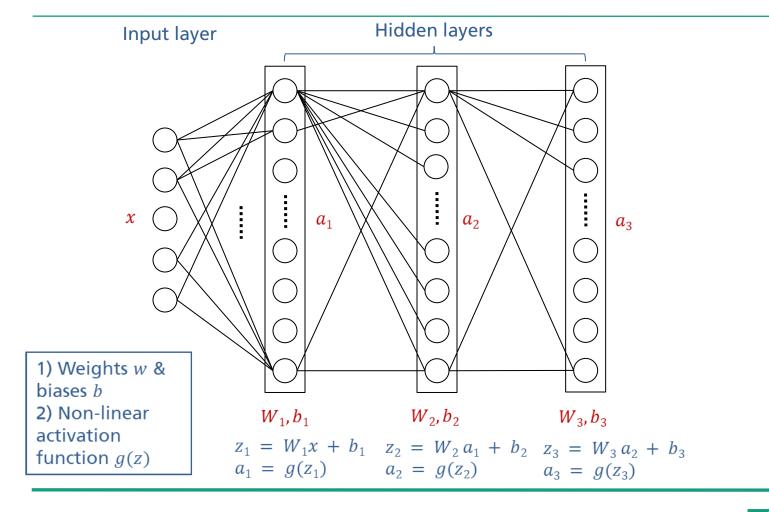






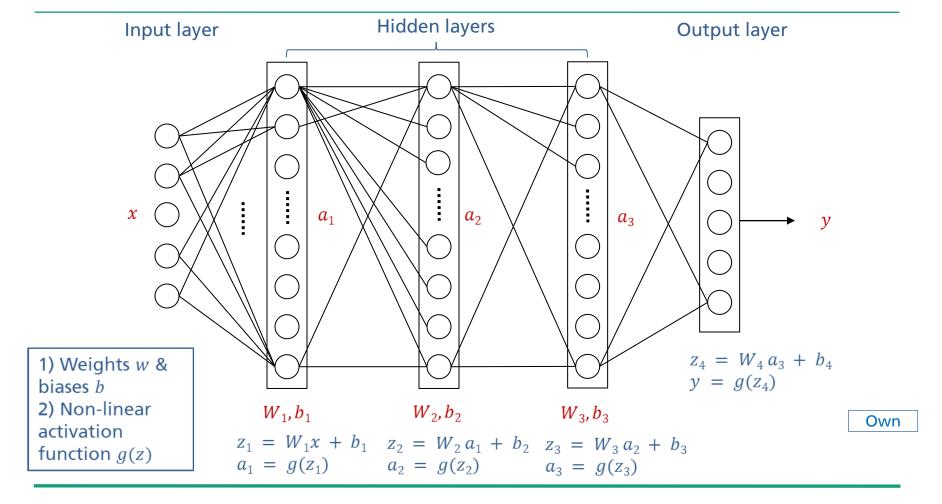
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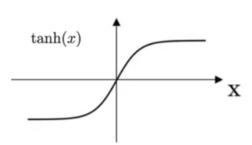




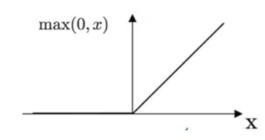
Deep Learning Activation Functions

- Activation functions add non-linearity
- Make networks more powerful in (complex) pattern recognition
- Examples:

