

VERILOG TIMING DEMYSTIFIED: REAL SIMULATION BEHAVIOR OF BLOCKING & NON-BLOCKING ASSIGNMENTS.

12/17/2025

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Design and simulate a Verilog module that uses a combination of blocking (=) and non-blocking (<=) assignments along with procedural delays and intra-assignment delays. Analyze how these constructs affect the execution order, signal update timing, and final value of a variable during simulation.

```
module test1();  
integer a = 0;  
  
initial  
begin  
#2 a = #2 2; // at t = 4 , a = 2  
a <= #3 3; // at t = 7, a = 3  
#2 a = 4; // at t = 6 , a = 4  
#2 a <= 5; // at t = 8 , a = 5  
#2 a = #2 6; // at t = 12, a = 6  
a = #2 7; // at t = 14 , a = 7  
a <= #2 8; // at t = 16, a = 8  
#2 a <= #5 9; // at t = 21, a = 9  
#3 a = 10; // at t = 19, a = 10  
end
```

```
initial  
$monitor("at time t = %0t, a = %0d", $time, a);  
endmodule
```

EDA Playground Link (Run & Observe Live):

<https://www.edaplayground.com/x/hCaH>

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Analyze the time-wise value changes of a by considering blocking vs non-blocking assignments, intra-assignment delays, and parallel execution using fork...join.

```
module test2();  
  
integer a = 0;  
  
initial  
begin  
    #2 a = #2 2; // at t = 4 a = 2  
    a <= #3 3; // at t = 7, a = 3  
    fork  
        #1 a = 4; // at t = 5 , a = 4  
        #2 a <= 5; // at t = 6 , a = 5  
    join  
        #2 a = #2 6; // at t = 10, a = 6  
        a = #2 7; // at t = 12 , a = 7  
        a <= #2 8; // at t = 14, a = 8  
        #2 a <= #5 9; // at t = 19, a = 9  
        #3 a = 10; // at t = 17, a = 10  
    end
```

```
initial  
    $monitor("at time t = %0t, a = %0d", $time, a);  
endmodule
```

EDA Playground Link (Run & Observe Live):

<https://www.edaplayground.com/x/wh3w>

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Analyze the given Verilog code to determine the value of a at each time step, considering all blocking and nonblocking assignments, delays, and the execution order. Pay special attention to the begin–end block inside the fork–join, which groups multiple statements as a single parallel thread.

```
module test3();  
integer a = 0;  
initial begin  
#2 a = #2 2; // at t = 4 a = 2  
a <= #3 3; // at t = 7, a = 3  
fork  
begin  
#1 a = 4; // at t = 5 , a = 4  
#2 a = 5; // at t = 7 , a = 5  
end  
#2 a = #2 6; // at t = 8, a = 6  
join  
a = #2 7; // at t = 10 , a = 7  
a <= #2 8; // at t = 12, a = 8  
#2 a <= #5 9; // at t = 17, a = 9  
#3 a = 10; // at t = 15, a = 10  
end  
initial  
$monitor("at time t = %0t, a = %0d", $time, a);  
endmodule
```

EDA Playground Link (Run & Observe Live):

<https://www.edaplayground.com/x/ghL>

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Analyze the Verilog module test4 where variable a undergoes a series of blocking (=) and non-blocking (<=) assignments with specified delays (e.g., #2 a = #2 2;, #3 a <= #3 3;). Determine the value of a at each time step, considering how the delays and assignment types affect the timing.

```
module test4();
integer a = 0;
initial begin
#2 a = #2 2; // at t = 4 a = 2
#3 a <= #3 3; // at t = 10, a = 3
fork
#1 a = 4; // at t = 8 , a = 4
#2 a <= 5; // at t = 9 , a = 5
join
#2 a = #2 6; // at t = 13, a = 6
a = #2 7; // at t = 15 , a = 7
a <= #2 8; // at t = 17, a = 8
#2 a <= #5 9; // at t = 22, a = 9
#3 a = 10; // at t = 20, a = 10
end
initial
$monitor("at time t = %0t, a = %0d", $time, a);
endmodule
```

EDA Playground Link (Run & Observe Live):

<https://www.edaplayground.com/x/ukF9>

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Technical Tips:

Diving Deep into Verilog Timing!

When designing digital systems, mastering blocking (=) vs non-blocking (<=) assignments, along with procedural delays and intra-assignment delays, is crucial for accurate simulation and synthesis. I recently experimented with multiple Verilog modules to observe these effects firsthand.

Key Observations from the Simulation Modules:

1 Blocking Assignments (=):

- Execute sequentially within a procedural block.
- The RHS is evaluated and the LHS updated immediately, before moving to the next statement.
- Intra-assignment delays (e.g., #2 a = #2 2;) delay the evaluation of the RHS, affecting when the value propagates.

2 Non-blocking Assignments (<=):

- Schedule updates at the end of the current time step.
- Allow multiple assignments to the same variable to be queued and updated in parallel, making them ideal for modeling register behavior.

3 Procedural Delays (#n):

- Introduce specific timing gaps in simulation, essential to model real hardware delays.
- When combined with blocking and non-blocking assignments, they influence which value appears at each simulation time step.

4 Fork-Join Parallelism:

- Enables multiple threads to execute in parallel.
- When combined with blocking assignments inside a fork-join, execution order is maintained within a thread, but parallel threads can update variables concurrently, leading to race conditions if not carefully managed.

5 Simulation Insights (Time-wise analysis):

- Carefully observing \$monitor outputs in EDA Playground showed that final values of a at each step depend on a combination of assignment type, delay, and execution order.

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- Blocking assignments dominate the sequential thread timing, whereas non-blocking assignments schedule updates later, reflecting realistic hardware behavior.

Tips for Practitioners:

- Always distinguish when to use `=` vs `<=`; the wrong choice can introduce simulation mismatches.
- Use intra-assignment delays for precise modeling of hardware delays.
- Combine `$monitor` with time-stamped logs to visualize the exact timing sequence.
- Be cautious with fork-join and multiple assignments to the same variable; race conditions can mask bugs.
- Regularly simulate on tools like EDA Playground to validate timing before synthesis.



Pro Tip:

Document time-step analysis tables alongside simulation outputs. It helps you predict the final values and makes debugging complex sequential logic much easier.



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<https://www.linkedin.com/in/madan-raj-c-r-b6029721b/>

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Try these examples live on EDA Playground:

- [Module test1](#)
- [Module test2](#)
- [Module test3](#)
- [Module test4](#)