

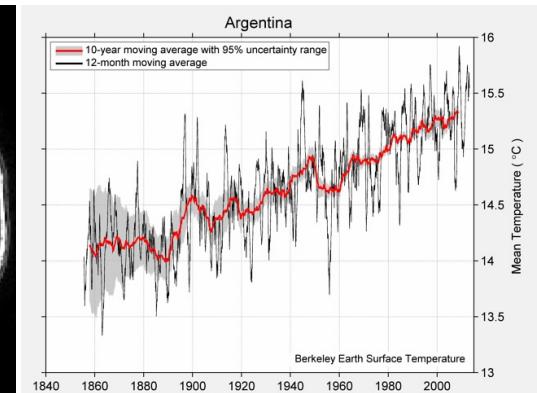
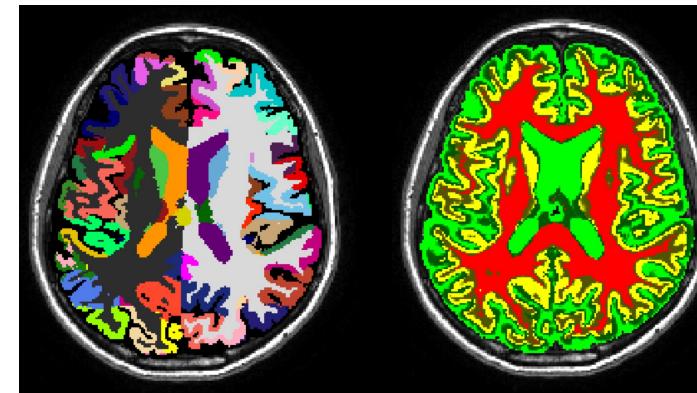
Clase 5

Redes neuronales más allá de la clasificación de imágenes

Enzo Ferrante

 eferrante@sinc.unl.edu.ar

 @enzoferante



Problemas en computer vision

Classification



CAT

No spatial extent

Semantic Segmentation



GRASS, CAT,
TREE, SKY

No objects, just pixels

Object Detection



DOG, DOG, CAT

Multiple Object

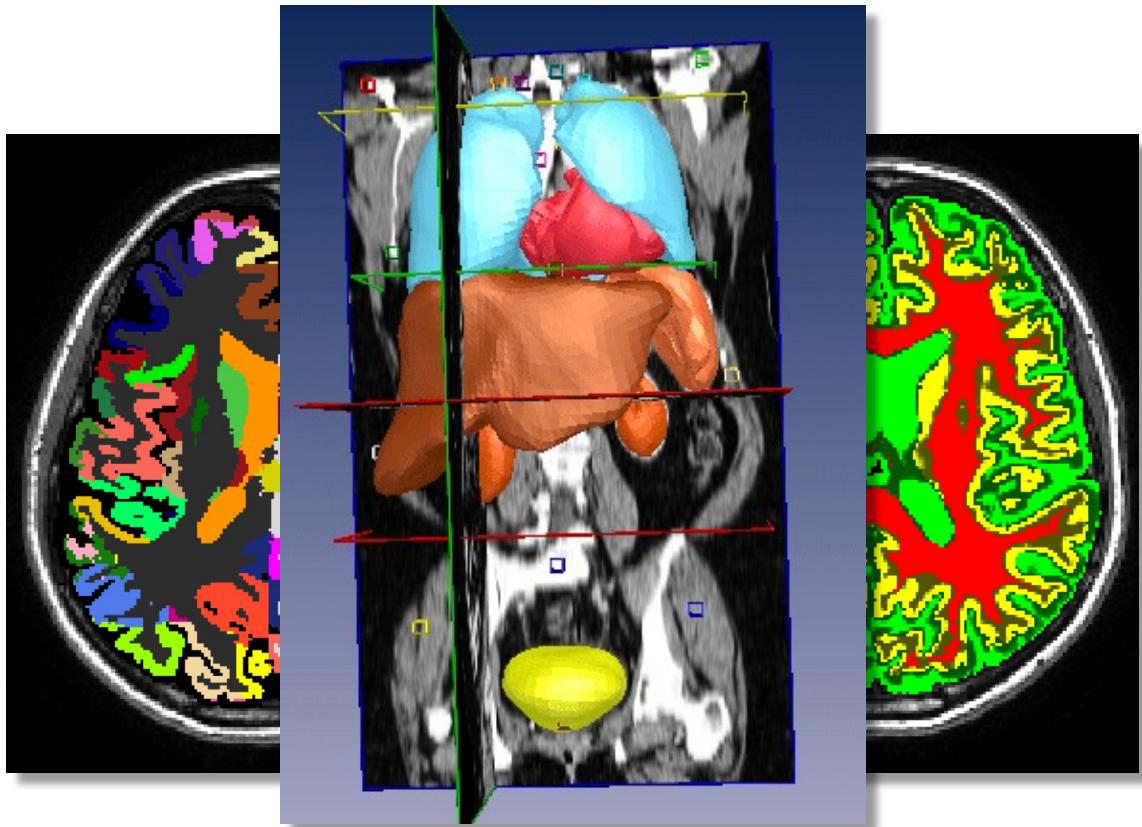
Instance Segmentation



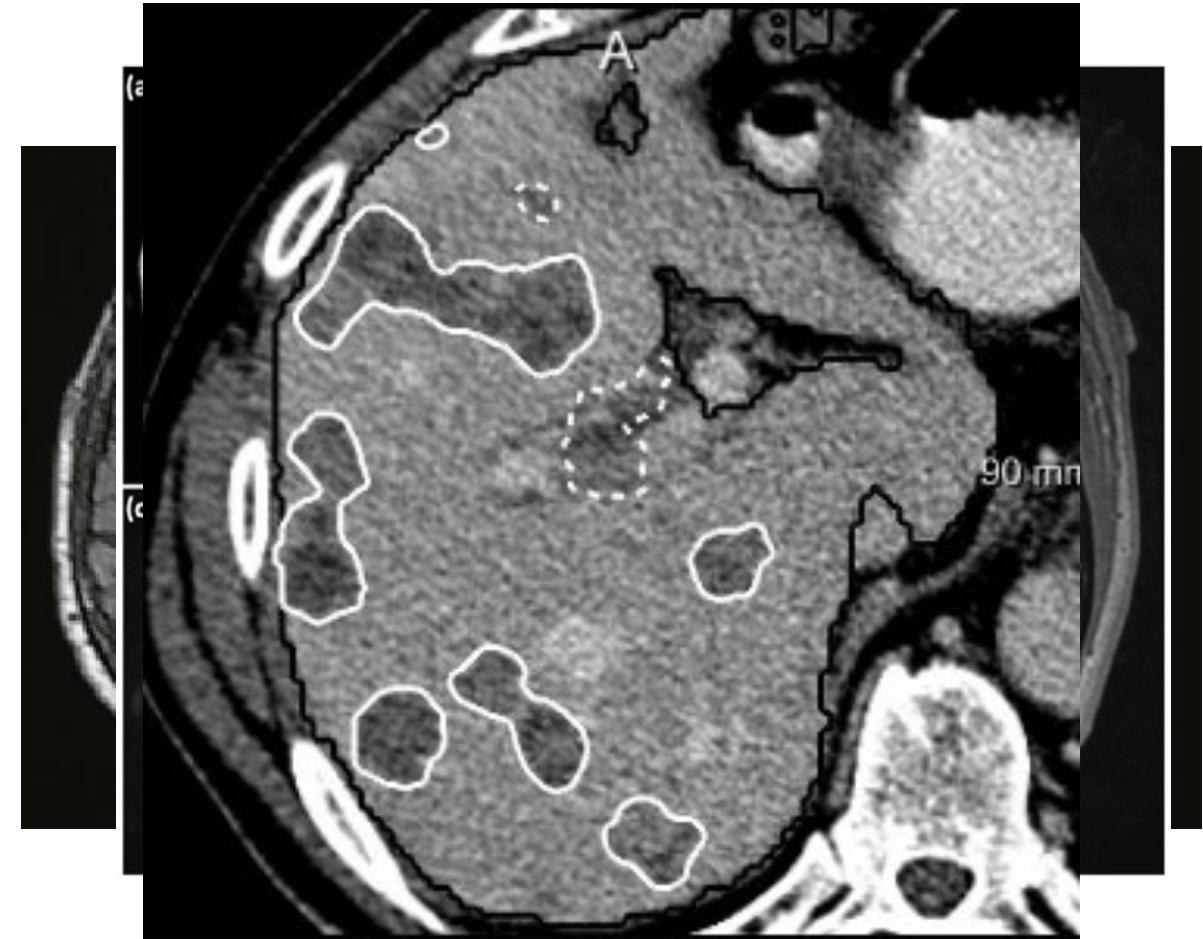
DOG, DOG, CAT

[This image is CC0 public domain](#)

Segmentación de imágenes médicas



Estructuras anatómicas

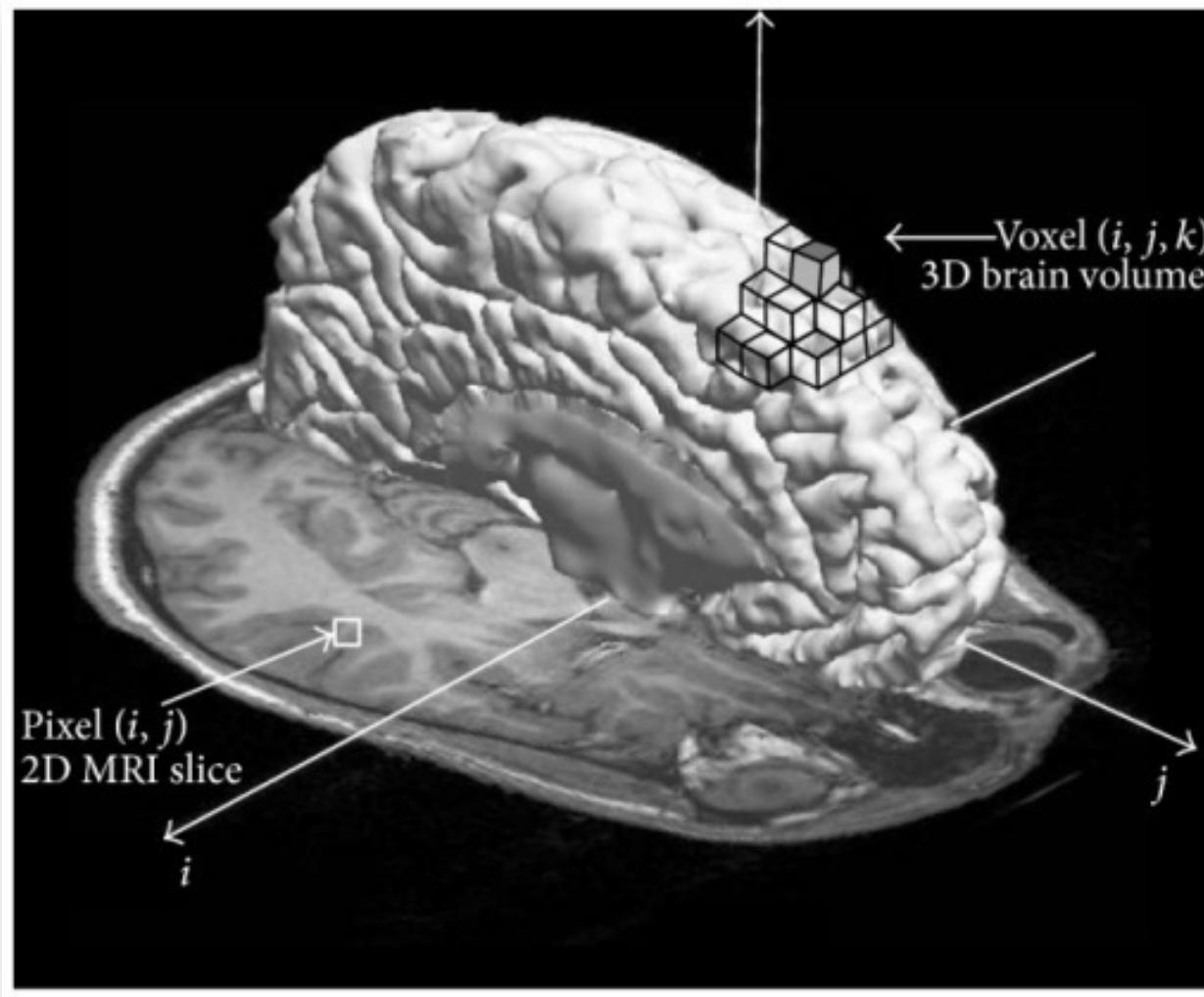


Estructuras patológicas

Segmentación de imágenes satelitales



Imágenes 2D vs Imágenes 3D



- Las imágenes pueden ser procesadas en 2D o en 3D.
- Diferencia espacio pixel y físico.

Múltiples canales de entrada

Full Color



Red



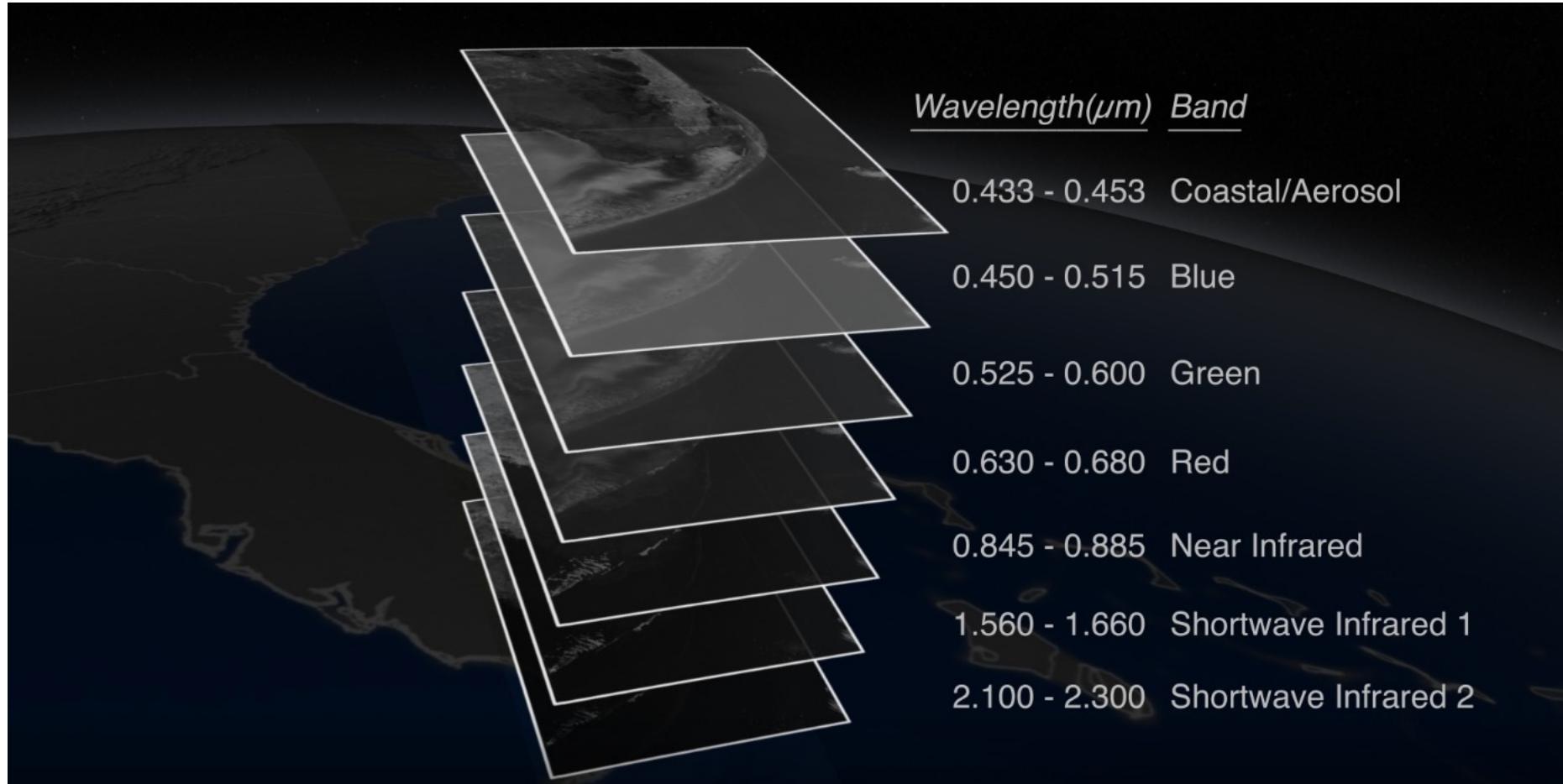
Green



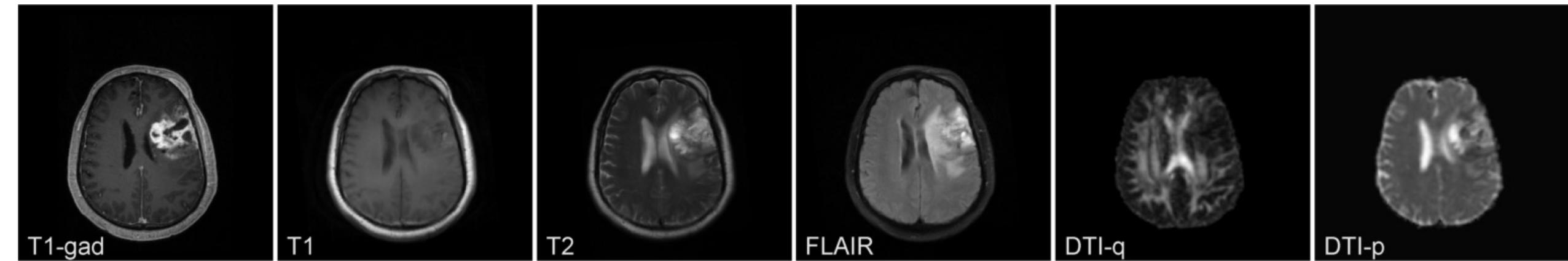
Blue



Múltiples canales de entrada

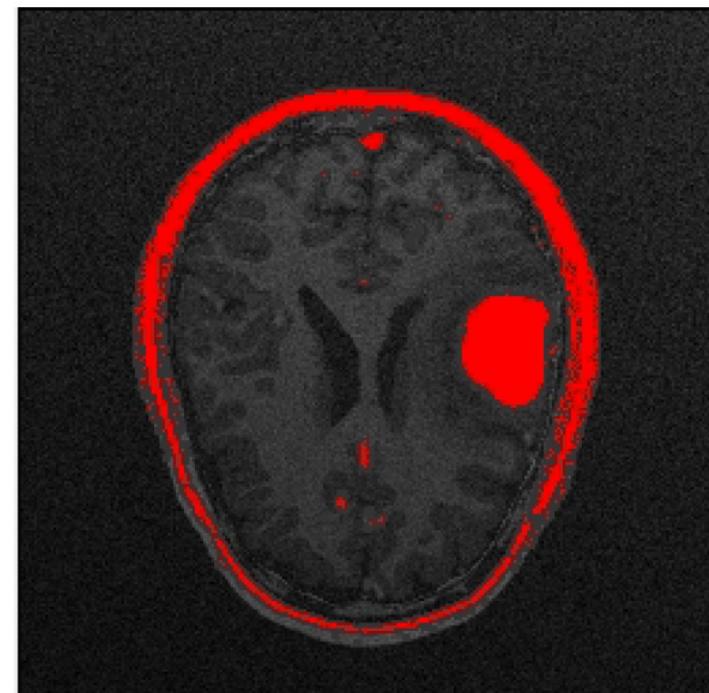
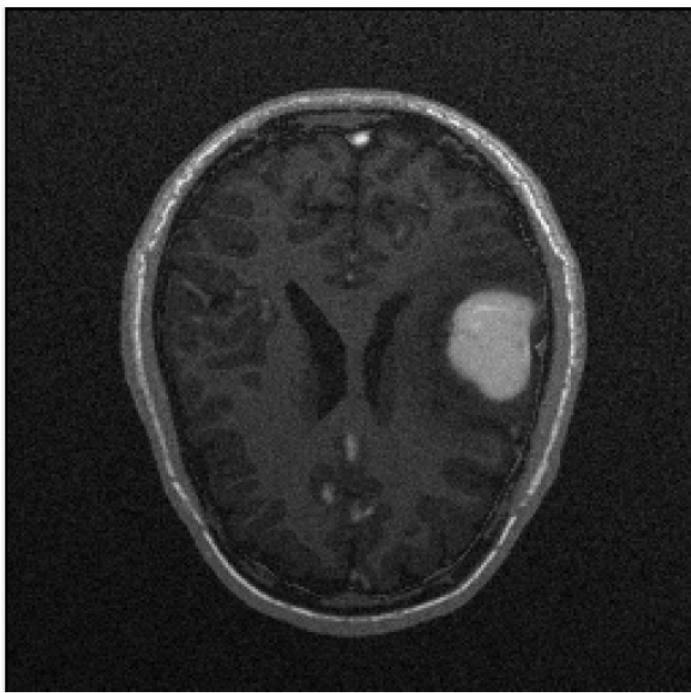