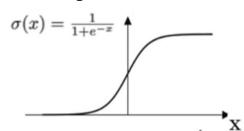
Hyper Tangent Function



ReLU Function



Sigmoid Function



Overview

Features v

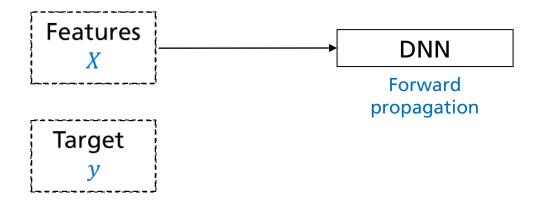
X

Target

y

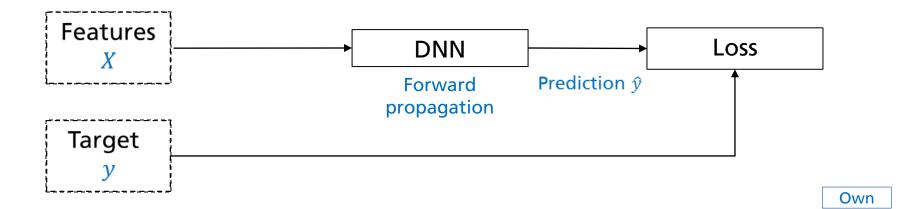
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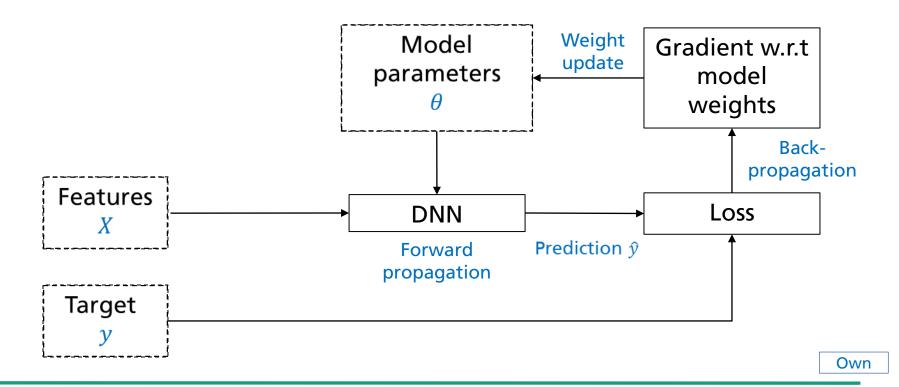






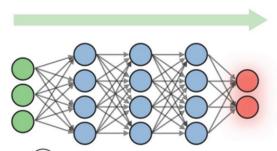








Forward propagation → propagate batch of training data through the network → compute loss (compare to targets)

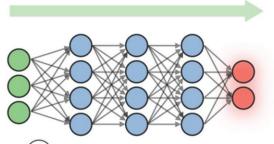


1) Forward propagation

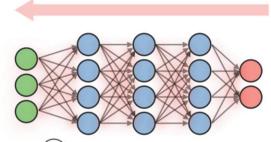
$$L(z,y) = - \Big[y \log(z) + (1-y) \log(1-z) \Big]$$



- Forward propagation → propagate batch of training data through the network → compute loss (compare to targets)
- Backpropagation → backpropagate loss → compute gradients of loss w.r.t. weights



(1) Forward propagation



(2) Backpropagation

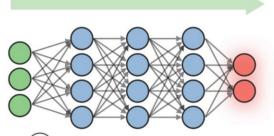
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$$rac{\partial L(z,y)}{\partial w}$$

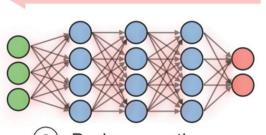
Fig. 20



- Forward propagation → propagate batch of training data through the network → compute loss (compare to targets)
- Backpropagation → backpropagate loss → compute gradients of loss w.r.t. weights
- Weights update → use gradients & learning rate to update weights



