#### **Path Accumulators**

When trying to keep track of a node from a root (or other node), keeping track of the paths taken prevents the same path being taken (looping). Think of these as bungee cords that come from a root and try to find a route.

- · Original recursion current branch of the data is in the past
- Prevents cycles (A leads to B and B leads to A)

```
(local [(define R (sqrt (length m)))
     ;; trivial:
      ;; reduction:
     ;; argument:
     (define (fn-for-p p path passed-start?)
        (cond [(equal? p end) (add1 (position-of start path))]
              ;if end is reached, then find the distance between start/path
              ;[(solved? p)
                               false]
              [(member? p path) false] ;termination condition/result
              [else
              (if (equal? p start)
                  (fn-for-lop (next-ps p) (cons p path) true)
                   ; if the starting node has been found, pass true as acc
                  (fn-for-lop (next-ps p) (cons p path) passed-start?))]))
                  ; if the starting node is yet to be found pass acc
     (define (fn-for-lop lop path dist)
        (cond [(empty? lop) false]
             [else
               (local [(define try (fn-for-p (first lop) path dist))]
                 (if (not (false? try))
                     (fn-for-lop (rest lop) path dist)))]))
     ;; CONSTRAINT: p is in lop
      (define (position-of p lop)
        (cond [(empty? p) (error "p was not in lop")]
              [else
               (if (equal? p (first lop))
                  (add1 (position-of p (rest lop))))]))
(fn-for-p (make-pos 0 0) empty false)))
```

## (Full Code)

```
(local [(define R (sqrt (length m)))
     ;; trivial:
      ;; reduction:
     ;; argument:
     (define (fn-for-p p path passed-start?)
       (cond [(equal? p end) (add1 (position-of start path))]
             ;if end is reached, then find the distance between start/path
             ;[(solved? p)
                             false]
             [(member? p path) false] ;termination condition/result
             Γelse
              (if (equal? p start)
                  (fn-for-lop (next-ps p) (cons p path) true)
                   ; if the starting node has been found, pass true as acc
                  (fn-for-lop (next-ps p) (cons p path) passed-start?))]))
                  ; if the starting node is yet to be found pass acc
     (define (fn-for-lop lop path dist)
        (cond [(empty? lop) false]
             [e] se
```

```
(local [(define try (fn-for-p (first lop) path dist))]
                 (if (not (false? try))
                    try
                     (fn-for-lop (rest lop) path dist)))]))
     ;; CONSTRAINT: p is in lop
     (define (position-of p lop)
        (cond [(empty? p) (error "p was not in lop")]
              (if (equal? p (first lop))
                  (add1 (position-of p (rest lop))))]))
     ;; Pos -> Boolean
      ;; produce true if pos is at the lower right
     (define (solved? p)
       (and (= (pos-x p) (sub1 R))
            (= (pos-y p) (sub1 R))))
     ;; Pos -> (listof Pos)
      ;; produce next possible positions based on maze geometry
     (define (next-ps p)
       (local [(define x (pos-x p))
                (define y (pos-y p))]
          (filter (lambda (p1)
                    (and (\leq 0 (pos-x p1) (sub1 R)); legal x
                        (<= 0 (pos-y p1) (sub1 R)) ;legal y
                        (open? (maze-ref m p1)))) ;open?
                  (list (make-pos x (sub1 y))
                       (make-pos x (add1 y))
                                                   ; down
                       (make-pos (sub1 x) y)
                                                     ;left
                       (make-pos (add1 x) y)))) ;right
     ;; Maze Pos -> Boolean
     ;; produce contents of maze at location p
     ;; assume p is within bounds of maze
     (define (maze-ref m p)
       (list-ref m (+ (pos-x p) (* R (pos-y p)))))]
(fn-for-p (make-pos 0 0) empty false)))
```

#### **Visited Accumulators**

When trying to keep track of all the nodes that have been checked, visited prevents ... . This is similar to spray paint where if a node has already been "visited," the program proceeds to the next node. This prevents

- Tail recursion every node visited in the computation
- Prevents cycles and joins (two paths to the same node)

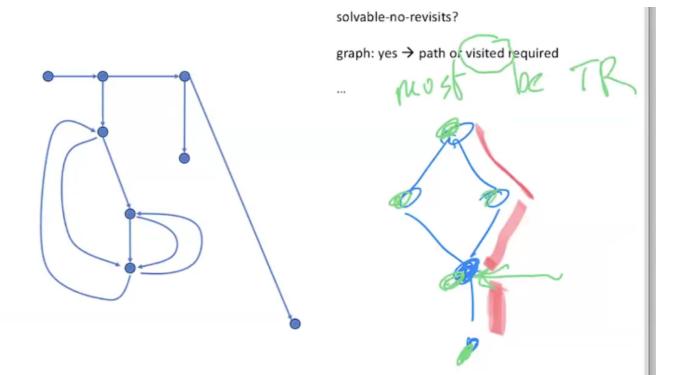
```
(define (solvable-no-revisits? m)
 (local [(define R (sqrt (length m)))
          ;; trivial: ...
          ;; reduction: ...
          ;; argument: ..
          (define (fn-for-p p p-wl visited)
            (cond [(solved? p) true] ;is condition met?
                  [(member? p visited) (fn-for-lop p-wl visited)]
                  ;if path has been visited, skip by "ignoring" current p by:
                  ; 1. not adding p to visited accumulator
                  ; 2. not adding p's children to worklist accumulator
                  [else
                  (fn-for-lop (append (next-ps p) p-wl) (cons p visited))]))
          (define (fn-for-lop p-wl visited)
            (cond [(empty? p-wl) false]
                  [else
```

```
(fn-for-p (first p-wl) (rest p-wl) visited)]))
; tail recursive to record all nodes visited.
...1
(fn-for-p (make-pos 0 0) empty empty)))
```