Múltiples canales de entrada

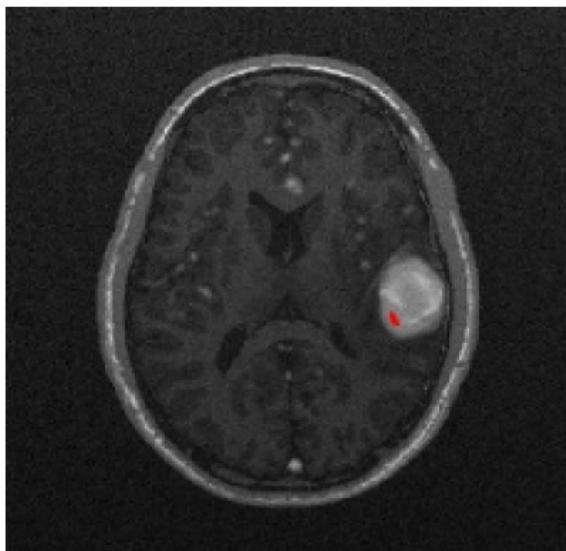


Técnicas clásicas de segmentación de imágenes

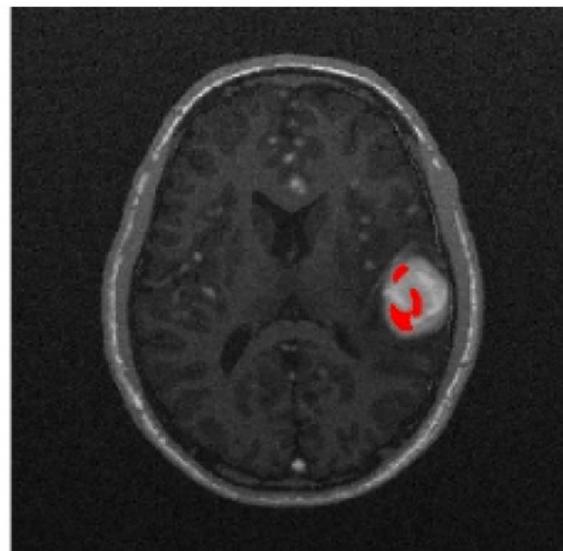
Umbralado



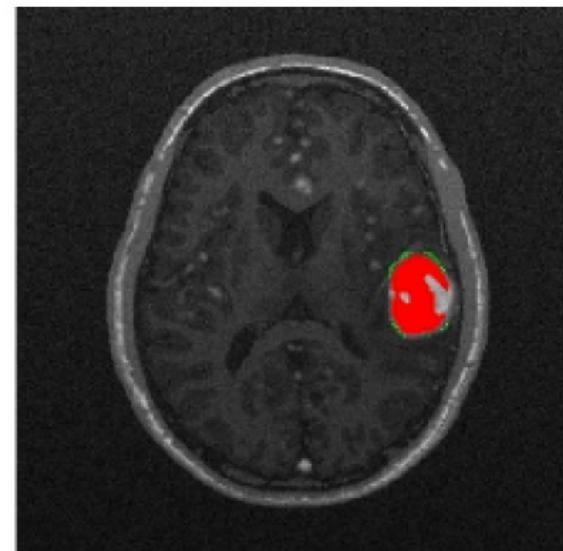
Crecimiento de regiones



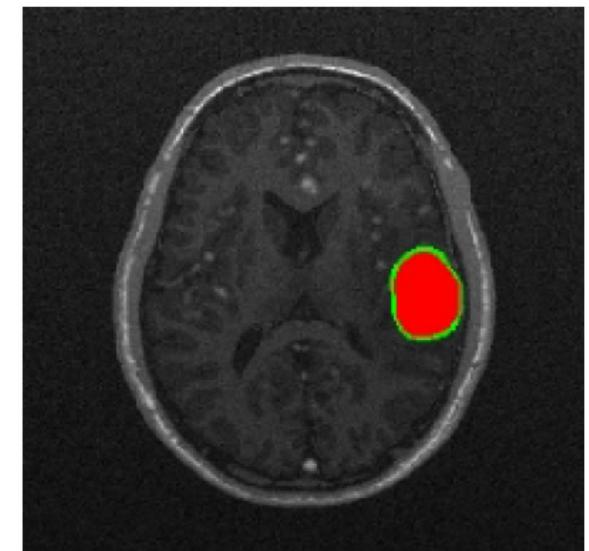
20%



50%



80%



100%

Watershed

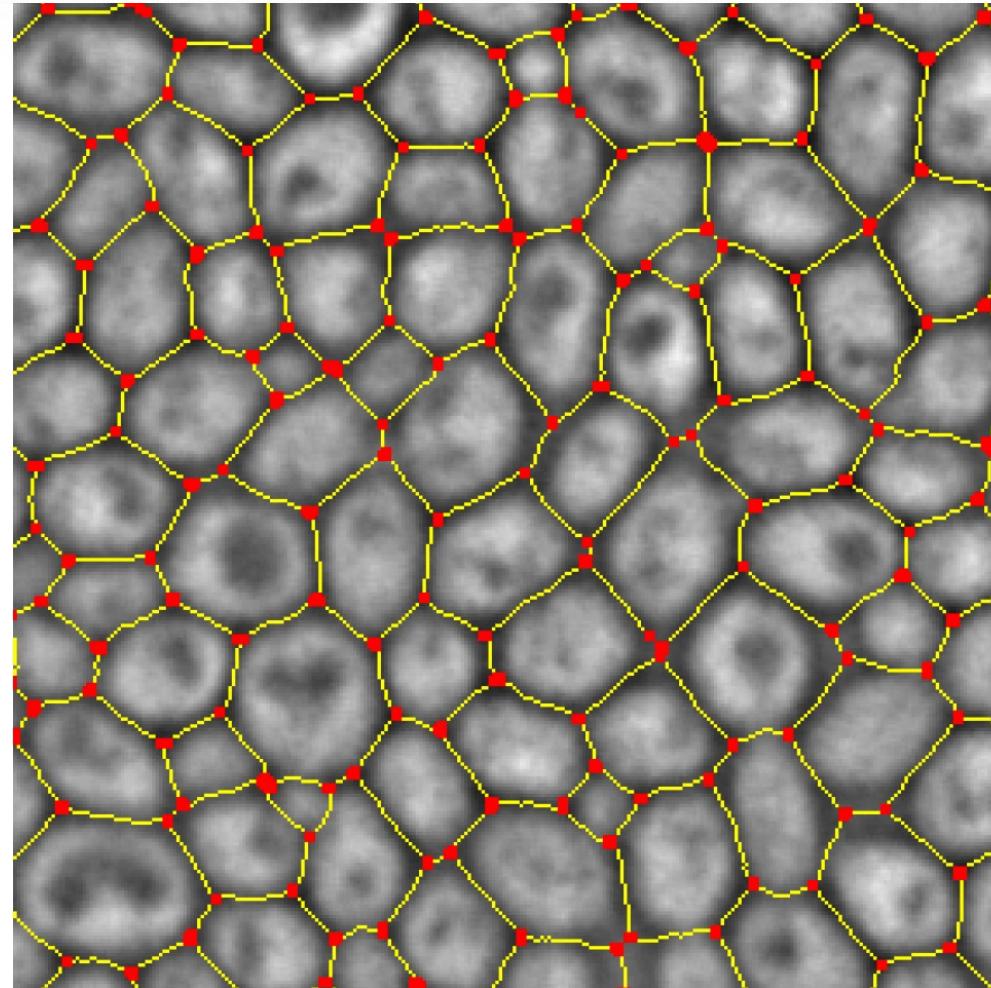
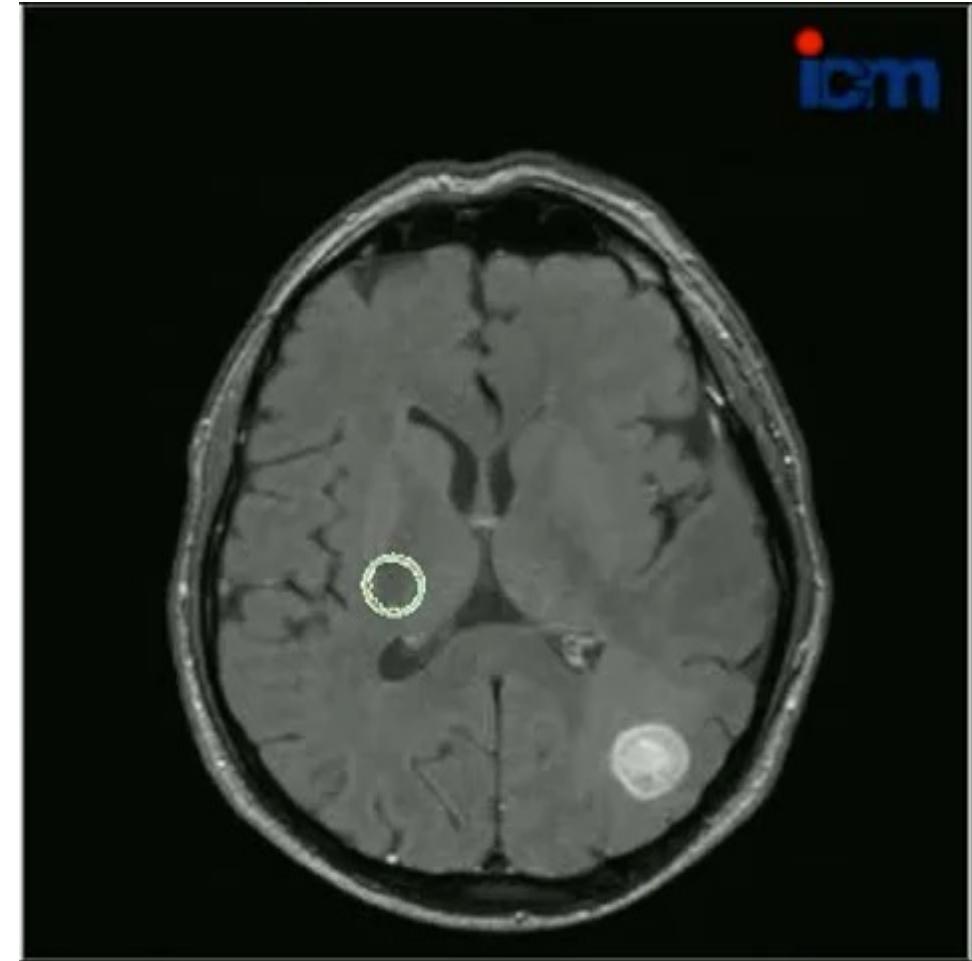
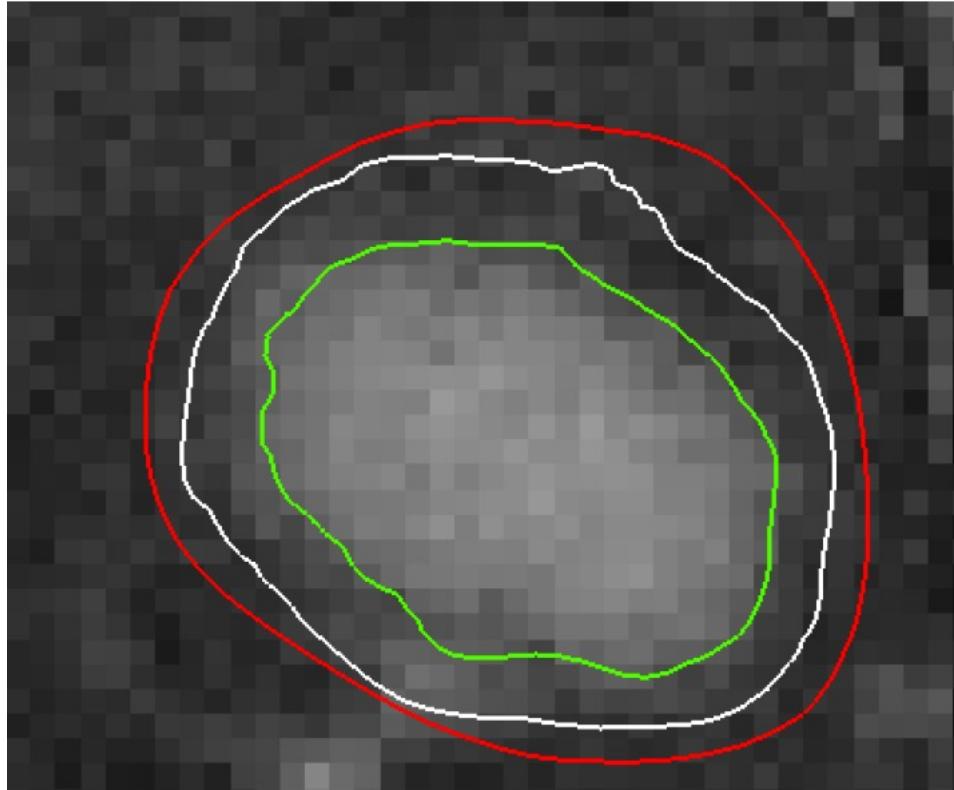


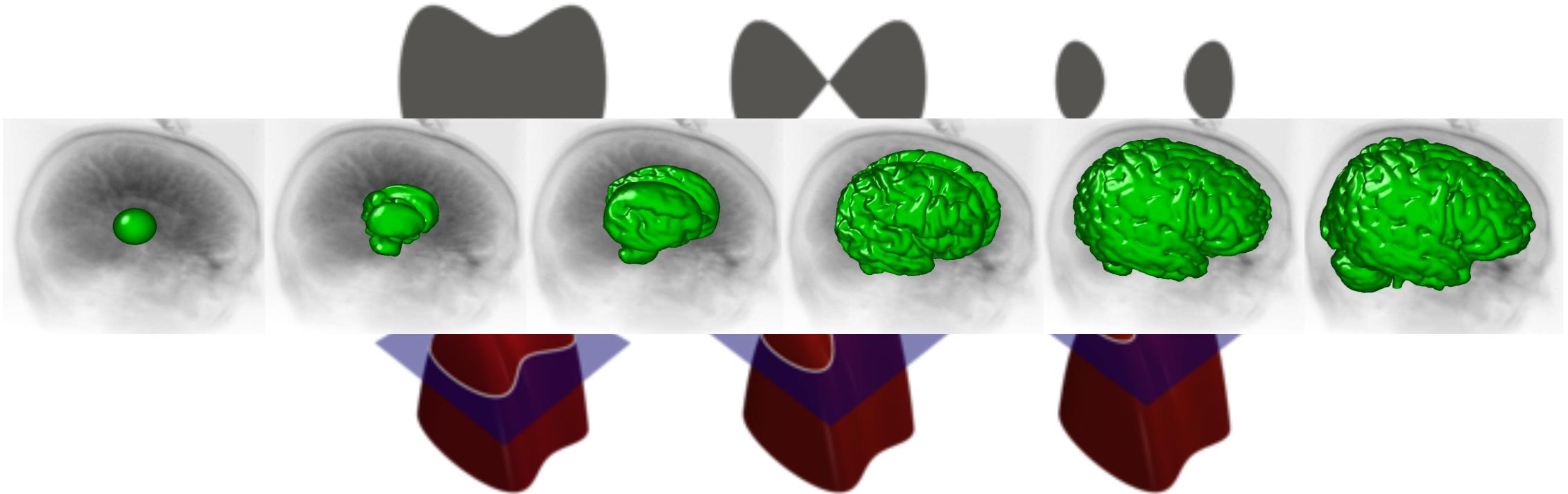
Imagen extraída de <http://biodynamics.ucsd.edu/ir>

Modelos deformables explícitos

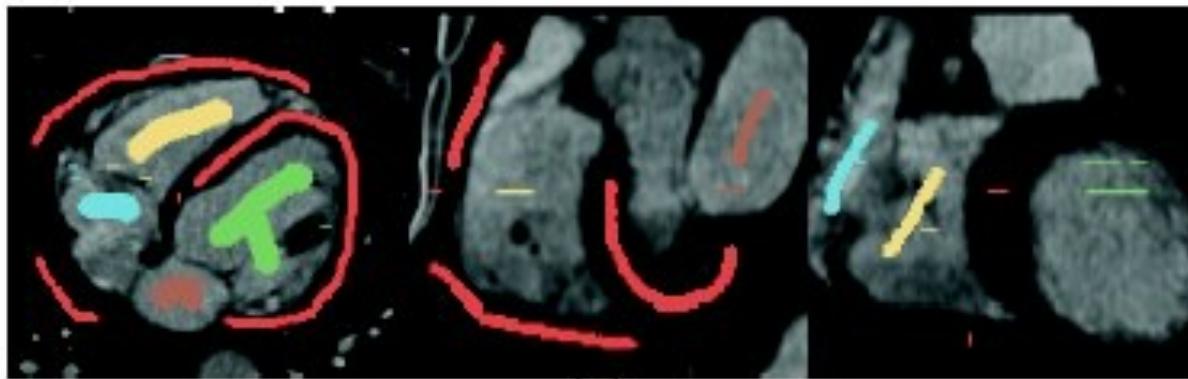
Ej. Contornos activos o Snakes



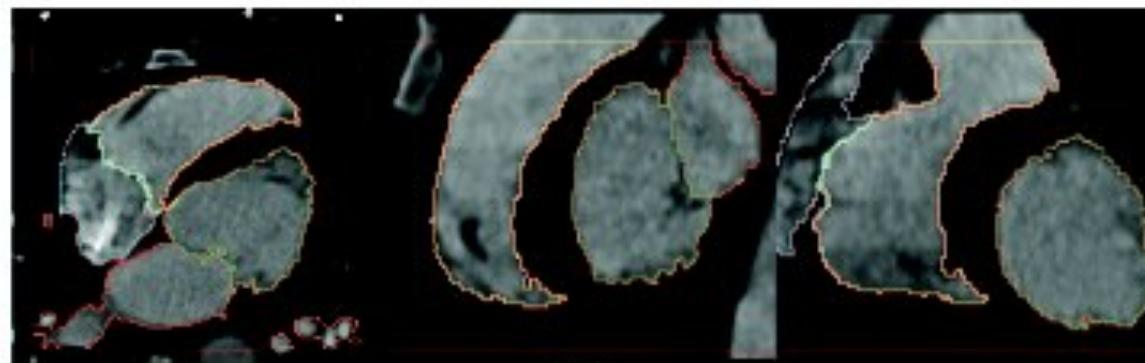
Level-sets



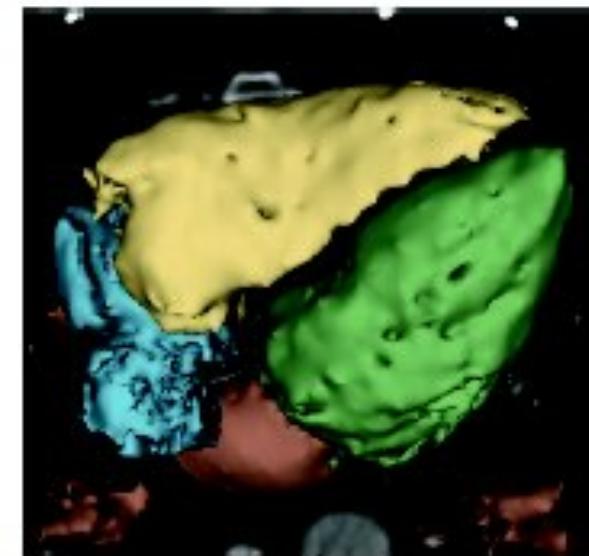
Segmentación interactiva



(a)

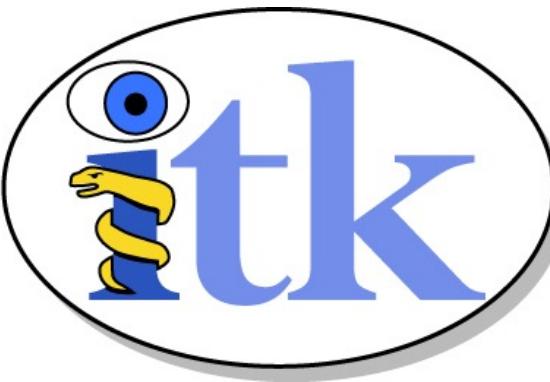
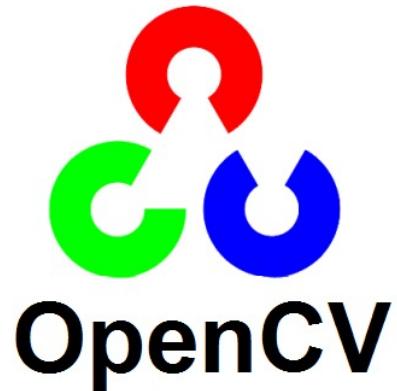


(b)



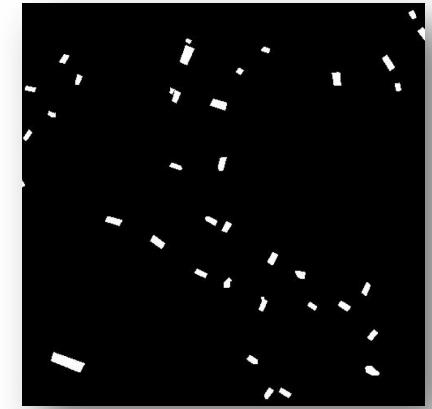
(c)

Donde encontrar todos estos métodos implementados?

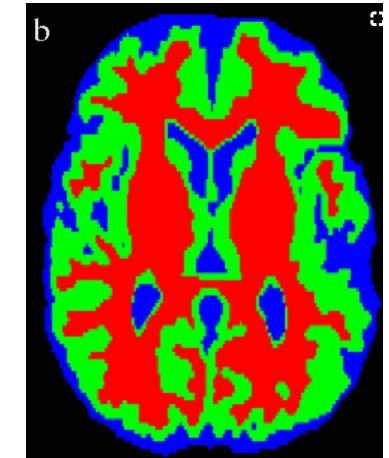
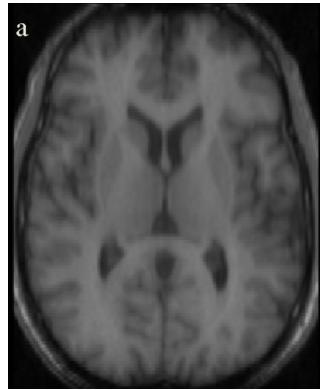


Redes neuronales convolucionales para la segmentación de imágenes

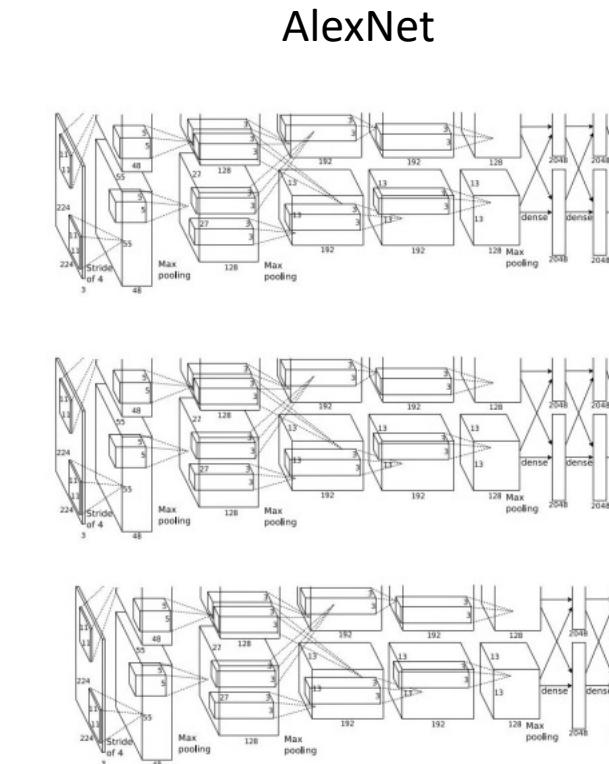
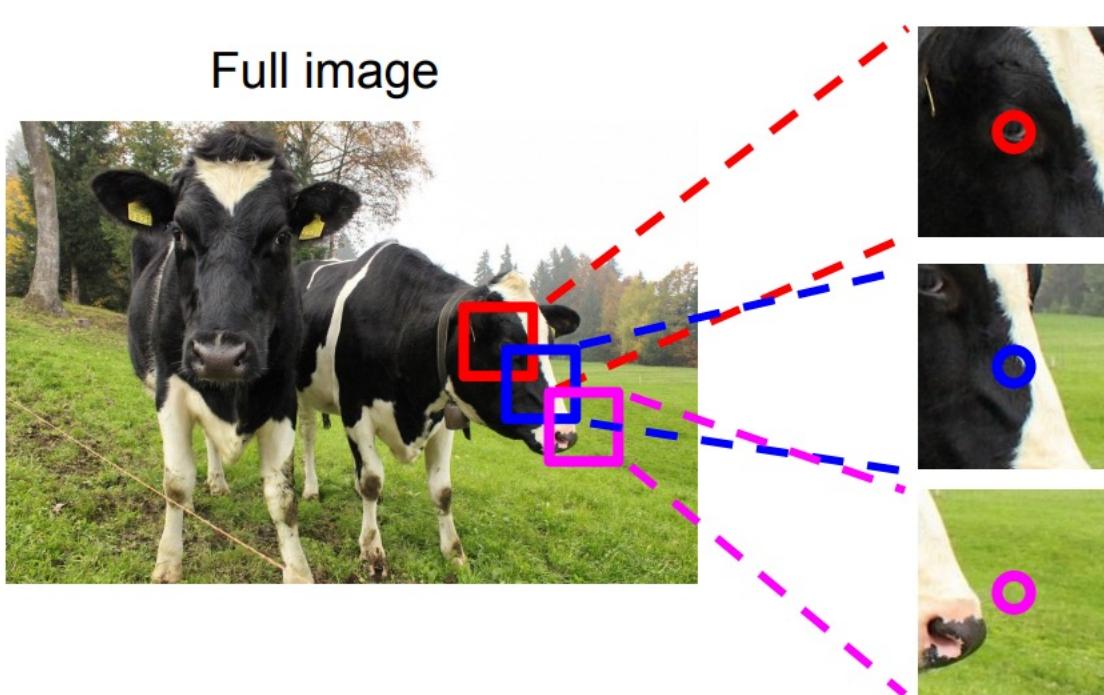
Segmentación de imágenes binaria



Segmentación de imágenes multiclas

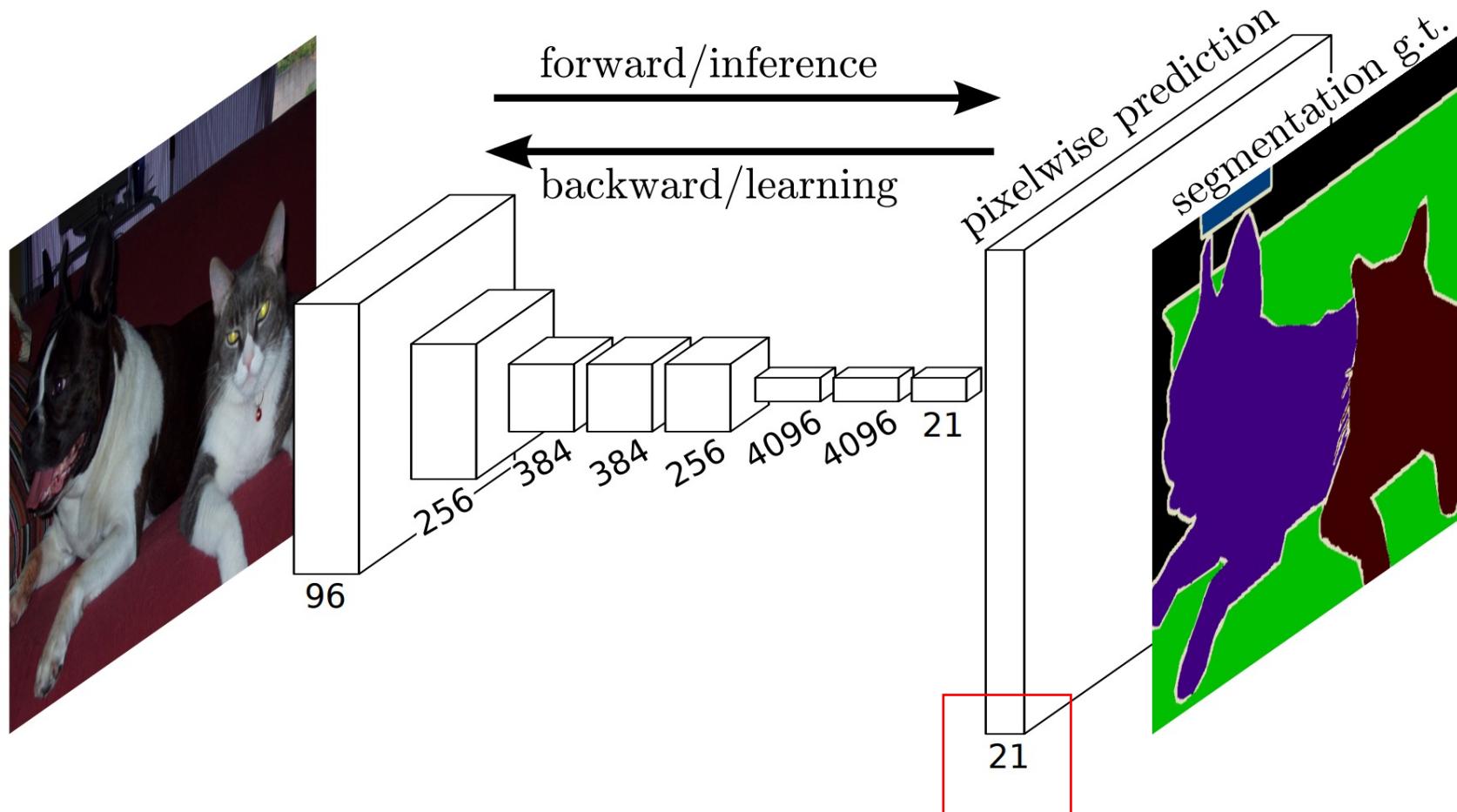


Primera solución: sliding window



Muy ineficiente porque no hace uso de las features compartidas entre parches

Fully Convolutional Networks



- El último feature map tiene tantos canales como posibles clases
- Computamos la función de pérdida para cada pixel y promediamos.