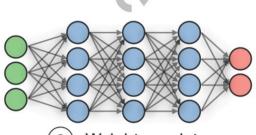
1 Forward propagation



(2) Backpropagation

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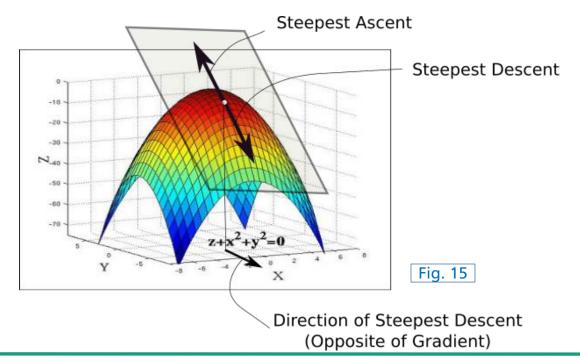
(3) Weights update

$$w \longleftarrow w - lpha rac{\partial L(z,y)}{\partial w}$$

Fig. 20

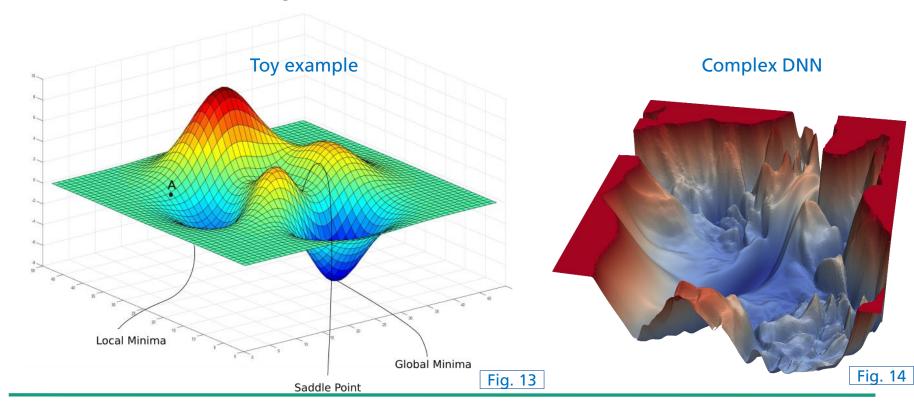


- Gradient descent
 - Move in opposite direction of gradient
 - Learning rate effects step size





- Loss contour
 - Goal → find global minima





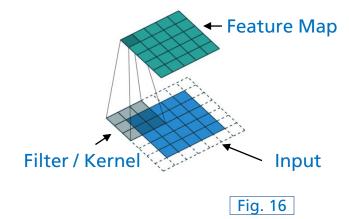
Deep Learning Playground

- A neural network playground!
 - https://playground.tensorflow.org



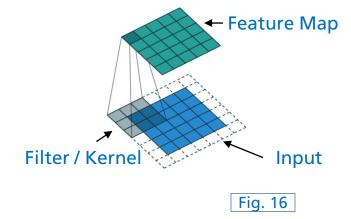
Deep Learning Convolutional Neural Networks (CNN)

- Convolutional layers
 - "Convolution" → (local) dot-product between filter and input



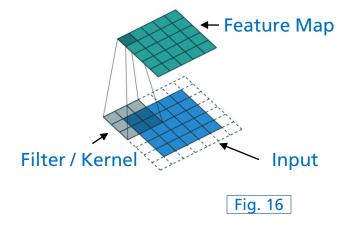
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 - Shared weights (across input)



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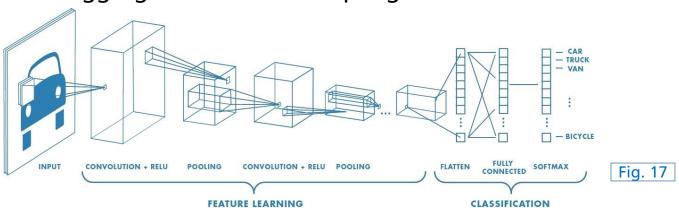
- Convolutional layers
 - "Convolution" → (local) dot-product between filter and input
 - Shared weights (across input)
 - translation of input → translation of activations (equivariance)

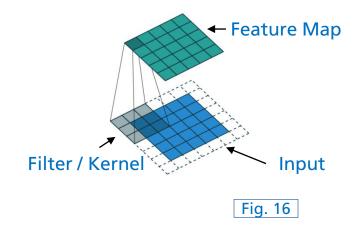


Deep Learning Convolutional Neural No.