### (Full code)

```
(local [(define R (sgrt (length m)))
        ;; trivial:
        ;; reduction:
        ;; argument:
        (define (fn-for-p p p-wl visited)
          (cond [(solved? p) true] ;is condition met?
                [(member? p visited) (fn-for-lop p-wl visited)]
                ;if path has been visited, skip by "ignoring" current p by:
               ; 1. not adding p to visited accumulator
                ; 2. not adding p's children to worklist accumulator
                 (fn-for-lop (append (next-ps p) p-wl) (cons p visited))]))
        (define (fn-for-lop p-wl visited)
          (cond [(empty? p-wl) false]
               [else
                (fn-for-p (first p-wl) (rest p-wl) visited)]))
        ; tail recursive to record all nodes visited.
        ;; Pos -> Boolean
        ;; produce true if pos is at the lower right
        (define (solved? p)
          (and (= (pos-x p) (sub1 R))
              (= (pos-y p) (sub1 R))))
        ;; Pos -> (listof Pos)
        ;; produce next possible positions based on maze geometry
        (define (next-ps p)
         (local [(define x (pos-x p))
                 (define y (pos-y p))]
            (filter (lambda (p1)
                     (and (<= 0 (pos-x p1) (sub1 R)) ; legal x
                           (<= 0 (pos-y p1) (sub1 R)) ;legal y
                          (open? (maze-ref m p1)))) ;open?
                    (list (make-pos x (sub1 y))
                          (make-pos x (add1 y))
                                                      ; down
                                                      ;left
                          (make-pos (sub1 x) y)
                          (make-pos (add1 x) y)))))
                                                     ;right
        ;; Maze Pos -> Boolean
        ;; produce contents of maze at location p
        ;; assume p is within bounds of maze
        (define (maze-ref m p)
          (list-ref m (+ (pos-x p) (* R (pos-y p)))))]
 (fn-for-p (make-pos 0 0) empty empty)))
```

#### BFS vs. DFS



```
(define (solvable-no-revisits? m)
 (local [(define R (sqrt (length m)))
         ;; trivial:
         ;; reduction:
         ;; argument:
         ;; visited is (listof Pos)
         ;; every position passed through so far in the tail recursion
          (define (fn-for-p p p-wl visited)
            (cond [(solved? p) true]
                  [(member? p visited)
                   (fn-for-lop
                                                   p-wl
                                                                 visited)]
                  [else
                   (fn-for-lop (append (next-ps p) p-wl) (cons p visited)♥]))
          (define (fn-for-lop p-wl visited)
            (cond [(empty? p-wl) false]
                  [else
                   (fn-for-p (first p-wl) (rest p-wl) visited)]))
```

```
(define (fn-for-p p path passed-start?)
   (cond [(and passed-start? (equal? p end))
          (add1 (position-in start path))]
          [(member? p path) false] ;ordinary recursion fail
          [else
          (fn-for-lop (next-ps p)
                        (cons p path)
                        (if (equal? p start)
                            true
                            passed-start?))]))
(define (fn-for-lop lop path passed-start?)
   (cond [(empty? lop) false]
         [else
           (local [(define try
                      (fn-for-p (first lop) path passed-start?))]
             (if (not (false? try))
                 try
                 (fn-for-lop (rest lop) path passed-start?)))]))
  ;; CONSTRAINT p is in path
  (define (position—in p path)
     (cond [(empty? path) "can't happen!"]
             [else
              (if (equal? (first path) p)
                    (add1 | (position-in p (rest path))_{1}))
;; Question 2:
;; I know that:
;; A. working through practice problems on my own is the best way to
    prepare for the final
;; B. WATCHING video is nowhere near as effective as playing a little,
     stopping, trying to get ahead, restarting and comparing what I
     did to the video
;; C. Office hours are the best place to work through practice problems
     because I can get hints from course staff rather than looking at solution
;; D. Using the problem bank is a good way to assess what material I already
;; have mastered and what material I should be working on
;; D2. The exam will have more than one problem, spending too much mental energy
    preparing for tandem worklist graph problems isn't a good use of my time
     until I am already comfortable with everything up to that point
;; E. All of the above
```

## What have you learned ... about design?

- Figuring out what you actually want is half the battle
  - · signature
  - purpose
  - · examples (wrapped in check-expect)
  - · information examples
  - · interpretation

## What have you learned ... about design?

- then the structure of the solution
  - · template origins
  - · accumulator types and invariants
- and the details
  - · fill in ... according to all above
  - debug

All 5 tests pass!

# What have you learned ... about design?

## but sometimes

```
50% of 50% Submitted tests: correct - all submitted test pass.
0% of 50% Additional tests: incorrect - 3 autograder internal additional tests failed.
```

- · despite your best efforts
- · what you end up with is not what you really wanted
- · go back and systematically revise the design, and learn from that error

Problems that build off of PSET 9-11