Fully Convolutional Networks

Fully Convolutional Networks for Semantic Segmentation

Jonathan Long*

Evan Shelhamer*
UC Berkeley

Trevor Darrell

{jonlong, shelhamer, trevor}@cs.berkeley.edu

Abstract

Convolutional networks are powerful visual models that yield hierarchies of features. We show that convolutional networks by themselves, trained end-to-end, pixels-to-pixels, exceed the state-of-the-art in semantic segmentation. Our key insight is to build “fully convolutional” networks that take input of arbitrary size and produce correspondingly-sized output with efficient inference and learning. We define and detail the space of fully convolutional networks, explain their application to spatially dense prediction tasks, and draw connections to prior models. We also extend contemporary classification networks (AlexNet [20], VGG [32]) into fully convolutional networks (FCN) trained end-to-end, pixels-to-pixels on semantic segmentation tasks. We show that FCNs can learn to make state-of-the-art without further machine learning, and we demonstrate how to train FCNs

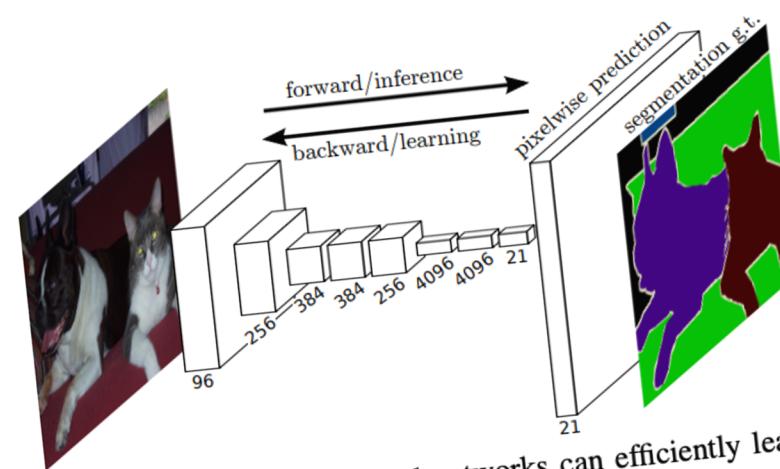
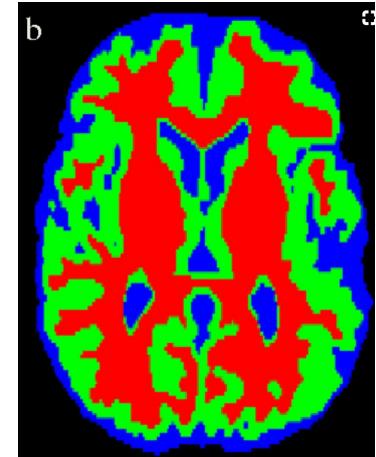
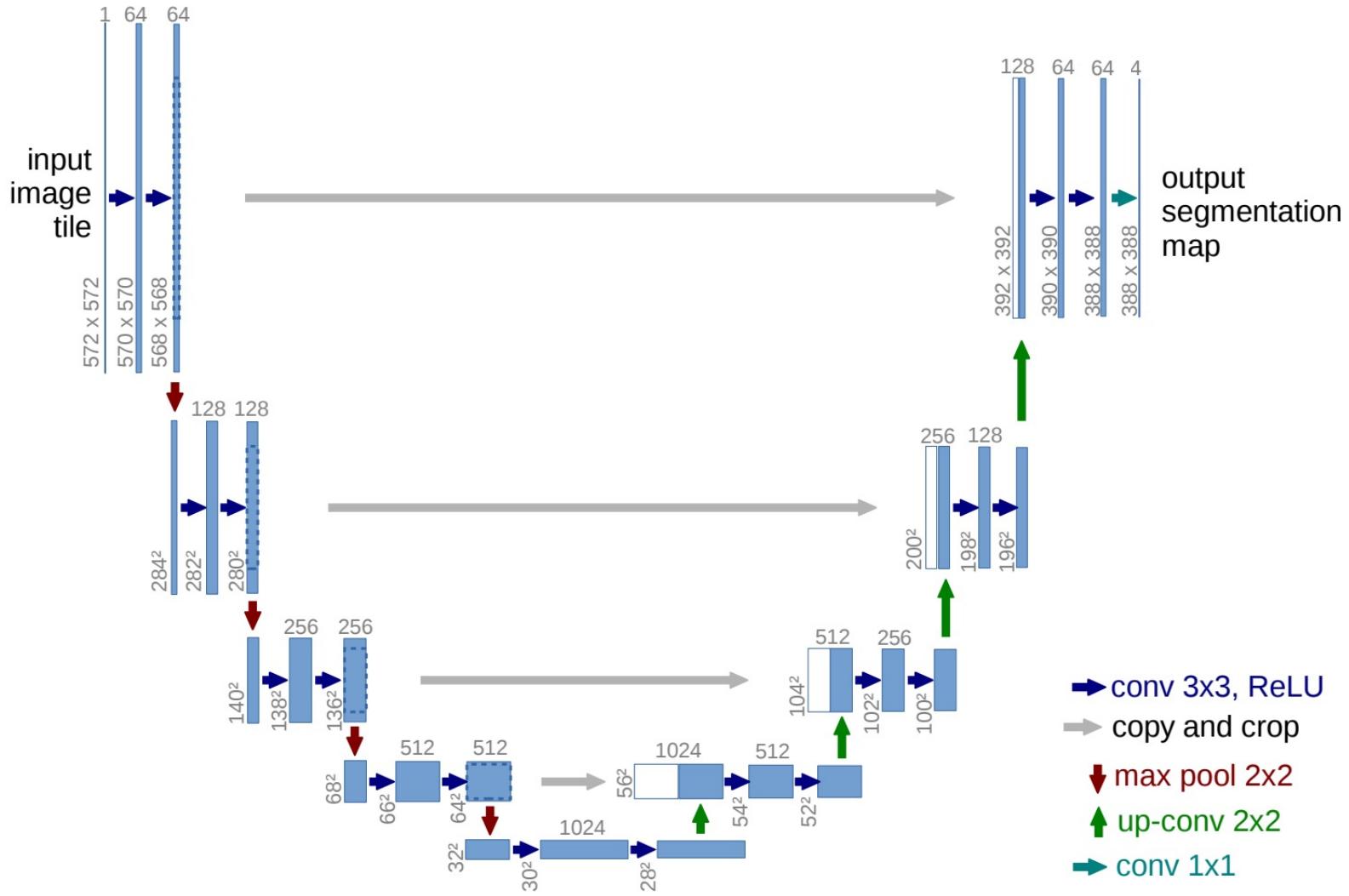
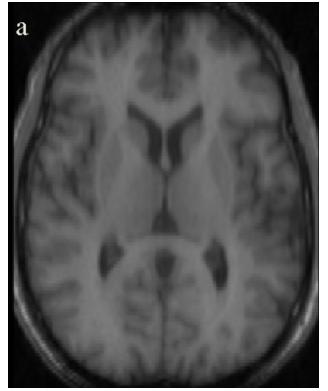


Figure 1. Fully convolutional networks can efficiently learn to make dense predictions for per-pixel tasks like semantic segmentation.

UNet: Arquitectura encoder-decoder para segmentación de imágenes



UNet: Arquitectura encoder-decoder para segmentación de imágenes

U-Net: Convolutional Networks for Biomedical Image Segmentation

Olaf Ronneberger, Philipp Fischer, and Thomas Brox

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University of Freiburg, Germany
ronneber@informatik.uni-freiburg.de,
WWW home page: <http://lmb.informatik.uni-freiburg.de/>

Abstract. There is large consent that successful training of deep networks requires many thousand annotated training samples. In this paper, we present a network and training strategy that relies on the strong use of data augmentation to use the available annotated samples more efficiently. The architecture consists of a contracting path to capture context and a symmetric expanding path that enables precise localization. We show that such a network can be trained end-to-end from very few images and outperforms the prior best method (a sliding-window convolutional network) on the ISBI challenge for segmentation of neuronal structures in electron microscopic stacks. Using the same network trained on transmitted light microscopy images (phase contrast and DIC) we won the ISBI cell tracking challenge 2015 by a large margin. More

Operaciones de upsampling: Unpooling

Nearest Neighbor

1	2
3	4



1	1	2	2
1	1	2	2
3	3	4	4
3	3	4	4

Input: 2 x 2

Output: 4 x 4

“Bed of Nails”

1	2
3	4



1	0	2	0
0	0	0	0
3	0	4	0
0	0	0	0

Input: 2 x 2

Output: 4 x 4

Operaciones de upsampling: Unpooling

Durante **MaxPooling**,
nos acordamos la posición original del valor

1	2	6	3
3	5	2	1
1	2	2	1
7	3	4	8

Input: 4 x 4

5	6
7	8

Output: 2 x 2

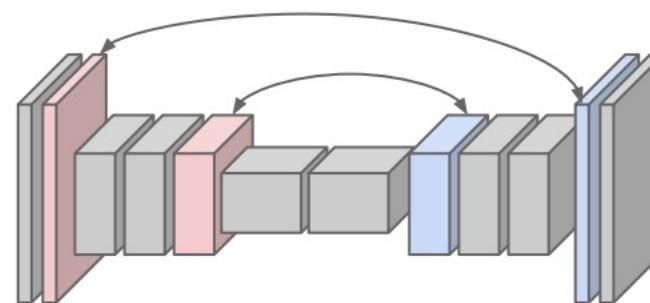
Rest of the network

1	2
3	4

Input: 2 x 2

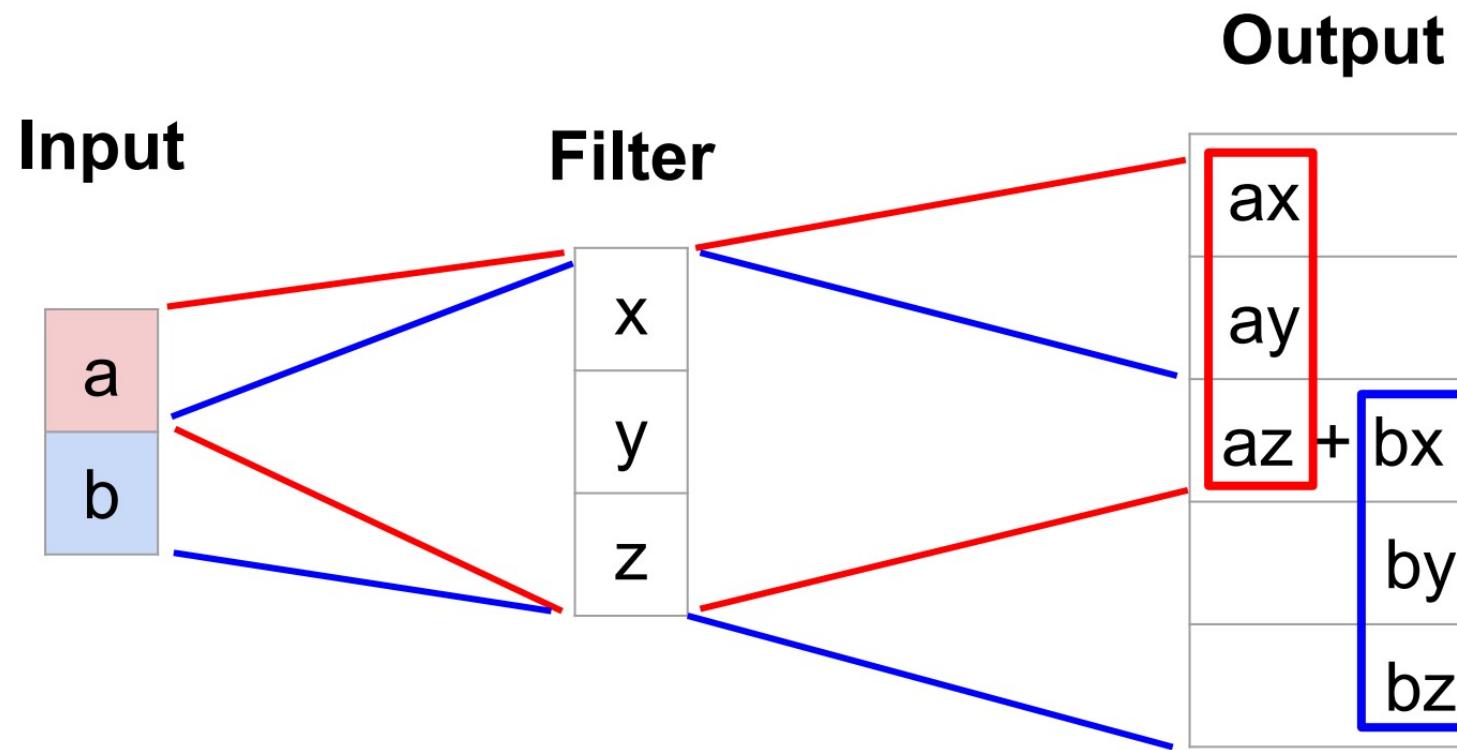
0	0	2	0
0	1	0	0
0	0	0	0
3	0	0	4

Output: 4 x 4



Transpose convolution

Ejemplo para una convolución 1D

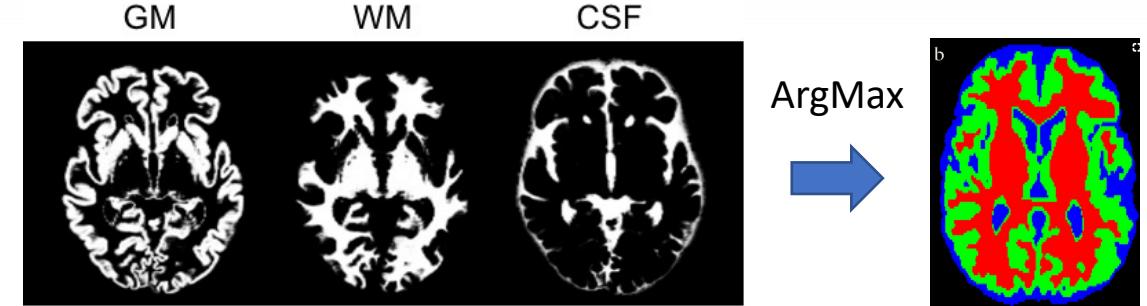
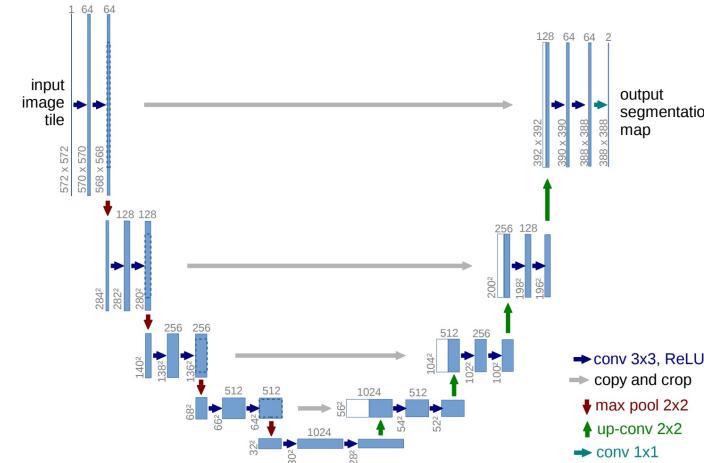
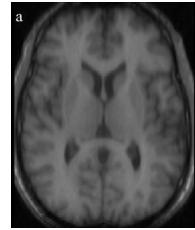


Por cada 1 pixel de la entrada, nos desplazamos 2 en la salida (stride = 2)

La salida se construye pesando los valores de la entrada con los distintos pesos de un kernel

En las zonas de overlap, se suma

Cálculo de la función de pérdida para segmentación



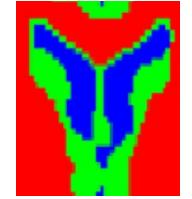
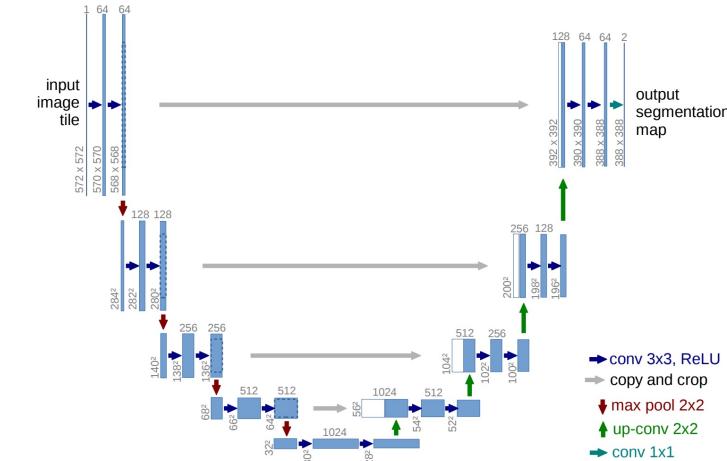
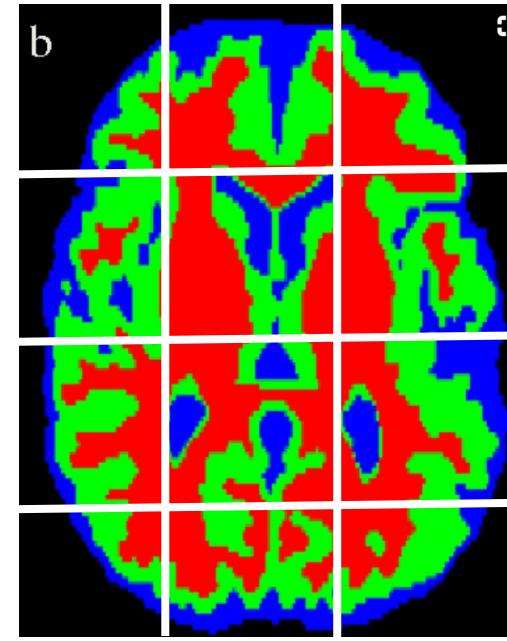
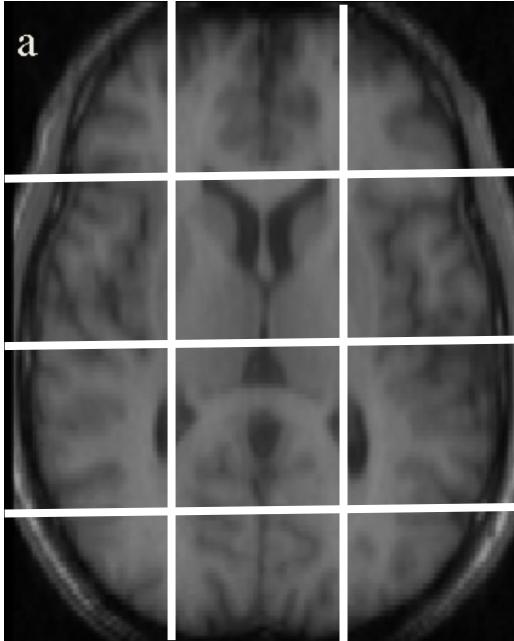
Mapa de probabilidad por clase
(cada voxel suma 1 entre los 3 mapas)

- Se calcula la **función de pérdida por pixel** (ej. Entropía Cruzada) de los mapas de probabilidad de salida comprándolos con la versión One-hot del ground-truth, **y luego se promedia por todos los pixeles de la imagen**

Redes totalmente convolucionales

- Si la red no cuenta con ninguna capa totalmente conectada (densa), entonces se dice totalmente convolucional
- Las capas densas pueden ser implementadas como capas convolucionales → Cómo?
- La gran ventaja de una red totalmente convolucional es que puede procesar imágenes de cualquier tamaño, y puede ser entrenada y evaluada en imágenes de diferentes tamaños.

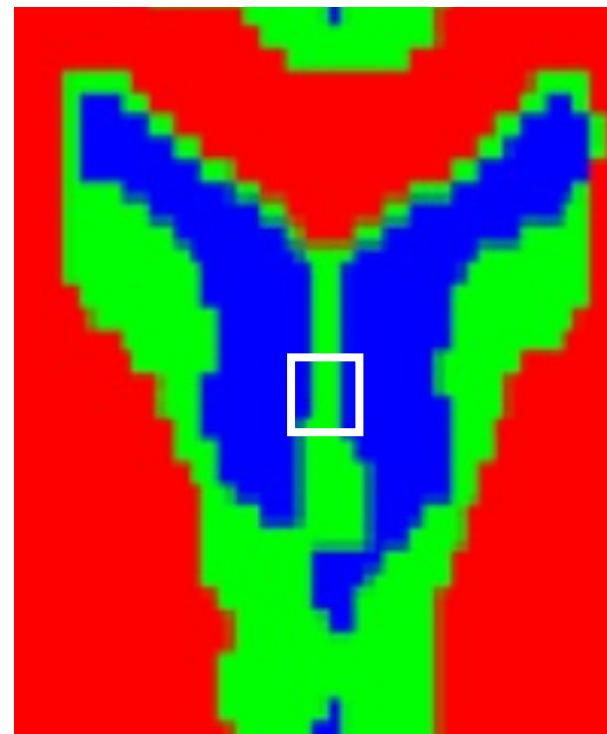
Entrenamiento por parches



- Los mini-batches se componen de parches, no de imágenes completas
- En test time, si la red es totalmente convolucional, basta con insertar la nueva imagen y la predicción será del tamaño acorde (*cuidado con los múltiplos de*).
- Si la red no es del tamaño acorde, se puede hacer el tiling fuera de la red, y luego reconstruir la segmentación

Estrategias de muestreo de parches

Para garantizar un entrenamiento equilibrado, es importante que cada mini-batch esté compuesto por parches centrados en diferentes etiquetas de forma equilibrada



Ayuda a solucionar el problema del desbalanceo de etiquetas

Procesando imágenes 3D

- Las arquitecturas son las mismas, pero utilizando convoluciones 3D en lugar de 2D
- Si la entrada era antes un tensor de dimensiones

(BatchSize, Channels, Width, Height,)

- Pasará a ser

(BatchSize, Channels , Depth, Width, Height)

CONV3D

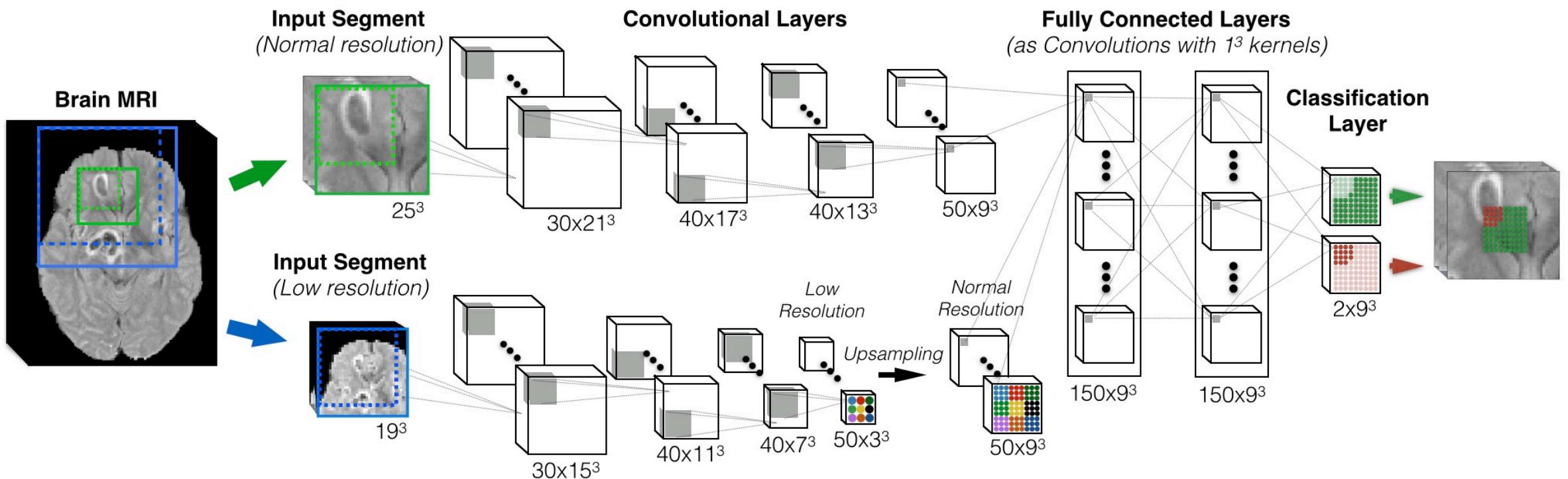
```
CLASS torch.nn.Conv3d(in_channels, out_channels, kernel_size, stride=1,  
                    padding=0, dilation=1, groups=1, bias=True, padding_mode='zeros')
```

[SOURCE]

Applies a 3D convolution over an input signal composed of several input planes.

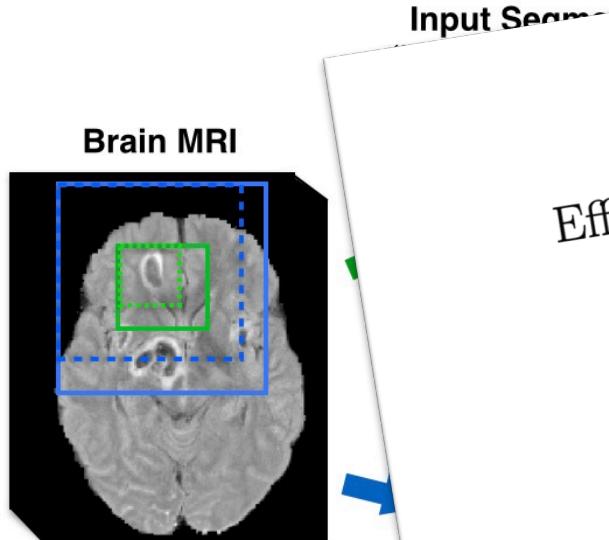
In the simplest case, the output value of the layer with input size (N, C_{in}, D, H, W) and output $(N, C_{out}, D_{out}, H_{out}, W_{out})$ can be precisely described as:

DeepMedic: ConvNets con branches multi-resolución



Kamnitsas et al, "Efficient multi-scale 3d CNN with fully connected CRF for accurate brain lesion segmentation", Medical Image Analysis, 2017.

DeepMedic: ConvNets con branches multi-resolución



Efficient Multi-Scale 3D CNN with fully connected CRF for Accurate Brain Lesion Segmentation

Konstantinos Kamnitsas^a, Christian Ledig^a, Virginia F.J. Newcombe^{b,c},
Joanna P. Simpson^b, Andrew D. Kane^b, David K. Menon^{b,c},
Daniel Rueckert^a, Ben Glocker^a

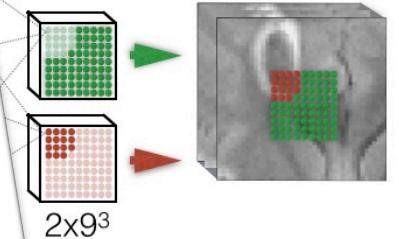
^a Biomedical Image Analysis Group, Imperial College London, UK

^b University Division of Anaesthesia, Department of Medicine, Cambridge University, UK

^c Wolfson Brain Imaging Centre, Cambridge University, UK

Abstract

We propose a dual pathway, 11-layers deep, three-dimensional Convolutional Neural Network for the challenging task of brain lesion segmentation. The devised architecture is the result of an in-depth analysis of the limitations of current networks proposed for similar applications. To overcome the computational cost of processing 3D medical scans, we have devised an efficient scheme which joins the processing of adjacent volumes while automatically adapt-





DeepMedic.

