

Temperature Dependence of T_1 Relaxation Time: An Inverse Problem Approach

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Introduction

The process of Magnetic Resonance Laser Induced Temperature Treatment (MRLITT) as a minimally invasive local treatment of cancerous tumors has received increasing attention in recent years. Performance of MRLITT crucially depends on parameters like tissue relaxation times, known as T_1 and T_2 . One of the major challenges in MRLITT process is temperature dependence of these parameters. Hence, one needs to have an accurate approximation of changes in relaxation times as a function of tissue temperature. In this manuscript, we study the effect of the temperature of T_1 relaxation time.

Problem Statement

It is well established that the T_1 relaxation time changes as a function of temperature [1]. In general, it is assumed that T_1 relaxation time linearly changes as a function of temperature u :

$$T_1(u) = T_1^{ref} (1 + m(u - u^{ref})) \quad (1)$$

where, u^{ref} denotes the tissue temperature in normal conditions and T_1^{ref} represents the corresponding value of relaxation time. Coefficient m denotes the sensitivity of T_1 relaxation time with respect to temperature u and it is usually between 0.01 and 0.02 for different tissue types. Note that due to tissue dependencies of parameters m and T_1^{ref} , it is a reasonable assumption to consider these parameters to be uncertain.

On the other hand, a measurement data is given by the following observation model

$$\rho = h(u) = \frac{\sin(\theta) \left(1 - e^{-\frac{T_r}{T_1(u)}}\right)}{\sin(\beta) \left(1 - \cos(\theta)e^{-\frac{T_r}{T_1(u)}}\right)} + \nu, \quad \nu \sim \mathcal{N}(0, \sigma) \quad (2)$$

where, θ and β are corresponding flip angles of the experiment and T_r denotes the repetition time. Note that β is usually considered to be a small angle and $\theta \gg \beta$ in general.

In case of different repetition times, the equation for ρ can be written as:

$$\rho = \frac{\sin(\theta) \left(1 - e^{-\frac{T_{r,1}}{T_1(u)}}\right) \left(1 - e^{-\frac{T_{r,2}}{T_1(u)}} \cos(\beta)\right)}{\sin(\beta) \left(1 - e^{-\frac{T_{r,2}}{T_1(u)}}\right) \left(1 - \cos(\theta) e^{-\frac{T_{r,2}}{T_1(u)}}\right)} + \nu \quad (3)$$

where, $T_{r,1}$ and $T_{r,2}$ denote the corresponding repetition times for flip angles θ and β .

The key goal of this article is to find a good estimate for temperature dependencies of parameter T_1 , given a set of data observations ρ_k , $k = 1, 2, \dots, n$. Note that the uncertainty in T_1 is related to uncertain parameters m and T_1^{ref} . Hence, the problem of T_1 estimation is equivalent with estimating the parameters m and T_1^{ref} .

Parameter Estimation

We use a minimum variance framework for estimating the parameters T_1^{ref} and m . To do so, let's first concatenate these parameters in a parameter vector Θ , i.e.

$$\Theta = [T_1^{ref}, \quad m]^T$$

Note that there exist some prior statistics, e.g. mean and covariance, for the parameter Θ :

$$\hat{\Theta} \equiv \mathcal{E}[\Theta] = \int_{\Theta} \Theta p(\Theta) d\Theta \quad (3)$$

$$\Sigma \equiv \mathcal{E}[(\Theta - \mathcal{E}[\Theta])(\Theta - \mathcal{E}[\Theta])^T] = \int_{\Theta} (\Theta - \mathcal{E}[\Theta])(\Theta - \mathcal{E}[\Theta])^T p(\Theta) d\Theta \quad (3)$$

Now, based on the minimum variance framework, posterior statistics of Θ are given as [2, 3]:

$$\begin{aligned} \hat{\Theta}^+ &= \hat{\Theta}^- + \mathbf{K}(\mathbf{z} - \mathcal{E}^-[h(u)]) \\ \Sigma^+ &= \Sigma^- + \mathbf{K}\Sigma_{hh}\mathbf{K}^T \end{aligned}$$

where, $\mathbf{z} = \rho_1, \rho_2, \dots, \rho_n$ is the measurement vector of n observations and the gain matrix \mathbf{K} is given by

$$\mathbf{K} = \Sigma_{\Theta h}^T (\Sigma_{hh}^- + \mathbf{R})^{-1} \quad (3)$$

and \mathbf{R} represent covariance matrix of the noise signal ν . The matrices $\Sigma_{\Theta h}$ and Σ_{hh} are defined as:

$$\begin{aligned} \hat{h}^- &\triangleq \mathcal{E}^-[h(u, \Theta)] = \int_{\Theta} \underbrace{h(u, \Theta)}_h p(\Theta) d\Theta \\ \Sigma_{\Theta h} &\triangleq \mathcal{E}^-[(\Theta - \hat{\Theta})(h - \hat{h}^-)^T] \\ \Sigma_{hh}^- &\triangleq \mathcal{E}^-[(h - \hat{h}^-)(h - \hat{h}^-)^T] \end{aligned}$$

