view\_frames Result Recorded at time: 75.588 agent1\_tf/odom Broadcaster: /gazebo Average rate: 10000.000 Hz Average rate: 30.583 Hz Most recent transform: 75.573 (0.015 sec old) Buffer length: 0.000 sec Buffer length: 1.733 sec agent1\_tf/base\_footprint Broadcaster: /agent2/robot\_state\_publisher Broadcaster: /agent1/robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (75.588 sec old) Most recent transform: 0.000 (75.588 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec agent2\_tf/base\_scan agent1\_tf/base\_link Broadcaster: /agent1/robot\_state\_publisher Broadcaster: /agent1/robot\_state\_publisher Broadcaster: /agent1/robot\_state\_publisher Broadcaster: /agent1/robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 30.560 Hz Most recent transform: 0.000 (75.588 sec old) Most recent transform: 0.000 (75.588 sec old) Most recent transform: 75.573 (0.015 sec old) Most recent transform: 0.000 (75.588 sec old) Buffer length: 0.000 sec Buffer length: 1.767 sec Buffer length: 0.000 sec Buffer length: 0.000 sec agent1\_tf/base\_scan agent1\_tf/wheel\_left\_link agent1\_tf/imu\_link Broadcaster: /agent1/robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (75.588 sec old) Buffer length: 0.000 sec

Broadcaster: /agent1/robot\_state\_publisher

Average rate: 30.560 Hz

Most recent transform: 75.573 (0.015 sec old)

Buffer length: 1.767 sec

agent1\_tf/wheel\_right\_link