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DEEPMEDIC

Deep Learning Suite for 3D Image Segmentation





nnU-Net: a self-configuring method for deep learning-based biomedical image segmentation

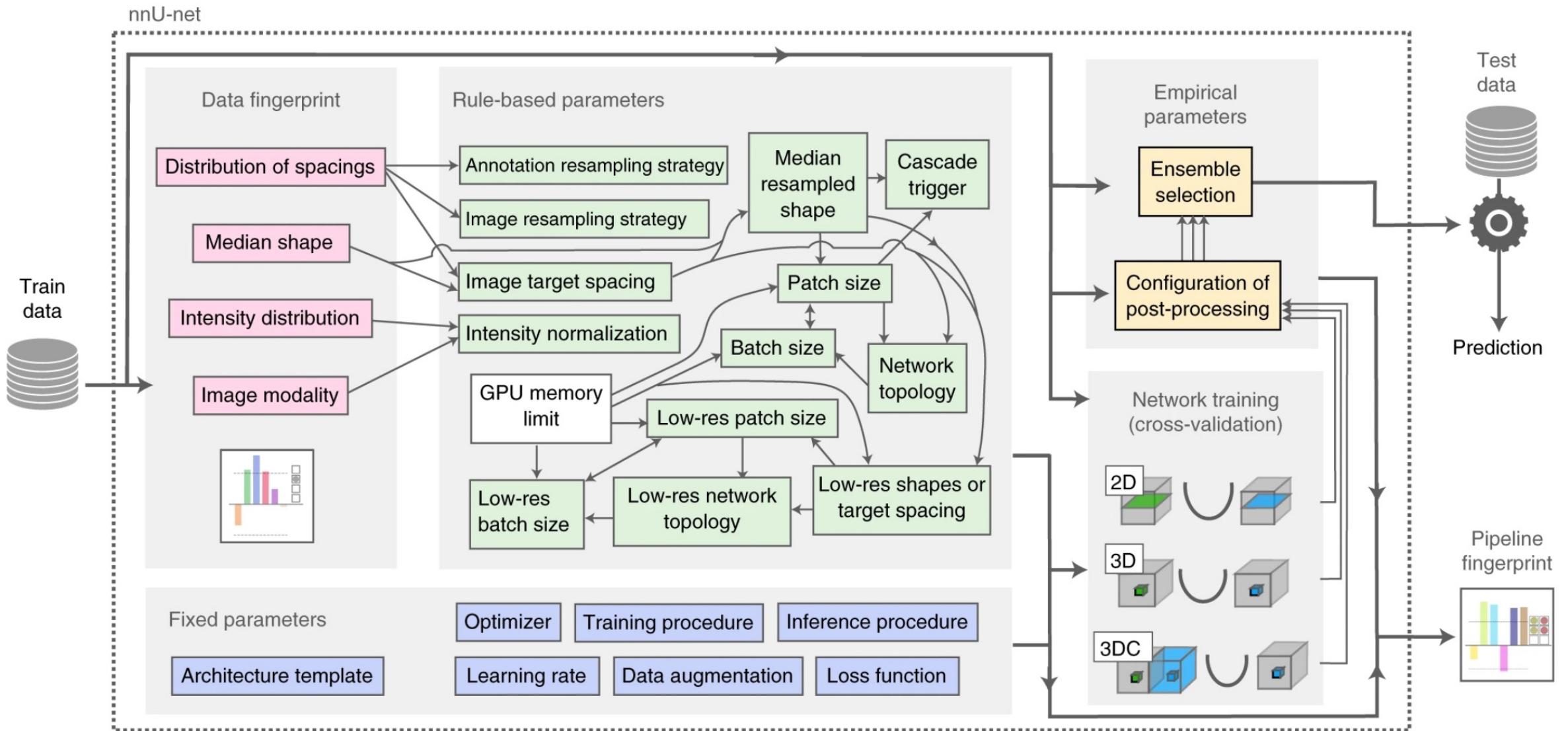
Fabian Isensee^{1,2,6}, Paul F. Jaeger^{1,6}, Simon A. A. Kohl^{1,3}, Jens Petersen^{1,4} and Klaus H. Maier-Hein^{1,5}

Biomedical imaging is a driver of scientific discovery and a core component of medical care and is being stimulated by the field of deep learning. While semantic segmentation algorithms enable image analysis and quantification in many applications, the design of respective specialized solutions is non-trivial and highly dependent on dataset properties and hardware conditions. We developed nnU-Net, a deep learning-based segmentation method that automatically configures itself, including preprocessing, network architecture, training and post-processing for any new task. The key design choices in this process are modeled as a set of fixed parameters, interdependent rules and empirical decisions. Without manual intervention, nnU-Net surpasses most existing approaches, including highly specialized solutions on 23 public datasets used in international biomedical segmentation competitions. We make nnU-Net publicly available as an out-of-the-box tool, rendering state-of-the-art segmentation accessible to a broad audience by requiring neither expert knowledge nor computing resources beyond standard network training.

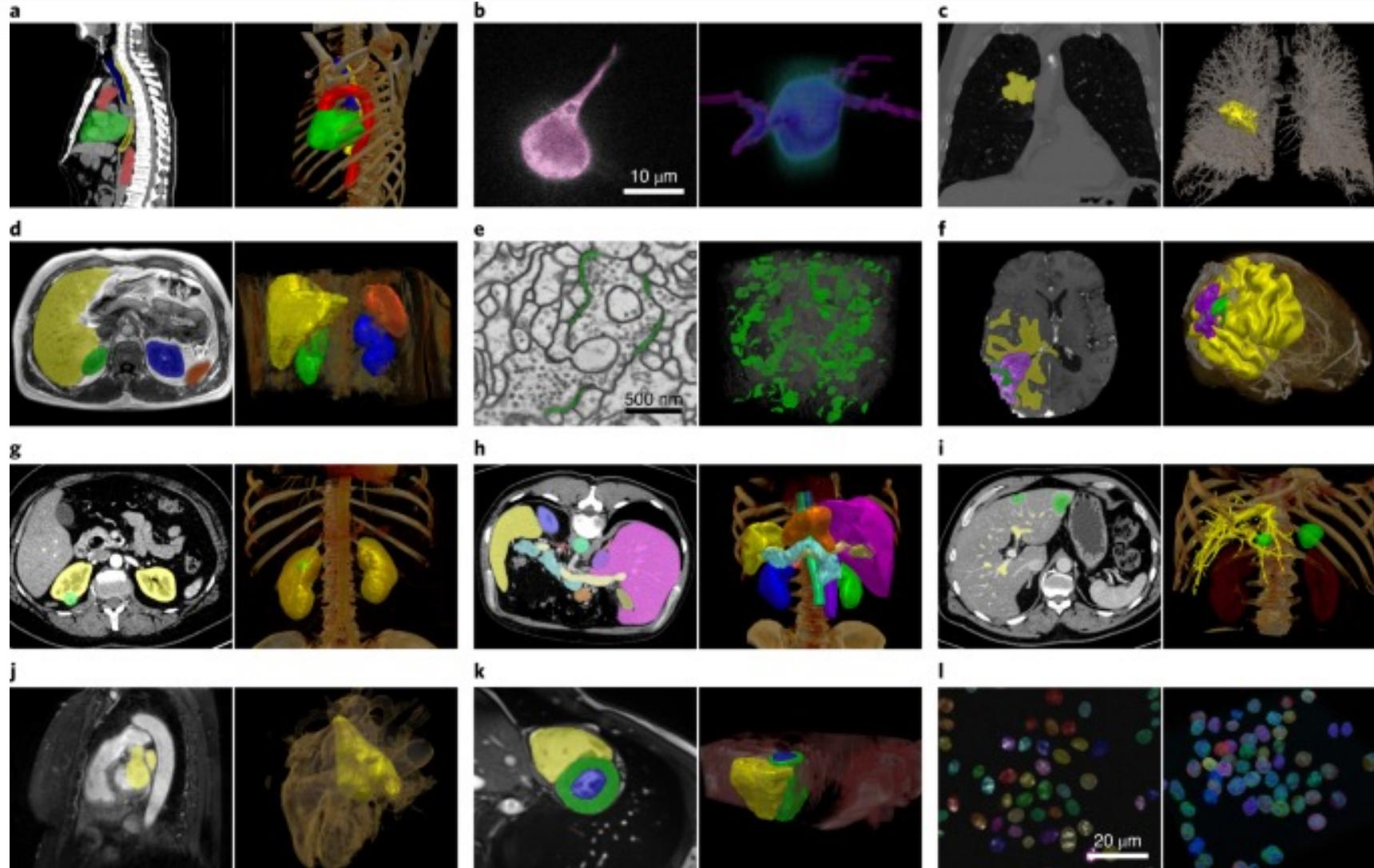
Semantic segmentation transforms raw biomedical image data into meaningful, spatially structured information and thus plays an essential role in scientific discovery^{1,2}. At the same time, semantic segmentation is an essential ingredient in numerous clinical applications^{3,4}, including applications of artificial intelligence in diagnostic support systems^{5,6}, therapy planning support⁷, intra-operative assistance² and tumor growth monitoring⁸. High

expert choices, for example, when considering the construction of a sensible problem-specific search space¹². As our analysis of the current landscape in international biomedical segmentation challenges indicates (Results), these practical limitations commonly leave users with a manual and an iterative trial-and-error process during method design that is mostly driven by individual experience, is only scarcely documented and often results in suboptimal

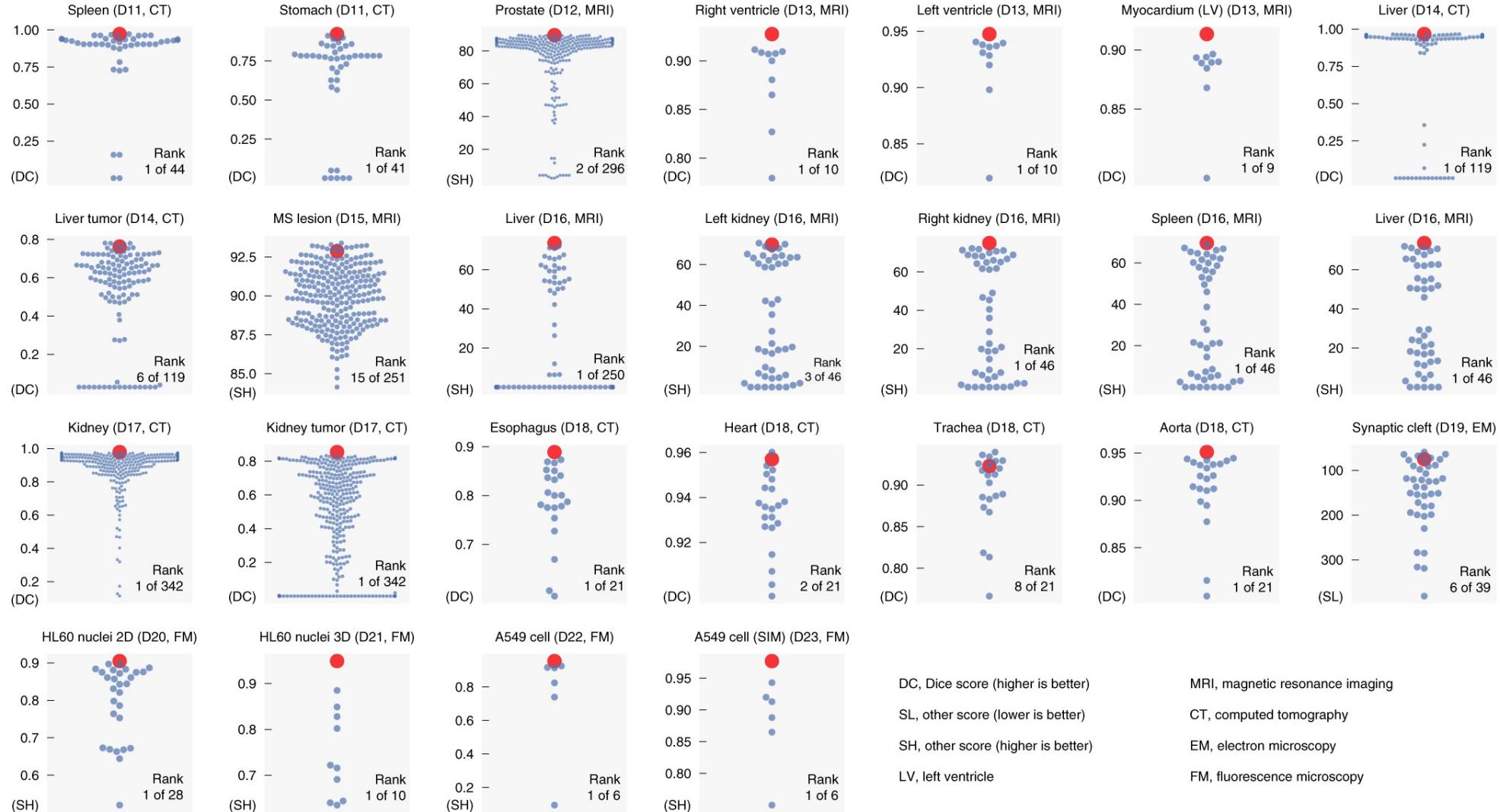
nnU-Net: a self-configuring method for deep learning-based biomedical image segmentation



nnU-Net: a self-configuring method for deep learning-based biomedical image segmentation



nnU-Net: a self-configuring method for deep learning-based biomedical image segmentation



**FabianIsensee** simplify the function for loading pretrained weights

ad081e9 9 hours ago 1,207 commits

documentation	nothing important	last week
nnunetv2	simplify the function for loading pretrained weights	9 hours ago
.gitignore	initial commit	4 years ago
LICENSE	setup.py	4 years ago
readme.md	update link to v1 branch	last month
setup.cfg	added more setup stuff	4 years ago
setup.py	fix typo in nnUNetv2_plan_experiment entry point	2 weeks ago



Welcome to the new nnU-Net!

Click [here](#) if you were looking for the old one instead.

Coming from V1? Check out the [TLDR Migration Guide](#). Reading the rest of the documentation is still strongly recommended ;-)

What is nnU-Net?

Image datasets are enormously diverse: image dimensionality (2D, 3D), modalities/input channels (RGB image, CT, MRI, microscopy, ...), image sizes, voxel sizes, class ratio, target structure properties and more change substantially between datasets. Traditionally, given a new problem, a tailored solution needs to be manually designed and optimized - a process that is prone to errors, not scalable and where success is overwhelmingly determined by the skill of the experimenter. Even for experts, this process is anything but simple: there are not only many design choices and data properties that need to be considered, but they are also tightly interconnected,

No description or website provided.

segmentation

- Readme
 - Apache-2.0 license
 - 3.5k stars
 - 76 watching
 - 1.2k forks
- [Report repository](#)

Releases 2

- nnU-Net V2 (Latest)
last month

[+ 1 release](#)

Packages

No packages published

Contributors 38

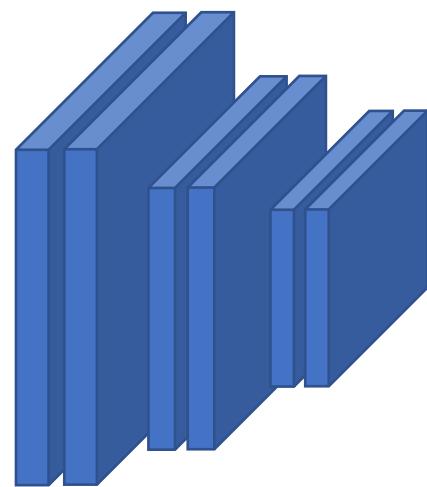


[+ 27 contributors](#)

Languages

Arquitectura básica para localización

Red con salidas múltiples



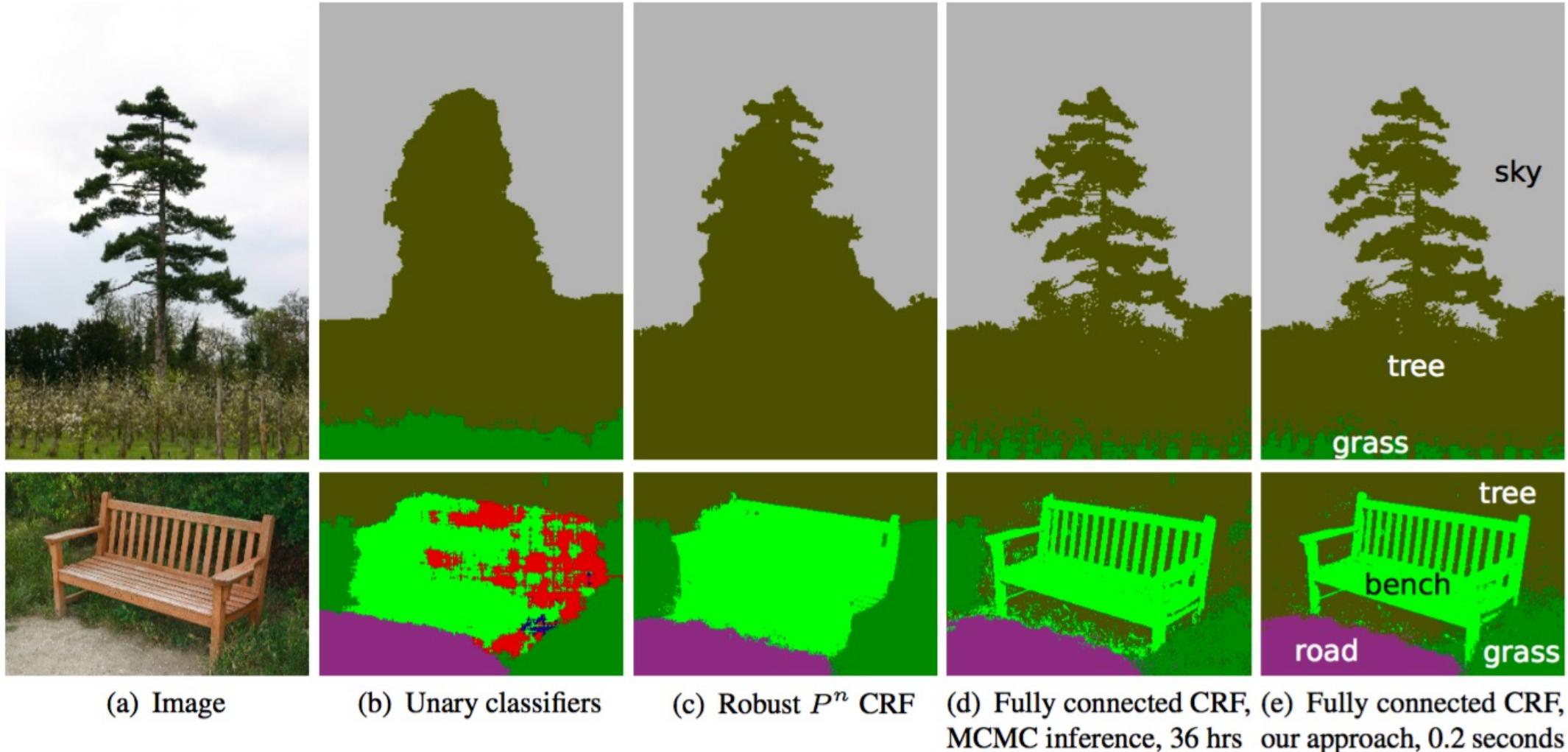
Clasificación
(Probabilidad por clase)

Regresión (x, y, w, h)

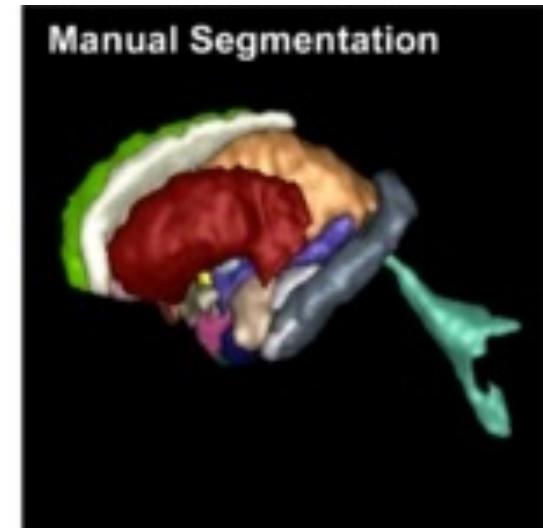
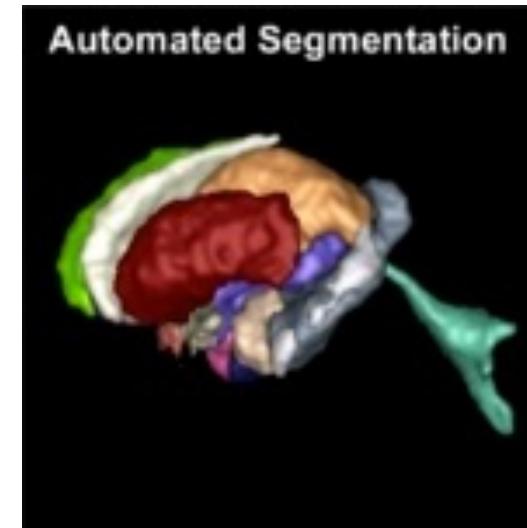
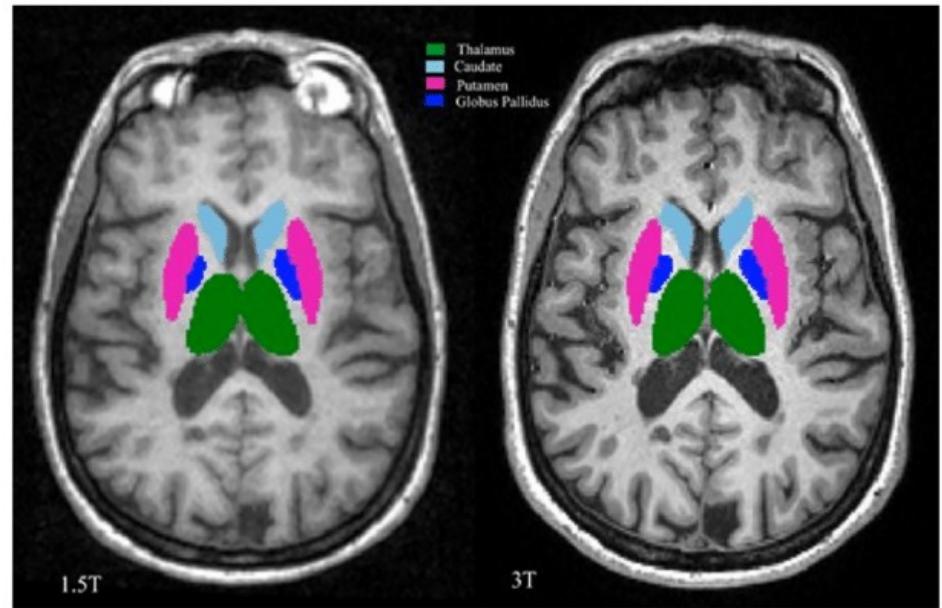


Medidas para evaluar la calidad de la segmentación

Medidas para evaluar la calidad de la segmentación

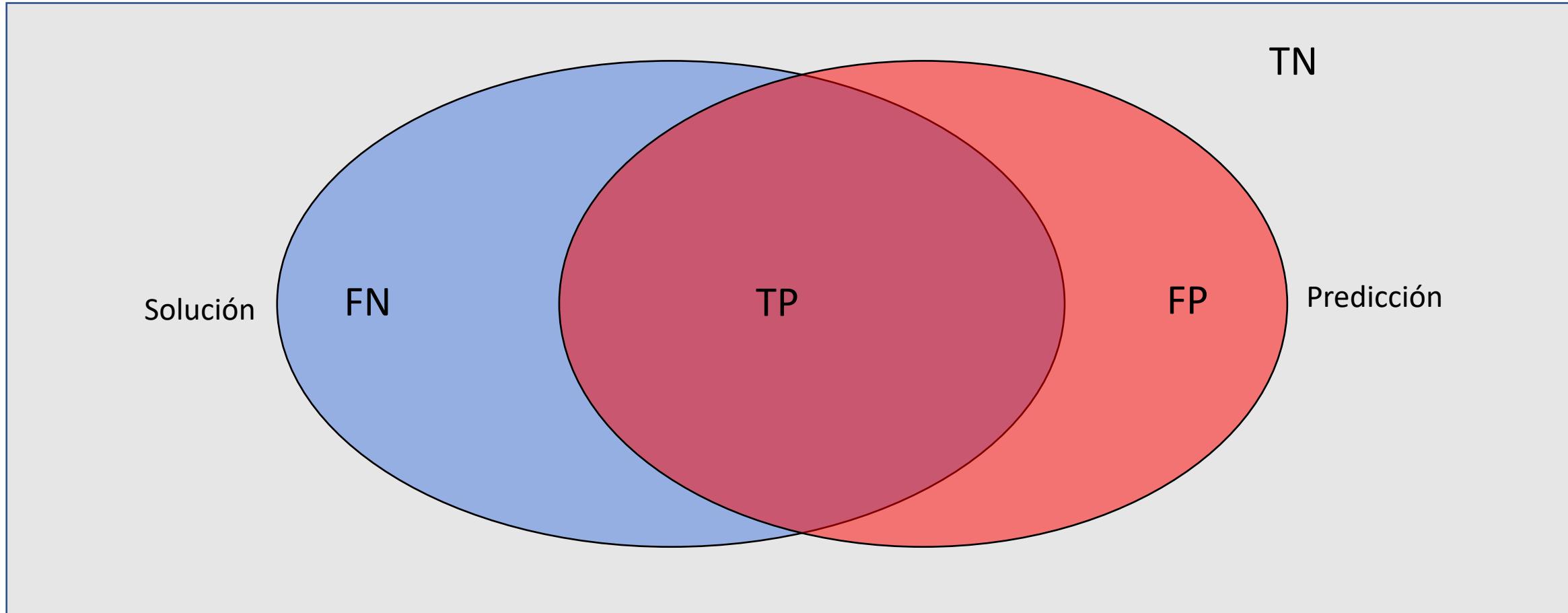


Medidas para evaluar la calidad de la segmentación



¿Intuición?