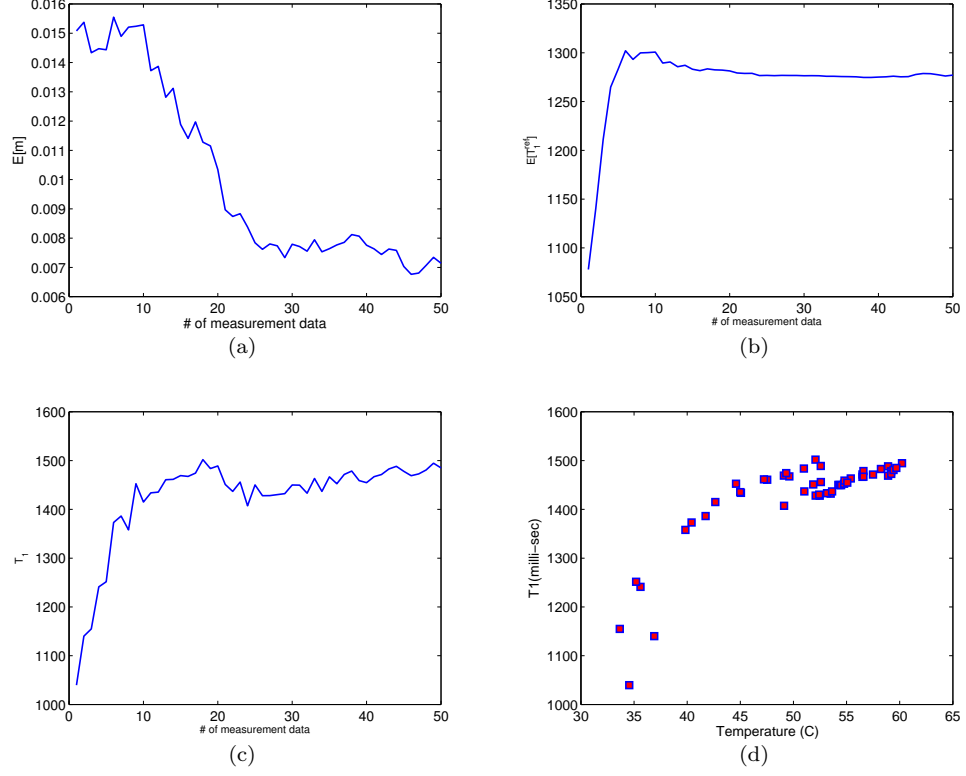


Figure 1: a-c) convergence of parameter estimates versus different number of data observations a) m , b) T_1^{ref} , and c) T_1 . Fig d) shows the variations of the estimated T_1 versus changes of tissue temperature.

Note that in above equations, superscripts $+$ and $-$ are used to represent posterior and prior values of the corresponding statistics.

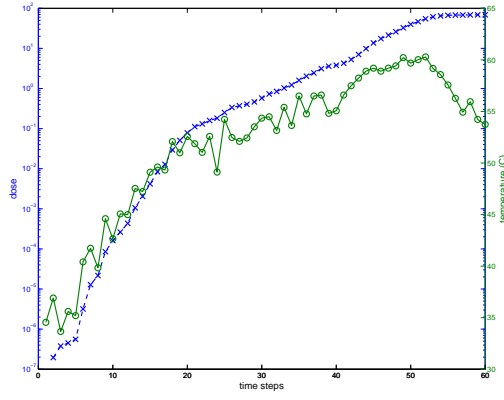
Numerical Simulations

For simulation purpose, we have considered the problem of estimating T_1 for a set of experimental data, resulted from MRLITT.

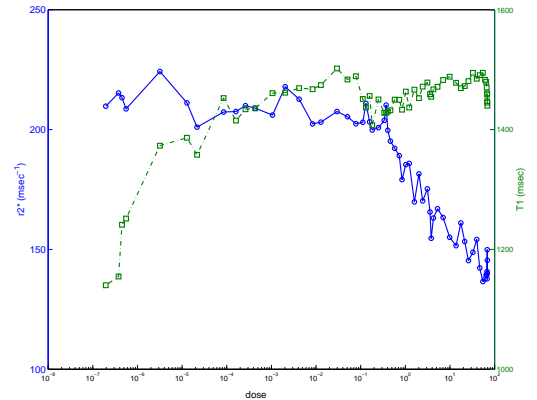
Figure 2: Variation of T_1 field during the heating

References

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- [3] R. Madankan, P. Singla, T. Singh, and P. D. Scott, “Polynomial-chaos-based bayesian approach for state and parameter estimations,” *Journal of Guidance, Control, and Dynamics*, vol. 36, no. 4, pp. 1058–1074, 2013.



(a)



(b)

Figure 3: a) variations of temperature and necrosis dose over time, b) variations of $r2^*$ and $T1$ versus necrosis dose

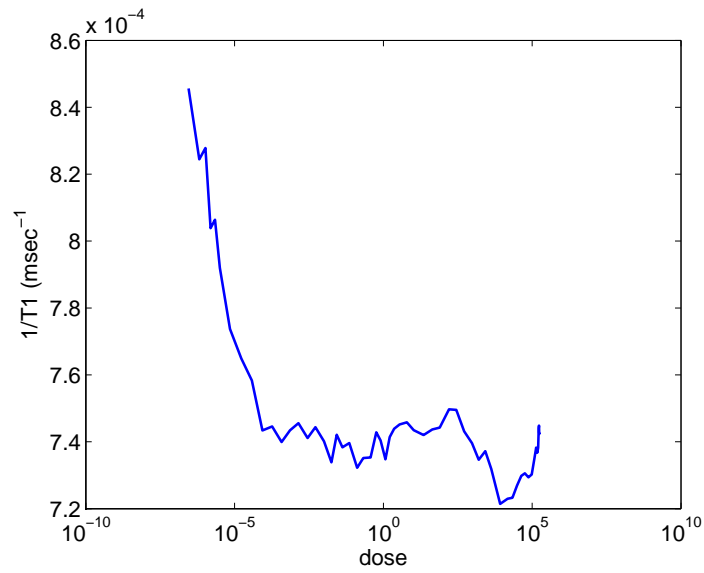


Figure 4: variations of $r1$ versus necrosis dose