Convolutional Neural Networks (CNN)

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 - "Convolution" → (local) dot-product between filter and input
 - Shared weights (across input)
 - translation of input → translation of activations (equivariance)
- lacksquare Pooling ightarrow local aggregation / down-sampling







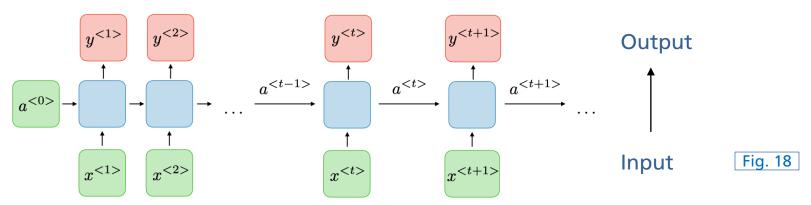
Deep Learning Recurrent Neural Networks (RNN)

- Recurrent layers
 - Model sequential data → model dynamic temporal behaviour
 - Internal memory state(s) → memorize previous data for future predictions



Recurrent Neural Networks (RNN)

- Recurrent layers
 - Model sequential data → model dynamic temporal behaviour
 - Internal memory state(s) → memorize previous data for future predictions
- Vanishing gradient problem
 - Gating mechanisms (Gated Recurrent Units (GRU), Long Short-term Memory (LSTM)





Recurrent Neural Networks (RNN)

- Application Examples
 - One-to-many: sequential music generation (given a starting note)

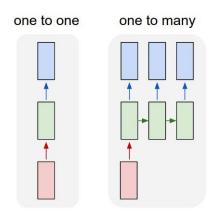


Fig. 19



Recurrent Neural Networks (RNN)

- Application Examples
 - One-to-many: sequential music generation (given a starting note)
 - Many-to-one: sentiment classification (positive vs. negative)

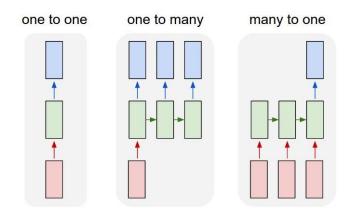
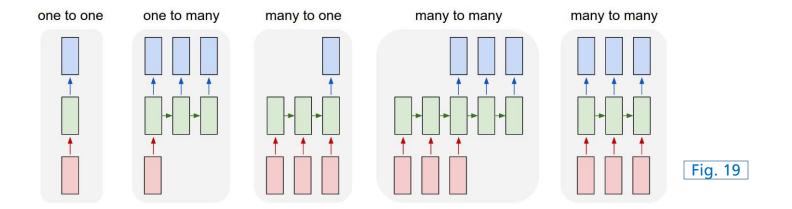


Fig. 19



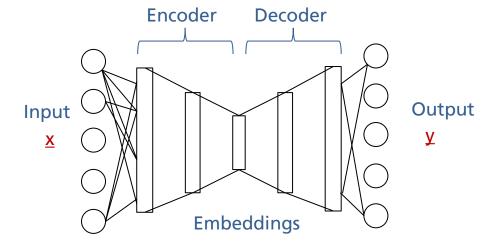
Recurrent Neural Networks (RNN)

- Application Examples
 - One-to-many: sequential music generation (given a starting note)
 - Many-to-one: sentiment classification (positive vs. negative)
 - Many-to-many: machine translation (e.g., Spanish to German)



Deep Learning Autoencoders

Symmetric architecture (decoder & encoder)