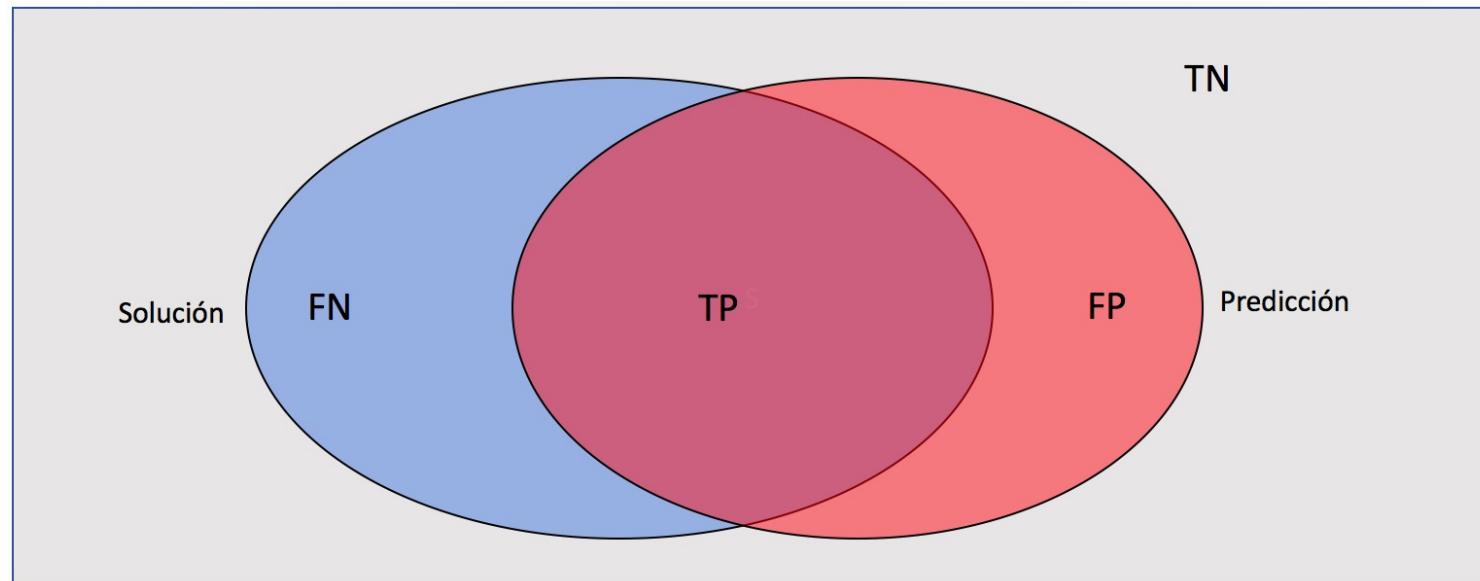
Intuición



Tasa de acierto (accuracy)

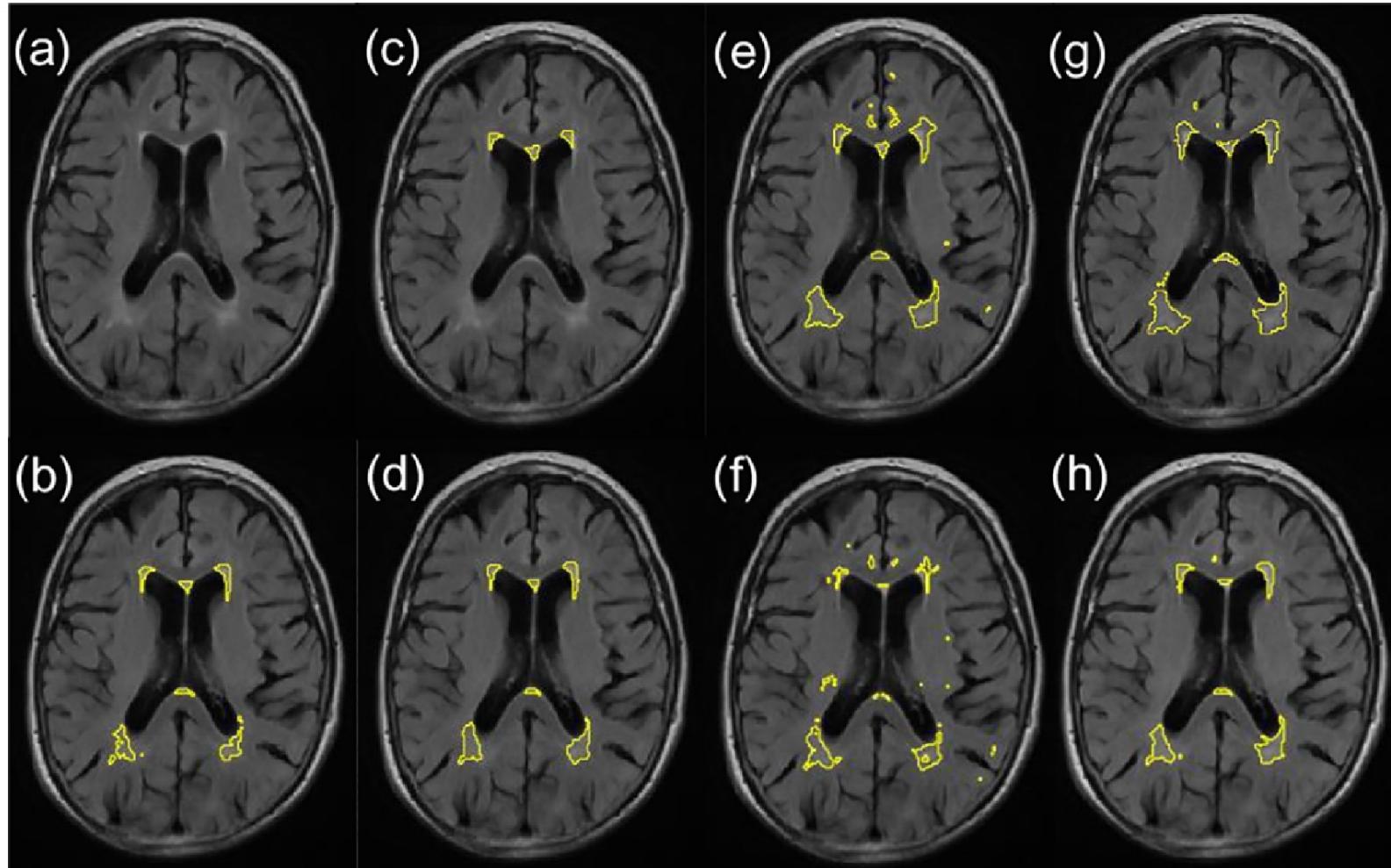
Tasa de acierto sobre el total de los píxeles

$$Accuracy = \frac{TP + TN}{FN + TP + FP + TN}$$



Tasa de acierto (accuracy)

Problema: Requiere datos balanceados



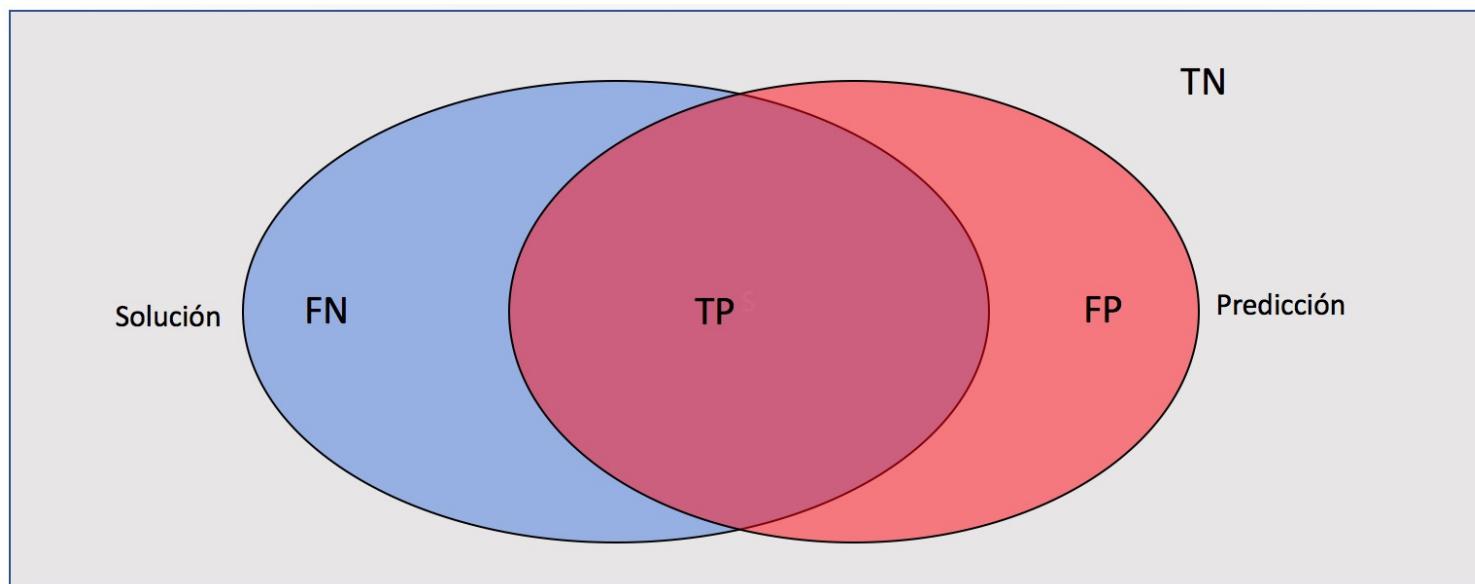
Leuкоараиозис (hiperintensidad en la materia blanca)

Medidas de solapamiento

Coeficiente Dice/ F1-Score

Se aplica en datos binarios

$$Dice = \frac{2 | Solución \cap Predicción |}{|Solución| + |Predicción|} = \frac{2 TP}{FN + 2 TP + FP}$$

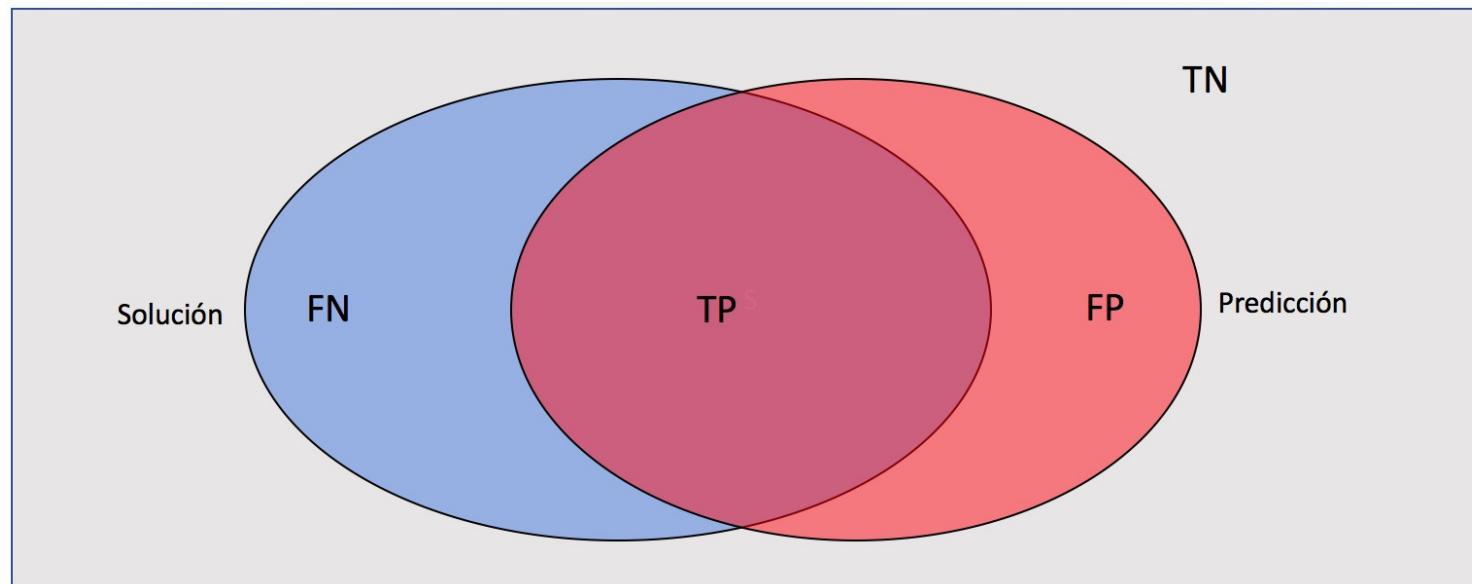


También suele usarse como función de pérdida!

Coeficiente Jaccard / IoU (Intersection over union)

Se aplica en datos binarios

$$Jaccard = \frac{|Solución \cap Predicción|}{|Solución \cup Predicción|} = \frac{TP}{FN + TP + FP}$$



Relación entre Dice/F1 y Jaccard/IoU

$$Jaccard = \frac{Dice}{2 - Dice}$$

- En general, Jaccard tiende a penalizar las malas clasificaciones más que Dice en términos cuantitativos.
- Dice y Jaccard están correlacionados positivamente

Soft Dice as a loss function

(Milletari et al, 2016)

$$Dice = \frac{2 |A \cap B|}{|A| + |B|}$$

$$Loss\ Soft\ Dice = 1 - Dice$$

$$\begin{bmatrix} 0.01 & 0.03 & 0.02 & 0.02 \\ 0.05 & 0.12 & 0.09 & 0.07 \\ 0.89 & 0.85 & 0.88 & 0.91 \\ 0.99 & 0.97 & 0.95 & 0.97 \end{bmatrix} \text{ prediction}$$

$$\begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{bmatrix} \text{ target}$$

$$|A \cap B| = \begin{bmatrix} 0.01 & 0.03 & 0.02 & 0.02 \\ 0.05 & 0.12 & 0.09 & 0.07 \\ 0.89 & 0.85 & 0.88 & 0.91 \\ 0.99 & 0.97 & 0.95 & 0.97 \end{bmatrix} * \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{bmatrix} \text{ prediction}$$

$$\xrightarrow{\text{element-wise multiply}} \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0.89 & 0.85 & 0.88 & 0.91 \\ 0.99 & 0.97 & 0.95 & 0.97 \end{bmatrix} \xrightarrow{\text{sum}} 7.41$$

$$|A| = \begin{bmatrix} 0.01 & 0.03 & 0.02 & 0.02 \\ 0.05 & 0.12 & 0.09 & 0.07 \\ 0.89 & 0.85 & 0.88 & 0.91 \\ 0.99 & 0.97 & 0.95 & 0.97 \end{bmatrix}^2 \text{ (optional)} \xrightarrow{\text{sum}} 7.82$$

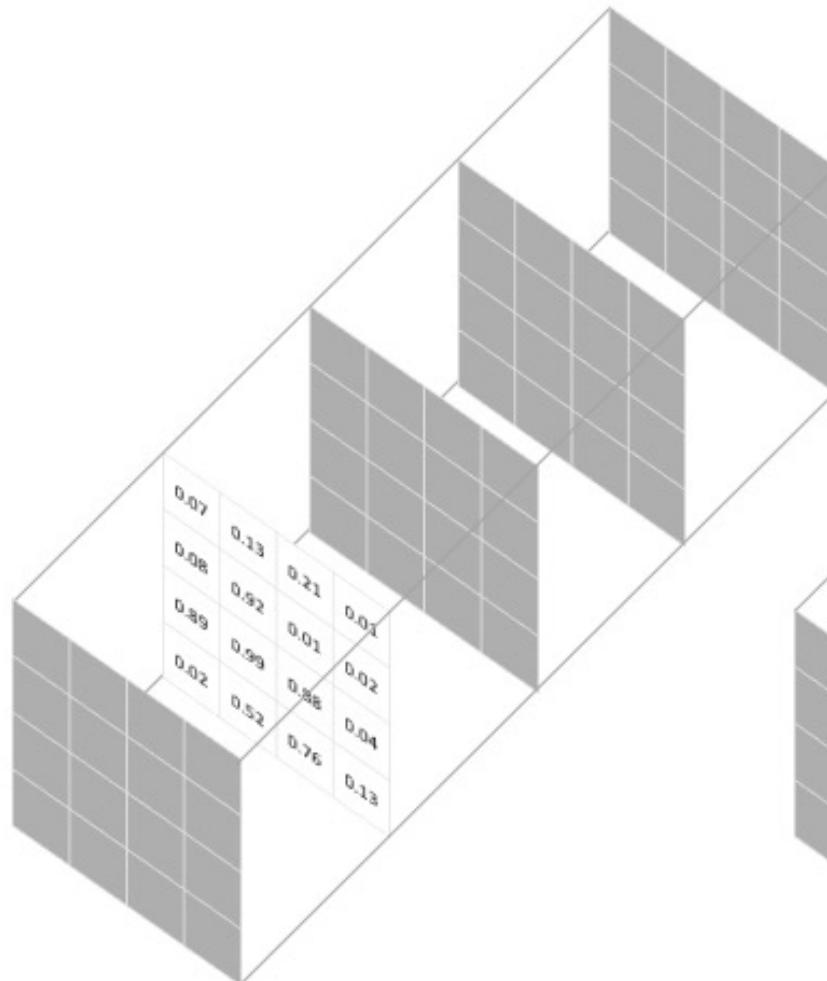
$$|B| = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{bmatrix}^2 \text{ (optional)} \xrightarrow{\text{sum}} 8$$

$$Dice = \frac{2 * 7.41}{7.82 + 8} = 0.936$$

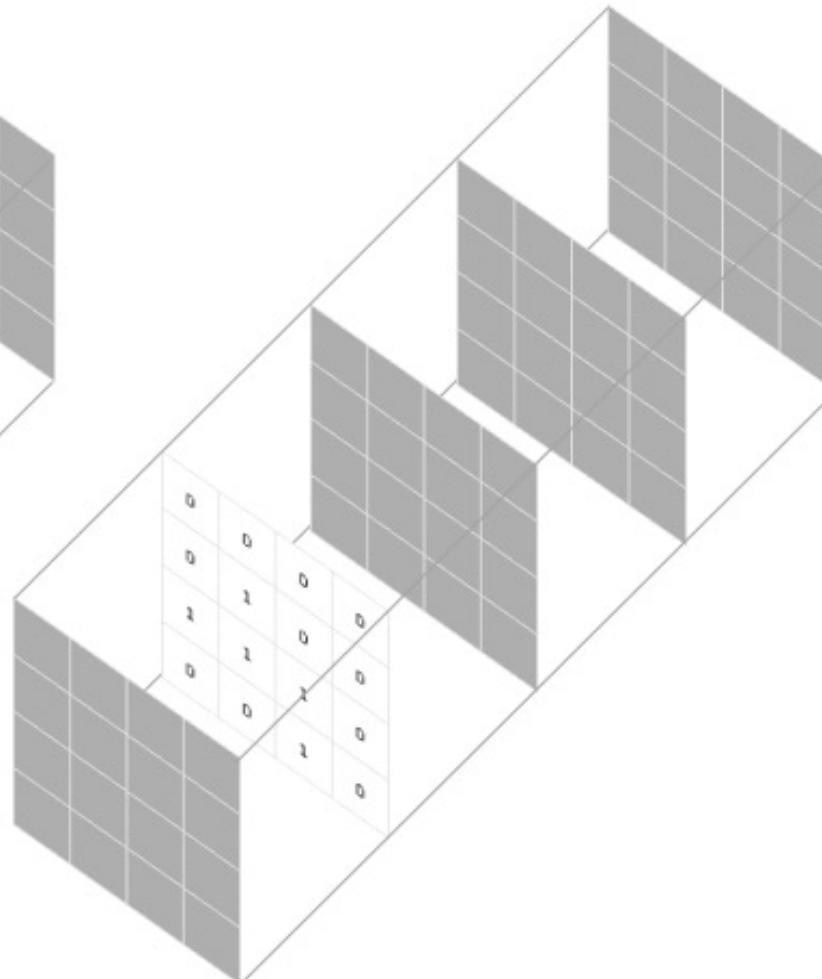
$$Loss\ Soft\ Dice = 1 - 0.936 = 0.064$$

Soft Dice as a loss function

Source: <https://www.jeremyjordan.me/semantic-segmentation/>



Prediction for a selected class



Target for the corresponding class

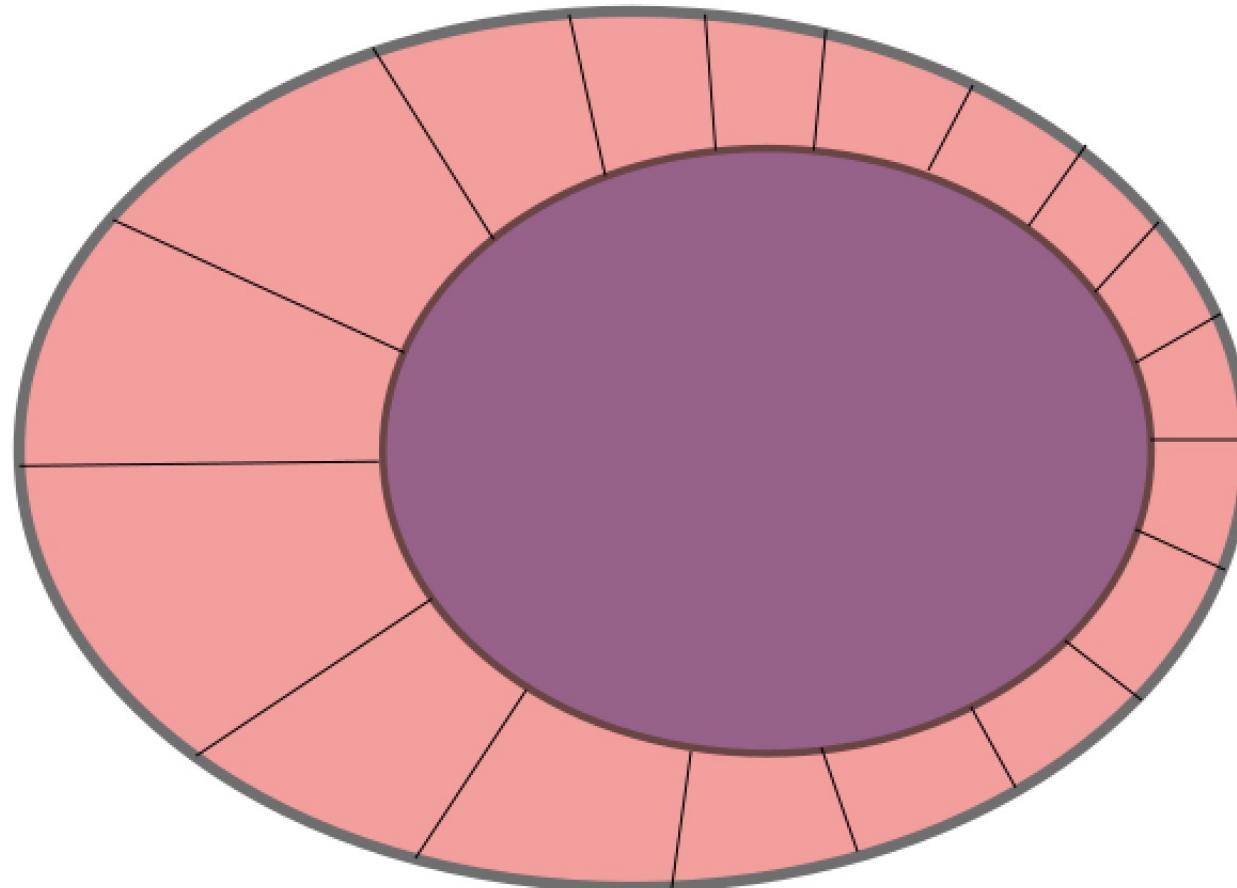
Soft Dice coefficient is calculated for each class mask

$$1 - \frac{2 \sum_{pixels} y_{true} y_{pred}}{\sum_{pixels} y_{true}^2 + \sum_{pixels} y_{pred}^2}$$

This scoring is repeated over all classes and averaged

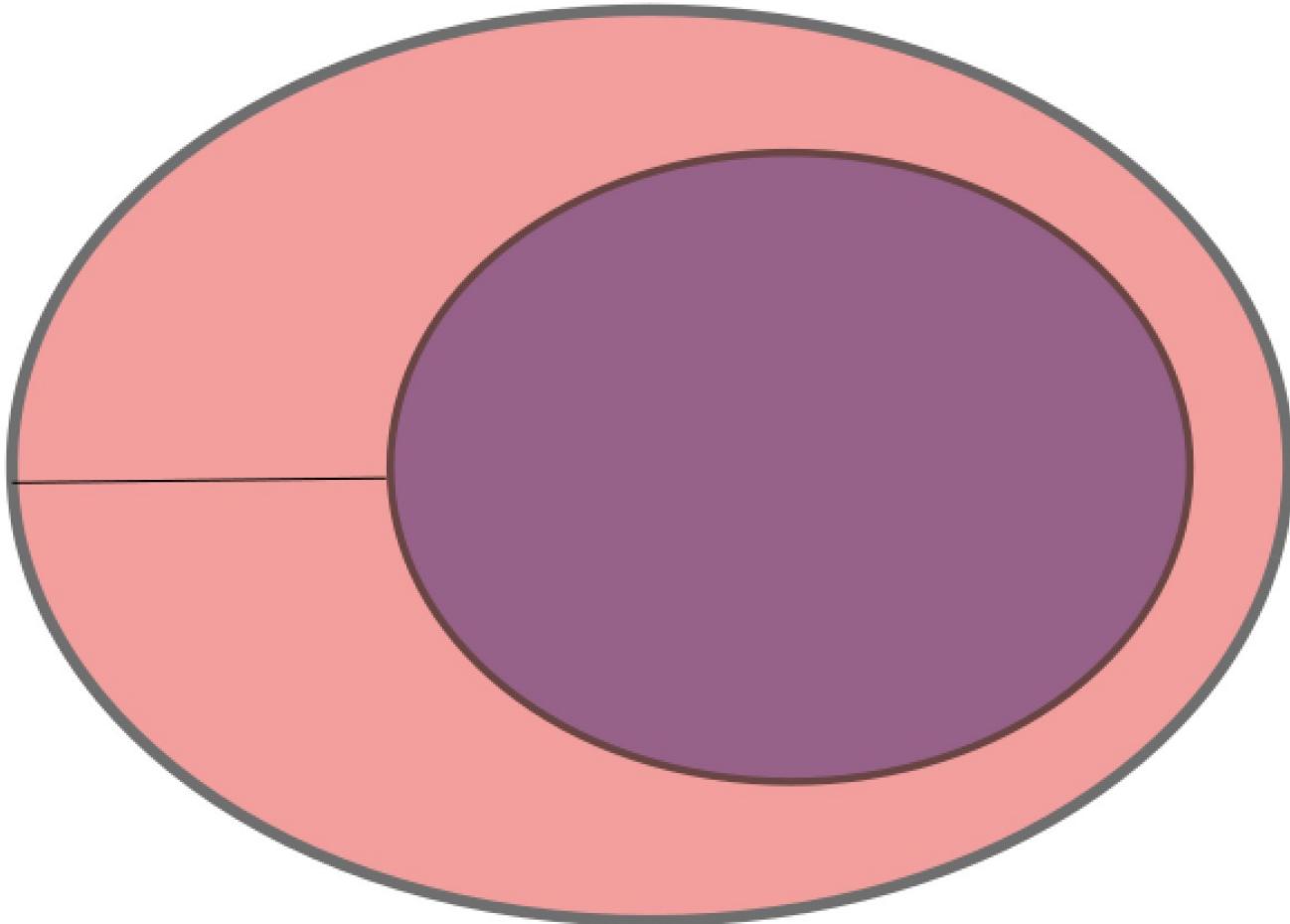
Medidas distancia entre contornos

Distancia media entre contornos



Distancia de Haussdorf

(máxima distancia entre contornos)



Distancia de Haussdorf

2

Kamnitsas, Bai, Ferrante, McDonagh, Sinclair, et al.

