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1 # AprilTag 3 code parameters
2 # Find descriptions in apriltag/include/apriltag.h:struct apriltag_detector
3 #      apriltag/include/apriltag.h:struct apriltag_family
4 tag_family:      'tag36h11' # options: tagStandard52h13, tagStandard41h12, tag36h11, tag25h9,
   tag16h5, tagCustom48h12, tagCircle21h7, tagCircle49h12
5 tag_threads:      2          # default: 2
6 tag_decimate:      1.0        # default: 1.0
7 tag_blur:          0.0        # default: 0.0
8 tag_refine_edges:  1          # default: 1
9 tag_debug:         0          # default: 0
10 max_hamming_dist: 2          # default: 2 (Tunable parameter with 2 being a good choice -
   values >=3 consume large amounts of memory. Choose the largest value possible.)
11 # Other parameters
12 publish_tf:       true        # default: false
13 transport_hint:    "raw"      # default: raw, see http://wiki.ros.org/-
   image_transport#Known_Transport_Packages for options
```