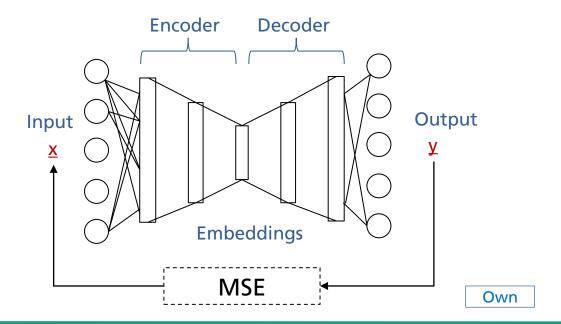


Own



Deep Learning Autoencoders

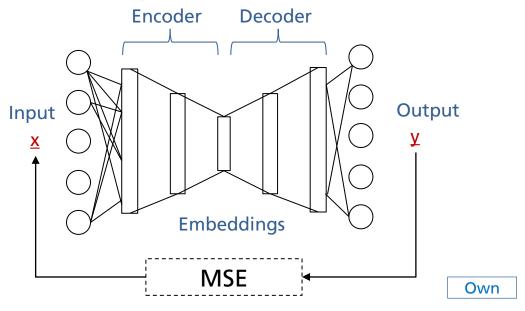
- Symmetric architecture (decoder & encoder)
- Objective: minimize reconstruction error (e.g., mean squared error, MSE)





Deep Learning Autoencoders

- Symmetric architecture (decoder & encoder)
- Objective: minimize reconstruction error (e.g., mean squared error, MSE)
- Compression of input (embedding)
- lacktriangle Prioritize important information ightarrow learn useful representations





Summary

- Introduction
 - Terminology, application scenarios
- Learning Paradigms
 - Unsupervised, supervised, self-supervised learning
- ML project pipeline
 - Data collection, pre-processing, split
 - Model selection, training, validation, testing
- Deep Learning
 - DNN, CNN, RNN, Autoencoders



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Images

- Fig. 1: [Machine Learning, 2016], p. 4, Fig. 2
- Fig. 2: https://i0.wp.com/www.sthda.com/sthda/RDoc/figure/clustering/ partitioning-cluster-analysis-k-means-plot-4-groups-1.png
- Fig. 3: https://i.stack.imgur.com/hsilO.png (https://scikit-learn.org/stable/auto_examples/classification/plot_classifier_comparison.html)
- Fig. 4: https://miro.medium.com/max/975/1*OyYyr9qY-w8RkaRh2TKo0w.png (reproduced)
- Fig. 5: https://lilianweng.github.io/lil-log/assets/images/self-sup-lecun.png
- Fig. 6: https://www.asimovinstitute.org/wp-content/uploads/2019/04/NeuralNetworkZoo20042019.png
- Fig. 7: https://www.educative.io/api/edpresso/shot/6668977167138816/image/5033807687188480
- Fig. 8: [Virtanen, 2018], p. 170, Fig. 6.7
- Fig. 9: https://miro.medium.com/max/915/1*SJPacPhP4KDEB1AdhOFy_Q.png
- Fig. 10: https://www.skampakis.com/wp-content/uploads/2018/03/simple_neural_network_vs_deep_learning.jpg
- Fig. 11: https://pic4.zhimg.com/80/v2-057b248288a8af2f01272a956f862873_1440w.png
- Fig. 12: https://blog.e-kursy.it/deeplearning4j-workshop/video/html/presentation_specific/img/4_activation_functions.png



Images

- Fig. 13: https://blog.paperspace.com/content/images/2018/05/challenges-1.png
- Fig. 14: https://www.cs.umd.edu/~tomg/img/landscapes/noshort.png
- Fig. 15: https://blog.paperspace.com/content/images/2018/05/grad.png
- Fig. 16: https://www.wandb.com/articles/intro-to-cnns-with-wandb
- Fig. 17: https://www.freecodecamp.org/news/an-intuitive-guide-to-convolutional-neural-networks-260c2de0a050/
- Fig. 18: https://wiki.tum.de/download/attachments/22578349/RNN1.png
- Fig. 19: https://stanford.edu/~shervine/teaching/cs-230/illustrations/architecture-rnn-ltr.png
- Fig. 20: [Srihari, 2020], p.8, (Fig. 1)



Thank you!

Any questions?

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