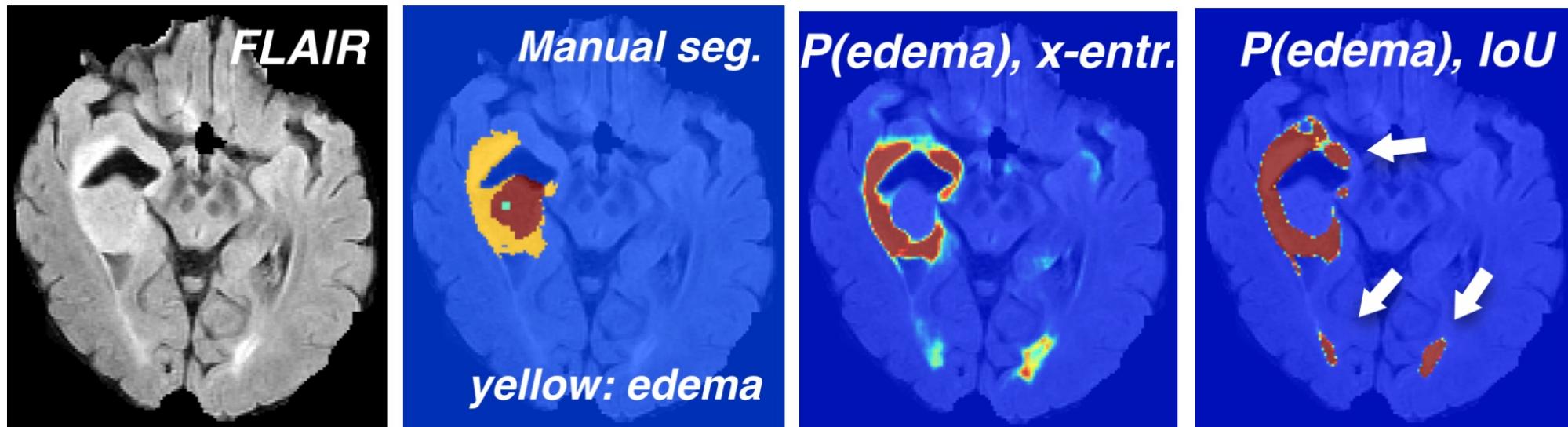
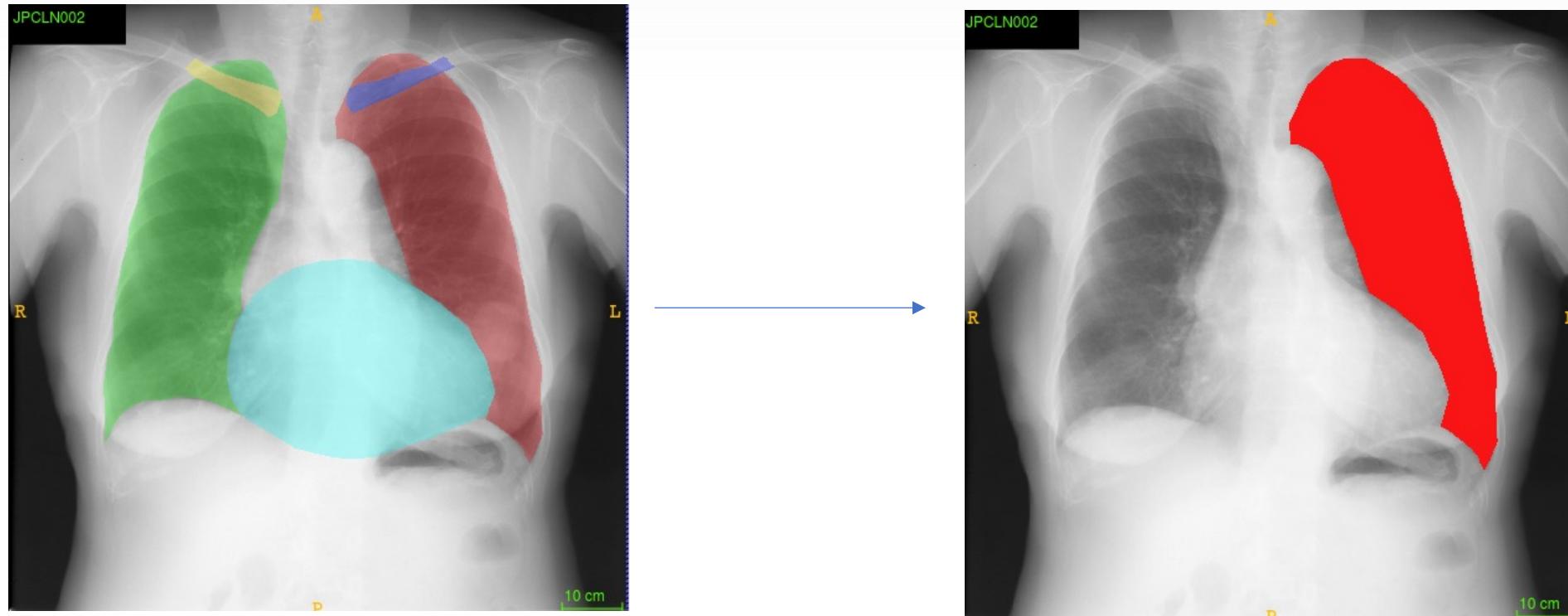


Fig. 1: Left to right: FLAIR; manual annotation of a BRATS'17 subject, where yellow depicts oedema surrounding tumour core; confidence of a CNN predicting oedema, trained with cross-entropy or IoU loss. Although overall performance is similar, training with IoU (or Dice, not shown) loss alters the CNN's behaviour, which tends to output only highly confident predictions, even when false.

Qué hacer en los casos multiclase?

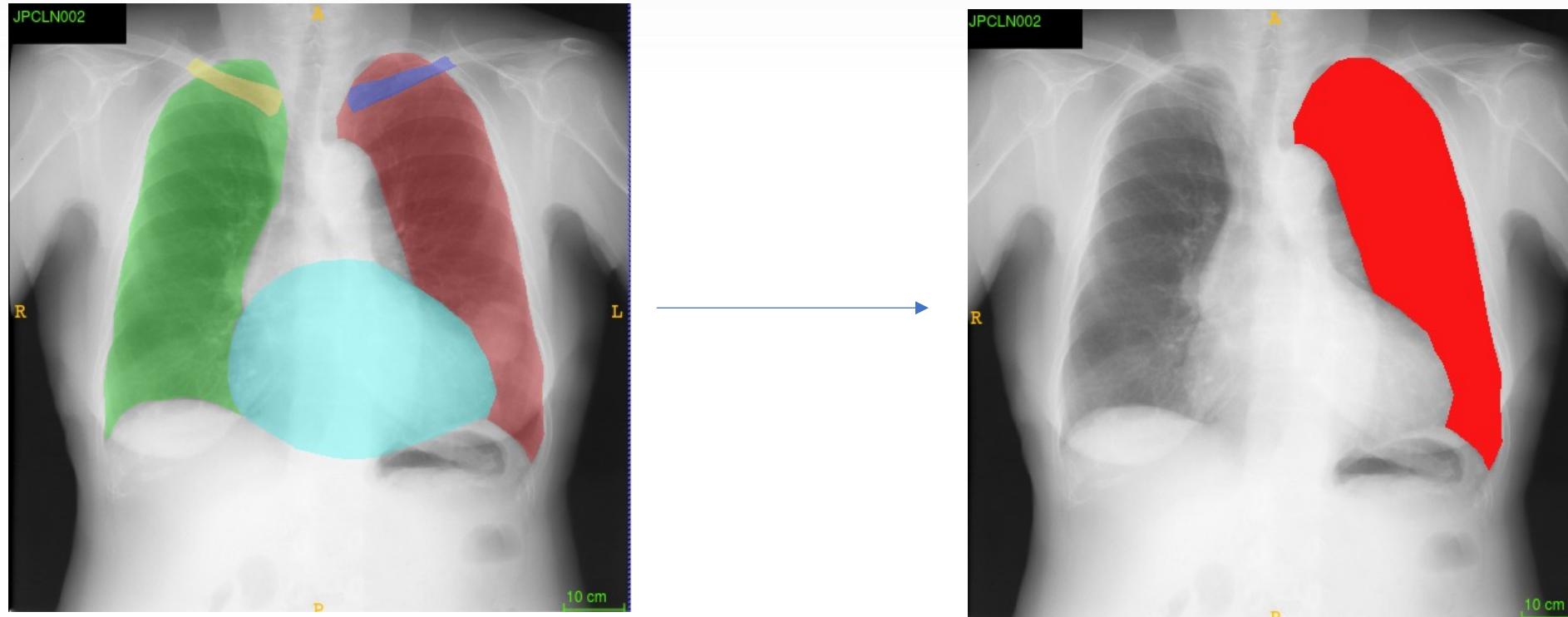
Medidas de calidad en segmentación multiclas



Para cada posible clase $c \in C$, se binariza el problema siguiendo:

- $\text{PredicciónBinarizada}(x) = 1 \quad \text{si} \quad \text{Predicción}(x) = c$
- $\text{PredicciónBinarizada}(x) = 0 \quad \text{si} \quad \text{Predicción}(x) \neq c$

Medidas de calidad en segmentación multiclas



Luego se computa una medida para cada etiqueta $c \in C$ y se analiza el comportamiento por etiqueta y en promedio

Medidas de calidad en Python

```
$ pip install medpy
```

Metric measures ([medpy.metric](#))

This package provides a number of metric measures that e.g. can be used for testing and/or evaluation purposes on two binary masks (i.e. measuring their similarity) or distance between histograms.

Binary metrics ([medpy.metric.binary](#))

Metrics to compare binary objects and classification results.

Compare two binary objects

<code>dc</code> (result, reference)	Dice coefficient
<code>jc</code> (result, reference)	Jaccard coefficient
<code>hd</code> (result, reference[, voxelspacing, ...])	Hausdorff Distance.
<code>asd</code> (result, reference[, voxelspacing, ...])	Average surface distance metric.
<code>assd</code> (result, reference[, voxelspacing, ...])	Average symmetric surface distance.
<code>precision</code> (result, reference)	Precision.
<code>recall</code> (result, reference)	Recall.
<code>sensitivity</code> (result, reference)	Sensitivity.
<code>specificity</code> (result, reference)	Specificity.
<code>true_positive_rate</code> (result, reference)	True positive rate.
<code>true_negative_rate</code> (result, reference)	True negative rate.
<code>positive_predictive_value</code> (result, reference)	Positive predictive value.
<code>ravd</code> (result, reference)	Relative absolute volume difference.

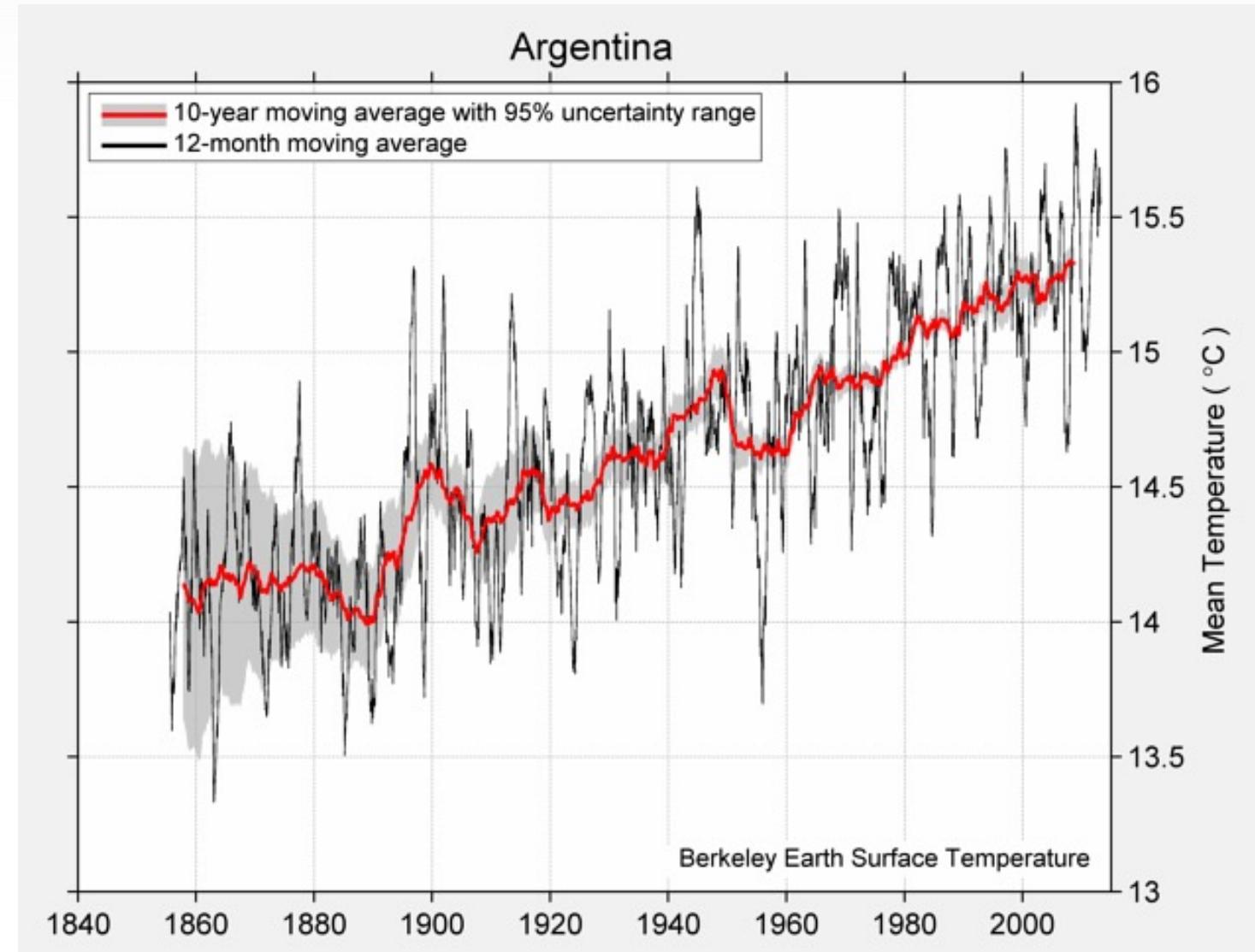
Redes neuronales convolucionales para el procesamiento de series de tiempo

Series de tiempo



Series de tiempo

Temperatura media
anual en Argentina



Fuente: Berkley Earth

Series de tiempo

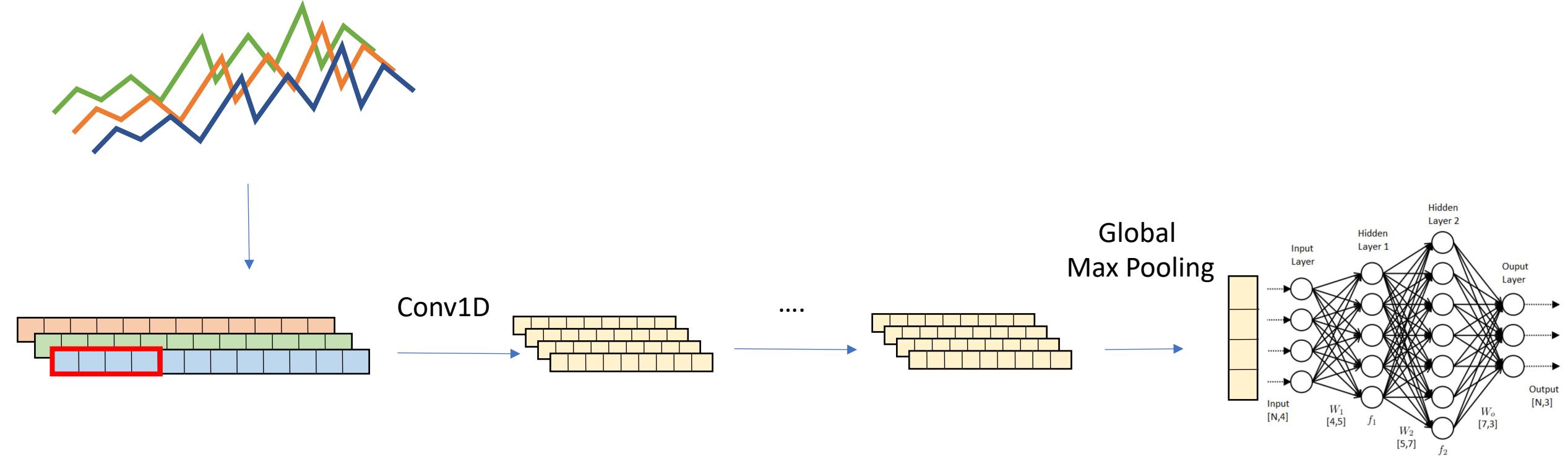
Electrocardiograma



Clasificación de series de tiempo



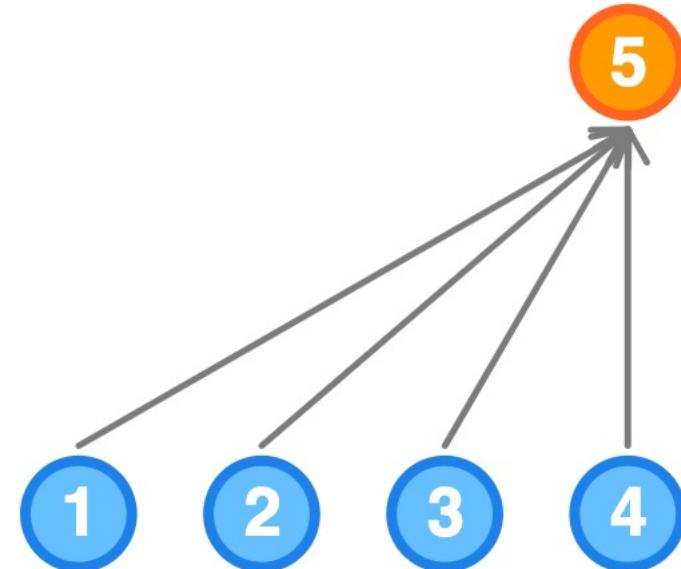
Clasificación de series de tiempo



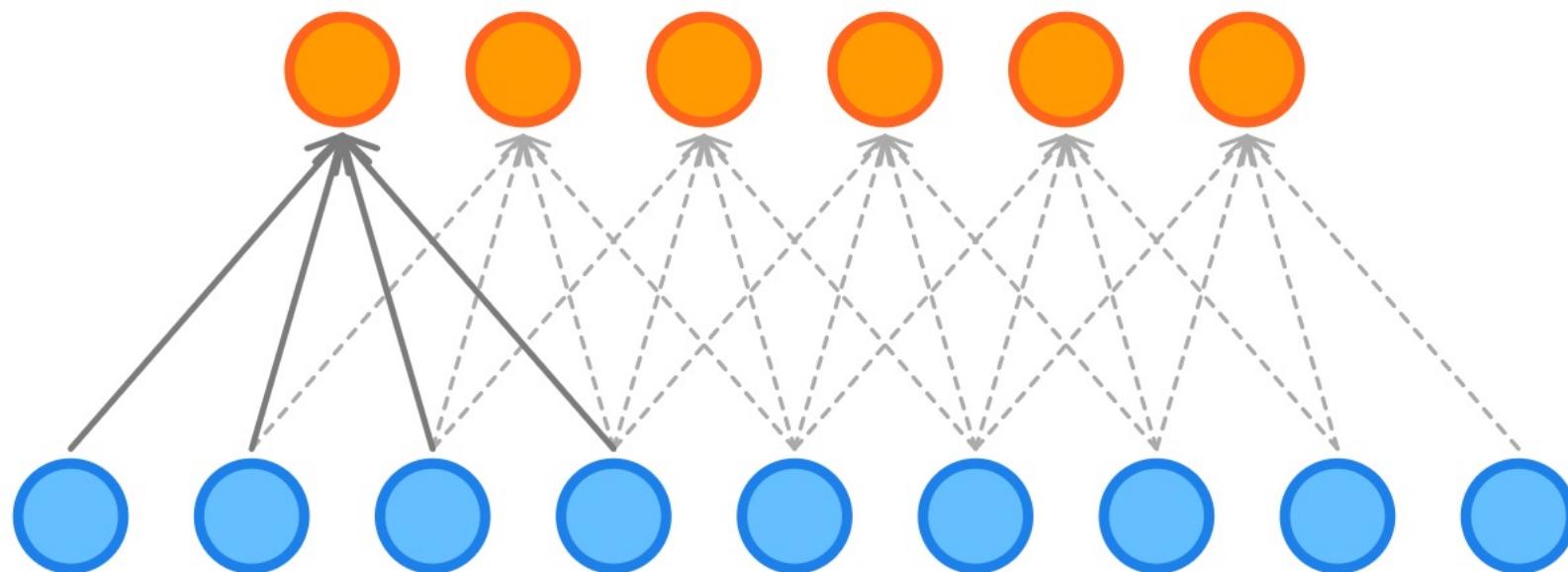
Predicción en series de tiempo



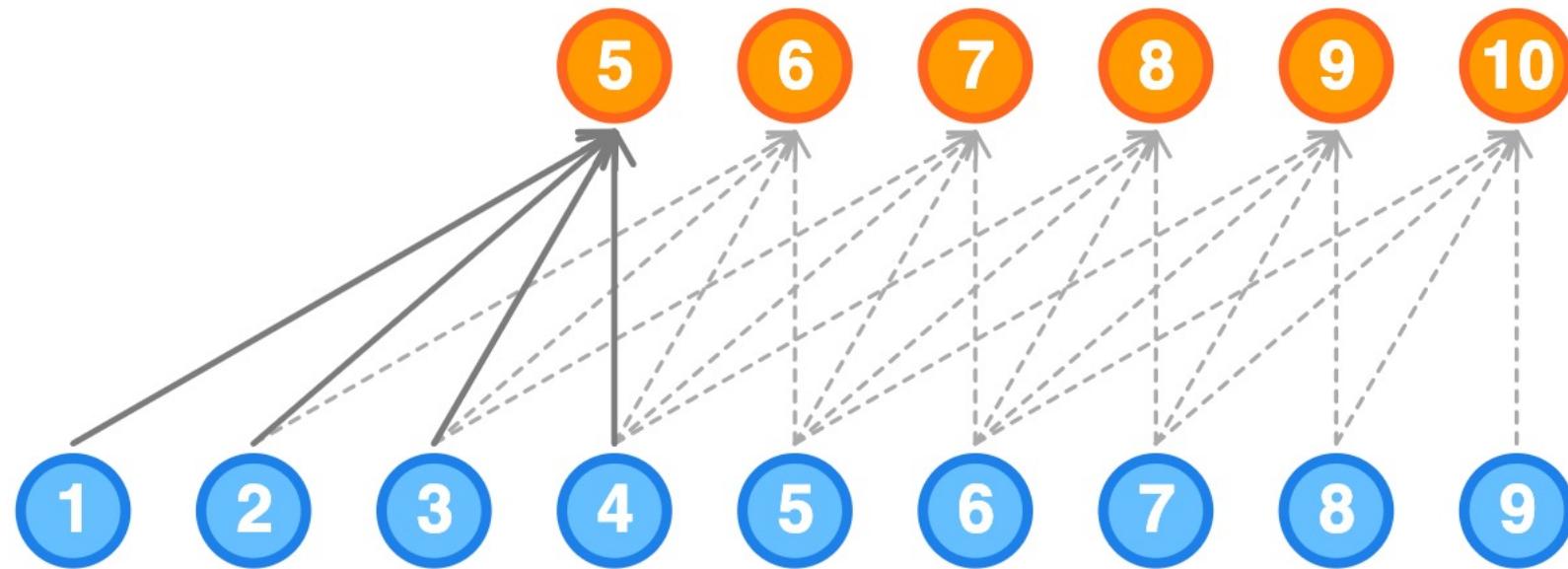
Perceptrón



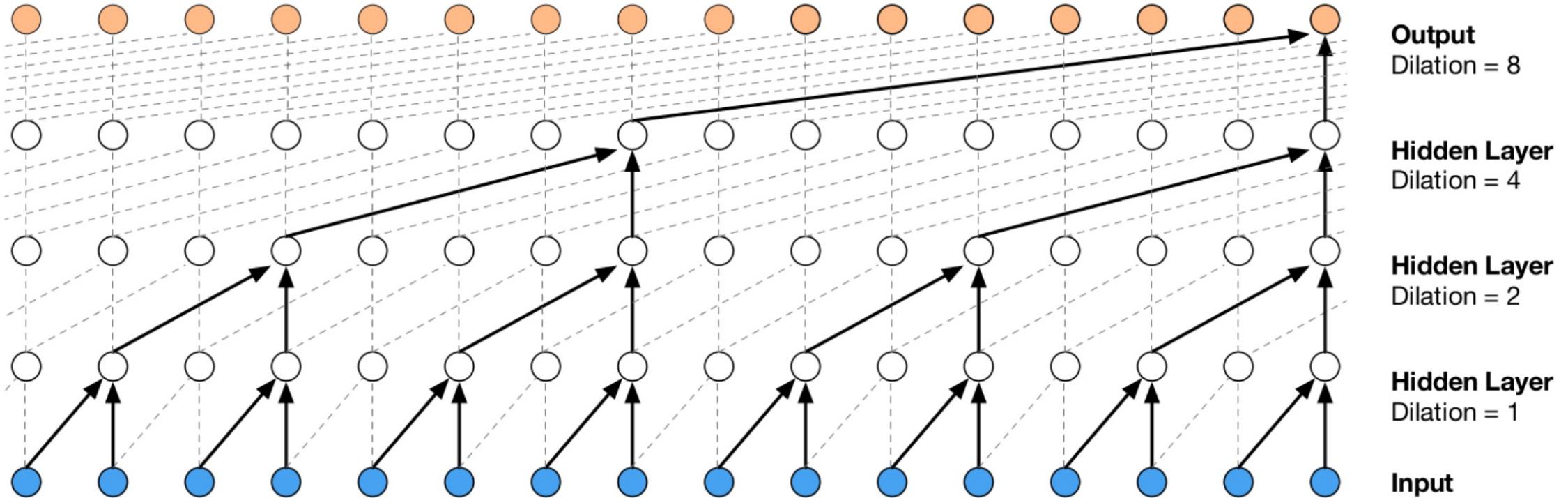
Convolución



Convolución causal



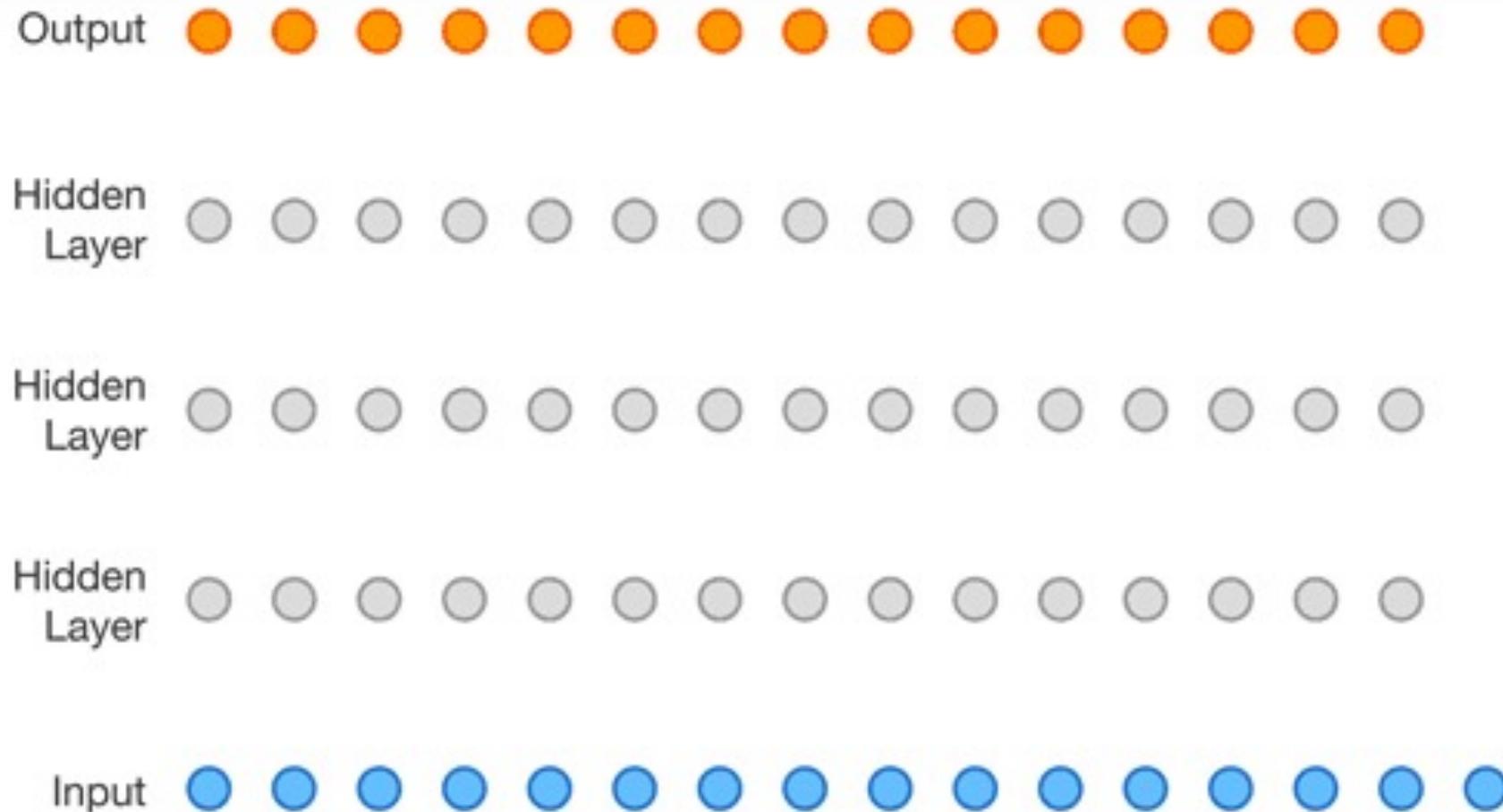
Predicción en series de tiempo



Predicción en series de tiempo: más allá de un paso



Predicción en series de tiempo: más allá de un paso



WaveNet

WAVENET: A GENERATIVE MODEL FOR RAW AUDIO

Aäron van den Oord

Karen Simonyan

Nal Kalchbrenner

Sander Dieleman

Oriol Vinyals

Andrew Senior

Heiga Zen[†]

Alex Graves

Koray Kavukcuoglu

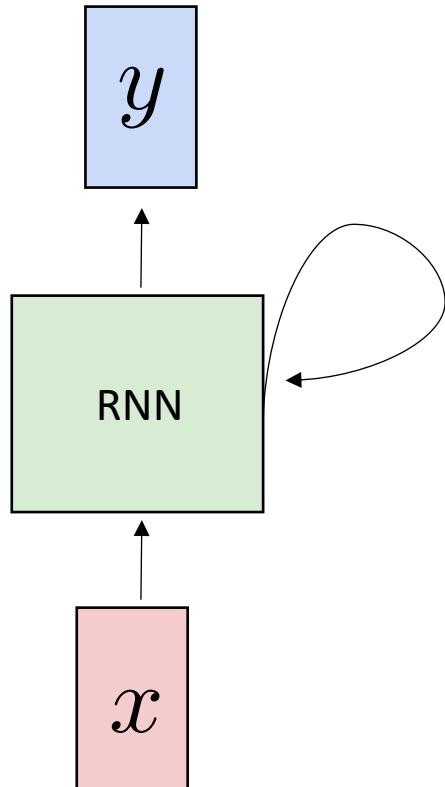
{avdnoord, sedilem, heigazen, simonyan, vinyals, gravesa, nalk, andrewsenior, korayk}@google.com
Google DeepMind, London, UK
† Google, London, UK

ABSTRACT

This paper introduces WaveNet, a deep neural network for generating raw audio waveforms. The model is fully probabilistic and autoregressive, with the predictive distribution for each audio sample conditioned on all previous ones; nonetheless we show that it can be efficiently trained on data with tens of thousands of samples and of audio. When applied to text-to-speech, it yields state-of-the-art results, with listeners rating it as significantly more natural than alternative systems for both English and Chinese. It also generates many different kinds of audio, such as percussive instruments, speech-like sounds, and environmental sounds.

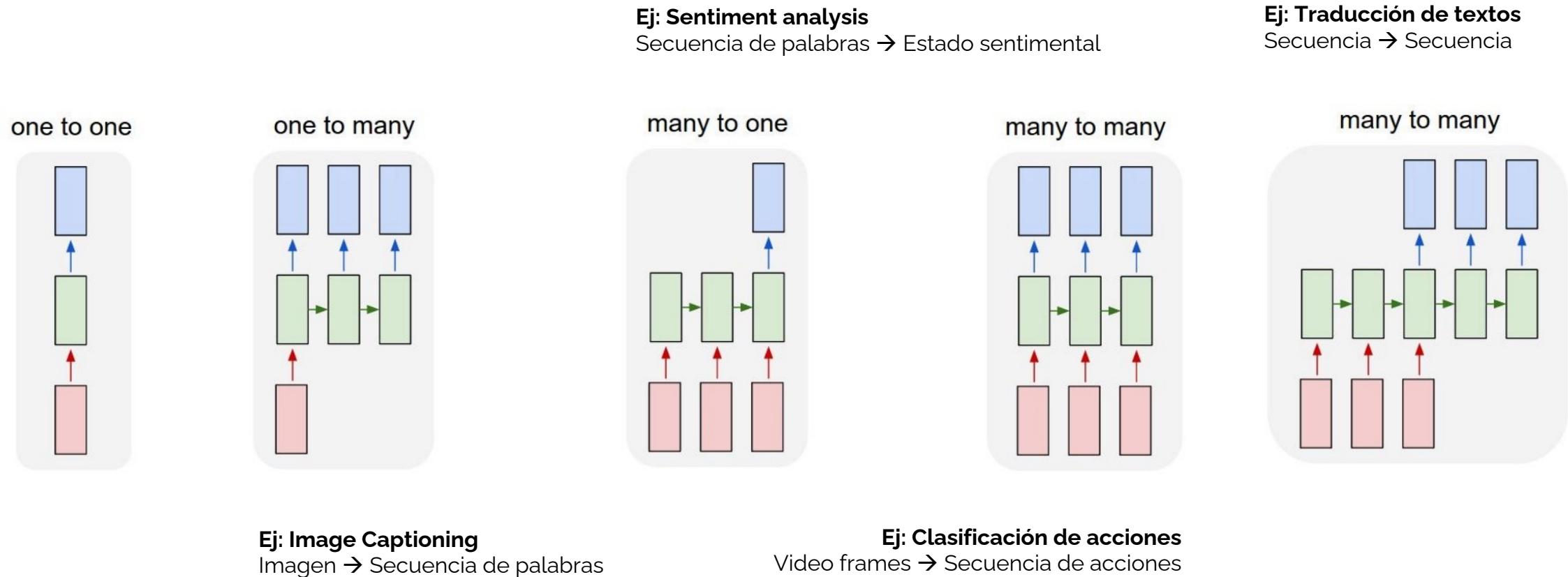
Redes recurrentes

Redes neuronales recurrentes

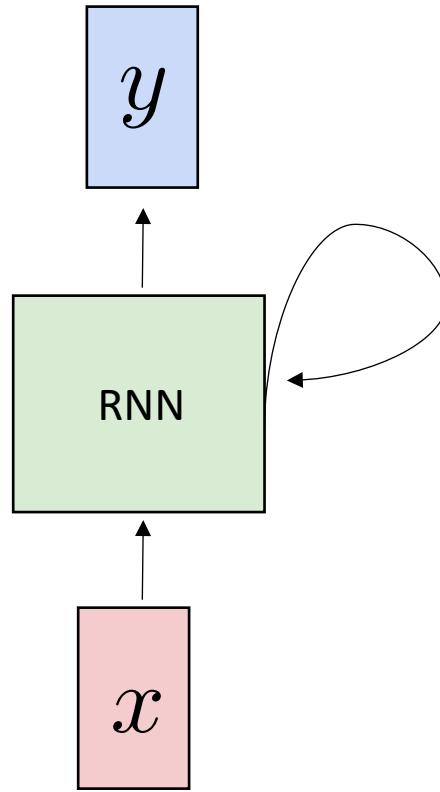


- Redes neuronales diseñadas para procesar datos secuenciales $\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(\tau)}$
- Así como las redes totalmente convolucionales pueden escalar a cualquier tamaño de imagen, las redes recurrentes pueden en principio procesar cualquier longitud de secuencia.
- La clave son los pesos compartidos (weight sharing) a través del tiempo

Redes neuronales recurrentes



Redes neuronales recurrentes



Función parametrizada por W (la misma para todos los instantes t)

$$h_t = f_W(h_{t-1}, x_t)$$

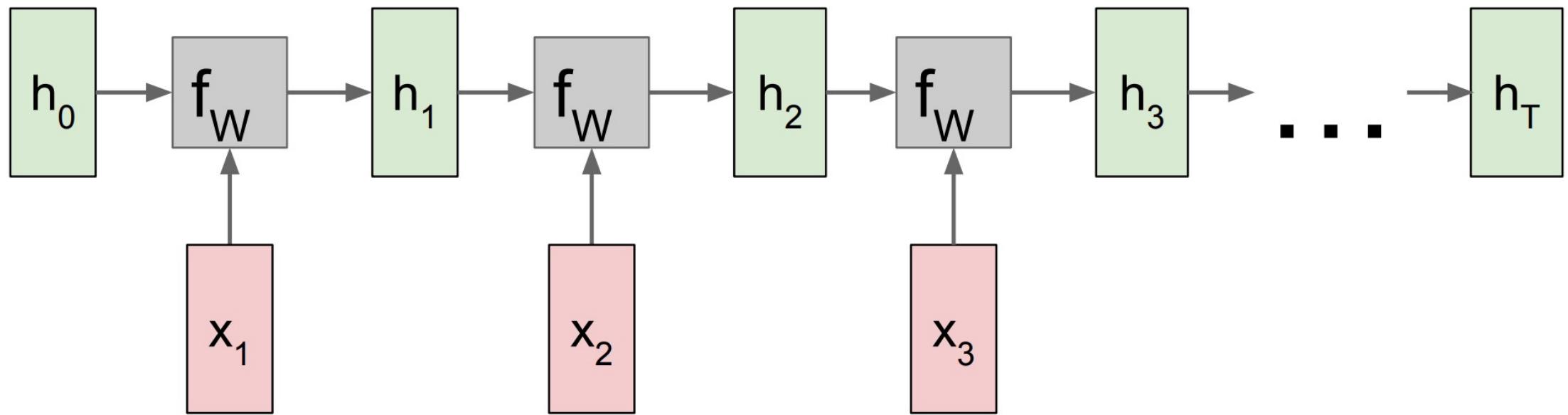
Nuevo Estado Antiguo Estado Entrada

A vertical arrow points downwards from the equation to the mathematical definition below.

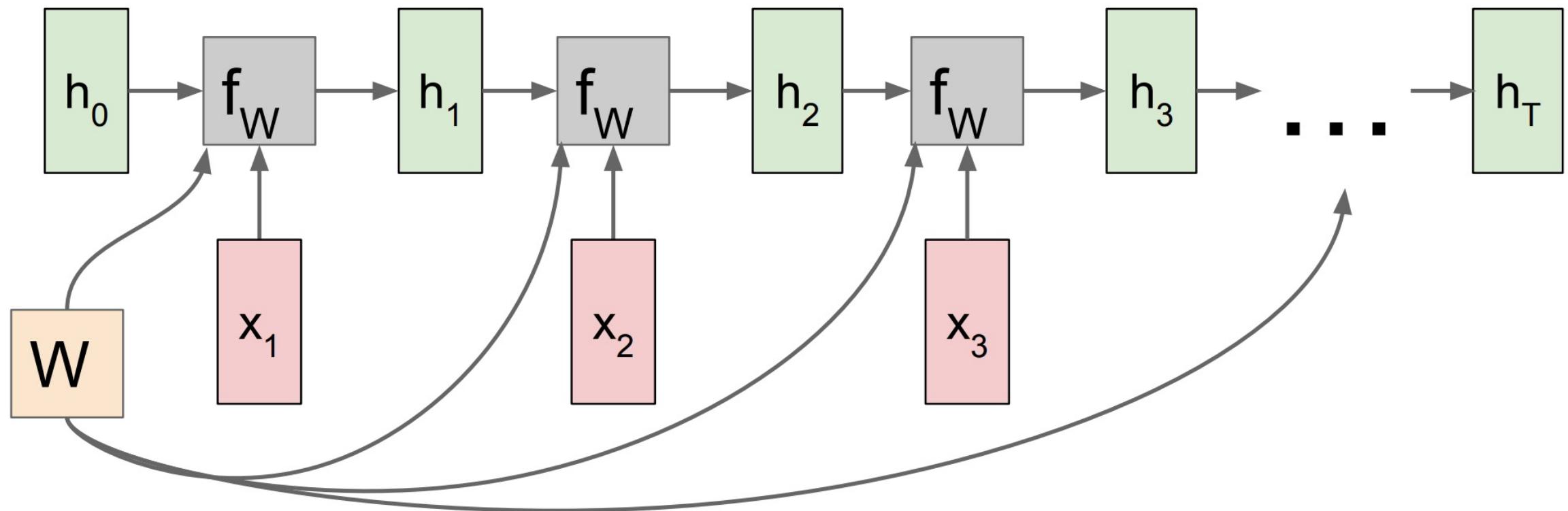
$$h_t = \tanh(W_{hh}h_{t-1} + W_{xh}x_t)$$

$$y_t = W_{hy}h_t$$

Grafo de cómputo



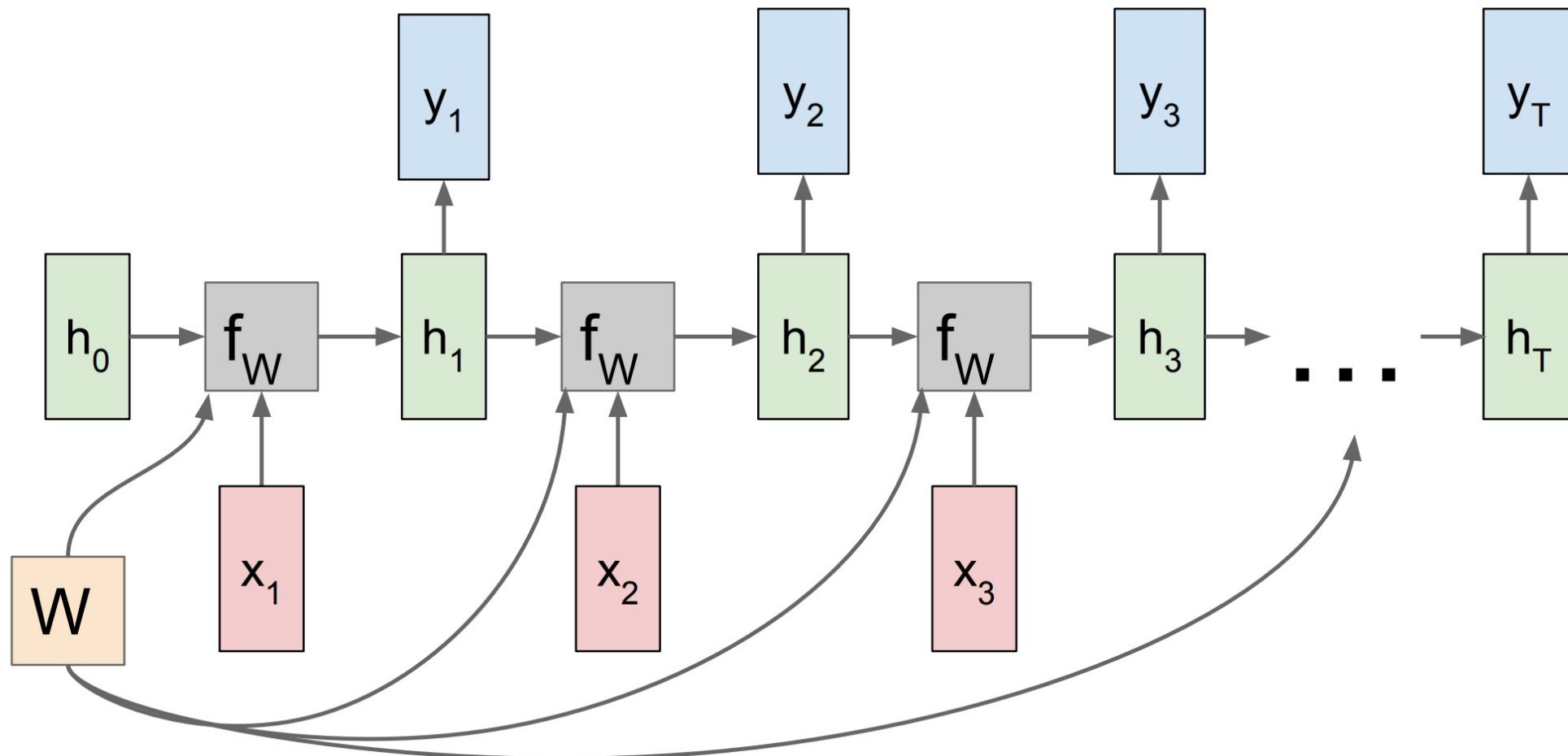
Grafo de cómputo



Retropropagación a través del tiempo

Grafo de cómputo

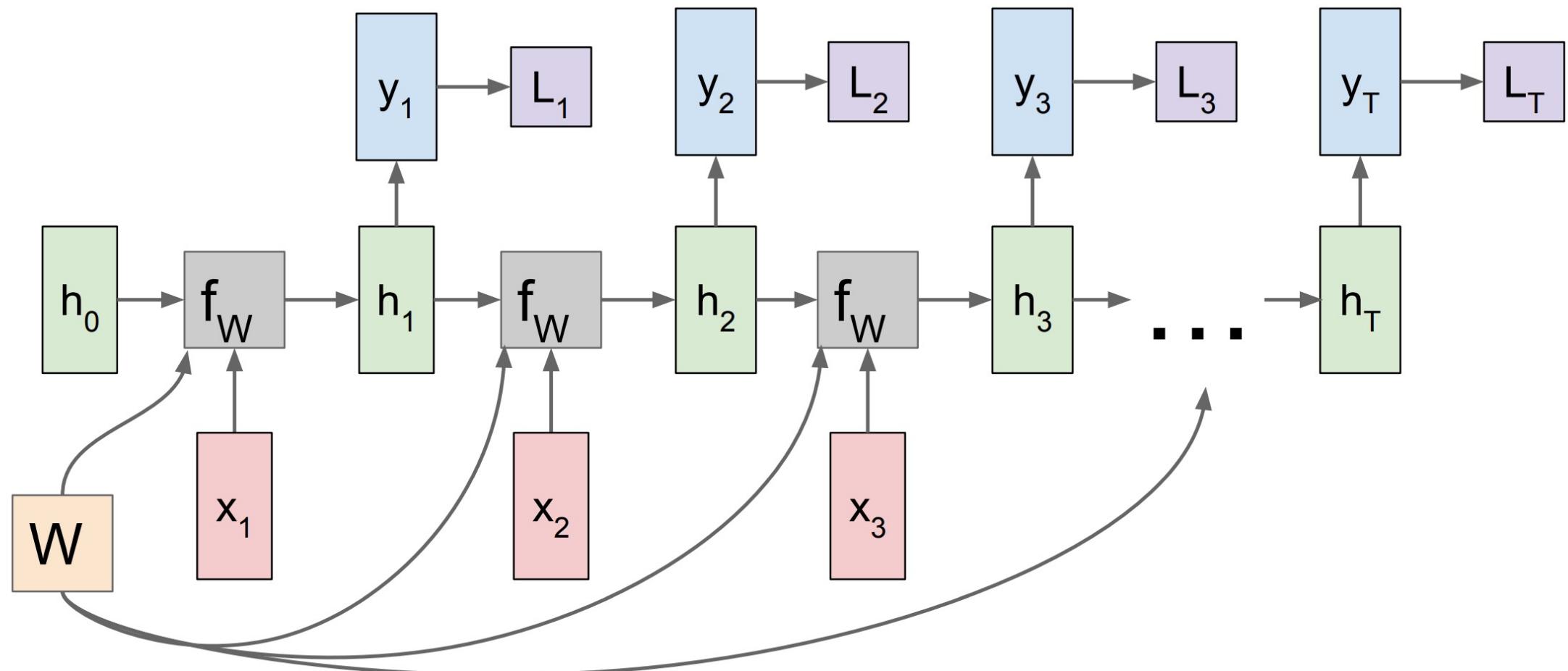
Many to many



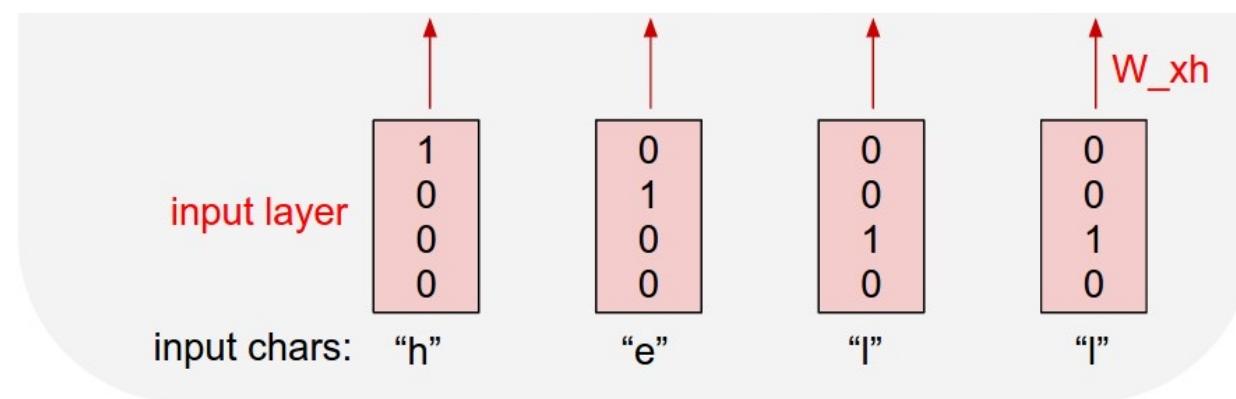
Grafo de cómputo

Many to many

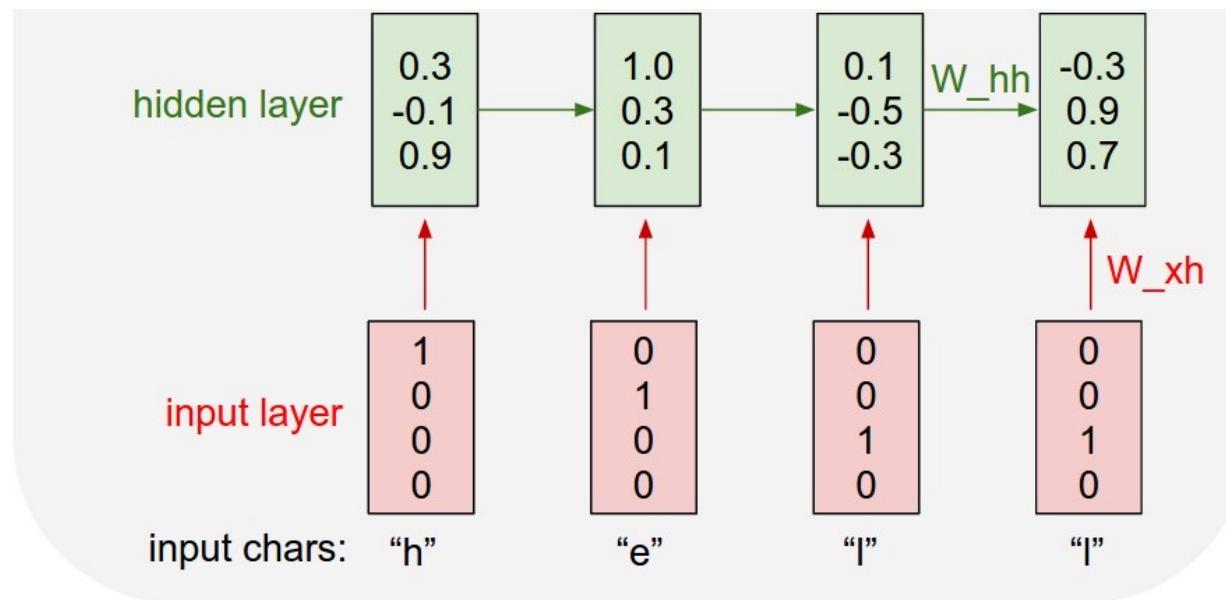
La función de pérdida la computamos como la suma de las L_i



Ejemplo: predicción de caracteres

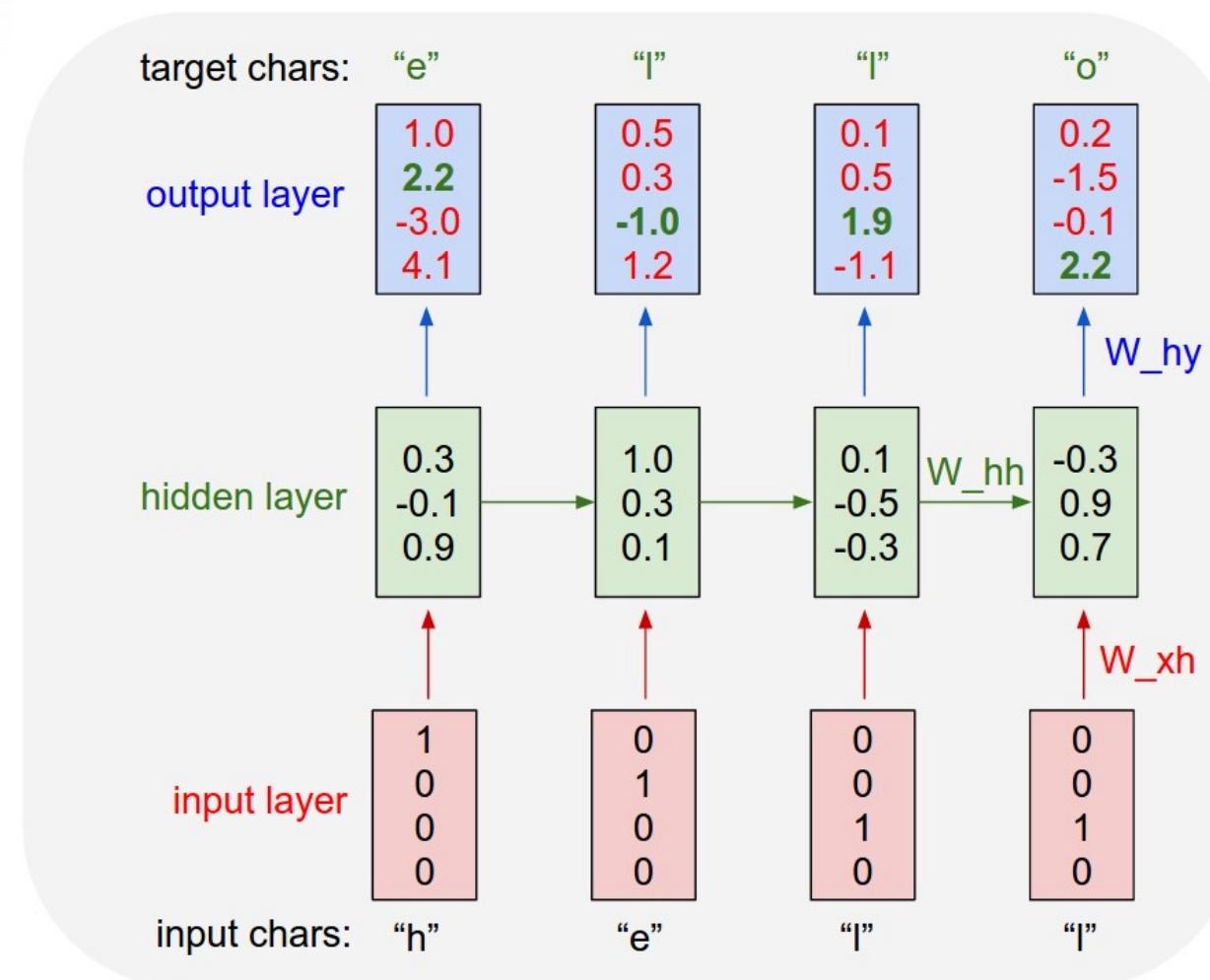


Ejemplo: predicción de caracteres



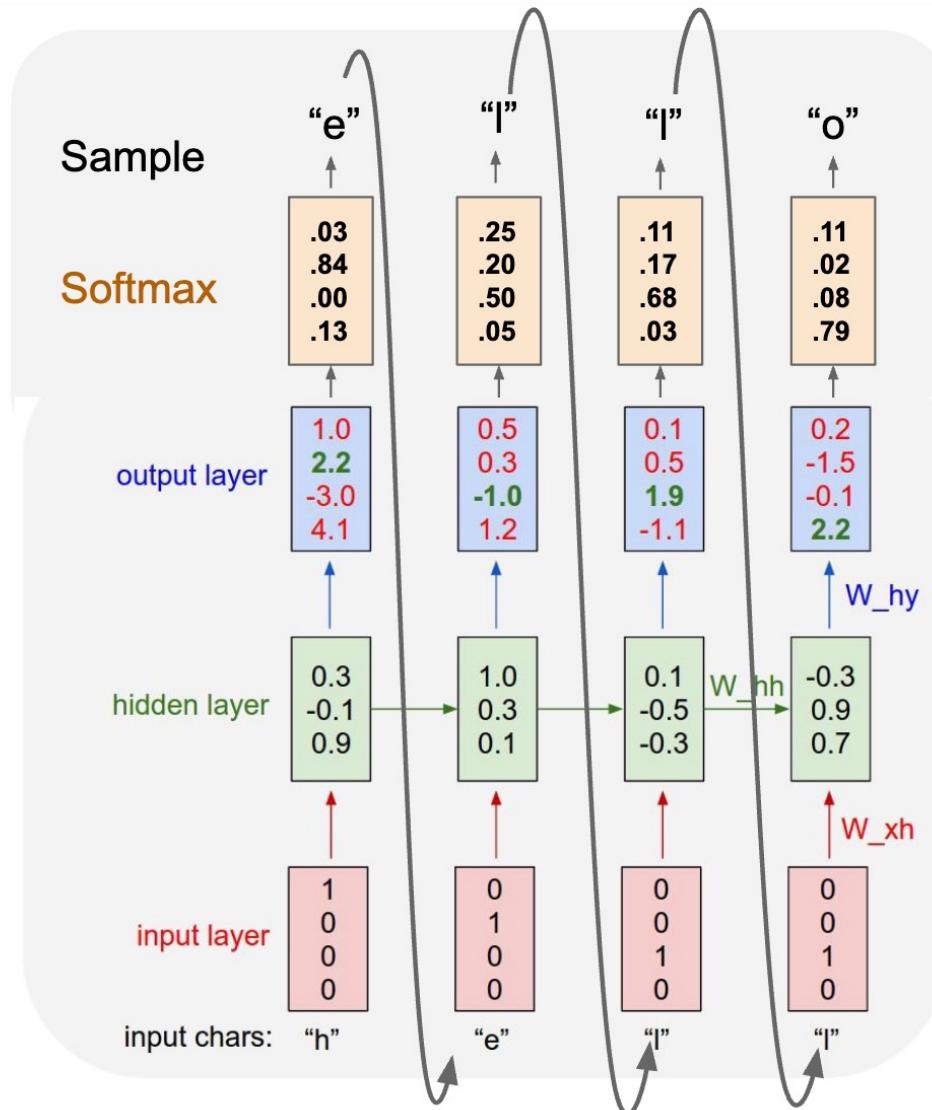
Ejemplo: predicción de caracteres

Vocabulario de 4 posibles caracteres



Ejemplo: predicción de caracteres

Una vez entrenado el modelo, podemos samplear!



Ejemplo: predicción de caracteres

Por ejemplo, un modelo entrenado en Shakespeare

PANDARUS:

Alas, I think he shall be come approached and the day
When little strain would be attain'd into being never fed,
And who is but a chain and subjects of his death,
I should not sleep.

Second Senator:

They are away this miseries, produced upon my soul,
Breaking and strongly should be buried, when I perish
The earth and thoughts of many states.

DUKE VINCENTIO:

Well, your wit is in the care of side and that.

Second Lord:

They would be ruled after this chamber, and
my fair nues begun out of the fact, to be conveyed,
Whose noble souls I'll have the heart of the wars.

Clown:

Come, sir, I will make did behold your worship.

VIOLA:

I'll drink it.

Ejemplo: predicción de caracteres

Por ejemplo, un modelo entrenado en papers matemáticos

For $\bigoplus_{n=1,\dots,m} \mathcal{L}_{m,n} = 0$, hence we can find a closed subset \mathcal{H} in \mathcal{H} and any sets \mathcal{F} on X , U is a closed immersion of S , then $U \rightarrow T$ is a separated algebraic space.

Proof. Proof of (1). It also start we get

$$S = \text{Spec}(R) = U \times_X U \times_X U$$

and the comparicoly in the fibre product covering we have to prove the lemma generated by $\coprod Z \times_U U \rightarrow V$. Consider the maps M along the set of points Sch_{fppf} and $U \rightarrow U$ is the fibre category of S in U in Section, ?? and the fact that any U affine, see Morphisms, Lemma ???. Hence we obtain a scheme S and any open subset $W \subset U$ in $\text{Sh}(G)$ such that $\text{Spec}(R') \rightarrow S$ is smooth or an

$$U = \bigcup U_i \times_{S_i} U_i$$

which has a nonzero morphism we may assume that f_i is of finite presentation over S . We claim that $\mathcal{O}_{X,x}$ is a scheme where $x, x', s'' \in S'$ such that $\mathcal{O}_{X,x'} \rightarrow \mathcal{O}'_{X',x'}$ is separated. By Algebra, Lemma ?? we can define a map of complexes $\text{GL}_{S'}(x'/S'')$ and we win. \square

To prove study we see that $\mathcal{F}|_U$ is a covering of \mathcal{X}' , and \mathcal{T}_i is an object of $\mathcal{F}_{X/S}$ for $i > 0$ and \mathcal{F}_p exists and let \mathcal{F}_i be a presheaf of \mathcal{O}_X -modules on \mathcal{C} as a \mathcal{F} -module. In particular $\mathcal{F} = U/\mathcal{F}$ we have to show that

$$\widetilde{\mathcal{M}}^\bullet = \mathcal{I}^\bullet \otimes_{\text{Spec}(k)} \mathcal{O}_{S,s} - i_X^{-1} \mathcal{F}$$

is a unique morphism of algebraic stacks. Note that

$$\text{Arrows} = (\text{Sch}/S)_{fppf}^{\text{opp}}, (\text{Sch}/S)_{fppf}$$

and

$$V = \Gamma(S, \mathcal{O}) \longrightarrow (U, \text{Spec}(A))$$

is an open subset of X . Thus U is affine. This is a continuous map of X is the inverse, the groupoid scheme S .

Proof. See discussion of sheaves of sets. \square

The result for prove any open covering follows from the less of Example ???. It may replace S by $X_{\text{spaces},\text{étale}}$ which gives an open subspace of X and T equal to S_{Zar} , see Descent, Lemma ???. Namely, by Lemma ?? we see that R is geometrically regular over S .

Lemma 0.1. Assume (3) and (3) by the construction in the description.

Suppose $X = \lim |X|$ (by the formal open covering X and a single map $\underline{\text{Proj}}_X(\mathcal{A}) = \text{Spec}(B)$ over U compatible with the complex

$$\text{Set}(\mathcal{A}) = \Gamma(X, \mathcal{O}_{X,\mathcal{O}_X}).$$

When in this case of to show that $\mathcal{Q} \rightarrow \mathcal{C}_{Z/X}$ is stable under the following result in the second conditions of (1), and (3). This finishes the proof. By Definition ?? (without element is when the closed subschemes are catenary. If T is surjective we may assume that T is connected with residue fields of S . Moreover there exists a closed subspace $Z \subset X$ of X where U in X' is proper (some defining as a closed subset of the uniqueness it suffices to check the fact that the following theorem

(1) f is locally of finite type. Since $S = \text{Spec}(R)$ and $Y = \text{Spec}(R)$.

Proof. This is form all sheaves of sheaves on X . But given a scheme U and a surjective étale morphism $U \rightarrow X$. Let $U \cap U = \coprod_{i=1,\dots,n} U_i$ be the scheme X over S at the schemes $X_i \rightarrow X$ and $U = \lim_i X_i$. \square

The following lemma surjective restrocomposes of this implies that $\mathcal{F}_{x_0} = \mathcal{F}_{x_0} = \mathcal{F}_{X,\dots,0}$.

Lemma 0.2. Let X be a locally Noetherian scheme over S , $E = \mathcal{F}_{X/S}$. Set $\mathcal{I} = \mathcal{J}_1 \subset \mathcal{I}'_n$. Since $\mathcal{I}^n \subset \mathcal{I}^n$ are nonzero over $i_0 \leq p$ is a subset of $\mathcal{J}_{n,0} \circ \overline{A}_2$ works.

Lemma 0.3. In Situation ???. Hence we may assume $q' = 0$.

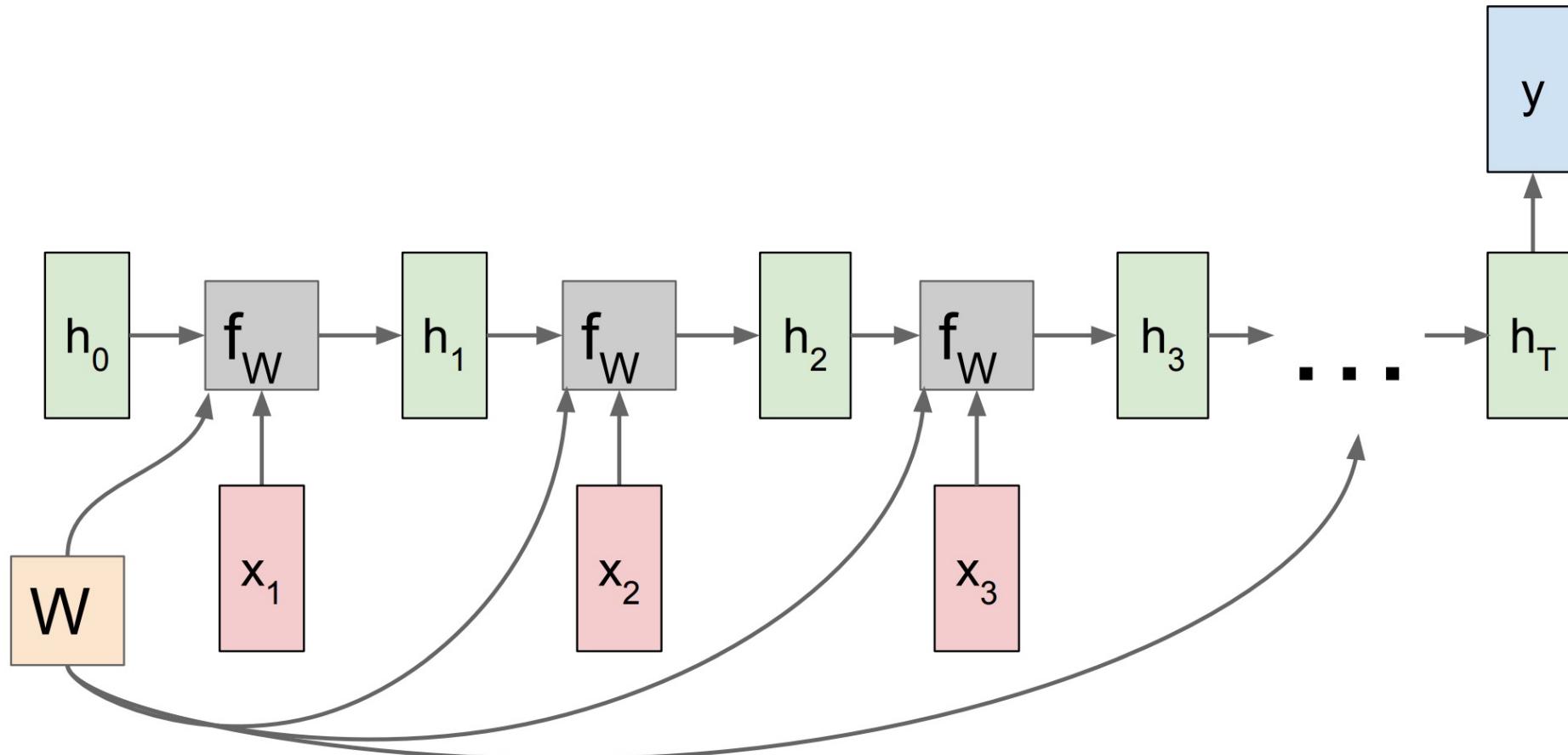
Proof. We will use the property we see that p is the next functor (??). On the other hand, by Lemma ?? we see that

$$D(\mathcal{O}_{X'}) = \mathcal{O}_X(D)$$

where K is an F -algebra where δ_{n+1} is a scheme over S . \square

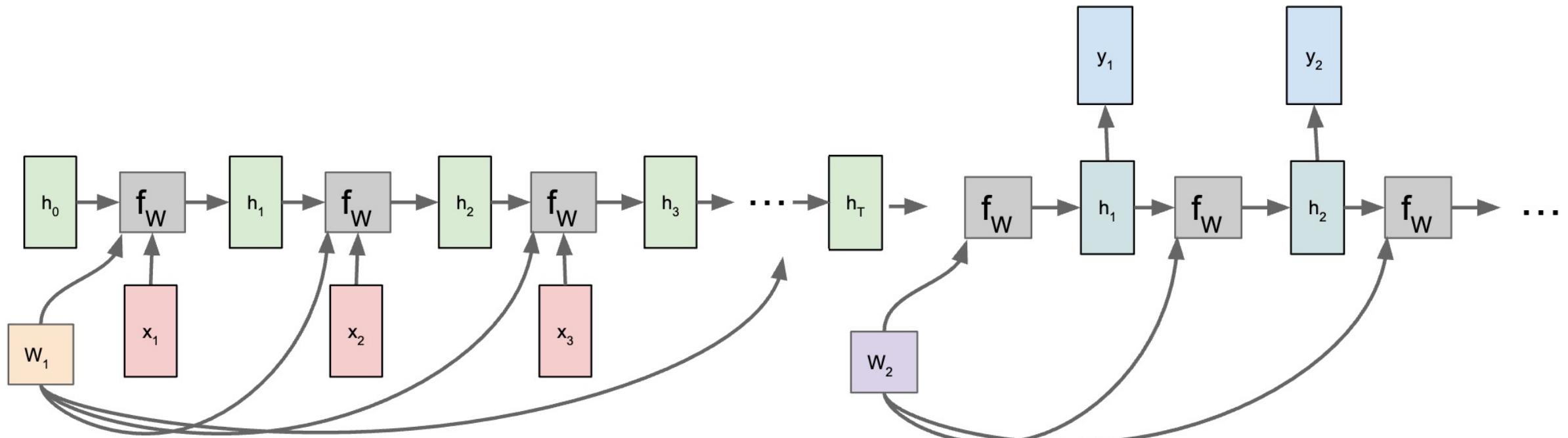
Grafo de cómputo

Many to one



Grafo de cómputo

Sequence to Sequence: Many to one + one to many



Encoder: codifica la secuencia de entrada en un embedding

Decoder: decodifica la secuencia de salida desde el embedding

Ejemplo de uso para image captioning

Deep Visual-Semantic Alignments for Generating Image Descriptions

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Abstract

We present a model that generates natural language descriptions of images and their regions. Our approach leverages datasets of images and their sentence descriptions to learn about the inter-modal correspondences between language and visual data. Our alignment model is based on a novel combination of Convolutional Neural Networks over image regions, bidirectional Recurrent Neural Networks over sentences, and a structured objective that aligns the two modalities through a multimodal embedding. We then describe a Multimodal Recurrent Neural Network architecture that uses the inferred alignments to learn to generate novel descriptions of image regions. We demonstrate that our alignment model produces state of the art results in retrieval experiments on Flickr8K, Flickr30K and MSCOCO datasets. We then show that the generated descriptions significantly outperform retrieval baselines on both full images and on a new dataset of region-level annotations.

1. Introduction

A quick glance at an image is sufficient for a human to point out and describe an immense amount of details about

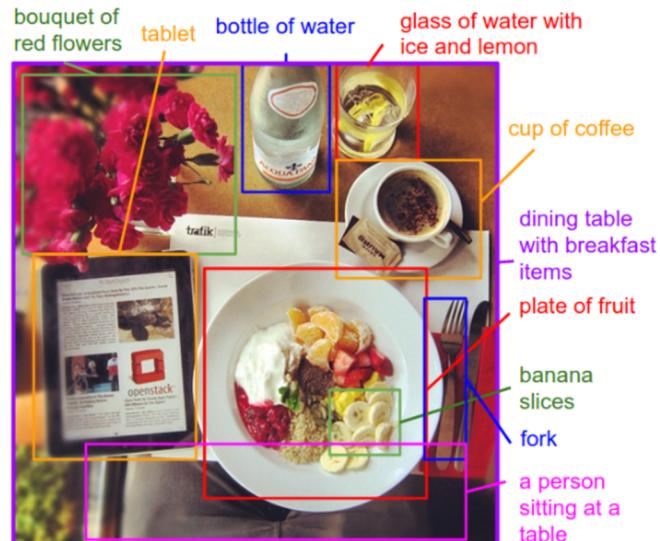


Figure 1. Motivation/Concept Figure: Our model treats language as a rich label space and generates descriptions of image regions.

generating dense descriptions of images (Figure 1). The primary challenge towards this goal is in the design of a model that is rich enough to simultaneously reason about contents of images and their representation in the domain of natural language. Additionally, the model should be free

Dataset of images and sentence descriptions

training image



"A Tabby cat is leaning on a wooden table, with one paw on a laser mouse and the other on a black laptop"

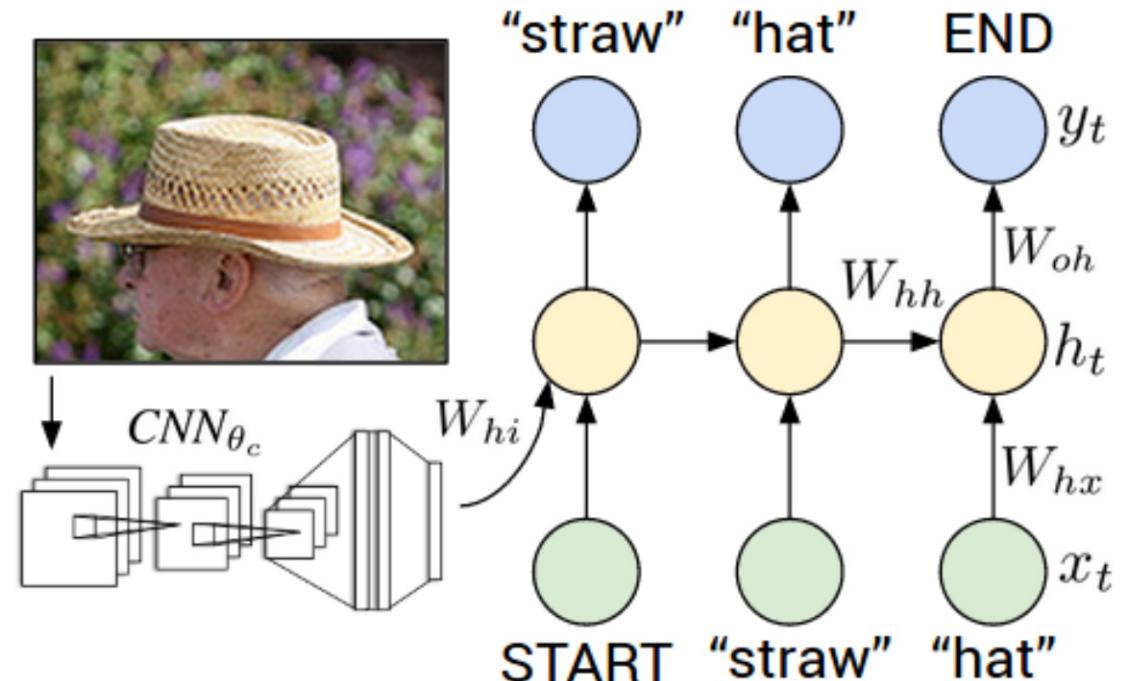
Ejemplo de uso para image captioning

before:

$$h = \tanh(W_{xh} * x + W_{hh} * h)$$

now:

$$h = \tanh(W_{xh} * x + W_{hh} * h + W_{ih} * v)$$



Clase 5

Redes neuronales más allá de la clasificación de imágenes

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 @enzoferante

